

EGO: a global 0.05° hourly GPP dataset for monitoring diurnal photosynthesis dynamics

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Abstract. Vegetation photosynthesis, quantified as gross primary productivity (GPP), regulates the terrestrial carbon sink and land-atmosphere exchanges. At sub-daily scales, diurnal GPP dynamics reveal rapid adjustments to changing light, temperature and water conditions that are largely obscured in daily-to-annual aggregates, underscoring the need for developing global hourly GPP products. However, existing hourly products mostly rely on traditional machine-learning schemes that lack explicit biophysical constraints and an adequate representation of water limitation, leading to large uncertainties, especially in arid regions. Besides, the added value of hourly products for resolving diurnal behavior and responses to environmental stress remains poorly quantified. Here, we develop a causal knowledge-driven upscaling framework that couples the Peter and Clark Momentary Conditional Independence guided causal weights with ensemble learning strategies. Based on eddy-covariance measurements and multi-source meteorological variables, vegetation properties, and land-cover fields, we generated a global 0.05° monthly-averaged hourly GPP product covering 06:00–18:00 local solar time from 2000 to 2022, named EGO (Eddy covariance site-based Global hOurly) GPP, and then evaluated how well EGO reproduces observed diurnal cycles and their responses to extreme events. EGO GPP achieves an R^2 of 0.76 and an RMSE of $4.17 \mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$ on independent test sites, and outperforms two recent hourly upscaling products (FLUXCOM and X-BASE; $R^2 \approx 0.60$ and $\text{RMSE} \approx 5.5 \mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$), with large improvement in drylands. EGO GPP clearly illustrates the diurnal progression of photosynthesis and captures observed diurnal metrics across diverse biomes, revealing strong midday depression and morning-skewed curves in drylands but near-symmetric cycles in high-latitude and humid tropical regions. Analyses of the June 2021 central North America drought and the August 2003 European heatwave further show that EGO reliably tracks diurnal photosynthetic responses to extremes, including GPP reductions, earlier centroid/peak times and intensified midday depression, consistent

35 with tower-based results. Looking ahead, EGO GPP provides a reliable foundation for investigating diurnal photosynthetic behavior, exploring vegetation–climate interactions and benchmarking Earth system models at a sub-daily scale. EGO GPP is available at <https://doi.org/10.5281/zenodo.18253238> (Liu et al., 2026).

1 Introduction

Vegetation assimilates atmospheric CO₂ into organic carbon through photosynthesis, forming the largest carbon flux between the biosphere and the atmosphere (Schimel et al., 2001; Keenan and Williams, 2018). Gross primary productivity (GPP) is defined as the total carbon fixed by terrestrial ecosystems through photosynthesis (Beer et al., 2010). Existing studies have investigated GPP dynamics across multiple temporal scales, from annual and monthly to daily and sub-daily (Ryu et al., 2019; Xiao et al., 2021). Analyses at longer timescales (e.g., daily, monthly and annual) provide valuable insights into photosynthetic phenology and interannual variability (Xiao et al., 2025). In contrast, shorter scales (e.g., sub-daily or hourly) focus on how vegetation photosynthesis responds to instantaneous changes in light, temperature, and water availability within a day (Urbanski et al., 2007). These short-term dynamics reveal rapid physiological regulation of vegetation, particularly via stomatal conductance, offering a unique window into the mechanisms of vegetation–environment interactions. Early flux tower-based studies showed that short-term variations in environmental factors can induce pronounced diurnal fluctuations in vegetation photosynthesis, that are often obscured in longer-timescale analyses (Baldocchi et al., 2001; Goulden et al., 2004; Wofsy et al., 1993). More recently, advances in remote sensing, especially the emergence of new-generation geostationary satellites, have enabled regional-scale studies that report several key physiological phenomena occurring at sub-daily timescales, including midday depression or increasing diurnal asymmetry in photosynthesis under stress (Li et al., 2023; Xiao et al., 2021; Zhang et al., 2023a). These studies extend beyond the spatial coverage of traditional tower-based monitoring, allowing diurnal dynamics to be characterized across broader regions. Nevertheless, current investigations remain largely confined to site or regional scales, limiting our understanding of diurnal photosynthetic behavior across global ecosystems. Consequently, monitoring the diurnal dynamics of vegetation photosynthesis at the global scale has become a key prerequisite for uncovering the general mechanisms that govern photosynthetic behavior and its responses to environment.

Polar-orbiting satellites provide near-global coverage and have therefore become the primary tools for generating global GPP products, such as the Moderate Resolution Imaging Spectroradiometer (MODIS) and Advanced Very High Resolution Radiometer (AVHRR) (Robinson et al., 2018; Xiao et al., 2019; Zhao et al., 2005). However, their sun-synchronous orbits provide only instantaneous snapshots at fixed overpass times, making it difficult to resolve continuous diurnal course of photosynthesis and fundamentally limiting their applicability for sub-daily studies. In recent years, new-generation geostationary satellites, including the Geostationary Operational Environmental Satellite, Himawari-8/9, and GK-2A etc., provide high-frequency, continuous observations, and have been used to monitor diurnal variations in photosynthesis, but their

65 coverage is restricted to specific regions, preventing truly global monitoring (Jeong et al., 2023; Li et al., 2023; Zhang et al., 2023a). In parallel, the Orbiting Carbon Observatory-3 (OCO-3) instrument onboard the International Space Station measures solar-induced chlorophyll fluorescence (SIF), a proxy for GPP, at varying local times, offering new opportunities to sample diurnal photosynthetic dynamics from space (Stavros et al., 2017; Taylor et al., 2020). Nevertheless, OCO-3 footprints are sparse and discontinuous in both space and time, which poses challenges for constructing continuous global maps of diurnal
70 photosynthesis (Deng et al., 2025; Liu et al., 2025; Zhang et al., 2023a). Unlike these satellite observations, eddy-covariance (EC) flux towers measure the turbulent exchange of carbon, water, and energy between ecosystems and atmosphere directly, providing near-continuous records at half-hourly or hourly resolution over multi-decadal periods (Xiao et al., 2025). They are widely regarded as the gold standard for flux measurements and remain the primary benchmark for validating gridded GPP products. Although global flux networks such as FLUXNET comprise hundreds of sites, their spatial distribution and
75 ecosystem representativeness remain highly uneven, making regional or global scale assessments challenging (Pastorello et al., 2020).

To overcome this challenge, machine-learning upscaling approaches based on EC measurements have demonstrated strong capabilities (Ichii et al., 2017). They learn complex relationships between environmental variables and GPP from large observations datasets and can then be extrapolated globally. A prominent example is FLUXCOM, the first global GPP product
80 derived from machine-learning upscaling method (Bodesheim et al., 2018). In its early version, FLUXCOM relied mainly on sub-daily radiation to drive the diurnal GPP cycle, since other hourly input variables were not yet available, inevitably overlooking short-term variability in environmental drivers such as temperature and water conditions. More recently, the FLUXCOM team incorporated hourly meteorological data from ERA5 and released X-BASE, which improved the robustness of upscaling framework (Nelson et al., 2024). However, even with these updates, certain limitations remain. As reported in
85 Nelson et al., (2024), this product exhibits considerable uncertainty in arid regions and a limited ability to capture water-related effects on diurnal photosynthesis. A plausible explanation is that the current predictor set does not fully represent the multiple dimensions of water limitation, even though both short-term water availability and long-term water balance strongly regulate ecosystem productivity and drought sensitivity in drylands (Liu et al., 2025). Beyond the choice of input variables, the modeling framework itself presents an additional challenge. Diurnal vegetation photosynthesis emerges from complex
90 interactions among biophysical and biochemical processes. Conventional machine learning models can capture non-linear relationships among many inputs, but their purely correlational nature limits direct process interpretation and raises questions about robustness under novel environmental conditions (Runge et al., 2019a).

Recently, approaches that combine causal inference with machine learning offer a promising pathway to better learn the complex relationships between environmental drivers and ecosystem fluxes (Kretschmer et al., 2021). Traditional machine
95 learning models typically rely on correlations rather than directional causal relationships (Yuan et al., 2022). Without causal guidance, these models risk capturing spurious associations driven by confounding factors such as predictors sharing similar

variations, which can render predictions unreliable (Galytska et al., 2023). As one of the state-of-the-art causal inference methods, the PCMCI (Peter and Clark Momentary Conditional Independence) offers a robust solution especially suitable for earth science applications, as it rigorously filters out confounding effects to identify true causal pathways (Runge et al., 2019b; Runge et al., 2023). Another benefit is its ability to represent time-lagged dependencies, which is critical for estimating hourly GPP, since previous research has highlighted that vegetation photosynthesis exhibits certain lagged responses to environmental fluctuations in sub-daily (Krich et al., 2020). By embedding the causal structure into machine learning models, PCMCI acts as a form of biophysical constraint that guides model training (Runge et al., 2023; Yuan et al., 2024). This concept is closely related to knowledge-guided machine learning (KGML), which incorporates prior process understanding or physical constraints into data-driven models (Ranjbar et al., 2026). PCMCI identifies causal relationships directly from observational data without relying on predefined process equations, thereby providing data-driven causal constraints that can guide machine learning models and improve their robustness. Recent applications of PCMCI in flux upscaling have shown encouraging results, for instance, Zhao and Zhu (2025) combined PCMCI with XGBoost to generate a global monthly ecosystem respiration product, which improved estimation accuracy by aligning model weight with causal pathways.

One additional important issue concerns the evaluation of hourly GPP products. Previous product-oriented studies rely on aggregated metrics such as coefficient of determination (R^2), root mean square error (RMSE), and bias (Bias), focusing on overall agreement with observations while providing little information on how well products reproduce diurnal shape of photosynthesis (Bodesheim et al., 2018; Leng et al., 2024; Zhang et al., 2023b). Yet the added value of hourly GPP lies precisely in its ability to resolve intra-day variations. Therefore, beyond conventional accuracy metrics, hourly GPP products should also be evaluated for their ability to reproduce key features of the diurnal photosynthetic cycle. Representative indicators include the diurnal GPP centroid, which reflects the temporal distribution of daily carbon uptake between morning and afternoon (Wilson et al., 2003), and relative midday depression (RMD), which captures the magnitude of midday photosynthetic suppression (Zhu and Zhu, 2025). Recent studies have revealed distinct diurnal features of vegetation photosynthesis, including global-scale morning–afternoon asymmetry (Khan et al., 2022; Lin et al., 2019; Liu et al., 2024), pronounced midday depression in mangrove ecosystems (Zhu and Zhu, 2025), and heatwave-induced advances of daily photosynthetic peak by 2–3 hours in dryland regions (Li et al., 2023). Demonstrating the capacities of the new hourly GPP products in capturing these environment-driven diurnal shifts is essential for their widespread use in global change studies.

Here, we develop a new global hourly GPP product using a causal-constrained machine-learning framework based on EC-site measurements. We combine a multi-dimensional set of predictors, including meteorological variables, vegetation properties and indicators of both short-term and long-term water availability, in order to more fully represent vegetation–environment interactions, and then conduct a multi-faceted evaluation of the product’s ability to reproduce key diurnal features of photosynthesis. Specifically, we aim to 1) produce a global 0.05°, hourly GPP product upscaled from flux-tower observations and assess its overall accuracy and robustness, 2) evaluate how well the product characterizes diurnal photosynthetic dynamics,

and 3) examine the capability of the product in capturing vegetation diurnal response to extreme climatic events. The resulting product is intended to provide a valuable resource for diurnal global carbon-cycle studies, to enable more accurate characterization of short-term vegetation–climate interactions, and to offer an observational benchmark for evaluating Earth system model simulations at sub-daily time scale.

2 Data

This study combined multi-source from ground-based, satellite and reanalysis datasets to develop a global hourly GPP product. EC measurements from 190 flux sites served as the primary reference for model training and validation, providing site-level benchmarks for ecosystem photosynthesis. As predictors, we used a suite of global gridded datasets of environmental, vegetation and land-cover variables for mapping hour GPP globally, and further compared our product with two existing hourly upscaled GPP datasets (FLUXCOM and X-BASE) in terms of overall accuracy, diurnal dynamics and spatial patterns.

2.1 Eddy covariance data

The FLUXNET2015 Tier 1 dataset (<https://fluxnet.org/>), spanning approximately 1990–2014, integrates long-term EC flux observations from multiple regional networks worldwide and provides harmonized tower data after standardized flux partitioning, quality control, and gap-filling (Pastorello et al., 2020). To further expand the training samples for modelling, we additionally incorporated data from AmeriFlux (<https://ameriflux.lbl.gov/>), covering ~1990 to the present (data up to 2022 were used), that follow the same processing pipelines with FLUXNET (Chu et al., 2023). Given that the footprint of EC observations differs from the 0.05° grid of the upscaled product, we applied additional filtering to reduce scale mismatch (Chu et al., 2021). We first used the MODIS land cover product (MCD12Q1 Version 6.1 with 500 m resolution, covering 2001–2022) and reclassified its vegetation types following the scheme in Table S1 to ensure consistency with the flux-site classification. For each flux site, we identified the corresponding 0.05° grid cell containing the tower location and calculated the fractional coverage of each reclassified vegetation type from all 500 m MODIS pixels within that grid cell for each year. The vegetation type with the largest fractional coverage was defined as the dominant class of that 0.05° grid cell. We kept only those flux sites whose vegetation type consistently matched the dominant class of their corresponding 0.05° grid cell throughout all available years, resulting in a total of 190 representative sites selected from 316 available sites across diverse vegetation types and Whittaker biomes (Fig. 1, Table S1).

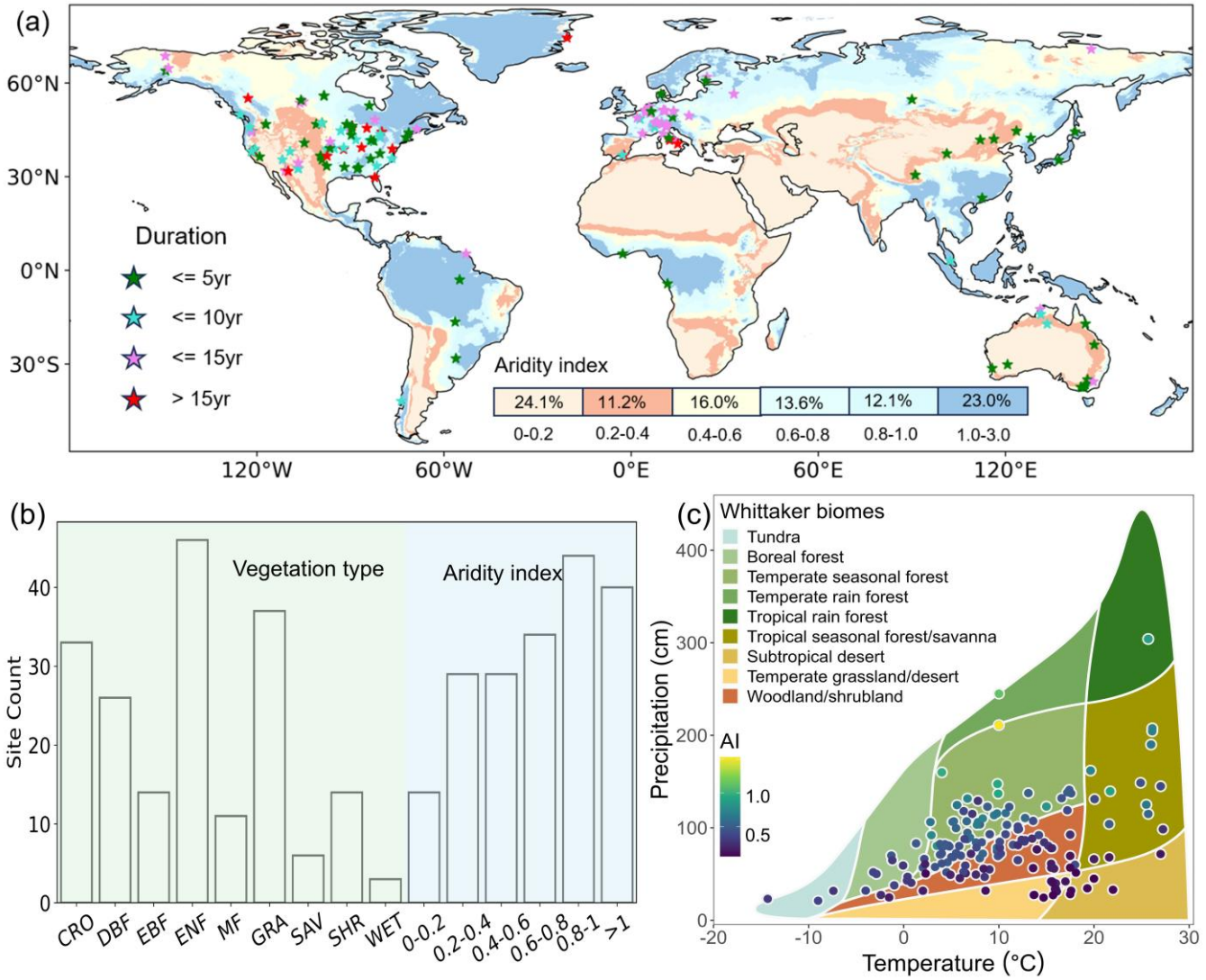


Figure 1. (a) Spatial distribution of the 190 eddy covariance flux sites used in this study. The background map shows the global aridity index, and the color bar indicates the proportion of land area within each aridity class. Sites with different observation durations are marked by star symbols in different colors. (b) Number of sites categorized by vegetation type and aridity gradient. (c) Distribution of sites across the Whittaker biome classification, where each site is positioned according to its mean annual temperature and precipitation. Vegetation type abbreviations are as follows: cropland (CRO), deciduous broadleaf forest (DBF), evergreen broadleaf forest (EBF), evergreen needleleaf forest (ENF), mixed forest (MF), grassland (GRA), savannas (SAV), shrubland (SHR) and wetland (WET).

To ensure data quality for model training and evaluation, we applied the following procedures to the tower-based GPP (GPP_NT_VUT): (1) removed negative values that are physiologically unrealistic; (2) retained only records with quality-control flags equal to 0 or 1; and (3) converted all timestamps to local solar time (LST) to remove phase shifts related to solar position and ensure physical consistency of diurnal variations (see Text S1 for details).

2.2 Global gridded datasets

2.2.1 Environmental variables

For climate forcing, we used the ERA5-Land reanalysis dataset (0.1°) from the European Centre for Medium-Range Weather Forecasts (ECMWF), which provides global hourly fields of incoming shortwave radiation (SW), air temperature (Ta), 0–100

cm soil water content (SWC), and dew point temperature (Table S2) (Munoz-Sabater et al., 2021). Based on 2 m air
 170 temperature and 2 m dew point temperature, we calculated hourly vapor pressure deficit (VPD) to quantify atmospheric dryness
 relevant for photosynthetic regulation (see Text S2 for details). The aridity index was obtained from the Global-AI_PET_v3
 dataset and defined as mean annual precipitation divided by potential evapotranspiration over the climatological baseline,
 thereby characterizing long-term water availability across ecosystems (Zomer et al., 2022). Regions with Aridity < 0.65 were
 classified as drylands, and all others as non-drylands (Koppa et al., 2024). To account for the influence of atmospheric CO₂
 175 concentration on photosynthesis, we used global 3-hourly CO₂ concentration data at $3^{\circ} \times 2^{\circ}$ from the NOAA CarbonTracker
 (<http://carbontracker.noaa.gov>) and applied time-weighted interpolation to generate continuous hourly CO₂ series (Chen et al.,
 2019). Given the distinct effects of diffuse (PARDF) and direct (PARDR) radiation on light use efficiency and GPP (Wang et
 al., 2023), we included the diffuse radiation fraction (DRF) as an additional predictor, computed from MERRA-2 hourly
 PARDF and PARDR (M2T1NXLFO; $0.5^{\circ} \times 0.625^{\circ}$) as $DRF = PARDF / (PARDF + PARDR)$.

180 2.2.2 Satellite datasets

We integrated multiple satellite datasets from MODIS platform. The MODIS MCD43C4 dataset provides daily Bidirectional
 Reflectance Distribution Function (BRDF)-adjusted global nadir surface reflectance at 0.05° resolution, which reduces the
 influence of viewing geometry and solar zenith angle. Using the red, near-infrared, blue, and shortwave infrared bands, we
 calculated enhanced vegetation index (EVI) and land surface water index (LSWI) to represent canopy greenness and surface
 185 moisture condition, respectively (see Text S3 for details) (Huete et al., 2002; Zeng et al., 2022). Additionally, we obtained the
 clumping index (CI) from the CAS-CI product and leaf area index (LAI) from the MODIS MOD15A2H Version 6.1 to further
 characterize the canopy structure (Wei et al., 2019). Here, we assumed that these vegetation structural parameters remain
 relatively stable throughout the diurnal cycle (Bodesheim et al., 2018; Leng et al., 2024).

Vegetation type information was derived from the MCD12Q1 Version 6.1 based on the International Geosphere-Biosphere
 190 Program (IGBP) classification at 500 m resolution. To align with our ecosystem modelling framework, the original IGBP
 classes were reclassified into a simplified scheme: forests (evergreen needleleaf forest, evergreen broadleaf forest, deciduous
 needleleaf forest, deciduous broadleaf forest, and mixed forest), shrublands (closed and open shrubland), savannas (woody
 savannas and savannas), and separate classes for grassland, cropland, and wetland. Detailed reclassification rules are listed in
 Table S1. To represent sub-grid landscape heterogeneity and reduce uncertainty from mixed pixels, we calculated the fractional
 195 coverage of each vegetation type within every 0.05° grid cell, denoting these variables as fraction of forest (FFO), shrubland
 (FSH), savannas (FSA), grassland (FGR), cropland (FCR), and wetland (FWE). Compared with using only the dominant class,
 this fractional representation provides a more nuanced description of vegetation composition and supports more detailed and
 accurate spatial upscaling across biomes. The benefit of this strategy can be found in Text S4 and Fig. S1 for more detail.

2.3 Hourly upscaled GPP products for comparison

200 To comprehensively evaluate the performance of our hourly GPP product, we compared it with two recently developed hourly GPP products that are also generated via machine-learning-based upscaling strategies. The first is FLUXCOM (Bodesheim et al., 2018), a pioneering upscaling product that provides global GPP at 0.5° resolution for 2001–2014; The second is X-BASE, a global 0.25° GPP product developed under the recent FLUXCOM-X framework covering 2001–2021 (Nelson et al., 2024). To our knowledge, these two products were upscaled from in-situ eddy covariance measurements and represent the efforts in
205 this field. All products were evaluated against site-level GPP, focusing on overall accuracy, representation of diurnal cycles, and spatiotemporal patterns.

3 Methodology

3.1 Feature selection

Prior to modeling, we performed feature selection to reduce the influence of redundant predictors (Fig. 2). Owing to its robust
210 screening strategy, Boruta is particularly suitable for high-dimensional and multi-source modelling tasks (Kursa and Rudnicki, 2010). The algorithm operates by creating shadow features to establish a baseline. Through iterative testing, predictors with lower importance than their corresponding shadow features are removed. We implemented this process using the BorutaPy package in Scikit-learn with 100 iterations to ensure result stability. As shown in Fig. S2, the clumping index and LAI were discarded, indicating that their information was likely redundantly captured by EVI. The remaining predictors were then
215 evaluated for multicollinearity using the variance inflation factor (VIF). The results showed that all retained predictors satisfied the collinearity criterion ($VIF < 10$) and were therefore used in subsequent modelling (Table S3). The final set of global gridded predictors used for modelling and upscaling is listed in Table S2.

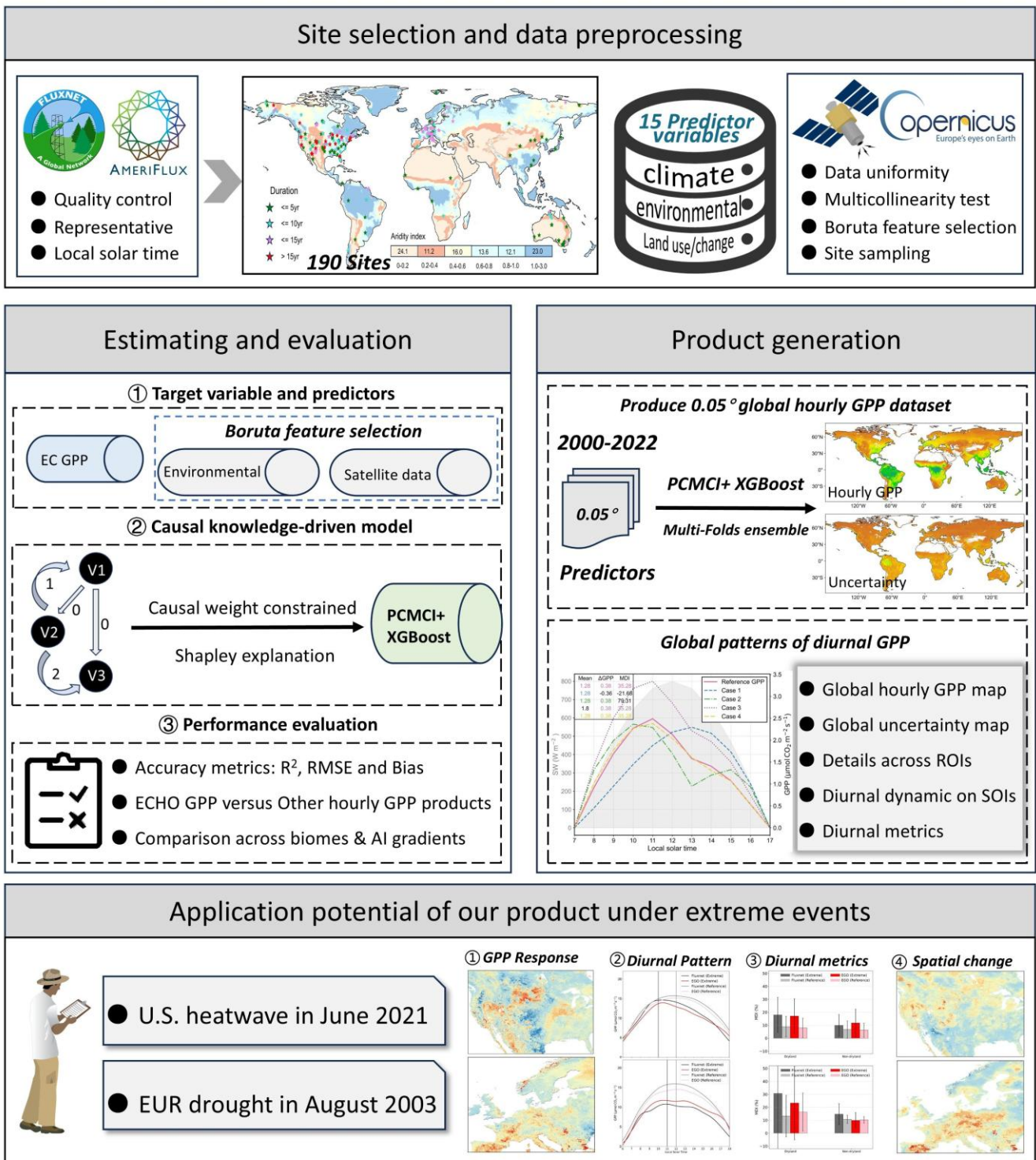


Figure 2. Workflow for generating the EGO (Eddy covariance site-based Global hOurly) GPP, encompassing data processing, model training, evaluation, and application assessment.

3.2 Predicting and upscaling

3.2.1 CKML-GPP model

We used a Causal Knowledge-driven Machine Learning model (CKML-GPP) to simulate hourly GPP, which integrates the powerful nonlinear regression capabilities of EXtreme Gradient Boosting (XGBoost) with the rigorous causal inference framework of PCMCI (Yuan et al., 2024; Zhao and Zhu, 2025). The PCMCI algorithm is particularly well-suited for earth

science applications as it effectively infers multivariate controls and time-lagged causal relationships in high-dimensional time series (Runge et al., 2023). It operates in two distinct stages: the PC algorithm (named after Peter Spirtes and Clark Glymour) and the Momentary Conditional Independence (MCI) test. First, the PC step iteratively filters the initial predictor pool to identify a reduced set of relevant necessary confounders for each variable. Then, the MCI test quantifies the causal strength and detects time-lagged dependencies between predictors and the target variable by conditioning on these identified parents to remove confounding effects. This two-step approach substantially enhances causal detection power by avoiding the statistical challenges of conditioning on high-dimensional variables.

In CKML-GPP, the causal structure identified by PCMCI serves as a physical constraint to guide the XGBoost training process. Specifically, causal weights derived from the MCI step are used to dynamically adjust the probability that each predictor is selected as a decision node in the tree structure. Predictors with stronger causal effects are assigned higher selection probabilities, so that the resulting model structure more closely reflects the dominant drivers of vegetation photosynthetic diurnal dynamics. To further enhance model performance and avoid subjective bias, we employed the Particle Swarm Optimization (PSO) algorithm to automatically search for the global optimum of hyperparameters (Ishaque and Salam, 2013). We also established three conventional machine learning models as baselines for performance comparison: EXtreme Gradient Boosting (XGBoost), Random Forest (RF), and Long Short-Term Memory (LSTM) (Fig. S3). These models all have strong capabilities for nonlinear regression, and have been widely applied in flux upscaling studies. In addition, to address potential uncertainties arising from grid-based input data during model training, we conducted additional experiments in which CKML-GPP was retrained using variables directly observed at the flux towers. This comparison enabled an assessment of model's sensitivity to input data quality. We also conducted an additional experiment by applying CKML-GPP to estimate daytime-partitioned GPP (GPP_DT) and comparing its performance with that obtained using GPP_NT (Fig. S4), to examine the robustness of model performance. Finally, we used the SHAP (SHapley Additive exPlanations) method to interpret the feature contributions of CKML-GPP, quantifying both the magnitude and direction of each environmental variable's influence on hourly GPP variation (Zhang et al., 2024).

3.2.2 Model training and evaluation

Before model training, all driving variables were harmonized in both spatial and temporal resolutions. Temporally, all input variables were converted to local solar time to ensure that the estimated GPP corresponded to the natural local diurnal cycle of vegetation. Spatially, all variables were resampled to a uniform 0.05° resolution. We adopted a 10-fold site-wise cross-validation strategy to train and evaluate the CKML-GPP model. Specifically, the available sites were randomly partitioned into 10 distinct subsets. In each iteration, nine subsets served as the training set, while the remaining one was used for testing. This procedure was rotated 10 times to ensure that every site functioned as an independent test sample exactly once, allowing us to compile a comprehensive validation dataset covering all sites (Fig. S5). Furthermore, to mitigate the impact of random

initialization and ensure result stability, we performed 20 independent runs with different random seeds for each fold. The final prediction for each test sample was derived from the ensemble average of these 20 runs.

For product comparison, we used only the predictions from the combined test folds, ensuring that each record used for evaluation was predicted by a CKML-GPP model that had not seen that sites during training, thereby providing a strictly out-of-sample validation dataset (Fig. S5). The validation dataset was subsequently used as the basis for a fair comparison between CKML-GPP and existing hourly GPP products, including FLUXCOM and X-BASE. For each flux tower record in this dataset, we extracted the corresponding grid-cell GPP values from EGO, FLUXCOM, and X-BASE at the same site location, month, and local solar hour, and compared them against observations. Because these products have different native spatial resolutions, we further harmonized the spatial resolution for product-level comparisons. Specifically, EGO was aggregated from its native 0.05° grid to 0.25° and 0.5°, respectively, matching the native spatial resolutions of X-BASE and FLUXCOM (Fig. S6). Model and products performance was systematically evaluated against tower GPP across vegetation types and aridity gradients. The evaluation metrics included the R^2 , RMSE, and bias. The detailed formulas for these metrics are given in Text S5.

3.2.3 Global mapping of hourly GPP

For each grid cell, the final GPP estimate was obtained by averaging the outputs from the 10-fold cross-validation models. For each fold, 20 independent runs with different random seeds were conducted, and the median prediction was taken as the fold output. This ensemble strategy, following previous studies, effectively reduces prediction uncertainty (Kang et al., 2025; Nathaniel et al., 2023; Zhao and Zhu, 2025). The resulting dataset is named EGO (Eddy covariance site-based Global hOurly) GPP. Considering computational efficiency and practical applicability, we generated global monthly-averaged hourly GPP from 2000 to 2022 at 0.05° resolution for local solar times from 06:00 to 18:00. Benefiting from the multi-fold training framework, model uncertainty (expressed as the standard deviation among 10-fold predictions) was also calculated (Fig. 2). In addition, we present globally aggregated multi-year diurnal GPP maps from EGO and two other products and further selected three regions of interest (ROI) for detailed analysis (including the Amazon, the central North America and Europe), enabling a comparative evaluation of spatial representational capability at both global and regional scales.

3.3 Diurnal metrics

To quantify the diurnal dynamics of vegetation photosynthesis, we used a set of metrics that describe the GPP diurnal curve from three complementary perspectives: absolute magnitude, diurnal asymmetry, and midday depression.

First, the absolute magnitude was defined as the mean GPP during the period from 6:00 to 18:00, reflecting the average intensity of daytime photosynthetic activity.

Second, diurnal asymmetry describes the difference in photosynthetic activity between morning and afternoon (Liu et al., 2024). This behavior is commonly quantified using metrics such as Δ GPP, diurnal centroid, and peak time. In this study, Δ GPP

was used as the primary asymmetry metric and was calculated as:

$$\Delta GPP = \frac{GPP_{AM} - GPP_{PM}}{GPP_{AM}} \times 100\% \quad (1)$$

where GPP_{AM} and GPP_{PM} denote the mean GPP during the morning (6:00–12:00) and afternoon (12:00–18:00), respectively.

The diurnal centroid and peak time were used as supplementary indicators (Li et al., 2023; Wilson et al., 2003), a centroid or peak time occurring before noon indicates higher GPP in the morning than in the afternoon.

Finally, we introduced the relative midday depression (RMD) to quantify the reduction in photosynthesis around midday (10:00–14:00), which reflects the physiological response of vegetation to stress. Based on the approach developed by (Zhu and Zhu, 2025), RMD quantified the normalized difference between the observed GPP curve and a hypothetical ideal GPP curve. Specifically, this ideal curve was constructed by fitting a parabolic curve to non-midday hour GPP values, thereby representing the expected diurnal trajectory in the absence of midday depression. The deviation between the observed GPP curve and this ideal curve was then used as a proxy for midday photosynthetic depression. RMD is calculated as:

$$RMD = \frac{\sum_{t=10}^{t=14} (GPP_i(t) - GPP_a(t))}{\sum_{t=10}^{t=14} GPP_a(t)} \times 100\% \quad (2)$$

where $GPP_i(t)$ and $GPP_a(t)$ are the actual and ideal GPP values at time t , respectively. A larger RMD indicates a greater deviation of actual GPP from the ideal curve and thus a stronger midday depression. To validate the sufficiency of these three metrics in capturing diurnal pattern, we conducted additional experiments, the details of which are presented in Text S6.

Because these diurnal metrics are standardized, they are directly comparable across ecosystems and provide a consistent basis for global-scale analysis. Accordingly, we produced global maps of these diurnal indicators to visualize their spatial patterns. To assess how well different hourly GPP products capture diurnal dynamics, we constructed a three-dimensional metric space with mean GPP, ΔGPP , and RMD as the three axes. The distance between each product's data points and the site-based reference points in this metric space was used to quantify its ability to reproduce the observed diurnal variation patterns.

3.4 Performance of EGO GPP under extreme events

To assess how well EGO GPP captures diurnal vegetation photosynthesis under extreme climate conditions across ecosystems, we analyzed two well-documented extremes: the severe drought that occurred in the central North America in June 2021 (Jiang et al., 2025) and the European heatwave in August 2003 (Garcia-Leon et al., 2021). For each case, we used flux tower observations with valid records for the corresponding months, covering the major ecosystem types in the central North America and Europe, respectively.

The evaluation consisted of two parts. To ensure a rigorous and independent assessment, we utilized the aggregated estimated GPP derived from the 10-fold cross-validation (i.e., the compilation of the 10 test sets), rather than the final upscaled product generated from the full dataset. Firstly, we quantified the accuracy of the estimated GPP during the extreme event. The

estimated hourly GPP were paired with corresponding tower-based GPP, and GPP anomalies during the event periods were calculated for both datasets. Specifically, the anomaly was calculated as $(GPP_{\text{extreme}} - GPP_{\text{reference}}) / GPP_{\text{reference}}$, where GPP_{extreme} represents the value during the specific event month, and $GPP_{\text{reference}}$ denotes the multi-year average for the same month excluding the event year. We then compared the R^2 , RMSE, and bias to evaluate the consistency between EGO GPP and the observation. Second, we examined the ability of EGO GPP to reproduce diurnal photosynthetic dynamics under extreme events. For each period, we extracted diurnal curves from both the flux tower data and EGO GPP at each site. Using the metrics defined in Section 3.4, we derived diurnal metrics for every site and grouped them into dryland and non-dryland classes. The capacity of EGO GPP to represent stress-induced changes was evaluated by calculating the absolute difference in metrics between the event and reference periods (e.g., $RMD_{\text{difference}} = RMD_{\text{extreme}} - RMD_{\text{reference}}$). These differences were then compared with tower-based results to verify whether the EGO accurately captured the shifts in diurnal patterns.

4 Results

4.1 Estimating and evaluation of hourly GPP

Comparative experiments among the three baseline models (Fig. S3) showed that XGBoost achieved the best performance (test set: $R^2 = 0.71$, $RMSE = 4.48 \mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$), followed by Random Forest, whereas LSTM performed relatively poorly. The proposed CKML-GPP model further improved prediction accuracy over XGBoost, increasing R^2 by 0.03 for the training set and by 0.05 for the testing set. These improvements indicate that the PCMCI-guided model not only enhances predictive skill to capture complex driving relationships, but also improved its generalization to unseen test samples. We further added a sensitivity experiment in which CKML-GPP was applied to daytime-partitioned GPP (GPP_{DT}) and compared with GPP_{NT} (Fig. S4). The results show that the model performance based on GPP_{DT} was generally consistent with that based on GPP_{NT} , suggesting the robustness of CKML-GPP across different partitioning methods. Based on the established CKML-GPP model, we generated the global hourly upscaling product, EGO GPP, and then compared with FLUXCOM and X-BASE against EC flux GPP (Fig. 3). To ensure a fair comparison, all products were compared under identical conditions using only the test set samples for EGO (Section 3.2.2). Under this setup, EGO achieved an R^2 of 0.76 and an RMSE of $4.17 \mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$, outperforming the other products which show R^2 values around 0.60 and RMSE value around $5.5 \mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$. Regarding bias, both FLUXCOM and X-BASE exhibited systematic underestimation of GPP, with substantial negative biases of -2.35 and -2.33 $\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$, respectively. In contrast, EGO effectively mitigated this underestimation issue, reducing the bias to merely -0.36 $\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$. This improvement is also reflected in the regression slope (Fig. 3a-c), where FLUXCOM and X-BASE remain around 0.60, whereas EGO reaches 0.78. As shown in Fig. 3d, EGO GPP aligned well with tower GPP across all quantiles, suggested excellent performance for both low and high GPP ranges. Moreover, we conducted a sensitivity experiment by resampling EGO to 0.25° and 0.5° , consistent with X-BASE and FLUXCOM, respectively (Fig. S6). Although

its performance declined slightly after resampling ($R^2 = 0.73$ at 0.25° and $R^2 = 0.71$ at 0.5°), EGO still outperformed both products, indicating robustness across spatial scales.

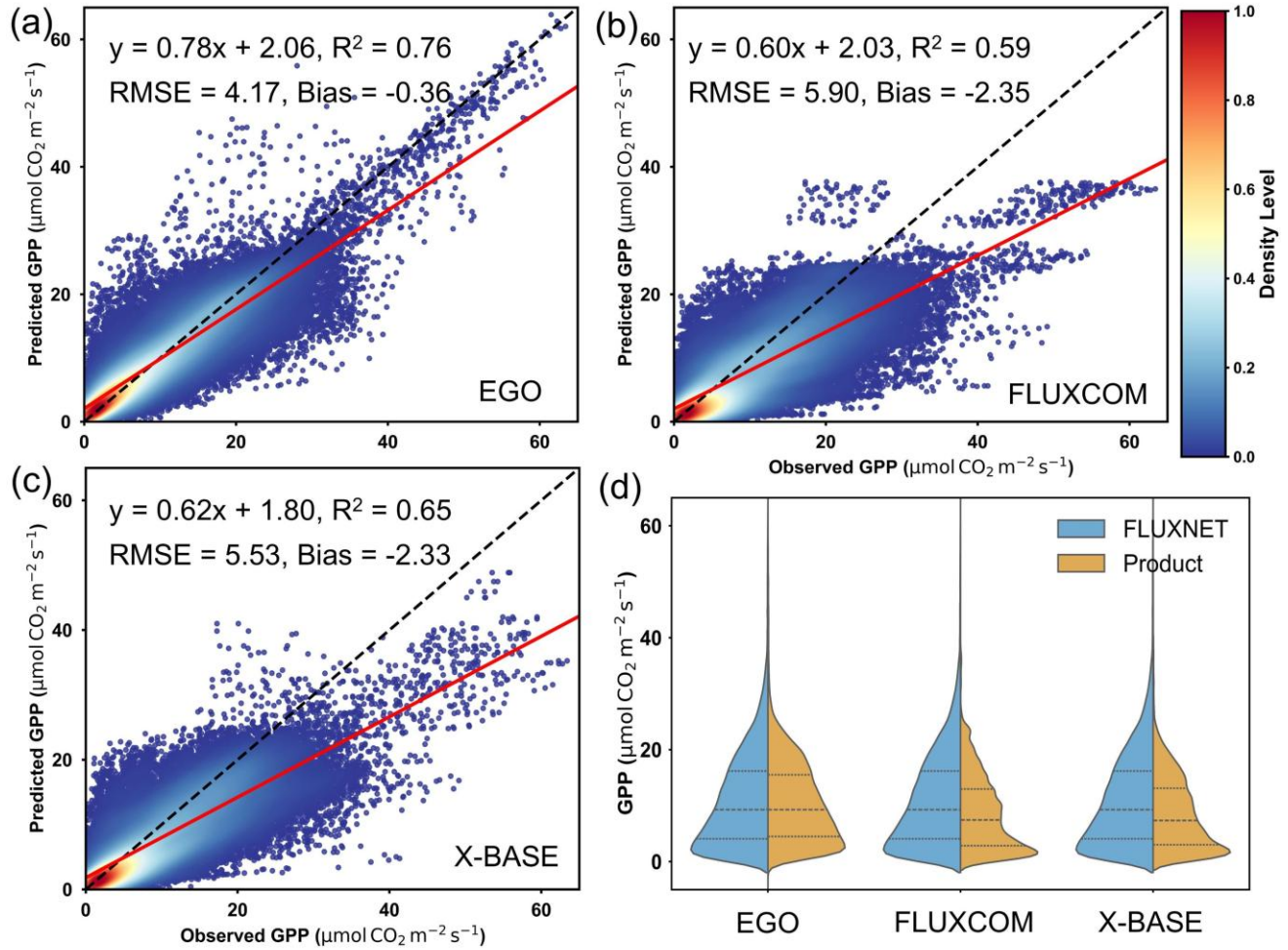


Figure 3. Comparison of the accuracy of EGO GPP and two existing hourly upscaling GPP products. (a-c) represent the predictive performance of EGO, FLUXCOM, and X-BASE, respectively. In each panel, the red solid line and black text indicate the regression line and corresponding performance metrics, while the black dashed line represents the 1:1 reference line. (d) The violin plots illustrate the distributions of tower GPP and products' GPP values—left for the tower and right for the product.

We then applied the SHAP method to interpret feature contributions in CKML-GPP. The results (Fig. 4) showed that SW was the dominant contribution (34.04%), consistent with its role as the primary energy source for vegetation photosynthesis, EVI (19.54%), Ta (10.03%), LSWI (9.32%), VPD (5.64%), and Aridity (5.33%) were identified as the next most influential drivers, together explaining over 80% of the model's output variance. Among these, SW, EVI, Ta, LSWI and Aridity exerted positive effects on GPP, whereas VPD showed a strong inhibitory effect. Regions dominated by forests and croplands tended to exhibit higher GPP, while areas with larger proportions of grasslands or shrublands showed lower GPP. SHAP interaction analysis (Fig. S7) revealed pronounced synergistic effects among SW, EVI, and LSWI, at a given level of EVI or LSWI, GPP increased substantially with increasing SW, indicating a synergistic coupling among energy supply, canopy structure, and surface moisture in regulating diurnal carbon uptake. In contrast, a strong negative interaction was observed between VPD and Aridity: the suppressive effect of VPD on GPP was more pronounced in drier environments (lower aridity index), implying that

ecosystems in drylands are more vulnerable to atmospheric drought.

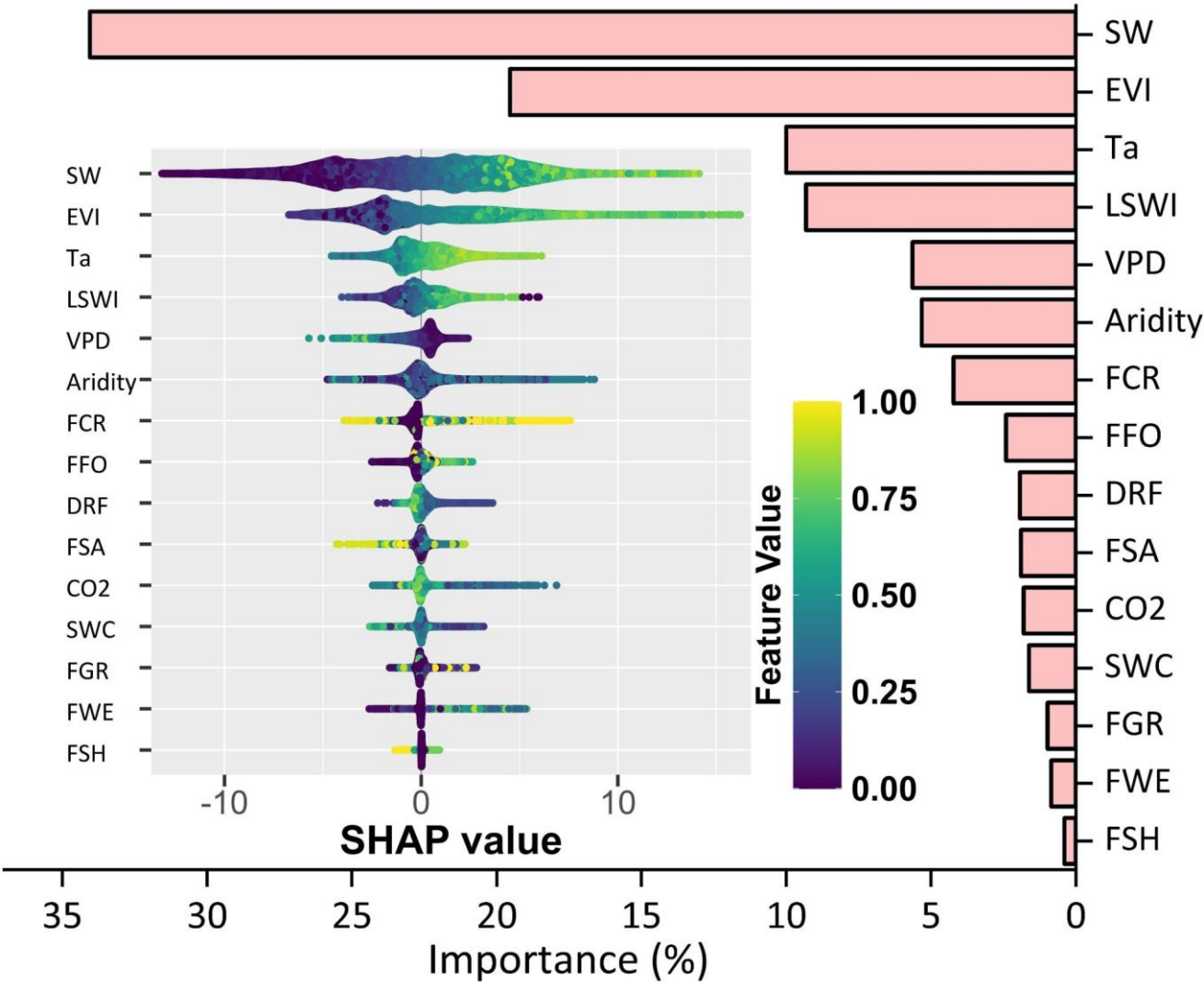


Figure 4. The importance of 15 drivers for hourly GPP modeling. From top to bottom, the importance decreased successively. The subgraph shows the contributions of each driver to hourly GPP. For instance, a high feature value can lead to a positive SHAP value (driver promotes GPP) or a negative SHAP value (driver inhibits GPP). Additionally, we reaffirm the abbreviations of each feature: incoming shortwave radiation (SW), enhanced vegetation index (EVI), air temperature (Ta), land surface water index (LSWI), vapor pressure deficit (VPD), aridity index (Aridity), diffuse radiation fraction (DRF), atmospheric CO₂ concentration (CO₂) and soil water content (SWC). FCR, FFO, FSA, FGR, FEW, and FSH denoting as the fraction of Cropland, Forest, Savannas, Grassland, Wetland and Shrubland in every 0.05° grid.

We further compared product accuracy across vegetation types and along the aridity gradient. As shown in Fig. 5, EGO GPP consistently outperformed the other products for nearly all vegetation types. For EBF, ENF, and GRA, the R^2 values of EGO GPP all exceeded 0.75. From Fig. 5b, the accuracy of FLUXCOM and X-BASE generally declined markedly with decreasing aridity index. In extremely arid zones (aridity index < 0.2), their R^2 values dropped sharply, indicating that these products struggle to represent photosynthesis in very dry environments. In contrast, EGO GPP maintained relatively high accuracy in these zones ($R^2 > 0.6$), and its performance showed weaker sensitivity to the aridity gradient. To explicitly assess the role of aridity index, we trained additional models with and without aridity index as a predictor (Fig. S8). Incorporating aridity index improved model performance for both the training and test sets, with particularly pronounced gains in drylands. In extremely arid zones, including aridity index increased R^2 by 0.13 for the training set and by 0.08 for the test set (Fig. S9). The largest

improvements were found in GRA, SAV, and SHR biomes, which are predominantly distributed in arid and semi-arid regions. These results indicate that aridity index provides complementary information on water availability that is not fully captured by other meteorological or vegetation variables, especially in water-limited ecosystems.

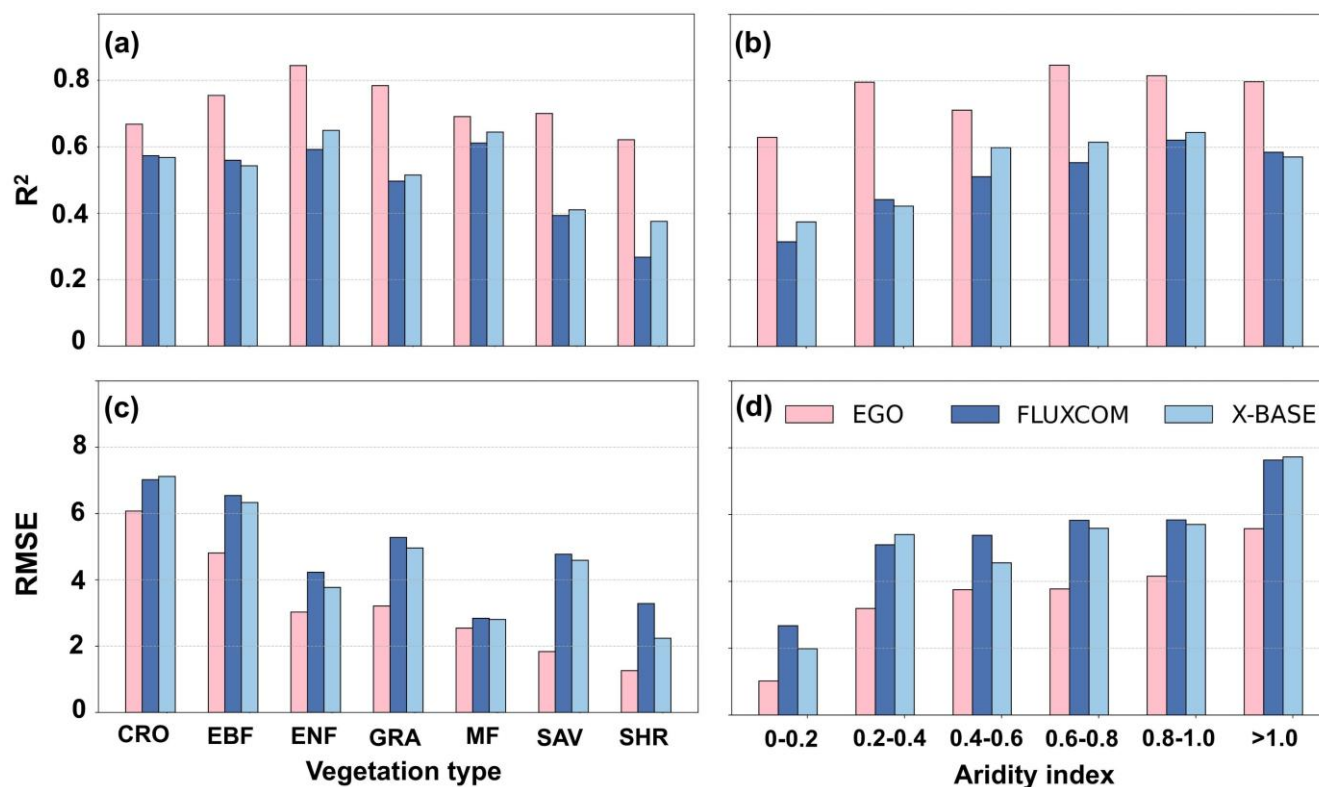


Figure 5. Accuracy comparison of hourly GPP products against tower GPP across different (a, c) vegetation types and (b, d) aridity gradients with R^2 shown in (a, b) and RMSE ($\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$) shown in (c, d).

4.2 Validation of diurnal GPP dynamic

To evaluate the capability of EGO in capturing diurnal photosynthetic variation, we aggregated tower GPP by local solar time within each vegetation type and extracted the corresponding GPP values from each product for comparison. As shown in Fig. 6, EGO showed a clear advantage in reproducing diurnal GPP curve across all vegetation types, whereas FLUXCOM and X-BASE generally underestimated GPP throughout the day. EGO GPP (red line) closely followed the diurnal patterns of tower-based GPP (black line), particularly for NF, CRO, and BF. This advantage extended to water-limited biomes like SAV and SHR (Fig. 6e and f). In these ecosystems, GPP is not only lower on average but also often peaks before 12:00 due to environmental stress, EGO was the product that mostly accurately captured this earlier peak, aligning closest with the reference curves, while the other products tended to produce lower value and inconsistent diurnal shapes that failed to reflect these patterns. As expected, comparisons at our six selected representative sites across biomes (Fig. S10) further showed that EGO most closely matched FLUXNET observations and effectively captured how diurnal GPP cycles varied across seasons.

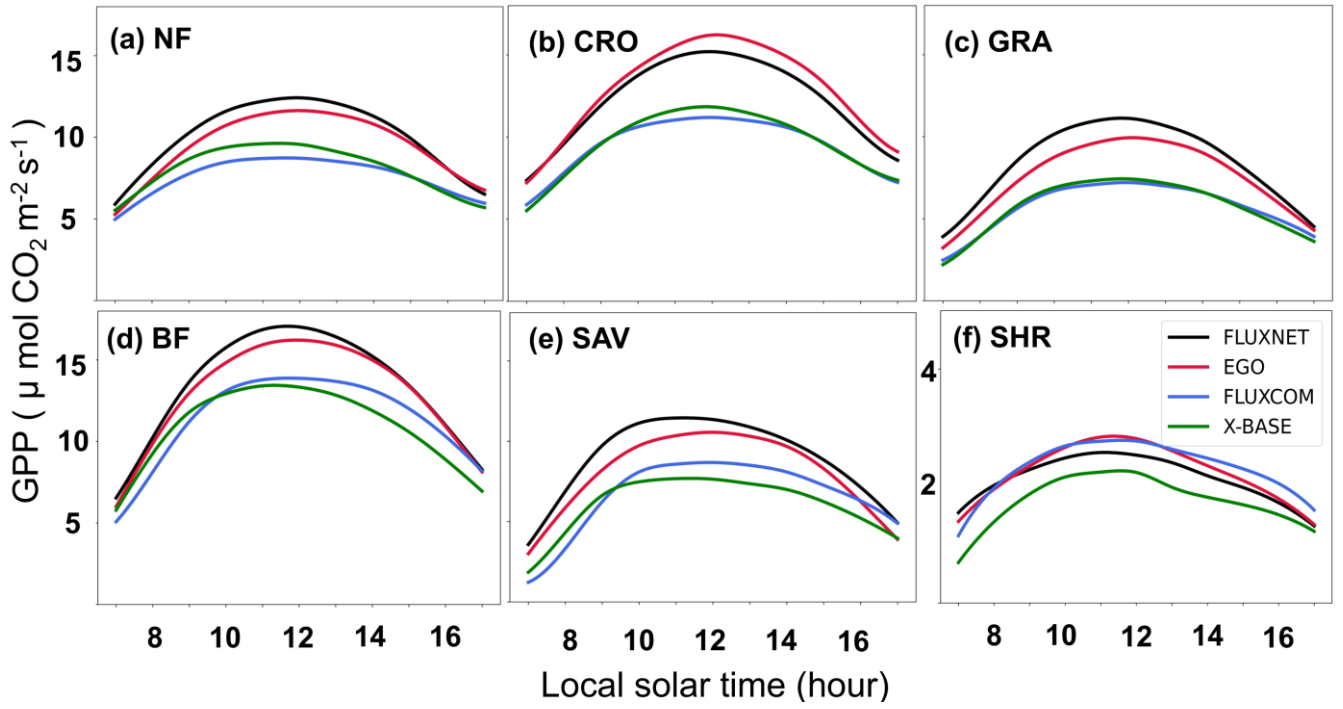


Figure 6. Mean diurnal GPP cycles for different vegetation types. Each curve represents the averaged diurnal GPP variation during growing seasons across all test sites within the same vegetation category. Observations and product estimates are shown in colors consistent with panel (f). For clarity, vegetation types were moderately aggregated: NF includes evergreen needleleaf forests (ENF) and deciduous needleleaf forests (DNF); BF includes evergreen broadleaf forests (EBF), deciduous broadleaf forests (DBF), and mixed forests (MF). CRO, GRA, SAV, and SHR was the abbreviation of Cropland, Grassland, Savannas, and Shrubland, respectively.

We further selected six sites with continuous 10-year records for each vegetation type and visualized their diurnal GPP dynamics using fingerprint plots (Fig. 7). These plots simultaneously display hourly variations of tower GPP, EGO GPP, and their differences for each month across multiple years, clearly illustrating the seasonal evolution and the daily progression of photosynthesis from dawn to dusk. For instance, a crop site (CH-Oe2, Fig. 7a) and a forest site (US-Ha1, Fig. 7b) exhibited persistently high photosynthetic activity throughout the daytime, maintaining substantial GPP values nearly year-round, whereas grass site such as US-SRG (Fig. 7d) and shrubland site such as US-Jo1 (Fig. 7e) showed lower GPP levels and pronounced seasonality. Across all sites, EGO GPP demonstrated high consistency with observations, with differences typically below $1 \mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$ at a given time. Importantly, no systematic overestimation or underestimation was apparent in either morning or afternoon periods, indicating its reliability in capturing the overall shape of diurnal GPP curves without introducing temporal bias.

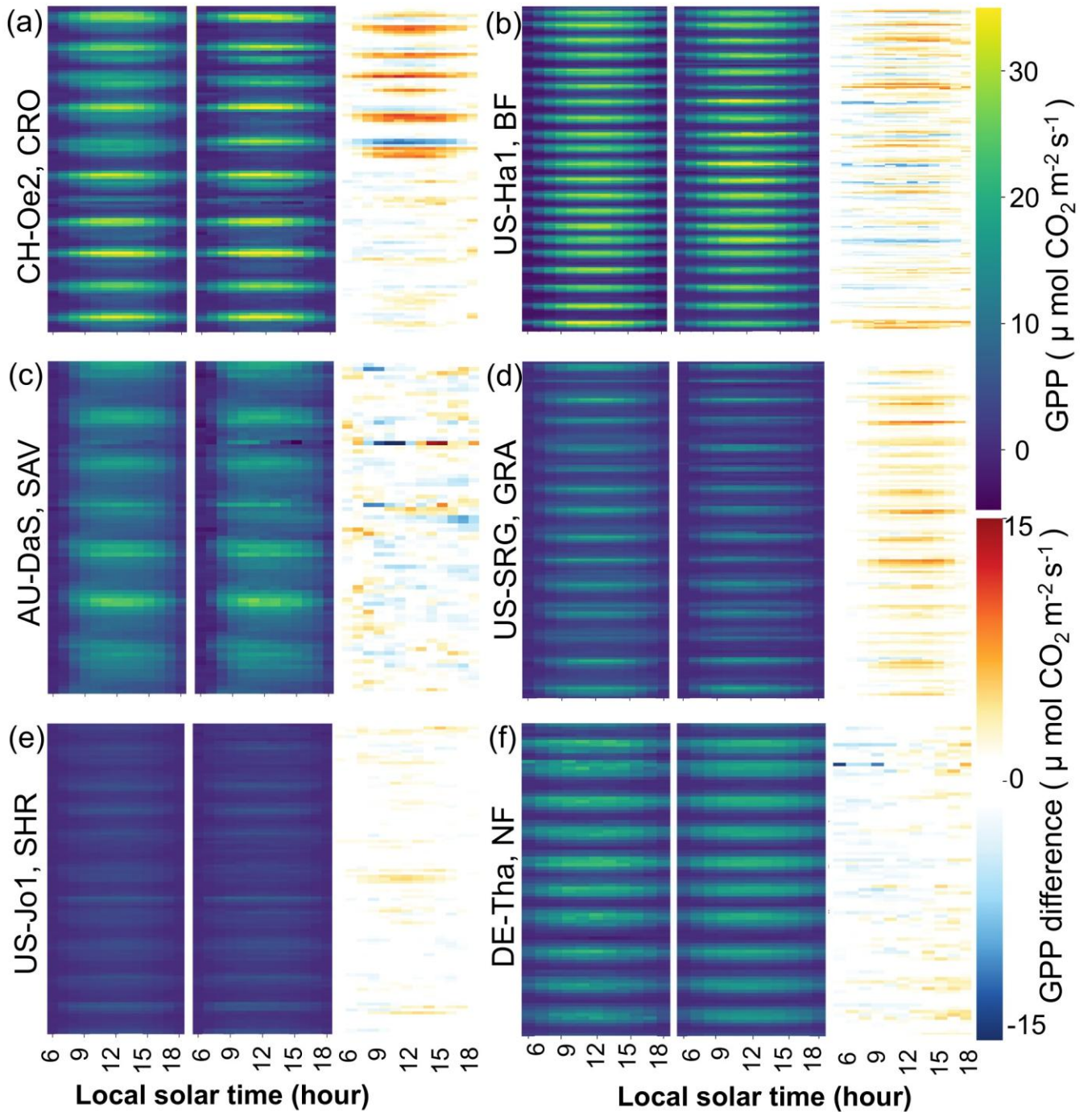


Figure 7. Fingerprint plots of hourly GPP for selected flux tower sites. (a-f) represented the site with the longest observation records across (a) CRO, (b) BF, (c) SAV, (d) GRA, (e) SHR and (f) NF. For each panel, the left plot and the middle plot represented observed and predicted hourly GPP while the right plot was the difference of the two. We manually set the color of legend when value less than 1 to white.

To systematically quantify diurnal GPP patterns, we conducted experiments reconstructing GPP curves by controlling different metric combinations (Text S6). We selected a representative diurnal curve from an arid site (US-Wkg, August 2013) as an example (pink curve in Fig. 8a), which exhibited clear midday depression and pronounced asymmetry ($\Delta\text{GPP} > 0$), with both centroid and peak time occurring before noon. When only the absolute magnitude was constrained (Case 1, blue curve), the reconstructed curve deviated substantially from the reference, with both peak and centroid times shifting toward the afternoon. Constraining both magnitude and asymmetry (Case 2, green curve), produced a more realistic curve overall but still failed to reproduce the midday depression. When asymmetry and midday depression were jointly constrained (Case 3, purple curve),

the curve shape closely matched the reference, although GPP magnitude was systematically overestimated. In contrast, when all three metrics were jointly constrained (Case 4, yellow curve), the simulated curve nearly overlapped with the reference. These experiments demonstrate that the combined use of mean GPP, Δ GPP and RMD can comprehensively characterize diurnal photosynthetic dynamic.

Under this framework, we constructed a three-dimensional metric space to evaluate how well different products captured diurnal GPP dynamics. In this space (Fig. 8b), a smaller distance between a product and the observed point indicated a more accurate representation of photosynthesis diurnal pattern. Across nearly all vegetation types, EGO GPP was closest to observations. Among the other products, X-BASE performed relatively well in NF and CRO, while FLUXCOM showed better performance in BF and GRA. Overall, EGO not only reproduces the absolute magnitude of GPP but also more accurately captures the diurnal shape of photosynthesis dynamics.

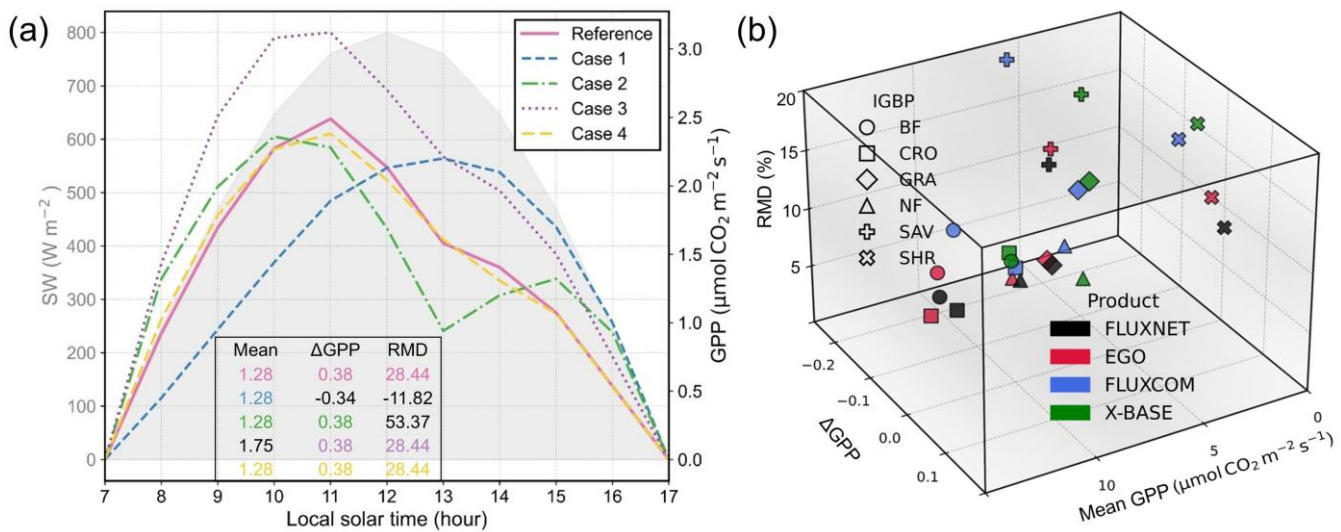


Figure 8. Diurnal GPP pattern evaluation based on diurnal metrics. (a) shows reference GPP and four controlled cases: (1) mean magnitude only, (2) magnitude and asymmetry, (3) asymmetry and midday depression, and (4) all three factors jointly controlled. For each case, a Gaussian-function-based curve generation method were used to produce 100 random diurnal GPP curves satisfying the control conditions, and their mean profiles were shown. (b) presents the performance of products in a three-dimensional metric space, where the X, Y, and Z axes represent Mean GPP (absolute magnitude), Δ GPP (asymmetry), and RMD (midday depression), respectively. Different vegetation types are marked by distinct symbols, and products are distinguished by colour. A smaller distance between a product and the observed point in this space indicates a closer match to the observed diurnal GPP dynamics.

4.3 Spatial pattern of global diurnal GPP

We first produced global maps to examine the spatial patterns of EGO GPP at different local solar time (Fig. 9 and Fig. S11). Photosynthesis commenced after sunrise when solar radiation became available. GPP increased throughout the morning (Figs. 9a-c) as light availability improved under favorable temperature and moisture conditions, peaked around noon (Figs. 9d-f), and declined in the afternoon as photosynthetic activity weakened. After sunset, GPP approached zero in the absence of sunlight (Figs. 9g-i). Spatially, regions such as the Amazon, central Africa, and Southeast Asia exhibited consistently high GPP, with midday values exceeding 25 μ mol CO₂ m⁻² s⁻¹ at noon. In contrast, high-latitude regions, the western United States, and Australia showed lower photosynthetic activity throughout the day, rarely surpassing 10 μ mol CO₂ m⁻² s⁻¹. Beyond these

450 general patterns, Fig. S12 reveals substantial seasonal variations in diurnal photosynthesis. During June–August, photosynthetic activity intensified across the Northern Hemisphere, with midday GPP exceeding $25 \mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$ in boreal and temperate forests. In December–February, the epicenter of global photosynthetic activity shifted southward, with enhanced photosynthesis in the Southern Hemisphere, particularly in the Amazon and southern Africa. The seasons transition reflects the gradual latitudinal migration of global photosynthesis belt driven by changing light availability. In terms of uncertainty (Fig. S13), the standard deviation of EGO GPP remains below $1 \mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$ across most regions and times, even in high-GPP areas.

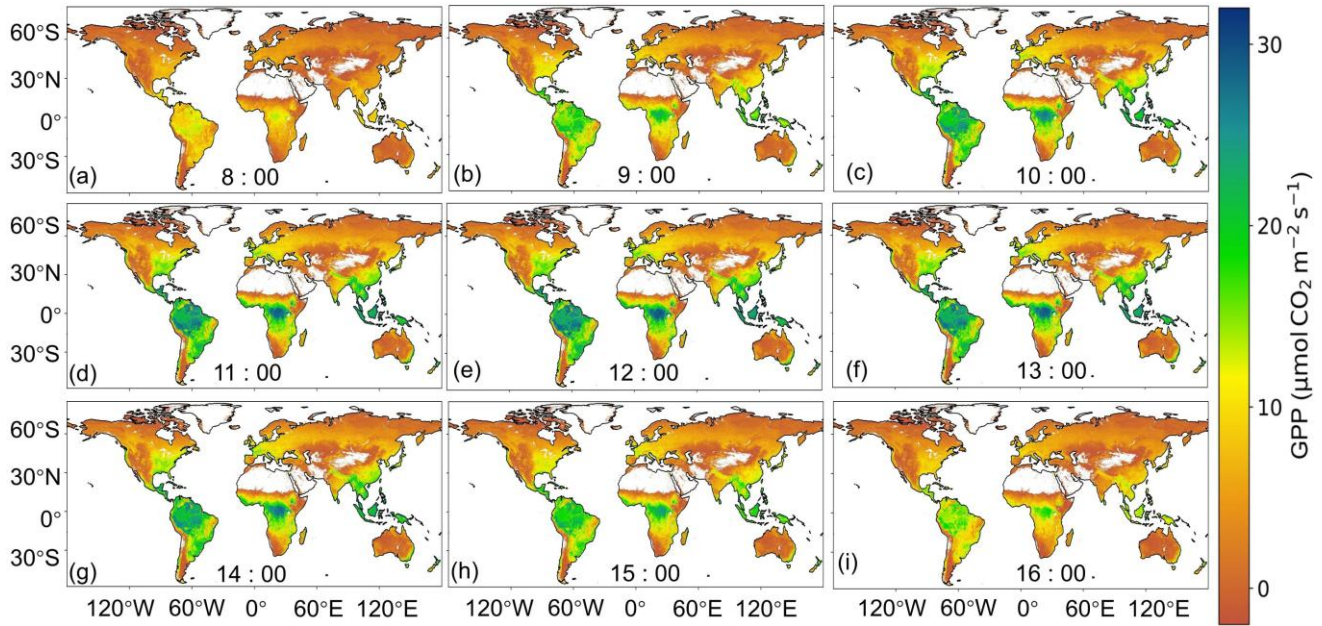


Figure 9. Global diurnal pattern of EGO GPP averaged over the growing seasons from 2000 to 2022, a-i represents the spatial distribution of hourly GPP at 1-hour intervals spanning from 08:00 to 16:00.

460 Within the selected ROIs, the Amazon represents a core region of strong photosynthetic activity, where EGO and the other products all captured persistently high GPP values ($\sim 15 \mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$) even in the late afternoon (Fig. 10e). Moreover, EGO delineates finer spatial variations within forest types and transition zones, whereas the other products appeared overly smoothed (Fig. 10c, h, and m). This enhanced spatial realism is attributed to the use of sub-grid fractional PFT cover instead of discrete coarse vegetation class labels, which better represents gradual transitions in land cover. Similar advantages in spatial detail are evident in the central North America (Fig. S14) and Europe (Fig. S15).

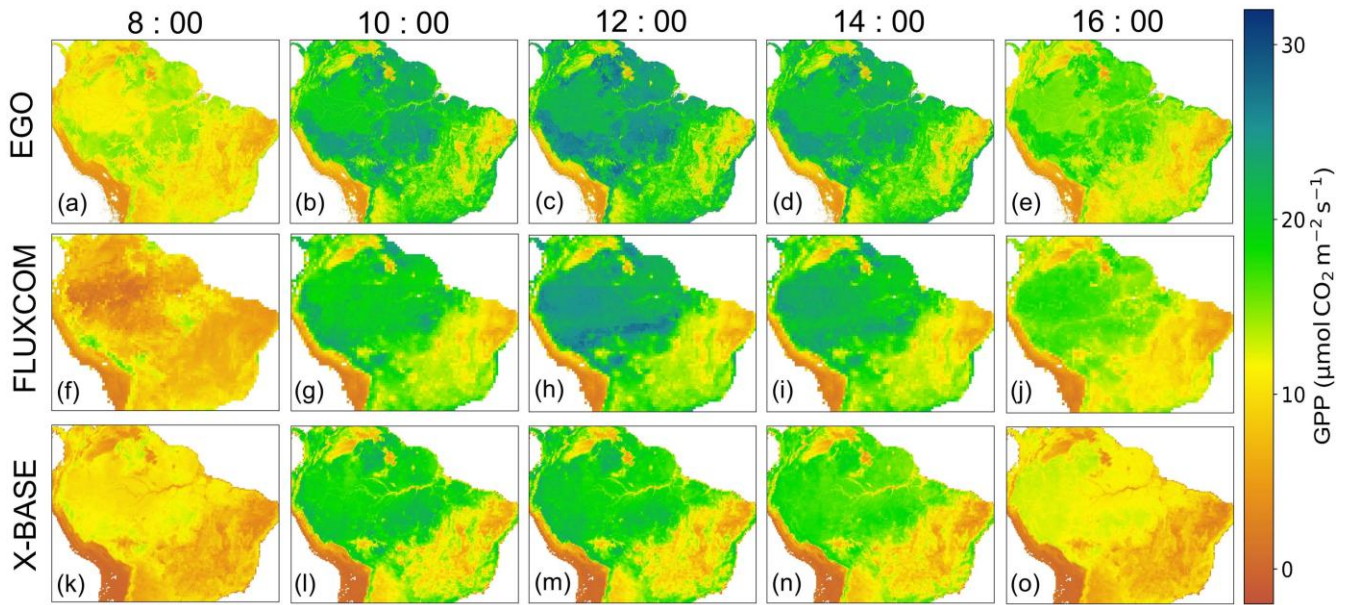


Figure 10. Detailed comparison of diurnal GPP among products in the Amazon. Columns 1-5 show GPP maps from 08:00 to 16:00 at 2 h intervals averaged over the growing seasons from 2000 to 2022, and rows 1-3 correspond to EGO, FLUXCOM, and X-BASE, respectively.

We then presented the multiyear growing-season averages of four diurnal metrics derived from EGO GPP including RMD, Δ GPP, centroid time, and peak time (Fig. 11). Together, these metrics reveal distinct regional characteristics of diurnal photosynthetic dynamics. High RMD values occur mainly in tropical and arid regions, particularly in tropical drylands such as the Somali Peninsula in East Africa, where RMD exceeded 30%. This indicates a pronounced midday depression of photosynthesis, strong physiological downregulation under intense radiation and severe water and heat stress. In contrast, high-latitude vegetation exhibited much weaker midday depression ($\text{RMD} < 10\%$) due to lower radiation and more favorable hydrothermal conditions. The spatial patterns of Δ GPP, centroid time, and peak time are strongly consistent. Globally, Δ GPP values are mostly negative, indicating that photosynthetic activity is generally stronger in the afternoon than in the morning. Positive Δ GPP values are concentrated in typical drylands such as the western United States, southern Africa, and Australia, where afternoon photosynthesis was strongly suppressed by water and heat stress. These regions also showed earlier centroid and peak times (before 12:00), associated with rapid morning increases and earlier declines in photosynthetic activity. Conversely, in high-latitude and tropical rainforest regions, Δ GPP is small or negative, and both centroid and peak time occur near or after noon, indicating that photosynthesis remains relatively active in the afternoon.

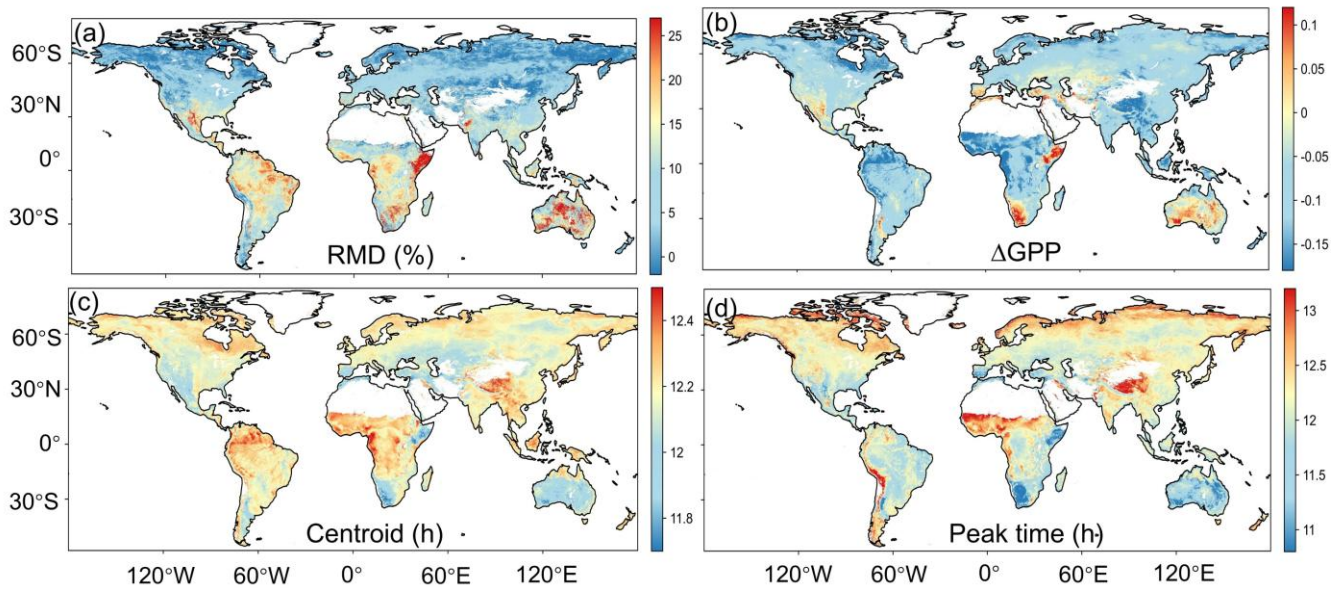


Figure 11. Global map of photosynthetic diurnal metrics derived from EGO GPP averaged over the growing seasons from 2000 to 2022. (a) RMD, (b) Δ GPP, (c) Centroid, and (d) Peak time.

4.4 Performance of EGO GPP in capturing the diurnal response of photosynthesis to extreme events

To further assess the performance of EGO GPP under extreme events, we examined two representative cases in the central North America and Europe and analyzed their impacts on diurnal vegetation photosynthesis. As shown in Fig. 12, vegetation in the northwestern U.S. experienced severe environmental stress in June 2021 relative to the multi-year average: soil moisture decreased by about 40%, while air temperature and VPD increased by approximately 30% and 50%, respectively. Against this backdrop, GPP across most of the U.S. declined markedly, particularly in the western and north-central U.S., where vegetation suffered the strongest stress and GPP losses, approached 50%. In both reference and extreme months, GPP showed a general pattern of lower values in the western U.S. and higher in the east (Fig. S16). We then evaluated EGO's performance using observations from 39 flux towers with valid records during extreme and normal June (Fig. S17a-c). EGO maintained robust performance during the extreme month ($R^2 = 0.69$), comparable to its accuracy in normal Junes ($R^2 = 0.80$). Importantly, EGO effectively captured the GPP anomalies induced by the drought, consistent with ground-based observations ($R^2 = 0.51$).

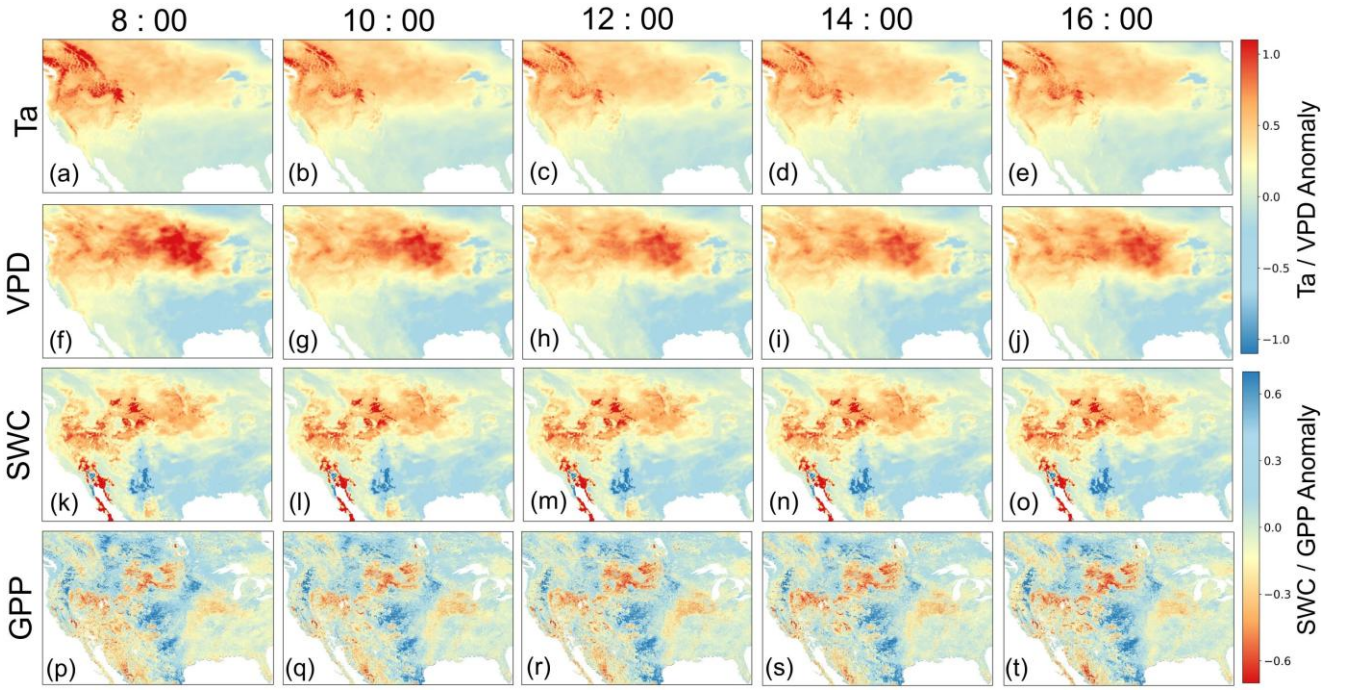


Figure 12. Spatial distribution of (a-e) Ta, (f-j) VPD, (k-o) SWC, and (p-t) GPP anomalies in the central North America during June 2021. For instance, $GPP\ Anomaly = (GPP_{2021} - GPP_{reference}) / GPP_{reference}$. $GPP_{reference}$ denotes the multi-year average for June excluding 2021.

To further examine diurnal responses, we aggregated observed and EGO GPP across dryland and non-dryland sites in the U.S. In drylands (Fig. 13a), intense water stress in June 2021 (black curve) led to a pronounced shift of the GPP peak, advancing by approximately two hours compared with reference years (gray curve). Consistently, RMD increased from 6.81% to 13.14%, and diurnal asymmetry strengthened (ΔGPP from -0.03 to 0.12). Non-dryland sites (Fig. 13b) showed more moderate changes: overall GPP decreased modestly, while RMD increased from 4.91% to 5.52%, and ΔGPP shifted from -0.04 to 0.02. Across both drylands and non-drylands, EGO GPP closely matched flux-tower observations. More importantly, EGO closely matched flux-tower observations, and successfully reproduced both the direction and magnitude of changes in key diurnal metrics under drought stress.

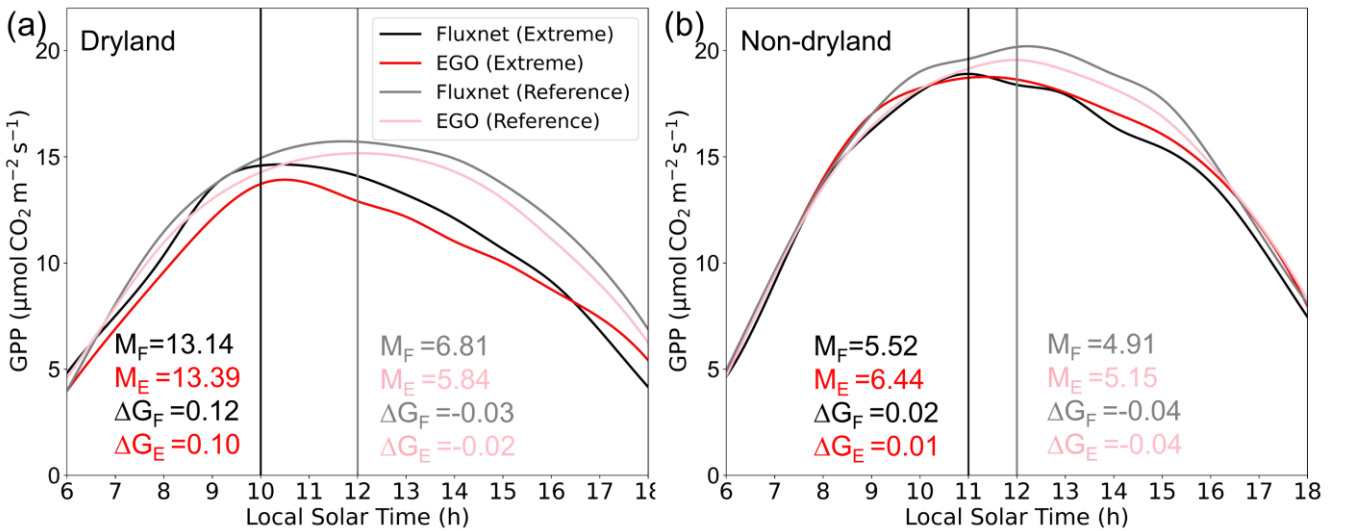


Figure 13. Mean diurnal GPP cycles aggregated for dryland (a) and non-dryland (b) sites in the U.S. Black and red lines denote average GPP cycles for June 2021, while gray and pink lines represent averaged years for June (Reference). The vertical line represents the peak

time. M and ΔGPP indicate RMD and ΔGPP ; F and E denote flux-tower observations and EGO GPP, respectively. Dark and light colors correspond to 2021 and reference-year metrics.

Spatial analyses (Fig. 14) further revealed systematic differences between dryland and non-dryland ecosystems across the U.S. The western U.S., characterized by extensive drylands, exhibited higher RMD and ΔGPP values alongside earlier centroid and peak times (before 12:00) compared to eastern U.S. Under the extreme drought event, these patterns intensified, particularly in the severely affected northwestern U.S., where RMD increased by about 15%, ΔGPP rose by roughly 0.1, the diurnal centroid advanced by nearly 0.2 hours, and peak time shifted earlier by 1 to 2 hours. Strengthening of both midday depression and diurnal asymmetry was more pronounced in drylands than in non-drylands. Diurnal metrics derived from EGO and tower-based GPP (Fig. S18), showed strong agreement for both dryland and non-dryland.

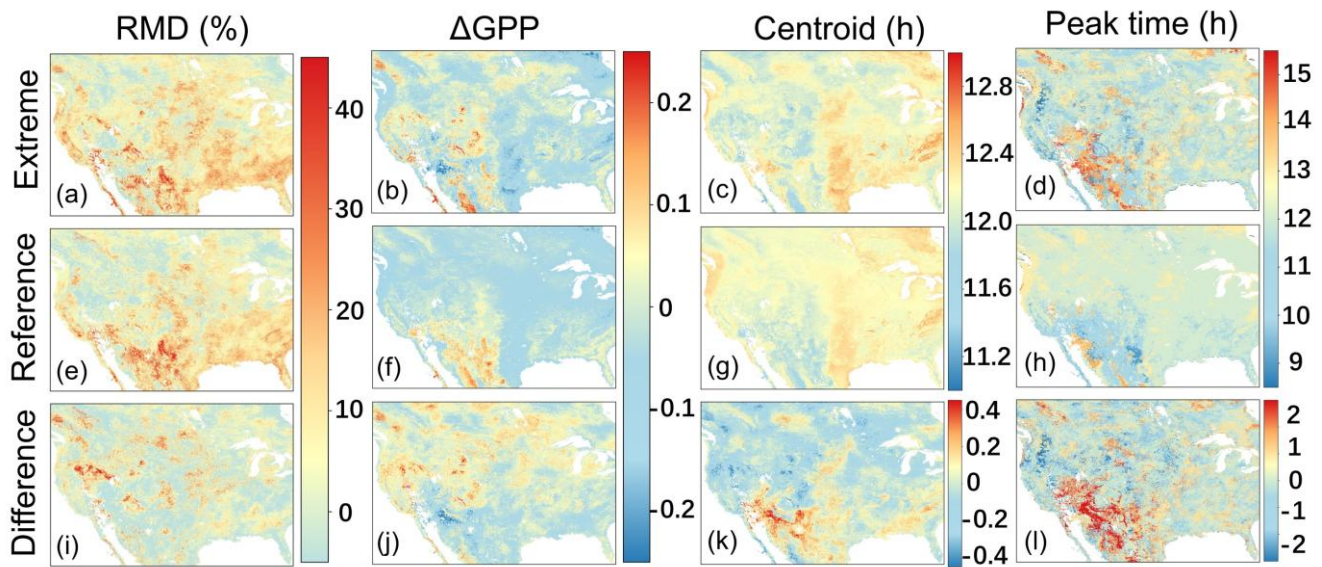


Figure 14. Spatial pattern of the diurnal metrics in the central North America during extreme (a-d) and averaged reference June (e-h), with (i-l) showing their differences (extreme minus reference).

A similar analysis for the August 2003 European heatwave yielded consistent conclusions. The heatwave caused temperature increases of up to 40% and strongly reduced GPP across all hours, with anomalies reaching about 45% (Fig. S20 and Fig. S21). The heatwave advanced GPP diurnal peaks by about one hour earlier across Europe, with more pronounced changes in drylands (Fig. S21): RMD increased from 4.51% to 9.67%, and ΔGPP shifted from -0.06 to 0.02. Non-drylands showed gentler responses, with limited changes in morning GPP changes but notable midday depression (RMD up to 8.33%). Although ΔGPP increased across most regions, diurnal asymmetry remained weak outside Mediterranean drylands (Fig. S22), indicating comparatively higher thermal resistance in non-dryland ecosystems. EGO again showed reliable performance during this event, capturing GPP anomalies ($R^2 = 0.40$) and associated changes in diurnal metric (Fig. S17d-f & Fig. S23). Taken together, these findings indicate that EGO can reliably characterize the diurnal GPP cycle across a range of hydroclimatic conditions, including both normal and extreme years and both dryland and non-dryland ecosystems, providing a useful dataset for future studies of sub-daily vegetation carbon dynamics.

5 Discussion

5.1 Advantages of EGO GPP

535 In this study, we developed EGO, a global hourly GPP product generated using a causal knowledge-driven machine learning framework that integrates the PCMCI causal discovery algorithm with an XGBoost model. EGO demonstrated strong performance across multiple dimensions: it achieved high accuracy in simulating tower-based hourly GPP (Section 4.1) and reconstructing diurnal GPP curves (Section 4.2), reliably characterized diurnal GPP dynamic at the global scale (Section 4.3), and accurately captured photosynthetic diurnal responses under extreme drought and heatwave events (Section 4.4). The robust

540 performance of EGO GPP stems from several advances in both model architecture and input variables. Firstly, EGO employs a semi-empirical modelling framework based on PCMCI-XGBoost model, enabling strong nonlinear representation while explicitly accounting for causal effect of predictor variables on GPP (Garcia-Leon et al., 2021). Identifying robust causal structures is critical for data-driven machine learning, as the magnitude of hourly GPP response to environmental changes strongly depends on the strength of specific causal effects rather than mere statistical correlations

545 (Galytska et al., 2023; Krich et al., 2020; Yuan et al., 2022). It has been successfully demonstrated in other complex ecological tasks, such as estimating wetland methane emissions (Yuan et al., 2024) and ecosystem respiration (Zhao et al., 2025; Zhao and Zhu, 2025). The superior performance observed in our evaluations also confirms the effectiveness of this causal modelling framework. Secondly, EGO integrates multidimensional predictors encompassing vegetation, radiation, both long-term and short-term water availability, and land-use dynamics, thereby allowing the model to fully learn the drivers of the diurnal GPP

550 cycle (Anav et al., 2015; Hou et al., 2022; Pei et al., 2025; Wang et al., 2023). Unlike previous products that primarily relied on short-term water variability predictors, EGO explicitly introduced the aridity index as a proxy for long-term climatic water balance which plays a pivotal role in regulating the diurnal hysteresis (Li et al., 2023; Liu et al., 2024). As shown in Fig. S9, incorporating aridity index as a predictor substantially improved hourly GPP simulation accuracy especially in drylands. This improvement directly mitigates the uncertainties of existing products in arid regions. Thirdly, we used sub-pixel vegetation

555 endmember abundance data rather than discrete vegetation type as model inputs. Traditional machine learning upscaling often assigns a single dominant vegetation class to each pixel, which neglects surface heterogeneity and introduces mixed-pixel bias (Bodesheim et al., 2018; Nelson et al., 2024). By contrast, the endmember abundances enable EGO to resolve continuous transitions among vegetation types and capture detailed local variations in photosynthesis (Qin et al., 2023). Finally, EGO adopted a 10-fold cross-validation ensemble strategy, where predictions from all folds were averaged to produce the final GPP

560 output. This ensemble integration not only stabilized the learning process against random sample partitioning but also improved generalization by aggregating information learned from diverse training subsets (Han et al., 2025; Kang et al., 2025). Consequently, the ensemble output demonstrated higher accuracy than any single-fold model and reduced the influence of potential overfitting. To our knowledge, EGO represents the highest spatial resolution (0.05°) global hourly GPP product

currently available, may extends the potential applicability for addressing localized ecological questions and refining global carbon budget assessments. Together, these advances in modelling strategy and data integration underpin the strong performance of EGO GPP and its capability to reproduce sub-daily vegetation carbon dynamics across biomes and climatic conditions.

5.2 Implications for future research

We developed quantitative metrics to characterize the morphology of GPP diurnal cycles, describing the curves in terms of absolute magnitude, asymmetry, and midday depression. Beyond providing site-scale diagnostics, we mapped the global distributions of these metrics and analyzed their variations under extreme drought and heatwave events, thereby offering a holistic perspective for assessing how vegetation photosynthesis responds to environmental perturbations. This framework offers a new analytical perspective for evaluating hourly GPP products, shifting the focus beyond traditional accuracy performance to diurnal dynamics.

Previous studies on diurnal photosynthetic dynamics have mostly been confined to regional or site scales (Lin et al., 2019; Zhu and Zhu, 2025). Our earlier study reported that the 2020 U.S. heatwave substantially altered diurnal GPP patterns especially in western dryland ecosystems, causing widespread afternoon depression and earlier diurnal centroids (Li et al., 2023). Zhang et al. (2023a) used OCO-3 and tower observations to reveal distinct morning-afternoon responses of Amazon forests to atmospheric warming and drying, where enhanced morning photosynthesis partially compensated for afternoon declines driven by high VPD. Xiao et al. (2021) combined Himawari-8 AHI with tower observations to demonstrate substantial afternoon GPP reductions during Australian heatwaves. These findings collectively highlight that vegetation can rapidly adjust to short-term environmental stresses through physiological processes such as stomatal regulation and photoprotective mechanisms which cannot be adequately captured by traditional daily or monthly GPP data (Novick et al., 2024; Xiao et al., 2025). With the increase in the frequency of extreme climate events, midday and afternoon depression of photosynthesis may intensify globally, underscoring the need for high-resolution GPP products capable of resolving these fine-scale dynamics (Li et al., 2023; Zhang et al., 2023c). Our systematic evaluation confirms EGO's capability in this regard. During the two representative extreme events in this study, EGO accurately captured stress-induced changes in diurnal metrics, including widespread GPP reductions, earlier peaks and centroids, and intensified asymmetry and midday depression.

Given these strengths, EGO GPP holds strong potential as a reliable data source for investigating global diurnal photosynthesis and exploring ecosystem dynamics under extreme stresses in future research. It should be noted that the dominant controls on GPP may vary with temporal aggregation. For example, soil moisture effects can become more important at longer time scales because of ecosystem water-memory effects, whereas temperature may play a stronger role in regulating annual-scale carbon uptake (Green et al., 2019; Jung et al., 2017). Here, EGO provides a useful opportunity for future studies to examine how the relative controls of radiation, temperature, and soil moisture shift from hourly to seasonal and annual time scales. Moreover,

595 EGO can serve as a valuable benchmark for Earth system models, supporting the development and evaluation of next-generation carbon cycle simulations at hourly time steps (Boucher et al., 2020; Liu et al., 2024; Seferian et al., 2019; Voldoire et al., 2019). We will continue to update and distribute EGO to facilitate advanced understanding of global vegetation dynamics in a changing world.

5.3 Uncertainties and limitations

600 Although EGO demonstrated robust performance, several limitations remain. Due to the uneven spatial distribution of global flux sites, most observations were concentrated in Europe and America (Fig. 1). As a result, the model is trained primarily on these regions, which may introduce bias at the global scale (Bodesheim et al., 2018; Nelson et al., 2024). While this is a prevalent issue in current studies, we anticipate that these uncertainties will be progressively alleviated by the continuous expansion of flux observation networks and strengthened international collaboration on data sharing (Xiao et al., 2025).

605 Another source of uncertainty arises from the fact that tower-based GPP is not directly measured but inferred from net ecosystem exchange through flux partitioning. Different partitioning approaches may introduce some uncertainty in estimated GPP and its diurnal patterns, as they rely on different assumptions about ecosystem respiration (Keenan et al., 2019; Sadegh et al., 2026). Moreover, we used MERRA-2 ($0.5^\circ \times 0.625^\circ$) and CarbonTracker ($3^\circ \times 2^\circ$) datasets to represent the effects of diffuse radiation fraction and atmospheric CO_2 concentration on diurnal GPP dynamics. Their spatial resolutions are coarser

610 than the EGO's 0.05° grid, some spatial detail may have been smoothed, especially in heterogeneous landscapes. Also, the intrinsic uncertainties associated with these reanalysis products may propagate into the model, ultimately affecting GPP estimating accuracy (Wang, 2026). Nevertheless, to our knowledge, these datasets were currently the good available sources that provide hourly variable, thus remain a reasonable compromise that balance data quality and feasibility. In addition, potential uncertainties may arise in mountainous regions. In complex terrain, topographic effects on solar radiation and satellite

615 observation geometry are difficult to fully correct, potentially impacting model performance (Cao et al., 2025; Hao et al., 2022). Since we used MCD12Q1 product, the model cannot capture GPP variations caused by intra-annual land use transitions (e.g., seasonal deforestation or crop rotation) that occur within a single year. Finally, limited by computational resources and data processing efficiency, the released EGO GPP was currently provided as monthly-averaged hourly data. Despite this, EGO is sufficient to support a wide range of studies focusing on diurnal photosynthesis dynamics. Looking ahead, our roadmap

620 includes leveraging advanced cloud computing to produce a daily-hourly product, which will significantly enhance the capability to resolve short-term ecosystem processes.

6 Conclusion

We developed a global hourly GPP product (EGO GPP) with 0.05° spatial resolution from 2000 to 2022, based on a causal knowledge-driven machine learning model. By integrating multi-dimensional predictors including meteorological variables,

625 vegetation properties, and indicators of both short-term and long-term water availability, EGO GPP effectively captures diurnal
vegetation photosynthetic processes. We systematically evaluated the product's performance through three aspects: overall
accuracy, representation of diurnal cycles, and spatiotemporal patterns. Results confirmed that EGO GPP exhibits robust
capabilities across all these dimensions. Furthermore, through case studies of two extreme climate events, we demonstrated
630 EGO's ability to reliably capture drought- and heatwave-induced changes in diurnal photosynthesis. In summary, EGO GPP
provides a reliable data foundation for advancing our understanding of global diurnal vegetation photosynthesis and its
complex interactions with the environment.

Data availability and code availability

EGO GPP and related codes is publicly available on the Zenodo platform through <https://doi.org/10.5281/zenodo.18253238>
(Liu et al., 2026). It has a spatial resolution of 0.05° and covers the period 2000–2022 with monthly-averaged GPP for each
635 hour between 6:00 to 18:00 of local solar time. It is important to note that, like other machine learning-based GPP products,
EGO may occasionally yield slightly negative GPP estimates, particularly under very low light conditions. Rather than
truncating these values, we retained them in the published dataset to avoid introducing systematic bias. Users can easily apply
a zero-threshold filter based on their specific application needs. The hourly GPP was stored in NetCDF4 format and their units
consistent with FLUXNET ($\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$). Moreover, users must apply a conversion factor of 0.001 to retrieve the actual
640 values. To facilitate user accessibility and interoperability, we also provided a Python script for converting NetCDF4 files to
GeoTIFF format.

Author contributions

Xing Li and Xi Liu designed the experiments, and Xi Liu carried them out. Xi Liu, Yanan Zhou and Cenliang Zhao developed
the model code and performed the simulations. Xi Liu prepared the original draft and all the co-authors review and editing
645 them.

Competing interests

At least one of the (co-)authors is a member of the editorial board of Earth System Science Data. The authors have no other
competing interests to declare.

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