



# RRBF-KMA: High-resolution radar–gauge merged precipitation dataset for South Korea (2016–2024)

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10 **Abstract.** This study presents a long-term, high-resolution precipitation dataset over South Korea generated by merging nationwide composite radar reflectivity with dense rain gauge observations from the Korea Meteorological Administration (KMA). The dataset provides precipitation at 10-minute temporal resolution and 0.5 km spatial resolution on a regular grid of  $2305 \times 2881$  pixels, covering the period from 2016 to 2024.

15 Rain gauge observations, originally recorded at 1-minute intervals, are quality-controlled and aggregated to 10-minute accumulations prior to merging. Radar inputs are obtained from the nationwide composite reflectivity product provided by KMA. To ensure temporal consistency in the merged precipitation fields, a radar–gauge bias correction scheme is applied in which scaling factors are updated at 10-minute intervals during precipitation events and constrained relative to preceding time steps. This approach reduces spurious temporal variability while maintaining sensitivity to evolving precipitation systems.

20 Residual differences between bias-corrected radar estimates and gauge observations are interpolated using a Residual Radial Basis Function (RRBF) method. The method models spatially structured residuals to preserve fine-scale radar-derived variability while incorporating gauge-based corrections. The entire merging procedure is computationally efficient, requiring approximately one minute per 10-minute analysis, which supports near-real-time implementation.

25 The dataset is evaluated through comparison with conventional geostatistical interpolation methods, with particular emphasis on bias characteristics and spatial coherence. The resulting product provides temporally continuous and spatially consistent precipitation fields suitable for hydrological applications, extreme rainfall analysis, and urban flood forecasting. The dataset, together with detailed documentation of the generation and validation procedures, is publicly available for research and operational use.

## 1. Introduction

30 High-resolution precipitation datasets are essential for meteorological and hydrological applications, including flood forecasting, hydrological modeling, and urban water management (Kidd and Huffman, 2011; Ochoa-Rodriguez et al., 2019).



In particular, sub-hourly and kilometer-scale rainfall estimates are required to resolve localized heavy rainfall events that can trigger flash floods and produce severe impacts in highly urbanized regions.

Several long-term radar-based precipitation datasets have been developed at national and continental scales, including  
35 RADKLIM over Germany (Winterrath et al., 2018), the UK radar composite product (Lewis et al., 2018), the European  
OPERA composites (Huuskonen et al., 2014), and EURADCLIM (Overeem et al., 2023). These datasets illustrate current  
practices for generating long-term radar-derived precipitation products, with emphasis on harmonized gauge quality control,  
bias correction, and temporally consistent radar–gauge merging to ensure homogeneity in gridded archives.

South Korea is characterized by complex terrain and frequent summer convective systems associated with the East Asian  
40 monsoon, resulting in highly variable precipitation at short temporal scales. These conditions require precipitation datasets  
with high spatial and temporal resolution to adequately represent localized heavy rainfall. Recent field campaigns, such as  
ICE-POP 2018 in South Korea (e.g., Gehring et al., 2021), have provided detailed observations of precipitation microphysics  
and highlighted the challenges associated with radar-based precipitation estimation in complex terrain and mixed-phase  
conditions.

45 Rain gauges provide accurate point measurements but are spatially limited (Habib et al., 2001). Weather radar offers broad  
spatial coverage and high temporal resolution but is affected by systematic biases, including attenuation, bright-band effects,  
and calibration uncertainties (Ciach and Krajewski, 1999; Berne and Krajewski, 2013; Bellon et al., 2005; Kwon et al., 2015;  
Lee and Zawadzki, 2005, 2006). Consequently, radar–gauge merging has become a widely adopted approach for quantitative  
precipitation estimation (Krajewski and Smith, 2002; Villarini and Krajewski, 2010).

50 Merging techniques range from simple mean field bias adjustment to geostatistical approaches such as kriging with external  
drift (Seo, 1998; Haberlandt, 2007; Jewell and Gaussiat, 2015). While these methods effectively reduce systematic radar  
errors, bias correction applied independently at each time step can produce temporally inconsistent scaling factors,  
particularly in rapidly evolving precipitation systems at sub-hourly resolution (Villarini and Krajewski, 2010; Goudenhoofd  
and Delobbe, 2009; Thorndahl et al., 2014; Ochoa-Rodriguez et al., 2019). Therefore, maintaining temporal consistency in  
55 mean field bias adjustment is essential for producing physically consistent precipitation estimates (Seo et al., 1999; Seed et  
al., 2000; Germann et al., 2009; Ryu et al., 2025). However, achieving such consistency remains challenging for sub-hourly  
datasets, where independently estimated scaling factors may fluctuate substantially and introduce artificial temporal  
variability.

To address these limitations, a temporally constrained radar–gauge bias correction framework is applied in combination with  
60 systematic gauge quality control procedures. In addition, to improve spatial smoothness and numerical stability, a residual  
radial basis function (RRBF) approach is used to interpolate differences between bias-corrected radar estimates and gauge  
observations. RBF-based methods have been widely applied in environmental interpolation over complex terrain and in  
radar–gauge merging (Ryu et al., 2024, 2025), and the RRBF framework enables the representation of spatially structured  
residuals while preserving fine-scale variability.



65 The framework is implemented using nationwide radar and rain gauge observations over South Korea for the period 2016–  
2024. The resulting dataset provides precipitation estimates at 0.5 km spatial and 10 min temporal resolution. Dataset  
characteristics, methodology, validation results, and data availability are described in the following sections.

## 2. Data

### 2.1 KMA radar data

70 The nationwide composite reflectivity fields produced by the Korea Meteorological Administration (KMA) were used in this  
study. Since 2016, these data have been continuously available through the KMA API Hub (KMA, 2025). The Hybrid  
Surface Rainfall (HSR) composite reflectivity product is provided at 5-minute intervals with a spatial resolution of 500 m ×  
500 m on a regular grid of 2305 × 2881 pixels and is distributed in compressed binary format (\*.bin.zip). All radar  
observation times are referenced to Korea Standard Time (KST, UTC+9).

75 The composite reflectivity fields are defined on a projected Cartesian grid using the Lambert Conformal Conic (LCC)  
projection, with a reference latitude of 38.0° N and a reference longitude of 126.0° E. The horizontal grid spacing is 500 m in  
both directions. This configuration is consistent with the operational HSR products distributed by KMA and ensures spatial  
consistency with other national meteorological datasets.

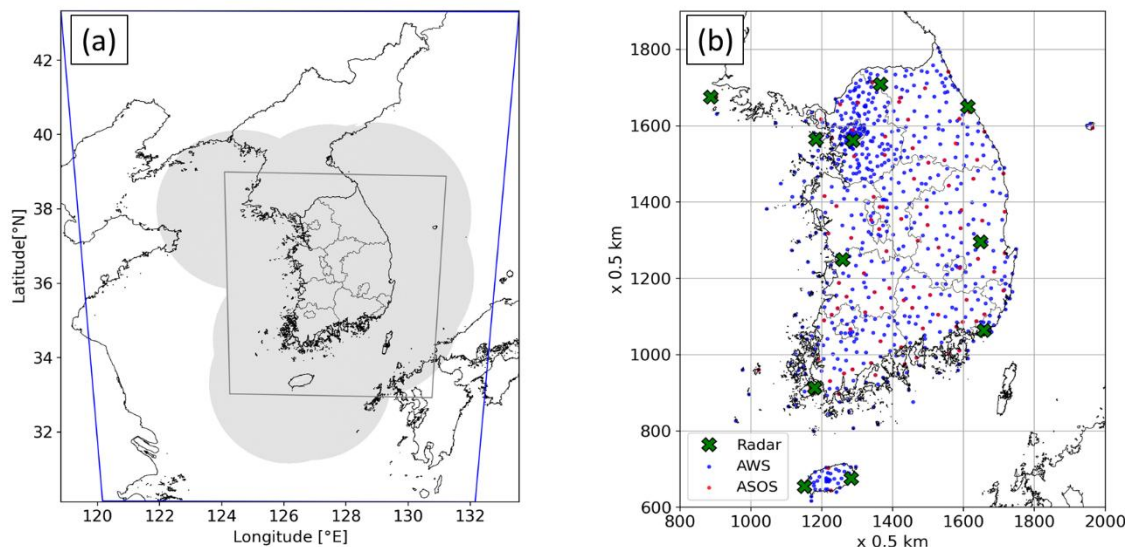
According to KMA documentation, individual radar volume data are processed using the Clutter Elimination Algorithm for  
80 Non-Precipitation Echoes of Radar data (CLEANER) prior to compositing (Oh et al., 2020). The quality-controlled radar  
data are subsequently combined using the HSR synthesis technique (Kwon et al., 2015; Lyu et al., 2017). During this process,  
reflectivity is projected to a near-surface altitude by selecting the lowest elevation scan not affected by terrain blockage.  
When beam shielding occurs, higher elevation scans are adaptively used to compensate for blocked beams, thereby reducing  
the influence of orographic effects and residual non-meteorological echoes. These procedures are implemented within the  
85 operational HSR processing framework of KMA.

Single-radar HSR fields from 11 weather radars operated by KMA (10 S-band and 1 C-band) are mosaicked to produce the  
nationwide composite reflectivity product. Between 2014 and 2019, most radars in the network were upgraded from single-  
to dual-polarization systems, and the Incheon International Airport radar was replaced with a dual-polarization system in  
August 2022. As a result, radar hardware configurations changed during the study period. In addition, operational scanning  
90 strategies, consequently compositing altitude selection and quality control procedures, may have evolved over time.  
Although the HSR composite is generated within a standardized framework, potential impacts of these changes on long-term  
reflectivity homogeneity cannot be fully excluded.

Figure 1 illustrates the radar domains and their locations used in this study. The blue outline denotes the fixed 500 m grid  
domain provided through the KMA API Hub and used for generating the merged radar–gauge precipitation fields. The gray-  
95 shaded area indicates the representative spatial coverage of the HSR composite. Although this coverage is not strictly  
constant over the 9-year period due to changes in radar operation and network configuration, it represents the typical extent



of nationwide radar coverage. Temporary radar outages and maintenance periods are reflected in the operational HSR composite product. No additional spatial gap filling or correction was applied to the radar data prior to merging. Reflectivity was converted to rainfall intensity using the operational Z–R relationship adopted by KMA (see Sec. 3.2, Eq. 1) before the radar–gauge merging procedure.



105 **Figure 1: (a) Radar observation domains. The blue outline shows the HSR domain provided through the KMA API Hub at 0.5 km resolution (2305 × 2881 pixels). The gray-shaded area denotes the nationwide HSR radar composite coverage, and the inner gray line indicates the verification domain. (b) Enlarged view of the verification domain, showing the locations of weather radars (green crosses), automatic weather systems (AWSs; blue dots), and automated synoptic observing systems (ASOSs; red dots).**

## 2.2 KMA rain gauge data

Rainfall observations were obtained from two nationwide automatic observation networks operated by the Korea Meteorological Administration (KMA): the Automatic Weather System (AWS) and the Automated Synoptic Observing System (ASOS). As of 2023, the combined network consists of approximately 550 AWS stations and 100 ASOS stations (Fig. 1b) across South Korea, corresponding to an average inter-station spacing of approximately 13 km. AWS stations are primarily installed in mountainous and rural areas to monitor localized weather conditions and are equipped with tipping-bucket rain gauges with a resolution of 0.5 mm per tip. ASOS stations are located at principal meteorological sites and follow World Meteorological Organization (WMO) standards, using weighing-type gauges with a measurement resolution of 0.1 mm. Both networks provide rainfall observations at 1-minute temporal resolution, with precipitation amounts recorded in millimeters (mm).

The 1-minute rainfall time series were subjected to quality control procedures prior to merging. These procedures included the detection of missing values, removal of physically unrealistic intensities, and identification of abrupt resets in cumulative tipping-bucket measurements (WMO, 2018). Records failing these checks were excluded from further analysis. The quality-



controlled 1-minute data were then aggregated into 10-minute accumulations to reduce short-term variability and measurement noise. These accumulations were subsequently converted to rainfall intensity ( $\text{mm h}^{-1}$ ) and used as gauge input for the radar–gauge merging procedure.

### 3. Methodology

This section describes the radar–gauge merging procedure used to generate the high-resolution precipitation dataset. The processing framework is designed to ensure temporal consistency and spatial representativeness while integrating radar and rain gauge observations. Figure 2 provides an overview of the workflow, including gauge preprocessing, radar rainfall estimation, temporally constrained bias correction, residual interpolation using the RRBf method, and validation.

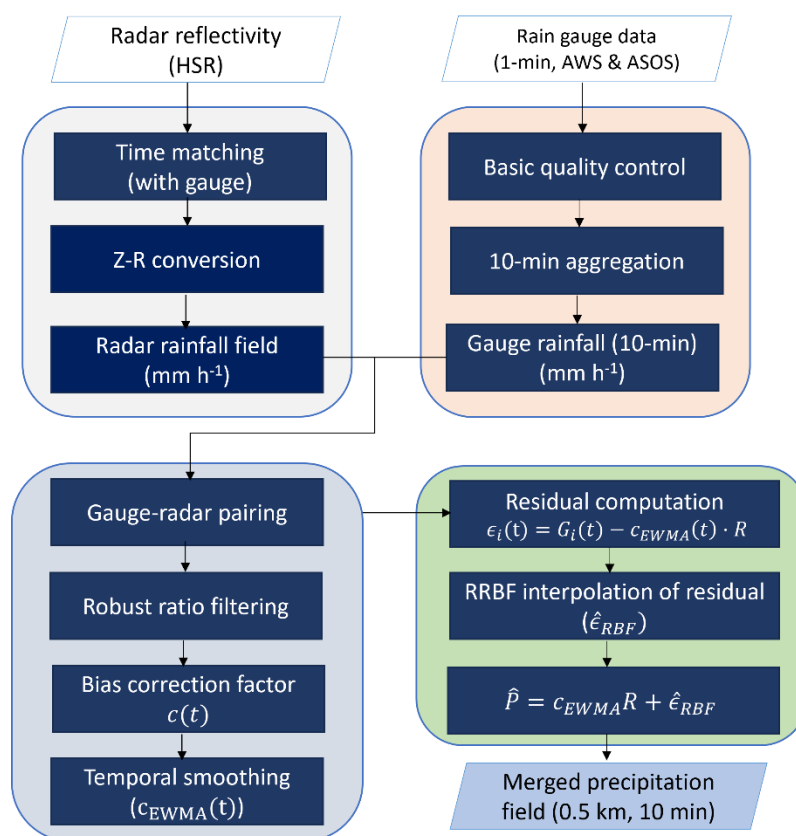


Figure 2: Overall workflow of the RRBf-based radar-gauge merging procedure.

#### 3.1 Gauge data processing

Rain gauge observations from the AWS and ASOS networks were subjected to basic quality control prior to merging. Missing values were identified, and range checks were applied to exclude unrealistic rainfall intensities exceeding 8 mm



135  $\text{min}^{-1}$  (El Hachem et al., 2022). Following Ryu et al. (2025), the quality-controlled 1-minute rainfall data were aggregated into 10-minute accumulations (that is, 10 min average rainfall rate) to reduce short-term variability. These average rainfall rates were used as gauge input for the radar–gauge merging procedure.

### 3.2 Radar rainfall estimation

Radar reflectivity from the nationwide HSR composite was converted to rainfall intensity using the operational Z–R relationship adopted by KMA:

$$Z = 148R^{1.59}, \quad (1)$$

140 as reported by Ro et al. (2022). Radar–gauge temporal matching followed the procedure described in Ryu et al. (2025). For each 10-minute radar time step, gauge rainfall was accumulated over the corresponding 10-minute period ending 8 minutes after the radar observation time and then converted to rainfall intensity ( $\text{mm h}^{-1}$ ). A minimum rainfall threshold of  $0.1 \text{ mm h}^{-1}$  was applied to both radar and gauge data, and values below this threshold were treated as no-rain.

### 3.3 Estimation of temporally consistent bias correction factor

145 Radar rainfall at each gauge location was extracted from the nearest grid cell. To reduce representativeness differences between point-scale gauge measurements and gridded radar data, radar rainfall was averaged over a  $3 \times 3$  pixel window ( $1.5 \text{ km} \times 1.5 \text{ km}$ ) centered on each station.

Bias correction factors were estimated only when both radar and gauge rainfall exceeded  $0.5 \text{ mm h}^{-1}$  and when at least 20 valid gauge–radar pairs were available. Individual ratios were calculated as

$$150 \quad q_i(t) = \frac{G_i(t)}{R_i(t)}, \quad (2)$$

where  $G_i(t)$  and  $R_i(t)$  denote gauge and radar rainfall at station  $i$  and time  $t$ , respectively. Ratios outside the 5th–95th percentile range were excluded to limit the influence of outliers. The raw bias correction factor was defined as

$$C(t) = \frac{\sum_{i=1}^N G_i(t)}{\sum_{i=1}^N R_i(t)}, \quad (3)$$

155 where  $N$  is the number of valid pairs. To reduce abrupt temporal variability, changes in  $C(t)$  relative to the previous time step were limited to  $\pm 30\%$ . The final correction factor was obtained using an exponentially weighted moving average (EWMA; Hunter, 1986):

$$C_{EWMA}(t) = \alpha C(t) + (1 - \alpha)C_{EWMA}(t - 1), \alpha = 0.5. \quad (4)$$

If fewer than 20 valid pairs were available, the correction factor from the previous time step was retained.

### 3.4 RRBF based residual interpolation

160 After bias correction, residuals between gauge observations and corrected radar rainfall were computed as

$$\epsilon_i(t) = G_i(t) - C_{EWMA}(t)R_i(t). \quad (5)$$



Residual interpolation was performed only when at least five stations satisfied the rainfall threshold ( $\geq 0.5 \text{ mm h}^{-1}$  for both radar and gauge observations). The residuals were interpolated at an arbitrary location  $z$  using a radial basis function (RBF) approach (Buhmann, 2003; Fasshauer, 2007; Ryu et al., 2025):

$$165 \quad \hat{\varepsilon}_{\text{RBF}}(z, t) = \sum_{i=1}^N w_i(t) \phi(|z - z_i|). \quad (6)$$

Here, an exponential RBF kernel was adopted, defined as  $\phi(|\cdot|) = \exp(-|\cdot|/s)$ , with a shape parameter of  $s = 16 \text{ km}$  (Ryu et al., 2024). When fewer than five stations satisfied the threshold, residual interpolation was omitted, and only the bias-corrected radar rainfall was retained. The final merged precipitation field was defined as

$$\hat{P}(z, t) = C_{\text{EWMA}} R(z, t) + \hat{\varepsilon}_{\text{RBF}}(z, t). \quad (7)$$

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### 3.5 Validation strategy

The merged precipitation fields were evaluated using a leave-one-out cross-validation (LOOCV) approach applied to the RRBF residual interpolation. At each time step, individual stations were sequentially excluded, and residuals at the excluded locations were estimated using the remaining stations. To reduce computational cost, LOOCV errors were calculated using  
175 Rippa's theorem (Rippa, 1999), which allows efficient estimation of cross-validation errors without recomputing the interpolation for each station. Validation metrics included mean absolute error (MAE), normalized mean absolute error (NMAE), normalized bias error (NBE), and the Pearson correlation coefficient (COR).

## 4. Description of the released dataset

### 4.1. Overview of temporal coverage

180 The dataset is a nationwide radar–gauge merged precipitation product covering the period from 1 January 2016 to 31 December 2024. Precipitation fields are provided at 10-minute intervals with a spatial resolution of 0.5 km on a regular grid consistent with the KMA HSR composite domain. The dataset is generated using the RRBF-based merging framework described in Section 3 and provides spatially continuous precipitation estimates over South Korea.

### 4.2. Temporal completeness and missing data

185 A total of 473,472 10-minute intervals are expected over the 9-year period. Among these, 170 time steps (0.036%) are missing due to unavailable or empty radar input files in the operational HSR archive. Most missing cases correspond to isolated single time steps. The only extended data gap occurred on 29 February 2016, when the national radar composite was unavailable for the entire day. No temporal interpolation or gap filling was applied to replace missing intervals. A complete list of missing timestamps is provided in Table 1.

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**Table 1. Summary of missing 10-minute RRBf precipitation timestamps (2016–2024). All time stamps are reported in Local Standard time (LST, UTC+9)**

Year	Missing count	Timestamps
2016	2 (incl. 1 full day)	20160229 (all day); 20160601 01:00
2017	1	20170903 20:00
2018	8	20180304 07:30; 20180329 01:40; 02:10; 03:40; 05:10; 05:40; 20180818 13:30; 20181225 19:50
2019	3	20190127 02:30; 20190312 10:50
2020	0	–
2021	7	20210304 11:50; 12:00; 20211130 14:40; 14:50; 15:00; 15:10; 15:20
2022	3	20221207 14:30; 14:40; 20221220 17:10
2023	2	20230828 08:00; 20231017 09:20
2024	2	20240320 17:00; 17:10
Total	26 single timestamps + 1 full day	170 missing slots

#### 4.3. File naming convention and data format

The dataset is stored as individual NetCDF files, each corresponding to a 10-minute average precipitation field. File names follow the convention Radar\_Gauge\_RRBf\_YYYYMMDDHHmm.nc, where YYYYMMDDHHmm denotes the timestamp in Local Standard Time (LST, UTC+9). The files are organized in a hierarchical directory structure by month and day, following the format YYYYMM/DD/Radar\_Gauge\_RRBf\_YYYYMMDDHHmm.nc, where YYYYMM represents the year and month and DD represents the day of the month. For data distribution, each monthly directory (YYYYMM) is archived as a compressed file named YYYYMM.tar.gz.

Within each file, precipitation is stored on a regular Lambert Conformal Conic (LCC) projected grid with a spatial resolution of 0.5 km. The grid consists of  $2305 \times 2881$  points in the east–west and north–south directions, respectively, consistent with the operational HSR radar grid provided by KMA. Each NetCDF file contains a single precipitation field corresponding to the observation time. Projection parameters and coordinate variables are defined in accordance with CF metadata conventions. All files are stored in NetCDF4 format with internal compression to reduce storage requirements while preserving data integrity.

#### 4.4 Variables and metadata

The primary variable (RR) represents the merged precipitation field expressed as rainfall intensity ( $\text{mm h}^{-1}$ ). The values correspond to 10-minute averages expressed as equivalent hourly rates. Data are stored as scaled 16-bit integers with a scale factor of 0.1. Each file also includes the temporally smoothed radar–gauge bias correction factor ( $C_{\text{EWMA}}$ ), stored as a



210 one-dimensional variable along the time dimension. Global attributes provide information on spatial resolution, projection parameters, temporal coverage, data sources, and processing history. All variables and metadata follow CF-compliant NetCDF conventions to facilitate interoperability and long-term reuse.

## 5. Results

### 5.1. Event-based evaluation of the radar–gauge merging method (summer 2022)

215 The performance of the RRBF-based merging framework was evaluated using rainfall events observed from June to August 2022 over South Korea. This period includes both convective and stratiform precipitation associated with the East Asian summer monsoon. Only time steps with 10-minute gauge rainfall rate greater than or equal to  $0.1 \text{ mm h}^{-1}$  were included in the analysis. Two types of temporal accumulation windows (10 min and 1 h) were used for cross-validation.

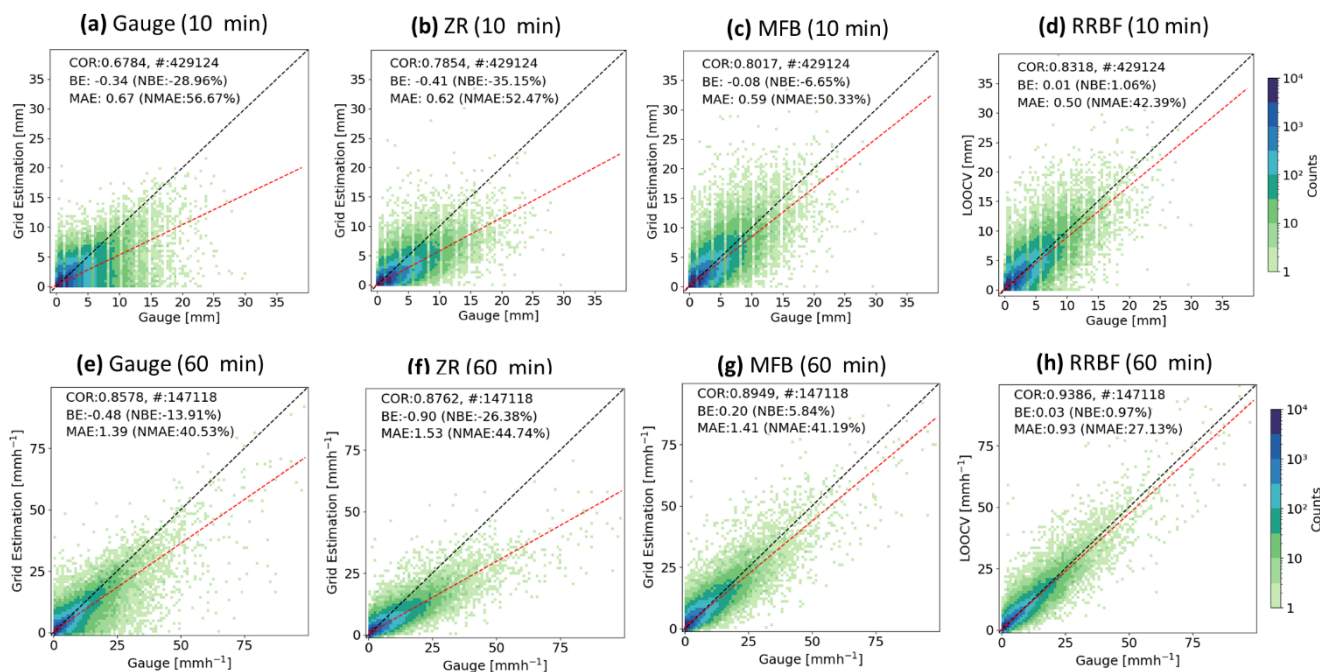
#### 5.1.1. Comparison of estimated accuracy against rain gauges

220 Figure 3 presents scatter density plots comparing estimated rainfall with rain gauge observations for summer 2022 events. Panels (a–d) show rainfall intensities ( $\text{mm h}^{-1}$ ) obtained by converting 10 min accumulations to hourly rates. Panels (e–h) show non-overlapping 60 min accumulated rainfall obtained by summing six consecutive 10 min accumulations. For reference (Fig. 3a, e), gauge-only rainfall fields were obtained by interpolating gauge observations using the RBF method. Radar-only estimates based on the operational Z–R relationship and mean field bias (MFB) adjustment are shown in Fig. 3b–  
225 c and Fig. 3f–g, respectively. The RRBF results (Fig. 3d, h) correspond to LOOCV estimates, ensuring independence between validation observations and interpolation inputs.

For rainfall intensities derived from 10 min accumulations (Fig. 3a–d), the Z–R estimates exhibit a negative bias (NBE =  $-35.15\%$ ) and relatively large dispersion (COR = 0.7854; MAE =  $0.62 \text{ mm h}^{-1}$ ). The MFB adjustment reduces the bias (NBE =  $-6.65\%$ ) but still shows considerable scatter around the 1:1 line. The RRBF method demonstrates higher correlation (COR = 0.8318) and lower MAE ( $0.50 \text{ mm h}^{-1}$ ), with near-zero bias (NBE =  $1.06\%$ ). The discrete banding patterns visible in the scatter plots, particularly along the x-axis, arise from the finite resolution of tipping-bucket rain gauges. Rainfall is recorded in discrete increments (e.g., 0.5 mm), and the conversion of 10 min accumulations to hourly rainfall intensities (multiplication by a factor of 6) results in quantized rainfall values, producing distinct linear patterns in the scatter distribution.

235 For the 60 min accumulated rainfall (Fig. 3e–h), all methods show improved agreement due to temporal aggregation. The RRBF method achieves the highest correlation (COR = 0.9386) and lowest MAE ( $0.93 \text{ mm h}^{-1}$ ), compared to the Z–R (COR = 0.8762; MAE =  $1.53 \text{ mm h}^{-1}$ ) and MFB (COR = 0.8949; MAE =  $1.41 \text{ mm h}^{-1}$ ) estimates.

Across both temporal aggregation approaches, the RRBF-based merging approach shows reduced bias and improved agreement with rain gauge observations relative to radar-only estimates. These results indicate that the RRBF framework  
240 provides consistent performance across different temporal scales.



245 **Figure 3: Scatter density plots comparing gauge interpolation, radar-only Z–R, mean field bias (MFB), and RRBF-merged precipitation estimates with rain gauge observations for summer rainfall events (June–August 2022). Panels (a–d) show rainfall intensities ( $\text{mm h}^{-1}$ ) obtained by converting 10 min accumulated rainfall to hourly rates. Panels (e–h) show non-overlapping 60 min accumulated rainfall (mm) obtained by summing six consecutive 10 min accumulations. The dashed black line indicates the 1:1 relationship, and the red dashed line represents the linear regression fit.**

### 5.1.2. Spatial characteristics of accumulated precipitation

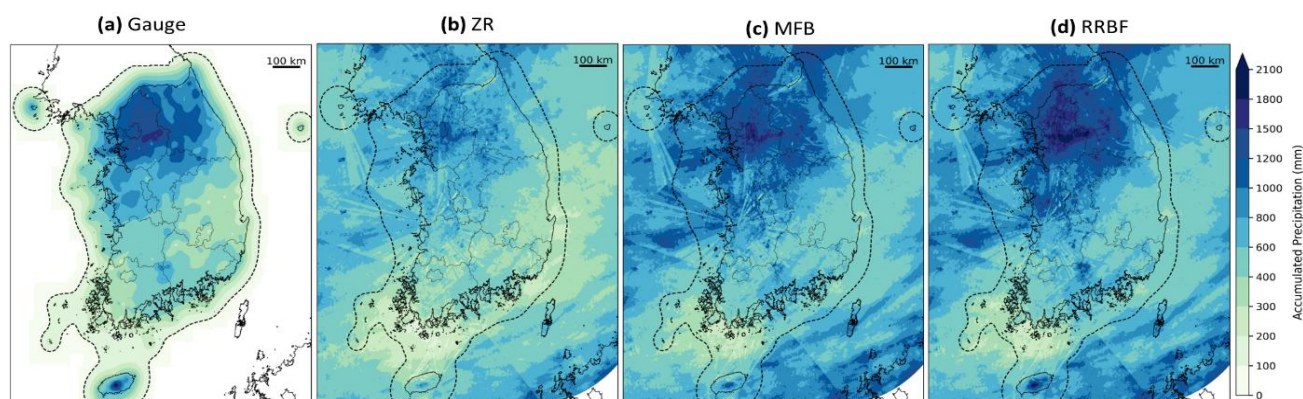
250 Figure 4 presents the spatial distribution of accumulated precipitation from June to August 2022 derived using different estimation methods. Panel (a) shows the gauge-based precipitation field obtained by applying radial basis function (RBF) interpolation to rain gauge observations, while panels (b), (c), and (d) show the corresponding accumulations from the radar-only Z–R product, the mean field bias (MFB)–corrected field, and the RRBF-based merged field, respectively.

255 The gauge-based RBF interpolation (Fig. 4a) reproduces localized rainfall maxima associated with summer precipitation but exhibits spatial smoothing and pronounced gradients in regions with sparse station coverage. The dashed contours indicate areas where the three-month accumulated precipitation exceeds 100 mm based on the gauge-only RBF field. This threshold is used as a practical criterion to identify regions with substantial seasonal rainfall and strong gauge influence and does not represent a physical boundary. Outside these regions, spatial uncertainty increases due to limited station density.

260 The radar-only Z–R product (Fig. 4b) captures the large-scale precipitation patterns over the Korean Peninsula but shows lower accumulated amounts in regions influenced by intense convective rainfall compared to the gauge-based field. The MFB-corrected field (Fig. 4c) reduces the overall differences in accumulated precipitation relative to the Z–R product; however, its spatially uniform adjustment results in residual spatial discrepancies.



The RRBF-based merged field (Fig. 4d) preserves the large-scale spatial structure of radar-derived precipitation while incorporating gauge-based adjustments. The resulting accumulation patterns show closer agreement with the gauge-based field in regions with dense gauge coverage. When precipitation is accumulated over the full three-month period, azimuthal spatial features associated with radar beam geometry and scanning characteristics remain evident (Figs. 4b and 4c). These artifacts originate from the HSR compositing process and therefore should be addressed within the radar processing stage. Although residual interpolation partially reduces these features, they are not fully eliminated.



270 **Figure 4: Spatial distribution of accumulated precipitation (mm) from June to August 2022 derived using different estimation methods: (a) gauge-based RBF interpolation, (b) radar-only Z–R product, (c) mean field bias (MFB)–corrected radar rainfall, and (d) RRBF-based merged precipitation. The dashed contours indicate regions where the three-month accumulated precipitation derived from gauge-only RBF interpolation exceeds 100 mm, representing areas with substantial gauge influence. All panels are shown over the same spatial domain.**

## 5.2. Long-term Validation (2016–2024)

275 To assess the long-term characteristics of the merged precipitation dataset, analyses were conducted over the full period from 2016 to 2024. The evaluation focuses on interannual variability and the spatial distribution of accumulated precipitation.

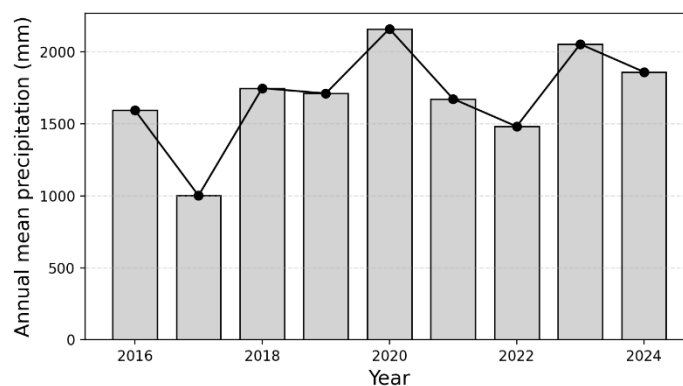
### 5.2.1. Interannual variability and accumulated precipitation

Annual accumulated precipitation was calculated for each year from 2016 to 2024 using the RRBF-based merged dataset. Annual totals were spatially averaged within the dashed region shown in Fig. 4, which represents an area with sufficiently  
280 dense gauge observations to ensure a consistent influence on the merged field and defines the analysis domain for interannual comparison.

Figure 5 presents the time series of annual mean precipitation over this domain. Pronounced interannual variability is evident throughout the 9-year period. Among the analyzed years, 2017 exhibits the lowest annual precipitation, whereas 2020 records the highest total, reflecting year-to-year differences in precipitation conditions. Despite these variations, the dataset



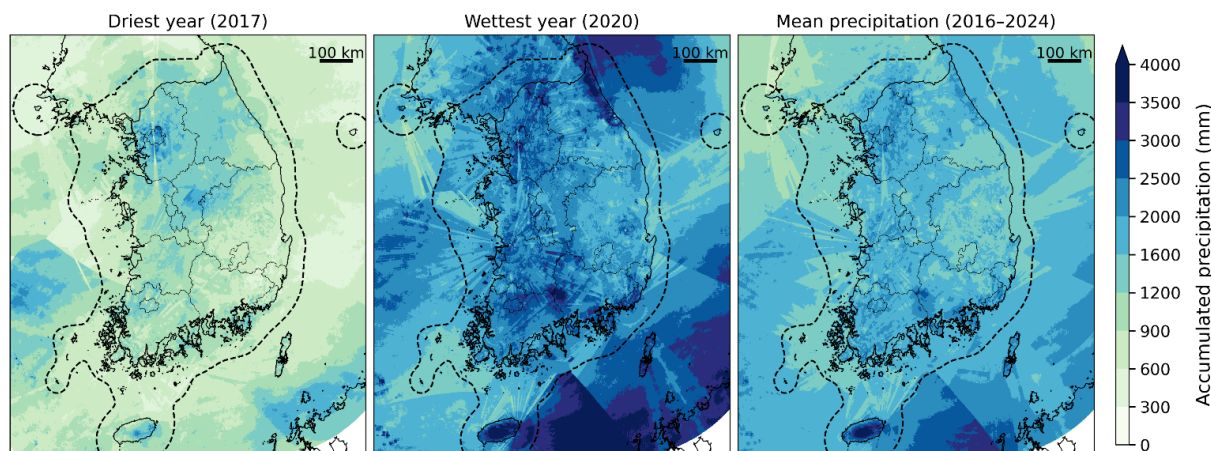
285 exhibits temporally consistent behavior without abrupt discontinuities. The time series indicates that interannual variability is robustly preserved across the full record from 2016 to 2024.



**Figure 5: Time series of annual mean precipitation averaged over the analysis domain for 2016–2024.**

Figure 6 shows the spatial distribution of annual accumulated precipitation for the driest year (2017), the wettest year (2020), and the 9-year mean over the period 2016–2024. The dashed boundary denotes the analysis domain used for the statistical evaluation presented in Fig. 5. In 2017, precipitation amounts are generally lower across most of the Korean Peninsula, whereas in 2020, higher precipitation totals are observed over widespread areas, particularly in the central and southern regions. The 9-year mean field represents the average spatial distribution of precipitation during the study period, characterized by localized maxima associated with orographic and coastal influences.

295 Compared to event-scale precipitation fields derived from short-term summer events, annual and multi-year accumulations exhibit substantially smoother spatial patterns. This smoothing reduces the apparent impact of short-term variability and radar observation artifacts. However, weak spatial signatures related to radar beam geometry are still detectable in some areas, indicating that residual structural artifacts of radar observations persist even in long-term accumulations. It should be noted that Fig. 6 presents only the sub-domain used for statistical analysis. The full dataset is available over the complete  
300 radar composite domain ( $2305 \times 2881$  grid points) shown in Fig. 1(a). Annual accumulation maps for all individual years over the full domain are provided in Appendix A.



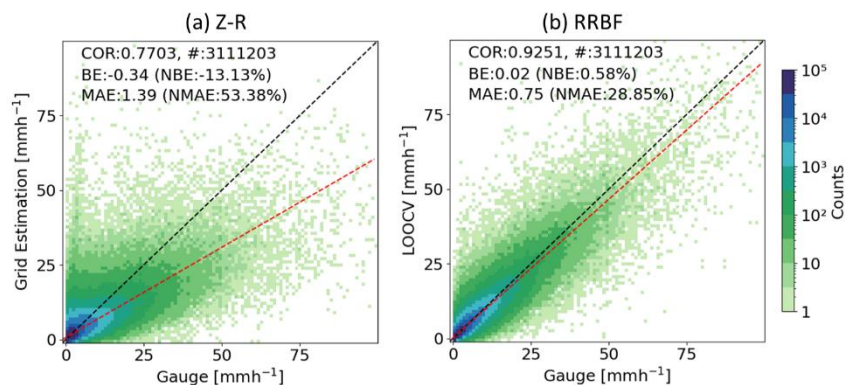
305 **Figure 6: Spatial distribution of annual accumulated precipitation derived from the RRBF-based merged dataset for (a) 2017 (driest year), (b) 2020 (wettest year), and (c) the 9-year mean (2016–2024). The dashed outline denotes the analysis domain used for interannual statistics.**

### 5.2.2. Validation against rain gauge observation

The long-term statistical performance of the merged precipitation dataset was evaluated against KMA rain gauge  
310 observations over the period 2016–2024 at an hourly time scale, using non-overlapping 60 min accumulated rainfall derived by summing six consecutive 10 min observations. Radar-only Z–R precipitation and RRBF-based merged precipitation were compared across multiple rainfall intensity thresholds. Figure 7 presents scatter density plots for cases with gauge-observed rainfall  $\geq 0.1 \text{ mm h}^{-1}$ . Radar-only values were obtained from the nearest radar grid cell at each gauge location, whereas RRBF values correspond to LOOCV estimates, ensuring independence between validation observations and interpolation  
315 inputs.

Consistent with the event-based analysis, the Z–R estimates exhibit a systematic negative bias across the full range of observed intensities, with increasing dispersion at higher rainfall rates. However, the long-term evaluation demonstrates that these error characteristics persist across the entire analysis period. In contrast, the RRBF estimates show a sustained reduction in bias and improved agreement with gauge observations over all intensity ranges. For rainfall  $\geq 0.1 \text{ mm h}^{-1}$ , the  
320 normalized mean absolute error (NMAE) decreases from 53.38% (Z–R) to 28.85% (RRBF), while the correlation coefficient increases from 0.7703 to 0.9251 (Table 2). The bias is also markedly reduced, from  $-13.13\%$  to  $0.58\%$ .

Table 2 summarizes performance metrics for rainfall thresholds of 0.1, 0.5, 1.0, and  $5.0 \text{ mm h}^{-1}$ . Across all thresholds, the RRBF-based estimates consistently demonstrate improved performance relative to radar-only Z–R estimates, indicating that the benefits observed in event-scale analysis are robust across long-term conditions.



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**Figure 7:** Scatter density plots of hourly precipitation comparing (a) radar-only Z–R estimates and (b) RRBf-based merged precipitation against rain gauge observations for the period 2016–2024. Only cases with gauge-observed rainfall greater than 0.1 mm h<sup>-1</sup> are included. Radar precipitation values are extracted from the grid cell closest to each gauge location, whereas RRBf estimates correspond to LOOCV results. Dashed lines indicate the 1:1 relationship, and colors represent the logarithm of sample density.

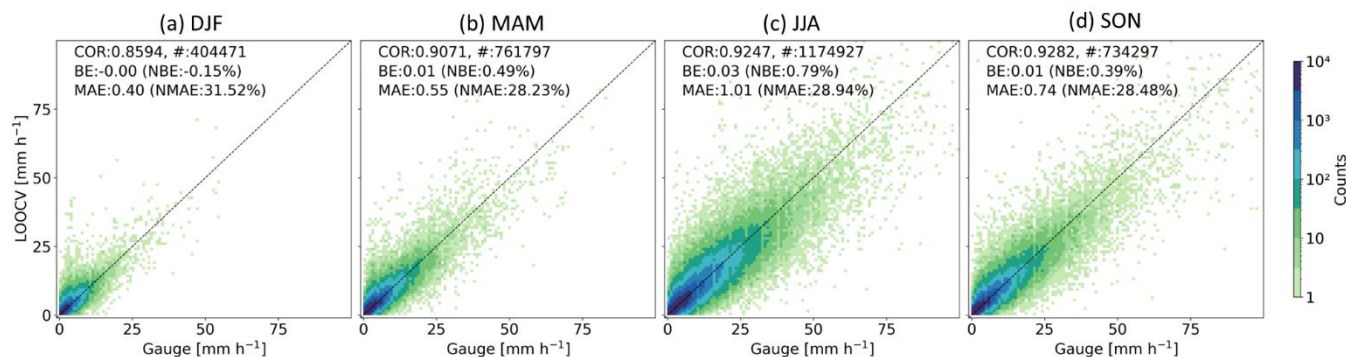
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**Table 2.** Statistical comparison of hourly radar-only Z–R and RRBf precipitation against KMA rain gauge observations for 2016–2024 at multiple rainfall thresholds.

Threshold value (mm)	Mean hourly precipitation	NBE (%)	COR ()	MAE (mm)	NMAE (%)	No. of pairs
Radar (Z-R):						
0.1	2.60	-13.13	0.7703	1.39	53.38	3111203
0.5	2.70	-14.12	0.7694	1.42	52.54	2972550
1.0	3.95	-17.75	0.7463	1.92	48.56	1897268
5.0	10.60	-30.73	0.6852	4.46	42.16	426599
RRBF:						
0.1	2.60	0.58	0.9251	0.75	28.85	3111203
0.5	2.70	0.01	0.9247	0.77	28.38	2972550
1.0	3.95	0.36	0.9150	1.09	27.72	1897268
5.0	10.60	-3.30	0.8699	2.54	23.95	426599

Seasonal variations in the performance of the RRBf-based precipitation estimates are presented in Fig. 8 for winter (December–February, DJF), spring (March–May, MAM), summer (June–August, JJA), and autumn (September–November, SON). The correlation coefficient ranges from approximately 0.86 in DJF to values exceeding 0.92 in JJA and SON. A relatively larger dispersion is evident during winter, whereas warm-season estimates show tighter clustering around the 1:1 reference line.

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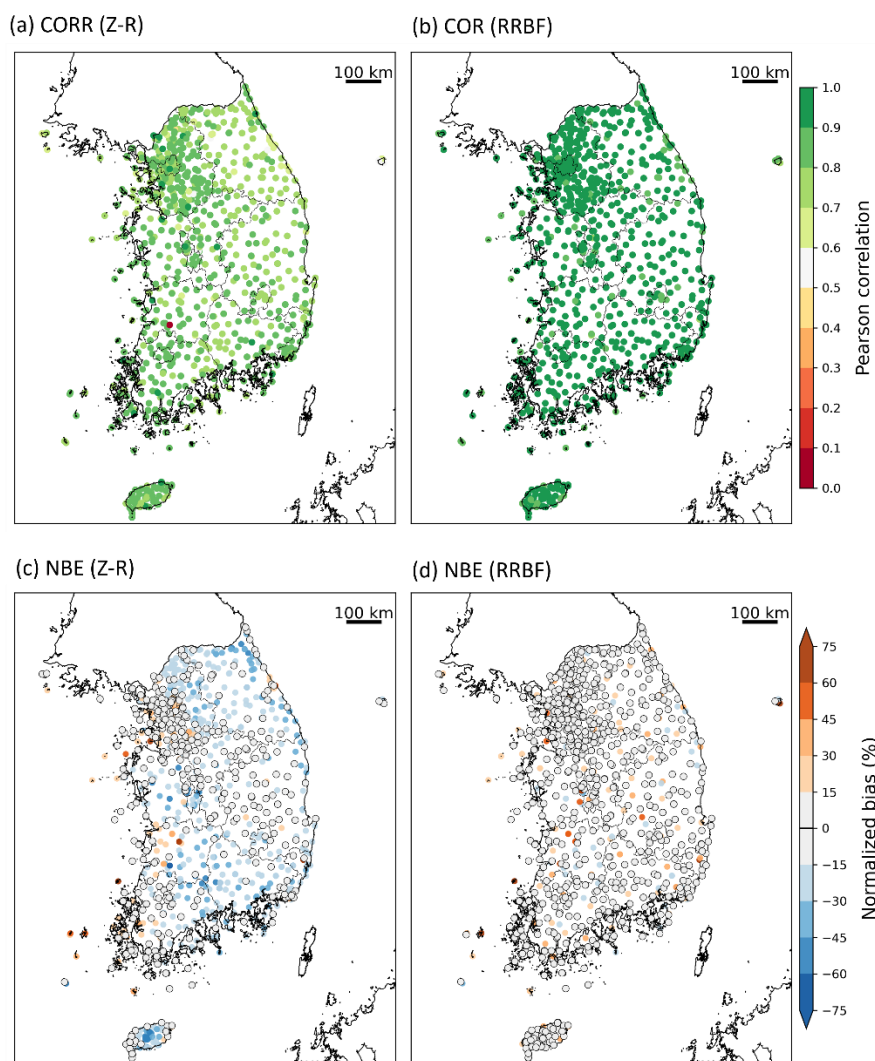
340 **Figure 8:** Seasonal scatter density plots of RRBf-based LOOCV precipitation estimates against rain gauge observations for (a) DJF, (b) MAM, (c) JJA, and (d) SON during the period 2016–2024. Colors denote the logarithm of sample density, and dashed lines indicate the 1:1 relationship. Performance statistics shown in each panel summarize seasonal variations in bias and correlation.

### 5.2.3. Spatial error distributions

345 To assess the spatial characteristics of estimation performance, station-based COR and NBE were computed for each rain gauge over the period 2016–2024 using non-overlapping 60 min accumulated rainfall derived from 10 min data. Only hours with gauge-observed rainfall  $\geq 0.5 \text{ mm h}^{-1}$  were included in the analysis. Figure 9 presents the spatial distribution of these metrics for radar-only Z–R estimates and RRBf-based precipitation. For the RRBf product, station-level statistics were derived from LOOCV estimates to ensure independence from the gauge observations used in the merging process.

350 For the radar-only Z–R estimates (Fig. 9a), correlation coefficients exhibit moderate to high values across South Korea, with pronounced spatial variability. Lower correlations are evident in some coastal regions and areas of complex terrain. In contrast, the RRBf-based estimates (Fig. 9b) show generally higher correlations at many stations and reduced spatial variability compared to the Z–R product.

The spatial distribution of normalized bias error further highlights differences between the two approaches. Radar-only Z–R estimates (Fig. 9c) are characterized by widespread negative bias across much of the domain, with spatially coherent underestimation in several regions, including coastal and mountainous areas. In the RRBf results (Fig. 9d), bias magnitudes are substantially reduced at many stations, and NBE values are more frequently centered near zero. Localized differences are apparent in regions such as the Seoul metropolitan area and Jeju Island, where bias patterns differ between the Z–R and RRBf estimates. Although some stations still exhibit relatively large positive or negative bias in the RRBf results, these are spatially isolated rather than regionally coherent. Overall, the station-based spatial analysis indicates that the RRBf-based precipitation estimates exhibit reduced bias magnitude and more spatially uniform correlation patterns compared to the radar-only Z–R estimates over the 2016–2024 period.



365 **Figure 9: Station-based spatial distributions of Pearson correlation coefficient (COR) and normalized bias error (NBE) for radar-only Z–R (a, c) and RRBF-based precipitation (b, d) over South Korea during 2016–2024. RRBF statistics are derived from leave-one-out cross-validation (LOOCV) estimates.**

#### 5.2.4. Temporal distribution of the bias adjustment factor

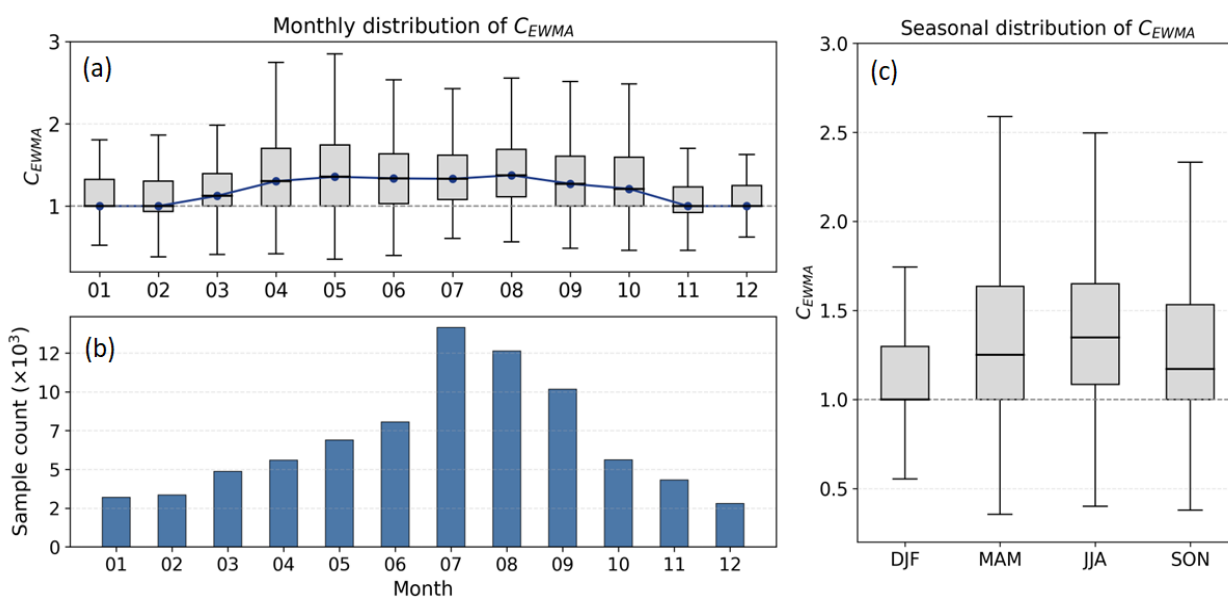
To investigate the temporal characteristics of the radar–gauge adjustment, the distribution of  $C_{EWMA}$  was analyzed by month and season for the period 2016–2024 (Fig. 10). The correction factor  $C_{EWMA}$  represents the multiplicative bias adjustment factor applied to radar-derived precipitation; values greater than 1 indicate that radar estimates are, on average, lower than gauge observations. Figure 10a presents monthly boxplots of  $C_{EWMA}$  aggregated over the 9-year period. Median values exceed 1 in all months. Slightly higher medians are observed from late spring to summer (May–August), whereas winter months exhibit comparatively lower values. The interquartile range varies seasonally, with broader distributions during the

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warm season and narrower distributions in winter. Monthly sample counts (Fig. 10b) show a pronounced seasonal cycle, with substantially higher counts in July and August and lower counts during winter months. Months with larger sample sizes also tend to exhibit wider distributions of  $C_{EWMA}$ .

Seasonal boxplots (Fig. 10c) indicate that median values are lowest in DJF and higher in the other seasons. Variability also differs by season, with broader interquartile ranges in MAM and JJA and narrower distributions in DJF. These seasonal patterns reflect differences in both the magnitude and variability of the radar–gauge adjustment factor across seasons during 2016–2024.



385 **Figure 10: Monthly and seasonal distribution of  $C_{EWMA}$  for 2016–2024. (a) Monthly boxplots with blue markers indicating monthly means; the dashed line denotes  $C_{EWMA} = 1$ . (b) Monthly sample counts ( $\times 10^3$ ). (c) Seasonal boxplots grouped into DJF, MAM, JJA, and SON; the dashed line denotes  $C_{EWMA} = 1$ .**

## 6. Data availability

The radar–gauge merged precipitation dataset for South Korea (2016–2024) is publicly available on Zenodo:

- Part 1 (2016–2020): <https://doi.org/10.5281/zenodo.19491708> (Ryu et al., 2026a)

- Part 2 (2021–2024): <https://doi.org/10.5281/zenodo.19562910> (Ryu et al., 2026b)

390 The dataset is distributed as monthly compressed archives (YYYYMM.tar.gz), each containing NetCDF files for individual 10-minute precipitation fields organized in the directory structure: 'YYYYMM/DD/YYYYMMDDHHmm.nc'. In addition to the precipitation data, Part 2 includes supplementary information such as metadata describing missing data periods, the spatial domain (latitude–longitude grid definition), and a README file providing detailed guidance on data structure and



usage. Radar input data were obtained from the KMA API Hub and are subject to KMA data policy. The merged dataset is  
395 released under the Creative Commons Attribution 4.0 International (CC BY 4.0) license.

## 7. Code availability

The processing code used to generate the dataset is not publicly available but may be provided by the corresponding author upon reasonable request.

## 8. Conclusions

400 This study presents a high-resolution radar–gauge merged precipitation dataset for South Korea covering the period 2016–  
2024. The dataset is provided at 0.5 km spatial resolution and 10 min temporal resolution and is based on nationwide  
composite radar reflectivity from the KMA and quality-controlled rain gauge observations from the AWS and ASOS  
networks. The merging framework combines a temporally smoothed multiplicative bias adjustment with residual  
interpolation using a radial basis function (RRBF). The bias correction factor is updated at 10 min intervals while  
405 incorporating information from previous time steps, and spatial discrepancies between radar and gauge observations are  
addressed through residual interpolation.

Event-based and long-term evaluations characterize the statistical, spatial, and seasonal performance of the merged dataset.  
Compared to radar-only Z–R estimates, the RRBF-based product exhibits reduced bias magnitude and higher correlation  
with rain gauge observations across rainfall thresholds and seasons. Station-based analyses further indicate more spatially  
410 uniform error characteristics relative to the radar-only product. The dataset captures interannual variability and spatial  
patterns of accumulated precipitation over 2016–2024. Seasonal variations in the bias adjustment factor reveal systematic  
differences in both magnitude and variability, consistent with seasonal rainfall characteristics.

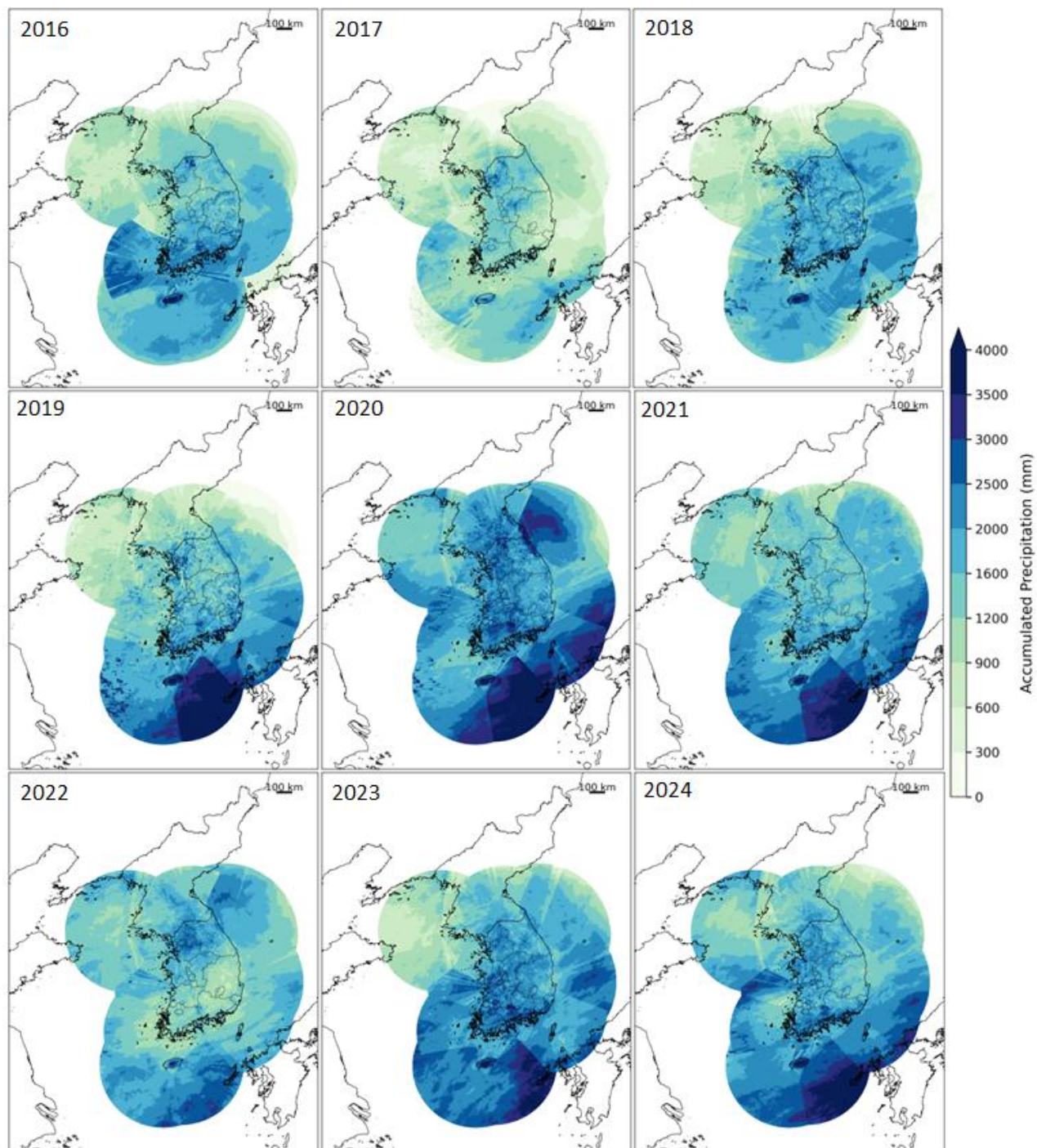
Despite these improvements, limitations inherent to radar-based precipitation estimation remain, particularly in regions  
affected by complex terrain and radar beam partial blockage. In addition, rain gauge quality control in this study was based  
415 on general range checks and consistency filtering; site-specific measurement uncertainties and representativeness issues may  
contribute to localized residual discrepancies. Further refinement of gauge quality assurance procedures may help reduce  
these uncertainties in future developments.

The resulting dataset provides a continuous, high-resolution precipitation record for South Korea and is intended to support  
hydrological, climatological, and related applications requiring sub-hourly rainfall information. The dataset is publicly  
420 available and can support applications such as extreme rainfall analysis, hydrological modeling, and satellite precipitation  
validation. As one of the first long-term radar–gauge merged precipitation products at sub-kilometer and sub-hourly  
resolution for South Korea, this dataset represents a valuable resource for studies requiring detailed precipitation information.



### **Appendix A: Annual accumulated precipitation over the full composite domain (2016-2024)**

Figure A1 presents the spatial distribution of annual accumulated precipitation derived from the RRBF-based merged dataset for 2016–2024 over the full radar composite domain ( $2305 \times 2881$  grid points), corresponding to the area shown in Fig. 1a. In contrast to Fig. 6, which is limited to the sub-domain used for validation analysis (Fig. 1b), the maps in this appendix provide the complete spatial coverage of the dataset. The full set of annual accumulation maps is made available as part of the dataset accompanying this publication. These maps represent the full spatial extent of the precipitation dataset developed and provided in this study, illustrating its capability to capture large-scale precipitation patterns across the entire radar composite domain. The annual accumulation fields exhibit coherent large-scale spatial structures, with relatively higher precipitation along southern coastal regions and in mountainous areas. Interannual variability is also evident across the full domain, including comparatively dry conditions in 2017 and enhanced precipitation in 2020.



435 **Figure A1:** Annual accumulated precipitation (mm) over the full radar composite domain ( $2305 \times 2881$  grid points) for the period 2016–2024. The maps correspond to the operational HSR composite coverage shown in Fig. 1(a) and represent the complete spatial extent of the RRBf-based merged precipitation dataset developed in this study.



### Author contributions.

440 Soorok Ryu conceived the study, developed the RRBF merging framework, processed the radar and gauge data, performed the validation analyses, and drafted the manuscript. Joon Jin Song contributed to radar data processing and technical support and assisted in manuscript revision. GyuWon Lee and Kyo Sun Lim supervised the research, contributed to conceptualization and interpretation of the results, and reviewed and edited the manuscript. All authors approved the final manuscript.

### Competing interests

445 The authors declare that they have no conflict of interest.

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