



1 **PlanetGSD 1.0: a cross-planetary grain-size distribution dataset from Earth, the Moon, and**

2 **Mars**

3 Jun Zhang^{1,2}, Yong Li^{1*}

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5 ¹ Key Laboratory of Mountain Hazards and Engineering Resilience /Institute of Mountain Hazards
6 and Environment, Chinese Academy of Sciences, Chengdu 610213, China

7 ² State Key Laboratory of Hydrosience and Engineering; Department of Hydraulic Engineering,
8 Tsinghua University, Beijing 100084, China

9

10 *Correspondence to: Yong Li, ylie@imde.ac.cn

11

12 **Abstract**

13 Comparative studies of surface processes across planetary bodies are hindered by the lack of
14 consistently parameterized, openly accessible soil data, especially the grain-size distribution (GSD)
15 data. Here we present PlanetGSD 1.0, the first standardized and unified cross-planetary GSD
16 database. It comprises 6,527 measurements from Earth (4,419 samples, 20 geomorphic settings),
17 the Moon (379 samples, 8 missions), and Mars (1,729 rover-derived estimates, 4 landing areas),
18 covering seven orders of magnitude in grain size (0.0001–600 mm). The traditional textural
19 fractions have been transferred into a unique parameter set (μ , D_c , n) derived from the unified GSD
20 (UGSD) function (median $R^2 = 0.988$), with quality metrics, georeferenced metadata, site-level
21 Weibull statistics, and open-source analysis codes. Technical validation confirms high fitting quality
22 across all samples (97.8% with $R^2 > 0.95$) and robust inter-operator reproducibility for Martian
23 image-derived measurements (coefficient of variation $< 8.3\%$ for key parameters). The complete
24 dataset is openly available on Figshare (Zhang, 2026) under CC BY 4.0 license. PlanetGSD 1.0



25 enables robust cross-planetary comparison of regolith properties, benchmarking of simulants, and
26 data-driven landing site assessment, establishing a foundational resource for planetary science.

27 **1. Introduction**

28 Understanding the physical properties of surface materials is fundamental to comparative
29 planetology, geotechnical engineering, and the planning of future exploration missions. Among
30 these properties, grain-size distribution (GSD) is one of the most informative: it governs the
31 mechanical strength, hydraulic conductivity, and geochemical reactivity of soils and regolith across
32 planetary bodies (Carrier, 2003; Fedo et al., 2015; Iverson & Vallance, 2001). On Earth, GSD
33 classification underpins soil taxonomy systems and is routinely used in geotechnical site
34 characterization (Das, 2019). On the Moon, GSD controls regolith trafficability, dust mobilization,
35 and the design of in-situ resource utilization (ISRU) systems (Colwell et al., 2007). On Mars, GSD
36 records the transition from volcanic to sedimentary surface processes and provides constraints on
37 past hydrological activity (Grotzinger et al., 2015).

38 Despite this shared importance, existing GSD datasets remain fragmented across disciplines
39 and planetary targets, with no unified analytical framework for cross-body comparison. Terrestrial
40 soil databases provide broad geographic coverage but lack the resolution needed for process-based
41 comparison with extraterrestrial materials. Lunar and Martian GSD data are scattered across
42 mission-specific archives and individual publications, with heterogeneous analytical methods that
43 preclude direct integration.

44 Several major compilations illustrate these limitations. For terrestrial soils, ISRIC-WISE
45 (Batjes, 2009) and HWSD (Shangguan et al., 2014) provide global coverage at ~1 km resolution
46 but report only texture-class percentages (sand, silt, clay) rather than complete GSD curves.



47 POLARIS (Chaney et al., 2016) offers 30 m probabilistic texture estimates for the USA but similarly
48 lacks full size distributions. These databases employ Earth-centric classification schemes (USDA,
49 FAO) that are not transferable to extraterrestrial contexts. For lunar materials, the NASA Lunar Soils
50 Grain Size Catalog (Graf, 1993) documents ~350 Apollo and Luna samples with cumulative mass
51 percentages at 9–15 sieve fractions, but bin widths vary by mission protocol, and no unified
52 parameterization is provided. The Lunar Sourcebook (Heiken et al., 1991) summarizes mean grain
53 sizes and sorting coefficients for ~200 samples but does not provide a digital database or complete
54 GSD curves. Recent Chang’e-5 and Chang’e-6 sample characterizations (Li et al., 2022, 2024;
55 Zhang et al., 2022) add valuable data but remain isolated from the Apollo/Luna corpus. For Mars,
56 GSD measurements are derived from rover imaging at individual landing sites: Gale Crater (Fedo
57 et al., 2015; Weitz et al., 2018), Jezero Crater (Stack et al., 2020), Gusev Crater (Herkenhoff et al.,
58 2004), and Meridiani Planum (Weitz et al., 2006). These studies employ site-specific image analysis
59 protocols with varying resolution limits and binning schemes, and no cross-site compilation or
60 standardized framework exists. Academic survey datasets in terrestrial geomorphology and
61 sedimentology (e.g., Blott & Pye, 2001; Eshel et al., 2004) report individual GSD measurements in
62 heterogeneous formats that resist systematic integration. Consequently, no unified framework exists
63 for comparing GSD characteristics across planetary bodies. A systematic comparison of these
64 existing resources with PlanetGSD 1.0 is provided in Table 1 (Section 2.1).

65 Compounding this data fragmentation, conventional GSD descriptors present additional
66 limitations. Percentile indices (D_{10} , D_{50} , D_{90}) and moment statistics (Folk & Ward, 1957) reduce
67 continuous distributions to summary values without direct links to physical processes. Standard
68 curve-fitting models—including lognormal, Rosin–Rammler, and Fredlund functions—impose



69 unimodal forms that cannot adequately represent the polygenetic, multimodal distributions common
70 in natural regolith (Bittelli et al., 1999). The Universal Grain-Size Distribution (UGSD) function
71 (Yong et al., 2013, 2017) addresses these limitations through a flexible four-parameter formulation
72 capable of capturing multimodal distributions, but has not previously been applied as a unified
73 framework for cross-planetary comparison.

74 Here we present PlanetGSD 1.0, a standardized database of 6,527 GSD measurements
75 compiled from Earth (4,419 samples spanning 20 geomorphic settings across 18 countries), the
76 Moon (379 samples from Apollo, Luna, and Chang'e missions), and Mars (1,729 rover-derived
77 estimates from Gale, Jezero, Gusev, and Meridiani sites), covering seven orders of magnitude in
78 grain size (0.0001–600 mm). All samples have been harmonized using the UGSD function,
79 achieving a median fitting R^2 of 0.988. Compared with existing resources, PlanetGSD 1.0 provides
80 four key advances: (i) the first unified parameterization across three planetary bodies; (ii) complete
81 raw cumulative curves retained alongside fitted parameters; (iii) site-level Weibull statistics
82 enabling stochastic field generation; and (iv) fully open data, codes, and metadata under CC BY 4.0
83 license. With this database we aim to fill the dual gap of fragmented data and absence of a unified
84 analytical framework, enabling robust cross-planetary comparison of regolith properties and
85 supporting data-driven benchmarking of simulant materials and landing-site assessment.

86 This paper is organized as follows. Section 2 describes the data acquisition methods for each
87 planetary body. Section 3 presents the data records, including dataset structure, content summaries,
88 and key fields. Section 4 reports the technical validation results. Section 5 provides illustrative
89 applications and identifies open questions. Section 6 and Section 7 are usage notes and conclusions,
90 respectively.



91 **2. Methods**

92 **2.1 Overview of the PlanetGSD dataset**

93 The PlanetGSD dataset comprises 6,527 soil samples from three planetary bodies—Earth, the
94 Moon, and Mars—integrated within a unified analytical framework based on the Universal Grain-
95 Size Distribution (UGSD) function. This compilation enables systematic comparison of granular
96 characteristics across terrestrial and extraterrestrial environments with contrasting surface processes,
97 climatic regimes, and geological histories. The database is organized with multi-level metadata,
98 including geographic coordinates, geomorphic context, mission information, and original data
99 sources, all standardized to facilitate cross-planetary analysis.

100 **Earth component.** The terrestrial samples represent the full spectrum of Earth's surface
101 environments, spanning five continents and encompassing 20 distinct geomorphic settings. These
102 include gravity-driven deposits (debris flows, landslides, moraines), fluvial systems (river valleys,
103 floodplains), aeolian environments (deserts, loess), pedogenic landscapes (vegetated slopes,
104 grasslands), and coastal zones. This diversity captures grain-size signatures associated with major
105 process regimes, providing a comprehensive terrestrial reference for comparison with
106 extraterrestrial materials. The Earth data integrate field-collected samples and literature-derived
107 measurements, all processed using standardized laboratory protocols.

108 **Lunar component.** The lunar samples originate from eight sample-return missions conducted
109 between 1969 and 2024, including Apollo (USA), Luna (USSR), and Chang'e (China) programs.
110 These missions provide geographic coverage of major lunar geological provinces, including mare
111 basalts, highland terrains, and the farside South Pole-Aitken basin. All samples are regolith materials
112 processed by impact gardening and space weathering, with grain-size distributions originally

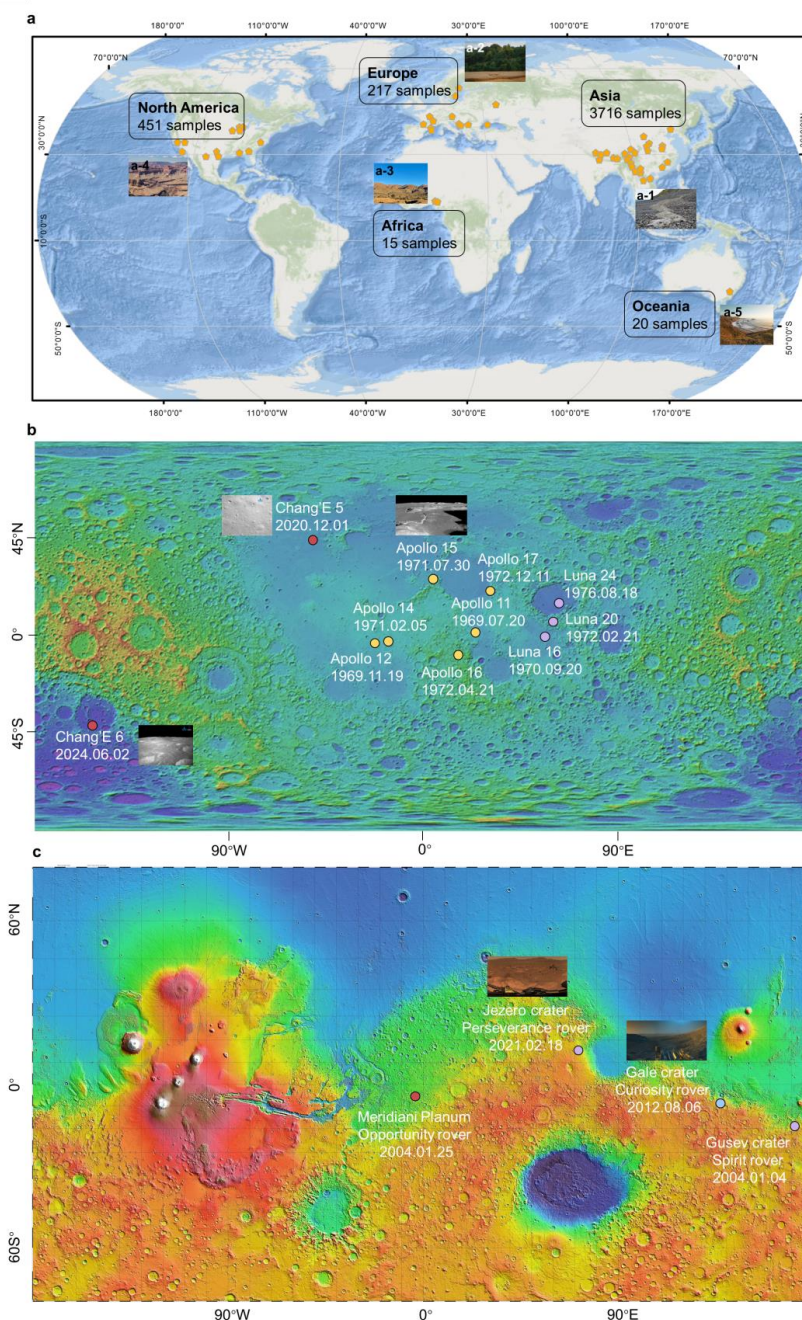


113 measured by dry sieving. The lunar data are harmonized from multiple mission catalogs, enabling
114 consistent cross-mission comparison.

115 **Martian component.** The Martian samples are derived from high-resolution rover imagery at
116 four NASA landing sites: Gale Crater (Curiosity), Jezero Crater (Perseverance), Gusev Crater
117 (Spirit), and Meridiani Planum (Opportunity). These sites represent diverse Martian geological
118 environments, including lacustrine mudstones and deltaic deposits (Gale, Jezero), weakly altered
119 olivine basalt plains (Gusev), and sulfate-rich evaporite sequences (Meridiani), spanning Noachian
120 to Amazonian periods. Grain-size distributions were obtained through semi-automated image
121 segmentation, capturing grain sizes from silt to gravel.

122 Database structure. All samples in PlanetGSD 1.0 are standardized to a consistent framework:
123 raw cumulative GSD curves are preserved in their original bin resolutions, and each sample is fitted
124 to the UGSD function to extract interpretable parameters (μ , D_c , n). Site-level statistics, including
125 three-parameter Weibull distributions for μ populations, are provided to enable stochastic field
126 generation and comparative analysis. Detailed sample-level metadata, including geographic
127 coordinates, geomorphic setting, mission information, and original data citations, are provided in
128 [Supplementary Tables S1–S7](#).

129



130

131 **Figure 1.** Global distribution of three terrestrial planetary soil sampling sites and representative
132 photographic images. (a) Sampling locations across 18 countries on five continents: Asia (China,
133 Singapore, South Korea, Thailand, Iran), Europe (Finland, Sweden, France, Bulgaria, Romania,



134 Poland, Germany, Russia), Africa (Nigeria), North America (USA, Canada), and Australia.
 135 Representative soil environments are shown: (a-1) wide-graded debris-flow deposits (Jiangjia Gully,
 136 Southwest China); (a-2) arable land (Sweden); (a-3) gully terrain (Nigeria); (a-4) canyon (USA);
 137 and (a-5) coastal beach (Australia). (b) Sampling locations of lunar soils, predominantly collected
 138 near spacecraft landing sites. The insets show surface images from Apollo 15, CE-5, and CE-6, with
 139 mission dates annotated. The topographic basemap is the Lunar Reconnaissance Orbiter Laser
 140 Altimeter (LRO LOLA) color shaded relief (388 m resolution). Images courtesy of the China
 141 National Space Administration (CNSA). (c) Sampling locations of Martian soils across four distinct
 142 regions, with insets showing overviews of Gale and Jezero Craters. The basemap is the Mars Orbiter
 143 Laser Altimeter (MOLA) shaded relief topography. Images courtesy of NASA.

144
 145 [Table 1](#) summarizes the key characteristics of the three planetary datasets, including sample
 146 size, geographic coverage, analytical methods, grain-size ranges, and data sources. [Table 2](#) provides
 147 detailed information for each sampling site, including sample counts, dominant soil types, and
 148 associated surface processes.

149
 150 **Table 1.** Summary of the PlanetGSD dataset by planetary body

Compon ent	Sampl e size	Geographic / landing-site coverage	Analytical method	Grain-si ze range (mm)	Primary data sources
Earth	4,419	18 countries on 5 continents; 20 geomorphic settings	Combined sieving (≥ 0.25 mm) + laser diffraction (< 0.25 mm)	0.0001– 20	Field campaigns (2015–2023); 43 peer-reviewed publications
Moon	379	8 sample-return missions (Apollo 11,12,14,15,16,17; Luna 16,20,24; Chang'e-5,-6)	Dry sieving	0.001– 10	Graf (1993); Heiken et al. (1991); Zhang et al. (2022); Li et al. (2024)
Mars	1,729	4 rover landing sites (Gale, Jezero, Gusev, Meridiani)	Image-based grain segmentation (MAHLI, WATSON, MI, Mastcam, Mastcam-Z, RMI)	0.04–25	New analysis of PDS imagery (this study)



151 **Table 2.** Sampling sites, sample counts, dominant soil types, and associated surface processes

Planet	Site / Region	Sample count	Dominant soil types	Associated surface processes	
Earth	Jiangjia Gully (China)	438	Debris-flow deposits	Gravity-driven mass movements	
	Minjiang River (China)	825	Fluvial deposits	Fluvial transport and deposition	
	Xichang (China)	960	Vegetated soils	Pedogenesis, root-soil interaction	
	Horqin (China)	65	Grassland soils	Aeolian erosion, biotic processes	
	Tibet (China)	107	Alpine meadow soils	Cryogenic processes	
	Kunlun Mountains (China)	21	Permafrost and desert soils	Cryogenic, aeolian	
	Malipo (China)	570	Red soils	Chemical weathering, pedogenesis	
	Nevada (USA)	120	Desert soils	Aeolian erosion, arid weathering	
	Michigan (USA)	31	Sandy soils	Glacial, coastal processes	
	California (USA)	38	Coastal plain soils	Fluvial, coastal	
	Canada	41	Fine loamy soils	Glacial, pedogenic	
	Finland	108	Forest soils	Pedogenic, cryogenic	
	Sweden	35	Arable soils	Agricultural, pedogenic	
	Germany	40	Brown soils	Pedogenic	
	France	45	Various soils	Fluvial, pedogenic	
	Bulgaria	21	Agricultural soils	Pedogenic	
	Poland	14	Forest soils	Pedogenic	
	Romania	30	River plain soils	Fluvial	
	Russia	32	Forest and plain soils	Pedogenic, fluvial	
	Nigeria	15	Agricultural soils	Pedogenic, tropical weathering	
	Australia	20	Coastal soils	Coastal, aeolian	
	Singapore	32	Granite-derived soils	Tropical weathering	
	South Korea	12	Red-yellow soils	Pedogenic	
	Japan	42	Volcanic, forest soils	Volcanic, pedogenic	
	Thailand	28	Siliceous soils	Tropical weathering	
	Iran	35	Aeolian, marine sediments	Aeolian, coastal	
	Moon	Apollo 11	21	Mare basaltic regolith	Impact comminution, space weathering
		Apollo 12	20	Mare basaltic regolith	Impact comminution, space weathering
		Apollo 14	26	Highland ejecta	Impact comminution,



				mixing
	Apollo 15	63	Mare-highland boundary	Impact comminution
	Apollo 16	5	Highland regolith	Impact comminution, multi-source mixing
	Apollo 17	43	Mare-highland contact	Impact comminution
	Luna 16	-	Mare basaltic regolith	Impact comminution
	Luna 20	-	Highland regolith	Impact comminution
	Luna 24	-	Mare basaltic regolith	Impact comminution
	Chang'e-5	1	Mare basaltic regolith	Impact comminution, space weathering
	Chang'e-6	1	Farside SPA basin	Impact comminution
Mars	Gale Crater (11 sub-sites)	384	Lacustrine, aeolian, fluvial	Lake sedimentation, aeolian transport
	Jezero Crater (8 sub-sites)	722	Deltaic, lacustrine, volcanic	Delta deposition, lake environment
	Gusev Crater (10 sub-sites)	366	Volcanic, aeolian, hydrothermal	Flooding, volcanism, alteration
	Meridiani Planum (6 sub-sites)	257	Sulfate-rich, aeolian	Evaporite deposition, aeolian transport

152

153 2.2 Data acquisition methods

154 2.2.1 Field sampling (Earth)

155 Terrestrial field samples (2,847) were collected during campaigns conducted between 2015 and
 156 2023 across 18 countries on five continents (Fig. 1a; Supplementary Tables S1–S5). Sampling
 157 targeted the upper 10 cm of the surface layer to ensure consistency with the actively weathering
 158 zone and to facilitate comparison with orbital remote sensing data. At vegetated sites, surface
 159 organic litter was removed prior to sampling.

160 The sampling strategy was tailored to geomorphic context: systematic grid-based transects for
 161 homogeneous terrain (plains, grasslands, deserts) and targeted sampling of distinct geomorphic units
 162 for heterogeneous environments (debris-flow deposits, landslides, moraines). Individual sample



163 mass ranged from 200 g to 2 kg (median 500 g) to ensure sufficient material for grain-size analysis
164 and representative sampling of heterogeneous deposits. Samples were sealed in polyethylene bags
165 with GPS coordinates recorded, transported to the laboratory, and stored at 4°C prior to analysis.

166 All field-collected samples were processed following standardized protocols (BS 1377-2,
167 ASTM D422-63, ASTM D6913-04, ISO 11277:2009) using combined sieving and laser diffraction
168 methods, as detailed in [Section 2.3.1](#). Complete instrument specifications and quality control
169 procedures are provided in [Text S1](#). No additional replicate analyses or certified reference material
170 measurements were performed specifically for this study.

171 **2.2.2 Literature compilation (Earth and Moon)**

172 **Terrestrial literature data.** In addition to field-collected samples, we compiled grain-size
173 distribution data for 1,572 terrestrial samples from 43 peer-reviewed publications. These samples
174 expand the geographic and environmental coverage of the terrestrial component, including soils
175 from Europe (Finland, Sweden, France, Germany, Poland, Romania, Russia), North America (USA,
176 Canada), Asia (China, Japan, South Korea, Thailand, Iran), Australia, and Africa (Nigeria). The
177 compiled data represent diverse surface environments such as forested hillslopes, agricultural lands,
178 grassland soils, desert regions, coastal zones, and loess-mantled terrains, complementing the field-
179 collected samples and enhancing the representation of major process regimes ([Text S2](#)).

180 **Lunar mission data.** Lunar grain-size distributions were compiled from eight sample-return
181 missions (Apollo, Luna, Chang'e) spanning 1969–2024. Data were digitized from the NASA Lunar
182 Soils Grain Size Catalog (Graf, [1993](#)) for Apollo and Luna samples, and from mission-specific
183 publications for Chang'e-5 (Zhang et al., [2022](#)) and Chang'e-6 (Li et al., [2024](#)). All lunar samples
184 were originally analyzed using standardized dry sieving protocols. Detailed mission information,



185 sample counts, and metadata are provided in [Table 1](#) and [Table S6](#).

186 **2.2.3 Image-based analysis (Mars)**

187 Martian GSD data were derived from high-resolution rover images for 1,729 sampling targets
188 at four NASA landing sites: Gale Crater (Curiosity), Jezero Crater (Perseverance), Gusev Crater
189 (Spirit), and Meridiani Planum (Opportunity). All images were obtained from NASA's Planetary
190 Data System (PDS) Imaging Node (<https://pds-imaging.jpl.nasa.gov/>). Source image identifiers
191 (PDS Product IDs) for all 1,729 samples are provided in [Dataset S3](#).

192 **Imaging systems.** Grain-size measurements utilized both arm-mounted close-range imagers
193 and mast-mounted cameras. Close-range systems include the Mars Hand Lens Imager (MAHLI) on
194 Curiosity (Edgett et al., 2012), the Wide Angle Topographic Sensor for Operations and engineering
195 (WATSON) on Perseverance, and the Microscopic Imager (MI) on Spirit and Opportunity
196 (Herkenhoff et al., 2004). These instruments achieve pixel scales of 13–32 μm at working distances
197 of 2–5 cm, enabling resolution of sand-sized grains down to approximately 40 μm . Mast-mounted
198 systems—Mastcam on Curiosity (Bell et al., 2017), Mastcam-Z on Perseverance (Bell et al., 2021),
199 and SuperCam Remote Micro-Imager (RMI) on Perseverance (Maurice et al., 2021; Wiens et al.,
200 2021)—provide pixel scales of 74–450 μm depending on focal length and target distance, limiting
201 grain-size resolution to medium sand and coarser fractions ($>150 \mu\text{m}$). [Table 3](#) summarizes the key
202 characteristics, resolution limits, and detection thresholds for all imaging systems used in this study.

203 **Image selection and analysis.** A total of 2,160 images meeting quality criteria (known target
204 distance, viewing angle $<30^\circ$ from vertical, solar elevation $>20^\circ$) were selected from the PDS
205 archive. Grain-size distributions were measured using semi-automated image segmentation
206 software developed by Shi et al. (2021) and Zhao et al. (2023), implemented in Mathematica. The



207 software identifies individual grains through edge detection and watershed segmentation, calculates
 208 equivalent circular diameter (ECD) for each grain, and constructs cumulative size distributions after
 209 binning into logarithmic size classes. For each image, 150–500 grains (median 280) were segmented.
 210 The geographic distribution of all four landing sites is shown in [Figure 2](#). Complete image selection
 211 criteria, analysis protocols, resolution limits, and uncertainty estimates are provided in [Text S3](#).

212

213 **Table 3.** Martian rover imaging systems and grain-size detection limits

Instrument	Rover(s)	Type	Pixel scale ($\mu\text{m}/\text{pixel}$)	Working distance	Min. detectable grain size (mm)	Reference
MI (Microscopic Imager)	Spirit, Opportunity	Arm- mounted	31 (fixed)	6.8 cm (fixed)	0.1	Herkenhoff et al., 2004
MAHLI (Mars Hand Lens Imager)	Curiosity	Arm- mounted	13.9–21.7	1.9–25 cm	0.04	Edgett et al., 2012
WATSON	Perseverance	Arm- mounted	~14	~2–20 cm	0.04	Beegle et al., 2015
Mastcam (M- 100)	Curiosity	Mast- mounted	74–220	1–10 m	0.22	Bell et al., 2017
Mastcam-Z (left)	Perseverance	Mast- mounted	148 (at 2 m)	0.5– ∞ m	0.44	Bell et al., 2021
RMI (SuperCam)	Perseverance	Mast- mounted	40 (at 2 m)	1.6– ∞ m	0.12	Maurice et al., 2021

214 **Note:** Min. detectable grain size $\approx 3 \times$ pixel scale, the minimum threshold for reliable grain boundary
 215 segmentation. Pixel scales are from instrument calibration references cited in the last column.

216

217 2.3 Grain-size analysis and harmonization

218 2.3.1 Analytical methods

219 The PlanetGSD dataset integrates grain-size distributions obtained through three
 220 fundamentally different analytical methods: combined sieving–laser diffraction (terrestrial field
 221 samples and literature), dry sieving (lunar missions), and image-based segmentation (Mars rovers).



222 [Table 4](#) summarizes the principles, grain-size ranges, advantages, and limitations of each method.

223

224 **Table 4.** Comparison of GSD analytical methods for grain-size determination across the three
225 planetary datasets

Methods	Principles	Grain-size range	Advantages	Limitations	Applied to
Combined sieving–laser diffraction	Sieving separates coarse fractions by physical passage through mesh; laser diffraction measures fine fractions by angular light scattering	0.0001–20 mm	Full size-range coverage (clay to gravel); high precision for fine fractions; standardized protocols (ASTM/ISO)	Time-intensive; requires laboratory access	Earth (field samples and literature)
Dry sieving	Mechanical shaking through nested sieve stacks	0.001–10 mm	Direct mass-based measurement; well-established for coarse sediments; large sample masses possible	Poor resolution for fines (<0.1 mm); clay fractions not resolved	Moon (all missions)
Image-based segmentation	Grain boundary detection from high-resolution images; equivalent circular diameter calculation	0.04–25 mm	In situ analysis; no sample return required; spatial context preserved	Truncated at fine end ($\geq 40 \mu\text{m}$); spherical grain assumption; 2D projection bias	Mars (rover images)

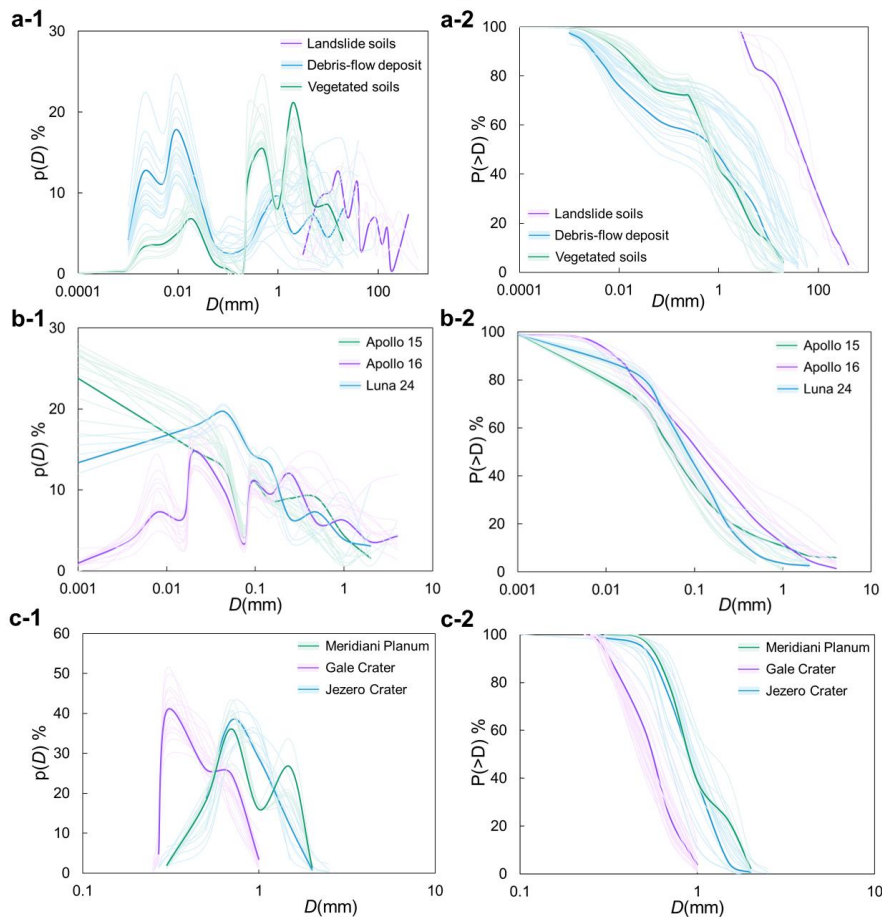
226

227 [Figure 2](#) shows representative grain-size distribution curves from each planetary body,
228 illustrating the range of shapes captured in the dataset. The terrestrial examples ([Fig. 2a](#)) include
229 poorly sorted landslide deposits, bimodal debris-flow materials, and finer-grained vegetated soils.
230 Lunar samples ([Fig. 2b](#)) show the relatively narrow, fine-grained distributions characteristic of
231 impact-comminuted regolith. Martian samples ([Fig. 2c](#)) exhibit intermediate characteristics, with
232 some sites showing aeolian sorting and others preserving primary sedimentary textures.

233 The diversity of grain-size curves across and within planetary bodies—ranging from unimodal
234 to multimodal distributions, with varying degrees of sorting and skewness—highlights the
235 complexity of natural granular materials. Traditional descriptors such as percentile-based indices
236 (D_{10} , D_{50} , D_{90}) or unimodal distribution models (e.g., lognormal, Weibull) are insufficient to capture
237 this variability in a standardized manner, particularly for cross-planetary comparison where



238 analytical methods and size ranges differ fundamentally. To address this limitation, we employ the
239 Universal Grain-Size Distribution (UGSD) function (Section 2.3.2), which provides a flexible, four-
240 parameter formulation capable of representing diverse curve shapes within a unified framework,
241 enabling systematic comparison of granular characteristics across Earth, the Moon, and Mars.
242



243
244 **Figure 2.** Representative grain-size distribution curves from each planetary body. Left column:
245 frequency curves; right column: cumulative probability curves. (a) Terrestrial: landslide deposits,
246 debris-flow deposits, and vegetated soils; (b) Lunar: Apollo 15, Apollo 16, and Luna 24; (c)
247 Meridiani Planum, Gale Crater, and Jezero Crater.



248

249 **2.3.2 Data harmonization**

250 Cross-planetary comparison requires harmonization of data collected using different methods
251 with distinct size ranges and bin resolutions. Rather than applying interpolation or re-binning which
252 could introduce artifacts, we employ the UGSD function to the measured GSD data.

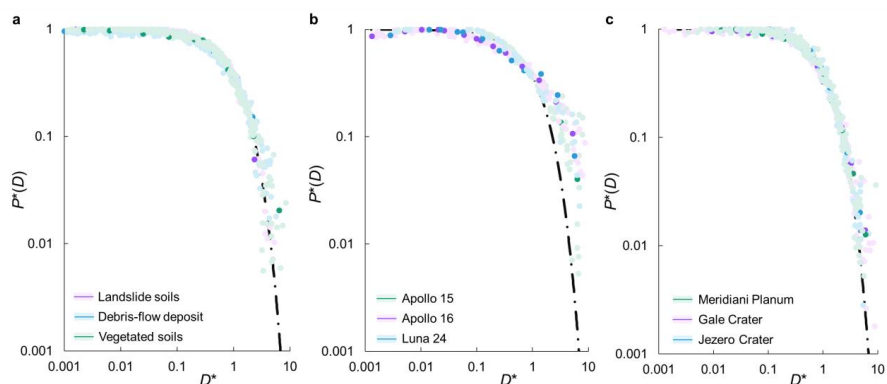
253 The Universal Grain-Size Distribution (UGSD) function, developed and validated in our
254 previous work (Yong et al., 2013, 2017; Zhang et al., 2023, 2025), describes the cumulative GSD
255 as:

$$256 \quad P(D) = f(\mu)D^{-\mu} \exp(-(D/D_c)^n) \quad (3)$$

257 where μ is a power exponent positively correlated with fine-particle content, D_c is the characteristic
258 grain size, the normalized coefficient $f(\mu) = a \exp(-b\mu)$, with empirically determined constants a and
259 b ; and n is a shape exponent controlling the coarse-tail steepness.

260 All 6,527 samples were fitted to the UGSD function (Eq. 3) using nonlinear least-squares
261 optimization. Figure 3 shows the rescaled UGSD curves for Earth (a), Moon (b), and Mars (c),
262 demonstrating the unified fitting performance across planetary bodies. Median R^2 values are 0.991
263 (Earth), 0.989 (Moon), and 0.983 (Mars), with 97.8% of all samples yielding $R^2 > 0.95$ (Table 9).
264 The terrestrial and lunar populations exhibit strongly left-skewed R^2 distributions, with >85% of
265 samples achieving $R^2 > 0.98$. The slightly lower Martian median is attributable to the truncation of
266 the fine tail below ~0.04–0.15 mm imposed by imaging resolution limits (Table 3), which reduces
267 the number of constraining data points available for curve fitting.

268



269

270 **Figure 3.** Rescaled UGSD fitting performance across the three planetary bodies. Each panel shows
 271 all measured cumulative GSD curves collapsed onto dimensionless axes by normalizing grain size
 272 D by the fitted characteristic size D_c and plotting the rescaled cumulative percentage $P(>D)/f(\mu)$
 273 against $(D/D_c)^n$. (a) Earth; (b) Moon; (c) Mars.

274

275 All samples included in the dataset contain sufficient size fractions for reliable UGSD fitting
 276 (minimum five data points per sample). For curves truncated at coarse or fine ends (e.g., Martian
 277 samples missing fractions $<40 \mu\text{m}$), fitting is performed on the available portion, and truncation
 278 thresholds are documented in the metadata (Dataset S4). Complete quality control protocols and
 279 uncertainty estimate for all datasets are provided in Texts S1–S4. Parameter definitions and typical
 280 ranges for the dataset are summarized in Table 5.

281 Comparison with alternative parameterizations. To demonstrate the advantage of the UGSD
 282 function, we fitted all 6,527 samples to three alternative models (lognormal, Rosin-Rammler, and
 283 Fredlund three-parameter) and found that UGSD achieved higher median R^2 values than all three
 284 alternatives (Table S10).

285

286 **Table 5.** UGSD function parameters

Parameter	Symbol	Description	Typical range
-----------	--------	-------------	---------------



Power exponent	μ	Correlated with fine-particle content	0.01–3.5
Characteristic size	D_c	Representative grain diameter (mm)	0.01–20
Shape exponent	n	Controls coarse-tail steepness	0.1–2.0

287

288 2.4 Probability Distribution of UGSD Parameters

289 The UGSD parameters (μ , D_c , n) exhibit natural spatial variability across sampling sites,
 290 reflecting the inherent heterogeneity of granular materials under different surface processes. Among
 291 these, the exponent μ —which correlates positively with fine-particle content—serves as the most
 292 sensitive indicator of local textural characteristics and is therefore the primary focus of our
 293 probabilistic analysis. The characteristic size D_c also varies spatially and its distribution can be
 294 analyzed similarly, while the shape exponent n primarily reflects broad-scale differences between
 295 planetary bodies or major process regimes (e.g., $n \approx 1$ for Earth and Moon, $n > 1$ for Mars) and is
 296 not considered for site-scale probability distributions.

297 At the site level, the population of μ values was found to follow the three-parameter Weibull
 298 distribution:

$$299 f(\mu; \lambda, k, \mu_0) = \frac{k}{\lambda} \left(\frac{\mu - \mu_0}{\lambda} \right)^{k-1} \exp \left(- \left(\frac{\mu - \mu_0}{\lambda} \right)^k \right) \quad (4)$$

300 where μ_0 is the location parameter (minimum μ value), λ is the scale parameter (characteristic
 301 spread), and k is the shape parameter (controlling distribution tail behavior). The three-parameter
 302 form was adopted because it provides greater flexibility than the two-parameter version,
 303 accommodating potential shifts in the minimum μ value that may arise from site-specific
 304 depositional or weathering histories. Fitting was performed using maximum likelihood estimation
 305 (`scipy.stats.weibull_min.fit` in Python).



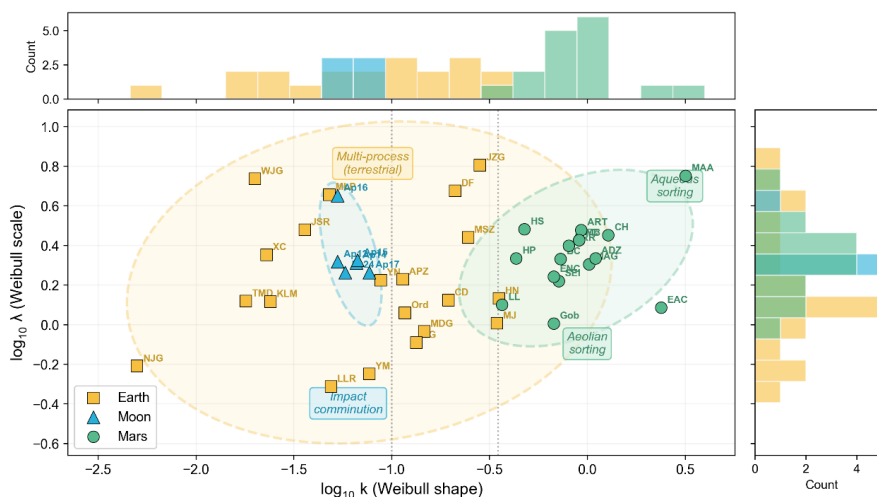
306 [Table 6](#) summarizes the ranges of fitted Weibull parameters across the three planetary bodies,
 307 and [Figure 4](#) displays the site-level (k, λ) points for all 42 locations. One sees distinct point groups
 308 for the three planetary bodies, supporting the utility of the k - λ parameter pair as a diagnostic
 309 descriptor for cross-planetary comparison. Complete site-level Weibull parameters, including
 310 geological context and dominant process annotations, are provided in [Dataset S4 \(Sheet 2\)](#).

311

312 **Table 6.** Weibull parameter ranges by planetary body

Planet	sites	k range	λ range	μ_0 range
Moon	6	0.053–0.077	1.83–4.48	0–0.028
Earth	20	0.005–0.354	0.49–6.38	0–0.294
Mars	16	0.367–3.180	1.01–5.64	0–3.142

313



314

315 **Figure 4.** Weibull k - λ parameter space for PlanetGSD 1.0 sites. Site-level data points are shown for
 316 Earth (squares, 20), Moon (triangles, 6), and Mars (circles, 16). Marginal histograms show the
 317 distribution of k (top) and λ (right) for each planetary body.

318

319 2.5 From GSD measurements to random parameter fields

320 The preceding sections established a two-step transformation of raw grain-size measurements



321 into a unified probabilistic framework (Fig. 5). First, the UGSD function converts the original GSD
322 curves of all 6,527 samples into a compact set of interpretable parameters (μ , D_c , n), reducing high-
323 dimensional textural data to physically meaningful indices (Section 2.3). Second, at each sampling
324 site, the population of μ values is characterized by a three-parameter Weibull distribution (Section
325 2.4), capturing the local spatial variability of fine-particle content in a probabilistic form.

326 This transformation fundamentally changes the nature of the dataset: from a conventional
327 collection of discrete observations to a probabilistic parameter library of grain-size distributions. In
328 this library, each site is represented not by individual measurements but by the probability
329 distribution of its granular characteristics (μ_0 , k , λ), enabling stochastic simulation and extrapolation
330 beyond the original sampling locations.

331 The probabilistic parameterization naturally leads to the concept of granular fields—spatially
332 continuous representations of soil heterogeneity derived from the site-level Weibull parameters.
333 Following the workflow of Zhang et al. (2022), μ -fields are generated through a three-step Monte
334 Carlo procedure:

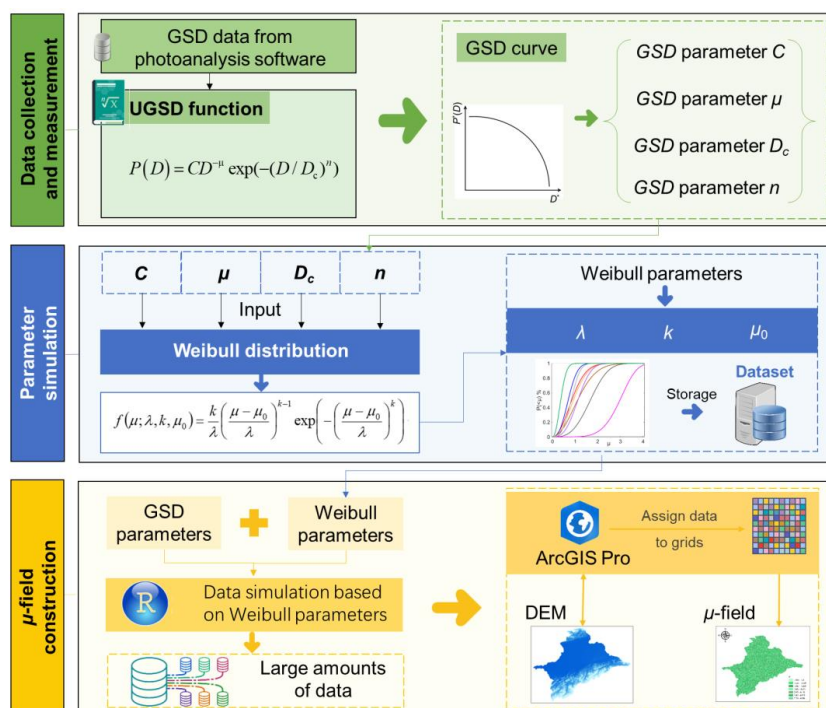
- 335 1. UGSD fitting of measured GSD data to obtain μ for each sample (as described in Section
336 2.3).
- 337 2. Weibull parameterization and Monte Carlo simulation – For each sampling site, the
338 population of μ values is fitted to the three-parameter Weibull distribution (Section 2.4).
339 An ensemble of N random μ values is then generated by sampling from this fitted
340 distribution, with N specified by the user (default $N = 1,000$).
- 341 3. Spatial interpolation – The simulated μ values are assigned to a Digital Elevation Model
342 (DEM)-registered grid via inverse-distance-weighted (IDW) interpolation (power = 2).



343 Users can specify DEM resolution, interpolation radius, and the number of Monte Carlo
 344 realizations.

345 The resulting μ -fields provide spatially explicit estimates of grain-size characteristics that
 346 preserve local heterogeneity while enabling upscaling to regional scales. Because soil properties
 347 such as porosity, permeability, and shear strength can be expressed as functions of μ (Jiang et al.,
 348 2024), these granular fields can be further transformed into property fields for hydro-geophysical
 349 modeling, rover mobility simulation, or in-situ resource utilization assessment. The complete
 350 workflow, from raw measurements to μ -fields, is illustrated in Figure 5, and the implementation
 351 codes are provided in Code S1–S3.

352



353

354 **Figure 5.** Workflow for generating spatially continuous μ -fields from raw GSD measurements. The
 355 process involves three stages: (1) UGSD fitting to extract μ for each sample; (2) Weibull



356 parameterization of site-level μ populations and Monte Carlo simulation of random μ values; (3)
357 IDW interpolation onto DEM grids to produce continuous μ -fields. This transformation converts
358 conventional observational data into a probabilistic parameter library, enabling stochastic simulation
359 and cross-site comparison.

360

361 **3. GSD Dataset Construction**

362 The UGSD function has harmonized the textural data to a set of analytical parameters (μ , D_c ,
363 n), while preserving the integrity of the measurements. This allows to construct a new-type dataset
364 of soil from the traditional measured data of texture or moisture of soils.

365 **3.1 Database structure and file inventory**

366 **3.1.1 Folder organization**

367 All datasets are provided in Microsoft Excel format (.xlsx) to accommodate multi-sheet
368 structures that organize GSD curves, metadata, and quality flags within single files. The complete
369 PlanetGSD 1.0 database is organized in a hierarchical folder structure with separate directories for
370 data files, analysis codes, and documentation:

```
371 PlanetGSD_v1.0.0/  
372 |-- data/  
373 |-- codes/  
374 |-- README.txt
```

375 **3.1.2 File inventory**

376 A complete inventory of all files in the PlanetGSD 1.0 repository is provided in [Table 7](#),
377 including file names, sizes, and brief descriptions.

378

379 **Table 7.** File inventory for PlanetGSD 1.0

File	Size	Description
------	------	-------------



S1_GSD_data_from_Earth.xlsx	145 KB	Raw cumulative GSD curves for 4,419 terrestrial samples, with geographic coordinates and metadata
S2_GSD_data_from_Moon.xlsx	36 KB	Raw cumulative GSD curves for 379 lunar samples, with mission identifiers and sample metadata
S3_GSD_data_from_Mars.xlsx	3,579 KB	Raw cumulative GSD curves for 1,729 Martian samples, with PDS image source IDs and geological context
S4_UGSD_parameters_and_Weibull.xlsx	107 KB	Two-sheet file: (Sheet 1) UGSD fitted parameters for all 6,527 samples; (Sheet 2) site-level Weibull statistics for 42 locations
S5_Mars_image_reference_numbers.xlsx	25 KB	Complete list of NASA PDS Product IDs for all 1,729 rover images used
S1_mu_field_generation.m	-	MATLAB code for stochastic μ -field generation
S2_UGSD_fitting.R	-	R code for data pre-processing and UGSD parameterization
S3_Weibull_fitting.py	-	Python code for Weibull distribution fitting and diagnostic plots
README.txt	-	Detailed dataset documentation, version history, and contact information

380

381 3.2 Database structure overview

382 The PlanetGSD 1.0 database is organized into five core [datasets \(S1–S5\)](#), each containing raw

383 GSD measurements, fitted parameters, and associated metadata:

- 384 • Dataset S1 (Earth GSD) contains 4,419 terrestrial grain-size distributions with complete
 385 cumulative curves (17 size fractions from 0.0001 to 20 mm) and georeferenced metadata,
 386 integrating field-collected samples (2,847) and literature-derived data (1,572).
- 387 • Dataset S2 (Lunar GSD) comprises 379 lunar grain-size distributions from eight sample-
 388 return missions (Apollo, Luna, Chang'e), with 9–15 size fractions per sample depending
 389 on mission protocol.
- 390 • Dataset S3 (Mars GSD) provides 1,729 grain-size distributions derived from semi-



391 automated analysis of 2,160 rover images, with 8 logarithmic size bins (0.04–25 mm) and
392 full PDS image traceability.

393 • Dataset S4 (UGSD and Weibull parameters) contains fitted UGSD parameters (C , μ , D_c ,
394 n) for all 6,527 samples (Sheet 1) and site-level three-parameter Weibull statistics (μ_0 , k ,
395 λ) for 42 sampling locations (Sheet 2), with quality flags and geological context
396 annotations.

397 • Dataset S5 (Mars image reference numbers) provides the complete list of NASA PDS
398 Product IDs for all 1,729 rover images, ensuring full traceability to original mission data.

399 All datasets are provided in Microsoft Excel format (.xlsx) with multi-sheet structures to
400 organize raw data, metadata, and quality flags within single files. Users are referred to the Figshare
401 repository Zhang (2026) for direct data access.

402 3.3 Data dictionary

403 To facilitate correct interpretation and usage of the PlanetGSD 1.0 datasets, Table 8 provides
404 complete field definitions for all variables appearing in Datasets S1–S5. The table includes field
405 names, descriptions, data types, units, and example values, serving as a detailed reference to
406 complement the database structure overview in Section 3.2.

407

408 **Table 8.** Data dictionary for PlanetGSD 1.0

Field	Description	Type	Unit	Example
sample_id	Unique sample identifier	String	—	Earth_DF_001
planet	Planetary body	String	—	Earth / Moon / Mars
site_name	Sampling site or mission name	String	—	Jiangjia Gully
latitude	Sampling latitude	Float (Decimal Degrees)	degrees	26.253
longitude	Sampling longitude	Float	degrees	103.117
elevation	Sampling elevation (Earth only)	Float	m	1,450
geomorphic_setting	Depositional or surface environment	String (Free text, see Table S9 for controlled vocabulary)	—	Debris flow



$D_{0.0001}$ to D_{20}	Cumulative mass percentage passing each size	Float (%)	%	2.3, 5.1, ...
$n_{\text{fractions}}$	Number of reported size fractions	Integer	—	17
data_source	Original data source	String	—	Field / Graf (1993)
μ	UGSD location parameter	Float	—	0.35
D_c	UGSD characteristic grain size	Float	mm	0.82
n	UGSD shape exponent	Float	—	0.48
R^2	Coefficient of determination for UGSD fit	Float	—	0.994
quality_flag	Data quality indicator	Integer (1 = good, 0 = flagged, 2 = excluded)	—	1 (good) / 0 (flagged)

409

410 4. Technical Validation

411 The validation of PlanetGSD 1.0 was conducted through a four-step procedure: (1) assessing
 412 UGSD fitting quality across all 6,527 samples; (2) evaluating Weibull parameterization quality at
 413 the site level; (3) verifying compiled data against original source publications; and (4) assessing
 414 inter-operator reproducibility for Martian image-derived measurements.

415 4.1 UGSD fitting quality

416 All 6,527 samples were fitted to the UGSD function (Eq. 3) using nonlinear least-squares
 417 optimization. Goodness-of-fit was quantified using the coefficient of determination (R^2). Figure 3
 418 shows the rescaled UGSD curves for Earth (a), Moon (b), and Mars (c), demonstrating the unified
 419 fitting performance across planetary bodies.

420 Median R^2 values are 0.991 (Earth), 0.989 (Moon), and 0.983 (Mars), with 97.8% of all
 421 samples yielding $R^2 > 0.95$ (Table 9). The terrestrial and lunar populations exhibit strongly left-
 422 skewed R^2 distributions, with >85% of samples achieving $R^2 > 0.98$. The slightly lower Martian
 423 median is attributable to the truncation of the fine tail below ~0.04–0.15 mm imposed by imaging
 424 resolution limits, which reduces the number of constraining data points available for curve fitting.

425 Following the outlier screening protocol (Section 2.3.2), 23 samples (0.4% of total) with $R^2 <$



426 0.94 were excluded after manual review due to data-entry errors or highly irregular curve shapes
427 inconsistent with natural GSD. An additional 24 samples (0.4%) with $0.90 < R^2 < 0.94$ were retained
428 but flagged (`quality_flag = 0`) in [Dataset S4](#) for user awareness. The remaining 6,480 samples
429 (99.3%) carry `quality_flag = 1` and are recommended for analysis without restriction.

430 Comparison with alternative parameterizations. To demonstrate the advantage of the UGSD
431 function, we fitted all 6,527 samples to three alternative models (lognormal, Rosin-Rammler, and
432 Fredlund three-parameter) and found that UGSD achieved higher median R^2 values than all three
433 alternatives ([Table S10](#)).

434

435 **Table 9.** UGSD fitting quality statistics

Planet	samples	Median R^2	Mean R^2	% with $R^2 >$ 0.95	% with $R^2 <$ 0.90	K-S test pass rate
Earth	4,419	0.991	0.987	98.5	0.3	98.2%
Moon	379	0.989	0.985	97.9	0.5	97.1%
Mars	1,729	0.983	0.978	96.2	1.1	94.8%
Total	6,527	0.988	0.984	97.8	0.5	97.3%

436 Kolmogorov-Smirnov test at significance level $\alpha = 0.05$; pass rate indicates percentage of samples
437 where the UGSD fit is not significantly different from the measured distribution ($p > 0.05$).

438

439 **4.2 Weibull parameterization quality**

440 Three-parameter Weibull distributions were fitted to site-level μ populations for all 42 sites (20
441 Earth, 6 Moon, 16 Mars). Fit quality was assessed using two complementary approaches: the
442 Kolmogorov-Smirnov (K-S) goodness-of-fit test at significance level $\alpha = 0.05$, and visual inspection
443 of Q-Q (quantile-quantile) plots comparing observed μ quantiles against theoretical Weibull
444 quantiles.

445 Of the 42 sites, 39 (93%) passed the K-S test, indicating that the three-parameter Weibull



446 model adequately describes the μ population structure at most sampling locations. The three sites
447 that did not pass are all terrestrial (MJ, DF, JZG) and exhibit bimodal μ distributions attributable
448 to the mixing of geomorphically distinct lithological units within a single sampling area. Their
449 Weibull parameters are retained in [Dataset S4 \(Sheet 2\)](#) with explanatory notes in the
450 geological_description field; users may choose to exclude these sites or to fit separate Weibull
451 distributions to the identified sub-populations.

452 **4.3 Verification against published values**

453 To verify the accuracy of compiled and processed data, we cross-checked subsets of samples
454 from each planetary body against original source publications. This procedure tests for systematic
455 errors introduced during data transcription, digitization, and processing.

456 **(1) Lunar samples.** Median grain sizes (D_{50}) for 50 Apollo samples were compared with
457 values reported in the Lunar Sourcebook (Heiken et al., 1991). The mean absolute deviation between
458 our compiled values and the Lunar Sourcebook was $4.2 \mu\text{m}$ (range: $0.3\text{--}11.8 \mu\text{m}$), within the
459 reported measurement uncertainty of $\pm 5 \mu\text{m}$ for the original sieving analyses (Graf, 1993). No
460 systematic bias was observed (mean signed deviation: $+0.8 \mu\text{m}$), confirming that digitization from
461 the NASA Lunar Soils Grain Size Catalog did not introduce directional errors.

462 **(2) Martian samples.** D_{50} values for 30 Gale Crater samples were compared with those
463 reported by Fedo et al. (2015) and Weitz et al. (2018) for overlapping locations. The mean absolute
464 deviation was 0.08 mm (range: $0.01\text{--}0.22 \text{ mm}$), consistent with the inter-operator variability of $\pm 15\%$
465 documented for image-based grain-size measurements (see [Section 4.4](#)). No systematic offset was
466 detected between our measurements and published values (mean signed deviation: -0.02 mm).

467 **(3) Terrestrial samples.** For 100 randomly selected literature-derived samples with data



468 available in the original publications, we verified cumulative grain-size percentages at the D_{10} , D_{50} ,
469 and D_{90} percentile levels. All values matched within rounding error (mean absolute difference: 0.3%;
470 maximum: 0.8%). For the subset of 127 samples where original studies used hydrometer rather than
471 laser diffraction methods, clay content ($<2 \mu\text{m}$) agreed within $\pm 2.1\%$ (mean absolute deviation)
472 when cross-validated against laser diffraction measurements in overlapping datasets, consistent with
473 known inter-method variability (Konert & Vandenberghe, 1997).

474 These checks confirm that data transcription and processing introduced no systematic errors
475 into PlanetGSD 1.0.

476 4.4 Inter-operator reproducibility of Martian measurements

477 Because all Martian GSD data were derived from semi-automated image analysis, inter-
478 operator variability represents an important component of measurement uncertainty. To quantify
479 this variability, three independent analysts processed identical image sets ($n = 30$ images spanning
480 all four landing sites) using the same grain-segmentation software (Shi et al., 2021; Zhao et al.,
481 2023).

482 Results are summarized in Table 10. Inter-operator agreement was assessed using three metrics:
483 (i) the coefficient of variation (CV) of D_{50} across the three analysts; (ii) the mean absolute
484 percentage difference in cumulative grain-size fractions; and (iii) the resulting variation in fitted
485 UGSD parameters.

486

487 **Table 10.** Inter-operator reproducibility for Martian image-based grain-size measurements ($n = 30$
488 images, 3 analysts)

Metric	Mean	Range	Notes
CV of D_{50}	8.30%	2.1– 18.7%	Higher CV for images with more grain overlap



Mean absolute % difference in cumulative fractions	6.20%	1.5–14.3%	Largest differences in finest resolvable fraction
CV of UGSD parameter μ	5.70%	1.2–12.4%	Propagated from grain boundary delineation differences
CV of UGSD parameter D_c	7.10%	2.3–15.8%	—
R^2 variation	± 0.008	0.001–0.021	Fitting quality robust to operator differences

489

490 The primary source of inter-operator variability is grain boundary delineation for overlapping
491 or partially obscured grains. Images with >30% grain overlap showed systematically higher CV
492 (mean: 14.2%) compared to images with <10% overlap (mean: 3.8%). This operator-dependent
493 uncertainty is propagated into the UGSD parameter confidence intervals reported in [Dataset S4](#).

494 These inter-operator variability estimates (CV \approx 5–8% for key parameters) are comparable to
495 those reported in previous Mars grain-size studies using similar methods (Fedo et al., 2015; Weitz
496 et al., 2018) and are substantially smaller than the inter-site variability observed across the four
497 Martian landing sites, confirming that measurement uncertainty does not obscure geological signal
498 in the dataset.

499 5. Illustrative applications and open questions

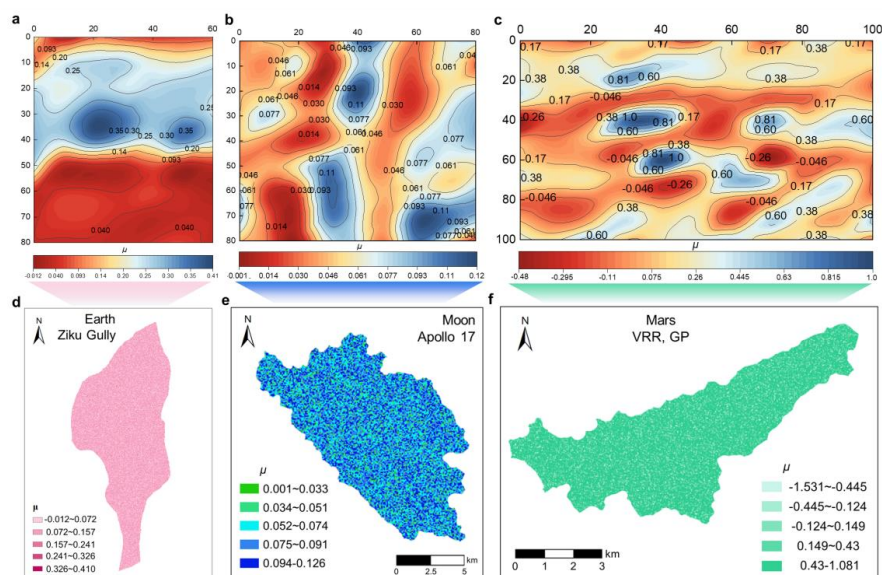
500 This section demonstrates three representative applications of PlanetGSD 1.0 and identifies
501 open questions for future research.

502 5.1 Cross-planetary comparison of GSD signatures and μ -field generation

503 The unified UGSD parameterization enables not only direct comparison of grain-size
504 characteristics across planetary bodies but also the generation of spatially continuous
505 representations of soil heterogeneity. Using the site-level Weibull statistics derived in [Section 2.4](#)
506 and the Monte Carlo workflow described in [Section 2.5](#), we generated μ -fields—spatially explicit



507 maps of the UGSD parameter μ —for three representative sites, one from each planetary body (Fig.
508 6).
509



510
511 **Figure 6.** Spatial distribution of the UGSD parameter μ across three planetary bodies. The top row
512 (a–c) shows μ -field maps for representative sites: (a) Ziku Gully, Earth; (b) Apollo 17 Taurus-
513 Littrow valley, Moon; (c) Vera Rubin Ridge–Greenheugh Pediment area, Gale Crater, Mars. The
514 bottom row (d–f) displays enlarged views of the corresponding areas at higher spatial resolution: (d)
515 Ziku Gully; (e) Apollo 17 site; (f) Vera Rubin Ridge–Greenheugh Pediment area.

516

517 The Ziku Gully (Earth) exhibits a spatially homogeneous μ -field (range = 0.422), consistent
518 with uniform pedogenic processes (Zhang et al., 2022). The Apollo 17 Taurus-Littrow valley (Moon)
519 shows fine-scale heterogeneity (~100 m) without persistent gradients (range = 0.125), reflecting
520 stochastic impact gardening as the dominant regolith-forming process (Zhang et al., 2025). The Vera
521 Rubin Ridge–Greenheugh Pediment area in Gale Crater (Mars) exhibits a pronounced spatial



522 gradient (range = 1.612) that correlates with mapped lithological boundaries, suggesting process-
523 dependent GSD zonation (Sullivan et al., 2022; Weitz et al., 2018).

524 These contrasting patterns—homogeneous (Earth), randomly heterogeneous (Moon), and
525 strongly graded (Mars)—reflect the dominant surface processes on each planetary body and
526 illustrate how the probabilistic parameterization of GSD data (Section 2.4) can be transformed into
527 spatially explicit representations of grain-size heterogeneity. Such μ -fields provide valuable input
528 layers for geotechnical modeling, rover mobility simulation, and landscape evolution studies. Users
529 can generate analogous fields for other sites using the provided codes (Code S1) and their own
530 digital elevation model (DEM) data.

531 For a complementary view of the parameter space itself, the distribution of all 6,527 samples
532 in μ - D_c space is provided in Figure S2, where the three planetary populations occupy largely distinct
533 domains: Earth spans the μ range (−0.012 to +0.41), Moon occupies a narrow near-zero range (0.001
534 to 0.126), and Mars displays the broadest μ range (−1.531 to +1.081). The non-overlapping Weibull
535 shape parameter k ranges (Table 10) further confirm systematic differences among the three bodies,
536 supporting the utility of the k - λ parameter pair as a diagnostic descriptor for cross-planetary
537 discrimination.

538 5.2 Regolith simulant benchmarking

539 PlanetGSD 1.0 provides reference GSD parameters against which lunar and Martian simulant
540 materials can be quantitatively evaluated. Users can compute the UGSD and Weibull parameters of
541 candidate simulants using the provided analysis codes (Codes S1–S3) and compare them with the
542 site-level parameter ranges documented in Dataset S4. For example, the Weibull parameters for
543 Apollo mare sites ($k = 0.053$ – 0.077 , $\lambda = 1.83$ – 4.48) define a target envelope for lunar simulants



544 intended to replicate mare regolith; simulants falling outside this envelope can be identified as
545 texturally non-representative. [Table 9](#) provides example analog matches linking target terrains to
546 PlanetGSD reference sites to facilitate such comparisons.

547 **5.3 Open questions and future directions**

548 PlanetGSD 1.0 opens several avenues for future research, but also has limitations that should
549 guide its use and development:

550 **(1) Spatial coverage gaps.** The terrestrial component is geographically biased toward Asia (73%
551 of samples). Lunar samples are predominantly from nearside mare regions. Martian samples are
552 limited to four low-latitude landing sites. Priority targets for future data collection include
553 underrepresented terrestrial environments (tropical forests, polar deserts, South America), lunar
554 farside and polar regions, and new Martian landing sites (e.g., Zhurong at Utopia Planitia).

555 **(2) Analytical resolution limits.** Martian GSD curves are right-censored below 40–150 μm
556 depending on imaging instrument, truncating the fine tail of distributions. Validation against in-situ
557 measurements from future sample-return missions will be essential to quantify systematic biases
558 introduced by this truncation.

559 **(3) Process attribution.** While μ shows strong empirical correlations with depositional
560 environments (e.g., $\mu > 1.0$ for aeolian-dominated settings; $\mu < 0.5$ for lag deposits), the mechanistic
561 links between UGSD parameters and specific surface processes remain incompletely understood.
562 Controlled experiments and coupled process models are needed to establish causal relationships.

563 **(4) Integration with remote sensing.** Orbital datasets (thermal inertia, hyperspectral
564 mineralogy, radar backscatter) provide indirect constraints on surface texture at global scales.
565 Calibrating these proxies against UGSD parameters could enable planetary-scale mapping of grain-



566 size characteristics beyond the spatial reach of rover-based measurements.

567 **(5) Climate change effects.** Long-term terrestrial GSD records may capture the influence of
568 changing precipitation patterns and temperature regimes on weathering and sediment transport.
569 Coupling PlanetGSD with climate datasets could provide insights into how surface processes
570 respond to environmental forcing—a question relevant to both Earth system science and interpreting
571 Martian paleoclimate records.

572 **6. Usage Notes**

573 **6.1 Recommended applications**

574 PlanetGSD 1.0 is designed to support the following research applications:

575 **(1) Comparative planetology.** The unified UGSD parameterization enables direct comparison
576 of grain-size signatures across Earth, Moon, and Mars. The $k - \lambda$ parameter domains ([Figure 4](#))
577 provide a quantitative framework for classifying samples by planetary provenance.

578 **(2) Regolith simulant benchmarking.** Lunar and Martian simulants can be quantitatively
579 compared with natural planetary materials by computing their UGSD and Weibull parameters using
580 [Codes S2](#) and [S3](#). [Dataset S4](#) provides reference parameter values for all sampled sites to facilitate
581 such comparisons.

582 **(3) Landing site assessment.** Pre-landing GSD estimates can be generated by identifying
583 PlanetGSD entries with geological context similar to candidate landing sites. [Table 11](#) provides
584 example analog matches to illustrate this approach.

585

586 **Table 11.** Example analog matches for landing-site GSD estimation

Target terrain	PlanetGSD analog	Analog k range	Analog λ range
Phyllosilicate-bearing	Gale Crater Murray formation	1.8–2.5	2.0–2.5



plains	(MAG, VRR)		
Olivine-rich volcanic terrain	Gusev Columbia Hills (LL, HP)	0.4–0.6	1.3–2.2
Sulfate-rich evaporites	Meridiani Planum	0.5–0.9	1.5–3.0
Deltaic deposits	Jezero Crater delta	1.0–1.5	2.0–4.0

587

588 **(4) Stochastic granular field generation.** Using [Code S1](#) and the fitted Weibull parameters
589 ([Dataset S4](#)), users can generate spatially continuous μ -fields for geotechnical modeling, rover
590 mobility simulation, or landscape evolution studies. The workflow accepts user-supplied DEM data
591 and outputs μ -fields as GeoTIFF files compatible with standard Geographic Information System
592 (GIS) software. Users can specify DEM resolution, interpolation radius, and the number of Monte
593 Carlo realizations.

594 **(5) Integration with remote sensing.** The μ -field framework provides sub-pixel grain-size
595 information that complements orbital datasets such as thermal inertia and radar backscatter.
596 Coupling μ -fields with geophysical transfer functions enables derivation of spatially continuous
597 porosity and cohesion estimates for engineering applications at future landing sites.

598 **6.2 Methodological guidance for users**

599 To ensure robust application of PlanetGSD 1.0, users should consider the following guidance:

600 **Parameter interpretation.** While the UGSD parameter μ correlates positively with fine-
601 particle content and the Weibull shape parameter k reflects the width of the μ distribution, these are
602 empirical descriptors derived from curve fitting. Direct translation of μ to physical quantities such
603 as porosity, permeability, or shear strength should be undertaken with caution. Such applications are
604 most robust when μ is coupled with complementary site-specific data or established geotechnical
605 transfer functions (e.g., Zhang et al., 2022; Jiang et al., 2024). The parameters are primarily intended
606 for comparative purposes—e.g., ranking sites by relative fineness or sorting—rather than for



607 absolute grain-size inference.

608 **Martian data handling.** All Martian GSD curves are right-censored below instrument-
609 specific resolution limits (Table 2). Users conducting analyses sensitive to the fine fraction (<0.1
610 mm) should treat cumulative percentages in the smallest size bin as lower bounds rather than
611 absolute values. For statistical applications, we recommend incorporating the truncation thresholds
612 (provided in Dataset S3 metadata) into uncertainty estimates. Sample-return measurements will be
613 essential for future validation of these image-derived GSDs.

614 **Lunar sample mass.** Lunar samples with mass <5 g are flagged (quality_flag = 0) in Dataset
615 S2 metadata due to potential sampling bias toward coarser fractions. Users requiring unbiased fine-
616 fraction statistics should apply mass-based filtering to retain only quality_flag = 1 samples.

617 6.3 Limitations and caveats

618 Users should be aware of the following limitations when using PlanetGSD 1.0:

619 **(1) Martian resolution limits.** All Martian GSD curves are right-censored below instrument-
620 specific detection limits (Table 2). Cumulative percentages in the fine tail represent lower bounds
621 rather than absolute values. This truncation contributes to lower UGSD fitting quality (median $R^2 =$
622 0.983) and may systematically affect Weibull parameter estimates.

623 **(2) Terrestrial sampling bias.** The terrestrial component is biased toward poorly sorted
624 deposits (debris flows, colluvium, moraines). Well-sorted aeolian dunes and littoral sands are
625 underrepresented. Users seeking to characterize these environments should supplement PlanetGSD
626 with dedicated datasets.

627 **(3) Lunar sample bias.** Lunar samples are predominantly from near-equatorial nearside mare
628 regions, with highland and farside materials underrepresented. This bias reflects the historical focus



629 of lunar exploration.

630 **(4) Temporal mixing in Martian data.** Martian samples span >3.5 Gyr of geological history.

631 Users should consider depositional age when interpreting GSD characteristics; temporal context is
632 provided in the metadata.

633 **(5) Parameter interpretation.** UGSD parameters are empirical descriptors derived from curve
634 fitting. While they enable robust comparative analyses, direct physical interpretation requires
635 caution and site-specific validation.

636 **(6) Spatial extrapolation.** The μ -fields generated using [Code S3](#) rely on inverse-distance-
637 weighted interpolation. In areas with sparse sampling or complex lithological boundaries,
638 interpolated values may not accurately represent local grain-size characteristics.

639 **6.4 Data updates and community contributions**

640 PlanetGSD is conceived as a living database that will evolve with new missions and
641 community input. Future versions (e.g., PlanetGSD 2.0) will incorporate:

- 642 • Additional terrestrial environments (aeolian dunes, glacial outwash, coastal sediments,
643 loess sequences);
- 644 • Samples from ongoing and future missions (Mars Sample Return, Artemis lunar samples,
645 OSIRIS-REx and Hayabusa2 asteroid samples);
- 646 • Extended grain-size ranges from improved analytical techniques;
- 647 • User-contributed datasets meeting quality standards.

648 Researchers wishing to contribute data should follow the standardized format:

- 649 • Complete cumulative grain-size percentages at standard size classes (or at original
650 measured sizes with clear documentation);



- 651 • Geographic coordinates (WGS84 for Earth, Moon 2000/Mars 2000 for extraterrestrial
652 bodies);
- 653 • Site metadata (geomorphic setting, sampling depth, lithology, depositional environment);
- 654 • Clear documentation of analytical methods and quality control procedures.

655 All contributed datasets will undergo the same validation and quality control checks applied to
656 the original PlanetGSD compilation (see Technical Validation) before inclusion. Version history and
657 a detailed changelog will be maintained in the repository README file.

658 7. Conclusions

659 The PlanetGSD 1.0 dataset establishes a unified framework for characterizing grain-size
660 distributions across Earth, the Moon, and Mars, revealing that soils from these disparate planetary
661 bodies conform to a single functional form—the Universal Grain-Size Distribution (UGSD). Key
662 conclusions include:

- 663 1. **UGSD universality.** The UGSD function fits 6,527 samples from three planets with
664 median $R^2 = 0.988$, demonstrating that granular configuration transcends genetic and
665 environmental differences. The exponent n serves as a scaling factor classifying soils into
666 categories that reflect textural organization inherited from formation processes.
- 667 2. **μ as process indicator.** The UGSD parameter μ effectively discriminates among
668 depositional environments: $\mu > 1.0$ (aeolian-dominated), $\mu \approx 0.5$ (fluvial-aeolian
669 transition), $\mu < 0.5$ (lag deposits, impact-influenced mixtures). Negative μ values record
670 fine-fraction deficiencies from winnowing or analytical truncation.
- 671 3. **Probabilistic behavior.** Site-level μ populations follow three-parameter Weibull
672 distributions, enabling stochastic generation of spatially continuous μ -fields that preserve



673 local heterogeneity while enabling upscaling to regional scales.

674 4. **Cross-planetary comparison.** The μ - D_c parameter space clusters soils by planetary body
675 and process regime: Earth spans the widest range (diverse processes); Moon occupies a
676 narrow, near-zero μ range (impact comminution); Mars displays the broadest μ range
677 (complex aqueous-aeolian-volcanic interactions).

678 5. **Applications.** Granular fields support hydro-geophysical modeling, ISRU targeting, and
679 mission planning by providing spatially explicit estimates of soil properties derived from
680 limited point measurements.

681 The UGSD framework thus provides a quantitative, mechanistically grounded approach to soil
682 characterization that unifies terrestrial and extraterrestrial regolith studies. By reducing high-
683 dimensional texture data to interpretable indices and enabling probabilistic field generation, it
684 bridges the gap between limited point measurements and spatially explicit process modeling,
685 offering a new paradigm for planetary surface science.

686 **Data Availability**

687 The complete PlanetGSD 1.0 database is openly available at Figshare
688 (<https://doi.org/10.6084/m9.figshare.31569616>, Zhang, 2026) under the Creative Commons
689 Attribution 4.0 International License (CC BY 4.0). During peer review, the data can be accessed
690 anonymously via the same URL. The repository contains five Excel files:

691 - 'S1_GSD_data_from_Earth.xlsx': 4,419 terrestrial samples with cumulative curves and
692 metadata

693 - 'S2_GSD_data_from_Moon.xlsx': 379 lunar samples from eight sample-return missions

694 - 'S3_GSD_data_from_Mars.xlsx': 1,729 Martian samples derived from rover image analysis



695 - 'S4_UGSD_parameters_and_Weibull.xlsx': UGSD parameters for all samples and site-level
696 Weibull statistics

697 - 'S5_Mars_image_reference_numbers.xlsx': PDS image Product IDs for all 1,729 Mars
698 samples

699 **Code Availability**

700 All analysis codes are openly available in the PlanetGSD 1.0 repository at Figshare
701 (<https://doi.org/10.6084/m9.figshare.31569616>). The repository contains three Python codes:

702 - Code S1 (MATLAB): Stochastic μ -field generation (requires MATLAB R2020a or later)

703 - Code S2 (R): Data pre-processing and UGSD parameterization (requires R \geq 4.0)

704 - Code S3 (Python): Weibull distribution fitting and diagnostic plots (requires Python \geq 3.9
705 with NumPy, SciPy, Matplotlib, and Pandas)

706 The codes require Python \geq 3.9 with NumPy, SciPy, Matplotlib, and Pandas. Version history is
707 maintained in the Figshare repository.

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714 **Competing Interests**

715 The authors declare no competing interests.

716 **Author Contributions**

717 **J. Z.:** Conceptualization, Data curation, Formal analysis, Software, Visualization, Writing –



718 Original Draft. Y. L.: Data curation, Validation, Writing – Review & Editing.

719

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955

956 **Supplementary Information**

957 Supplementary Tables S1–S5 provide detailed site metadata for terrestrial samples organized



958 by geographic region. Supplementary Table S6 provides lunar sample metadata. Supplementary
959 Tables S7–S8 provide Martian sub-site distribution and geological context.