



State-of-the-art hydrological datasets exhibit low water balance consistency globally

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Abstract

The proliferation and diversification of hydrological datasets have significantly advanced hydrological research. However, the coherence across these datasets remains poorly understood, hindering the comparability of findings derived from different data sources and variables. Here, we demonstrate that state-of-the-art hydrological datasets exhibit overall low consistency when evaluated through the lens of water balance – specifically, the relationship between variations in soil moisture and the difference between precipitation, evapotranspiration, and runoff. Our analysis reveals that satellite-based precipitation datasets generally show the highest consistency, while gauge-based datasets perform better in densely monitored regions of the Northern Hemisphere. For evapotranspiration, runoff, and soil moisture, reanalysis datasets demonstrate broader areas of higher consistency compared to gauge- or satellite-based products. Spatial patterns of consistency are strongly influenced by aridity and temperature, which affect measurement and modelling accuracy, while vegetation cover further modulates the performance of soil moisture datasets. Notably, dataset consistency has improved significantly in northern mid-latitudes over recent decades, likely reflecting advancements in observational technologies and the effects of climate warming. These findings underscore the importance of continued efforts to enhance dataset coherence and reliability for robust hydrological assessments.

1 Introduction

Over the past decades, the advancement of hydrological science and interconnected water-related research fields was accompanied by the emergence of datasets that depict the spatiotemporal changes of variables in the water cycle (Tang et al., 2024; Zarei and Destouni, 2024; Gebrechorkos et al., 2024; Douville et al., 2021; Oki and Kanae, 2006; Wang-Erlandsson et al., 2022; Mehta et al., 2024; Markonis et al., 2024). At the same time, understanding the consistency across the increasing suite of datasets is crucial not only for research on the responses and interactions within hydrology, but also for practitioners and management in terms of regional water scarcity (Mekonnen and Hoekstra, 2016; Mehta et al., 2024), ecosystem function and



41 water availability (Denissen et al., 2022), and the Earth system resilience (Wang-Erlandsson et
 42 al., 2022; Jaramillo and Destouni, 2015). Nevertheless, the water balance consistency among
 43 different suites remains largely unknown, while current studies mostly detail the dataset
 44 performance in terms of accuracies against observations and/or reference data, modeling
 45 behaviors, or water and energy balance closure (Tang et al., 2024; Gebrechorkos et al., 2024; Pan
 46 et al., 2020; Zarei and Destouni, 2024; Abolafia-Rosenzweig et al., 2021).

47 Gridded hydrological datasets are derived based on different types of observations and methods,
 48 such as (i) spatial interpolation based on gauge/station/*in-situ* measurements (Dorigo et al., 2011;
 49 Pastorello et al., 2020; Do et al., 2018; Harris et al., 2020), (ii) radiative transfer modelling based
 50 on satellite measurements (Cooley et al., 2022; McCabe et al., 2017), (iii) land surface modelling
 51 with integrated data assimilation of hydrological and other variables (Muñoz-Sabater et al.,
 52 2021). Meanwhile, datasets also could be developed based on a combination of these approaches
 53 and observations (Beck et al., 2019; Yao et al., 2014). In this context, each of these approaches is
 54 characterized by inherent advantages and disadvantages. For example, in the case of precipitation
 55 (P), gauge-based datasets are based on ground truth but at the same time they are influenced by
 56 errors related to wind and air flow anomalies around the gauges, by the spatial distribution of
 57 gauges which potentially misses some of the spatial heterogeneity of precipitation patterns, and
 58 by uncertainties in spatial interpolation (Lanza et al., 2022; Mishra and Coulibaly, 2009; La et
 59 al., 2002). By contrast, satellite-based P datasets can capture spatial patterns more consistently
 60 (Tang et al., 2022; Ashouri et al., 2015; Funk et al., 2015), but have difficulties in estimating P
 61 amounts arriving to the surface. Further, reanalysis datasets based on land surface models show
 62 strengths in addressing temporal gaps caused by missing records and incomplete observation
 63 periods (Hersbach et al., 2020; Gelaro et al., 2017), but suffer from inaccurate or incomplete
 64 consideration of land surface processes affecting hydrological dynamics. From this aspect,
 65 machine-learning algorithms present an alternative opportunity to produce seamless data, firstly
 66 happening for estimating P (Ashouri et al., 2015) and recently also being applied to
 67 evapotranspiration (ET), runoff (R), and soil moisture (SM) datasets (Nelson et al., 2024; Ghiggi
 68 et al., 2019; O and Orth, 2021).

69 As a result of the different derivation approaches and the influence of environmental factors,
 70 disagreements between hydrological datasets remain (Hirschi et al., 2025; Markonis et al., 2024;
 71 Sun et al., 2018). These uncertainties limit the fundamental understanding of patterns, changes,
 72 and variabilities of water variables (Markonis et al., 2024; Wang et al., 2024; Han et al., 2024;
 73 Douville et al., 2021; Greve et al., 2014; Zhang et al., 2024a; Denissen et al., 2022). The scarcity
 74 of observations across time, space, and hydrological variables hinders a comprehensive analysis
 75 of datasets' performance and reliability. However, observations are not our only source of
 76 knowledge about Nature, but known physical laws also provide information. This way, for
 77 example the water balance equation can be used to evaluate the consistency across combinations
 78 of hydrological datasets, a question which has remained largely unclear because assessments are
 79 usually specific to individual datasets (Zarei and Destouni, 2024; Abolafia-Rosenzweig et al.,
 80 2021). Such a combinatorial and factorial analysis requires (i) gridded datasets of all involved
 81 variables and (ii) independence between them in the sense that they are not derived with, e.g., the
 82 same model or approach which inherently enforces water balance closure. Thanks to the recent
 83 emergence of many hydrological datasets (Muñoz-Sabater et al., 2021; Ghiggi et al., 2019;
 84 Miralles et al., 2025), these requirements are now met, opening a novel opportunity for
 85 hydrological dataset evaluation.



In this study, we evaluate the water balance consistency across a comprehensive set of P , ET , R and SM datasets. This encompasses gauge/station-based, satellite-based and reanalysis-based datasets, and offers 8,294 combinations of water balance-variables from independently derived datasets (Fig. 1a). For each combination, we evaluate adjusted R^2 as the performance of linear regression of temporal changes in $P-ET-R$ against changes in SM (ΔSM) to determine its water balance consistency. Then, combining an individual dataset with all possible combinations of datasets for the remaining water balance-variables we can assess its performance through the average of the R^2 scores obtained for all considered combinations. This way, the common limitations and strengths of different derivation-based datasets for each variable (i.e., P , ET , R , and SM) are distinguished across space and time. In addition to determining the performance of a large set of considered hydrological datasets across the globe, we also evaluate the resulting spatial patterns for possible causes in order to provide guidance for further dataset development.

2 Materials and Methods

2.1 Data and Independent combinations

We utilized 20 P datasets, 11 ET datasets, 7 R datasets, and 9 SM datasets to obtain respective monthly values across the global land area, where the P , ET , and R values are monthly amounts and ΔSM values are the soil moisture differences between the last day and the first day of each month. According to their sources, these datasets were summarized into three categories:

- Gauge/station-based products: CPC (Xie et al., 2010), CRU TS v4.06 (Harris et al., 2020), UDel v5.01 (Legates and Willmott, 1990), EM-EARTH (Tang et al., 2022), GPCC v2022 (Schneider et al., 2022), and PREC/L (Chen et al., 2002) for P , X-BASE (Nelson et al., 2024) for ET , GRUN (Ghiggi et al., 2019) for R , as well as SoMo.ml (O and Orth, 2021) for ΔSM .
- Satellite-based products: CHIRPS v2.0 (Funk et al., 2015), CMAP (Xie and Arkin, 1997), CMORPH v1 (Xie et al., 2017), GPCP(M) v2.3 (Adler et al., 2018), GPCP(D) v1.3 (Huffman et al., 2001), GPM IMERG v07 (Huffman et al., 2023), PERSIANN-CDR (Ashouri et al., 2015), MSWEP v2.8 (Beck et al., 2019) for P , MODIS (Running et al., 2021), PT-JPL (Fisher et al., 2008), PML-v2 (Zhang et al., 2019), GLASS (Yao et al., 2014) for ET , GLEAM v4.1 (Miralles et al., 2025) for both ET and ΔSM , SMAP L4 v7 (Reichle et al., 2019) for both R and ΔSM , as well as ESA CCI v08.1 (Gruber et al., 2019) for ΔSM .
- Reanalysis products: 20CR v3 (Slivinski et al., 2021), JRA-55 (Japan Meteorological Agency, 2013), ERA5 (Hersbach et al., 2020), NCEP-NCAR R1 (Kistler et al., 2001), and NCEP-DOE R2 (Kanamitsu et al., 2002) for P , MERRA-2 (Gelaro et al., 2017) for P , ET , R , and ΔSM , as well as GLDAS-2.0 (Rodell et al., 2004), GLDAS-2.1 (Rodell et al., 2004), GLDAS-2.2 (Li et al., 2019), ERA5-land (Muñoz-Sabater et al., 2021) for ET , R , and ΔSM .

All the datasets were either provided in or resampled in 0.25-degree resolution by linear interpolation, and their temporal coverages are within the period of Jan-2000 to Dec-2022. Various components of GLDAS (i.e., -2.0, -2.1, and -2.2) were used here because they are based on different forcings, models, and data assimilation strategies (see more details in Tables S1–S4). The ΔSM from different datasets were the depth-weighted averages of their available soil layers (Li et al., 2023a). SoMo.ml ΔSM covers 0–50 cm related to the commonly observed depths in



130 *situ* measurements; ESA CCI ΔSM represents the top surface layer (of < 2 cm thickness)
 131 captured by satellite observations; GLEAM ΔSM , SMAP ΔSM , and MERRA-2 ΔSM represent a
 132 root zone layer of 0–100 cm; and GLDAS-2.0/2.1/2.2 and ERA5-land ΔSM cover deeper depths
 133 (> 100 cm). Despite different depths, the ΔSM was assumed to record the variability of $P - ET -$
 134 R in the water balance, on the basis that its variability constitutes a large portion of the variability
 135 in terrestrial water storage (Freedman et al., 2014). In this context, a suite of P , ET , R , and SM
 136 datasets forms a considered combination, such as

137 P_{CPC} , ET_{X-BASE} , R_{GUN} , and $\Delta SM_{SoMo.ml}$

138 Among the considered datasets as listed above, 13,860 combinations (that is $20 \times 11 \times 7 \times 9$ for P ,
 139 ET , R , and S) were initially available. However, considering the temporal availability and the
 140 dependence between dataset sources of different water balance components, parts of
 141 combinations were excluded by three rules:

142 1) The combinations with short overlapping time periods cannot be considered. In particular,

- 143 • SMAP L4 products have only one year overlap (i.e., 2015) with 20CR v3, so the
- 144 combinations with P from 20CR v3 and R and/or ΔSM from SMAP were not considered;
- 145 • The combinations with GRUN R (covering until 2014) and R and/or ΔSM from SMAP
- 146 (starting from 2015) were not available;
- 147 • The combinations with water balance components from GLDAS-2.0 (also covering until
- 148 2014) and SMAP were not available;
- 149 • The combinations with SMAP L4 products and either PT-JPL or UDel v5.01 (covering
- 150 until 2017) were not considered.

151 2) The combinations with water balance components from the same dataset source were not
 152 considered, which include the combinations with GLEAM ET and ΔSM , the combinations with
 153 SMAP ET and ΔSM , and the combinations with any two or more variables from MERRA-
 154 2/GLDAS/ERA5-land. In this perspective, since the difference between ERA5 and ERA5-land
 155 was mainly because of the non-linear dynamical downscaling technique (Muñoz-Sabater et al.,
 156 2021), the combinations with ERA5 P and ERA5-land $ET/R/\Delta S$ were also not considered.

157 3) If a dataset was driven by another dataset, the water balance components from these two
 158 datasets were also not considered in combination. In particular:

- 159 • GRUN was driven by GSWP3, a dynamically downscaled and bias-corrected version of
- 160 the 20CR, so the combinations with 20CR P and GRUN R were excluded;
- 161 • SoMo.ml was driven by meteorological data from ERA5, so the combinations with ERA5
- 162 P and SoMo.ml ΔSM were excluded;
- 163 • PML-v2 used the GLDAS-2.1 meteorological forcings, which includes GPCP(D) v1.3, so
- 164 the combinations with GPCP(D) P and PML ET , as well as those with GPCP(D) P and
- 165 GLDAS-2.1 ET , were excluded;
- 166 • GLEAM v4.1 used P from MSWEP v2.8 as one of the inputs, so the combinations with
- 167 MSWEP P and GLEAM $ET/\Delta SM$ were excluded;
- 168 • The inputted P for SMAP L4 was from CPC and GPCP(M), and therefore, the
- 169 combinations with CPC/GPCP(M) P and SMAP $R/\Delta SM$ were excluded;
- 170 • Since the land surface component of MERRA-2 bias adjusted P by using CPC, CMAP,
- 171 and GPCP(M), the combinations with CPC/CMAP/GPCP(M) P and MERRA-2
- 172 $ET/R/\Delta SM$ were excluded;



- The GLDAS-2.2 was forced with the meteorological analysis fields from the European Centre for Medium-Range Weather Forecasts (ECMWF) Integrated Forecasting System (IFS)(Rui et al., 2022), which includes ERA5, so the combinations with ERA5 P and GLDAS-2.2 $ET/R/\Delta SM$ were excluded.

At the same time, there are different levels of (in)dependence such that the decision on whether or not to consider certain datasets as independent is not always straightforward. The following cases are not fully independent but considered sufficiently independent for the context of our study:

- The datasets driven by similar forcings, such as SoMo.ml ΔSM and ERA5-land ET and R , are considered to form independent combinations;
- MSWEP generated based on a group of P datasets including ERA5 is considered sufficiently independent from the ERA5-land ET , R , and ΔSM ;
- ESA CCI ΔSM which was assimilated into GLEAM ΔSM is considered independent from GLEAM ET .

After applying these exclusion rules, there remained 8,294 independent combinations.

2.2 Performance assessment in terms of water balance consistency

For each considered combination of hydrological datasets, we assess adjusted R^2 scores in water balance in each grid cell through a linear regression model considering all available months:

$$(P - ET - R)_s = k \cdot \Delta SM_s \quad (1)$$

where s is the spatial index (grid cell) and k is the proportionality factor. Note that this is not supposed to equal to 1 in our context because of the differences in units between the left side of the equation (mm for P , ET , and R) and the right side ($m^3 \cdot m^{-3}$ for ΔSM). The linear regression model lets us avoid the conversion of ΔSM unit from $m^3 \cdot m^{-3}$ to mm, reducing uncertainties from considering soil moisture datasets with different soil depths. P , ET , R , and ΔSM are $M \times 1$ vectors, where M is the number of months. We removed the models with M smaller than 36 to ensure enough input data. The adjusted R^2 score for each model was used to represent the ability of each combination of datasets to describe the variability in water balance at each grid point. Since the water balance is a physical law that should be obeyed according to mass balance, the ability of describing variability here is attributed to the performance of each combination for each grid cell.

Since different independent combinations have different temporal coverages (i.e., different M), we analyzed whether the varying M would affect the accuracy results. For this purpose, a fixed study period of Feb-2003 to Dec-2014 (where M is fixed to be 143) was selected. We calculated the degree of water balance closure, evaluated based on the adjusted R^2 score, of all available independent combinations for this fixed M . We compared the R^2 values between varying M and fixed M for each considered combination by calculating their linearly regressed R^2 scores and slopes. Most of the regressed R^2 and slopes are distributed between 0.9 and 1 (Fig. S1). This indicates that the considered time period has no significant influence on the resulting degree of water balance closure. Therefore, we assessed the performance across different time periods for different combinations of datasets, depending on their temporal coverage and overlap (ensuring a minimum overlap of 3 years). This allows us to involve a larger number of combinations compared to a fixed M , while we also provided the results calculated based on the combinations used in the following temporal changes analysis, which have only large and less varying M (Fig.



216 S2).

217 In a next step, the overall performance in terms of water balance consistency for each individual
 218 dataset in each grid cell was inferred from the averaged R^2 across all combinations of datasets
 219 containing the respective dataset. In other words, the performance of each individual dataset is
 220 assessed through the R^2 scores in water balance for describing variability when combining it with
 221 all suitable combinations of state-of-the-art datasets for the other water balance components.

222 Since the performance inferred from water balance consistency is based on the ability to describe
 223 variability in water balance, different temporal resolutions directly affected magnitudes and
 224 frequencies of the variability (Maurer and Hidalgo, 2008). Accordingly, we repeated the above
 225 calculations for the datasets available at daily and yearly resolutions, where 3,647 and 8,294 (the
 226 same as monthly) independent combinations were considered, respectively (Text S1–S2).

227 **2.3 Potential influence factors on dataset performance**

228 To further understand how the global spatial patterns of each dataset's performance (Figs.
 229 S3–S6) were influenced, we considered a set of potential influence factors of the spatial patterns:
 230 soil texture, aridity index, tree cover fraction, area equipped for irrigation, monthly mean
 231 temperature, observation density, and topography. For the first five factors, we calculated them
 232 for each independent combination because the factors are changing from dataset to dataset, and
 233 then obtained the averages for each dataset through all the considered combinations that include
 234 this dataset. In detail,

- 235 • Soil clay content was used to indicate soil texture influence, since small particles and
 236 large surface areas can create small pore sizes to hold water tightly, affecting *SM*
 237 conditions and through local water cycles to influence other water variables (Cleophas et
 238 al., 2022). The clay contents were provided by the Harmonized World Soil Database
 239 version 2.0 (HWSD v2.0) (Nachtergaele et al., 2023) for seven soil layers, and the layers
 240 used for each independent combination were selected according to the depth of *SM*
 241 dataset in that combination and depth-weighted for a whole layer.
- 242 • Regarding the aridity index, we used the multi-year averages of *ET* and divided them by
 243 those of *P* to obtain an aridity index map for each independent combination (O and Orth,
 244 2021; Li et al., 2022).
- 245 • The tree cover fraction from NASA Vegetation Continuous Fields Version 1 data product
 246 (Hansen and Song, 2018).
- 247 • Area equipped for irrigation from Mehta et al. (2024) were averaged among the available
 248 periods for each independent combination.
- 249 • The monthly mean 2m air temperature was averaged based on the daily average
 250 temperature from ERA5 and calculated for each month in each considered combination.
- 251 • Unlike the upper factors, the observation density is different from variable to variable, not
 252 from combination to combination. We counted the number of stations/sites for different
 253 observation networks of the water variables: CPC global stations for *P*, eddy covariance
 254 sites in FLUXNET2015 (Pastorello et al., 2020) and AmeriFlux for *ET*, streamflow
 255 stations in the Global Streamflow Indices and Metadata Archive (GSIM) (Do et al., 2018)
 256 for *R*, and sites of *in-situ* measurement in the International Soil Moisture Network
 257 (ISMN) (Dorigo et al., 2011) and the National Center for Monitoring and Early Warning
 258 of Natural Disasters of Brazil (CEMADEN) (Zeri et al., 2020) for *SM*. Here, we referred
 259 to Ruiz-Vásquez et al. (2022) to sum up the stations/sites located in each grid cell and its



- 260 eight neighboring grid cells (Fig. S7).
 261 • The topography information is represented by the standard deviation of 15 arc-second
 262 elevation (Noaa National Centers for Environmental Information, 2022) within each
 263 0.25° grid cell.

264 An explainable machine learning method was applied for quantitative attribution (Li et al., 2022)
 265 in order to determine the relative roles of the considered factors for the resulting global spatial
 266 patterns of each dataset's performance. For each dataset, we trained one random forest model,
 267 where the global performance map was the target variable, the seven maps of the above-
 268 described factors were the predictors, and a common hyperparameter setting (numbers of
 269 estimators: 100; maximum features: 30%) was used (Li et al., 2022). Before training, the
 270 correlation matrix of the seven predictors for each random forest model was calculated to
 271 evaluate the potential collinearity between predictors. Since the correlations are within a range of
 272 -0.5–0.6 (Figs. S8–S11 for *P*, *ET*, *R*, and *SM* datasets, respectively), collinearity is not a major
 273 issue to affect our model predictions (Dormann et al., 2012). The performance of random forest
 274 models was determined by the cross-validation out-of-bag R^2 , which mainly distributes around
 275 0.8 for all the trained models and therefore indicates the usefulness of these models for the
 276 following attribution (Fig. S12). Then, SHapley Additive exPlanations (SHAP) feature
 277 importance was calculated to quantify the marginal contributions of predictors to each dataset's
 278 overall accuracy (Li et al., 2023a), and we identified the relative importance among predictors by
 279 ranking their global averaged absolute SHAP values (Li et al., 2023b).

280 2.4 Temporal changes in dataset performance

281 Since the temporal coverages of independent combinations are inconsistent, the independent
 282 combinations with less than two thirds of available monthly data for either the first period of Jan-
 283 2000 to Dec-2010 or the second period of Jan-2011 to Dec-2022 were removed in the temporal
 284 changes analysis. The remaining independent combinations ($n = 2,589$) were used to calculate
 285 the water balance consistency for the first period and the second period separately. The overall
 286 performance in terms of water balance consistency was calculated for the first or the second
 287 periods of each dataset by averaging the respective period's adjusted R^2 scores among all the
 288 independent combinations of the datasets considered in this study. In this way, the temporal
 289 change in performance for each dataset was obtained by subtracting the overall performance of
 290 the first period from that of the second period.

291 To account for the uncertainties of these temporal changes, bootstrap confidence intervals
 292 (Kulesa et al., 2015) were calculated for the performance in both the first and the second periods
 293 of the 2,589 independent combinations. For each of these independent combinations, whose
 294 number of available monthly data for the first and the second periods are denoted as M_1 and M_2 ,
 295 respectively, we obtained 100 random samples for the first/second period with replacement. The
 296 amount of data in one sample is M_1 for the first period and M_2 for the second period, and 100
 297 samples indicate that 100 adjusted R^2 scores were calculated for the first/second period based on
 298 equation (1). Accordingly, a bootstrap distribution for the first/second period with 100 samples
 299 was obtained, and its confidence interval was evaluated by the 5th and 95th percentiles. When the
 300 5th percentile of the second period is higher than the 95th percentile of the first period, or the 95th
 301 percentile of the second period is lower than the 5th percentile of the first period, the change in
 302 performance of this independent combination from the first to the second period is significant.
 303 Finally, grids in the map of temporal changes in performance for each dataset were masked by
 304 n/a (i.e., not available) if they did not have over 50% independent combinations showing



305 significant changes.

306

307 3 Results

308 3.1 Water balance consistency of considered datasets

309 Fig. 1b–e summarizes the performance of considered datasets in terms of their water balance
 310 consistency, based on monthly calculations (see Methods). Colors distinguish gauge-based,
 311 satellite-based and reanalysis datasets. Overall, the R^2 scores are fairly low, indicating prevailing
 312 inconsistencies across considered datasets in terms of the water balance. From the combinations
 313 with top ten performance, it is likely that the P from PERSIANN-CDR, ET from PT-JPL, R from
 314 GRUN, and SM from GLDAS-2.1 would contribute to high water balance consistency (Fig.
 315 S13).

316 For P datasets, the overall performance of satellite-based datasets is generally higher than gauge-
 317 based and reanalysis datasets, where the CHIPRS v2.0 and PERSIANN-CDR show the highest
 318 global medians (Fig. 1b). This is related to their limited spatial coverage omitting high-latitude
 319 regions with typically low water balance consistency (Fig. S3), while for 50°S–50°N,
 320 PERSIANN-CDR, GPM IMERG v07 and MSWEP v2.8 show the highest medians (Fig. 1b).
 321 Besides, GPM IMERG v07 and MSWEP v2.8 exhibit the largest areas with the best performance
 322 across datasets. Fig. 2 maps the types of datasets with the highest water balance consistency for
 323 each considered variable. It shows that given the comparatively good performance of GPM
 324 IMERG v07 and MSWEP v2.8, satellite-based precipitation dataset types perform best across
 325 most of the globe, particularly in the tropics and subtropics (Fig. S14 and Fig. 2a). Gauge-based
 326 P datasets perform best in high-latitude regions which in the Northern Hemisphere are
 327 characterized by abundant *in-situ* observations (Fig. S7).

328 ET and R datasets show similar global patterns and medians of overall performance among the
 329 different dataset types (Figs. S4–S5 and Fig. 1cd). However, for the spatial patterns, PT-JPL and
 330 GLDAS-2.2 have distinctly larger areas with the best performance compared to other ET datasets
 331 (Fig. S14b), leading to comparable best-performance areas between satellite-based and reanalysis
 332 ET datasets (Fig. 2b). Similarly, gauge-based and reanalysis R datasets show the largest areas
 333 with the best performance (Fig. 2c), where GRUN and ERA5-land datasets are the respective
 334 main contributors (Fig. S14c).

335 Among SM datasets, SoMo.ml and ESA CCI v08.1 have the lowest global medians of overall
 336 performance. This is because they only represent the surface layers instead of the entire soil
 337 column (Fig. 1e). Meanwhile, the SM datasets with simulations of deep soil layer generally
 338 performed better in most global regions, such as the reanalysis and GLDAS-2 products (Fig. 2d
 339 and Fig. S14d).

340 Additionally, we calculated our analysis at daily and annual time scales. Results indicate
 341 substantially less water balance consistency with the lowest R^2 scores at the annual scale (Fig.
 342 1b–e and Fig. S15). However, different temporal resolutions did not alter the relative ranking
 343 patterns among the datasets (Fig. 1b–d), except for SM whose memory is likely to be more
 344 sensitive to the varying resolutions (Fig. 1e).

345

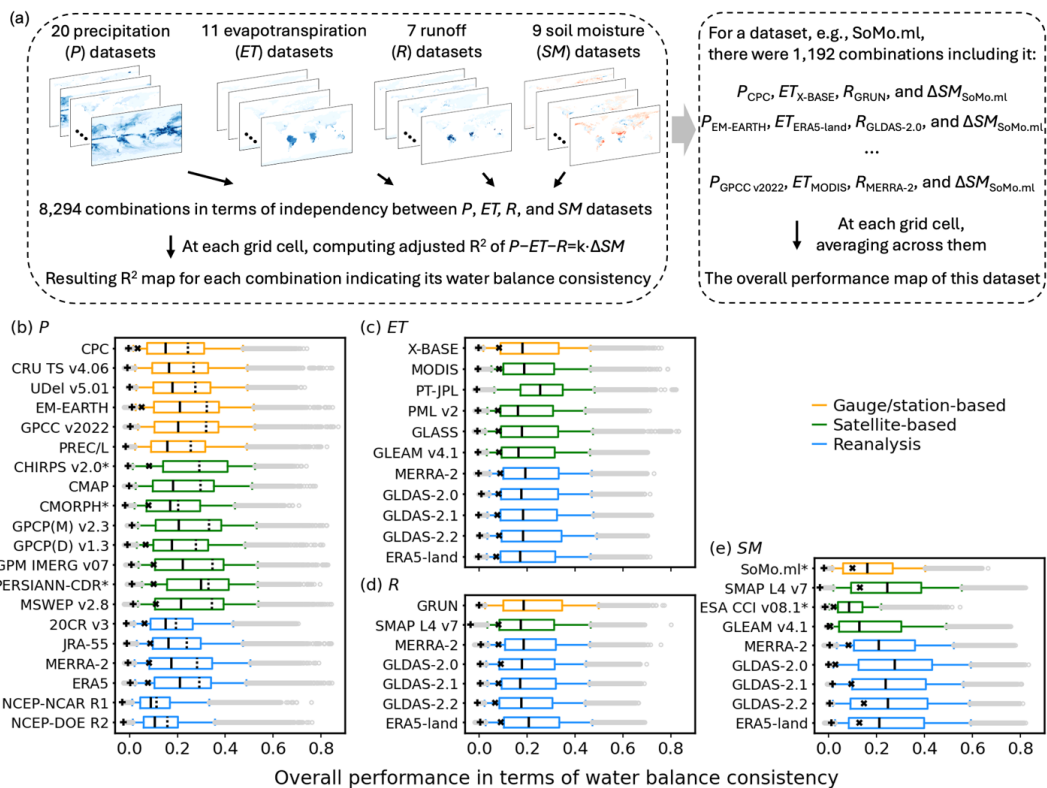


Fig. 1. Illustration of water-balance approach and calculated performance of considered datasets. (a) Performance is determined based on R^2 scores measuring consistency of each dataset when combined with all independent datasets in terms of the water balance (Methods). (b–e) The boxplots summarize the performance of considered datasets. Colors indicate the type of each dataset. Each box shows the median value, as well as the 5th, 25th, 75th, and 95th percentiles of the global pattern of water balance consistency derived from monthly data. Median results for performing the analysis with daily and annual data are indicated through crosses and pluses, respectively (Text S1–S2). Asterisks (*) following the name of P dataset indicate its limited spatial coverage omitting high-latitude regions with typically low performance, and dashed line in each box indicates median of only 50°S–50°N. * of SM dataset indicates that the dataset does not consider the entire soil column.

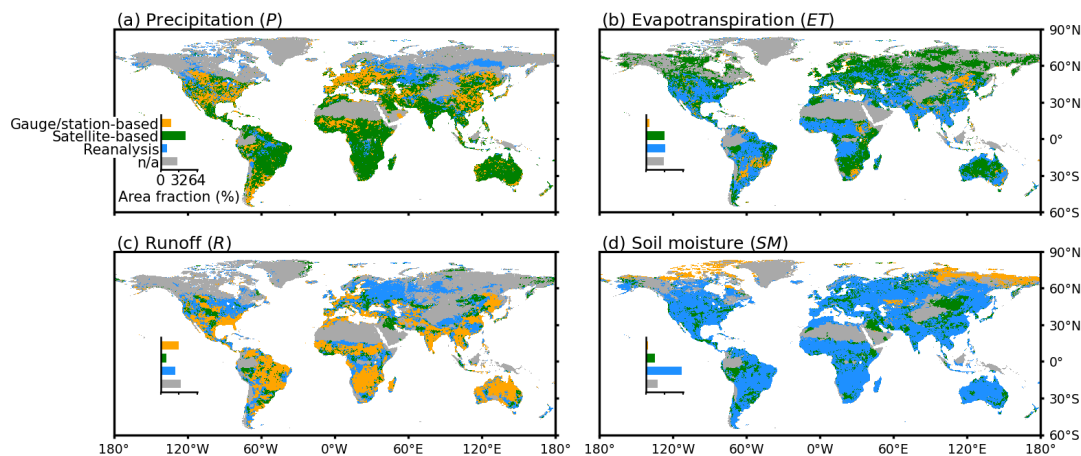


Fig. 2. Types of best-performing datasets across hydrological variables. Colors indicate type of dataset with the highest water balance consistency. Gray color indicates that multiple datasets show similar water balance consistency (with R^2 scores varied within 5%) or low water balance consistency (with all R^2 scores lower than 0.2).

3.2 Potential reasons influencing water balance consistency

Next, we aim to diagnose possible reasons for regional discrepancies of dataset performance in terms of water balance consistency. For this purpose, we consider a large set of variables that may affect the water balance consistency of a given dataset, including soil and vegetation characteristics, climate, and gauge density (Methods). By applying an explainable machine learning method (i.e., SHAP), temperature and aridity (i.e., ET/P) were diagnosed as the key factors to influence the spatial performance patterns of P , ET , and R datasets, while for SM datasets temperature and tree cover are critical (Fig. 3 and Figs. S16–S19). Our results demonstrate that the performance of P datasets is higher in the sub-humid and sub-arid regions (where the aridity index is 0.6–1.0) with monthly mean temperatures between 10°C and 15°C (Fig. 3a and Fig. S20). The results for ET and R datasets are largely similar to those of P datasets (Fig. 3b–c and Figs. S21–S22), while comparatively good performance of SM datasets is found in regions with a moderate tree cover fraction (5–50 %) and warm temperature (10–15 °C) (Fig. 3d and Fig. S23). These influence patterns were summarized according to medians across dataset performance, while using maximum does not alter the results (Fig. S24).

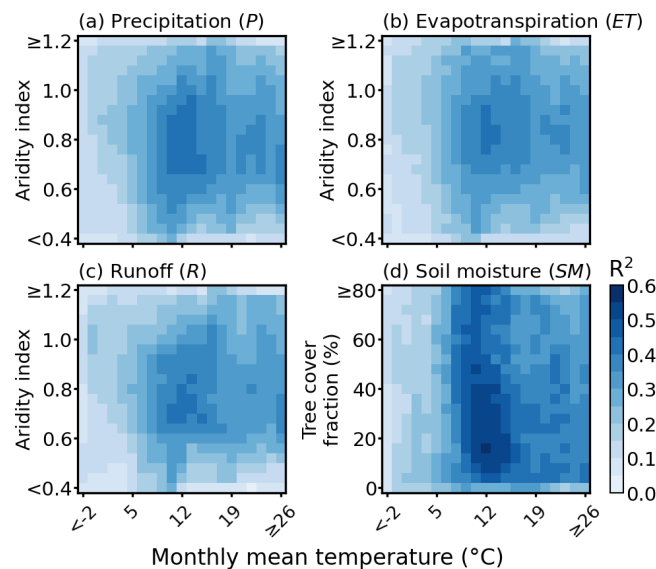


Fig. 3. Influence of temperature and aridity (or tree cover for SM) on water balance consistency of datasets. The consistency through water balance is quantified by R^2 scores (Fig. 1), and median R^2 scores across $P/ET/R/SM$ datasets for each climate/vegetation class (Figs. S20–S23) are shown.

3.3 Temporal changes in water balance consistency of dataset

We furthermore assess changes in the diagnosed dataset performance inferred from water balance consistency over time. This is done by splitting our study period and repeating the analysis for the sub-periods 2000–2010 and 2011–2022, and includes an assessment of significance (Methods). For the P datasets, the majority of global grid cells show no temporal change in water balance consistency, and among the grid cells with temporal changes, we found mostly increases (Fig. 4a). These increasing changes were mainly observed in middle- and high-latitude regions of the Northern Hemisphere, while the P dataset from ERA5 shows the highest median level of performance improvement (Fig. S25). At the same time, we find similar spatial patterns of changes in water balance consistency for ET , R , and S datasets, with most grid cells showing no change (Fig. 4b–d). Among the grid cells with significant changes, performance in terms of water balance consistency increases prevail and are mostly located in high-latitude regions and in regions with scarce observations in the Northern Hemisphere (Fig. 4b–d, Fig. S14 and S26–S28).

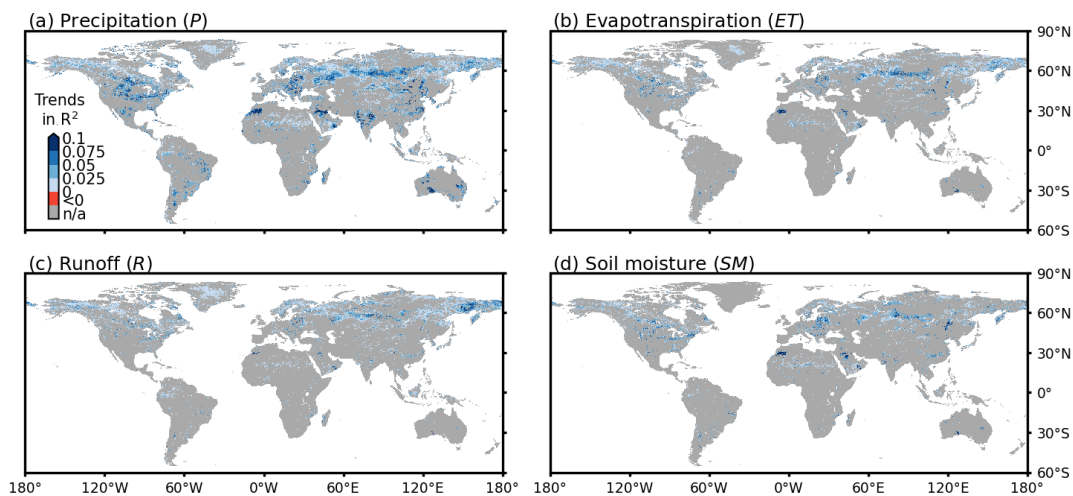


Fig. 4. Temporal changes in water balance consistency of P , ET , R , and SM datasets from 2000–2010 to 2011–2022. Based on the changes in R scores for each dataset (Figs. S25–S28), median values are shown in each grid cell where at least half the considered datasets showed significant changes (Methods), representing common temporally changing patterns.

4 Discussion

The spatial performance patterns derived from our water balance consistency approach reveal high similarity among P datasets (Fig. S3), consistent with findings from recent studies on P dataset agreement (Markonis et al., 2024; Dosio et al., 2021). Beyond these similarities, our grid cell-level comparisons suggest that satellite-based P datasets outperform others in large regions of southern America, Africa, south and Southeast Asia, and inner Australia, while gauge-based P datasets excel in many grid cells across the United States, Europe, and East Asia (Fig. 2). This suggests that the satellite-based P datasets are superior in regions with sparse or no gauging stations (Fig. S7), compared to gauge-based and reanalysis datasets. However, all P datasets exhibit higher water balance consistency in moderately humid or dry regions, with long-term mean temperature also influencing the performance (Fig. 3 and Fig. S20). Lower consistency of gauge-based datasets in humid and dry regions may stem from challenges in mapping spatial variability of extreme rainfall (Mishra and Coulibaly, 2009) and accurately recording light precipitation events (Lanza et al., 2022), as consistency is based on seasonal variabilities in water balance. Additionally, P datasets show lower consistency in cold regions because of difficulties in measuring solid precipitation (La et al., 2002). Similarly, satellite-derived precipitation is relatively insensitive to light rainfall (Laviola et al., 2013), struggles with extreme rainfall estimates (likely due to retrieval algorithms and infrequent temporal sampling of polar orbits) (Barlow et al., 2019), and often fails to detect snowfall or perform well over snow- and ice-covered surfaces (Alijanian et al., 2017). In contrast, reanalysis datasets perform better in cold regions, benefiting from assimilated meteorological observations and atmospheric states (Barlow et al., 2019; Dosio et al., 2021; Sun et al., 2018).

The ET , R , and SM datasets generally show global spatial performance patterns similar to those of P datasets (Figs. S4–S6). This is partly because uncertainties in P datasets propagate through



the water cycle (Fallah et al., 2020), affecting the water balance consistency of *ET*, *R*, and *SM* datasets. Nevertheless, our approach identifies distinct relative performances across hydrological variables and dataset types (Fig. 2 and Fig. S14), as it considers independent combinations of datasets. For *ET*, the satellite-based PT-JPL dataset performs comparatively well, likely due to its advanced consideration of plant physiological limitations and water stress. The reanalysis dataset GLDAS-2.2 also performs comparatively well, probably due to its assimilation of terrestrial water storage (Table S2 and Fig. S14). For *R*, the machine-learning model-driven GRUN, constrained by *P* and temperature in large basins, and ERA5-land dataset, perform best in most regions (Tables S3 and Fig. S14). For *SM*, reanalysis datasets perform best, likely because they are constrained by physical laws and considers deeper soil moisture variability (Table S4 and Fig. S14). Overall, our results highlight the importance of physical constraints and of data assimilation in enhancing water balance consistency of hydrological variables (Pan et al., 2020; Tang et al., 2024; Yang et al., 2023; Ruiz-Vásquez et al., 2023).

Dataset performance varied significantly across time scales, with the highest correspondence at the monthly scale, where seasonal variability is well-captured and synoptic weather variability is mitigated. This explains the extremely lower water balance consistency observed at the annual scale for all datasets. At a daily time scale, the variability of the involved variables is high, including more extreme values, and apparently under-constrained by available observations (Maurer and Hidalgo, 2008; Fisher et al., 2008). Furthermore, we find widespread increases in water balance consistency across hydrological variables during our study period in mid-to-high latitude regions of the Northern Hemisphere (Fig. 4). These regions have experienced reduced snow-cover durations (Bormann et al., 2018) and extents (Mudryk et al., 2020), as well as less snowfall (O'gorman, 2014), which has weakened *R* seasonality (Wang et al., 2024) and enhanced the influence of *P* variability on *R* seasonality (Han et al., 2024). Given the influence patterns in Fig. 3, higher temperatures and reduced solid precipitation likely enhance *P* dataset performance. Also, the absence of strong increases in extreme precipitation events in these regions (Asadieh and Krakauer, 2015) may contribute to improved consistency. Previous studies have shown that models incorporating updated vegetation information, such as leaf area index (LAI) seasonality, perform better in these regions (Ruiz-Vásquez et al., 2023; Nogueira et al., 2021), aligning with our observed improvements over time (Fig. 4). This underscores the importance of accurately representing the coupling between *ET* and *SM* for dataset performance, as inferred from our approach.

Data availability

All data needed to evaluate the conclusions in the paper are present in the paper and/or the online repository. Additionally, their access links are provided in the following. CPC is available at <https://www.psl.noaa.gov/data/gridded/data.cpc.globalprecip.html>; CRU TS v4.06 is available at https://crudata.uea.ac.uk/cru/data/hrg/cru_ts_4.06/; UDel v5.01 is available at <https://climate.geog.udel.edu/>; EM-EARTH is available at <https://www.frdr-dfdr.ca/repo/dataset/8d30ab02-f2bd-4d05-ae43-11f4a387e5ad>; GPCC v2022 is available at https://opendata.dwd.de/climate_environment/GPCC/html/fulldata-monthly_v2022_doi_download.html; PREC/L is available at <https://psl.noaa.gov/data/gridded/data.precl.html>; CHIRPS v2.0 is available at <https://www.chc.ucsb.edu/data/chirps>; CMAP is available at <https://psl.noaa.gov/data/gridded/data.cmap.html>; CMORPH v1 is available at



477 <https://www.ncei.noaa.gov/products/climate-data-records/precipitation-cmorph>; GPCP(M) v2.3
 478 is available at <https://psl.noaa.gov/data/gridded/data.gpcp.html>; GPCP(D) v1.3 is available at
 479 <https://rda.ucar.edu/datasets/d728007/>; GPM IMERG v07 is available at
 480 https://disc.gsfc.nasa.gov/datasets/GPM_3IMERGDF_07/summary?keywords=%22IMERG%20
 481 [final%22](https://disc.gsfc.nasa.gov/datasets/GPM_3IMERGDF_07/summary?keywords=%22IMERG%20); PERSIANN-CDR is available at [https://www.ncei.noaa.gov/products/climate-data-](https://www.ncei.noaa.gov/products/climate-data-records/precipitation-persiann)
 482 [records/precipitation-persiann](https://www.ncei.noaa.gov/products/climate-data-records/precipitation-persiann); MSWEP v2.8 is available at <https://www.gloh2o.org/mswep/>;
 483 20CR v3 is available at https://psl.noaa.gov/data/gridded/data.20thC_ReanV3.html; JRA-55 is
 484 available at <https://rda.ucar.edu/datasets/d628000/>; ERA5 is available at
 485 <https://cds.climate.copernicus.eu/datasets/reanalysis-era5-single-levels?tab=overview>; NCEP-
 486 NCAR R1 is available at <https://psl.noaa.gov/data/gridded/data.ncep.reanalysis.html>; NCEP-
 487 DOE R2 is available at <https://psl.noaa.gov/data/gridded/data.ncep.reanalysis2.html>; MERRA-2
 488 is available at https://gmao.gsfc.nasa.gov/reanalysis/MERRA-2/data_access/; X-BASE is
 489 available at https://meta.icos-cp.eu/collections/_185vWiIV81AifoxCkty50YI; MODIS is
 490 available at <https://lpdaac.usgs.gov/products/mod16a2gfv061/>; PT-JPL is available at
 491 <http://josh.yosh.org/>; PML-v2 is available at <https://doi.org/10.5281/zenodo.10647618> (Zhang et
 492 al., 2024b); GLASS is available at <http://www.glass.umd.edu/Download.html>; GLEAM v4.1 is
 493 available at <https://www.gleam.eu/>; GLDAS-2.0/2.1/2.2 are available at
 494 <https://disc.gsfc.nasa.gov/datasets?keywords=GLDAS>; ERA5-land is available at
 495 <https://cds.climate.copernicus.eu/datasets/reanalysis-era5-land?tab=overview>; GRUN is available
 496 at https://figshare.com/articles/dataset/GRUN_Global_Runoff_Reconstruction/9228176; SMAP
 497 L4 v7 is available at <https://nsidc.org/data/spl4smgp/versions/7>; SoMo.ml is available at
 498 <https://www.bgc-jena.mpg.de/geodb/projects/Data.php>; ESA CCI v08.1 is available at
 499 <https://climate.esa.int/en/projects/soil-moisture/>.

500

501 **Code availability**

502 The core codes for calculating the water balance consistency of each combination and each
 503 dataset, as well as assessing the potential influence based on explainable machine learning and
 504 uncertainties of the temporal changes based on bootstrap confidence intervals, are available at
 505 <https://github.com/HowHuang/WaterBalanceConsistency>.

506

507 **Author contributions**

508 R.O. conceived the original idea, which was further developed in collaboration with H.H. and
 509 J.L. H.H. aggregated the datasets used in this study, did the analysis, and prepared the original
 510 paper. H.H., J.L., A.C., M.R.V., and R.O. contributed to interpreting the results and discussion
 511 and improving the paper.

512

513 **Competing interests**

514 The authors declare that they have no competing interests.

515

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Competing interests

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