

Tracer-based Rapid Anthropogenic Carbon Estimation (TRACE)

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1 Abstract

The ocean is one of the largest sinks for anthropogenic carbon dioxide (C_{anth}) and its removal of CO_2 from the atmosphere has been valued at hundreds of billions to trillions of US dollars in climate mitigation annually. The ecosystem impacts caused by planet-wide shifts in ocean chemistry resulting from marine C_{anth} accumulation are an active area of research. For these reasons, we need accessible tools to quantify ocean C_{anth} inventories and distributions and to predict how they might evolve in response to future emissions and mitigation activities. Unfortunately, C_{anth} estimation methods are typically only accessible to trained scientists and modelers with access to significant computational resources. Here we make modifications to the transit-time-distribution approach for C_{anth} estimation that render the method more accessible. We also release software called “Tracer-based Rapid Anthropogenic Carbon Estimation version 1” (TRACEv1) that allows users—with one line of code—to obtain C_{anth} and water mass age estimates throughout the global open ocean from user-supplied values of geographic location, pressure, salinity, temperature, and the estimate year. We use this code to generate a data product of global gridded open-ocean C_{anth} distributions (TRACEv1_GGC_{anth}, Carter, 2025) that ranges from the preindustrial era through 2500 c.e. under a range of shared socioeconomic pathways (SSPs, or atmospheric CO_2 concentration pathways). We estimated the skill of these estimates by reconstructing C_{anth} in models with known distributions of C_{anth} and transient tracers and by conducting perturbation tests. In the model-based reconstruction test, TRACEv1 reproduces the global ocean C_{anth} inventory to within $\pm 10\%$ in 1980 and 2014. We discuss implications and limitations of the projected C_{anth} distributions and highlight ways that the estimation strategy might be improved. One finding is that the ocean will continue to increase its net C_{anth} inventory at least through 2500 due to deep ocean ventilation even with the SSP where intense mitigation successfully decreases atmospheric C_{anth} by $\sim 60\%$ in 2500 relative to the 2024 concentration. A notable limitation of this and similar projections made with TRACEv1 is that ongoing and potential future warming and changing oceanic circulation patterns with climate change are not captured by the method.

2 Introduction

Humans are emitting ~ 10 PgC as carbon dioxide gas (CO_2) to the atmosphere every year and a portion of these emissions ($\sim 25\%$) has entered the ocean (Friedlingstein et al., 2022). Ocean carbon accumulation mitigates global warming by slowing atmospheric CO_2 accumulation. However—in a series of chemical processes known as ocean acidification—the elevated carbon content in seawater also shifts ocean carbonate chemistry toward lower pH and carbonate ion content and toward higher hydrogen ion (H^+) content and CO_2 partial pressure ($p\text{CO}_2$). These chemical shifts have varying and important impacts on marine organisms and potentially on entire ocean ecosystems (Doney et al., 2009, 2020). It is important to be able to distinguish between the ocean’s large natural background dissolved inorganic carbon (DIC) content and the excess anthropogenic carbon (C_{anth}) if we are to understand the extent, climate impact, and likely future outcomes of ocean C_{anth} accumulation.

Ocean C_{anth} is defined as the difference between the DIC in the modern ocean and the DIC that would be present if humans had never emitted CO_2 (Sabine et al., 2004). It is not a measurable quantity as defined. Without a direct measure, C_{anth} must be estimated, and there are numerous approaches to estimating C_{anth} within the literature including global ocean biogeochemical model (GOBM) simulations (Khatriwala et al., 2013), data-assimilation-based ocean

circulation models coupled with air-sea exchange parameterizations (Devries, 2014), approaches that rely on preformed property estimates and remineralization ratios (Vázquez-Rodríguez et al., 2009) or empirical relationships (Touratier and Goyet, 2004; Yool et al., 2010), comparisons of repeated hydrographic sections (Carter et al., 2019; Gruber et al., 2019b; Müller et al., 2023), techniques such as the transit-time-distribution (TTD) or Green's Function approaches that rely on transient tracers of air-sea exchange to infer histories of atmospheric contact and interior ocean circulation (Khatiwala et al., 2009; Waugh et al., 2006), as well as approaches that combine one or more of these other approaches (Sabine et al., 2004). Isotopic approaches address the related, but not identical, question of “how much of the DIC in seawater is of anthropogenic origin (e.g., Eide et al. 2017)?” Research continues to improve upon these methodologies and to better quantify their uncertainties, often using reconstructions of exactly-known model-simulated C_{anth} distributions (Carter et al., 2019; Clement and Gruber, 2018; He et al., 2018; Matsumoto and Gruber, 2005; Waugh et al., 2006).

There are several qualities that are desirable for C_{anth} estimation strategies. Foremost among these is accuracy, but it is also helpful for estimation approaches to be (1) accessible; (2) computationally efficient; and (3) able to return estimates for the past, present or future.

- 1) Accessibility: Implementation of most C_{anth} estimation strategies requires nuanced understanding of the methodology so that decisions can be made about the parameters used in forward or inverse models or how and whether to account for various biogeochemical processes (e.g., calcification, organic matter ballasting, or iron dynamics and limitation). In addition, many C_{anth} estimation strategies require the presence of collocated high-quality measurements of physical and biogeochemical properties (e.g., empirical multiple linear regression C_{anth} change estimates) or transient tracer content measurements (e.g., TTD or Green's Function based estimates).

- 2) Computational efficiency: Some C_{anth} estimation strategies require downloading and employing large sparse matrices (Davila et al., 2022) and others require iterative inverse model reconstructions or forward model simulations to be run with GOBMs (DeVries et al., 2017; Khatiwala et al., 2013).

- 3) Able to be estimated for the past, present, or future: Many C_{anth} estimation techniques are limited to a narrow time window. For example, the “extended multiple linear regression” approaches are usually limited to the period spanned by repeated shipboard hydrographic measurements (Carter et al., 2019; Gruber et al., 2019a; Müller et al., 2023). A related problem is the need to adjust a DIC dataset that was measured across years or decades to be specific to a single reference year or year of interest. To make this adjustment, it is important to know how much the DIC value would have changed due to C_{anth} accumulation between when it was measured and the reference year. Simplistic adjustments invoking transient steady state (Gammon et al., 1982) C_{anth} accumulation are commonly employed (Carter et al., 2021a; Clement and Gruber, 2018; Lauvset et al., 2016; Müller et al., 2023), but are problematic for larger adjustments that are often associated with longer time gaps. An example of an application that faces these challenges is given in Supplementary Text S1.

90 Here we describe, assess, and present results from a new method that we call “Tracer-based Rapid Anthropogenic
Carbon Estimation version 1” or TRACEv1, which aims to provide C_{anth} estimation that meets these needs without
overly compromising on C_{anth} estimate accuracy. TRACEv1 is an approach that retains much of the skill of the more
complex approaches and yet is quick, nearly global, easy to use, computationally efficient, able to generate plausible
projections over a limited time horizon, and requires only coordinate information (longitude, latitude, and depth),
95 salinity (S), temperature (T), the desired year for the estimate, and (for projections) the assumed shared-socioeconomic
pathway (i.e., SSP, or atmospheric CO_2 concentration over time).

In this manuscript we present three products. The first is the TRACEv1 code itself; the code is initially released only
for the MATLAB computing language, though a Python port is planned. The code contains subroutines that use neural
100 networks to remap the preformed property estimates of Carter et al. (2021b) to the locations and conditions provided
by users calling the TRACEv1 routine. The second is an estimate of the likely uncertainties in TRACEv1 estimates
based on an analysis of the errors found when the method is trained using transient tracer information extracted from
a GOBM simulation—with a spatial and temporal distribution that mirrors the availability of CFC-11, CFC-12, and
 SF_6 measurements in the real ocean—and is used to reconstruct the exactly-known GOBM C_{anth} distributions. The
105 third is a data product of global C_{anth} from TRACEv1 with varied 10-to-100-year resolution from 1750 through 2500.
This product uses a variety of SSPs for projections after 2015.

3 Methods

First, we describe the conceptual framework for TRACEv1 and explain in detail how it works. Then we introduce the
110 observational datasets used to train TRACEv1 and explain how transit time distribution parameters and preformed
properties are empirically fit and estimated on demand. Finally, we explain how TRACEv1 is used to generate the
TRACEv1_GGC $_{\text{anth}}$ product (Carter, 2025).

3.1 Conceptual framework and historical context

115 TRACEv1 emulates the inverse Gaussian (IG) TTD method for C_{anth} estimation, but with several modifications.
Traditionally, the TTD approach makes assumptions about the distribution of ages (length of time since seawater was
last in contact with the atmospheric) of the various parcels of seawater that combine to produce the seawater observed
in the ocean interior. Assumptions are also needed about the degree of air-sea equilibration with transient tracers.
These assumptions are collectively used to tune the age distribution to match transient tracer observations, and then
120 similar assumptions are used to infer the C_{anth} content that would be expected for that mixture of seawater from the
distribution of ages and the known history of atmospheric CO_2 accumulation (e.g., He et al. 2018). TRACEv1 also
follows these steps. The most important modification is that we reduce the TTD shape to a single term (α), optimize
this term to reflect transient tracer and modeled ideal age distributions as normal, and then train a neural network
capable of predicting this term using only physical measurements of seawater and coordinate information. This allows
125 us to estimate C_{anth} from a TTD without the need for collocated transient tracer observations at the time and place
where the estimate is desired.

When optimizing α , CFC-11, CFC-12, and SF₆ are dominant constraints for younger waters, while water mass ideal ages (A) (Thiele and Sarmiento, 1990)—taken from a model that assimilates transient tracer observations and measurements of the long-lived ¹⁴C radionuclide—are primarily included as a constraint for older water masses. SF₆ measurements are particularly strong constraints for the youngest waters ventilated since the 1990s maxima in CFC-11 and CFC-12 concentrations, but are only available for ~30 % of the measured bottles. All available constraints are used for optimizing all water parcels, and the strong constraint for young (old) waters and weak constraint for old (young) waters provided by transient tracers (A) is a natural result of how the values and misfits of each constraint vary with the age of the water mass. The transient tracer constraints therefore dominate in younger waters where the transient tracer measurements are largest while the A constraint dominates in water masses that are older than the advent of measurable atmospheric transient tracer concentrations in the 1940-1960s. For water parcels older than ~1940, there is essentially no sensitivity to the transient tracer information. TRACEv1 is therefore more of an observation-based product in the surface ocean and an observation-tuned-model-based product in the deep ocean.

Several recent developments have enabled TRACEv1: First, the training data are taken from the recent 2023 update to the Global Data Analysis Project version 2 (GLODAPv2.2023) data product (Lauvset et al., 2024). This data product contains >270k bottle measurements with both CFC-11 and CFC-12 and >70k more measurements with CFCs and SF₆ measurements (Fig. 1); SF₆ was first included in the 2022 GLODAP release (Lauvset et al., 2022). CFC distributions have long been used to estimate C_{anth} , and oceanographic SF₆ measurements are available from many recent cruises owing to methodological developments by Tanhua et al. (2004) and advances allowing CFC and SF₆ measurements on the same samples (Bullister et al., 2006) implemented by transient tracer teams globally (Erickson et al., 2023). Second, water mass ideal ages from the recently-released transport matrix solutions of the Ocean Circulation Inverse Model of (John et al., 2020) provide an additional constraint for TRACEv1. TRACEv1 uses a preformed property data product (Carter et al., 2021b) to estimate the composition of seawater when it was last exchanging CO₂ with the atmosphere. Finally, the approach is assessed against newly simulated C_{anth} , CFC, and SF₆ distributions (Müller, 2023) that were generated as part of the second Regional Ocean Carbon Cycle Assessment and Processes effort (RECCAP2, e.g., DeVries et al. 2023). The simulated CFC and SF₆ distributions (Schwinger, 2024) were not previously published as part of the RECCAP2 data product or used by the analyses.

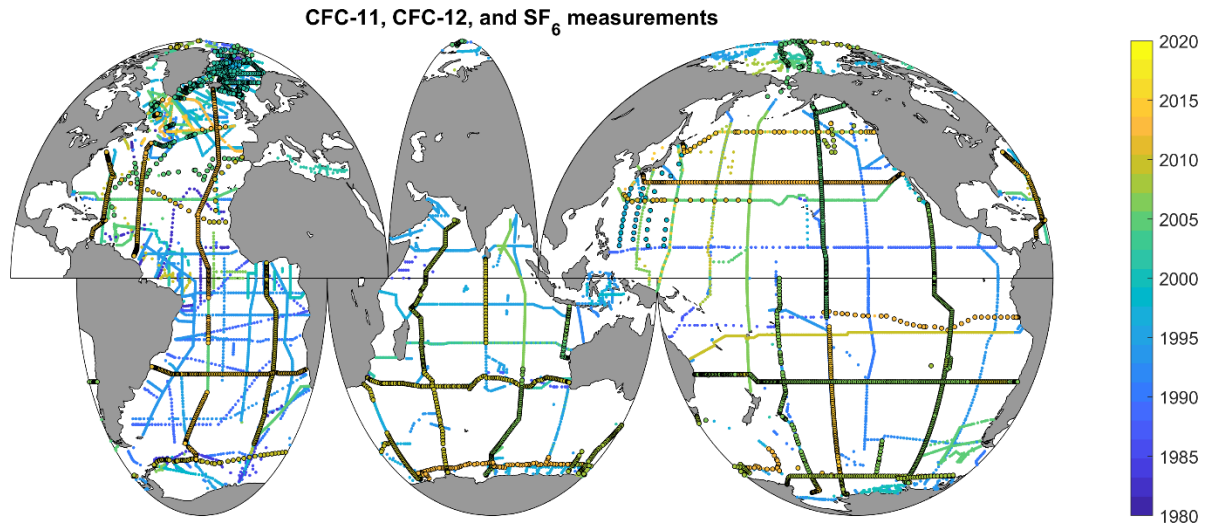


Figure 1. Locations and years of measurements of CFC-11 and CFC-12 in the GLODAPv2.2023 data product (Lauvset et al., 2024). Dark borders around measurements indicate SF_6 is available alongside CFC-11 and CFC-12.

3.2 How TRACEv1 works

We begin with a summary of the TRACEv1 functions and then explain the various steps in greater detail: The TRACEv1 code:

1. uses a neural network to estimate an age distribution for seawater from a user-specified location, T , and S , and returns the mean age if this is a desired output;
2. uses a record or projection of the atmospheric CO_2 in the years leading up to the date of the desired estimate to determine an anthropogenic CO_2 level for each component of the water mass mixture;
3. convolves the age distribution with the component's CO_2 history to estimate a component-fraction-weighted mean atmospheric CO_2 for the water parcel;
4. uses another set of neural networks to estimate the preformed properties of this water mass mixture from the user-specified location, T , and S ;
5. estimates the degree of CO_2 disequilibrium expected for the surface ocean when responding to rapid changes in atmospheric mole fraction of CO_2 , $x\text{CO}_2$;
6. and solves for the C_{anth} distribution as the difference between the DIC value that corresponds to the surface ocean equilibration level associated with the transient $x\text{CO}_2$ and the DIC value that corresponds to a “preindustrial” atmospheric $x\text{CO}_2$ of 280 ppm. The TRACEv1 code allows users to substitute arbitrary reference preindustrial $x\text{CO}_2$ values to obtain estimates that are comparable to literature estimates that have used alternative baselines, but all calculations provided herein are obtained using 280 ppm.

Committees of neural networks (henceforth just “neural networks”) are used to estimate four pieces of information from S , T , and location information in a standard TRACEv1 estimate (and a fifth neural network is invoked when T information is not supplied by the user). The neural networks are similar in construction to those used by the ESPER_NN routines (Carter et al., 2021a), and are described in more detail in Supplementary Text S2. While the

ESPER_NN routines utilize many combinations of possible predictors, only S and T are chosen for the TRACE neural networks because they are among the most frequently available predictor measurements and because they collectively represent the density structure of the ocean. Advection and diffusion along density layers in the ocean is the dominant mechanism by which C_{anth} enters the ocean interior, and variations in density, both spatially and temporally, are therefore expected to correlate with the interior ocean distribution of C_{anth} . Three of the neural networks estimate preformed biogeochemical properties of the seawater (explained below) and the fourth is a parameter related to the TTD construction called α . A fifth neural network allows T to be estimated from S if T is not provided as a user input. This is not the recommended use of TRACEv1; it is recommended that users who invoke this functionality perform validation of the estimates returned for their purposes and not rely on the validation provided in this paper, which is based on estimates obtained using both T and S .

Preformed properties are estimates of the properties that interior ocean seawater mixtures had when they last were in contact with the atmosphere near the ocean surface. These are the properties that impact air-sea gas exchange equilibrium processes when C_{anth} was last able to change through contact with the atmosphere. In TRACEv1 preformed total titration seawater alkalinity content (TA^0), preformed dissolved inorganic silicate content (Si^0), and preformed dissolved inorganic phosphate content (P^0) are collectively used with $p\text{CO}_2$ as constraints for the carbonate chemistry of seawater near the sea surface. These three quantities are estimated from three separate neural networks trained using latitude, longitude, depth, S , and T from the Lauvset et al. (2016) global gridded version of the GLODAPv2 data product as predictor information and the preformed property estimates of Carter et al. (2021b), estimated for the same gridded product, as target/validation data. Errors in preformed properties are small contributors to the overall C_{anth} uncertainty (Supplementary Text S3).

The fourth neural network estimates α , which is used to construct the TTD. The TTD is an evolution of the “water mass age” concept (Bolin and Rodhe, 1973; Hall and Haine, 2002). While a water mass age is an estimate of the average length of time since a given parcel of interior ocean seawater was last at the ocean surface, a TTD comes from the recognition that interior ocean seawater is better represented as a mixture of many different water parcels—each with a different history of atmospheric contact and interior ocean circulation—than as a single parcel of water with a single A . One-dimensional pipe flow with diffusion results in a distribution of ages that can be well approximated using an inverse gaussian (IG) age-fraction distribution (Peacock and Maltrud, 2006; Waugh et al., 2003) and provides good agreement with available transient tracer data (Sonnerup et al., 2013; Stanley et al., 2012; Waugh et al., 2004). However, there are places in the ocean where comparatively “young” (i.e., recently ventilated) waters mix with very old deep waters in appreciable amounts (e.g., Antarctic Intermediate Water, which is formed through the mixing of fresh surface waters near the polar front with upwelling upper circumpolar deep water, see: Naveira Garabato et al., 2009), and in these areas the one-dimensional pipe model age distribution is inadequate (Ito and Wang, 2017; Peacock and Maltrud, 2006). With this and similar concerns driving innovation, many variants on the underlying TTD shape have been used. However, our limited experimentation with these variants did not reveal any meaningful improvement over the simple IG distribution for reconstructing modeled C_{anth} (Hall et al., 2002; Waugh et al., 2003, 2006) so we

retain the simple IG formulation. Given the limited number of options tested, it is plausible that alternative age distributions could outperform the distribution fitting terms that we employ for TRACEv1. This is particularly likely for A estimates, as erroneous transit time distribution shapes have been shown to be less problematic for C_{anth} than for A due to the similarities between the atmospheric growth curves for transient tracers and C_{anth} (Vaughn et al., 2006).

The traditional form of the inverse Gaussian for an arbitrary coordinate variable “ x ” is:

$$f(x) = \sqrt{\frac{\lambda}{2\pi x^3}} e^{\frac{-\lambda(x-\mu)^2}{2x\mu^2}} \quad (1)$$

where μ is the mean and λ is the shape parameter. However, in TTD literature, it is more common to specify this equation as:

$$f(x) = \sqrt{\frac{\Gamma^3}{4\pi\Delta^2 x^3}} e^{\frac{-\Gamma(x-\Gamma)^2}{2x\Delta^2}} \quad (2)$$

where Γ is equivalent to μ and the new shape parameter Δ is related to λ by:

$$\lambda = \frac{\Gamma^3}{2\Delta^2} \quad (3)$$

Some consideration has been given in the literature to the ideal values for Δ and Γ for TTD analyses. Based on the results of He et al. (2018), we choose a $\Gamma=1$ and $\Delta=1/1.3$ (or ~ 0.77) and we find in our model-based assessments that this assumption performs equivalently (within uncertainties) to the common alternative assumption of $\Gamma=\Delta=1$. The standard form of the IG probability distribution with a $\Gamma=1$ and $\Delta\sim 0.77$ (Eqn. 2), or a $\mu=1$ and a $\lambda=3.4$ (Eqn. 1), is evaluated from $x=0.01$ to $x=5$ (by increments of 0.01) using the “makedist” function in MATLAB.

The predicted parameter α is used to convert a unitless IG distribution into an age distribution. This α is used to identify the ages associated with this IG probability distribution, where the age values assigned to the 500 $f(x)$ values equal $[1:500]*\alpha$ years. The resulting age-probability distribution is then interpolated to integer ages for the most recent 1000 years. When α is <2 it becomes impossible to interpolate across all 1000 years, but in these cases the missing values correspond to negligible fractional contributions and are neglected. The sum of these interpolated contributions usually diverges slightly from 1 due to the discretization of the continuous probability distribution and the inability to interpolate to all years, so the non-neglected component fractions are further divided by their sum to ensure they add to unity. Thus, when α is a large number the mean A of the Gaussian distribution is large (Fig. 2) and when α is smaller A is smaller.

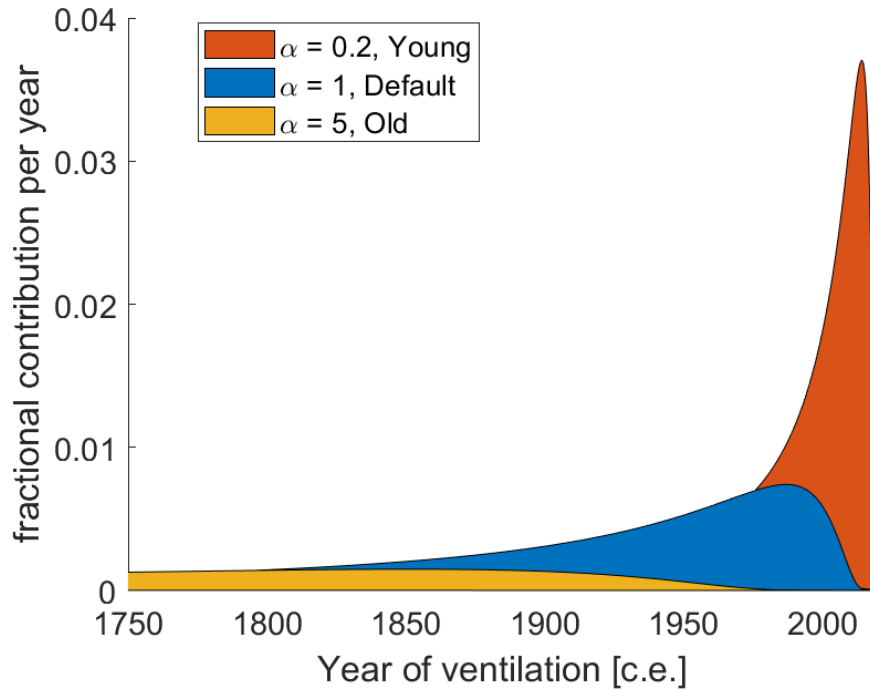


Figure 2. Three example ventilation-year distributions for a parcel of water observed in the year 2020. The “Young,” “Default,” and “Old” mixtures in orange, blue, and yellow have mean ages of ~17, 91, and 460 years, respectively. Fractions of a given color add up to 1 when summed across all years.

Once the age distribution is known, the atmospheric CO₂ record is convoluted into the age distribution as follows (Hall et al., 2002): First, the atmospheric record or projection is interpolated to obtain values for the year of the desired estimate minus the ages in the distribution. Then for each of the (up to) 1000 fractions of the water mass, the fraction-weighted mean ages (\bar{A}) and concentrations ($\bar{[X]}$) can be computed as fraction-weighted sums. E.g. for gas X with atmospheric concentration $[X]$ summed over the $i=1:1000$ years prior to the estimate of interest this would be computed as:

$$\bar{[X]} = \sum_{i=1}^{1000} f_i [X]_i \quad (4)$$

For the \bar{A} calculation, $[X_i]$ is replaced in this equation with i years. The concentration values reflect complete air-sea equilibration, which is inconsistent with net ocean uptake of CO₂ from air-sea gas exchange. For example, in the Regional Carbon Cycles and Processes model simulations there is a 108 ± 4 μatm increase in the surface ocean $p\text{CO}_2$ in 2018 relative to the preindustrial value compared to a 128.72 moles/mol change in the atmospheric $x\text{CO}_2$ (DeVries et al., 2023; Müller, 2023). Also, the air sea CO₂ disequilibrium is thought to vary temporally (He et al., 2018) and be sensitive to the rate of atmospheric $x\text{CO}_2$ change. We therefore derive an empirical relationship between atmospheric $x\text{CO}_2$ and the median model-observation-hybrid apparent surface ocean $p\text{CO}_2$ record given by Jiang et al. (2023). A variety of predictive relationships were tested, and the strongest predictive relationship (lowest RMSE) was obtained for:

$$p\text{CO}_{2,\text{oce},\text{year}} = x\text{CO}_{2,\text{atm},\text{year}} - 0.144 * (x\text{CO}_{2,\text{atm},\text{year}} - x\text{CO}_{2,\text{atm},\text{year_minus_65}}) \quad (5)$$

Equation (5) suggests the expected surface ocean $p\text{CO}_2$ value in an arbitrary year $p\text{CO}_{2,\text{oce},\text{year}}$ can be estimated as a function of the atmospheric $x\text{CO}_2$ in that year ($x\text{CO}_{2,\text{atm},\text{year_minus_65}}$) and the difference between that atmospheric value and the value in the atmosphere 65 years prior ($x\text{CO}_{2,\text{atm},\text{year}}$). Applying equation (5) to the $x\text{CO}_2$ record before use in TRACEv1 meaningfully reduces the mismatch between the simulated surface ocean $p\text{CO}_2$ and the atmospheric $x\text{CO}_2$ (Fig. 3). An additional constant offset of $-5.37 \mu\text{atm}$ was found in the best fit relationship (not shown on the right side of equation 5), but this term likely reflects the water vapor correction between $x\text{CO}_2$ and $p\text{CO}_2$ and, potentially, parameterized net model degassing of riverine carbon. TRACEv1 neglects this constant offset because the code separately applies the water vapor correction for each parcel of seawater (Dickson et al., 2007) when converting between $x\text{CO}_2$ and $p\text{CO}_2$ and because including this term would have a nearly identical impact on preindustrial $p\text{CO}_2$.

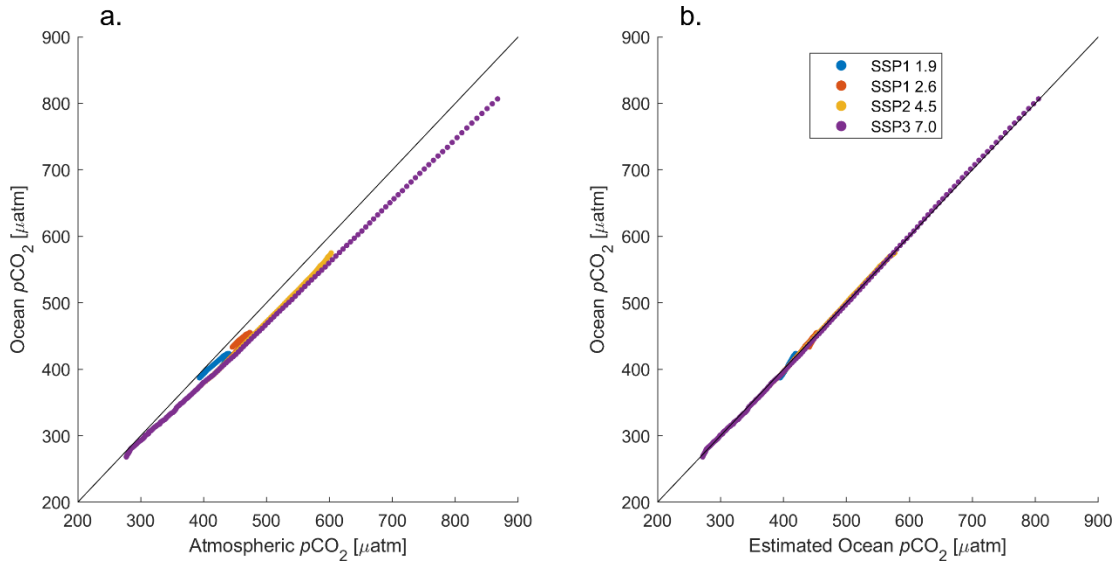


Figure 3. A comparison between surface ocean $p\text{CO}_2$ values in the model-based data product of Jiang et al. (2023) and (a.) the modeled atmospheric $x\text{CO}_2$ value and (b.) the value obtained from equation (5). Black 1:1 lines are provided for reference, and the colored dots indicate projected and historical values from 4 different SSPs.

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Once water-fraction-weighted mean $p\text{CO}_2$ values $\overline{p\text{CO}_{2,\text{oce}}}$ are estimated for a parcel of seawater, the expected equilibrium DIC value for the water parcel when last at the ocean surface is calculated using estimated TA^0 , Si^0 , and P^0 . These calculations are repeated with both the $\overline{p\text{CO}_{2,\text{oce}}}$ and a user-provided preindustrial $x\text{CO}_2$ value (default is 280 ppm, adjusted for water vapor), and their difference is attributed to C_{anth} . During fitting of the α values (described later) a similar procedure is followed for transient tracer observations with CFC and SF_6 equilibrium constants (Warner and Weiss, 1985; Bullister et al., 2002, respectively), though without adjustments for incomplete equilibration because the equilibrium timescales for these tracers are shorter than for CO_2 .

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Carbonate chemistry calculations are computed with the CO2SYS code written for MATLAB (Van Heuven et al., 2011) and modified herein to increase the tolerance for pH changes during iteration from 0.0001 to 0.001 when converging on a pH value (to speed up the calculation). Carbonate dissociation constants from Lueker et al. (2000) are used with the total boron calculation from Uppström (1974) and the K_F calculation from Perez and Fraga (1987). S and T values that are outside the viable range for these carbonate chemistry constants ($S=19$ to 48 and $T=2$ °C to 35 °C) are overridden with the nearest viable S and T values. This override has a minimal impact on most C_{anth} calculations for common seawater types, but we caution here that TRACEv1 is not intended for use in freshwater or brackish environments. Information on computing optimization is provided in Supplementary Text S4.

3.3 Data and model output used to train and run TRACEv1

The α parameter is fit to the CFC-11, CFC-12, and SF₆ partial pressures that would be found in a gas phase in complete air-sea equilibrium with seawater with the measured composition, as well as to A from the “Ocean Circulation Inverse Model” (OCIM) transport matrix (John et al., 2020) when the zero-age boundary layer is set equal to the shallowest layer in the OCIM model. For the real ocean, the transient tracer partial pressure values are taken as calculated from discrete seawater measurements in the GLODAPv2.2023 data product (Lauvset et al., 2024). Collocated measurements of salinity and temperature are also extracted from this data product. For the model reconstruction test, C_{anth} , S , and T are taken from or computed from the NorESM RECCAP2 simulations (Müller, 2023). In addition to the standard RECCAP2 outputs, this model was also used to simulate CFC-11, CFC-12, and SF₆ through the start of 2015 (Schwinger, 2024). The approaches used to obtain scattered values from gridded model output and to obtain scattered ages from the OCIM transport matrix are given in Supplementary Text S5.

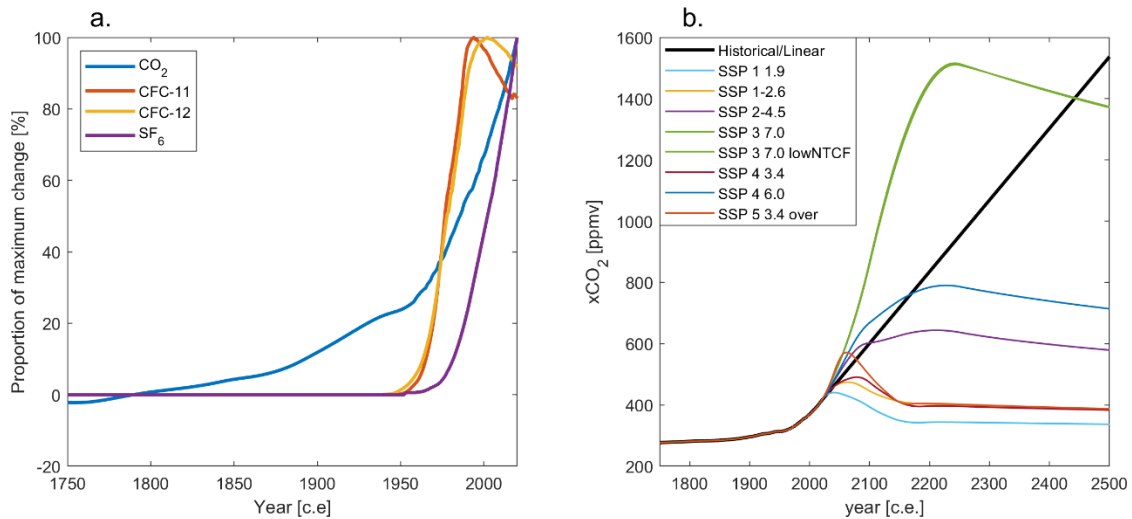


Figure 4. (a.) The time history of atmospheric transient tracer and CO₂ concentrations expressed as a percentage of their maximum deviation through 2020 c.e. from their assigned preindustrial values of 0 ppmv for CFC-11, CFC-12, and SF₆ and 280 ppmv for CO₂. **(b.)** The 9 atmospheric CO₂ concentration pathway options used by TRACEv1, with all but “Historical/Linear” being SSPs as given by Meinshausen

et al. (2020). Both versions of SSP 3 7.0 fall nearly on top of each other on this plot and are assigned the same colors.

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TRACEv1 allows 9+ options for atmospheric CO₂ projections/histories and relies on a single reconstruction of transient tracers (Fig. 4). Observed atmospheric CFC and SF₆ information (Fig. 4a) is taken from a data product compiled by the United States Geological Survey's Groundwater Dating Laboratory (see: data availability). The atmospheric xCO₂ reconstruction starting in the year 1 c.e. and continuing through the year 1000 is taken from the synthesis by Frank et al. (2010) for all CO₂ options. Before the year 1 c.e. all reconstructions are set to a constant value of xCO₂=277.14 ppmv equaling the atmospheric concentration in the year 1 c.e. From 1001 and through 1959, all reconstructions follow the historical concentrations of the SSPs as defined by Meinshausen et al. (2020), which are identical over this time range. From 1959 through 2022, the first option, which is called "Historical/Linear" and is the default option if no alternative is specified, uses the Mauna Loa measurements by Keeling et al. (1976) and Thoning et al. (1989), and if TRACEv1 is instructed to use this record to generate an estimate for a year that is after 2022 then the slope from a linear trend fit to the last 10 years of the historical record is used to project to the year of the desired estimate. The remaining 8 options are SSPs: 1-1.9, 1-2.6, 2-4.5, 3-7.0, 3-7.0-lowNTCF, 4-3.4, 4-6.0, and 5-3.4-over, all as defined by Meinshausen et al. (2020). The SSPs diverge from each other starting in 2017. Between year 1959 and 2017 c.e. the SSP values have a small average bias of +0.6 ppmv compared to the historical Mauna Loa measurements with a root-mean squared disagreement of 0.8 ppmv. Additional custom concentration pathways options can be added by appending a new column of atmospheric CO₂ concentrations to a plain text file (CO2TrajectoriesAdjusted.txt) that is read by TRACEv1 and by entering the number of the new option in the TRACEv1 code (i.e., if a 10th option is added the CO₂ pathway option for the "AtmCO2Trajectory" input would be 10). However, any user provided concentration pathways should be adjusted by equation 5 before appending them to this file.

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3.4 Fitting TRACEv1 parameters

The parameters are optimized using a bounded minimum "search" function ("fminsearchbnd" in MATLAB) with an initial value of $\alpha=1$, an upper bound of $\alpha=1000$, and a lower bound of $\alpha=0.001$. This function uses a Nelder-Mead simplex algorithm (Lagarias et al., 2006) with iterative variations of the α term by 5 % to minimize a cost function. For each iteration of this solver, the $j=3$ (i.e., CFC-11, CFC-12, and SF₆) transient tracer constraints and the A are first calculated as described in Eqn. 4. The cost function that is minimized for this solver (ε^2) is the sum of the squared normalized errors of the three partial pressures and A , or:

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$$\varepsilon^2 = \sum_{j=1}^3 \left(\frac{pX_{\text{meas}}^j - pX_{\text{calc}}^j}{pX_{\text{ATM}}^j} \right)^2 + \left(\frac{A_{\text{OCIM}} - A_{\text{calc}}}{A_{\text{Max}}} \right)^2 \quad (5)$$

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Here the pX_{meas}^j is the measured partial pressure of transient tracer j extracted from discrete GLODAPv2.2023 product or (for the model validation experiments) from GOBM output; pX_{calc}^j is the value calculated from α and the record of atmospheric trace gas concentrations as described above; and $pX_{\text{ATM}_2020}^j$ is the atmospheric partial

pressure of tracer j in the year 2020. This third term is included to normalize the errors to a more comparable scale. Without this term, the $p\text{CFC-12}$ (SF_6) errors would be assigned higher (lower) weight than the errors in the other two transient tracers due to their greater (smaller) atmospheric partial pressures. Similarly, A_{OCIM} is the interpolated OCIM age, A_{calc} is the calculated A , and A_{max} is the ideal age of the oldest grid cell found in the OCIM age calculations (1354 years).

This process is repeated for the observational record and for the model output. The version of TRACEv1 that is trained on model output is referred to as TRACEv1_validation_NorESM, and details for this comparison are provided in Supplementary Text S6. The version trained on real world observations is referred to as TRACEv1. We generate 10 versions of TRACEv1 in which we retrain TRACEv1 after perturbing the transient tracer measurements from each cruise in GLODAPv2.2023 by a cruise-wide relative offset and each measurement by measurement-specific random perturbations. In Supplementary Text S7 we quantify the likely impact of measurement uncertainties in the transient tracer measurements on the final C_{anth} estimates via Monte Carlo analysis.

3.5 C_{anth} data product creation

We use the gridded, temporally-averaged GLODAPv2 data product Lauvset et al. (2016) for S , T , latitude, longitude, and depth and vary only the year of the estimate to equal [1750; 1800; 1850; 1900; 1950; 1980; 1994.5; 2000; 2002; 2007.5; 2010; 2014.5; 2020; 2030; 2050; and 2100]. Estimates are only made using the historical/linear and SSP1-1.9 reconstructions prior to 2010 (and we note that the SSPs are identical over this period). In 2020 and thereafter, estimates are provided for each of the 9 CO_2 concentration pathway options separately. The estimates in 1994.5, 2002, 2007, and 2014 are provided for comparison and interoperability with published literature distributions (Gruber et al., 2019a; Lauvset et al., 2016; Müller et al., 2023; Sabine et al., 2004).

We anticipate that the small differences between the 1850 and 1750 CO_2 concentration estimates could prove useful for reconciling literature estimates of C_{anth} that have been made to be specific to these two common choices of reference year. Our C_{anth} definition is specific to the 280 ppmv atmospheric concentration rather than to a specific year. It is therefore possible for TRACEv1 to return very small negative C_{anth} values, particularly for estimates following periods when CO_2 reached minima of $\sim 277 \pm 1$ ppmv in the first, sixth, and eighteenth centuries c.e. The last time the atmospheric CO_2 concentration was believed to equal 280 ppmv was 1790 c.e. (Frank et al. 2010) and TRACEv1 allows users to specify an alternative reference concentration.

4 Results and discussion

We discuss the uncertainty assessment and compare TRACEv1 reconstructions to alternatives, discuss the TRACEv1 projections through 2500, and highlight some areas where TRACEv1 is limited and might be improved. We compare TRACEv1 A estimates to alternatives in Supplementary Text S8.

4.1 Uncertainty estimation

375 In Supplementary Text S5 we describe the results of our uncertainty assessments from model reconstruction ($_{MR}$) C_{anth} distributions. In Supplementary Text S6 we present the results of the Monte Carlo ($_{MC}$) analysis. Here, we combine the results of these analyses to estimate the uncertainty of TRACEv1 ($U_{TRACEv1}$) estimates that results from several sources. The model C_{anth} reconstruction estimates reveal methodological uncertainties including the limitations of an IG TTD and the inaccuracies associated with using a neural network across a large geographical area, as well as the
 380 uncertainties that result from potential OCIM A distribution and preformed property distribution errors. The Monte Carlo analysis reveals uncertainties that result from random uncertainties and cruise-wide offsets in transient tracer concentration measurements. We add these uncertainties in quadrature to obtain the overall uncertainty estimate ($\pm 1\sigma$) for TRACEv1 ($U_{TRACEv1}$):

$$385 \quad U_{TRACEv1} = \sqrt{u_{MC}^2 + u_{MR}^2} \quad (6)$$

Here, u_{MC} is the Monte Carlo RMSE estimate of $1 \mu\text{mol kg}^{-1}$ for C_{anth} and $\pm 0.3\%$ for inventories, u_{MR} is the uncertainty estimate from the model reconstruction of $4.4 \mu\text{mol kg}^{-1}$ for C_{anth} and 15% for inventories, conservatively chosen since the model reconstruction reproduces inventories to within 10% in 1980 and 2014. The uncertainty appears to
 390 grow with the estimate and over time, so 15% of the estimated C_{anth} is used when this value exceeds $4.4 \mu\text{mol kg}^{-1}$. These uncertainty estimates neglect the contribution of uncertainty in the S and T values used in the neural network to the overall C_{anth} estimate uncertainty, which we believe to be small relative to $U_{TRACEv1}$, but we note that users can conduct perturbation tests if they are supplying particularly uncertain S and T information. $U_{TRACEv1}$ is an optional output from TRACEv1. In Supplementary Text S6 we show that reconstruction errors are significantly larger in
 395 marginal seas with few or no transient tracer measurements and are also elevated near coasts and in areas of strong upwelling. $U_{TRACEv1}$ should be considered an underestimate in these regions. We do not attempt to estimate uncertainty in the optional A TRACEv1 output.

4.2 C_{anth} reconstructions and data product comparisons

400 The reconstructions and projections from TRACEv1 (Table 1) match past anthropogenic inventory estimates obtained from analyses based on measurements of DIC changes and distributions (Fig. 5) in 1994 ($118(\pm 26)$ PgC from Sabine et al. (2004) vs. $127(\pm 19)$ for TRACEv1), 2007 ($118(\pm 26) + 29(\pm 2.5) = 147(\pm 26)$ Pg C; Müller et al. (2023), updating Gruber et al. 2019a vs. $161(\pm 24)$ for TRACEv1), and 2014 ($118(\pm 26) + 29(\pm 2.5) + 27(\pm 2.5) = 174(\pm 26)$ Pg C from Müller et al. 2023 vs. $182(\pm 27)$ for TRACEv1). The agreement with the DIC based approaches is reassuring, as there is little
 405 overlap in the data or methodologies used to generate the DIC-based estimates compared to the data and methods used to obtain the TRACEv1 routines: Müller et al. (2023), did not rely on transient tracer information and the data used in this study are, on average, more recent than the CFC-11 and CFC-12 information used by Sabine et al. (2004) (Fig. 1).

410 The regional distribution of C_{anth} inventory qualitatively matches prior estimates as well, with significantly higher
column inventory estimates in the North Atlantic (Fig. 6; Table 1). Similarly, there are areas of higher column
inventories generally in the Southern Hemispheres of the other ocean basins as mode and intermediate waters are
exported northward from the Southern Ocean. Within Figure 6, bathymetric features such as the Kerguelen Plateau
and the Mid-Atlantic Ridge are visible when they displace waters that would otherwise contain meaningful quantities
415 of C_{anth} , and a band of low column inventories can be seen within the Antarctic Circumpolar Current where old deep
waters upwell to near the ocean surface.

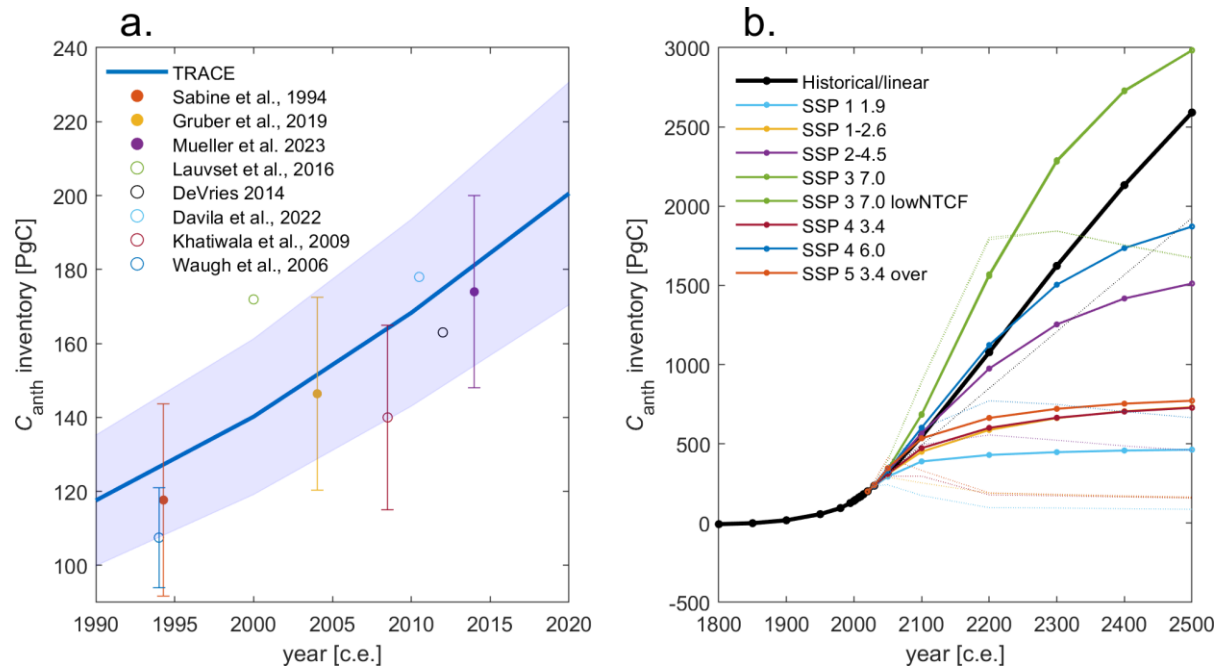


Figure 5. Panel (a.) shows the global C_{anth} inventory projected by TRACEv1 with a blue range indicating the uncertainty estimate. Circles show estimates from literature data-based C_{anth} distribution estimates with filled circles indicating estimates rooted primarily in DIC measurements and open circles indicating estimates rooted primarily in fitting transient tracer distributions. Panel (b.) shows projected values through 2500 c.e. in solid lines for various SSPs as labeled. Thin dotted lines indicate the inventories that would be obtained by projecting the 2020 c.e. estimate using transient steady state assumptions (Gammon et al., 1982) with the atmospheric CO_2 concentrations from the SSPs of the same color line. Both versions of SSP 3 7.0 fall nearly on top of each other on this plot and are assigned the same colors.

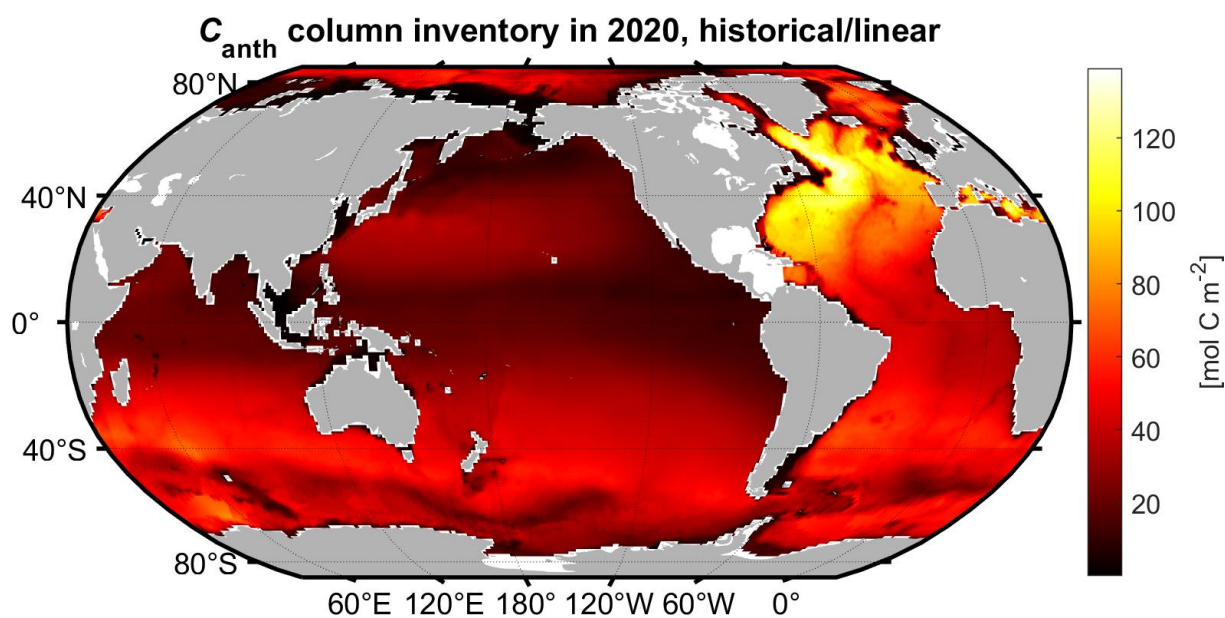


Figure 6. Column inventory of C_{anth} mapped for 2020 using TRACEv1 with the historical/linear atmospheric CO_2 pathway.

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Table 1. TRACEv1 estimates of C_{anth} inventories (in $\text{PgC} \pm 1\sigma$ uncertainties) calculated by ocean basin calculated for the specified points in time. The Atlantic becomes the Arctic at 40°N whereas the Pacific transitions at 67°N . The Southern Ocean is defined as the area in all basins south of 40°S . Anthropogenic inventories are small and negative in 1750 because of the ~ 200 year-long period with a < 280 ppmv CO_2 atmosphere prior to the Industrial Era.

Year	Pacific	Atlantic	Indian	Arctic	Southern	Total
1750	-3(± 1)	-2(± 1)	-1(± 1)	-1(± 1)	-2(± 1)	-8(± 2)
1800	-2(± 1)	-2(± 1)	-1(± 1)	0(± 1)	-2(± 1)	-7(± 1)
1850	-1(± 1)	0(± 1)	0(± 1)	0(± 1)	0(± 1)	-1(± 1)
1900	4(± 1)	4(± 1)	2(± 1)	2(± 1)	4(± 1)	18(± 3)
1950	15(± 2)	14(± 2)	7(± 2)	6(± 1)	14(± 2)	56(± 9)
1980	25(± 4)	24(± 4)	13(± 2)	9(± 2)	24(± 4)	95(± 14)
1994	35(± 5)	32(± 5)	17(± 3)	11(± 2)	32(± 5)	127(± 19)
2000	39(± 6)	35(± 5)	19(± 3)	13(± 2)	35(± 5)	140(± 21)
2002	40(± 6)	37(± 6)	20(± 3)	13(± 2)	37(± 6)	147(± 22)
2007	44(± 7)	40(± 6)	21(± 3)	15(± 2)	40(± 6)	161(± 24)
2010	47(± 7)	42(± 6)	22(± 4)	15(± 3)	42(± 6)	168(± 25)
2014	50(± 8)	45(± 7)	24(± 4)	16(± 3)	46(± 7)	182(± 27)
2020	56(± 8)	50(± 8)	27(± 4)	18(± 3)	50(± 8)	201(± 30)

TRACEv1 has a more variable agreement with estimates based on transient tracer information. The estimates are higher than—but within uncertainties of—the Green's function fits of Khatiwala et al. (2009) and a TTD based inventory estimate (Vaughn et al., 2006). TRACEv1 estimates of $168(\pm 25)$ PgC are within uncertainties of the 178 PgC inventory of Davila et al. (2022) calculated in 2010 using the Total Matrix Intercomparison approach. At 172

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(± 26) PgC, TRACEv1 estimates are near the OCIM estimates of DeVries (2014) of 160-166 PgC in 2012, though this not surprising since the A estimates implied by an OCIM solution were used as a fitting parameter for TRACEv1. The TTD-based C_{anth} inventory for 2002 in the gridded GLODAPv2 data product of Lauvset et al. (2016) is 179 PgC compared to a TRACEv1 estimate of 147(± 22) PgC in the same year. In Supplementary Text S9 we show that the main disagreement between the TRACE estimates and the GLODAPv2 gridded product (Lauvset et al., 2016) is found in the deep ocean, where GLODAPv2 inventories consistently exceed TRACE inventories below ~ 500 m. There are several possible reasons for this disagreement, but the true cause is unclear.

4.3 C_{anth} inventory projections

Table 2. TRACEv1 projections of global ocean C_{anth} inventories (in PgC) until the middle of the millennium if the indicated atmospheric CO_2 concentration pathway is followed.

	2020	2030	2050	2100	2200	2300	2400	2500
Historical/Linear	201(± 30)	236(± 35)	315(± 47)	545(± 82)	1078(± 162)	1623(± 243)	2132(± 320)	2591(± 389)
SSP_1_1.9	200(± 30)	235(± 35)	293(± 44)	389(± 58)	430(± 64)	448(± 67)	458(± 69)	463(± 69)
SSP_1-2.6	200(± 30)	236(± 35)	310(± 46)	450(± 68)	588(± 88)	662(± 99)	706(± 106)	731(± 110)
SSP_2-4.5	200(± 30)	238(± 36)	326(± 49)	567(± 85)	975(± 146)	1254(± 188)	1417(± 213)	1512(± 227)
SSP_3-7.0	200(± 30)	240(± 36)	341(± 51)	687(± 103)	1570(± 235)	2290(± 343)	2730(± 410)	2984(± 448)
SSP_3-7.0lowNTCF	200(± 30)	240(± 36)	341(± 51)	683(± 102)	1559(± 234)	2281(± 342)	2725(± 409)	2982(± 447)
SSP_4_3.4	200(± 30)	236(± 35)	311(± 47)	473(± 71)	601(± 90)	665(± 100)	704(± 106)	728(± 109)
SSP_4-6.0	200(± 30)	237(± 36)	329(± 49)	602(± 90)	1123(± 169)	1504(± 226)	1735(± 260)	1871(± 281)
SSP_5-3.4over	200(± 30)	240(± 36)	346(± 52)	535(± 80)	663(± 100)	721(± 108)	754(± 113)	772(± 116)

The C_{anth} inventory projections (Table 2, Fig. 5b) indicate that even if humanity acts to rapidly reduce C_{anth} in the atmosphere and manages to bring atmospheric $x\text{CO}_2$ down to 337 μatm by the middle of the millennium in line with the ambitious SSP 1-1.9, the ocean will never—on this time horizon—cease to take up additional C_{anth} , picking up an additional 5.4 PgC between 2400 and 2500 c.e. This builds on the findings of Koven et al. (2022) and Jones et al. (2016) using full model simulations through 2300 c.e., and suggests that the impacts of ocean acidification are likely to continue to spread throughout the ocean depths even with a highly successful carbon management policy. Nevertheless, such action remains important for preventing ocean acidification because the degree of surface and interior ocean acidification depends strongly on which SSP we follow. This is particularly true for the well-lit surface euphotic zone that is the base of most marine food webs: the relative proportion of marine C_{anth} shifts increasingly from the surface ocean to the ocean depths over time (Fig. 7a), and this tendency becomes more pronounced the more rapidly and completely that atmospheric CO_2 emissions are curtailed and reversed (Fig. 7b). Indeed, several SSPs show reduced surface C_{anth} relative to modern values despite the continued ocean C_{anth} accumulation. An important caveat is that these findings do not consider the impacts of changes in heat and freshwater content, circulation, or changes in the ocean's biological pump, and only reflect the impact expected from changing atmospheric $x\text{CO}_2$ and ocean buffer capacity.

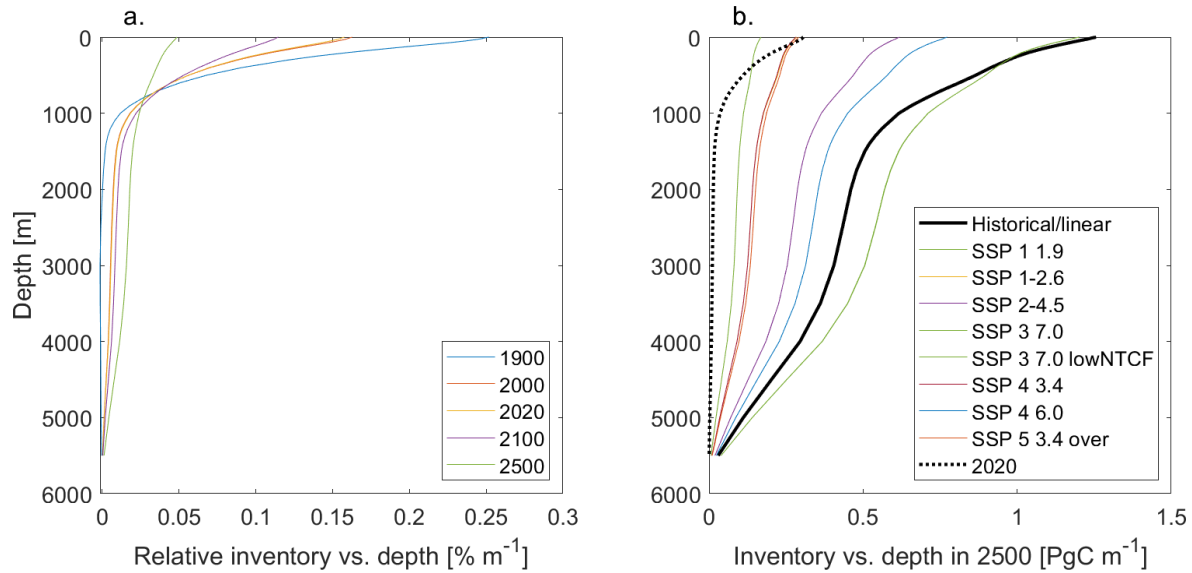


Figure 7. (a.) The relative inventory of C_{anth} vs. depth in various years of the historical/linear projection, expressed as the percentage of the total DIC inventory that is found within each 1 m interval. Here, a shrinking surface value indicates a greater proportion of the signal is found at depth, but does not necessarily imply a lesser surface C_{anth} . Panel **(b.)** shows the total inventory in 2500 vs. depth in solid lines for each of the CO₂ concentration pathways used by TRACEv1, with the 2020 historical/linear inventory plotted as a dashed line for comparison. Both versions of SSP 3 7.0 fall nearly on top of each other on this plot and are assigned the same colors.

One intended use for TRACEv1 is adjusting DIC measurement to a reference year. The simple approximation of transient steady state (Gammon et al., 1982) has been used in several recent studies (e.g., Lauvset et al. 2016; Clement and Gruber 2018; Carter et al. 2021a; Müller et al. 2023), and our projections show that this assumption performs plausibly for projections over short timescales. However, we contend that TRACEv1 provides a superior means of adjusting DIC measurements to be appropriate for a reference year. For example, the differences between modeled C_{anth} between 1980 and 2014 in NorESM disagree with the differences between TRACEv1 estimates for those same years by an average of $-0.1 (\pm 3.0) \mu\text{mol kg}^{-1}$. The statistics are worse at $-1.2 (\pm 3.6) \mu\text{mol kg}^{-1}$ when modeled differences are compared instead to the differences between the 1980 C_{anth} values and the 1980 values scaled to 2014 using transient steady state assumptions. Thus, both adjustments are reasonable from 1980 to 2014, but the transient steady state adjustment tends to overpredict the change. Also, unlike TRACEv1, transient steady state adjustments require an independent estimate of C_{anth} (for the comparison above they were provided the exactly-correct model C_{anth} distribution in the earlier year, though this is never known in the real ocean) Finally, the transient steady state assumption is also known to break down if the atmosphere ceases to increase in its tracer concentration exponentially, and this occurs for CO₂ in all SSPs by 2500 c.e. and in most of them much sooner (Meinshausen et al., 2020). It can be seen in these cases that transient steady state results in large errors in the projected C_{anth} inventories by mid-millennium and even projects spurious decreases (Fig. 5b).

4.4 Limitations and future directions

There are several notable limitations of the TRACEv1 method:

1. It presumes fixed circulation and is unable to resolve most timescales and modes of C_{anth} variability.
2. It shows larger reconstruction errors in regions that lack training data, which is a common problem for neural networks and other regression strategies (e.g., Carter et al., 2021). As transient tracer measurements with the strong SF_6 constraint are still relatively rare (approximately 5 % of the GLODAPv2.2023 data product contains all three transient tracer measurements), it is likely that TRACE will improve as more such measurements become incorporated. However, version 1 of TRACE should be used with caution in regions without training data, and this caution applies to many marginal seas (Figs. 1 and S1).
3. TRACEv1 appears to overestimate C_{anth} in surface waters where there is meaningful upwelling, though perhaps not by a larger extent than alternative C_{anth} estimation strategies. This is unfortunate because such surface waters are frequently found in areas of naturally low pH that are of interest for ocean acidification research.
4. The method has not yet been well validated in a high-resolution model representation of a coastal environment, so its uncertainties are not well estimated outside of the open ocean. While the circulation information encoded in TRACEv1 has been optimized within a limited parameter space, it is likely—based on past literature exploring many options for simplifying the complex distributions of myriad water types that mix in the ocean interior—that the comparatively simple single term that we employ herein to constrain interior ocean age distributions could be meaningfully improved. We leave this to future work.
5. Furthermore, the TTD approach is limited by the need for an assumed air-sea disequilibrium and the possibility that the degree of disequilibrium for transient tracers varies meaningfully over time and space and between CFCs and SF_6 (Shao et al., 2013; Sonnerup et al., 2015) and differs from the related term for air-sea CO_2 disequilibria, which seems likely due to the slow relaxation of CO_2 disequilibria (Jones et al., 2014) and the faster rate of transient tracer equilibration (Wanninkhof 2014). A common assumption of 100 % equilibration tends to result in TTD approaches overestimating the C_{anth} (Waugh et al., 2006). We include an empirical relationship intended to deal with this issue but note that its formulation remains somewhat ad hoc and based on model simulations of surface ocean conditions.
6. TRACEv1 is aimed at resolving the accumulation of C_{anth} under “steady state” circulation. However, it is possible that it is able to resolve some non-steady-state components of C_{anth} accumulation when it is called with time-varying temperature and salinity records as predictors. It is yet untested to what degree this is an effective strategy for capturing such variability.

We include the version number in TRACEv1 both to signal that future improvements are likely and to disambiguate the function from other software routines that might have similar names. There are several ways that TRACEv1 might be improved.

1. Some fitting strategies have shown improvements when the signal of interest is fit to the disagreement between observations and a model prior, instead of being fit directly to the signal. This approach could

improve estimates if a model prior age distribution can be obtained and be re-gridded to global locations of interest in a computationally efficient manner.

2. Further optimization of the shape of the TTD could result in improved C_{anth} reconstructions.
3. MATLAB is an open-source language, but it is not freely available. It would therefore further improve the accessibility of C_{anth} estimates if TRACEv1 were released in a freely-available computing package. Prior experience suggests that a modest amount of script is required to convert neural-networks from MATLAB to Python, and somewhat less is required to transition the code to Julia. This is left to future work.

5 Data availability statement

The gridded GLODAP product is available at <https://glodap.info/>. The CFC and SF₆ atmospheric record data product was obtained from the USGS Groundwater Dating Lab website https://water.usgs.gov/lab/software/air_curve/index.html. The TRACEv1_GGC_{anth} product is available at Zenodo <https://doi.org/10.5281/zenodo.15003059> (Carter, 2025). The NorESM modeled distributions of transient tracers are also available with Zenodo (Schwinger, 2024).

6 Code availability statement

TRACEv1 code can be found and freely obtained at <https://github.com/BRCScienceProducts/TRACEv1>.

7 Conclusions

We present a new method called TRACEv1 for rapidly estimating the time varying C_{anth} distribution throughout the open ocean, including detailed error estimates. TRACEv1 is available as a function in the MATLAB programming language. We further provide a data product with C_{anth} distributions for a range of years (TRACEv1_GGC_{anth}, Carter, 2025) on the GLODAPv2 gridded product grid used by Lauvset et al. (2016). We use this data product to examine how the C_{anth} distribution varies with depth and time and show that the ocean can be expected to continue to increase its C_{anth} inventory through 2500 c.e. for all SSPs. We find that SSP_3-7.0 results in the largest projected 2500 ocean C_{anth} inventory of 2984 (± 448) PgC, and this represents a ~ 15 -fold increase over the 2020 C_{anth} inventory.

There are several strengths of the TRACEv1 method, which relies on TTDs to estimate C_{anth} distributions from a time-evolving atmospheric CO₂ trajectory. The method is easy and quick to implement, shows fidelity to model reconstructions and agreement with recently published data-based estimates, and only requires S and T measurements and spatiotemporal coordinate information to produce an estimate. It also provides means to plausibly adjust collections of DIC measurements collected over time to a common time by removing the influences of C_{anth} changes. While the reconstruction fidelity of TRACEv1 estimates were quite high in a test using model output with exactly known C_{anth} distributions, we nevertheless believe the primary advantage of TRACEv1 and the new data product is their accessibility.

8 Competing interests

The authors declare they have no conflict of interest.

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10 Author contributions

BRC led conceptualization of the work, coding, drafting of the manuscript, and generation of the data products. All authors aided with conceptualization and provided edits and feedback on drafts of the manuscript. JSchwinger also generated simulated fields of CFCs and SF_6 . JDSandborn, JES, and LMD also tested portions of the code.

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