# **30** months data set of glider physico-chemical data off Mayotte Island near the Fani Maoré volcano

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**Abstract.** In May 2018, an unprecedented long and intense seismic-volcanic crisis broke out off the island of Mayotte (Indian Ocean) and was associated with the birth of an underwater volcano (Fani Maoré). Since then, an integrated observation network has been created (REVOSIMA), with the given objective of monitoring and better understanding underwater volcanic phenomena. Recently, an unmanned submarine glider (SeaExplorer glider) autonomous ocean glider (ALSEAMAR's SeaEx-

- 5 plorer) has been deployed to supplement the data obtained during a series of oceanographic surveys (MAYOBS) carried out on an annual basis. Operated by ALSEAMAR in collaboration with IFREMER, the glider performed a continuous monitoring of 30 months of the water column between September 2021 and April 2024 from the sea surface to 1,250 meters water depth with the objective to acquire hydrological properties, water currents and dissolved gas concentrations. This monitoring already showed that it is feasible and valuable to measure showed the feasibility and value to measure autonomously, continuously
- 10 and at a high spatio-temporal scale, physical (temperature, salinity, ocean current) and biogeochemical parameters  $(O_2, CH_4, CO_2, bubbles/droplets, vertical speeds anomalies related to droplets) over several months from a glider. In particular, innovating sensing capabilities (e.g., MINICO2, ADCP) have shown great potential in the context of the Mayotte seismic volcano crisis, despite technical challenges (complex algorithms, sensor capabilities, etc.).$

## 1 Introduction

15 Mayotte is a French overseas department, part of the volcanic archipelago of the Comoros Islands, northwest of Madagascar. It was last volcanically active on land less than 7,000 years ago (Zinke *et al.*, 2003; 2005).

On May 10, 2018, a seismic-volcanic crisis of unprecedented intensity and duration began off the two main islands of Grande-Terre and Petite-Terre (Lemoine *et al.*, 2020). More than 11,000 earthquakes were recorded, up to a magnitude of 5.9, in an area where only two seismic events had been recorded since 1972 (Feuillet *et al.*, 2021). At sea, the epicenters of these earthquakes

20 were divided into the Proximal area (5 to 15 km east of Petite-Terre) and Distal area (25 km east of Petite-Terre). Following the start of this seismic crisis on July 1, 2018, surface displacements were measured by the GPS stations present in



**Figure 1.** Map view of Mayotte (a); the Fani Maoré volcano edifice is represented by the white triangle which lies 50 km southeast of Mayotte and the Horseshoe area is represented by the red triangle and the red dotted line located 10 km east of Mayotte. Map view of Africa and Middle East (b) where the red triangle star is the Mayotte Island. Map illustrating the bathymetry of the Horseshoe structure (c). The red dots correspond to the discovered emission sites of magmatic fluid identified with the multibeam echosounder during the REVOSIMA MAYOBS cruises (https://doi.org/10.12770/070818f6-6520-49e4-bafd-9d4d0609bf7d) and validated by in situ visual observations with the ROV VICTOR during the GEOFLAMME cruise (DOI 10.17600/18001297). Bathymetric data were provided with a resolution of 20 m (https://doi.org/10.18142/291).

Mayotte, revealing an eastward displacement of between 21 and 25 cm for all these stations, as well as a subsidence of between 10 and 19 cm depending on their location (Feuillet *et al.*, 2021).

In response to this crisis, French laboratories and institutions (<del>IPGP/CNRS/BRGM/IFREMER/IPGS</del> Institut de Physique du Globe de Paris (IPGP), Centre National de la Recherche Scientifique (CNRS), Bureau de Recherches Géologiques et Minières

- 25 Globe de Paris (IPGP), Centre National de la Recherche Scientifique (CNRS), Bureau de Recherches Géologiques et Minières (BRGM), Institut Français de Recherche pour l'Exploitation de la Mer (IFREMER), Institut de Physique du Globe de Strasbourg (IPGS)) created a volcanological and seismological monitoring network in Mayotte, the Réseau de surveillance volcanologique et sismologique de Mayotte (REVOSIMA) http://www.ipgp.fr/fr/revosima/acteurs-reseau. This observatory, both marine and terrestrial, benefits from the financial support of several ministries (Ministry of Overseas, Ministry of the Inte-
- 30 rior, Ministry of Higher Education, Research and Innovation, Ministry of Ecological Transition and Solidarity) and aims to further our understanding of the seismic-volcanic activity for preservatives measures in order to protect populations. As part

of REVOSIMA, several oceanographic cruises have been carried out (MAYOBS cruises, https://doi.org/10.18142/291) and bulletins monitoring seismo-volcanic activity are published monthly (http://www.ipgp.fr/fr/revosima/actualites-reseau). The first oceanographic cruise (MAYOBS1) was carried out from May 02 to 18, 2019 on the RV *Marion Dufresne*, and led to the

- 35 discovery of the on-going eruption of the brand new Fani Maoré submarine eruptive volcano. A new volcanic structure formed during this crisis around 800 m high, located 50 km off the coast of Mayotte, at a depth of 3,500 meters below sea surface m (Feuillet *et al.*, 2021, Aiken *et al.*, 2021, Fig. 1). The estimated volume of magma emitted during this eruptive period is  $6.55 \ km^3$ , ranking this event as the largest submarine volcanic eruption ever documented (Feuillet *et al.*, 2021). Four other on-going lava flows were revealed during subsequent oceanographic cruises revealing the presence of four other lava outlets
- 40 in the nearby area around the new volcano (Feuillet *et al*, 2021.). During the MAYOBS cruises, the Horseshoe preexisting volcanic structure, located above the Proximal swarm at an average seafloor depth of 1,400 mbss m, was a particular area of interest (Fig. 1). Acoustic plumes and geochemical anomalies (elevated concentrations of dissolved gases such as carbon dioxide  $CO_2$ , methane  $CH_4$  and dihydrogen  $H_2$ ) were detected using a multibeam echo-sounder and CTD rosette measurements. These acoustic plumes are detectable in the water column from the seafloor up to around 500 mbss m and are distributed over
- 45 23 active emission sites to this day identified to date (Scalabrin, 2023; Fig. 1). while The specific magmatic origin of these magmatic fluid emissions has yet to been determined (Mastin *et al.*, 2023). The ocean circulation around the Mayotte Island, and more generally in the Mozambique Channel, is part of the Agulhas Current. This current is one of the strongest and most regular known, as well as the strongest in the Southern Hemisphere with a western land boundary. The ocean circulation around the Mayotte Island is mainly influenced by the instabilities of Northeast
- 50 Madagascar Current (NEMC) which originates from the splitting of the westward South Equatorial Current (SEC) (Schott. et al., 2009). While the anticyclonic eddies, mainly generated west of Cape Amber (the northernmost cape of Madagascar), strongly influence the circulation around Mayotte island, cyclonic eddies formed along the northwest coast of Madagascar rarely reach the island (Collins et al., 2014). The large-scale circulation is also strongly influenced by seasonally reversing winds linked to the monsoon regimes (Manyilizu et al., 2016).
- 55 This highly complex circulation consists of a southward flow coupled with mesoscale eddies (diameter ≥ 300 km) that can affect the entire water column (de Ruijter *et al.*, 2002; Halo *et al.*, 2014). The general circulation in the area is even more complex due to the significant influence of the islands on the local hydrodynamic context. There is also considerable variability in hydrographic parameters in the first 1,500 m of the water column. The temporal

variability of these phenomena ranges from short-term (a few hours to a few days) to annual variations, due in particular to the

- 60 passage of anticyclonic eddies to the south. The signature of these eddies can be seen in hydrographic characteristics such as temperature and salinity. Significant variability in hydrographic parameters is observed within the upper 1,500 m of the water column. This temporal variability spans a broad range of timescales. High-frequency variations (from a few hours to several days) are primarily driven by tidal forcing. At intermediate timescales, fluctuations with periodicity of 60 to 90 days are associated with the passage of anticyclonic eddies, particularly in the southern part of the study area (Collins *et al.*, 2014). On
- 65 longer timescales, annual variability is evident and is largely governed by large-scale climatic forcing. Strong deep currents ( $\approx 0.4 0.5 \text{ m/s}$ ) below 1,000 m are also present in the area, locally highly variable with strong interactions with the bathymetry

and the tide.

Relatively little reference data is available for the near area of the Mayotte Island and it remains poorly understood. Tide gauges have been installed on the coasts of the main islands, and internal tidal waves have been observed during MAYOBS campaigns.

70 In order to monitor the dissolved gas dynamics related to volcanic events in the Horseshoe area and as a complement to regular oceanographic cruises, SeaExplorer glider deployments from ALSEAMAR (https://www.alseamar-alcen.com/) equiped with biogeochemical sensors are carried out since September 17, 2022 2021 with funding from REVOSIMA. These deployments are still carried out up to date to ensure the monitoring of this seismo-volcanic crisis.

The SeaExplorer glider is a member of the family of autonomous underwater drones that can provide continuous collection of high-resolution underwater data between the surface and its maximum depth rating (1,250 m) over very wide spatial (several

- thousand kilometers) and temporal (up to two months) coverage. Supervised by an Iridium satellite link, the vehicle enables near-real-time observation and monitoring of the oceans from a control center on land. The Global Ocean Observing System (GOOS), led by the Intergovernmental Oceanographic Commission (IOC) of UNESCO, and co-sponsored by the World Meteorological Organization (WMO), the United Nations Environment Programme (UNEP) and the International Science Council
- 80 (ISC), has been coordinating national ocean observing efforts for more than 20 years. In this international effort, the role of autonomous glider observations has always been seen as a means to compensate for the limitations of other observing means (Stommel, 1989). The contribution of gliders began in earnest in the 2010s, when the technology was mature enough to contribute to global observations (Testor *et al.*, 2010). Since 2016, the OceanGliders component of GOOS has also been in charge of the coordination and improvement of the use of gliders around the world.

## 85 2 Data and Methods

#### 2.1 Mission overview

The glider has been deployed at sea near to the eastern coast of Petite-Terre since September 17, 2021 (12 km southwest of the Horseshoe area 12°53.5', 45°19' E). It is operated for 14 days on average before being recovered at sea to recover collect the full data set. The glider is then immobilized on land for one night to recharge the battery and perform regular maintenance

90 before being redeployed the next day.

In the course of more than two and a half years of deployment, six gliders have been used for 72 deployments (see Appendix A table A1).

These gliders are equipped with a CTD (conductivity, temperature, depth), either a SeaBird GPCTD or a LEGATO CTD from RBR. Dissolved oxygen sensors are also deployed, an SBE43F from SeaBird coupled with the GPCTD and an AROD-FT from

95 JFE coupled with the LEGATO. These two sets of sensors, while having small technology differences (pumped sensors for SeaBird and unpumped sensors for RBR and JFE), provide comparable data (see Appendix D table D1). The scientific payload also includes an ADCP 1MHz from Nortek (Signature1000 specs with casing modified for glider integration AD2CP), a METS (dissolved methane sensor) from Franatech and a MINICO2 (dissolved CO<sub>2</sub> sensor) from Pro-Oceanus (see Appendix A table A1).

- 100 To carry out the mission, a specific and unusual sampling strategy was implemented. Until August 2023, the glider was limited to its maximum immersion depth of 1,000 mbss m. In order to stay as near as possible to the seafloor where magmatic fluid emissions occur and should be sampled, the glider's navigation consisted in a 3-phase progression : a downward phase where the glider reached a depth of 1,000 mbss m; a forward navigation phase, with about followed by about ten ascent/descent phases (i.e. yo) between 900 and 1,000 mbss m; followed by and a final phase of ascent to the surface. Dives carried out in the
- 105 Horseshoe area last on average 8 to 9 hours, with 6 hours in average between 900 and 1,000 m, covering a distance of around 6 km. This radial navigation strategy enables objective sampling of the zone of interest, covering all its quadrants equally, with maximum sampling effort at its center, decreasing progressively with distance (Fig. 2). For the first time, two glider prototypes with a maximum immersion capacity of 1,250 mbss m have also been deployed in

For the first time, two glider prototypes with a maximum immersion capacity of 1,250 mbss m have also been deployed in the area since August 2023. A slightly different navigation method was chosen, opting for spirals instead of straight forward
110 dives. The radius of these spirals is 1.5 km, in order to cover the entire study area as nearly as possible over the duration of a

- Initially, a wide mapping of the area has been chosen until August 2023 to detect seeps seafloor fluid emissions and get an idea of the physico-chemical properties over a large area. With this new navigation method, sampling is then focused on better characterization of the seeps active fluid sites (Fig. 2).
- 115 These spirals also consist of a downward phase to a depth of 1,250 mbss m, followed by several yos between 800 and 1,250 mbss m, and finally an ascent to the surface. These types of dives last an average of 10 hours. This sampling method was chosen to ensure the good quality of data from dissolved gas sensors by flushing the sensors (see section 2.2.2) and to focus the navigation on known active sites and their immediate surroundings.

The amount of data produced during continuous acquisition at high sample rates between September 2021 and April 2024 is quite substantial ( $\sim 2.2$  million measuring points per sensor corresponding to  $\sim 22,000$  dives).

#### 2.2 Data processing

deployment.

The CTD and dissolved gas sensors mounted on the SeaExplorer glider acquire measurements at a frequency of 1 Hz, subsequently averaged into 30-second time series available through the SEANOE data center (see Data availability). To optimize power consumption, the ADCP operates at a lower sampling frequency of 0.1 Hz, with its data similarly averaged into 30second intervals.

#### 2.2.1 CTD and DO data

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For the sensor pair GPCTD and SBE43F processing, the salinity (SAL) is derived from raw conductivity measurements and the potential density with reference pressure of 0 dbar is approximated with the 75-term function of temperature (TEMP), salinity and pressure (PRES) (Roquet *et al.*, 2015). Computations were performed according to international standards and

using TEOS-10 GOOS standards (http://www.teos-10.org/pubs/IOC-XXV-3\_e.pdf).
 Data processing is carried out in accordance with OceanGliders SOPs (Lopez-Garcia *et al.*, 2022, https://github.com/OceanGlidersCommunity). Moreover, the thermal lag effect was described and addressed using the method-



**Figure 2.** Map illustrating the sampling effort based on the number of profiles acquired below with the 1,000 mbss m max depth rating SeaExplorer between September 2021 and August 2023 in rectangles of  $0.5 \ 0.25 \ km^2$  (a) and map illustrating the sampling effort based on the number of profiles acquired by the 1,250 mbss m max depth rating SeaExplorer between August 2023 and April 2024 in rectangles of  $0.5 \ 0.25 \ km^2$  (b). The triangles are the active fluid emission sites identified with the multibeam echosounder during the REVOSIMA MAYOBS cruises (DOI 10.12770/070818f6-6520-49e4-bafd-9d4d0609bf7d) and validated by *in situ* visual observations with the ROV VICTOR during the GEOFLAMME cruise (DOI 10.17600/18001297). Isobaths are processed from GEBCO gridded bathymetry data (DOI 10.5285/1c44ce99-0a0d-5f4f-e063-7086abc0ea0f).

#### ology described in Garau et al., 2011 for both CTD sensors.

Computation of dissolved oxygen data in physical units was performed following Owens and Millard, 1985 algorithm.

135 For the sensor pair LEGATO CTD and AROD-FT, the data are processed internally by the sensors. Dissolved oxygen data are directly available in  $\mu mol/kg$  while SAL data is also computed from the conductivity cell within the sensor.

 $O_2$  time-series acquired with the different sensors used underwent large discontinuities, which were ubiquitously related to instrumental deficiencies. To face with this issue, the time-series was split into discrete segments according to the different regimes, all based on <del>Ocean Glider</del> OceanGliders SOP (Lopez-Garcia *et al.*, 2022). The assembled proposed adjustments

140 (gain) were applied to make the entire glider time-series continuous. Gain values applied for each discontinuity can be found in Appendix B table B1. Illustrative examples of profile corrections are presented in Appendix C Fig. C1. Sensors unit, range, precision and resolution can be found in Appendix D table D1.

#### 2.2.2 Dissolved gases CH<sub>4</sub> and CO<sub>2</sub> data

The response time of membrane-based sensors is a major constraint for profiling platforms (Fiedler et al., 2013). Although the

145 glider is a rather slow profiling device, the MINICO2 response time cause an appreciable hysteresis in vertical  $CO_2$  profiles. A time-lag correction algorithm (Miloshevich *et al.*, 2004) has been applied on carefully smoothed vertical profiles of  $CO_2$  (to minimize noise amplification caused by the processing algorithm), using the following model, sequentially:

$$CO_{2,corr}(t) = \frac{CO_{2,raw}(t) - CO_{2,raw}(t-1)e^{\frac{-\Delta t}{\tau}}}{1 - e^{\frac{-\Delta t}{\tau}}}$$
(1)

Where  $CO_{2,raw}(t)$  is the measured value at the time t,  $CO_{2,raw}(t-1)$  is the measured value at the previous time stamp,  $\Delta t$  is

- the time between two measurements, CO<sub>2,corr</sub>(t) is the time-lag corrected (TLC) measurement at t and τ is the response time. Previous studies have shown pronounced changes in τ that linearly depends on water TEMP (Fietzek *et al.*, 2014): the warmer the water, the faster the response time. In the absence of published values for the MINICO2 sensor, the linear relationship was determined empirically minimizing the difference in CO<sub>2</sub> between upcast and downcast profiles of a dive. Finally, raw CO<sub>2</sub> data recorded in ppm were converted in µmol/l from manufacturer calculation sheet and using in-situ temperature and salinity values measured by the CTD.
  - The measurement of  $CH_4$  might be impacted by various external factors such as temperature, in-situ  $CH_4$  or the moving speed of the glider. Main consequences are an artificially increasing  $CH_4$  with decreasing temperature, an hysteresis between the uplift and the downlift phases of a profile and thermal and temporal lags (Meurer *et al.*, 2021, Russell-Cargil *et al.*, 2018).
- In the present study, these issues were first addressed by adapting the sampling strategy. Indeed, the glider was programmed to dive in deep multiple yos to limit the impact of varying environmental conditions. This way, it is expected that temporal changes in  $CH_4$  (e.g. induced by natural seepage) would be more easily detectable compared to a situation where the glider would cross regularly strong temperature gradients. Comparison of  $CH_4$  profiles between uplift and downlift upcast and downcast phases enabled the computation of a lag in the sensor response time ( $\tau$ ) of about 6 minutes. Adjusted  $CH_4$  ( $CH_{4,corr}$ ) were thus calculated following the Meurer *et al.*, 2021 algorithm:

165 
$$CH_{4,corr}(t) = CH_4(t+\tau)$$
 (2)

where t is the time, while  $\tau$  varies according to the sensor used (Appendix A table A1). Sensors unit, range, precision and resolution can be found in Appendix D table D1.

#### 2.2.3 ADCP data

170 For the purpose of this project, the ADCP was programmed to obtain water-current profiles with a high-resolution. Values of main tunable parameters can be found in Table 1. The method used to retrieve ocean currents is the "shear method" (Visbeck, 2002) to substract the unknown motion of the glider from the absolute water velocity calculated by the ADCP. It is worth noting that glider ADCP measurements must undergo several quality control steps before profiles of ocean velocity

#### Table 1. ADCP configuration and processing

Parameter	Description	Values
Position	Sensor mounting	Downward looking
NPING	Number of ping averaged	4
CS	Cell size	<del>1</del> 2 m
CN	Number of cells	<del>30</del> 15
SR	Sampling rate	10s

can be properly estimated. It is a critical issue and this must be done with great caution. Pasqueron de Formmervault et al.,

- 175 2018 developed a number of tests specifically adapted for the SeaExplorer glider. As stated in Pasqueron de Fommervault *et al.*, 2018, ocean velocity data retrieved from glider-mounted ADCP show a mean difference of 1.5 cm/s compared to reference mooring data. This value corresponds to a simple yo pattern using a SeaExplorer glider. In our case, using repeated multi-yo patterns until August 2023, followed by spiral multi-yos from August 2023 to April 2024, the uncertainty is likely higher than 1.5 cm/s. Based on our preliminary assessments, it may remain below 10 cm/s, although this upper bound should be
- 180 considered with caution.

The quality of the data set was assessed at the end of each mission by comparing the depth-integrated water-current between two consecutive surfacings to the mean current deduced from the hydrodynamical model of the glider (model calculating the glider's position according to the various navigation parameters recorded during its yo).

The processing of water-current data with the "shear method" requires reconstructing vertical profiles by cutting the time-series on the basis of dives. In case of multi-yos, which are not optimal to retrieve best quality water-current measurements, all yos

- 185 on the basis of dives. In case of multi-yos, which are not optimal to retrieve best quality water-current measurements, all yos between two consecutive surfacings are merged to reconstruct a single average water-current profile. Since the tidal current oscillates over a period of about 12 hours, its oscillations are therefore almost always averaged over the duration of a 10-hours dive. To process the ADCP data, overlapping shear values were averaged over a given interval of 2 m to determine a mean shear profile for a dive.
- 190 While ADCPs are primarily used to measure the velocity of the particles, they can also provide information about the backscatter index (BI) that in turn is a proxy of the density of backscatterers in the water-column scatterers in the water. This information is measured in the form of the intensity of the received reflections, also referred to as the backscattering strength or signal amplitude. The method to retrieve BI from raw ADCP measurments employs a formula based on the sonar equation for sound scattering from small particles (Deines, 1999; Van Haren and Gostiaux, 2010; Mullison, 2017; Gentil *et al.*, 2020):

$$BI = EI + Tl_a + Tl_w \tag{3}$$

EI is the echo intensity estimated from ADCP signal amplitude from all beams using the Mulison (2017) equation.  $Tl_g$  is the beam spherical spreading, which is simply a geometric term due to the cone shape of the acoustic beams.  $Tl_w$  is the transmission loss by the sound absorption in seawater calculated according to Francois and Garrison (1982) and taking into account absorption by boric acid and magnesium sulfate.

200 Finally, glider ADCP measurements also directly allows to compute vertical velocities by subtracting the glider motion from pressure measurements:

$$U_{z_G}(z,t) = \frac{\Delta z(z,t)}{\Delta t(z,t)} \tag{4}$$

where Δz(z,t)/Δt(z,t) is the temporal derivative of the glider depth between two consecutive ADCP measurements. This computation is not accurate enough to obtain vertical oceanic velocities (O mm/s) but adequate to measure large vertical movements of scatterers such as CO<sub>2</sub> droplets (O cm/s).

## 2.3 Quality control process

An objective and automatic quality control (QC) procedure was applied on the basis of UNESCO oceanographic best practices Based on UNESCO's best oceanographic practices (https://repository.oceanbestpractices.org/handle/11329/413), which are also used for Argo floats, an objective and automatic quality control (QC) process was applied. Quality flags (QF) are composed

210 of four quality values (Table 2).

The procedure allows to flag outliers but may be deficient in identifying some erroneous data. Tests presented hereafter relate

Table 2. Quality flag scheme

Quality flag value	Quality flag name	Definition
1	Good	Passed quality control
2	Not evaluated	QC test not performed
3	Suspect	Failed subjective QC test
4	Bad	Failed objective QC test
5	Below detection level	Applicable for $CH_4$ data below the sensor detection level $(3 \ nmol/l)$

to the other variables and are based on published methods (Pouliquen 2011, Schmechtig *et al.*, 2016) and recommended by the scientific community within international programs, such as EGO quality control manual for CTD and BGC (BioGeoChemical) data (https://archimer.fr/doc/00403/51485/92689.pdf, 2022).

215 A gross filter is applied on observed data using a global range test first (Table 3) with min and max values taken from EGO quality control manual World Ocean Atlas 2018 documentation (Garcia *et al.*, 2019). Values that fail this test are flagged with a QF = 4. To our knowledge there are not yet international recommendation for  $CH_4$  and  $CO_2$ , thus values were chosen based on *in situ* measurements from MAYOBS cruises.

For all parameters, data acquired when the CTD pressure is negative (i.e. in-air measurement) were flagged bad (QF = 4).

Furthermore, a large difference between sequential measurements, where one measurement greatly differs from adjacent ones, were also flagged bad if failing the following algorithm (only used to identify spikes in temperature, salinity and  $O_2$  profiles, EGO quality control manual, 2022):

Table 3. Global range test derived from World Ocean Atlas 2018 climatology used for QC

Parameter	Min value	Max value
Temperature [°C]	<del>-2.5</del> 4	<del>40</del> 30
Salinity [PSU]	<del>2</del> 34.7	<del>41</del> 35.3
Dissolved oxygen $[\mu mol/kg]$	<del>-5</del> 100	<del>600</del> 220
Dissolved $CH_4$ [ $nmol/l$ ]	0	2000
$CO_2 ~[\mu mol/l]$	5	100

$$Test = \left|\frac{V2 - (V3 + V1)}{2}\right| - \left|\frac{V3 - V1}{2}\right| \tag{5}$$

where V2 is the measurement being tested as a spike, and V1 and V3 are the values preceding and ensuing. The V2 value is flagged when the test value exceeds:

TEMP : 6.0°C for PRES < 500 db or 2.0°C for PRES  $\geq$  500 db

SAL : 0.9 for PRES < 500 db or 0.3 for PRES  $\geq 500$  db

 $O_2$  : 50  $\mu mol/kg$  for PRES <500 db or 25  $\mu mol/kg$  for PRES  ${\geq}500$  db

To our knowledge there are no international recommendations for  $CH_4$  and  $CO_2$  yet. Thus, no spike test was applied on these variables.

Finally, subjective visual inspection was performed for each variable to identify outliers that were not flagged by the automatic and objective procedure. These measurements were associated with a QF = 3.

Membrane-based sensors ( $CO_2$  and  $CH_4$ ) are also deficient at high glider's speed (lag cannot be compensated correctly).

235 Thus,  $CO_2$  and  $CH_4$  data acquired at glider's speed exceeding 0.25 m/s were flagged and excluded. This typically occurs when the glider ascends in an alarm state, which is rather rare.

All data provided has been quality controlled. Therefore, QF = 2 is not used in this data set.

Following these various objective and subjective tests, the remaining data volume of each data is provided in Appendix E table E1.

240 Every 6 months, a reassessment of the processing chain (algorithm, QC) and delayed mode adjustments (drift, offset) is proposed.

## 3 Results and discussion

#### 3.1 Hydrological data set

Hydrological data presented are adjusted and associated with a QF = 1.

245 Time-series of temperature, salinity and potential density are presented in Fig. 3, averaged vertical profiles are presented in

Fig. 4 and temperature-salinity diagram exhibiting the different water masses is shown in Fig. 5.

As for temperature, vertical profiles exhibit a relatively warm upper layer ( $\sim 0.100 \text{ mbss m}$ , 26-30 °C). The seasonal thermocline (steep thermal gradient of  $\sim 0.1 \text{ °C/m}$ ) is observed between  $\sim 100-200 \text{ mbss m}$  and the permanent thermocline is located at  $\sim 500 \text{ mbss m}$  and is mainly composed of South Indian Central Water (SICW, Miramontes *et al.*, 2019). Below 500 mbss

250 m, temperature are in the range 5-10 °C, with a minimum reached below 1,000 mbss m. In this layer, both Red Sea Water (RSW), that enters into the Mozambique Channel from the north, and Antarctic Intermediate Water (AAIW), that enters from the south are found (Miramontes *et al.*, 2019).

The vertical distribution of the salinity is more complex. Overall, the upper layer is characterized by values ranging from  $\sim$  34.7 and 35.5 PSU. A subsurface salinity maximum is observed at  $\sim$  200-300 mbss m with salinity values reaching up to 35.5

255 PSU. At around 600 mbss m, a local salinity minimum (34.6-34.8 PSU) is observed but followed by a slight increase to reach  $\sim$  34.85 below 1,000 mbss m.

Deeper in the water-column (i.e., below  $\sim 100 \text{ mbss m}$ ), the variability in hydrological properties is lower. However, disruptions in the vertical distribution of temperature and salinity is elearly viewable visible, such as between June and July 2022 (between the gray dotted lines in Fig. 3) and can be attributed to the general circulation of the area or the mesoscale variability. Below 1,000 mbss m the variations are  $\sim 1^{\circ}$ C and  $\sim 0.1$  for temperature and salinity respectively (Fig. 6).

- Most of the temporal variability is observed in the surface layer, above the 1024 kg  $m^{-3}$  isopycnal. These changes are particularly obvious in the temperature-salinity diagram (Fig. 5), but are puzzling. They can indicate indicating the succession of two distinct water-masses (Collins *et al.*, 2016). Indeed, low salinity are typical of the Tropical Surface Water and contrasts with the higher salinity Subtropical Surface Waters (Di Marco *et al.*, 2002). Surface temperature exceeding 29°C (which are regularly
- 265 observed from December to April, Fig. 4 and 7) can also be the signature of the influence on the South Equatorial Current that contains Pacific waters (Di Marco *et al.*, 2002) or associated to the transient presence of mesoscale eddies. Finally, and according to Wyrtki (1971), seasonal processes (and episodically tropical storms) may also account for the observed variability. Highest sea-surface temperatures and low salinity are generally observed during austral summer while in winter, colder and saltier waters dominate. This seasonal variability is observed in this part of the water column (Fig. 7), with warm ( $\sim 27 - 28$
- 270 °C) and salty (~ 35.3 − 35.4) surface waters from November 2021 to July 2022 and from October 2022 to July 2023 during warm and humid austral summer in Mayotte.

The analysis of the data set also highlighted the importance of smaller temporal scales processes. In particular, vertical fluctuations of potential density levels (and temperature and salinity) of several dozen meters increasing as it gets close to the bottom were observed at a  $\sim 12$  h period (Fig. 7). Likely a result of internal tides, the sampling strategy chosen consisting of deep multi-yos unfortunately does not allow their quantification and study (section 2.2.3).

275 multi-yos unfortunately does not allow their quantification and study

# 3.2 Dissolved gas data set

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Similarly to the hydrological data set, data presented are adjusted and associated with a QF = 1.

Measured  $O_2$ ,  $CO_2$  and  $CH_4$  concentrations by the glider are shown in Fig. 3. Typical vertical distributions are observed (Fig. 4) and can be explained by ubiquitous physical (e.g., dissolution, sea-air exchanges) and biological oceanic processes



**Figure 3.** Temperature (a), salinity (b), potential density with reference pressure of 0 dbar (c), dissolved oxygen (d),  $CO_2$  (e) and  $CH_4$  (f) Hovmöller diagram in function of depth (Y-axis) and time (X-axis). Isolines are calculated by applying a Gaussian filter to each data field. White areas correspond to time periods with no data due to sensor downtime or glider recovery.



**Figure 4.** Averaged vertical profiles of temperature (a), salinity (b),  $O_2$  (blue) and apparent oxygen utilization (AOU, orange) (c),  $CO_2$  (d),  $CH_4$  (e) and backscatter index (BI) calculated from the cell 2 of the ADCP (f) over 10 meter bins for the whole data set with variability represented as  $\pm 2$  standard deviations (shaded areas).

280 (photosynthesis and respiration).

High  $O_2$  concentrations corresponding to oxygen saturation concentration are measured ( $O_2$  concentrations of about 180-200  $\mu mol/kg$ , apparent oxygen utilization between 0-20  $\mu mol/kg$ , Fig. 3 and 4) at the surface layer (0 - 100 mbss m) because of both dissolution from the atmosphere and  $O_2$  production by phytoplankton. As the distance to the surface increases  $O_2$  generally declines, due to  $O_2$  removal by consumption of deep-water organisms and by the decomposition of organic material

by bacteria (Hedgpeth, 1957). In the glider data set, minimum  $O_2$  values ( $O_2$  in the range 70-100  $\mu mol/kg$ ) are observed below 1,000 mbss m. In spite of this decrease,  $O_2$  content rise to a subsurface maximum at ~ 400-500 mbss m with values reaching up to 200  $\mu mol/kg$ . This high  $O_2$  core (> 180  $\mu mol/kg$ ) is characteristic of the South Indian Central Water (Di Marco *et al.*, 2002).

Regarding the  $CO_2$  vertical distribution (Fig. 4), it is essentially the reverse of  $O_2$ , mainly because both gases are involved

290 in the same biological processes in opposite ways. In the surface, photosynthesis consumes  $CO_2$  and thus concentrations are low (~ 15  $\mu mol/l$ ). In deeper waters,  $CO_2$  concentration increases as respiration exceeds photosynthesis and decomposition of organic matter adds additional  $CO_2$  to the water. In this data set, minimum  $CO_2$  concentrations are found in the surface



Figure 5. Temperature salinity diagram. The color indicates the  $O_2$  concentration and the water masses associated are written noted. TSW stand for Tropical Surface Water, STSW for Subtropical Surface Waters, SICW for South Indian Central Water, AAIW for Antarctic Intermediate Water and RSW for Red Sea Water.

layer (0 - 100 mbss m) with concentrations measured between 15-20  $\mu mol/l$ , and maximum  $CO_2$  values are measured below 1,000 mbss m depth with concentrations generally higher than 40  $\mu mol/l$  and sporadically exceeding 50  $\mu mol/l$ . Moreover, the signature of SICW with its oxygen maximum at ~ 400-500 mbss m (Di Marco *et al.*, 2002) is not matched by a  $CO_2$ 

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minimum at this depth.

The vertical distribution of  $CH_4$  differs significantly from the ones of  $O_2$  and  $CO_2$  (Fig. 3 and 4). Almost no  $CH_4$  is detected in the layer 0-600 mbss m (values are below 10 nmol/l). This is not surprising because the ocean is supposed to be depleted in  $CH_4$  apart from specific areas (methanogenesis in marine sediments, natural seepage by volcanoes or hydrothermal vents,

- 300 pollution, Oremland *et al.*, 1978). Most of  $CH_4$  increases occur in the 900-1,250 mbss m layer where the sampling effort is maximum. In this layer, when  $CH_4$  anomalies are detected (above the sensor detection limit), a gradient of increasing concentration with depth is observed. High values relative to the background are regularly observed with a maximum recorded on February 18, 2022, when  $CH_4$  reached 120 nmol/l at a 1,000 mbss m. Although observations above 900 mbss m are scarce, several vertical profiles also show significant  $CH_4$  concentrations up to 700 mbss m.
- There is also variability in dissolved gas concentrations, with periods (e.g., September 2022 to mid-October 2022 and mid-November 2022 to February 2023) of decreasing  $CH_4$  or  $CO_2$  concentrations not yet explained (Fig. 8).



**Figure 6.** Surface layer (0 to 5 mbss m) daily average temperature (a) and salinity (b) and deep layer (950 to 1,250 mbss m) daily average temperature (c) and salinity (d). Color alternation reflects the succession of glider missions.

The amount of data produced during continuous acquisition at high sample rates is substantial (~ 2.2 million measuring points per sensor corresponding to ~ 22,000 profiles), and Considering the amount of data produced, semi-automatic methods are thus required to reduce this data set to relevant information. Here we focus on parameters that track magmatic fluid emissions  $(CO_2 \text{ and } CH_4)$  and define anomalies as observations that deviate significantly from the majority of the data.

- Identifying anomalies (that refer to fluid emissions) is challenging since it requires the decoupling between natural variability (e.g., water masses, seasonality) and changes induced by fluid emissions. In particular, CO<sub>2</sub> and CH<sub>4</sub> signals are characterised by slowly varying background values related to dissolved gases accumulation and flushing over a large area. The CH<sub>4</sub> baseline is low (<10 nmol/l) and has a magnitude of variability of about 6 nmol/l. On the other hand, CO<sub>2</sub> baseline is more elevated
  315 (~ 45 µmol/l at a 1,250 mbss m), because of the natural presence of CO<sub>2</sub> in seawater and CO<sub>2</sub> anomalies below 900 mbss
  - m, but fluctuations around the mean values do not exceed ~  $3 \mu mol/l$ .

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Results also show that both  $CO_2$  and  $CH_4$  baselines have similar temporal evolutions, supporting the hypothesis that this variability is likely to be real. For the purpose of anomaly detection, the baseline was thus subtracted to the raw data:

$$Gas, anomaly_{deep}(t) = Gas, measured_{deep}(t) - Gas, baseline_{deep}(t)$$

$$\tag{6}$$



**Figure 7.** High-frequency ( $\sim 12$  h period) oscillations of temperature (a) and salinity (b) in function of depth (Y-axis) and time (X-axis). Glider depth is represented by the light gray dotted-line and Isopyenes isopycnals are also calculated and displayed in black. Data are interpolated with a triangulation-based cubic interpolation over a 12 m grid.

320 However, the cause of this low-frequency variability still remains to be clarified. At this time, it is not clear if baseline fluctuations are related to accumulation/dispersion processes or induced by changes in fluid emissions rate, both compatible with the chosen anomaly definition.

Of the 22000 profiles, 5 % were associated with significant  $CH_4$  anomalies (greater than the sensor detection limit plus twice the standard deviation) and 2 % with significant  $CO_2$  anomalies related to dissolved gas emissions (same definition as for the  $CH_4$ ).

Data show that  $CO_2$  and  $O_2$  have similar patterns. Such a co-variation is expected in the ocean and related to biotic processes. Examining this relation at depth > 700 mbss m (i.e., below the STSW) indeed confirms a high  $CO_2$  and  $O_2$  correlation (linear correlation coefficient,  $R^2 = 0.96$ ). Several single measuring points deviate from the linear relationship (Fig. 8). They are all found in the upper curve, i.e. at depth where  $CO_2$  is high and  $O_2$  low. Most of these points are also associated with high  $CH_4$ 

330 concentrations, which strongly suggests that these  $CO_2$  anomalies are related to a non-biotic  $CO_2$  source.

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Figure 8.  $O_2/CO_2$  relationship below 700 mbss m, the colorbar indicates the  $CH_4$  concentration. Data are taken from September 2021 to January 2023 and below 600 mbss m.

#### 3.3 Ocean current and acoustic backscatter data set

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ADCP-derived water currents show a large profile-to-profile variability that encompass, in all likelihood, spatial and temporal variability. Strongest currents are measured in the surface (0-100 mbss m layer) but velocities remain elevated up down to 1,250 mbss m (Fig. 9).

Overall, eastward velocities do not exhibit clear patterns. Values are oscillating with no preferential direction (Fig. 9). Conversely, northward velocities are characterized by a distinguishable temporal variability. From several weeks to several months, the current direction changes, with long periods of time when the direction of flow remains unchanged. The strongest currents appear to be aligned with the continental slope (north-south axis), which may be related to barotropic currents.

340 Strong deep currents ( $\approx 0.4 - 0.5 m/s$ ) below 900 m are also present in the area, locally highly variable with strong interactions with the bathymetry and the tide (Fig. 9).

Backscatter data estimated from ADCP measurements and expressed as the backscatter index (BI) are represented on Fig. 4 as an averaged profile. This averaged profile primarily depicts water-masses optical properties changes which are determined by



**Figure 9.** Time-series of northward (a) and eastward (b) velocities measured by the ADCP in the 0-100 mbss m layer and time-series of northward (c) and eastward (d) velocities measured by the ADCP in the 900-1,250 mbss m layer. The data shown correspond to daily mean values, computed separately for the depth layers: the surface layer (0-100 m) and the deep layer (900-1250 m).

phyto- and zoo-plankton abundance, mineral particles concentration (Mullison, 2017; Gentil *et al.*, 2020). Thus, and as it can
be expected, BI shows maximum values in the surface layer (0-100 mbss m), where most of the biological activity takes place.
Deeper in the water-column, BI is generally lower, although sometime peaking at the level of the South Indian Central Water and in the ~ 900-1,250 mbss m layer when crossing dissolved gases plumes or moving around the seafloor.

Similarly, the BI variability in the surface mirrors changes in temperature and salinity to a certain extent and several glider dives showed a BI increase at depth, when the glider approaches the continental shelf. This variability is not fully understood
and likely to be a multi factor cause resulting in from a decoupling of the surface, subsurface and deep dynamics. Whatever the processes envisioned, in all likelihood, a direct contribution of magmatic fluid emissions can be discarded.

- In the other hand, BI profiles are noisy and variable with depth and despite this large variability, the signature of bubble/droplets appears to be unambiguous, associated with a large density of positive spikes of great amplitude and associated vertical velocity anomalies of about 15 cm/s, which is the ascent velocity of gas droplets in the ocean (Rehder et al., 2009; Leblond et al.,
- 355 2014, Fig. 10). BI increases in the deep layer were considered to be related to acoustic plumes bubble/droplet plumes if several consecutive BI values exceed  $\sim$  50 dB in at least 6 cells of the ADCP to discard the few possible misdetection at this depth. This was used as a criterion for BI anomaly detection but each dive was also visually inspected.

Of the 22,000 profiles, 457 ( $\sim 2\%$ ) were associated with significant BI anomalies. The relative low occurrence of BI detections indicates that acoustic bubble/droplet plumes are likely to be of limited spatial extension ( $\sim$  hundreds of meters) especially

Although associating BI detections directly to an a fluid emission active site is complex (uncertainty in glider positioning, tilt of droplets/bubbles plumes of several hundred meters because of deep and tidal currents), data show that most of known active sites were indeed identified by the glider. 95% of BI detections are found within a radius of 700 m from an active site and the remaining 5% always at a distance less than 1.6 km.

compared with dissolved and neutrally buoyant gas plumes.

- 365 Repeated dissolved gases and BI anomalies in the 800-1,250 mbss m layer (Fig. 10) provide evidence that elevated  $CO_2$ anomalies in the 900-1,250 mbss m layer are related to magmatic fluids emissions from the seafloor. BI detections outside of the 95th percentile are observed around the Horseshoe zone may arise from intermittent, small, unidentified sites or false detections. Further analysis is needed to confirm the nature of these detections. Temporal variations in dissolved gas concentrations ( $CH_4$  and  $CO_2$ ) and BI anomalies are presumably caused by a complex
- array of factors, including spatial variability related to the glider pathway. However, on the basis of our current knowledge, we assume that a large part of the observed changes can indeed be related to the variability of seafloor fluid emissions in the Horseshoe area as well as the orientation and direction of the current at depth.

### 3.4 Discussion

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- 375 Over the 30 months of deployments, values of  $CH_4$  and  $CO_2$  show some interesting patterns, with a large profile-to-profile variability observed in dissolved gas deep anomalies. High anomaly values exceeding the detection limit of the sensor plus two times the standard deviation (20 nmol/l for the  $CH_4$  and 7  $\mu mol/l$  for the  $CO_2$  anomalies) are observed throughout the time-series. In the 900-1,000 mbss m layer (more than 90% of the data set), the maximum  $CH_4$  anomaly value is reached on February 21, 2022 (116.9 nmol/l) and the maximum  $CO_2$  anomaly value on September 04, 2022 (29.2  $\mu mol/l$ ).
- 380 Although a direct correlation between currents and gas anomalies is speculative, our data suggests a potential impact of mesoscale structures on gas concentrations in the 900-1,250 mbss m layer. The underlying processes are still poorly understood from the sole analysis of the glider data set, but several processes would be worth to be investigated (trapping, dispersion, diffusion, upwelling, etc.). Furthermore, additional bottom current data could potentially greatly assist be useful for this analysis. In order to assess the spatial distribution, anomalies are plotted on maps (Fig. 11). This provides a comprehensive view of
- 385 the area impacted by fluid emissions, over the 30 months duration of deployments. On Fig. 11, data are binned in 7 discrete concentrations intervals and superimposed from weakest to strongest values with circles of decreasing size. Only data that exceed criteria of detection are colored, and the maxima of the colorbar are equal to the 99th percentile. Highest gas anomalies were all observed in the center and in the immediate vicinity of the Horseshoe edifice and the magnitude of the anomalies progressively decrease as the glider moves away from the center. The radius of gas anomalies detection is around 10 km, and
- 390 the total area impacted by fluid emissions spread over about 300 km<sup>2</sup>. These maps, that gather all data since September 17, 2021, also show that the distributions of gases anomalies are not isotropic. In particular, relatively high concentration relative



Figure 10. Example of a glider between 800-1,250 spiral realised track carried out above known fluid active sites. On the left side :  $CO_2$  and  $CH_4$  concentrations are represented respectively in red and purple centered and reduced (to get a common representation of the two dissolved gases despite the different baselines and anomalies) as a function of the transeet dive progress (a). The minimum and maximum of each data are represented by a circle. The figure shows BI data calculated from each paired cell of the ADCP (b), followed by vertical velocity calculated from the ADCP data (c) data and finally bathymetric profile along this dive (d). On the figure right side : are shown a isobaths map of the Horseshoe area with the underwater glider position under water in black and the different current including the plot of direction and velocity for different currents calculated during this dive (surface geostrophic current in red, ADCP-calculated 800-1250 m deep current in purple and tidal current in grey) (e) and the local tide height (f). Surface geostrophic current is estimated from sea level anomalies (SLA) data computed with respect to a twenty-year [1993, 2012] mean (https://doi.org/10.48670/moi-00149). Tidal current parameters are computed with MIKE21 model.



Figure 11. Map of  $CH_4$  (a) and  $CO_2$  (b) anomalies above the detection limit of these sensors recorded during the whole glider survey. The gray triangles are the active fluid emission sites identified with the multibeam echosounder during the REVOSIMA MAYOBS cruises (DOI 10.12770/070818f6-6520-49e4-bafd-9d4d0609bf7d) and validated by *in situ* visual observations with the ROV VICTOR during the GEOFLAMME cruise (DOI 10.17600/18001297).

to the far field are observed northward which can highlight a preferred export direction for these quantities of dissolved gas. Many questions still remain in our understanding of the underlying processes. We can for example mention the spatial decoupling between acoustic and dissolved gas plume or the contribution of physical factors in modulating the extension, direction and intensity of the plumes (water-currents, internal tides).

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To face with these scientific challenges, the synergy between the glider with other observations and measurement tools (CTD cast, ROV, moorings), numerical models and satellite products is promising. Several attempts studies in this direction have been initiated, and although clear results are not yet available, ongoing work is progressing steadily.

Reference data acquired during MAYOBS cruises allowed for a cross-calibration exercise of the dissolved gases sensors. An
 exercise has been carried out during MAYOBS25 cruise in September 2023 and MAYOBS30 cruise in September 2024 by harnessing two gliders on the CTD cast in order to compare dissolved gases from glider sensors and Niskin samples. The aim of these calibrations is to quantitatively calibrate dissolved gas sensors in order to calculate the fluxes of fluids emitted at the seabed.

#### 4 Conclusions

405 The data set presented here demonstrates the feasibility of collecting long-term physico-chemical measurements (including CTD, ADCP, and dissolved gases such as  $O_2$ ,  $CH_4$ , and  $CO_2$ ) using a glider platform over periods extending up to 30 months, with interruptions limited to deployment/recovery operations and brief maintenance interventions.

The overall quality of the produced data set is remarkable and acquired without any interruption other than deployment/recovery period of the glider and fast repairs. CTD, dissolved gases ( $O_2$ ,  $CH_4$  and  $CO_2$ ) and ADCP data are available through this 30

410 months data set in an area lacking in reference data.

This is one of the few glider missions that has simultaneously sampled  $CH_4$  and  $CO_2$  data as well as the longest glider time series of these dissolved gas measurements that we are aware of. It also opens the possibility for new projects and research with the ability to identify these variables detect and monitor CH4 and CO2 underwater distribution (GEORGE project (Next Generation Multiplatform Ocean Observing Technologies for Research Infrastructures, https://george-project.eu/), Hauri *et al.*,

415 2024).

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The vertical distribution of hydrological, dissolved gas and BI data highlighted anomalies due to magmatic fluids in the Horseshoe area, while ADCP-calculated current depicted an active area subject to strong currents both at the surface and at depth. The data analysis is still ongoing but the glider platform showed its full potential ability to monitor, track and characterize seafloor fluid emissions mainly composed of  $CO_2$  droplets off Mayotte Island. This experiment proves the feasibility of inte-

420 grating a glider into making of this tool and ideal a real-time early warning system. In particular, the continuous monitoring at a high spatio-temporal scale of the 0-1,250 mbss m layer appears to be relevant to complement traditional oceanographic cruises (synoptic and high-quality data but with a limited resolution temporal scale) and to ensure an operational observing system.

The robustness of the platform (SeaExplorer glider) has also been demonstrated thanks to this data set, with 901 days at sea over 929 days (97 % of its time spent at sea).

The quasi-permanence of elevated gas concentrations ( $CO_2$  and  $CH_4$ ) in the Horseshoe area support that fluid emissions are likely to have been continuous and detectable over the 30 months of the mission and detectable above 1,250 mbss. Regular detections of acoustic plumes above all identified active sites have provided direct evidence of active seepage during

the survey and the presence of bubble/droplets above 1,250m-depth.

430 Many questions still remain in our understanding of the underlying processes. We can for example mention the spatial decoupling between acoustic and dissolved gas plume or the contribution of physical factors in modulating the extension, direction and intensity of the plumes (water-currents, internal tides).

To face with these scientific challenges, the synergy between the glider with other observations and measurement tools (CTD east, ROV, moorings), numerical models and satellite products is promising. Several attempts studies in this direction have been initiated, and although clear results are not yet available, ongoing work is progressing steadily.

Reference data acquired during MAYOBS cruises allowed for a cross-calibration exercise of the dissolved gases sensors. An exercise has been carried out during MAYOBS25 cruise in September 2023 and MAYOBS30 cruise in September 2024 by

harnessing two gliders on the CTD cast in order to compare dissolved gases from glider sensors and Niskin samples. The aim of these calibrations is to quantitatively calibrate dissolved gas sensors in order to calculate the fluxes of fluids emitted at the seabed.

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*Data availability.* Raw and processed data are available from the SEANOE data center : https://doi.org/10.17882/99960 (Heumann *et al.*, 2024).

# Appendix A

Deployment	Recovery	Glider	Mission ID	AD2CP	MINICO2	GPCTD	LEGATO	SBE43F	AROD	METS
17/09/2021	07/10/2021	SEA042	001	100584	39-636-18	0114		2610		1635
11/10/2021	27/10/2021	SEA042	002	100584	39-636-18	0114		2610		1635
29/10/2021	12/11/2021	SEA042	003	100584	39-636-18	0114		2610		1635
13/11/2021	29/11/2021	SEA042	004	100584	39-636-18	0114		2610		1635
30/11/2021	13/12/2021	SEA042	005	100584	39-636-18	0114		2610		1635
14/12/2021	27/12/2021	SEA042	006	100584	39-636-18	0114		2610		1635
28/12/2021	10/01/2022	SEA042	007	100584	39-636-18	0114		2610		1635
11/01/2021	21/01/2022	SEA042	008	100584	39-636-18	0114		2610		1635
22/01/2021	02/02/2022	SEA042	009	100584	39-636-18	0114		2610		1635
03/02/2022	16/02/2022	SEA042	010	100584	39-636-18	0114		2610		1635
17/02/2022	01/03/2022	SEA042	011	100584	39-636-18	0114		2610		1635
03/03/2022	14/03/2022	SEA042	012	100584	39-636-18	0408		3343		1635
15/03/2022	29/03/2022	SEA027	013	102759	39-636-18	0408		3343		1635
30/03/2022	10/04/2022	SEA027	014	102759	39-636-18	0408		3343		1635
13/04/2022	27/04/2022	SEA027	015	102759	39-636-18	0408		3343		1635
28/04/2022	12/05/2022	SEA027	016	102759	39-636-18	0408		3343		1635
13/05/2022	27/05/2022	SEA027	017	102759	39-636-18	0408		3343		1635
28/05/2022	11/06/2022	SEA027	018	102759	39-636-18	0408		3343		1635
12/06/2022	27/06/2022	SEA027	019	102759	39-636-18	0408		3343		1635
28/06/2022	08/07/2022	SEA027	020	102759	39-636-18	0408		3343		1635
10/07/2022	25/07/2022	SEA027	021	102759	39-636-18	0408		3343		1635
04/08/2022	16/08/2022	SEA017	022	102759	39-636-18	0408		3343		1635
17/08/2022	28/08/2022	SEA017	023	102759	39-636-18	0408		3343		1635
29/08/2022	12/09/2022	SEA017	024	102759	39-636-18	0408		3343		1635
13/09/2022	27/09/2022	SEA017	025	102759	39-636-18	0408		3343		1635
28/09/2022	11/10/2022	SEA017	026	102759	39-636-18	0408		3343		1635
12/10/2022	25/10/2022	SEA017	027	102759	39-636-18	0408		3343		1635
26/10/2022	08/11/2022	SEA017	028	102759	39-636-18	0408		3343		1635

# Table A1. Glider missions performed with deployment and recovery, glider used, mission ID and sensors serial numbers

Deployment	Recovery	Glider	Mission ID	AD2CP	MINICO2	GPCTD	LEGATO	SBE43F	AROD	METS
09/11/2022	22/11/2022	SEA017	029	102759	39-636-18	0408		3343		1635
23/11/2022	06/12/2022	SEA017	030	102759	39-636-18	0408		3343		1635
07/12/2022	19/12/2022	SEA017	031	102759	39-636-18	0408		3343		1655
20/12/2022	02/01/2023	SEA017	032	102759	39-636-18	0408		3343		1635
03/01/2023	12/01/2023	SEA017	033	102759	39-636-18	0408		3343		1635
13/01/2023	28/01/2023	SEA027	034	102889	42-030-18		210554		59	1635
29/01/2023	08/02/2023	SEA027	035	102889	42-030-18		210554		59	2016
18/02/2023	02/03/2023	SEA017	036	102886	42-030-18		210554		59	2753
03/03/2023	16/03/2023	SEA017	037	102886	42-030-18		210554		59	2753
17/03/2023	30/03/2023	SEA017	038	102886	42-030-18		210554		59	2753
31/03/2023	14/04/2023	SEA017	039	102886	42-030-18		210554		59	2753
15/04/2023	29/04/2023	SEA017	040	102886	42-030-18		210554		59	2753
30/04/2023	14/05/2023	SEA017	041	102886	42-030-18		210554		59	2753
15/05/2023	29/05/2023	SEA017	042	102886	42-030-18		210554		59	2753
30/05/2023	12/06/2023	SEA017	043	102886	42-030-18		210554		59	2753
13/06/2023	26/06/2023	SEA017	044	102886	42-030-18		210554		59	2753
27/06/2023	10/07/2023	SEA017	045	102886	42-030-18		210554		59	2753
11/07/2023	24/07/2023	SEA023	046	103361	42-030-18	0284		2733		2753
28/07/2023	09/08/2023	SEA083	RD8	102880	43-186-18	0408		3489		2821
10/08/2023	24/08/2023	SEA083	RD9	102880	43-186-18	0408		3489		2821
25/08/2023	30/08/2023	SEA083	RD10	102880	43-186-18	0408		3489		2821
26/07/2023	09/08/2023	SEA023	047	103361	42-030-18	0284		2733		2753
12/08/2023	24/08/2023	SEA017	048	103361	42-030-18	0284		2733		2753
25/08/2023	04/09/2023	SEA017	049	103361	42-030-18	0284		2733		2753
30/08/2023	31/08/2023	SEA083	RD11	102280	39-636-18	0408		3489		2821
05/09/2023	12/09/2023	SEA017	050	103361	42-030-18	0284		2733		2753
13/09/2023	16/09/2023	SEA017	051	103361	42-030-18	0284		2733		2753
11/09/2023	16/09/2023	SEA083	RD12	101592	39-636-18	0408		3489		2821
23/09/2023	30/09/2023	SEA017	052	103361	42-030-18	0284		2733		2753
23/09/2023	30/09/2023	SEA083	RD13	101592	39-636-18	0408		3489		2821
02/10/2023	12/10/2023	SEA083	RD14	101592	39-636-18	0408		3489		2821
13/10/2023	01/11/2023	SEA083	RD15	101592	39-636-18	0408		3489		2821
02/11/2023	17/11/2023	SEA083	RD16	101592	39-636-18	0408		3489		2821

Deployment	Recovery	Glider	Mission ID	AD2CP	MINICO2	GPCTD	LEGATO	SBE43F	AROD	METS
18/11/2023	28/11/2023	SEA023	053	102886	42-030-18		210554		59	2821
02/12/2023	15/12/2023	SEA017	054	103361	39-636-18	0284		2733		2821
29/11/2023	02/12/2023	SEA083	RD17	105522	39-636-18	0408		3489		2821
15/12/2023	23/12/2023	SEA083	055	102880	39-636-18	0408		3489		2821
15/12/2023	25/12/2023	SEA027	056	104651	42-030-18	0114		3343		2016
26/12/2023	09/01/2024	SEA027	057	104651	42-030-18	0114		3343		2016
10/01/2024	23/01/2024	SEA027	058	104651	42-030-18	0114		3343		2016
24/01/2024	09/02/2024	SEA027	059	104651	42-030-18	0114		3343		2016
10/02/2024	26/02/2024	SEA027	060	104651	42-030-18	0114		3343		2016
27/02/2024	14/03/2024	SEA027	061	104651	42-030-18	0114		3343		2016
16/03/2024	02/04/2024	SEA027	062	104651	42-030-18	0114		3343		2016

# 445 Appendix B

**Table B1.** Offset and Gain values applied to  $O_2$  data depending on profile dive number with reference profiles acquired during MAYOBS cruises.

Profile	Gain
1-4547	1
4548-5349	1.21
5350-7022	1
7023-7796	1.37
7797-8197	1
8198-8389	1.24
8340-13058	1
13059-17884	0.81
17885-19042	1.33
19043-20025	1.22
20026-20240	1
20241-20352	1.10
20353-20635	1
20636-21138	1.36
21139-21450	0.76
21451-21913	1
21914-22047	1.32

# Appendix C



Figure C1. Vertical profiles of corrected (blue) and uncorrected (red) temperature, salinity, and  $O_2$  concentration as a function of depth from dive 13089.

# Appendix D

# Table D1. Sensor informations

Parameter	Temper	rature	Conduc	ctivity	Dissolv	ved oxygen	$CO_2$	$CH_4$	Ocean currents and BI
Manufacturer	RBR	Seabird	RBR	Seabird	JFE	Seabird	Pro Oceanus	Franatech	Nortek
Sensor	LEGATO	GPCTD	LEGATO	GPCTD	AROD-FT	SBE43F	Mini-CO <sub>2</sub>	METS	AD2CP
Unit	°C	7	mS/	'cm	μπ	$\mu mol/kg$		nmol/l	-
Range	-5 to +42	-5 to +42	0 to 85	0 to 90	0 to 425	0 to 120% of saturation	0 to 45000	10 to 1,000	post-processing
Precision	$\pm 0.002$	$\pm 0.005$	$\pm 0.003$	$\pm 0.003$	2% of measurement	2% of saturation	3% of measurement	50	post-processing
Resolution	< 0.00005	0.001	0.001	0.0001	0.01	0.5% of saturation	0.1% of measurement	5	post-processing
Sampling rate	1 Hz	1 Hz	1 Hz	1 Hz	0.1 Hz				

#### Appendix E

Quality flag value	Temperature	Conductivity	Dissolved oxygen	$CO_2$	$CH_4$
1 to 4	100%	100%	100%	100%	100%
1 to 3	95.9%	98.2%	99.3%	94.5%	97.1%
1	95.4%	92.4%	84.3%	78.9%	94.7%

Table E1. Percentage of total data going through QC (total number of points for each data is 2,232,706)

Author contributions. All authors except GL took part in data acquisition of the data set by reviewing the data at two weeks interval since
 450 September 2021. HA was in charge of overall data processing and formatting, with the support of ML, PO and BL. All authors participated in the writing of the initial and revised versions of the paper; RE focusing more specifically on the dissolved gases data set, LP on the ocean current data set and SC on the acoustic backscatter data set.

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