

A Sentinel-2 Machine Learning Dataset for Tree Species Classification in Germany

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Abstract. We present a machine learning dataset for tree species classification in Sentinel-2 satellite image time series of bottom of atmosphere reflectance. [It is geared towards training classifiers, but less suitable for validating resulting maps.](#) The dataset is based on the German national forest inventory of 2012, as well as analysis ready satellite imagery computed using the FORCE processing pipeline. From the national forest inventory data, we extracted the tree positions, filtered 387 775
5 trees in the upper canopy layer and automatically extracted the corresponding bottom of atmosphere reflectance time series from Sentinel-2 L2A images. These time series are labeled with the corresponding tree species, which allows pixel-wise classification tasks. Furthermore, we provide auxiliary information such as the approximate tree position, the year of possible disturbance events or the diameter at breast height. Temporally, the dataset spans the years from July 2015 to end of October
10 non-tree background. Spatially, it covers entire Germany. The dataset is available under following DOI (Freudenberg et al., 2024): <https://doi.org/10.3220/DATA20240402122351-0>

1 Introduction

Climate change increases the risk of severe weather events such as heavy rainfall or droughts in Central Europe (Toreti et al., 2023). The recent past has seen large-scale forest diebacks due to drought, disease or insect manifestations or a combination of these disturbances (Senf et al., 2020; Senf and Seidl, 2021b). Forest managers face the challenge of adapting their management practices through diversification and other strategies to mitigate these threats. Here, remote sensing will play an increasingly important role as it can support well-informed decisions by providing extensive land cover and forest information at higher temporal frequencies than ground-based forest monitoring approaches. In this context, information on tree species is essential for many forest management decisions.

Tree species classification in satellite imagery is important, not only for scientific, but also for practical applications in forestry and nature conservation. This task has been in focus since the early days of space-borne remote sensing with the first Landsat sensors (Walsh, 1980) and it continues today with the application of machine-learning methods to large areas (Bolgen et al., 2022; Blickensdörfer et al., 2024).

Sentinel-2 (S2) satellite images are the ideal basis for such analyses, as they are standardized, freely available and collected with high temporal revisit frequency. Machine learning, particularly deep learning, is commonly employed to tackle classification tasks in image data, albeit requiring substantial amounts of training data (Bolgen et al., 2022; Lake et al., 2022; Yuan and Lin, 2020). Deep learning is a type of machine learning that uses neural networks with multiple layers to automatically learn patterns from large datasets (Goodfellow et al., 2016). In the context of tree species classification, generating training data is demanding and one has to resort to visual interpretation and on-screen labeling of high resolution aerial images, ideally combined with validation in the field – or one has to source labels from forest inventory data.

Ahlswede et al. (2023) have addressed the problem of training data compilation and created a multi-modal training dataset, containing aerial, as well as Sentinel-1 and 2 images of over 50 000 sites in the state of Lower Saxony, Germany. The dataset contains image-wise labels for 20 European tree species, generated from stand level forest inventory data. Utilizing different deep learning models, the authors achieved an F_1 score of 54.6%, using Sentinel-2 data alone. The F_1 score is the harmonic mean of user's and producer's accuracy, or precision and recall, respectively. They conclude that “the integration of multi-seasonal data might disentangle further species-related information regarding phenology phases” (Ahlswede et al., 2023, p. 691) – this is what we aim for with the dataset presented here.

Hemmerling et al. (2021) used exactly this kind of multi-seasonal Sentinel-2 data to classify 17 different tree species in the state of Brandenburg, Germany. They applied a random forest classifier to time series of the years 2018 and 2019 and reached F_1 scores between 67% and 99% for the nine most frequent species, thereby demonstrating that at least a subset of species can be separated using S2 time series comparable to the ones provided here. As in the first study, the authors obtained their labels from forest inventories conducted by state authorities.

These two studies are noteworthy exceptions regarding the amount of training data used, because the used datasets were relatively large. Fassnacht et al. (2016) reviewed studies on tree species classification from remotely sensed data and conclude that “investigations focusing on [...] a single often comparably small test site by far dominated the reviewed studies”. This

hinders the generalizability of results and the applicability of generated models to other areas: a dataset covering a large area and long time spans is needed.

To overcome the problem of limited training data we tap the largest dataset of field observations of tree species in Germany: the national forest inventory (NFI). The German NFI ~~is conducted at full scale every~~ runs on a cycle of 10 years, with a subsample after 5 years, and covers more than 25 000 sites, over 60 000 sampling points and more than 500 000 trees across all ownerships and site conditions (Polley et al., 2018). For each tree, several variables such as species, relative position and diameter at breast height (DBH, 1.3 m) are recorded. The resulting dataset is the most comprehensive available for German forests and the derived statistics provide valuable insights into the forest condition, composition and development on regional and national level. However, the design of the NFI was not tailored for creating remote sensing reference datasets but to provide an efficient sampling and plot design for estimating key forest variables. From a remote sensing perspective, one of the major caveats is, that the exact sampling positions need to be kept confidential, e.g., to prevent biased estimates when management practices are changed in the plot vicinity.

The goal of the work presented is twofold: first, to make satellite data at NFI plot positions available for third parties without revealing the exact geolocations and second, to analyze the separability and temporal patterns of tree crown reflectances for tree species in Germany. We link NFI records to bottom of atmosphere reflectance (BOA) time series from matching Sentinel-2 images, enabling tree species classification and other applications for a broad range of potential users. Said time series were extracted from analysis ready data generated by the Framework for Operational Radiometric Correction for Environmental monitoring (FORCE) (Frantz, 2019), hosted on the CODE-DE¹ platform. The resulting dataset provides BOA reflectances from July 2015 to October 2022 and in sum contains the time series of 387 775 individual trees and 70,242 non-tree locations. Multiplying the counts of tree and non-tree locations with their individual number of observed time steps yields a total of ca. 75.3 million data points for trees and 13.8 million observations for non-tree background, covering the entirety of Germany and 48 tree species and 3 species groups. The primary purpose of the data is training classifiers for detecting tree species in satellite images from the Sentinel-2 mission, but it could also be used for studying phenological and spectral patterns of tree species. It is less suitable for validating maps at pixel level. The dataset is available online under <https://doi.org/10.3220/DATA20240402122351-0> (Freudenberg et al., 2024) with CC BY 4.0 license.

2 Materials and methods

2.1 Study area and national forest inventory

The dataset covers the entire area of Germany, including islands. More specifically, it contains 24 925 of the 25 382 cluster plots recorded in the 2012 national forest inventory. The missing cluster plots either contained only trees below the canopy layer, the field inventory was conducted in a non-standard way (e.g. with custom post-processing of the coordinates) or the cluster plot coordinates were simply missing from the database we obtained. Temperate broadleaf and mixed forests prevail in most

¹<https://code-de.org>

regions of the country. Coniferous forests, mainly consisting of *Picea abies* (Norway spruce), dominate at higher elevations and forests with *Pinus sylvestris* (Scots pine) occur on the sandy soils of the north-eastern part of the country. In ~~2012~~2022, about 32% of Germany was covered by forest (~~Polley et al., 2018~~), but due to heavy (~~Riedel et al., 2024~~). Heavy droughts and following insect infestations in the years 2018–2022 ~~a decline in growing stock could be observed~~ resulted in a decline of growing stock in certain areas (Reinosch et al., 2024; Thonfeld et al., 2022; Holzwarth et al., 2023).

The German national forest inventory is conducted on a regular, square sampling grid as shown in Figure 1 with a grid size of 4 km × 4 km or less, depending on the federal state. At each grid point there are four inventory plots, aligned in a 150 m × 150 m square. The south-western corner of the square aligns with the 4 km × 4 km grid, as shown in Figure 2.

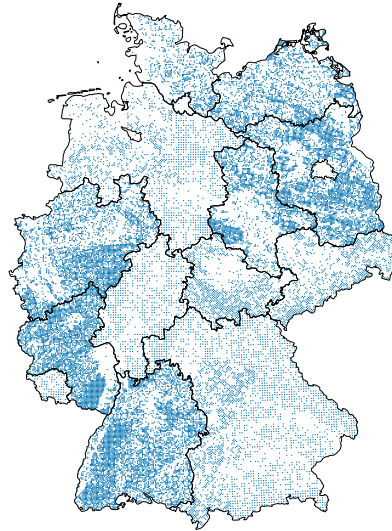


Figure 1. The sampling positions of the German national forest inventory 2012. Borders: © GeoBasis-DE / BKG (2024)

85 The geolocation of each subplot is measured with a Global Navigation Satellite System (GNSS) device, which may or may not be differentially corrected using correction information from terrestrial reference stations. At ~~this~~the subplot, two angle count samplings are performed (Gregoire and Valentine, 2007), which means that trees whose diameter at breast height (DBH) covers more than a certain solid angle are recorded.

90 The first angle count sampling includes all trees within a distance from the sample location of 25 times their DBH (basal area factor 4). The positions of the selected trees are determined by measuring their azimuth angle using a compass and their distance to the plot center by an ultrasonic device (Haglölf Vertex or similar) or in edge cases via measuring tape. Furthermore, the tree species, DBH and other variables are recorded. At these measured tree positions, the BOA reflectances were extracted and related to the corresponding, ground-measured information - how this was done is described later.

95 A second angle count sampling captures the surrounding forest composition by recording the species of all trees within a radius of 33.34 or 50 times their DBH (basal area factor 2 or 1), depending on how many trees were observed in the first sampling ~~with basal area factor 4~~. The second angle count sampling allows to tell, which sub-plots are pure stands, i.e. have

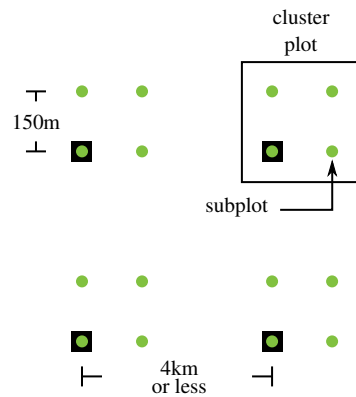


Figure 2. The German national forest inventory sampling grid (black squares) and the subplots (green). The south-western subplot in each cluster plot is aligned with the overarching grid.

only one tree species in them. The information about stand purity is included in the dataset, so that the end user can filter for trees in pure stands.

2.2 NFI reference data selection

100 The reflectances recorded in a Sentinel-2 pixel represent the mixture of all land cover – or in our case tree species – within the pixel. However, in closed canopy forests the BOA reflectance is dominated by the uppermost canopy layer and we can safely assume that trees overshadowed by larger individuals contribute only little to the overall reflectance within a pixel. To compile the provided training dataset we therefore filtered the NFI data for trees that are probably visible from above. We first removed all trees that grow in the understory; this information is recorded during the inventory. For the remaining

105 trees we modeled a circular growing space using the NFI’s official method described in (Riedel et al., 2017, pp. 39, 40). The model establishes a species-specific linear relation between basal area and the growing space of a tree. The growing space ~~“approximately corresponds to the crown projection area”~~ (Riedel et al., 2017, pp. 39, author’s translation), so we use these terms interchangeably in the following is a measure for the area occupied by a tree as a whole in an idealized forest stand. In lack of a model for direct estimation of crown area from basal area, we use the growing space as a proxy for it and stick to the term “crown area”. The model is defined in equation A1 and the parameters are supplied in Table A1 in the appendix. As we

110 know the position of each tree, as well as its predicted crown area, we removed trees that are probably not visible from above by a heuristic algorithm.

~~Trees were considered visible if they were either the biggest (in terms of basal area) within a~~ We counted a tree as visible if it either had the largest basal area of all trees within a radius of 3m radius or if there were no other trees within that distance.

115 ~~Additionally, trees were classified as visible if their crown area overlapped the union of all other crown areas by not more than 50% or if its crown area was overlapped by less than 50% , as depicted in Figure 3 by surrounding trees.~~ Trees classified as visible by this heuristic formed the basis for the training dataset.

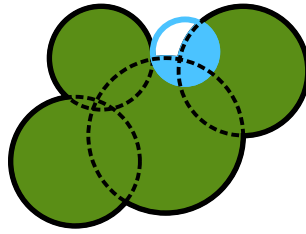


Figure 3. Sketch of a tree group: Green trees are assumed to be visible. The blue tree overlaps with more than 50% of its area with other trees and is therefore discarded.

To allow training classification methods for the discrimination between tree and non-tree pixels, we added non-forest observations to the dataset. For this, we sampled the tree cover density layer provided by the Copernicus Land Monitoring Service for the year 2018 within a 300 m × 300 m patch around the NFI plots². The tree cover density layer is sampled at locations that are at least 20 meters away from the next pixel with tree density greater than 10%.

2.3 Satellite data selection

We used images from the Sentinel-2 satellites, pre-processed to analysis-ready level, which includes atmospheric correction and cloud masking, by the FORCE processing pipeline (Frantz, 2019). FORCE provides a way to compute harmonized time series that are spatially and spectrally well aligned, which is discussed in more detail later. The resulting data comprises all S2 bands with 10 or 20 m resolution, with the 20 m bands pan-sharpened (resampled) to 10 m resolution. Additionally, FORCE provides quality assurance information (QAI) that aids in filtering out undesirable image conditions such as clouds, snow, or high water vapor content. The data is hosted on the CODE-DE³ and EO-Lab⁴ platforms. End users have the option to either download the pre-processed data or can re-process it using the same settings utilized in generating the FORCE data cube on CODE-DE. The necessary parameter files are provided alongside the dataset.

2.4 Time series extraction and data processing

~~As the~~ Previous studies have taken different approaches for linking forest field data with satellite images: Many work only with pure stands (e.g., Verhulst et al. (2024); Hościło and Lewandowska (2019)), while others assign plot-specific species compositions (e.g., Blickensdörfer et al. (2024)). Some sample individual pixels within polygons (Hemmerling et al., 2021; Grabska-Szwajczer et al. (2020)), cut out pixels covered by a fixed area plot (Persson et al., 2018), or even calculate reflectances at the single tree crown level (Plakman et al., 2020).

As the German NFI performs angle count sampling, it is not possible to exactly determine how much of a given area (e.g. a Sentinel-2 pixel) is covered by which tree species ~~or land cover type. Previous studies have related all pixels in a certain radius around the sampling point to the found species composition or the dominant species, e.g. based on the basal~~

²<https://land.copernicus.eu/en/products/high-resolution-layer-tree-cover-density>

³<https://code-de.org>

⁴<https://eo-lab.org>

140 ~~area (Blickensdörfer et al., 2024). Here, we take a different approach and adjacent land cover types. In such cases, there are~~
~~mainly two approaches, one can follow for relating field and satellite data, which we call “tree-centric” and “pixel-centric”.~~
~~The “tree-centric” approach assigns the most probable reflectance value to individual tree crowns by directly extracting them~~
~~from the satellite image. In contrast, the reflectance time-series at each tree position. While this poses challenges, mainly due~~
~~to co-registration errors of the satellite and GNSS data and duplication of pixels, it also opens new possibilities for combining,~~
145 ~~filtering and analyzing the data.~~ “pixel-centric” approach labels individual pixels with species information, for example, a
species composition derived from inventory data. We chose the tree-centric approach, as it accounts best for the response
design of the angle count sampling. With angle count sampling, an assignment of species information to pixels is difficult
because it does not provide a full census of all trees over a specifiable area.

We started by clipping $300\text{ m} \times 300\text{ m}$ image patches containing the 24 925 filtered NFI cluster plots and their surroundings
150 from the FORCE data cube, as depicted in Figure 4. We extracted the bottom of atmosphere reflectance (BOA) as well as the
quality assurance information (QAI). Before extraction, we filtered the plots to ensure they contained at least one pixel with
data, not affected by clouds or cloud shadows.

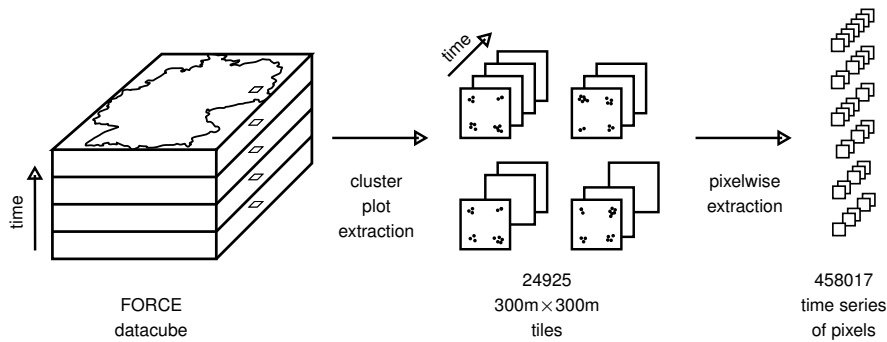


Figure 4. The time series extraction workflow: First, $300\text{ m} \times 300\text{ m}$ tiles are clipped from the FORCE datacube for Germany for all records between 2012 and 2022. Second, the pixel-wise time series are extracted from the tile time series.

In a second step, we extracted the BOA and QAI pixel time series from the extracted patches at each tree position. In
cases where a single tree covered more than one $10\text{ m} \times 10\text{ m}$ Sentinel pixel, we calculated the area-weighted average of all
155 pixels intersected by the tree’s crown area, as depicted in Figure 5. Each extracted satellite observation was then linked to its
acquisition date, the corresponding NFI data and more information. Senf and Seidl (2021a) provide a Landsat-based map of
forest disturbances for Germany between 1986 and 2020 at a resolution of 30 m. To be able to identify possible disturbance
events, we included the disturbance year from this map in the dataset. However, this still leaves a gap between 2020 and 2022,
for which no disturbance information is available. This was bridged by attaching the information whether the trees were still
160 present during the 2022 NFI. To enable approximate spatial analyses, we furthermore included the center coordinate of the 1
km INSPIRE grid tile the cluster plots are located in. The INSPIRE grids (INSPIRE MIG, 2023) are a set of Pan-European

geographical grid systems in the ETRS89-LAEA coordinate reference system with their origin at 52° N 10 ° E. The grids have a power-of-ten spacing in meters; we used the 1 km grid.

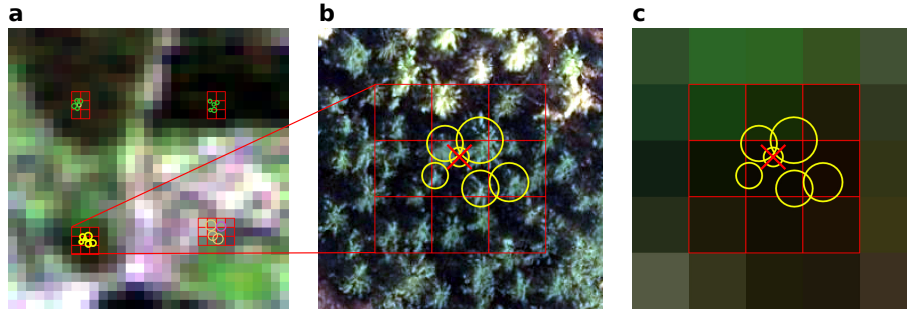


Figure 5. (a) The whole cluster plot cutout of 300 m×300 m. S2-Image: European Space Agency (2021) (b) The lower left subplot with the corresponding orthophoto for reference. Douglas firs in the lower part, Norway spruce in the upper part of the image. Image: © BKG (2021) (c) The S2 pixels corresponding to the subplot with circles depicting the modeled tree crown areas. The crossed out tree is omitted because it overlaps too much with surrounding trees.

The final dataset comprises the columns presented in Table 1 and an excerpt is given in Table C1 in the appendix. All samples were randomly split into training and validation sets based on their cluster plot IDs with a ratio of 70% - 30%. This rules out any spatial overlap between the training and test sets and reduces correlations between the two. For benchmark studies, we recommend using this split to ensure comparability across publications.

2.5 Assessment of the geolocation accuracy of the NFI plots

The tree positions in the NFI are measured in polar coordinates relative to the plot center, using a compass for the angle and an ultrasonic device for the distance measurement. We assume that the errors for angle and distance are small compared to the GNSS error of the plot center position measurement. GNSS measurements can be differentially corrected by using ground-based reference stations to increase positional accuracy. Depending on the federal state and field team, coordinates of the plot centers are measured with corrected GNSS devices or not. Of the sub-plots with trees in the dataset, 76.5% were corrected, 22.5% were not, and the remainder has unknown status.

To estimate the accuracy of the plot center coordinates, we compared the field-measured tree positions with tree positions derived from true-ortho aerial images, obtained from the Federal Agency for Cartography and Geodesy. These images are ortho-rectified using a surface model and aligned with high accuracy to ground control points. The ATKIS orthophoto standard guarantees a geolocation error with standard deviation of 0.4 m or less (Arbeitsgemeinschaft der Vermessungsverwaltungen der Länder der Bundesrepublik Deutschland (AdV), 2020). Two expert image interpreters then manually shifted a sample of 200 NFI plot positions, and thereby the trees, to match the true tree positions by comparing local tree patterns as depicted in

⁵<https://force-ee.readthedocs.io/en/latest/howto/qai.html#quality-bits-in-force>

Table 1. Dataset contents and column description.

Column name	Data type	Description
tree_id	Integer	A globally unique tree id. Negative values represent non-tree records.
tnr	Integer	Cluster plot id
enr	Integer	Corner id (1-4). Negative values represent non-tree records.
time	Integer	The acquisition date, encoded as Unix time, representing the number of seconds elapsed since 1970-01-01, 00:00 UTC. Every date was randomly shifted by up to three days.
species	Integer	The tree species, encoded according to the official NFI schema, provided within the dataset in a separate table “x_ba”.
boa	byte array	The BOA reflectance values: 10 signed 16-bit integers, one for each band, encoded as 20 byte blob. To hamper the identification of exact plot positions, each value was multiplied with a uniform random number between 0.95 and 1.05.
qai	Integer	Quality assurance information bit-flags, encoded as 16-bit integers, allowing for filtering based on image quality. The FORCE documentation provides details on the meaning of each bit ⁵ .
is_train	Bool	Whether the record belongs to the training or validation set.
is_pure	Bool	Whether the record comes from a pure stand according to the NFI definition.
dbh_mm	Integer	Diameter at breast height (1.3 m) in millimeters.
height_dm	Integer	Tree height in decimeters.
crown_area_m2	Float	Modeled tree crown area in m ² .
x_wgs84	Float	Longitude of the corresponding 1 km Inspire grid tile center.
y_wgs84	Float	Latitude of the corresponding 1 km Inspire grid tile center.
is_corrected	Bool	Whether the NFI position measurement was differentially corrected.
disturbance_year	Integer	The disturbance year according to the map provided by Senf and Seidl (2021a).
present_2022	Bool	Whether the tree was observed again in the 2022 forest inventory.
doy	Integer	The day of year of the acquisition, corresponding to the shifted date.

Figure 6. This allows to quantitatively evaluate the deviation of measured from true positions and to compare the accuracy of corrected and uncorrected measurements.

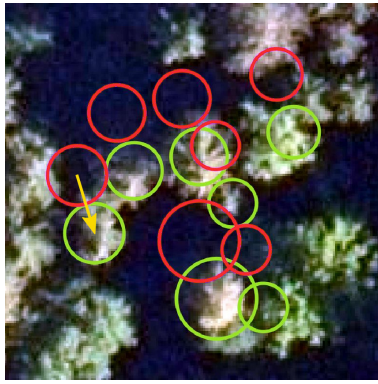


Figure 6. Original, measured GNSS coordinates (red) were shifted (here by 4.8 m) to the visually best matching position (green) in aerial orthophotos to quantify GNSS errors. Circles depict modeled crown areas.

2.6 Species separability analysis

To detect inconsistencies within the dataset, we computed the infrared reflectance histograms of five species for mixed and pure stands. If the histogram shows artifacts like double peaks or differs strongly between pure and mixed stands, this could hint to deficiencies in the respective part of the dataset. The histograms were computed for band B8 (842nm842 nm), averaged over all records in June 2021 for a sample of five species whose occurrence is correlated – *Betula pendula* often grows along with *Pinus sylvestris* and *Fagus sylvatica* often appears together with *Quercus* spp. June 2021 has been chosen because both Sentinel satellites were operational and, unlike the preceding years and 2022, 2021 was not particularly dry.

190 3 Dataset description and statistics

3.1 Numerical species distribution

Due to the highly varying dominance of tree species in Germany, the numerical distribution of the different species (Figure 7) is heavily imbalanced. The most abundant species is *Pinus sylvestris* (Scots pine), followed by *Picea abies* (Norway spruce), *Fagus sylvatica* (European beech) and the different *Quercus* (Oak) species. A complete list of included tree species and their counts can be found in appendix Table C3.

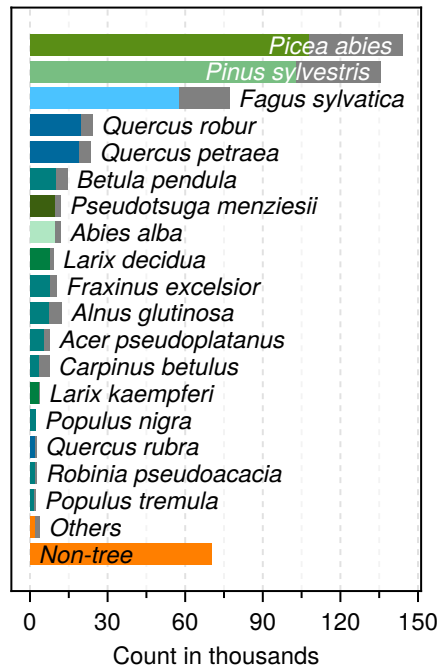


Figure 7. The numerical species distribution in the training dataset (colored) and in the original NFI 2012 data (gray).

3.2 Temporal signatures of selected species

Coniferous and broadleaf Evergreen and deciduous trees can be clearly separated visually by inspecting the time series of their infrared (IR) reflectance, as depicted in Figure 8. In the presented time series, the observations for a given species and point in time have been averaged across all undisturbed individuals in pure stands. Whether a stand is pure or not was determined using the second angle count sampling of the NFI (basal area factor of 1 or 2). Obviously, deciduous broadleaf trees exhibit a much stronger seasonal pattern than coniferous trees evergreen coniferous trees in our dataset. This separation is less evident in the green band, likely due to its higher susceptibility to atmospheric effects and its lower absolute reflectance, which deteriorates combine to diminish the signal to noise ratio. While the temporal infrared profiles of *Fagus sylvatica* and *Quercus robur* are generally distinguishable across most years, there are instances where differentiation becomes challenging (e.g. 2016 and 2020). *Quercus robur* tends to have a slightly lower IR reflectance on average, particularly in summer. *Picea abies* and *Pinus sylvestris* also differ only slightly in the infrared, with *Picea abies* having lower average values on trend. Overall, differentiating species by their temporal profiles alone seems challenging without considering their spectrum at the same time. Figure B1 in the appendix depicts the same data as Figure 8 but additionally includes error bands that were omitted here for clarity.

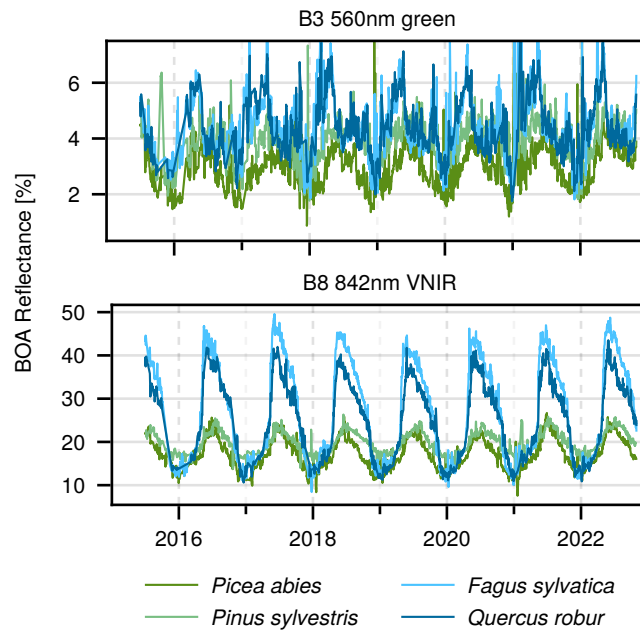


Figure 8. Time series of BOA reflectance for indicated species, averaged over all undisturbed individual trees in pure stands at a given time. The data has been filtered to exclude all types of cloud cover and their shadows, snow, and pixels with high aerosol optical depth.

Looking at a random selection of four individual trees' time series, depicted in Figure 9, it becomes clear that at the level of a single tree, the differences between species still seem to be present, but with high variance from year to year.

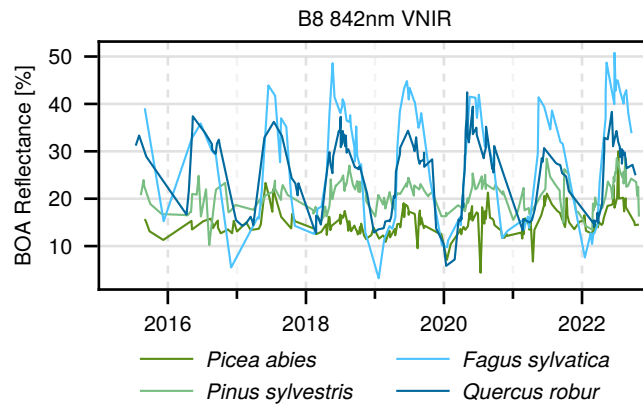


Figure 9. Time series of random single trees of different species.

Figure 10 shows the total observation count over time, i.e. how often each tree was imaged within a month, summed up across all trees. After the commissioning of Sentinel-2B in June 2017 the number of observations increases. As one would

expect, there are more observations in the summer months when clouds are less likely and especially from 2018 onward the counts regularly reach over 1 million.

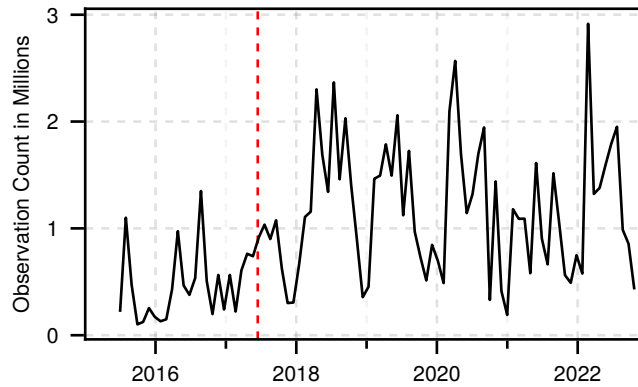


Figure 10. Total monthly observations of all trees in the dataset (tree count multiplied by individual observation count per month). The vertical red line corresponds to the Sentinel-2B commissioning date.

215 3.3 Spectral signatures

Besides the temporal variation of the reflectance, the spectral variation is an important feature for the tree species classification – however, the species are not necessarily separable by their spectrum alone, as can be seen in Figure 11. It depicts the Sentinel-2 spectra of the five most frequent species, as well as the background class. *Fagus sylvatica* and *Quercus petraea* for example have almost matching spectra, especially in the shorter wavelengths. The resulting spectra match the ones presented in Immitzer et al. (2016).

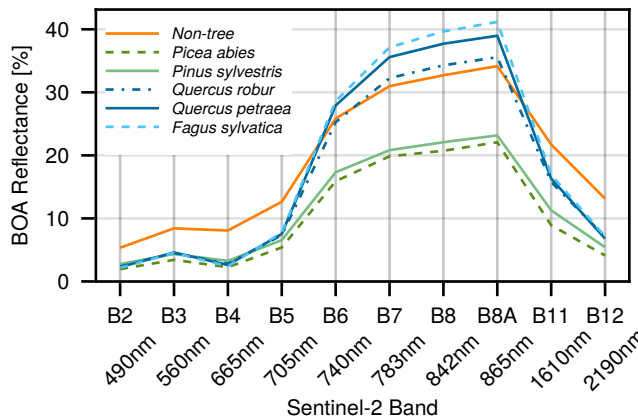


Figure 11. Average spectrum of the five most frequent species in the dataset, plus the background class. Records from pure stands have been averaged between May and August (inclusive) of the years 2017–2022.

3.4 Spatial distribution

It can be expected that the temporal signatures vary with local conditions, e.g. along an latitudinal or elevation gradient. Therefore, it is important to analyze the spatial coverage of the training data. Figure 12 shows that *Picea abies* (a) is mainly present in the south-west of Germany and in the lower mountain ranges. *Pinus sylvestris* (b) on the other hand, is predominant on the sandy soils of the north-eastern part of the country. The different *Quercus* species (c) occur mostly in the west of Germany, but are also present throughout the rest of the country. *Fagus sylvatica* (d), lastly, co-occurs with *Quercus* spp., but in contrast to them, manages to settle in the higher and therefore colder hillscales of the central parts of Germany. Note however, that these spatial distributions are derived from the dataset, which does not mirror the NFI one to one due to filtering and the availability of satellite images.

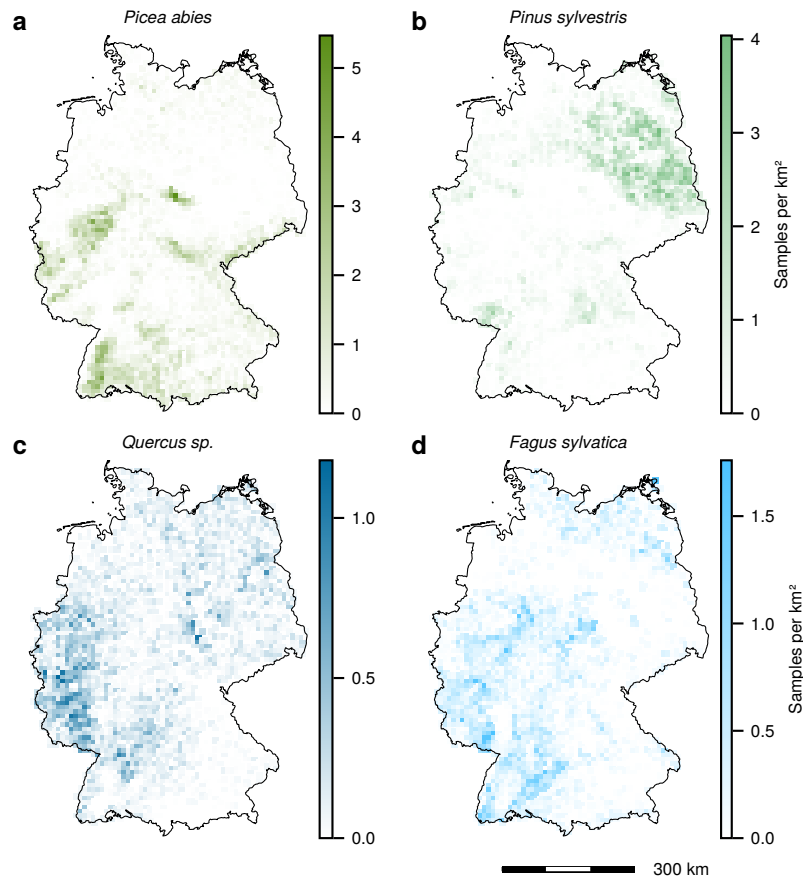


Figure 12. Spatial tree distribution for different species. Note the different scales. Borders: © GeoBasis-DE / BKG (2024)

230 3.5 NFI geolocation accuracy estimation

The analysis of the spatial accuracy of the NFI plot coordinate GNSS measurements reveals that 95% of corrected GNSS positions deviated by less than 11.2 m, and 81% by less than 5 m; Figure 13 depicts the corresponding histogram along with the empirical cumulative density function. Against expectations, the comparison of corrected and uncorrected GNSS measurements shows no significant difference.

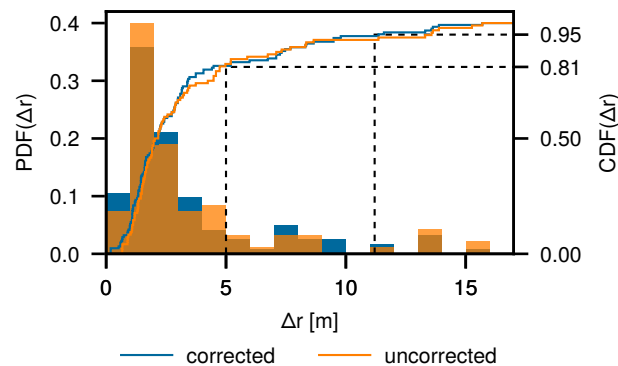


Figure 13. Histogram of distances by which plot locations were shifted from the original GNSS positions. Differentially corrected measurements are depicted in blue.

235 3.6 Separability analysis

Figure 14 shows the histograms of S2 band B8 (842nm) averaged over all records in June 2021 for the species pairs *Betula pendula* – *Pinus sylvestris* and *Fagus sylvatica* – *Quercus robur* – *Quercus petraea*, each computed over mixed and pure stands, respectively. [These combinations were chosen because the respective species are often co-occurring.](#) The reflectance distributions for *Pinus* and *Betula* clearly differ between mixed and pure stands. In mixed stands, the distributions are relatively wide and overlap, whereas in pure stands, there are separable peaks (albeit some overlap remains) and the distance between maxima is larger. Comparing *Fagus sylvatica* to the two *Quercus* species, one can see that the distributions overlap much more, as all three species are broad-leaved. In mixed stands, there is hardly any observable difference between the distributions. For pure stands, the distributions still overlap significantly, but the distance between peaks is slightly larger than in mixed stands.

4 Discussion

245 4.1 Geolocation accuracy

Sentinel-2: To obtain the presented dataset, we linked spatial information from two different data sources: georeferenced satellite images and on-ground GNSS measurements. A misalignment of these sources might lead to extracting wrong pixel values from the image data. FORCE co-registers all Sentinel-2 images with averaged Landsat time series. The Landsat images

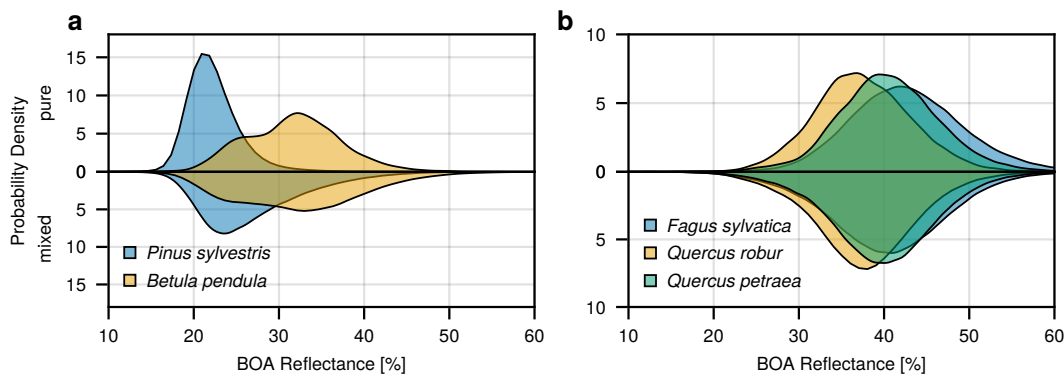


Figure 14. Histogram of near infrared (842 nm) BOA reflectances, averaged over all trees in June 2021, for (a) *Pinus sylvestris* and *Betula pendula* and (b) *Fagus sylvatica*, *Quercus robur* and *Quercus petraea*. The upper parts represent pure stands and the lower parts mixed stands.

are in turn co-registered with the Sentinel-2 global reference image which results in a geometric accuracy of 10.2 m at the 90% confidence level for Landsat 8 (Haque et al., 2022) (8 m at 80% confidence). Consequently, this is the best estimate for the spatial accuracy of the used S2 images. The reason for this cyclic co-registration of Sentinel to Landsat to Sentinel is, that so far only the S2 level 1 archive has been processed to a common standard⁶. The level 2 data, which compensates atmospheric effects and is needed for coherent time series, is not yet available at a standardized processing baseline in any public archive.

NFI geolocation accuracy: The comparison of corrected and uncorrected GNSS measurements showed no significant difference in spatial accuracy, at least not the way we measured it. As differential correction unquestionably increases the GNSS accuracy, we suppose that increasing the count of sampled plots as well as the number of image interpreters would change our result. Furthermore, trees growing skew and outliers when matching the crown patterns might have negatively influenced the results. Lastly, it will be interesting to analyze the accuracy of trained classifiers as a function of correction status.

Combined geolocation accuracy: The combined geolocation accuracy is difficult to compute for several reasons: 1) the satellite images are corrected by FORCE, as discussed above, 2) the satellite image accuracy is latitude- and time-dependent⁷ and 3) the GNSS errors we measured do not follow a Gaussian distribution. Neglecting these points and using the values derived for the 80% confidence level, namely 8 m for the satellite images and 5 m for the GNSS positions, we obtain an error estimate of 9.4 m. This is nearly equivalent to the pixel size, which means that the extracted pixel values are still likely to represent a reasonable approximation of the targeted trees, whose diameter is of comparable size. Lastly, the error of 9.4 m is likely overestimated for two reasons: first, the true error distributions of GNSS and satellite geolocation error magnitudes is Log-Normal (opposed to a Rayleigh distribution), typically having a higher share of small magnitudes. Second, the 8 m satellite geolocation error is derived for a single Sentinel-2 scene, but it is averaged out by the co-registration process.

⁶<https://sentinels.copernicus.eu/web/sentinel/technical-guides/sentinel-2-msi/copernicus-sentinel-2-collection-1-availability-status>

⁷S2 Data Quality Reports: <https://sentiwiki.copernicus.eu/web/document-library>

4.2 Adverse imaging conditions

During the extraction process, we filtered out most pixels with cloud cover or cloud shadows. FORCE employs the FMASK algorithm (Zhu and Woodcock, 2012) for cloud detection, which has an accuracy of 84% for cloud / clear detection and 72% detection accuracy for cloud shadows (Aybar et al., 2022). Consequently, falsely labeled image regions lead to commission or omission errors in the final dataset, i.e. usable pixels might have been removed by being labeled as cloudy or cloud pixels could be in the dataset. However, there are other imaging conditions that might affect the quality of a pixel like high aerosol content, snow or poor illumination conditions. FORCE encodes this information in the quality assurance information and end users can use this to further narrow the dataset down to only the highest quality pixels.

4.3 Extraction of non-forest points

The non-forest points were randomly sampled within the extracted 300 m × 300 m tiles. In consequence, we only sampled non-forest points from areas like city centers or industrial zones where they are situated close to forest – which is rather unlikely. Therefore the extracted non-forest points are biased towards rural villages and agricultural areas.

4.4 Taxonomic identification

The field teams of the NFI data are trained and undergo testing before being allowed to take samples. However, it cannot be ruled out that under adverse conditions certain species are confused. We cannot quantify this error, but assume that the vast majority of tree species identifications are correct, in particular for the common species.

4.5 ~~Mixed and duplicate pixels~~ Tree-centric pixel extraction

~~At present, we cannot exactly quantify the effect of pixels that contain different tree species on our dataset, as it is in most cases impossible to derive the species shares of a pixel based on the NFI data. The NFI does not fully sample a given plot, so in most cases, labels are only available for parts~~ As described in section 2.4, there are different ways of linking satellite image data with field information. We took a “tree-centric” approach and extracted reflectances for every tree in the dataset. Compared to the pixel-centric approach, this comes with advantages and disadvantages. The main advantage of the tree-centric approach is that it reflects the response design of angle count sampling and one obtains the best estimate for the spectral reflectance of a given pixel. Another source for mixed pixels are the 20 m resolution bands of Sentinel-2 that are pan-sharpened to 10 m by FORCE, thereby distributing identical information across several pixels tree crown. This allows to extract data also for rare species and such, that only appear in mixed stands, albeit their statistics will be influenced by mixed pixels. Lastly, one does not need to define a dominant species based on arbitrary thresholds, as done in Persson et al. (2018), for example.

~~Due to the method we used to extract pixel values, trees that are~~ A drawback in comparison to the pixel-centric approach is, that different tree crowns can receive the same spectral signature. For example, if two tree crowns are completely located within the same S2 pixel, they receive identical values and information is duplicated. We checked the non-randomized dataset for duplicate bottom of atmosphere reflectances among the tree records. Non-tree points were sampled from a larger area,

so duplication plays no role in their case. To identify duplicates, we grouped the dataset by cluster id, corner id, time and
300 reflectance spectrum. If there were N identical reflectances per group, we counted N-1 as duplicates. In total, the dataset subset
for trees contains ca. 4.87 million duplicate entries out of ca. 66 million, which translates to 7.38%. Out of these 4.87 M
duplicates, 3.86 M (5.84%) are duplicates with identical species label and 1.01 M (1.53%) have differing species labels. Ergo,
at least 0.77% ($1.01 \text{ M} / 66 \text{ M} / 2$) of the labels are wrong.

Should the user wish to reduce the correlation between samples or remove duplicate pixel time series, we recommend the
305 following procedure: first, group the dataset by subplot; second, compute the correlation of the full time series between the
different trees in the plot; and finally, remove all trees that correlate beyond a certain threshold, except for one.

A weakness that both approaches, tree-centric and pixel-centric, share are mixed pixels: At present, we cannot exactly
quantify the effect of pixels that contain different tree species on our dataset, as it is in most cases impossible to derive the
species shares of a pixel based on the NFI data. The NFI does not fully sample a given plot, so in most cases, labels are
310 only available for parts of a given pixel. Another source for mixed pixels are the 20 m resolution bands of Sentinel-2 that are
pan-sharpened to 10 m by FORCE, thereby distributing identical information across several pixels.

4.6 Species separability analysis

Figure 14 (a) showed that the IR-reflectance distributions of *Pinus* and *Betula* are wide and overlap in mixed stands, whereas
they are more separated in pure stands. We interpret this as a potential indication that, at least for this species pair, the dataset
315 may contain mislabeled data due to insufficient spatial accuracy or that the extracted pixel values originate from mixed pixels
containing other species or land cover classes.

In contrast, comparing *Fagus* and *Quercus* spp. in mixed and pure stands revealed no significant differences, with the re-
flectance distributions overlapping substantially. However, this does not necessarily indicate labeling errors; it could also reflect
naturally occurring values. This highlights the necessity of including factors beyond spectral data, e.g. temporal profiles as
320 shown in Figure 9, for accurate species classification.

4.7 Considerations for map production

The purpose of this dataset is to train classifiers, ultimately for mapping of tree species. These classifiers will have a certain
model accuracy, derived from e.g. the validation split of the presented dataset. However, caution is required when judging the
accuracy of generated maps based on the model accuracy - the model accuracy should not be used as sole basis for validation.
325 This applies to the current dataset as well, since heuristic data filtering or pixel duplication may have altered the distribution
of reflectance values in a way that could negatively affect the results. Users should also consider this when applying additional
data filters, e.g. for the diameter at breast height. Consequently, we recommend auxiliary data for validating generated maps. If
users wish to validate maps based on the presented dataset, they can do so using aggregate statistics, such as at state level, since
the dataset contains coarse location data that makes it suitable for such analyses. However, such analyses will be restricted to
330 trees that are visible from above according to our heuristic. Further, areas covered by tree species, as derived from produced
maps, can be compared to population estimates from the NFI, which are publicly available (J.H. von Thünen-Institut, 2024).

Lastly, the “area of applicability” approach developed by Meyer and Pebesma (2021) can be used to ensure that models are not applied outside the predictor variable space, thus preventing potential bias.

5 Conclusion and outlook

335 In this work, we ~~presented the so far~~ present the most comprehensive dataset so far of annotated Sentinel-2 time series data for tree species detection in Germany. With over 380 thousand trees of 48 species observed for over seven years, this dataset can significantly advance research into automatic tree species classification for Germany, and central Europe. At the same time the described approach can serve as a pilot study for making national forest inventory data from other countries accessible for the remote sensing community e.g. for training machine learning models without releasing the exact geolocations publicly.

340 Lessons learned from its application can be used to enhance future inventories and datasets. For example, it could show that for underrepresented species more labels are required, which in turn could be sampled in targeted inventories.

As discussed in the previous section, the dataset still has several shortcomings that could be improved. To achieve better agreement between labels and images, the spatial accuracy of the data sources has to be increased. To do so, we suggest that in future all NFI position measurements are taken using differential GNSS devices, although we saw no significant differences

345 in accuracy. Furthermore, we expect that aligning the Sentinel-2 images directly with the S2 global reference image instead of averaged Landsat time series would improve their spatial accuracy and make it easier to derive interpretable error metrics. We consider releasing an updated dataset version as soon as Sentinel-2 L2A collection one is fully accessible.

The main focus of further efforts will be to increase the number of labels for weakly represented classes, e.g. by utilizing automatically classified high resolution orthophotos as reference. First attempts to automatically identify underrepresented tree

350 species in standard RGBI aerial images with 20 cm spatial resolution have failed, so the presented dataset is still limited regarding less abundant species. Another option to increase the overall amount of data would be to incorporate forest inventory data at the stand level from e.g. state forest enterprises, however, this data often only provides estimates of tree species proportions within management units, but no geolocation of individuals.

We hope that this dataset fosters the research into time series-based classification of tree species and believe it offers many

355 possibilities for analyses that go beyond the ones presented here. Users can freely recombine the provided data and for example calculate basal or crown area proportions per sampling location and use this information as labels instead. Using classification methods in general, one could investigate which spectral bands and which points in time are crucial for precise species classification. As the dataset not only contains the time series of individual trees’ BOA reflectances, but also their approximate location, spatio-temporal patterns in tree phenology could be assessed on individual species level. For example, the onset of

360 leaf emergence could be analyzed first in the dataset alone, and later by using species maps generated by a derived classification method. Lastly, the dataset could be used to correlate reflectances and approximate health conditions with meteorological events like droughts on a per-species level. This would open up further research into climate-change resistant species and enables the identification of endangered forest stands. In the future we plan to release updated versions of the dataset, particularly after the final publication of the 2022 NFI.

365 **6 Data availability**

All data is available online under <https://doi.org/10.3220/DATA20240402122351-0> (Freudenberg et al., 2024) with CC BY 4.0 license.

Author contributions. MF: coding, assembling the dataset, main work on manuscript, SS: data provision, proof reading, advice in research questions, PM: advice in research questions, manuscript development, proof reading

370 *Competing interests.* The authors declare to have no conflicts of interest.

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375 **Appendix A: Crown area estimation**

Following equation is used to model the crown area, using the parameters α and β from table A1 (Riedel et al., 2017, pp. 39, 40).

$$A_C = \alpha + \beta A_B \tag{A1}$$

A_C : Tree crown area, A_B : Basal area

380 **Appendix B: Additional Figures**

Appendix C: Database excerpt and species counts

Table A1. Parameters of the crown area equation (Riedel et al., 2017, p. 40). We corrected the α value for poplar; the original value is 23, which is a typing error.

Tree Species Group	α [m ²]	β	Max.	
			Stem Count	Assigned Tree Species
Fir	2.85	200	3500	All firs except hemlock
Douglas Fir	5.00	200	2000	Douglas fir
Pine	1.00	300	10000	All pines
European Larch	5.00	285	2000	European larch
Japanese Larch	5.00	260	2000	Japanese larch (+ hybrids)
Beech	1.33	300	7500	Beech, hornbeam (whitebeam)
Oak	1.11	395	9000	Pedunculate oak, sessile oak, Turkey oak, swamp oak
Red Oak	2.50	350	4000	Red oak
Ash	2.50	330	4000	All other deciduous trees not mentioned
Alder	2.50	435	4000	Alder, black alder, white alder/grey alder, green alder
Birch	2.50	525	4000	Silver birch, downy birch (+ Carpathian birch)
Poplar	2.30	320	350	All poplars
Spruce	2.85	195	3500	All spruces as well as arborvitae, hemlock, sequoia, yew, Lawson cypress, other conifers

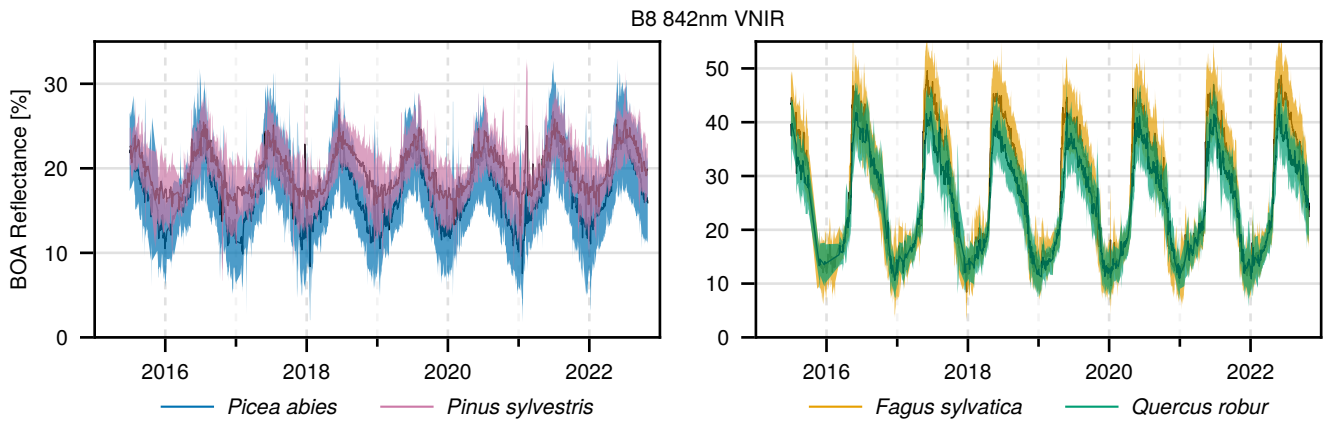


Figure B1. Time series of infrared reflectance and the standard deviation for indicated species, averaged over all undisturbed individual trees in pure stands at a given time. The bands have a width of 2 standard deviations. The data has been filtered to exclude all types of cloud cover and their shadows, snow, and pixels with high aerosol optical depth.

Table C1. Database excerpt. The bottom of atmosphere (BOA) reflectance is encoded as 10 signed 16 bit integers, the quality assurance information (QAI) is a single 16 bit integer. DOY abbreviates day of year.

tnr (cluster id)	enr (corner id)	tree_id	species	time	BOA	QAI	is_train	is_pure	
455	1	69831	211	1440374400	10 16-bit integers	8192	1	0	...
455	1	69831	211	1448064000	10 16-bit integers	10256	1	0	...
455	1	69831	211	1455494400	10 16-bit integers	10240	1	0	...
455	1	69831	211	1460592000	10 16-bit integers	8192	1	0	...
455	1	69831	211	1463961600	10 16-bit integers	8192	1	0	...
455	1	69831	211	1467072000	10 16-bit integers	8192	1	0	...
⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮

dbh_mm	height_dm	crown_area_m2	x_wgs84	y_wgs84	is_corrected	disturbance_year	present_2022	DOY	
...	231	243	20.4	9.80714	47.64294	1	0	1	236
...	231	243	20.4	9.80714	47.64294	1	0	1	325
...	231	243	20.4	9.80714	47.64294	1	0	1	46
...	231	243	20.4	9.80714	47.64294	1	0	1	105
...	231	243	20.4	9.80714	47.64294	1	0	1	144
...	231	243	20.4	9.80714	47.64294	1	0	1	180
...	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮	⋮

Table C2. List of all included tree species with counts (part 1).

Species Code	Species	Common Name	Count
-1	-	other land cover	70242
10	<i>Picea abies</i>	Norway spruce	107798
12	<i>Picea sitchensis</i>	sitka spruce	937
19	<i>Picea spec.</i>	other spruces	232
20	<i>Pinus sylvestris</i>	Scots pine	102730
21	<i>Pinus mugo</i>	mountain pine	88
22	<i>Pinus nigra</i>	European black pine	606
24	<i>Pinus cembra</i>	Swiss pine	3
25	<i>Pinus strobus</i>	eastern white pine	431
29	<i>Pinus spec.</i>	other pines	65
30	<i>Abies alba</i>	silver fir	9375
33	<i>Abies grandis</i>	grand fir	384
39	<i>Abies spec.</i>	other firs	291
40	<i>Pseudotsuga menziesii</i>	Douglas fir	9598
50	<i>Larix decidua</i>	European larch	7674
51	<i>Larix kaempferi</i>	Japanese larch (+hybrids)	3308
90		other coniferous trees	139
94	<i>Taxus baccata</i>	European yew	11
100	<i>Fagus sylvatica</i>	beech	57341
110	<i>Quercus robur</i>	English oak	19617
111	<i>Quercus petraea</i>	sessile oak	18697
112	<i>Quercus rubra</i>	Northern red oak	1861
120	<i>Fraxinus excelsior</i>	common ash	7469
130	<i>Carpinus betulus</i>	hornbeam	3411
140	<i>Acer pseudoplatanus</i>	sycamore maple	5042
141	<i>Acer platanoides</i>	Norway maple	598
142	<i>Acer campestre</i>	field maple	387
150	<i>Tilia spec.</i>	linden tree (indigenous species)	1294
160	<i>Robinia pseudoacacia</i>	black locust	1553
170	<i>Ulmus spec.</i>	elm, native species	406
181	<i>Castanea sativa</i>	chestnut	416
190		misc. broadleaf trees with long life expectancy	246
191	<i>Sorbus domestica</i>	service tree	2
193	<i>Sorbus aria</i>	common whitebeam	51
200	<i>Betula pendula</i>	silver birch	9729
201	<i>Betula pubescens</i>	moor birch	858
211	<i>Alnus glutinosa</i>	black alder	7098
212	<i>Alnus incana</i>	grey alder	460
220	<i>Populus tremula</i>	common aspen	1402
221	<i>Populus nigra</i>	European black poplar (+ hybrids)	1945

Table C3. List of all included tree species with counts (part 2).

Species Code	Species	Common Name	Count
222	<i>Populus x canescens</i>	grey poplar (+hybrids)	196
223	<i>Populus alba</i>	silver poplar	109
224	<i>Populus trichocarpa x maximoviczii</i>	balsam poplar	636
230	<i>Sorbus aucuparia</i>	European rowan	270
240	<i>Salix spec.</i>	willow	1203
250	<i>Prunus padus</i>	bird cherry	77
251	<i>Prunus avium</i>	wild cherry	1357
252	<i>Prunus serotina</i>	black cherry	132
290		misc. broadleaf trees with short life expectancy	92
292	<i>Malus sylvestris</i>	European crab apple	37
293	<i>Pyrus communis</i>	European wild pear	42
295	<i>Sorbus torminalis</i>	wild service tree	71

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