Enriching the GEOFON seismic catalogue with automatic energy magnitude estimations

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Abstract. We present a seismic catalogue including energy magnitude M_e estimated from P-waves recorded at teleseismic distances in the range $20^\circ \le \Delta \le 98^\circ$ and for depths less than 80 km. The catalogue is built starting from the event catalogue disseminated by GEOFON, considering 6349 earthquakes with moment magnitude $M_w \ge 5$ occurring between 2011 and 2023. Magnitudes are computed using 1031396 freely available waveforms archived in EIDA and IRIS repositories, retrieved through

- 5 standard FDSN webservices (https://www.fdsn.org/webservices/). A reduced, high quality catalogue for events with $M_w \ge$ 5.8 and from which stations and events with only few recordings were removed forms the basis of a detailed analysis of the residuals of individual station measurements, which are decomposed into station and event specific terms, and a term accounting for remaining variability. The derived M_e values are compared to M_w computed by GEOFON and with the M_e values calculated by IRIS. Software and tools developed for downloading and processing waveforms for bulk analysis and an
- 10 add-on for SeisComP for real-time assessment of M_e in a monitoring context are also provided alongside the catalogue. The SeisComP add-on is part of the GEOFON routine processing since December 2021 to compute and disseminate M_e for major events via the existing services.

Copyright statement. TEXT

1 Introduction

15 Several magnitude scales have been defined to characterize the size of an earthquake. We can, however, divide magnitude scales in two groups: one including magnitudes based on the amplitudes and periods of different seismic phases measured on band-limited signals (e.g., the body- and surface-wave magnitudes, Gutenberg, 1945a, b); the other including magnitude scales related to estimations of macroscopic physical parameters of the earthquake source. The latter comprise the moment (M_w , Kanamori, 1977; Hanks and

- Kanamori, 1979) and the energy (M_e , Boatwright and Choy, 1986) magnitudes, which are based on seismic moment (Aki, 1966) and radiated seismic energy (Haskell, 1964), respectively. These two magnitude scales are somewhat complementary because, although both represent an estimation of earthquake-related energy, they are determined by different parts of the source spectrum. The seismic moment characterizes extrapolated from the low frequency end and represents the release of elastic energy stored in the Earth's
- crust or mantle, being proportional to the integrated slip across the fault surface. The radiated seismic energy describes the fraction of the total energy released being radiated as seismic waves across all frequencies, i.e., it depends on the earthquake dynamics such as rupture velocity but also stress drop. M_e estimates have been shown to play an important role when used in conjunction with M_W to better characterise the tsunami and shaking potential of an earthquake (Newman and Okal, 1998; Di Giacomo et al., 2010).
- M_w is routinely computed from long period signals of broad-band recordings and it has become a robust and reliable source parameters parameter for large and moderate earthquakes worldwide (Di Giacomo et al., 2021). On the other hand the computation of M_e is hindered by the necessity of integrating the velocity power spectra over a wide frequency range whilst using signals in a limited bandwidth and taking into account propagation effects at high frequencies.
- Aiming at validating and testing for operational purposes the procedures, we present a seismic catalogue of M_e computed following the methodology proposed by Di Giacomo et al. (2008) and Di Giacomo et al. (2010) for the rapid assessment of energy magnitude (i.e., without requiring additional source information other than the hypocentral location). The approach is based on the analysis of spectra computed for teleseismic vertical-component P-waveforms. Teleseismic P-waves are commonly used to compute M_e
- 40 for global earthquakes as their energy loss during propagation can be more reliably modeled compared to S-waves. We further present a detailed analysis of the residuals in a reduced high quality catalogue for events with $M_w \ge 5.8$ with respect to the M_w available in the GEOFON catalogue and the M_e values computed by IRIS.

2 Energy magnitude computation

45 2.1 Single station estimation

We implement the methodology proposed by Di Giacomo et al. (2008) and Di Giacomo et al. (2010) to compute M_e . Teleseismic vertical component P-waveforms (BHZ channels) are analyzed in the distance range from 20° to 98°, and for earthquakes shallower than 80 km. Standard teleseismic range usually starts at 30°, but we use 20° to allow closer stations to be used for rapid response purposes. Shortest distances,

50 however, are difficult to include for global earthquakes as regional effects are not well accounted for with a 1-D model. Propagation effects are accounted for by frequency-dependent amplitude decay functions, computed numerically (Wang, 1999) for the ak135Q model (Kennett et al., 1995; Montagner and Kennett, 1996) in the frequency range 0.012-1 Hz.

An estimate of radiated seismic energy E_s is obtained for <u>each</u> single station from the integral of the power spectra of the vertical component P waveform, corrected for propagation effects (Haskell, 1964):

$$E_{s} = \left[\frac{2}{15\pi\rho\alpha^{5}} + \frac{1}{5\pi\rho\beta^{5}}\right] \int_{f_{1}}^{f_{2}} \left|\frac{\dot{u}(f)}{G(f)/2\pi f}\right|^{2} df$$
(1)

where α , β , and ρ are the P-wave velocity, S-wave velocity and the density at the source, respectively; f is the frequency and $f_1 = 0.012$ Hz and $f_2 = 1$ Hz are the lower and upper limits of the considered spectral bandwidth; $\dot{u}(f)$ is the P-wave velocity spectrum; G(f) is the median value of Green's functions spectrum

60 for displacement, which are computed across a wide range of plausible focal mechanism solutions and the median value is extracted computed from multiple combinations of focal mechanisms, varying strike, dip and rake over regular grid (Di Giacomo et al., 2008).

We used analysis windows starting just 10 seconds before the P arrival and with lengths of 90 s for $M_w \le 7.5$, 120 s for $7.5 < Mw \le 8.5$ and 180 s for $M_w > 8.5$. The energy magnitude M_e estimate for a single event station-pair event-station pair is in turn computed as $M_e = 2/3(log_{10}E_s - 4.4)$, with E_s given in Joule (Bormann et al., 2002). The procedure provides M_e estimates at each recording station that can be averaged to minimize path-specific deviations not accounted for by the theoretical model (e.g., directivity and focal mechanism effects, regional variations in attenuation).

2.2 Open-source tool for computing M_e

⁷⁰ The above procedure is implemented in the package *me-compute* (Zaccarelli, 2023). The program uses *stream2segment* (Zaccarelli et al., 2019; Zaccarelli, 2018) to download events, station metadata and wave-forms from FDSN compliant repositories in a SQL database.

In our application, the download is configured to fetch events from the GEOFON (Quinteros et al., 2021) event web service, selecting events with computed Mw in the time span 2011-2023. Waveforms

- are download from EIDA (Strollo et al., 2021) and IRIS (https://service.iris.edu/) data centers. The processing routine is implemented in a Python module which computes the station energy magnitude for each downloaded waveform segment, as summarized in section 2.1, and then calculates the event energy magnitude M_e as the mean of all station magnitudes within the 5th–95th percentile range. The final output consists of the following files:
- a tabular file in HDF format, where each row represents the metadata and measurements, specifically also the station energy magnitude estimate, for a single waveform.
 - a tabular file in CSV format aggregating the results of the previous file, where each row represents a seismic event, reporting the event data end metadata, including the M_e estimate for the event.
 - an HTML file visualising selected content reported in the csv file, where the information for each event can be visualized on an interactive map
 - one file per processed event in QuakeML format, where we included also the M_e value.

All files produced by *me-compute* are disseminated in the data archive (Bindi et al. (2023); https://doi.org/ 10.5880/GFZ.2.6.2023.010), along with the *stream2segment* and *me-compute* configuration files.

3 Catalogue compilation

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We use *me-compute* to compute M_e for $M_w \ge 5$ earthquakes since 2011 in the GEOFON catalogue. Table 1 summarizes the steps followed to compile the disseminated M_e catalogue. The catalogue reports the single waveform energy magnitude M_{eij} estimated at station j for earthquake i. The energy magnitude M_e for each considered event i is then computed as the median of M_{eij} over the set of recording stations, without considering station static corrections. The starting data set D0 consists of more than one million

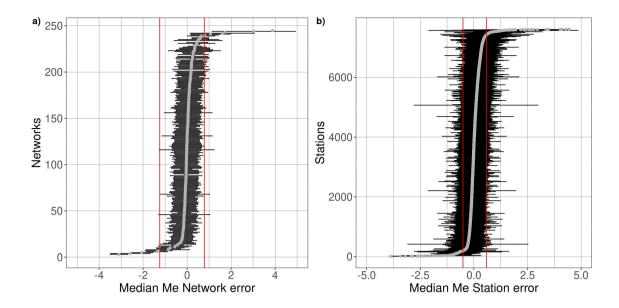


Figure 1. Median network residuals (circles) for data set D0 (left) and median station residuals for data set D1 (right); red lines correspond to the 2.5 and 97.5 percentiles of the distributions; for each network (left) and station (right) the horizontal bars correspond to the interval median (circle) ± 1 median absolute deviation (MAD). Few values falling outside the range considered for the horizontal axis are not shown.

waveforms (channels BHZ) generated by 6963 earthquakes recorded by 7765 stations belonging to 246 different networks. Only recordings with an average SNR for the amplitude greater than 3 within the frequency range of interest are included in D0. Several integrity and quality checks are applied to remove outliers and faulty signals. Data set D1 is obtained by analyzing the median residual at the network level, discarding 14 networks characterized by median residuals outside the 2.5 and 97.5 percentile range (Fig-ure 1a). Data set D2 is then generated by analyzing the station median values and excluding 382 stations with residuals outside the 2.5-97.5 percentile range (Figure 1b). Most of the networks and stations removed will have instrumental problems or faulty metadata regarding instrument responses, although in

some cases stations with very strong site effects might also be excluded.

The anomaly score, a classifier proposed by Zaccarelli et al. (2021); Zaccarelli (2022) is used An anomaly score is computed to further refine the data set by flagging anomalous amplitudes using the software sdaas (Zaccarelli, 2022). The software, developed from the work of Zaccarelli et al. (2021) is based on a machine learning algorithm specifically designed for outlier detection (Isolation forest) which computes an anomaly score in [0, 1], representing the degree of belief of a waveform to be an outlier. The score can be used to assign robustness weights, or to define thresholds above which data can be discarded. After

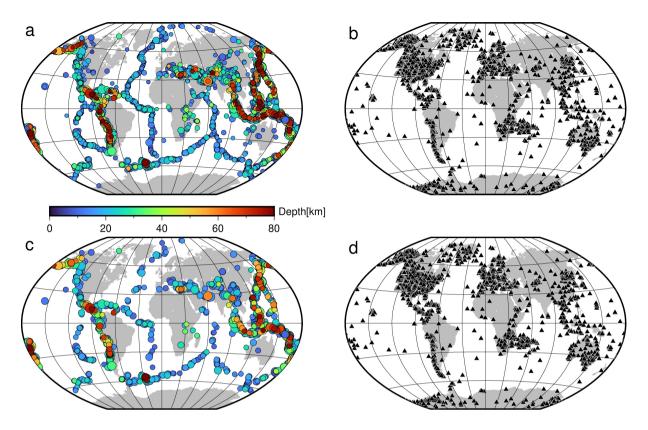


Figure 2. Panels a and b show event and station locations for data set D3 (Table 1), respectively; panels c and d show event and station locations for data set D6 (Table 1), respectively.

inspecting the distribution of the anomaly scores, we set the threshold to 0.62 for $M_w < 7.5$ and to 0.80 for $M_w \ge 7.5$.

The spatial distribution of events and stations generating the preferred (extended) data set D3 are shown in Figures 2a,b; this dataset is disseminated as part of the supplementary dataset. The corresponding M_e residuals are shown in Figure 3 against distance and M_w . The largest positive residuals correspond mostly to earthquakes with $M_w < 6$ recorded at distances $\Delta > 60^\circ$, where the implemented methodology is expected to generate biased station M_e estimates due to the limitations in the analyzed bandwidth and low signal-to-noise ratio (Di Giacomo et al., 2008, 2010). The overall residual distribution is unbiased and does not show trends of the mean value with distance and magnitude.

Therefore, we further limit the dataset by only considering events with $M_w \ge 5.8$ and at least 10 single station measurements; we further exclude stations with less than 10 recordings in total. We added a column in the disseminated event D3 dataset to flag lines fulfilling these further requirements; those flagged Table 1. Data sets considered in this study.

Dataset	records	networks	stations	events	SelectionSelections applied sequentially
D0	1126465	246	7765	6963	$M_w \ge 5$
D1	1072381	232	7617	6944	Network selection (2.5-97.5 perc.)
D2	1034833	228	7235	6880	Station selection (2.5-97.5 perc.)
D3	1031396	228	7234	6349	Anomaly score (< 0.62, < 0.8 for M_w < 7.5, \geq 7.5, resp.
D4	754025	228	7228	1731	$M_w \ge 5.8$
D5	751567	227	7135	1731	#records per station ≥ 10
D6	750903	227	7135	1671	#record per event ≥ 10
Dg				153	comparison between D6 and real time

lines correspond to data set corresponding to D6, the final product of this study. It consists of ~ 750000 waveforms for 1671 earthquakes and 7135 stations. The event and station locations of D6 are shown in Figures 2c and 2d.

125 4 Quality assessment via residual analysis

We perform residual analysis to validate the D6 catalogue. The relationship between M_e and M_w is analyzed by performing the following mixed-effects regression (Bates et al., 2015)(Bates et al., 2015; Stafford, 2014):

$$M_{eij} = c_1 + c_2 M_{wi} + \delta S_j + \delta E_i + \epsilon_{ij} \tag{2}$$

- where M_{eij} is the single waveform energy magnitude estimate at station j for earthquake i; intercept c₁ and slope c₂ parameters define the median model; δS_i and δE_j are terms that capture station-specific and earthquake-specific adjustments, respectively; ε_{ij} accounts for the left-over effects (i.e., residuals that are specific to a particular path/waveform). The random effects δS, δE and ε are zero-mean normal distributions by construction. In particular, δS_j (inter-station residual) can represent site effects or instrumental gain corrections, with most of the latter probably removed by the outlier filtering stages described above.
- The inter-event residual δE_i is an event-specific deviation from the M_e expected for a given M_w from the linear regression term. Finally, ϵ_{ij} can be thought of as a noise term for individual measurements, which can be either related to path-specific heterogeneity in attenuation with respect to the 1D reference model, or the influence of ambient noise on the actual measurement.

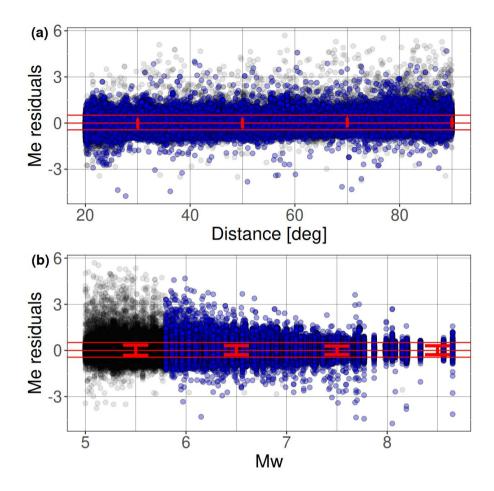


Figure 3. Energy magnitude residuals versus distance (a) and moment magnitude (b) for data set D3. <u>Blue dots indicate residuals also</u> included in D6. The horizontal red lines bound the 90% confidence interval [-0.43,0.50] of the residual distribution; the error bars indicate the mean ± 1 standard deviation of the residuals computed over different distance (20° wide) and magnitude (1 m.u. wide) intervals.

The inter-event and inter-station term distributions are shown in Figure 4, which are described by standard deviations of τ=0.27-0.246 and φ_S= 0.19-0.188 m.u., respectively; the standard deviation of the ε is φ₀=0.23-0.232 m.u. By combining Combining the inter-event variability τ with the intra-event one equal to φ = √φ₀² + φ_S variability equal to φ = √φ₀² + φ_S², we obtain the total standard deviation σ = √τ² + φ² = 0.407, which represents the variability of the single station M_{eij} residuals with respect to the average M_e computed per event. It is worth noting that the δS_j values can be used as station corrections to compute the energy magnitude of new events. In this case, the inter-station contribution to the total variability is removed and the expected variability of the M_{eij} distribution is reduced to

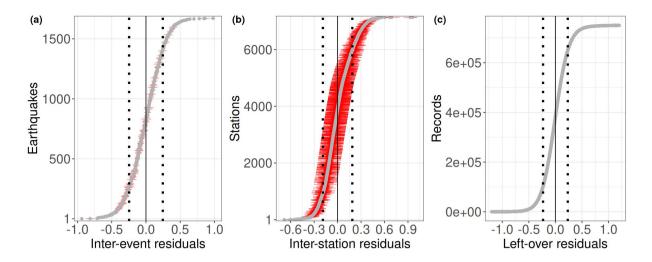


Figure 4. Cumulative distribution functions for event δE (a), station δS (b), and left-over ϵ distributions (circles) determined according to the mixed-effects regression in equation 2 applied to data set D6. Dotted lines correspond to standard deviations $\pm 1\tau$ (a), $\pm 1\phi_S$ (b, and $\pm 1\phi_0$ (c). Red horizontal lines in panels (a) and (b) are the standard errors of the random effects; in panel (c), values of ϵ exceeding ± 1.2 in absolute value are not shown.

 $\sqrt{\tau^2 + \phi_0^2} = 0.338$. Finally, the linear regression model is defined by the coefficients $c_1 = (0.77 \pm 0.09)$ m.u. and $c_2 = (0.92 \pm 0.01)$. Considering the simplicity of the linear model in equation 2 and the large data set analyzed, the uncertainty on the median model (sometimes referred to as σ_{μ} , Atik and Youngs (2014)) is very low, increasing from 0.007 for $M_w = 6$ to 0.039 for $M_w = 9$.

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We show the spatial distribution of δS in Figure 5. Since M_{eij} is computed considering spectral values below 1 Hz, and using teleseismic recordings for distances above 20°, δS capture station-specific effects connected to large-scale geological and tectonic crustal features, as exemplified in Figure 5b 5 for stations located in Europe: positive δS (i.e., M_{eij} larger than the median) are observed for stations located in basins like in the Po plain, in the Moesian region, in the Netherlands, and in the East Anatolian fault region; negative values δS (i.e., M_{eij} lower than the median) are observed for stations located in mountain ranges such as the Pyrenees, the Alps, or in Harz highlands, but also tectonically highly active regions like but cratonic as the East African rifts. The station terms can represent both site amplification, e.g. for stations

in sedimentary basins, and anomalously high or low attenuation in the crust and or mantle surrounding the station. The station-specific residuals are disseminated along with the catalogue to allow the computation of M_e for future earthquakes taking into account static magnitude corrections to reduce variability.

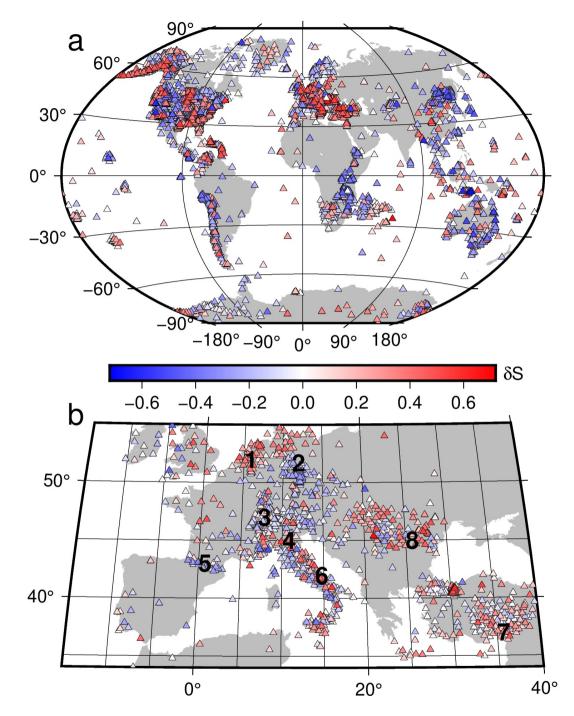


Figure 5. (a) Distribution of the site-specific residuals δS , see equation 2 and (b) zoom over a portion of Europe. Numbers in (b) indicate the following locations: 1. Netherlands; 2 Harz highlands, Germany; 3 Switzerland; 4 Po plain, Italy; 5 Pyrenees mountain range; 6 Apennines mountain range; 7 East Anatolian fault region;8 Moesian platform.

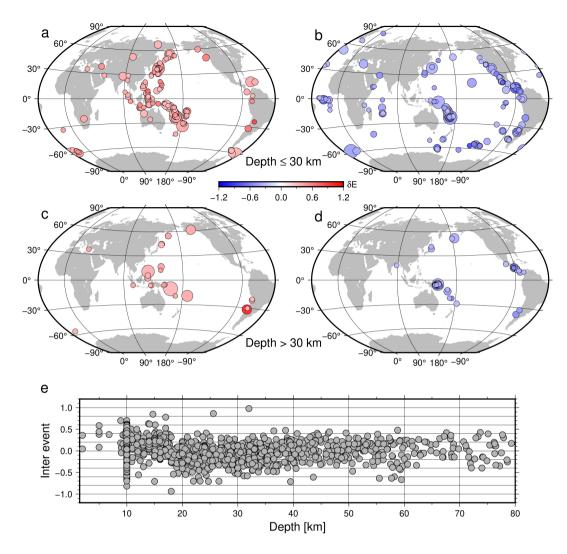


Figure 6. Extreme values for event specific residuals δE for the M_{eij} versus M_w mixed-effects model of equation 2. Only values below the 10th percentile (panels b and d) and above the 90th percentile (panels a and c) of the distribution are shown (the percentiles are about \pm 0.3). In panels a and b, earthquakes with hypocentral depths shallower than 30 km are selected; in panels c and d, events deeper than 30 km are considered. The distribution of δE versus depth for all events is shown in panel e.

The spatial distribution of the inter-event variability, δE , is shown in Figure 6 for the smallest and largest values.

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Considering depths shallower than 30 km (panels a and b), continental Asia, Philippines and Indonesia, Aleutian islands show positive values; California, Mexico, central America, the Atlantic ridge are characterized mostly by negative values. Considering deeper events (panels c and d), Japan and Philippines have

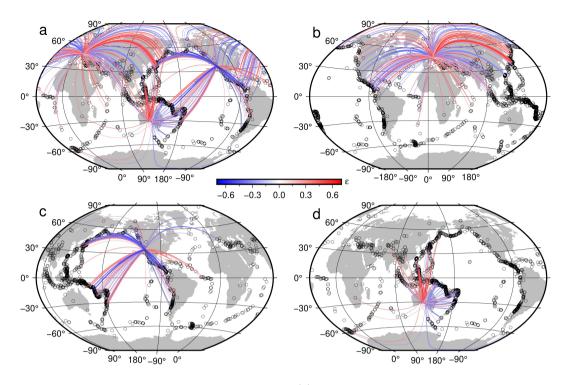


Figure 7. Left-over residual distribution ϵ of equation 2-2, showing only $|\epsilon| > 0.30$. a) residuals associated to three different receiving areas; b) as in panel a) but considering only the European receiving area; c) as in panel a) but considering only the receiving area in California; d) as in panel a) but considering only the receiving area in Australia. Circles indicate the earthquake locations.

mostly positive values, Mexico and central America mostly negative values. The event specific residuals are also disseminated along with the catalogue for increasing the usefulness of the product from the event point of view and to allow the user to perform further refinements.

Path-specific residuals ϵ are shown in Figure 7 for three selected receiving areas in Europe, California and Australia. Since in the partition of the residuals the left-over distribution ϵ represents the component not related to systematic station and event effects, they are mostly connected to lateral variability in attenuation in the Earth's interior with respect to the used global 1D model and amplitude variation related to P wave radiation patterns for different focal mechanisms.

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Finally, the M_{eij} versus M_w scaling defined by the linear regression coefficients c_1 and c_2 of equation 2 is shown in Figure 8.

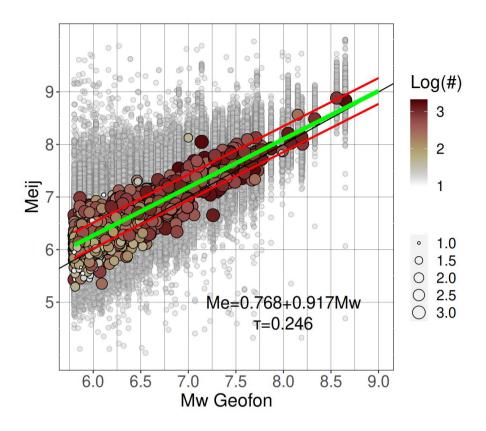


Figure 8. M_{eij} versus M_w scaling. Gray circles are the station M_{eij} estimates, filled circles represent event M_e values calculated as medians of all station estimates for that event; colour indicates how many stations contributed to each estimate. The best fit line in green is derived from the mixed-effects regression, equation 2, considering \pm one inter event standard deviation τ (red lines). The faint black line shows equality for reference.

4.1 Catalogue validation: comparison with IRIS

The energy magnitude computed in this study is compared to the values disseminated by IRIS through the SPUD service IRIS DMC (2013). The methodology implemented by IRIS is described by Convers and Newman (2011) and based on the analysis of Boatwright and Choy (1986) and Newman and Okal (1998). Like usSimilar to our approach, the energy flux is computed from the P-wave group (P+pP+sP) in the frequency domain. The single-station estimations are corrected for frequency-dependent anelastic attenuation effects and converted back to the energy radiated by the source by applying corrections for geometrical spreading, depth and mechanism-dependent effects for P-waves, and considering a theoretical partition of the energy between P- and S-waves. The energy is computed considering the frequency range 0.014-2 Hz (broadband for $M_e(BB)$) or 0.5-2 Hz (high frequency for $M_e(HF)$), analyzing stations in the distance range $25^{\circ} - 80^{\circ}$. The duration of the time window used for the computation is based on analysis of the cumulative high-frequency energy (0.5-2 Hz) as a function of time. The crossover time used to compute the energy flux is identified at the intersection between the near constant increasing rate for short-times and the relative flat asymptotic behaviour for long duration. The SPUD service disseminates both the high-frequency $M_e(HF)$ and broad-band $M_e(BB)$ estimates.

Two regression models are calibrated against the broad-band and high-frequency estimates disseminated by IRIS through SPUD: $M_e = -0.076 + 1.002M_e(HF) \pm 0.234$ and $M_e = 0.795 + 0.896M_e(BB) \pm 0.175$, as-. The best-fit models, shown in Figure 9, are $M_e = (-0.076 \pm 0.229) + (1.002 \pm 0.033)M_e(HF)$ and

 $M_e = (0.795 \pm 0.188) + (0.896 \pm 0.027) M_e(BB)$ with standard deviation of the residuals equal to 0.234 and 0.175, respectively. For the magnitude range from 6 to 8, this results in biases of 0.06 m.u. for M_e vs $M_e(HF)$, and varying from 0.17 to -0.04 m.u. for M_e vs $M_e(HF)M_e(BB)$, i.e., our estimates are nearly unbiased relative to $M_e(HF)$ and tend to slightly overestimate $M_e(BB)$ at the lower end of the applicability range.

4.2 Catalogue validation: role of style of faulting

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The faulting style is classified into normal, reverse and strike slip categories based on the plunge of the P,T and N axes (Frohlich and Apperson, 1992) as extracted from the GEOFON moment tensor solutions: normal fault(NF) if plunge(P) $\geq 60^{\circ}$; strike slip (SS) if plunge(N) $\geq 60^{\circ}$; thrust fault (TF) if plungeT $\geq 50^{\circ}$. In the other cases, the earthquake is labeled with OF (other faulting styles). To investigate the role of the style of faulting (SOF), we separate the event term into a fixed offset for each SOF class and a perturbation term for each event. If we indicate with k = 1, 2, 3, 4 the classes of the SOF grouping factor (corresponding to NF, SS, TF, and OF) and with k_i the class of event *i*, the equation for the extended mixed-effects model is

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$$M_{eij} = e_1 + e_2 M_{wi} + \delta S_j + [\delta SOF_{k_i} + \delta E_{SOF_i}] + \epsilon_{ij}$$
(3)

where δSOF are the terms characterising the average effects of the the different SOFs and δE_{SOF} are accounting for inter-event differences within each SOF class (nested random effects). The standard deviations of the δS , δSOF , δE_{SOF} and ϵ distributions are $\phi_S = 0.190$, $\tau_{SOF} = 0.095 \tau = 0.236$, $\phi_0 = 0.232$, respectively, generating a total standard deviation $\sigma = 0.393$. The SOF terms are: $\delta SOF_1 = 0.098$ (NF),

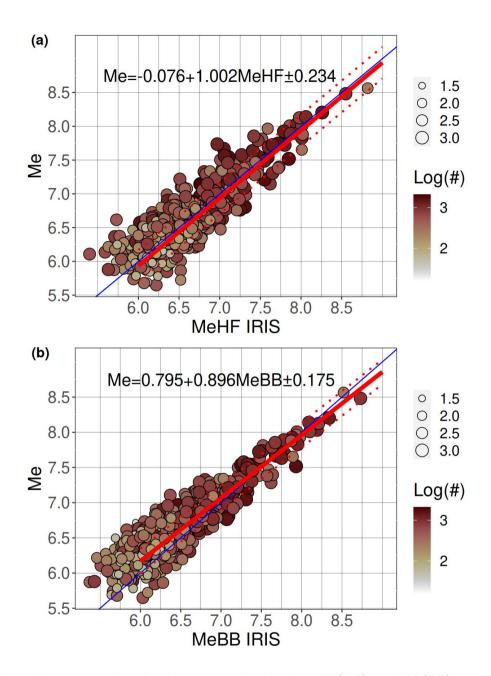


Figure 9. Comparison with energy magnitude disseminated by IRIS considering a) $M_e(HF)$ and b) $M_e(BB)$ (717 common events). The red line shows the linear regression fit, and the dotted lines show one standard deviation of the M_e residuals. The blue line shows line of equality for reference.

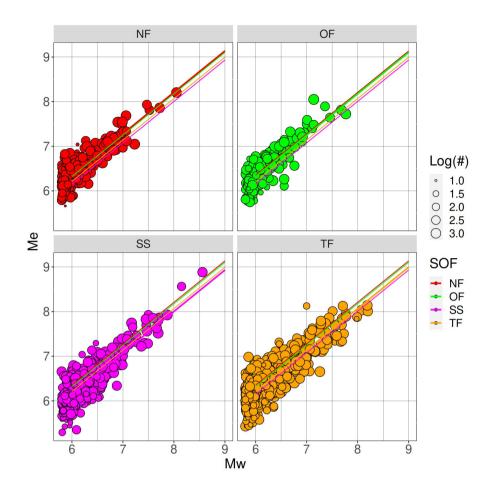


Figure 10. M_e versus Mw categorized with SOF.

- 215 $\delta SOF_2 = -0.108$ (SS), $\delta SOF_3 = -0.045$ (TF), $\delta SOF_4 = 0.055$ (OF) (Figure 10). The largest difference is between SS and NF, in total 0.206 m.u.. There is a systematic impact of the SOF on the intercept of the model but associated variability is smaller compared to the inter-event variability τ (in other words, SOF effects are statistically significant but distributions of inter-event terms separated according to faulting style are strongly overlapping).
- The SOF effects might arise due to physical differences (on average) between the different faulting types, e.g., due to systematically different stress drops, differences in the maturity of faults or typical environments (intra-plate vs interplate)that, where different faulting types occur most often, or they might be artifacts due to the fact that the DiGiacomo (Di Giacomo et al., 2008) method used here does not account for radiation pattern effects, and the teleseismic arrivals utilised here sample preferentially certain

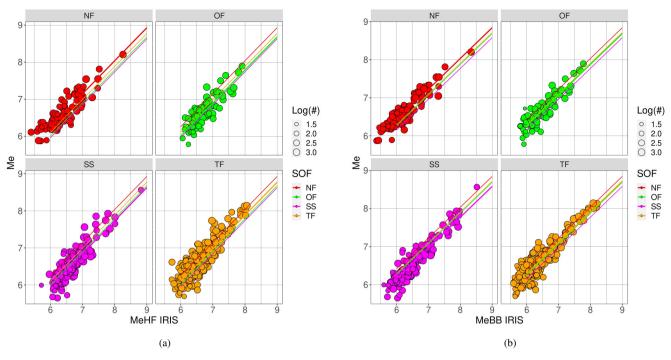


Figure 11. M_e versus $M_e(BB)$ and $M_e(HF)$, categorized with SOF.

parts of the focal sphere. Therefore, we also investigate the role of the SOF in the relationship between M_e derived in this study and the $M_e(HF)$ and $M_e(BB)$ values disseminated by IRIS. We recall that the methodology implemented by IRIS accounts for radiation pattern effects, which are related to the SOF. For this analysis, the regression model is the following

$$M_e = g_1 + g_2 M_{iris} + \delta SOF + \epsilon \tag{4}$$

where M_{iris} is either $M_e(HF)$ or $M_e(BB)$. Results shown in Figure 11 confirm that the largest intercept difference is between normal and strike-slip events, and the differences in terms of m.u. are also similar between the other SOF. This suggests that a large part of the SOF term is influenced by radiation pattern effects, and interpretations of these differences in terms of geodynamics or hazard potential should be done very cautiously. 240

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The module, derived from *me-compute* has been integrated to the SeisComP package (Helmholtz Centre Potsdam GFZ German Research Centre for Geosciences and GEMPA GmbH (2008)) and is part of the GEOFON routine real-time processing since December 2021. The first event for which M_e calculations are available and disseminated via the usual GEOFON services is https://geofon.gfz-potsdam.de/eqinfo/ event.php?id=gfz2021xxzt, that occurred on 2021-12-07 10:28:00.3 UTC, (M_e 5.7 and M_w 5.5). The *scmert* add-on is available at *https://github.com/SeisComP/scmert*.

The add-on has been configured at GEOFON to trigger the calculation for each origin created by the automatic processing with magnitude ≥ 5.5 , and to compute station magnitudes M_{eij} for all stations/channels according to the definition of M_e in the distance 20°-98°. The *scmert* procedure is applied with the settings used by the GEOFON earthquake monitoring service, using stations available in real time from the GEOFON Extended Virtual Network (https://geofon.gfz-potsdam.de/eqinfo/gevn/), including station-selection and distribution trimming of 25%. The workflow for M_e computations is as follows: as soon as an automatically detected event reaches the magnitude threshold, *scmert* is triggered and starts to compute M_{eij} upon receiving data from stations beyond 20°. The process continues until the selected window length (determined by the actual preliminary magnitude) of the last station at 98° is acquired. The first estimate of the magnitude M_e is released shortly after collecting 20 M_{eij} estimates from individual station, usually within a few minutes of the earthquake's origin time. SeisComP modules continue to refine the estimate until no further updates are required (this includes manual release at later stages). The computed station magnitudes M_{eij} are fully integrated also into the SeisComP Origin Locator View Graphical

255 User Interface (*scolv GUI*, Figure 12) with station magnitudes and residuals displayed in a dedicated energy-magnitude tab.

The energy magnitude values from both modules are compared in Figure 13. We used *scmert* with the same settings as the GEOFON earthquake monitoring service, including station selection and trimming of the distributions. The values are in good agreement, and the best fit model is $M_e = 0.057 + 0.987M_e(GEO)$ with a standard deviation of 0.118. The average difference computed for magnitudes between 6 and 8 is -0.028.

All values for M_e that have been calculated since the start of the routine processing with *scmert* can be accessed via the fdsnws-event web service running at GEOFON by specifying Me as magnitude type (i.e.,

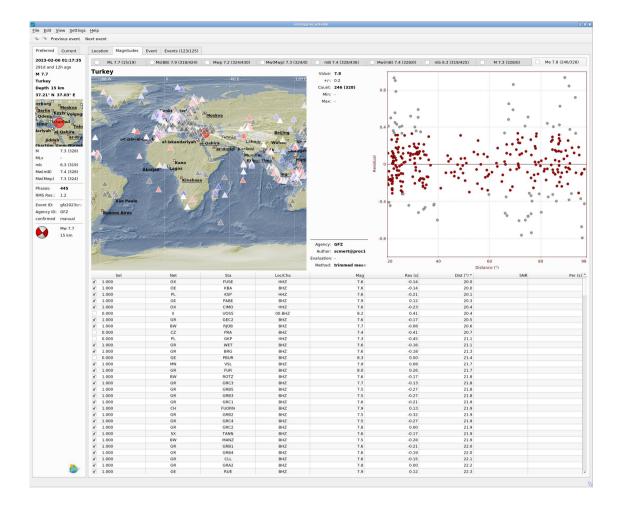


Figure 12. Screenshot of the SeisComP Origin Locator View (*scolv*) interactive tool to the Mw 7.7 Turkey earthquake, that occurred on February 6, 2023, 01:17 UTC along the East Anatolian fault. The obtained network magnitude value of M_e is 7.8. Stations used are color coded according to Me magnitude residuals (top left frame), in gray stations excluded from the network magnitude not matching the distance range definition or trimmed while computing the average magnitude because within the +/- 12.5%. The top right scatter plot shows M_e residuals by distance (in red those that contributed to actual M_e network magnitude). The topography shown in the map is generated using the ETOPO1 global relief model (?).

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https://geofon.gfz-potsdam.de/fdsnws/event/1/query?starttime=2021-12-07&magnitudetype=Me& includeallmagnitudes=true&nodata=404). These values are also disseminated to other agencies (e.g. ISC, EMSC) via the usual downstream channels, including real-time push service.

6 Conclusive remarks

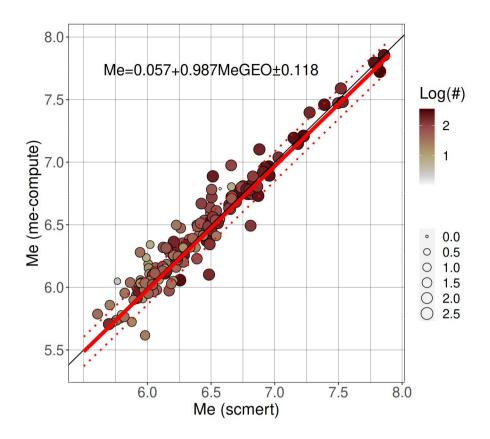


Figure 13. Comparison between M_e computed in real-time by GEOFON with *scmert* add-on for SeiscomP (x-axis) and off-line estimation using *me-compute* (y-axis), considering 153 common events.

We computed the energy magnitude M_e for 6349 events in the moment magnitude catalog disseminated by Geofon. When combined with M_w , M_e allows for a better characterization of the tsunami and shaking potential of an earthquake. The procedure used to compile the data set, which includes 1031396 M_e values for each recording station, is described in detail. Residuals are evaluated using a mixed-effects regression, which partitions the overall residuals into event-specific and station-specific contributions. These random effects are included in the distributed catalog, enabling the computation of M_e for future events using inter-station residuals as station corrections to reduce the uncertainty on M_e . They also enable the assessment of energy magnitude adjustments for specific regions or faulting mechanisms by using inter-event residuals, and locating propagation anomalies with respect to the global model used to compute Green's functions using the left-over residuals. The methodology employed for computing Me (Di Giacomo et al., 2008) is suitable for the rapid assessment of Me (Di Giacomo et al., 2010). Therefore, it has been implemented as a module for SeiscomP, allowing for the automatic computation of M_e in real-time and keeping the M_e catalog up-to-date.

7 Code and data availability

Code used for computing the energy magnitude is available at:

- off-line computations: me-compute https://doi.org/10.5880/GFZ.2.6.2023.008
- real-time computations in SeiscomP: scmert https://github.com/SeisComP/scmert
- Analyses have been performed in R (R Core Team (2020)) and we used the Generic Mapping Tools (Wessel et al. (2013)) to produce Figures 2, 5, 6, and 7. The archive including the energy magnitude catalogue (D3 and D6 in Table 1) and example of configuration files is available at: Bindi et al. (2023), https://doi.org/10.5880/GFZ.2.6.2023.010.

Author contributions. D.B., A.S. and D.DG. conceptualized the study; R.Z. developed the python code used to compile the disseminated
 catalogue; A.H. developed the addon for SeiscomP; D.B. developed the quality checks; P.E., A. H. and A. S. organized the publication of *M_e* by GEOFON via web-services; all authors participated to the finalization of the article.

Competing interests. The authors declare no competing interests.

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