



1 A Global Forest Burn Severity Dataset from Landsat Imagery 2 (2003–2016)

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8

9 **Abstract:** Forest fires, while destructive and dangerous, are important to the functioning and renewal of ecosystems.
10 Over the past two decades, large-scale, severe forest fires have become more frequent globally, and the risk is expected
11 to increase as fire weather and drought conditions intensify. To improve quantification of the intensity and extent of
12 forest fire damage, we have developed a Global Forest Burn Severity (GFBS) database of information on the amounts
13 of biomass that were consumed by fire between 2003 and 2016. To build it, we used the Fire Atlas product to determine
14 when and where forest fires occurred during that period and then overlaid the available Landsat surface reflectance
15 products to obtain pre-fire and post-fire normalized burn ratios (NBRs) for each burned pixel, designating the
16 difference between them as dNBR and the relative difference as RdNBR. Using the CONUS-wide Composite Burn
17 Index (CBI) as a ground truth, we evaluated the performance of GFBS relative to the performance of the existing
18 MODIS-based global burn severity dataset (MOSEV). The results showed that dNBR of GFBS was more strongly
19 correlated with CBI ($R^2 = 0.4$) than dNBR of MOSEV ($R^2 = 0.08$). RdNBR of GFBS also exhibited better agreement
20 with CBI ($R^2 = 0.31$) than RdNBR of MOSEV ($R^2 = 0.04$). At global scale, while the dNBR and RdNBR spatial
21 patterns extracted by GFBS were similar to those of MOSEV, MOSEV tended to provide higher burn severity levels
22 than GFBS. We attribute this difference to variations in reflectance values and the different spatial resolutions of the
23 two satellites.

24

25 1. Introduction

26 In recent years, many regions around the world have experienced an increase in the frequency, intensity, and extent
27 of wildfires (Doerr and Santín, 2016; Shukla et al., 2019; Dupuy et al., 2020). Wildfires are now among the most
28 popular research topics as a result of this rising global concern, which is further heightened by changes expected in
29 fire regimes as a consequence of changes in climate and land use (Moreira et al., 2020). While most wildfires occur
30 in grasslands and savannas (Scholes and Archer, 1997; Abreu et al., 2017), forest fires are more dangerous and
31 destructive and perhaps of greater interest because of their importance to the functioning and renewal of ecosystems
32 (Flannigan et al., 2000; Nasi et al., 2002; Flannigan et al., 2006). Changes brought by the warming climate, which has



33 dried fuels and lengthened fire seasons across the globe (Jolly et al., 2015), are also particularly significant to forested
34 ecosystems with abundant fuels (Kasischke and Turetsky, 2006; Aragão et al., 2018).

35 With the rapid development of remote sensing techniques, more frequent observations from satellites
36 facilitate the monitoring of global fire activities. The valuable information they provide at fine spatial and temporal
37 resolutions can be used to study the number and size distributions of individual fires (Archibald and Roy, 2009;
38 Hantson et al., 2015; Oom et al., 2016), fire shapes (Nogueira et al., 2016; Laurent et al., 2018), and locations of
39 ignition points (Benali et al., 2016; Fusco et al., 2016). Among the most widely accepted techniques are those based
40 on the Moderate Resolution Imaging Spectrometer (MODIS) (Chuvieco et al., 2016), which retrieves information on
41 the entire Earth in 36 spectral bands every one to two days. The MODIS-derived burn area (BA) products are essential
42 for ascertaining the patterns of fire occurrence, extent, propagation (Rodrigues and Febrer, 2018), and frequency
43 (Andela et al., 2019). Based on these products, an essential indicator called “burn severity” has been derived for
44 determining the degree of biomass consumption and the overall impact of fire on ecosystems (Keeley, 2009).

45 Traditionally, burn severity could be quantified from satellite sensors through spectrum information. The
46 changes caused by fire to near-infrared (NIR) and shortwave infrared (SWIR) reflectance are highly sensitive to,
47 respectively, canopy density and moisture content (Chuvieco, 2010). Several burn severity datasets based on this
48 method have been generated and released. Regionally, the Monitoring Trends in Burn Severity (MTBS) dataset, which
49 includes burn severity assessments for the contiguous United States (CONUS) and provides information on fire
50 perimeters and severity classes, uses satellite data—specifically, Landsat imagery (Eidenshink et al., 2007). Similarly,
51 the Canadian Landsat Burn Severity (CanLaBS) product uses Landsat imagery to assess, and map burn severity at a
52 national scale (Guindon et al., 2021). Globally, MODIS burn SEVerity (MOSEV) has provided monthly burn severity
53 data with global coverage at 500m spatial resolution, based on MODIS Terra and Aqua satellites (Alonso-González
54 and Fernández-García, 2021). Despite the satellite those datasets used and the target those datasets for, products for
55 assessing and mapping global forest burn severity based on Landsat (30m resolution) are not yet available. Such
56 products would support advances in fire management strategies and ecosystem conservation efforts, leading to more
57 resilient and sustainable landscapes.

58 In this paper we describe a new global dataset comprising information on burn severity derived at high spatial
59 resolution from Landsat imagery from the period 2003–2016. This dataset represents a step forward in quantifying
60 and analyzing wildfire impact on forest ecosystems worldwide. We begin with a section detailing the input data and
61 the algorithm we used to process the dataset, as well as the analytical techniques employed. The next section presents
62 the characteristics of the dataset and its performance in representing the distribution of forest fires. In the results
63 section, we analyze the advantages and disadvantages of the dataset and set forth its main contributions to forest fire
64 management strategies worldwide. The last section summarizes the primary findings and suggests possible
65 implications of the dataset.

66 2. Data and Method



67 Below we delineate the specifics of data input and pre-processing and the analytical techniques we employed to create
68 the dataset. The Global Fire Atlas was the main source of global fire records, which we overlaid with annual land
69 cover types from MCD12Q1 to determine when and where forest fires occurred. We then utilized the reflectance
70 information from Landsat’s satellite archives to calculate burn severity indices for the burned forest areas. Finally, we
71 used the CONUS-wide Composite Burn Index (CBI) as a ground truth to evaluate the performance of GFBS relative
72 to that of the existing MODIS-based global burn severity dataset (MOSEV).

73 **2.1. Input data**

74 The input data we used to build the GFBS dataset comprised the fire records available in the Global Fire Atlas for the
75 years 2003–2016 and all Landsat images for the same period.

76 The Global Fire Atlas tracks the daily dynamics of individual fires globally to determine the time and location
77 of ignition, area burned, and duration, as well as daily expansion, fireline length, velocity, and direction of spread. A
78 detailed description of its underlying methodology is provided by Andela et al. (2019).

79 The Terra and Aqua combined Moderate Resolution Imaging Spectroradiometer (MODIS) Land Cover Type
80 (MCD12Q1) Version 6.1 data product provides global land cover types at yearly intervals (USGS, 2022). With its
81 global coverage and the insights, it offers into the planet’s diversity of land cover types, the MCD12Q1 dataset is
82 pivotal to various ecological and environmental studies.

83 *Landsat 5,7,8* scene is a 16-day composite image with 7, 8, 11 surface reflectance bands. With its 30m
84 resolution and global coverage, it provides a high-quality, atmospherically corrected snapshot of the Earth’s surface.
85 Use of the best available observations gathered over the 16-day period ensures the image is as clear and accurate as
86 possible, minimizing issues, such as cloud cover, that can obscure the satellite’s view.
87 (<https://developers.google.com/earth-engine/datasets/catalog/landsat>).

88 **2.2. Pre-processing**

89 To pre-process the data, we first imported individual fire polygons from the Global Fire Atlas into the Google Earth
90 Engine (GEE) and then collected the most recent Landsat images based on the tags demarcating the start and end times
91 of each individual fire. We applied a cloud- and snow-masking algorithm to remove any snow, clouds, and their
92 shadows from all imagery based on each sensor’s pixel quality assessment band. By mosaicing the masked images,
93 we created a composite with the smallest possible cloud and shadow extent (Google Earth Engine Developers, 2022).
94 (<https://developers.google.com/earth-engine/guides/landsat>).

95 **2.3. Algorithm overview**

96 We estimated the burn severity indices in two steps, as shown in Figure 1: first, we calculated the normalized burn
97 ratios (NBRs) from the mosaiced Landsat composites, and second, we selected the pre- and post-fire NBRs for each
98 burned pixel to create burn severity indices—dNBR and RdNBR—based on the differences between the NBRs.



99 In the first step, we determined the forest fire polygons using the Global Fire Atlas data associated with the
100 MCD12Q1 land cover data and then utilized reflectance information from Landsat’s satellite archives to obtain the
101 forest fire NBRs from the Landsat composites.

102 In the second step, we used the pre- and post-fire dates by the Global Fire Atlas data to obtain the
103 corresponding pre- and post-fire NBRs, which allowed us to create the burn severity indices—that is, dNBR and
104 RdNBR—based on the respective differences between them.

105 We took additional steps to validate the performance of the dataset by comparing the CBIs over CONUS
106 with those based on the MOSEV dataset. These steps are detailed in Sections 2.3.1, 2.3.2, and 2.3.3.

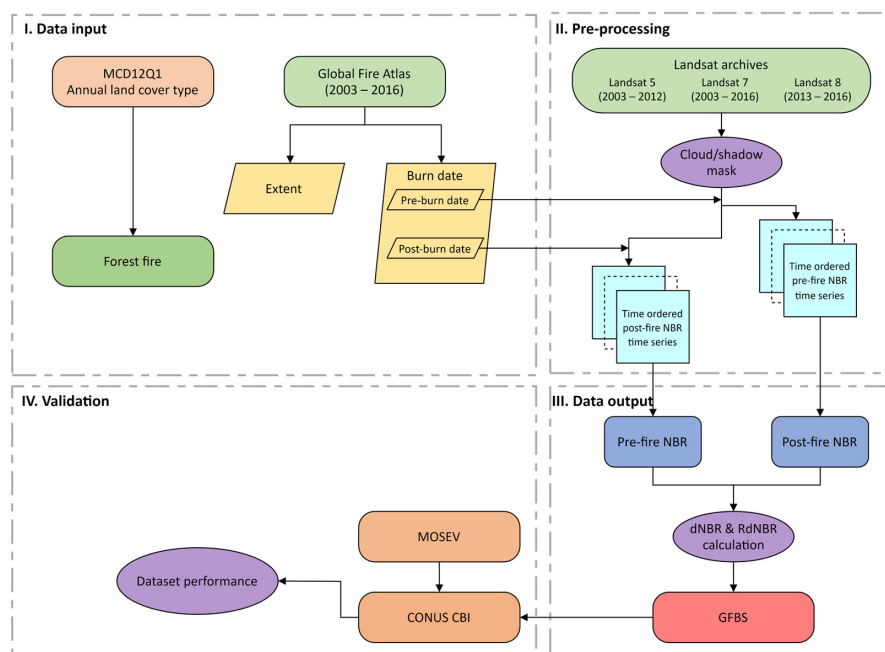


Figure 1. Methodology for building the GFBS database (2003–2016) and validation and comparison with the MOSEV benchmark.

107 2.3.1. Identification of global forest fires

108 To identify global forest fires, we first overlaid the fire polygons from the Global Fire Atlas with MCD12Q1
109 data from the corresponding year. Based on Annual International Geosphere-Biosphere Programme (IGBP) classifications
110 of land cover, we identified a forest fire polygon within each area where we found forest to be the dominant land cover
111 type within the fire extent—that is, wherever the proportion of burned pixels representing forest, including evergreen
112 needleleaf forests, evergreen broadleaf forests, deciduous needleleaf forests, deciduous broadleaf forests, and mixed
113 forests, was largest relative to the proportion of burned pixels for other land cover types, such as shrublands and
114 grasslands.



115 **2.3.2. Estimation of the normalized burn ratio (NBR)**

116 We calculated the normalized burn ratio (NBR) spectral index for each Landsat composite. according to the formula
117 in Equation 1:

$$118 \quad \text{NBR} = (\text{NIR} - \text{SWIR}) / (\text{NIR} + \text{SWIR}), \quad (1)$$

119 In Landsat series 4 through 7, we collected NIR information from Band 4 and SWIR information from Band 7. In
120 Landsat 8, we collected NIR information from Band 5 and SWIR information from Band 7.

121 **2.3.3. Estimation of dNBR and RdNBR**

122 Having obtained burn area locations and burn dates from the Fire Atlas product, we selected from the Landsat 16-day
123 time series valid pre-fire and post-fire NBR pixels that were, respectively, from the date most closely preceding the
124 start date and the date most closely following the end date of each burned polygon within a three-month time window.

125 The dNBR index, calculated according to Key and Benson (2006) as shown in equation (2), is the reference
126 burn severity spectral index used by the European Forest Fire Information System ([https://effis.jrc.ec.europa.eu/about-](https://effis.jrc.ec.europa.eu/about-effis)
127 [effis](https://effis.jrc.ec.europa.eu/about-effis)) and by the United States' Monitoring Trends in Burn Severity program (<https://www.mtbs.gov>). Larger dNBR
128 values indicate higher burn severity:

$$129 \quad \text{dNBR} = \text{preNBR} - \text{postNBR} \quad (2)$$

130 RdNBR is another burn severity spectral index that is widely used, including by the United States' Monitoring
131 Trends in Burn Severity program (<https://www.mtbs.gov/>, last access:1 May 2021). As formulated in equation (3)
132 (Miller and Thode, 2007), higher RdNBR values indicate higher burn severity:

$$133 \quad \text{RdNBR} = \text{dNBR} / \sqrt{|\text{preNBR}|} \quad (3)$$

134 **2.4. Validation**

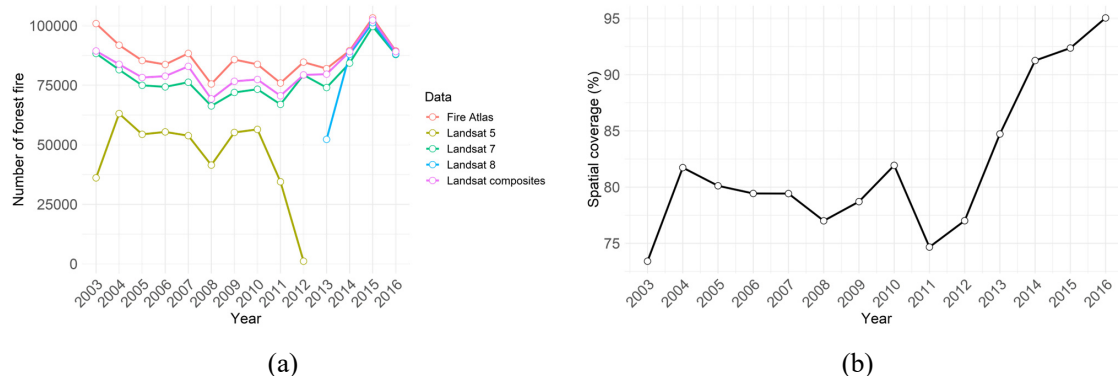
135 To validate the GFBS database developed in this study, we used the ground-measured CONUS-wide Composite Burn
136 Index from 2003 to 2016. CBI was developed by Key and Benson (2006) to assess the aboveground effects of fire on
137 vegetation and soil land use types (i.e., burn severity). The index ranges continuously from 0.0 (unburned) to 3.0 (high
138 severity). These values can be compared to satellite-derived burn severity data to develop regression equations
139 (<https://burnseverity.cr.usgs.gov/products/cbi>). In this study, we used all available CBI values over CONUS to
140 establish the regression relationship between CBI and the dNBR and RdNBR values of the GFBS database. We applied
141 the coefficient of determination to evaluate the performance of GFBS relative to the corresponding performance of
142 the MOSEV database, which is currently used to evaluate global burn severity.



143 3. Results

144 3.1. Landsat mosaiced composites

145 Figure 2 (a) shows the number of forest fire polygons globally between 2003 and 2016, representing individual fire
146 events, from the Global Fire Atlas dataset. Approximately 80,000 forest fire events occur in the world each year on
147 average, with more than 90,000 happening in 2004 and more than 100,000 in 2003 and 2015, respectively. Figure 2
148 (a) also displays the availability of Landsat imagery covering the burn area where individual forest fires happened
149 worldwide. From 2003 to 2012, Landsat 5 could provide images covering only 35% to 68% of the recorded forest fire
150 events in the Global Fire Atlas, while Landsat 7 images could cover 83% to 93%. From 2013 to 2016, Landsat 7
151 images covered about 90% to 98% of the fire events, while Landsat 8 images covered more than 97%. The Landsat
152 composites combining all available Landsat 5 and Landsat 7 images from 2003 to 2012 and Landsat 7 and Landsat 8
153 images from 2013 to 2016 significantly increased the number of forest fires shown by Landsat images, with coverage
154 of the fire events ranging from 88% to 99%. Figure 2 (b) shows the distribution of the spatial coverage of cloud-free
155 Landsat composites for individual fires from the Fire Atlas. We used a cloud and shadow removal algorithm to
156 eliminate invalid poor-quality pixels from recorded forest fires, resulting in a line chart showing the distribution of
157 the percentages of valid pixels to the total burn pixels in each year. Overall, the spatial coverage was above 72%, and
158 the coverage has been above 85% since 2013, when Landsat 8 was launched.



159
160 **Figure 2. (a) Numbers of individual fires from the Fire Atlas and available Landsat imagery; (b) Spatial coverage of**
161 **cloud-free Landsat composites for individual fires from the Fire Atlas.**

160 3.2. Validation against CBI

161 Figure 3 shows the spatial locations of available CBIs over CONUS from 2003 to 2016. Of the 1,315 ground-surveyed
162 CBI reports for forest fires during that time, most came from western states, such as Arizona, Colorado, and Oregon,
163 where forest fires are more frequent and severe. Fewer CBI records are available in eastern states, such as Florida and
164 Georgia.

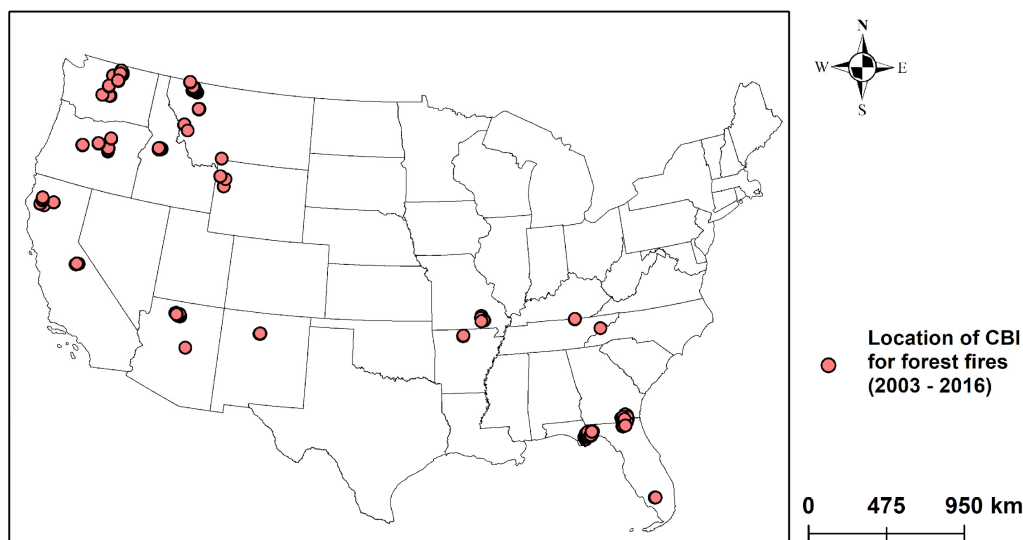
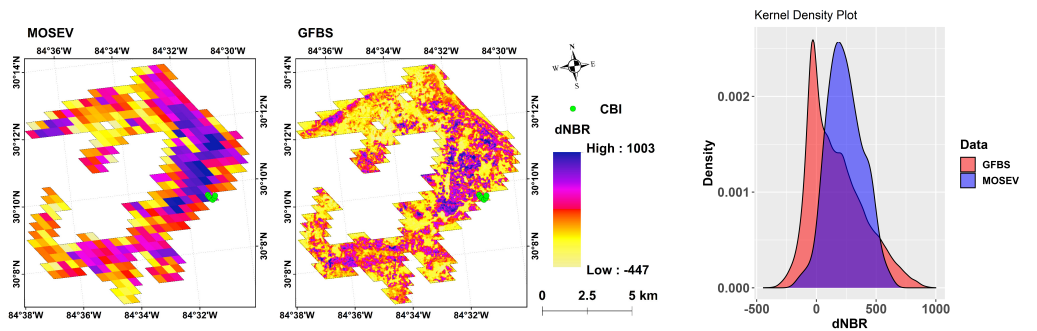


Figure 3. Spatial locations of forest fire CBIs over CONUS.

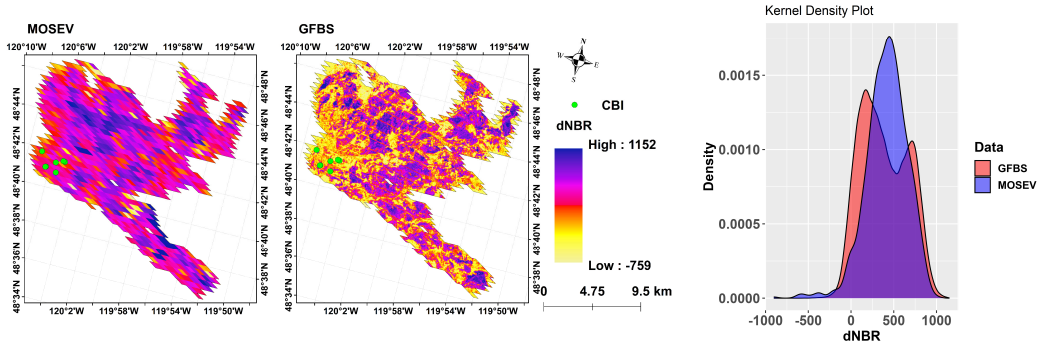
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166 Figure 4 (a), (b), (c) and (d) shows the spatial patterns of dNBR over CONUS for the forest fires with the
167 largest burn areas (referred to as annual maximum forest fire hereafter) in 2004, 2006, 2007, and 2013 respectively
168 for which CBI records are available. The figures present the associated probability density functions (PDFs) of dNBR
169 values from GFBS and MOSEV, along with spatial distribution maps of dNBR. The similarity in spatial patterns
170 between GFBS burn severity and MOSEV burn severity is obvious. Significant differences occur, however, between
171 GFBS dNBR and MOSEV dNBR. We found that, when we relied on MODIS products, MOSEV dNBR tended to
172 underestimate the high severity and overestimate the low severity of the annual maximum forest fire in 2004,
173 compared with GFBS dNBR. This could also be inferred from the PDFs, where MOSEV dNBR distributed more on
174 the mean value of dNBR around 300, while GFBS dNBR distributed more on the extreme low and high values. For
175 the annual maximum forest fire in 2007, especially, MOSEV dNBR greatly overestimated the severity levels compared
176 to GFBS dNBR, a difference that was also reflected in the large deviation of mean dNBR values in the PDFs of dNBR
177 for the GFBS and MOSEV datasets.

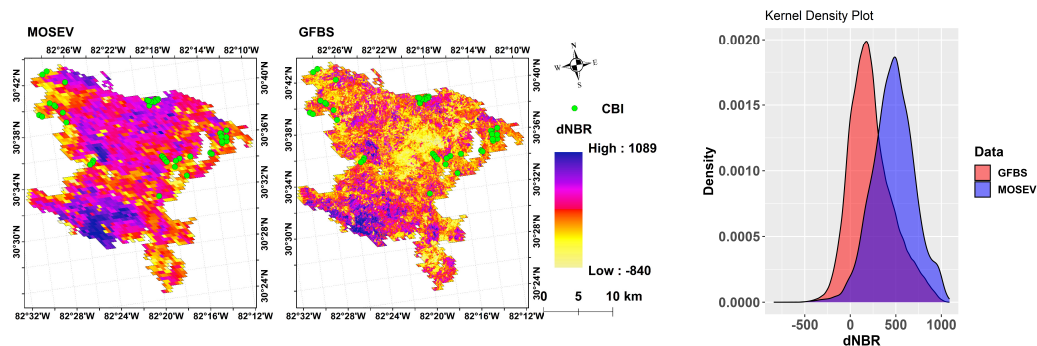
178 The density plot of dNBR in Figure 4 also clearly shows two peaks for GFBS dNBR, at around 100 (low
179 severity) and 700 (high severity), for the annual maximum forest fire in 2006. MOSEV dNBR shows a single peak at
180 around 500, indicating that MOSEV dNBR underestimated high severity while overestimating low severity, compared
181 with GFBS dNBR. For the annual maximum forest fire in 2013, although the density plot presents two peaks for both
182 GFBS and MOSEV dNBR, the corresponding dNBR values where the peaks are located differ. For GFBS dNBR, the
183 two peaks are around 0 and 900, representing the low and high severity, respectively, while for MOSEV dNBR they
184 are around 400 and 600.



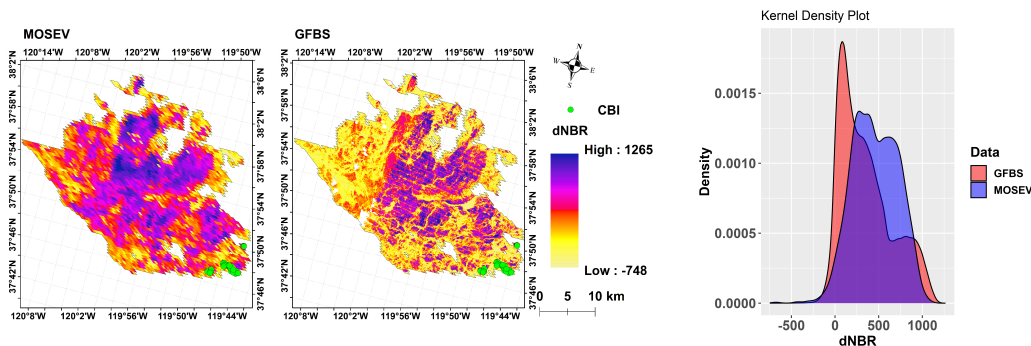
(a)



(b)



(c)

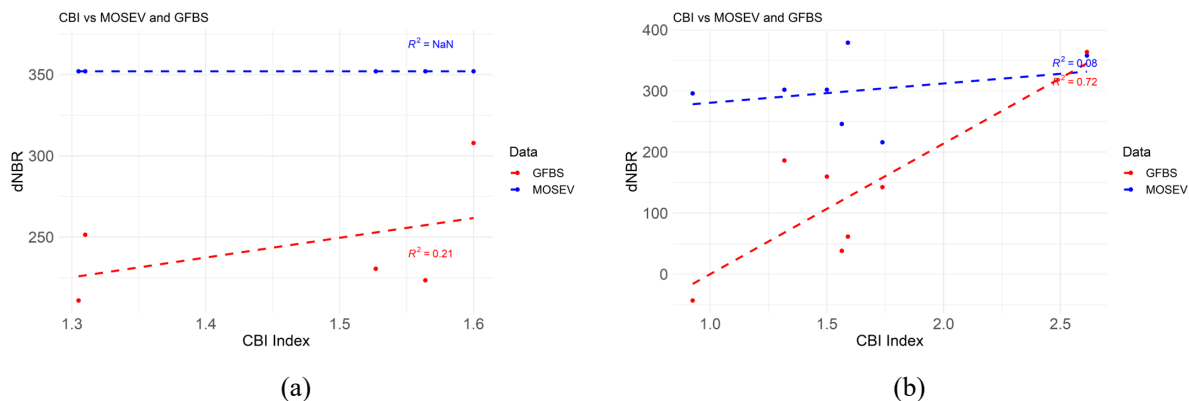


(d)

Figure 4. Spatial patterns of dNBRs for annual maximum fires over CONUS with distribution of probability density functions in (a) 2004, (b) 2006, (c) 2007, and (d) 2013, derived from the GFBS and MOSEV datasets.

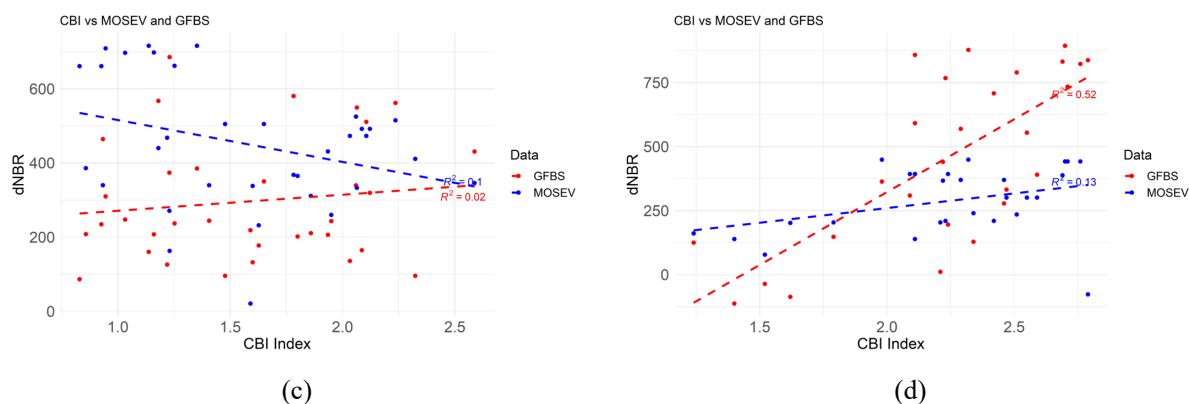
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186 Figure 5, panels (a), (b), (c), and (d), present the scatterplots of CBI against GFBS dNBR and MOSEV dNBR for the
 187 annual maximum forest fires in 2004, 2006, 2007, and 2013, respectively. For the annual maximum forest fire in 2004,
 188 the figure clearly shows a positive correlation with CBI ($R^2 = 0.21$) for GFBS dNBR, while we found no correlation
 189 for MOSEV dNBR. For the annual maximum forest fire in 2006, we found good agreement with the CBI for GFBS
 190 dNBR, with an R^2 value of 0.72, while the R^2 value was only 0.08 for MOSEV dNBR. Although correlation with CBI
 191 was poor for both GFBS and MOSEV dNBR for the annual maximum forest fire in 2007, the former still showed a
 192 positive trend to CBI, while the relationship for the latter was negative. For the annual maximum forest fire in 2013,
 193 GFBS dNBR ($R^2 = 0.52$) was more strongly correlated with CBI than MOSEV dNBR ($R^2 = 0.13$).



(a)

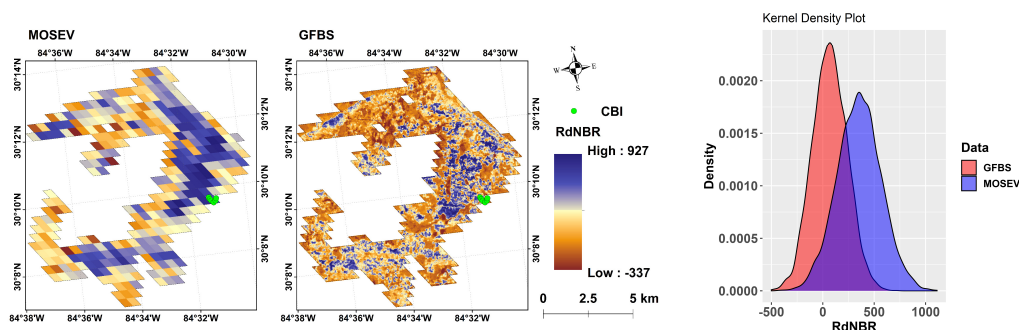
(b)



194 **Figure 5. Scatterplots of CBI against dNBR of GFBS and MOSEV for annual maximum fires in (a) 2004, (b)**
 195 **2006, (c) 2007, and (d) 2013.**

196

197 Figure 6 (a), (b), (c) and (d) shows the spatial patterns of RdNBR for the forest fires over CONUS with the largest
 198 burn areas (referred to as annual maximum forest fire hereafter) in 2004, 2006, 2007, and 2013 respectively for which
 199 recorded CBIs are available. Like Figure 4, Figure 6 displays the spatial distribution maps of RdNBR from GFBS and
 200 MOSEV, along with the associated probability density functions (PDFs) of RdNBR values. The figure exhibits similar
 201 spatial patterns for GFBS and MOSEV dataset, but the burn severity level in terms of RdNBR differed. RdNBR for
 202 MOSEV data tended to be higher than for GFBS dNBR, which can be clearly seen in the density plots of GFBS and
 203 MOSEV RdNBRs that the mean RdNBR in the distribution of MOSEV is obviously larger than the mean RdNBR in
 204 the distribution of GFBS, for the annual maximum forest fires in 2003, 2006 and 2007. The density plots of GFBS
 205 and MOSEV RdNBR for the annual maximum forest fire in 2013 are largely overlapped, but MOSEV RdNBR
 206 distributes more on the mean values around 800 than GFBS RdNBR, while GFBS RdNBR distributes more on the
 207 extreme low and high values. These findings demonstrate that MOSEV RdNBR represents higher burn severity levels
 208 than GFBS RdNBR.



(a)

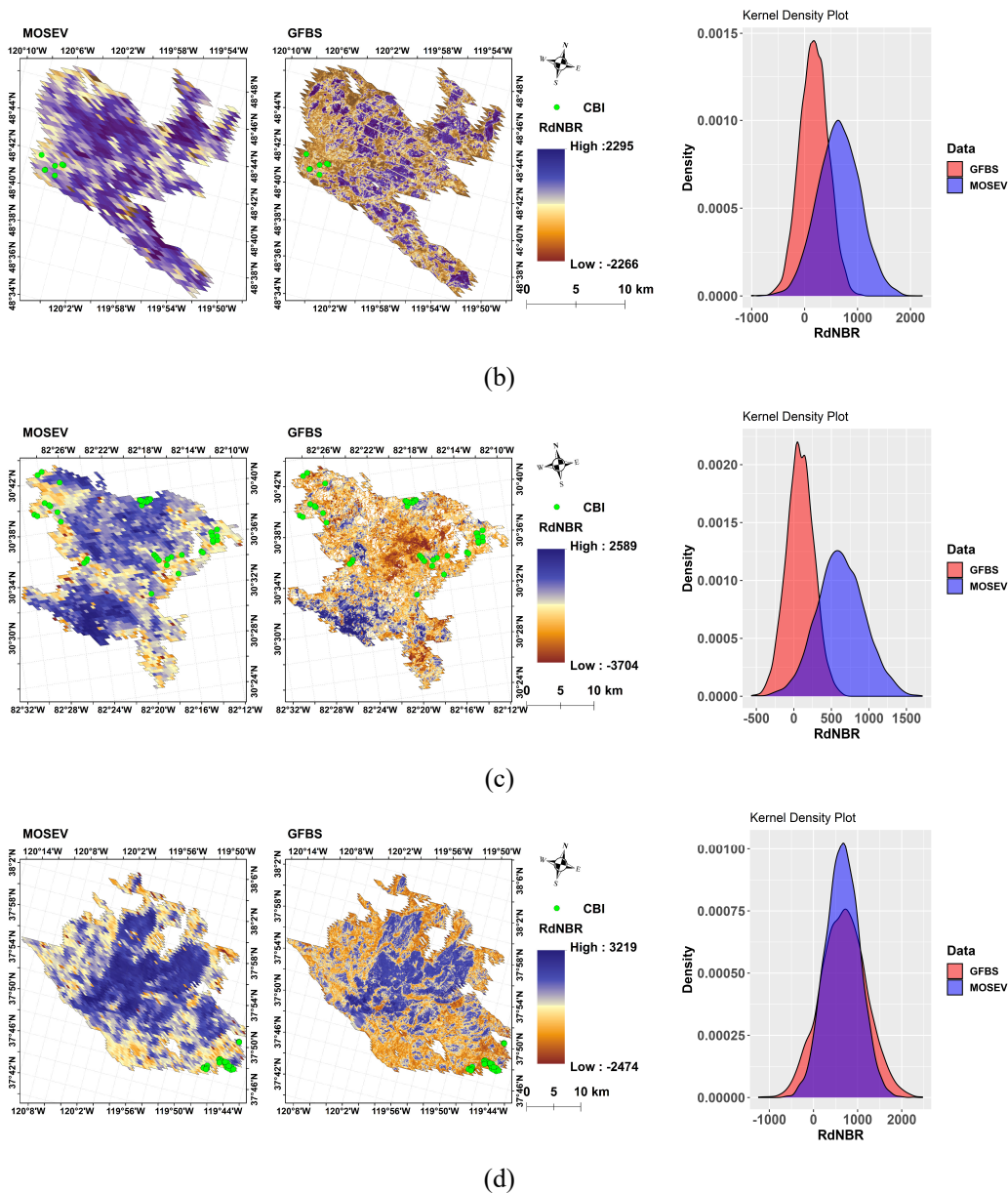


Figure 6. Spatial patterns of RdNBRs for annual maximum fires over CONUS with distribution of probability density functions in (a) 2004, (b) 2006, (c) 2007, and (d) 2013, derived from the GFBS and MOSEV datasets.

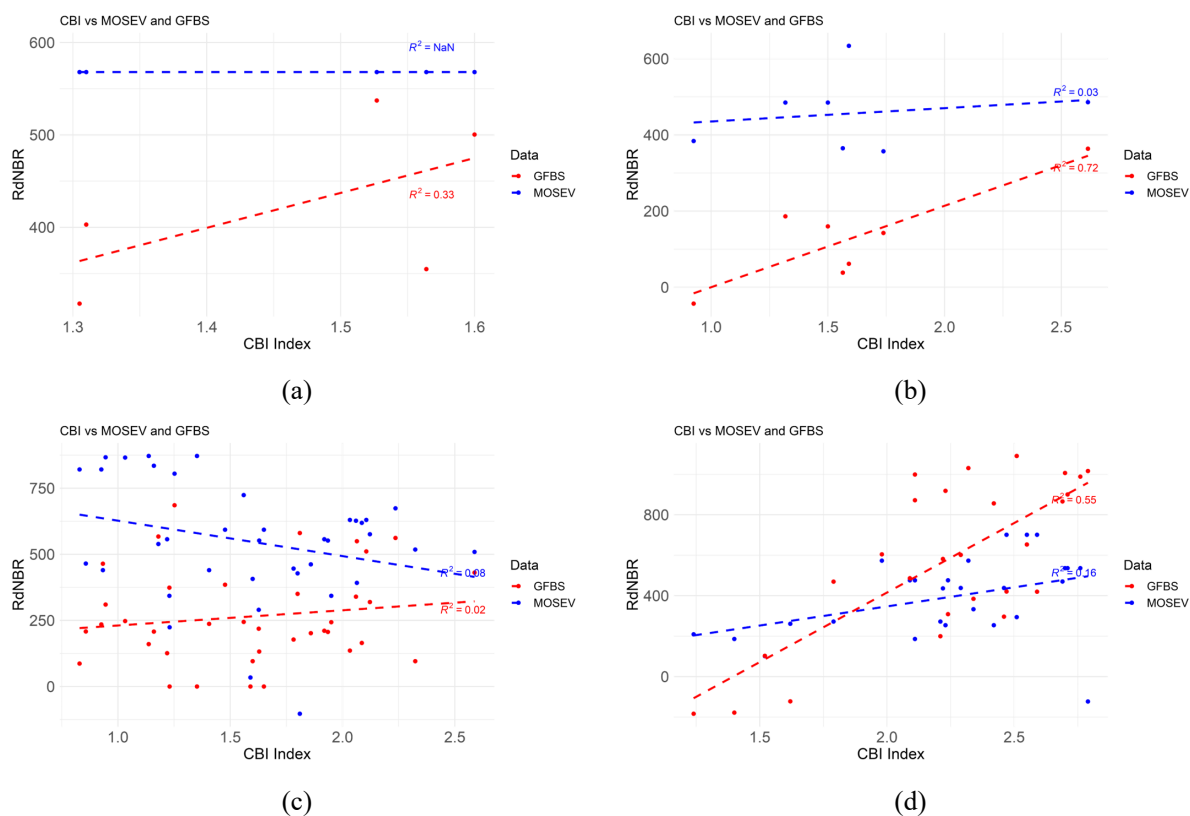
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210 Figure 7, panels (a), (b), (c), and (d), present the scatterplots of CBI against GFBS RdNBR and MOSEV
 211 RdNBR for the annual maximum forest fires in 2004, 2006, 2007, and 2013, respectively. For the annual maximum



212 forest fire in 2004, the figure shows a positive correlation with CBI ($R^2 = 0.33$) for GFBS dNBR, while we found no
 213 correlation for MOSEV dNBR. For the annual maximum forest fire in 2006, we found good agreement with the CBI
 214 for GFBS dNBR with an R^2 value of 0.72, while the R^2 value was only 0.03 for MOSEV dNBR. Although correlation
 215 with CBI was poor for both GFBS and MOSEV dNBR for the annual maximum forest fire in 2007, the former still
 216 showed a positive trend to CBI, while the relationship for the latter was negative. For the annual maximum forest fire
 217 in 2013, GFBS dNBR ($R^2 = 0.55$) was more strongly correlated with CBI than MOSEV dNBR ($R^2 = 0.16$).

218



219 **Figure 7. Scatterplots of CBI against RdNBR of GFBS and MOSEV for annual maximum fires in (a) 2004, (b)**
 220 **2006, (c) 2007, and (d) 2013.**

221

222 Figure 8 (a) and (b) shows the scatterplots of CBI against GFBS dNBR and MOSEV dNBR, respectively,
 223 for all forest fires from 2003 to 2016 over CONUS. Considering all forest fires, we found GFBS dNBR more strongly
 224 correlated with CBI ($R^2 = 0.4$) than MOSEV dNBR ($R^2 = 0.08$). As for RdNBR, Figure 8 (c) and (d) show the



225 scatterplots of CBI against GFBS RdNBR and MOSEV RdNBR, respectively, GFBS still performed better than
226 MOSEV when regressed with CBI with an R^2 of 0.31, which was larger than that of MOSEV RdNBR (0.04).

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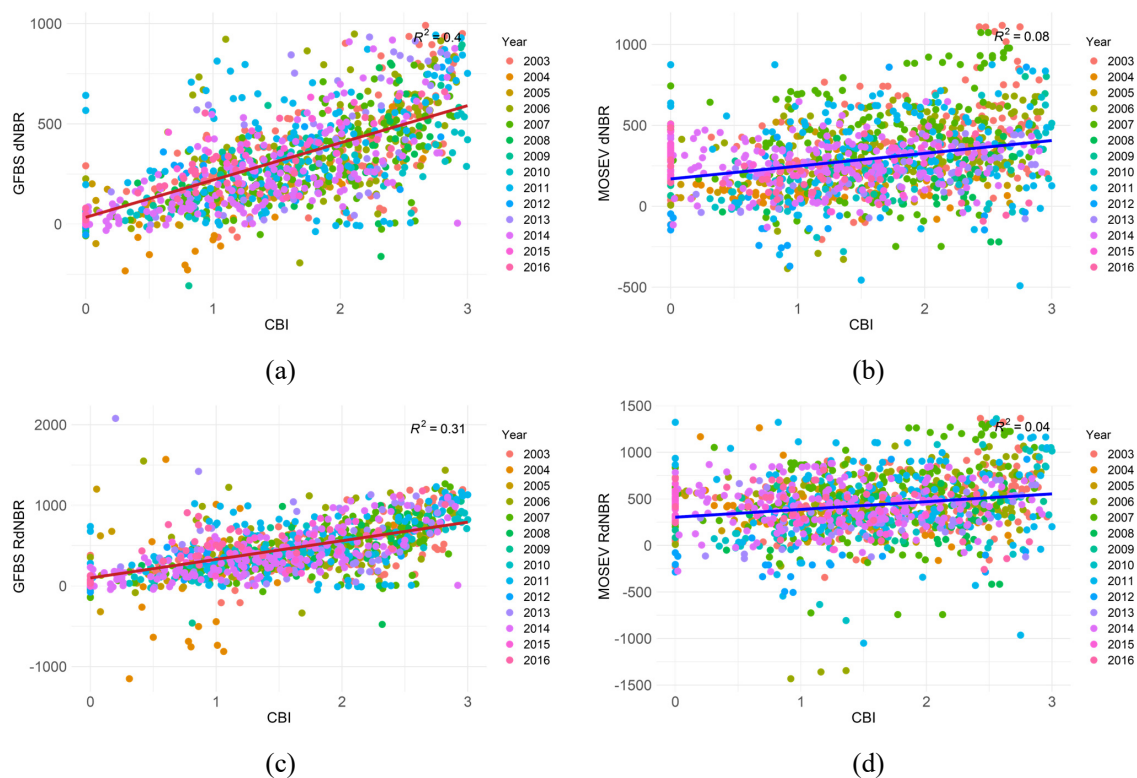


Figure 8. Scatterplots of CBI against (a) dNBR of GFBS, (b) dNBR of MOSEV, (c) RdNBR of GFBS, and (d) RdNBR of MOSEV for all forest fires from 2003 to 2016 over CONUS.

228

229 3.3. Comparison of GFBS and MOSEV globally

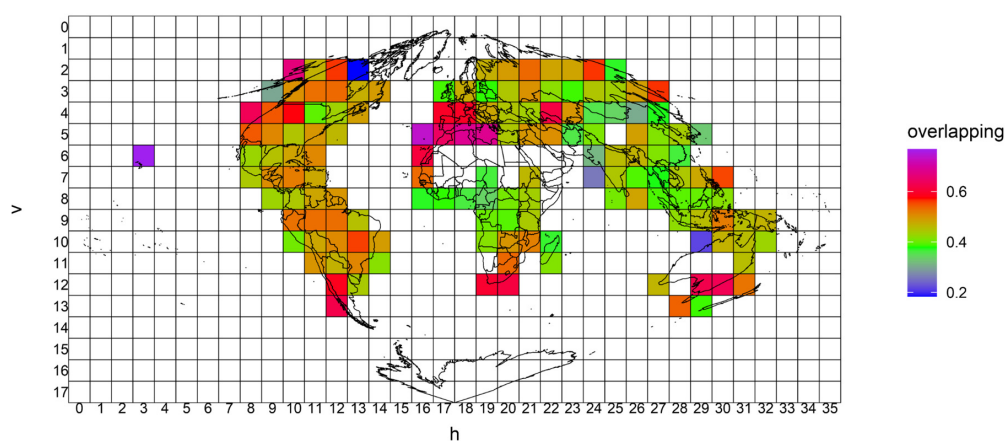
230 Figure 9 (a) displays the global spatial distributions of the areas of overlap between the density plots of GFBS dNBR
231 and MOSEV dNBR, which is defined as the area intersected by two probability density functions presented in Figure
232 4 and Figure 6. The overlapping areas in density plots typically represent the percentage of common values between
233 the distributions of two datasets, which ranges from 0 to 1 with the larger value indicating the two distributions are
234 more likely come from the same distribution. As the figure shows, we found the overlap over most of the world to be
235 above 0.4, indicating a close similarity of 40% between the burn severity information provided, respectively, by GFBS



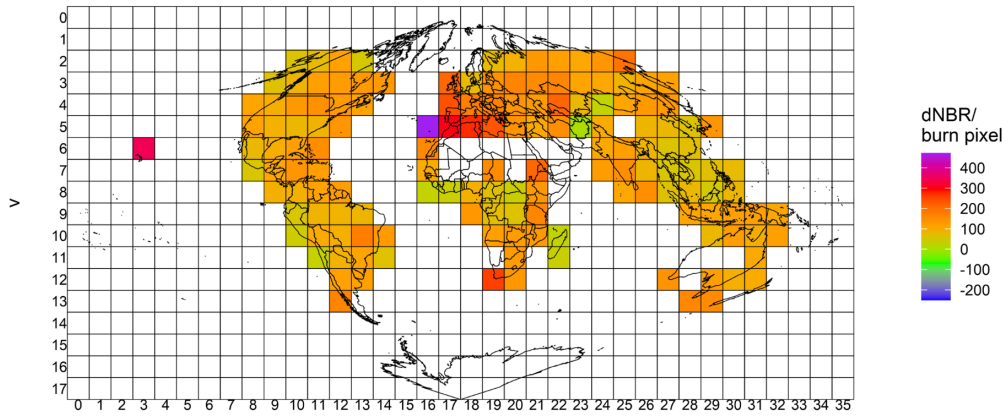
236 and MOSEV in these regions. For some regions, like South America, Western Europe, and southeast Australia, the
237 overlap was above 0.6.

238 In Figure 9 (b), which shows the global distribution of the mean dNBR for each burn pixel derived from
239 GFBS, it is obvious that we found the global spatial heterogeneity of burn severity to be small, with dNBR values
240 around 100 and 200. The exception was Western Europe, where dNBR was above 300. The global distribution of the
241 mean dNBR for each burn pixel derived from MOSEV, as shown in Figure 9 (c), however, indicated a large spatial
242 variability in burn severity. The MOSEV dataset, for example, indicated that the forest fires in north CONUS and
243 Canada should have the average dNBR value above 300, while in the GFBS dataset the average dNBR value was
244 around 100 to 200. The MOSEV dataset also indicated the average dNBR values for forest fires in South Africa and
245 China should be close to or below 0, while in the GFBS dataset they were around 100 to 200.

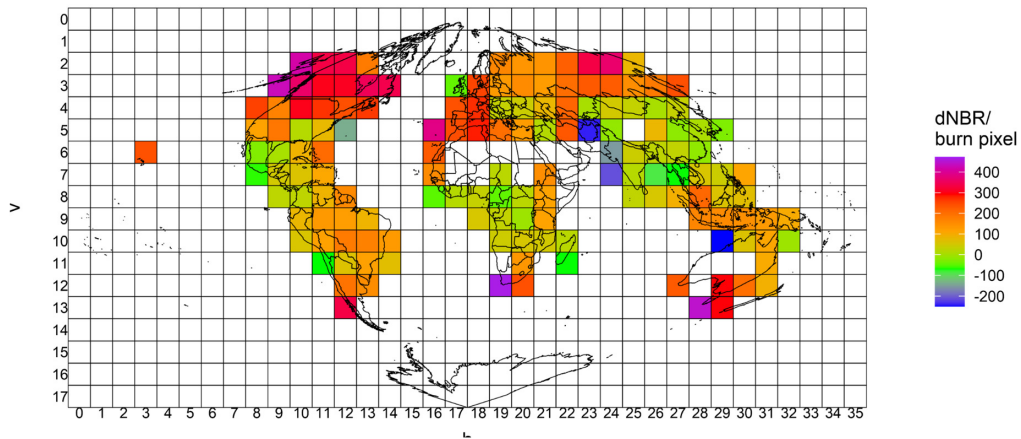
246 Figure 9 (d) presents a more detailed comparison between the GFBS dNBR and MOSEV dNBR globally,
247 showing the difference in the mean dNBR for each burn pixel, as calculated by MOSEV dNBR minus GFBS dNBR.
248 Globally, MOSEV data indicated higher forest burn severity over CONUS and Canada as well as southeast Australia
249 than shown by GFBS data. MOSEV data presented lower forest burn severity over Mexico, South Africa, Europe,
250 China, and Southeast Asia. These findings revealed that the forest burn severity information provided by GFBS might
251 be less under- or overestimated than that provided by MOSEV for some fire-prone areas, such as CONUS, as validated
252 in this study. The finding could also be applicable to other regions, including Canada, South Africa, and Australia.
253 This improved accuracy over MOSEV data would support advances in decision making in fire management strategies
254 and ecosystem conservation efforts.



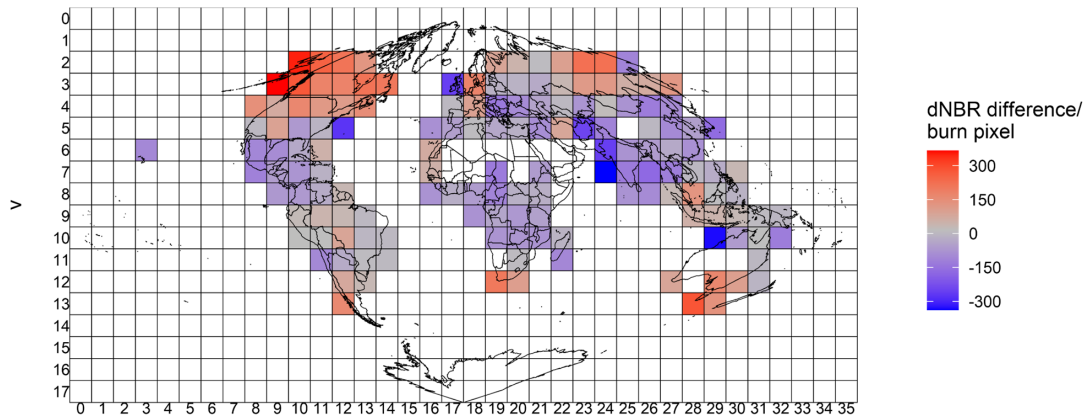
(a)



(b)



(c)



(d)



Figure 9. Global spatial distributions of (a) overlapping areas between the density plots of GFBS dNBR and MOSEV dNBR, (b) the mean dNBR per burn pixel from GFBS, (c) the mean dNBR per burn pixel from MOSEV, and (d) the differences in the mean dNBR per burn pixel between MOSEV and GFBS (MOSEV – GFBS).

255

256 4. Discussion

257 Our GFBS dataset is the first to provide fine spatial resolution (30m) burn severity information for global forest fires
258 from 2003 to 2016. As suggested by the validation against the CBI ground reference, GFBS can capture more spatial
259 variability and provide higher performance than the MOSEV dataset. In addition, GFBS is shown to have less over-
260 or underestimation than MOSEV for some fire-prone areas, like CONUS, Canada, South Africa, and Australia, which
261 could support advances in decision making in fire management strategies and ecosystem conservation efforts.

262 The difference in the performance of GFBS and MOSEV with respect to burn severity can be attributed to
263 two sources. The first is the spatial resolution. We based GFBS on Landsat (5, 7, and 8) images with a resolution of
264 30 meters, while MOSEV is based on MODIS Terra MOD09A1 and Aqua MYD09A1 images with a resolution of
265 500 meters. GFBS dNBR varies from 210 to 310, showing a better correlation with CBI than MOSEV. The coarse
266 resolution of MOSEV could also make it more difficult to capture extreme values, as we found to be the case for the
267 annual maximum forest fires in 2006 over CONUS. GFBS dNBR clearly showed two peaks in the density plot of
268 dNBR at around 100 and 700, representing the low and high severity, respectively. MOSEV dNBR, however, showed
269 only a single peak at around 500, indicating that the extreme low/high values in the 30m grid were averaged in the
270 500m grid.

271 The difference in the performances of the two data sets was related to spectrum reflectance information. The
272 NBR is commonly calculated using near-infrared (NIR) and shortwave infrared (SWIR) bands. In MOSEV, the bands
273 used to calculate NBR are NIR: Band 2 (Range: 0.841–0.876 μm) and SWIR: Band 7 (Range: 2.105–2.155 μm). In
274 GFBS, they are Landsat 5 Band 4 (Range: 0.76–0.90 μm) and SWIR: Band 7 (Range: 2.08–2.35 μm); Landsat 7 Band
275 4 (Range: 0.77–0.90 μm) and SWIR: Band 7 (Range: 2.09–2.35 μm); and Landsat 8 Band 5 (Range: 0.85–0.88 μm)
276 and SWIR: Band 7 (Range: 2.11–2.29 μm). While MODIS and Landsat 8 are close in NIR and SWIR band
277 information, Landsat 5 and 7 both have wider spectrums in NIR and SWIR than MODIS.

278 One limitation of the GFBS database is related to the relatively long revisit period of Landsat satellites (16
279 days). This low temporal resolution may impede us from obtaining the dense cloud-free NBR time series that can be
280 indispensable to calculating burn severity indices in regions of persistent cloud cover. This study has shown, however,
281 that using and combining all available Landsat images, including those from Landsat 5, 7, and 8, could significantly
282 improve the probability of obtaining dense cloud-free NBR time series. With the launch of Landsat 9 in September
283 2021 and other satellites like Sentinel-2 (in June 2015, with a five-day revisit period), it is highly possible that we
284 could build a denser cloud-free NBR time series to calculate burn severity.



285 A second limitation of GFBS is that it uses different band information varies in spectrum range from Landsat
286 5, 7, and 8, which might cause data quality to differ across years, while MOSEV uses the same bands in all years,
287 showing better data consistency.

288 5. Conclusion

289 We have introduced a newly developed GFBS database, which provides forest burn severity information with global
290 coverage for the period 2003–2016. We identified global forest fires by overlaying the Global Fire Atlas data with the
291 annual land cover data, MCD12Q1, and proposed an automated algorithm for calculating the severity of these fires.
292 The algorithm used the band information from Landsat 5, 7, and 8 surface reflectance imagery to compute the most
293 used burn severity spectral indices (dNBR and RdNBR) with a 30m spatial resolution and provide the output as the
294 GFBS dataset. The validation results over CONUS showed dNBR of GFBS more strongly correlated with CBI ($R^2 =$
295 0.4) than dNBR of MOSEV ($R^2 = 0.08$). RdNBR of GFSS also showed better agreement with CBI ($R^2 = 0.31$) than
296 RdNBR of MOSEV ($R^2 = 0.04$). Thus, this database could be more reliable than prior sources of information for future
297 studies of forest burn severity at the global scale in a computationally cost-effective way, as well as for studies to
298 which forest burn severity could be relevant, such as in forest management and CO₂ emissions research.

299 One future direction for this study will be to extend the GFBS dataset to the present based on updated Global
300 Fire Atlas data or other datasets providing similar burn area and burn date information. A second is to show the similar
301 spatial patterns in presenting burn severity from GFBS and MOSEV dataset, the less over/underestimated GFBS data
302 could serve as an optional input for adjusting the bias in MOSEV data and take the advantage of high spatial resolution
303 of GFBS data, the spatial downscaling of MOSEV data is applicable in regions where GFBS and MOSEV show high
304 consistency.

305 **Competing interests:** The authors declare they have no conflict of interest.

306 **Data availability:** The GFBS data are freely accessible at <https://doi.org/10.5281/zenodo.10037629> (He et al., 2023)

307 **Author contributions:** KH and EA designed and organized the manuscript. KH and XS prepared the related materials
308 and ran the models for generating GFBS and the related assessments. XS and EA made contributions to the scientific
309 framework of this study and discussed the interpretation of the results. All authors discussed the results and
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