

# Response to the Reviews

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Earth System Science Data  
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Dear Editor:

Thank you for guiding our paper through peer-review. We have addressed all of the referees' comments as detailed in our point-by-point replies below. In particular, we made the following main changes to the manuscript:

- We have clarified the relationship between the cloud types used by us and the WMO cloud genera, now using the terminology of "WMO-like" types;
- We have stated more clearly that our comparison to ICON-A data is only intended as an example and that comprehensive climate model evaluation would require more steps, such as using an instrument simulator;
- We mention some limitations of CClim more prominently, such as the incomplete sampling of the diurnal cycle;

Yours sincerely,  
*Arndt Kaps on behalf of the author team*

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# Response to Referees

## Earth System Science Data

Manuscript: essd-2023-424

Title: Characterizing clouds with the CClim dataset, a machine learning cloud class climatology

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Date: January 13, 2024

We thank the two referees for their helpful comments. In this document, we answer each point raised by the referees. The original referees' comments are given in **blue**, our answers in **black**. All line numbers refer to the "track changes" version of the revised manuscript.

## Referee: 1

This paper is a noteworthy addition to the growing literature of applying ML to Earth Science remote sensing, in this case cloud remote sensing. As the observational systems change and certain capabilities are interrupted or discontinued, we need innovative methods to cover data gaps. AI and ML have a lot to offer in that regard.

My recommendation is to accept the paper with minor revisions. I was tempted to recommend a major revision because I think that the active dataset is not used to its full potential, but it'd be unfair to demand from the authors a paper of a different direction. So this paper is judged on the merits of the fundamental choices they have made. Still, there are some major issues on how ML was implemented (see below).

What makes this paper in my opinion less than it could have been is the information content of the active observations they decided to use: so-called "cloud types". There are two issues: (1) The main appeal of active observations is that they can resolve (in many cases) cloud vertical structure, so to choose just a cloud type "flag" (the only or most dominant cloud type in an active observation "ray" or profile) seems like the least interesting choice;

We thank Referee 1 for providing helpful comments to improve the manuscript.

The authors agree that taking full advantage of the vertically resolved cloud column would be more interesting. However, such an approach comes with several technical challenges. The goal of the first stage of ML, as explained in [1] is to effectively extend the coverage of the spatially extremely sparse CC-L product. Any information on the 3D structure inferred from 2D MODIS observations would introduce more ambiguity than working with column-representative cloud types. In fact, such an approach is currently investigated by collaborating researchers but with inconclusive results so far.

(2) Even these "cloud types" from 2B-CLDCLASS-LIDAR (CC-L) are taken too literally by the authors: they're not the WMO cloud types the authors imply them to be, but just cloud labels that may have some association; but I suspect frequently they do not have the morphological characteristics that surface observers use to classify clouds. More on this topic below. On cloud types:

The WMO has 10 main cloud classifications <https://cloudatlas.wmo.int/en/cloud-classification-summary.html>. There's no Deep Convection (DC) as in CC-L, but rather Cumulonimbus (Cb). There is also cirrocumulus and cirrostratus, which do not exist in 2BCL (presumably all under Cirrus). But the biggest tell of the lack of correspondence between CC-L and WMO is the small occurrence frequency of stratus (noted by the authors). If one checks daytime stratus occurrence over the ocean from surface (ship) observers in the Warren Atlas <https://atmos.uw.edu/CloudMap/Web0/index.html>, there is plentiful stratus in the extratropical oceans. So, the same way the 9 ISCCP cloud types defined by arbitrary boundaries in the TAU-CTP joint histogram cannot be taken as equivalent to the corresponding WMO cloud types (cloud morphology as appears from surface), mentioned by the authors, the CC-L cloud types can also be assumed to mean the same thing as the WMO classification. Another tell: the small SW CRE peak the authors find for Ns which are optically thick rain-producing clouds.

We agree with the referee, that speaking of WMO cloud types is not fully correct and thus confusing. We

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therefore applied the following changes listed below in the revised manuscript and now speak of “WMO-like” classes. The differences in naming conventions between CC-L and WMO have been clarified and the observed differences to the Warren Atlas mentioned. As there are no major conceptual differences between the CC-L classification and WMO genera from [6], deviations are likely caused CC-L’s sensor characteristics. The inconsistency with the Ns CRE noted by the referee is probably not caused by these definitions but rather by the ML algorithms confusing Ns and As, as well as the frequent co-occurrence of Ns and As. The following changes have been applied to the text:

- (Abstract L5): ...eight major cloud types, designed to be similar to those defined by the World Meteorological Organization (WMO) ...;
- (Introduction L45-46): The cloud types contained in CCclim are physically consistent with most of the major cloud genera defined by the World Meteorological Organisation [7]...;
- (Data and Methods L85-90): These are used in CUMULO to provide target labels as WMO-like cloud types from CloudSat’s 2B-CLDCLASS-LIDAR dataset (hereafter CC-L) [6]. We call the cloud types “WMO-like” because they are defined to correspond to eight of the ten WMO genera, with the Dc (deep convective) type replacing the WMO’s cumulonimbus and cirrocumulus/cirrostratus being contained in the Ci (cirrus) type. While these classes are defined to be consistent with the WMO definitions, misclassifications can occur, caused for example by the small footprint of the active sensors;
- (CC-L methods L112-113): CC-L contains WMO-like cloud-type labels obtained by a fuzzy-logic classifier [6]. The classifier assigns one of eight classes that are comparable to the WMO cloud genera...;
- (Capabilities L328-333): The CCclim dataset presented in this paper allows for the investigation of clouds grouped by WMO-like cloud type with a long temporal coverage and high spatial resolution as daily samples. Using multiple cloud properties to define the classes makes them physically consistent and well-aligned with the morphological WMO genera. We showed that categorizing complex atmospheric data into established types is more expressive and interpretable than individual cloud properties;
- (Capabilities L337-338) This makes CCclim suitable for statistical analyses of clouds and enables quantification of seasonal cycles of WMO-like cloud types on a global scale.

**Other major comments:**

– Applying the ML algorithm cloud type to off-nadir MODIS pixels, when the training has been conducted with nadir MODIS cloud retrievals (that coincide with the active observations) can be justified only if it has been previously shown that the cloud retrievals are statistically the same at different parts of the MODIS swath, i.e., there are no biases in off-nadir retrievals (especially as one moves further away from nadir).

While there is a difference in the retrievals of nadir and off-nadir cloud properties [2], quantifying its effect on cloud types is difficult, as there are no coinciding CC-L labels for off-nadir MODIS pixels. Discarding all off-nadir MODIS pixels would result in a considerable loss of spatial coverage. Since it seems reasonable to assume that differences in the retrieved physical cloud properties from nadir and off-nadir pixels are minimized by the MODIS retrievals (assuming the opposite would call into question the validity of much of the MODIS data), such viewing angle effects are expected to have a rather small effect on the results compared with other factors such as using a single representative cloud type for each column. This is now mentioned in L131-134.

–Similarly, applying the ML algorithm to ESACCI clouds (from AVHRR) has to be justified by showing that MODIS and AVHRR cloud property retrievals are statistically equivalent (the authors are aware they’re not – lines 337-338). Because of different retrieval algorithms I doubt they are. Also, does ESACCI also include morning clouds? The training was conducted with afternoon clouds.

In [1] (Fig. 11, Table VI), the predictions of the ML algorithm from ESACCI data were compared to the distribution of the original CC-L labels, showing decent agreement for all cloud types. This comparison accounts for errors introduced by both stages of the ML algorithm and ensures that the *output* of the method is sensible even if the distribution of the *input* values in a different dataset is slightly different. This comparison is, therefore, more conclusive than a comparison of ESACCI and MODIS, as it shows that the method achieves the intended goal: reproducing the CC-L labels and being robust to small changes in the input data.

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Different sampling of morning or afternoon clouds is not expected to influence the results significantly as the relationship between the physical cloud properties and the derived cloud type are essentially independent of the time of day. The incomplete sampling of the diurnal cycle could, however, influence the representation of daily mean values of the cloud-type RFOs. The RF is not very susceptible to small changes in the data due to a fairly high number of trees (400). We therefore do not expect the statistical differences mentioned by Referee #1 to have a discernible effect on the cloud-type distributions in CClim.

– Similarly, applying the ML algorithm on climate models clouds is a huge stretch. What makes the model clouds equivalent to those of MODIS? You cannot even rigorously define a cloud-only grid column optical thickness when the grid is not overcast (depends on cloud fraction profile and overlap). At the minimum the model should've provided cloud output from the MODIS simulator.

We agree with the referee that care has to be taken when using CClim to quantitatively evaluate a climate model. We, therefore, clarified in the revised version that we do not intend to do an actual evaluation of ICON-A, but only show an example of how CClim could be used if climate model standard output would include variables like optical depth as instantaneous values. Using results obtained with a MODIS simulator in the model would certainly be desirable, but such a simulator is not readily available for ICON. We added the recommendation to use a satellite simulator (preferably `Cloud_cci`) when using CClim to evaluate climate models to Section 4. L324-326 now state that to perform actual climate model evaluation, instrument simulator output would be preferable.

Inconsistencies between the optical thickness values from ICON-A and the training data are, however, not expected to have a large impact as the latter contains grid-cell averages of the optical thickness, which is similar to the approach of ICON-A. The radiation parametrization of ICON-A uses the column-integrated water, such that computation of the column's optical thickness (in contrast to the resulting radiative fluxes) does not depend on the overlap assumption. We now make clear in L287-289 that our values are free from overlap assumptions.

Some minor comments:

– Figure 1 would have been more complete if the datasets used in each step (CUMULO, ESACCI, etc) were added as labels.

We updated Figure 1 to make it more clear what constitutes CUMULO. The ESACCI data is not included in Figure 1.

– Figure 2: Unclear to me: So if I properly weighted land and ocean and then normalized by the undetermined, I'd get close to what is shown in Fig. 2a? Perhaps you can say that.

This is correct, and we added this information to the figure caption.

– Figure 4: Why do this over the southern oceans where (beyond the nearly non-existent St) there is virtually no Cu and no DC? Perhaps show time series and trends for different regions for each cloud type, namely the areas where each dominates relative to its global mean? (Fig. 6)

Such an analysis would certainly be interesting but would in our opinion require at least four new plots equivalent to Figure 4, to illustrate the cloud-type behavior in selected regions of interest. We think this would be beyond the scope of a dataset description paper and rather belong into a scientific application paper.

– Figure 7: An interesting complement to Fig. 7 would be a table showing the contribution of each cloud type to the global CRE, weighted by RFO (subject to the disclaimer of no "pure" grid cells).

Unfortunately, such a detailed decomposition is not feasible due to the way the data have been processed. Simply weighting the results by RFO would assume that the total CRE can be linearly decomposed by cloud type, while in reality this is not the case.

– Lines 319-322: Of course there'll be few St in CClim since you started with small frequency of St in CC-L. Same with DC. The difference between DC and St is though that DC are truly very rare while St are artificially rare in CC-L.

We think these limitations are noteworthy and would thus like to keep this statement in the text.

– Lines 344-346: Not sure what you mean by this.

We rephrased these sentences to clarify the meaning as follows (L370-376): The few datasets attempting

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to assign objective WMO-like cloud types often disagree on important details. For example, while [4] are in good qualitative agreement with the ISCCP cloud distributions, they find, for instance, a much higher cirrus fraction in the tropics. In comparison, CCCLim is less affected by problems common to these purely passive-sensor-based datasets, such as dealing with multilayer clouds [3]. Cluster-based datasets are however not suitable for a direct comparison with CCCLim, as even intercomparison of datasets produced with unsupervised methods is difficult since the derived clusters do not have a common physical basis across all datasets.

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## Referee: Peter Kuma

We would also like to thank Peter Kuma for helping us to improve the manuscript.

Calling the CC-L cloud types WMO cloud types is misleading. The WMO cloud genera are defined using ground-based visual observations, as standardised by the WMO International Cloud Atlas. While CC-L definitions of cloud types aim to be similar to the WMO cloud genera, they are not the same. The deep convective (Dc) type is also not a WMO cloud genus. I think that the authors should be more clear about this.

We agree that calling the CC-L cloud types WMO cloud types is misleading and needs to be changed. We clarified the differences and changed the text to "WMO-like" throughout the manuscript. For a detailed answer and all changes applied to the revised version, please see our reply to comment (2) of referee #1 above.

There is a considerable overlap between the presented work and Kaps et al. (2023a). It is not entirely clear if the authors use the exact same methods as in the previous paper, or if anything is different. I think that the authors do not necessarily have to duplicate the description of the methods in this manuscript, and can instead reference the previous paper, which is really a pre-requisite for understanding this manuscript.

We clarified the overlap by saying explicitly (L149) that we use exactly the same RF model as the one trained for [1].

L177-178, Fig. 4 caption: The Cloud\_cci AVHRR L3U PM daily data are a composite of instantaneous values and not a daily mean, because the satellite overpass time is always at about the same local time, and the data have not been corrected with a diurnal cycle model. Stengel et al. (2020): 'All data are collected on two processing levels: (a) Level-3U, which represents daily composites of non-averaged data collected on a global latitude-longitude grid with  $0.05^\circ$  resolution and'. Unless some more sophisticated processing is done on the input data, the CClim dataset also represents daily composites of instantaneous values.

There is some processing being done by averaging the RF outputs and the daily composite inputs, resulting in one mean value per day, which is (as the referee pointed out) not to be confused with a daily mean value averaging the whole diurnal cycle. This is now stated more clearly in L189.

It is not clear whether the results only represent daytime clouds or nighttime as well. The authors say that the Cumulo dataset is only available for daytime, but they do not say whether they apply the RF on nighttime grid cells from Cloud\_cci and ICON-A. If they only apply it on daytime, it should be made more clear that the results can be biased toward daytime clouds and not representative of polar night conditions. If they apply it on nighttime too, this should be mentioned as a limitation due to the fact that this is assuming that the statistical links between the input physical quantities and cloud types applying during daytime also apply during nighttime (reference training data for nighttime are lacking in this case).

The referee is correct that the RF is trained only on daytime data. ESACCI includes both, daytime and nighttime measurements, with nighttime data typically having higher uncertainties. We are not aware of reasons why the underlying statistical relationship between the retrieved physical cloud properties and the cloud types should be different during day and nighttime. A higher uncertainty in the nighttime retrievals is, however, expected to result in higher uncertainties in the derived cloud type. We see, for instance, a roughly 30% difference in the cloud/liquid/ice water path and optical depth retrievals between night and day. Therefore, we added to Section 5 (L364-365) that such deviations/uncertainties in the retrievals will have a corresponding effect on the CClim cloud types.

Because the comparison between cloud types derived from ICON-A and Cloud\_cci is between 3-hourly instantaneous output of the model and daily composites of AVHRR measurements, it is not necessarily comparing the same time of day at local time. Because clouds tend to exhibit a diurnal cycle, this can introduce biases. This should be at least mentioned as a limitation. Also comparing 35 years of CClim from AVHRR with 2 years from ICON-A is not necessarily a good idea because the global climate has changed during the last 35 years. Comparing the same 2 years of both would be better.

We agree with the points raised by the referee. Our comparison to ICON is only intended as an example and is not suitable to perform a quantitative model evaluation. This is now stated more clearly in the manuscript by naming these limitations and adding the recommendation to use a satellite simulator to create model

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output for evaluation to reduce biases introduced by the spatially and temporally incomplete sampling of the satellite as well as by instrument specific limitations. We also added the note that ideally either the same time periods from the model and the satellite data or climatological averages (20 years or more) should be compared. In order to illustrate the example application of CCCLim for model evaluation, however, we do not think that additionally showing CCCLim data only for the two ICON years would bring more insights.

One potential limitation that the authors do not mention is that cloud-related quantities such as cloud top pressure and cloud optical depth are not always directly comparable with those derived from radiance measured by a satellite instrument. For this reason, simulators for ISCCP and MODIS such as COSP exist. Because the RF takes these quantities as a input from the observations and the model without using an instrument simulator, an artificial bias can be introduced in the comparison.

We agree that using a satellite simulator to create the model output used for comparison would be ideal. For ICON-A, however, such output was not available. The example comparison shown here is only an illustration of how we envision CCCLim to be used for model evaluation if the required output from climate models was available. We actually hope to encourage modelers with this example to provide such output in future simulations or model intercomparison projects that could then be used for a quantitative model evaluation. This is now stated more clearly at the end of Section 4.

The authors should include short sections in the Methods describing the Cumulo dataset and ICON-A. The section on CC-L should at least briefly describe how the CloudSat-CALIPSO cloud types are defined in the original dataset.

Following the referee’s recommendation, we extended the MODIS and CC-L section to express more clearly how they constitute CUMULO (L106 and L113, respectively). As the main focus of the paper is to introduce CCCLim and show some potential scientific applications, we think a more detailed model description beyond the references given and our description of the data we use is probably not adding much as we could have taken any model as an example with at least the basic output required for this illustration available.

A global regular angular (longitude-latitude) grid has unequal area of grid cells by latitude. This means that grid-cell averages are calculated over larger areas over polar latitudes than equatorial latitudes. This can have an effect on a predictor, such as the RF used on the coarse-grained Cloud\_cci data or ICON-A data. I think that this should be at least discussed.

As shown in [1], we do not expect this to be a big problem. We added this statement to the revised version (L152-153).

I think it would be possible to use a single machine learning model to determine the cloud types instead of two (IResNet on the fine scale followed by RF on the coarse scale). One could train a CNN to predict coarse grid cell cloud type fractions by training on grid cells where CC-L data are available (averaged over the coarse grid cell and represented as fractions of cloud types). It seems to me that the two step approach can be both more complex and less stable. Can the authors comment on this?

The suggested single-step approach would combine all of the reduction in resolution into one step, meaning that only a few labeled samples per cell would be considered representative of a complete grid cell as the CC-L data are very sparse (see e.g. the globes in Figure 1). Our 2-step approach ensures that cells without CC-L coverage adequately contribute to the cloud-type fractional amounts. One could argue that the second step is actually unnecessary for high-resolution applications, but as we show in [1], the intermediate step of pixel-wise labeling is crucial to take advantage of the active sensor data.

I suggest that the authors use terms ‘cloud type’ and ‘cloud class’ consistently throughout the manuscript. They seem to be used interchangeably, but it would be better to use either only one of them, or define the distinction between them.

We now consistently use “cloud type” throughout the text.

The active satellites sensors used as a reference for the CC-L cloud types have known problems with detecting low clouds. The CloudSat radar is affected by ground clutter, and the CALIPSO lidar signal is often attenuated by overlapping clouds before reaching mid and low-level clouds. These problems in turn also affect the presented dataset, and should be mentioned as a limitation.

Following the recommendation of the referee, we added these limitations to the text referring to Marchand et al. (2008) as a reference for CloudSat’s difficulty in detecting low-level clouds due to surface clutter as an

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example (L340-342). We would like to note that uncertainties in the CC-L cloud types resulting from these limitations are not mentioned in the CC-L ATBD [6].

The authors train the RF on MODIS but apply it to Cloud\_cci. It is not clear if this produces any side-effects. Ideally, the authors should compare the results of applying the RF on MODIS and Cloud\_cci for the same testing time period (excluded from training).

As we could show in [1] by comparing the statistics of the predictions on ESACCI to the label distributions from the original CC-L dataset, application of the RF to ESACCI works quite well. A direct comparison of predictions from individual MODIS and ESACCI scenes as suggested by the referee would be valuable. But as the two datasets cannot easily be collocated, only a statistical comparison would be possible. In this respect, a statistical comparison with the CC-L ground truth is preferable to assess possible side-effects of the change in dataset.

Fig. 4: Long-term AVHRR datasets are usually not very well suited for determining trends due to discontinuities in the orbital parameters of the satellite series. This limitation can also translate to any derived dataset. Can the authors comment on whether the slopes shown in the figure are reliable? The authors mention this on L339, but it would be better to also caution the readers in the context of Fig. 4, and also on L8-10.

The CC4CL algorithm [5] used to create the ESACCI dataset attempts to remove inconsistencies between individual sensors without removing any trends. While the computed slopes should be treated with caution, though as mentioned in L339 of the initial submission. We added a disclaimer to the caption of Figure 4 that datasets derived from ESACCI, such as CClim are not suitable for dedicated trend analyses. As trends are not mentioned in the abstract we would to keep the sentence in L8-10 as is.

L14-15: or its radiative effects: This could be a problem with reanalyses which usually parametrise clouds, which can result in radiation fluxes not corresponding to the actual cloud cover.

We rephrased this sentence to make it less ambiguous by replacing "or its radiative effects" with "in association with its properties".

L275: This waveband corresponds closely to the absorbing band used for the MODIS retrievals of cod and cer.: But what about AVHRR? Since the comparison here is between cloud types derived from ICON-A and from AVHRR.

As we could show in [1], application to ESACCI is possible without discernible side effects, even though AVHRR does not have a detector for this waveband. Thus, the validity of our example to illustrate an application of CClim is not expected to be strongly affected. In a comprehensive climate model evaluation, though, one might want to investigate the effect of changing the waveband or preferably use an instrument simulator to create the model output for comparison. We added the recommendation to use a satellite simulator for such a comparison (see above for details).

L290-291: With respect to CClim the simulation also exhibits an increase in high cloud RFO (Ci, Ns): Ns is classified as a middle level cloud in the WMO International Cloud Atlas.

Thanks for pointing this out. This was indeed misleading. We now write "increase in the RFO of higher clouds with significant ice content".

L351-352: there is arguably no better way to obtain cloud observations from space than combining radar, lidar and passive instruments.: I think that this is merely stating the obvious. Since there are currently no other satellite instruments relevant to cloud measurements other than lidar, radar and passive instruments, combining them necessarily has to give the best opportunity to obtain cloud measurements. One could also consider other kinds of passive measurements such as those by geosynchronous satellites, multi-angle measurements (MISR), passive microwave, Doppler lidar (Aeolus) and passive instruments on deep space satellites (DSCOVR). Including those in a combined analysis could produce more accurate results. The fuzzy logic classifier used in CC-L could have many different alternatives, for example using unsupervised learning or by supervised learning using ground-based observations. I do not think that one could say that it is the best, but rather one of many options of how to classify clouds.

We agree that including even more datasets is likely to further improve the results. We rephrased the sentence as follows: "Even though subjective thresholds are being used in the fuzzy logic classifier of CC-L, combining the different cloud observations from space radar, lidar and from passive instruments is a clear advantage over classification methods that do not use active sensor data such as such as many unsupervised approaches.



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Using additionally other kinds of passive measurements could further improve the results.” (L381-385).

Technical comments Greater attention is needed to make the plots accessible to people with colour blindness. For example, in Fig. 1, 2, 6 and 7 some of the cloud type colours could not be distinguished. I recommend testing this for example with KMag on Linux.

We agree with the referee that this is an important aspect of any publication. This is why we made efforts in the initial manuscript to make the figure accessible to everyone by using a color scale especially designed to be colorblind-friendly and by using a colorblindness simulator. In another attempt, we are now using a different scale that is (supposedly) very accessible and recommended at <https://clauswilke.com/dataviz/>. L355: This section should contain links to all of the datasets used, including Cumulo, ERA5, MODIS, 2BCLDCLASS-LIDAR, Cloud\_cci and ICON-A.

The ESACCI and ERA5 data sources have been moved from the acknowledgments to the data availability section, and a link for CUMULO has been included. Since we did not use CC-L and MODIS data other than the data provided by CUMULO, we do not believe that additional links to the (original but unused) datasets used should be included here. We did not provide a link for ICON-A data as this was used for an example application only and no scientific conclusions are drawn concerning ICON that would justify the upload of a large volume of ICON results.

L372: It should be made clear that the DOI is a DOI.

Thanks for spotting this. Has been changed accordingly.

Fig. 2: This is more of a style issue, but pie charts are usually not considered a good visualisation method because the proportions are hard to compare. Bar charts usually provide a much better experience.

We replaced the pie charts with stacked bars.

Fig. 3, 8, 9: Ideally, all colour bars should have labels. Fig. 4: The plots should have y-axis labels. Fig. 5: Plots should have a y-axis label RFO.

We adapted the Figures accordingly.

Fig. 10: The plots are probably too small. I recommend dedicating more space to the figure. The axes should have better labels, i.e. not just the cloud type name, but also that it is RFO on the x-axis, and probability density on the y-axis.

The extra labels have been included, the white space reduced and the height increased.

## References

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