

1 **TRIMS LST: A daily 1-km all-weather land surface temperature** 2 **dataset for the Chinese landmass and surrounding areas (2000–2022)**

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9 **Abstract.** Land surface temperature (LST) is a key variable within the Earth's climate system and a necessary input parameter
10 required by numerous land-atmosphere models. It can be directly retrieved from satellite thermal infrared (TIR) observations,
11 but cloud contamination results in **many invalid pixels**. To investigate the temporal and spatial variations of LST in China,
12 long-term, high-quality, and spatio-temporally continuous LST datasets (i.e., all-weather LST) are urgently needed. Fusing
13 satellite TIR LST and reanalysis datasets is a viable route to obtain long time-series all-weather LST. Among satellite TIR
14 LSTs, the MODIS LST is the most commonly used and a few all-weather LST products generated in this way have been
15 reported recently. However, the publicly reported all-weather LSTs are not available during the temporal gaps of MODIS
16 between 2000 and 2002. In this context, we report a daily (**four observations per day**) 1-km all-weather LST dataset for the
17 Chinese landmass and surrounding areas – TRIMS LST. Different from other products, the TRIMS LST begins on the first
18 day of the new millennium (i.e., January 1, 2000). The TRIMS LST was generated based on the Enhanced Reanalysis and
19 Thermal infrared remote sensing Merging (E-RTM) method. Specifically, the original RTM method was used to generate the
20 TRIMS LST outside the temporal gaps. Two newly developed approaches, including the Random-Forest based Spatio-
21 Temporal Merging (RFSTM) approach and Time-SEquential LST based Reconstruction (TSETR) approach, were used to
22 produce Terra/MODIS-based and Aqua/MODIS-based TRIMS LSTs during the temporal gaps, respectively. Thorough
23 evaluation of the TRIMS LST was conducted. **A comparison with the GLDAS and ERA5-Land LST demonstrates that TRIMS**
24 **LST has similar spatial patterns but higher image quality, more spatial details, and no evident spatial discontinuities. The**
25 **results outside the temporal gap show consistent comparisons of TRIMS LST with MODIS and/AATSR LST, with mean bias**
26 **deviation (MBD) of 0.09 K/0.37 K and standard deviation of bias (STD) of 1.45 K/1.55 K. Validation based on *in-situ* LST at**
27 **19 ground sites indicate that the TRIMS LST has a mean bias error (MBE) ranging from -2.26 K to 1.73 K and a root mean**
28 **square error (RMSE) ranging from 0.80 K to 3.68 K. There is no significant difference between the clear-sky and cloudy**
29 **conditions. For the temporal gap, it is observed that RFSTM and TSETR perform similarly to the original RTM method.**
30 **Additionally, the differences between Aqua and Terra remain stable throughout the temporal gap. The TRIMS LST has already**
31 **been used by scientific communities in various applications such as soil moisture downscaling, evapotranspiration estimation,**

32 and urban heat island modelling. The TRIMS LST is freely and conveniently available at
33 <https://doi.org/10.11888/Meteoro.tpsc.271252> (Zhou et al., 2021).

34

35 **1 Introduction**

36 Land surface temperature (LST) is a key variable related to the energy exchange at the interface between the land surface and
37 the atmosphere. It is the result of the thermal feedback of various ground surface to incident solar radiation and atmospheric
38 downward radiation. Therefore, it is a necessary input parameter required by numerous land–atmosphere models (Jiang and
39 Liu, 2014; Li et al., 2013b, 2023c). LST have been widely used in a variety of studies, such as surface evapotranspiration (ET)
40 estimation (Anderson et al., 2011; Ma et al., 2022), urban heat island (UHI) modelling (Alexander, 2020; Liao et al., 2022),
41 drought monitoring (Zhang et al., 2017), and ecological assessment (Sims et al., 2008).

42 In the past four decades, especially since the beginning of the new millennium (i.e., 2000), China and its surrounding areas
43 have experienced rapid economic development and population growth, accompanied by notable changes to the natural
44 environment (Yang and Huang, 2021). Meanwhile, China has adopted a series of interventions to protect the environment
45 since the 1980s, such as the **Grain for Green Program** (Wang et al., 2017), Three-North Shelter Forest Program (Zhai et al.,
46 2023), and Red Lines of Cropland (a policy to ensure that Chinese arable land does not drop below 120 million hectares).
47 These interventions have played a key role in changing the land use/cover and regulating the climate (Chen et al., 2019a). In
48 addition, with the warming climate, extreme weather and meteorological disasters occur frequently in China and its
49 surrounding areas (Chen et al., 2019b). **Since LST is highly sensitive to land cover change, heat waves, droughts, and**
50 **vegetation information (Li et al., 2023a; Su et al., 2023), making it an important indicator of global climate change** (Mildrexler
51 et al., 2018; Peng et al., 2014), it is important to investigate the spatial and temporal variations of LST for these areas. This
52 requires a long-term, high-quality, and spatio-temporally continuous LST dataset.

53 LST can be obtained through *in-situ* observations, model simulations, and remote sensing retrievals. However, LST is spatially
54 and temporally heterogeneous and highly affected by various factors such as land cover, soil type, topography, climatic, and
55 meteorological conditions (Liu et al., 2006; Zhan et al., 2013). *In-situ* observations based on spatial 'point measurement' are
56 not able to obtain spatially continuous LST, and the current model simulation suffer from coarse spatial resolution. In contrast,
57 satellite remote sensing, which has advantages of better spatial continuity, larger coverage, good ability for repeating
58 observations, and much higher spatial resolution, has become an important way to obtain LST for large areas (Li et al., 2013b).
59 Satellite thermal infrared (TIR) remote sensing can directly obtain the regional and global LST efficiently. A series of satellite
60 TIR LST products are currently available to users, including platforms such as polar orbiting and geostationary satellite
61 platforms. Among the satellite TIR LST products, the Moderate-resolution Imaging Spectroradiometer (MODIS) LST products
62 is the most widely used because of its global coverage, long time-series (since February 24, 2000 for Terra and since July 4,
63 2002 for Aqua), high quality, and good accuracy (Aguilar-Lome et al., 2019; Sandeep et al., 2021; Wan, 2014).

64 Although MODIS LST products (especially with a 1-km spatial resolution) have shown good performance in related
65 applications, they generally have significant spatial absences due to cloud contamination, especially in low and middle latitudes
66 in China (e.g., the Tibet Plateau and southern China) (Duan et al., 2017). Cloud contamination restricts the LST products from
67 playing a more critical role in subsequent applications (Li et al., 2023c). **Furthermore, there is a temporal discontinuity**
68 **(hereafter termed as the temporal gap) in Terra/Aqua MODIS during 2000-2002; thus, it is not easy to generate the all-weather**
69 **LST products for these gaps.**

70 In recent years, many methods have been developed to generate all-weather LST based on satellite TIR LST and other data
71 (Jia et al., 2022; Zhang et al., 2022). Typical methods include spatial-temporal interpolation, surface energy balance (SEB),
72 and multisource data integration (Ding et al., 2023; Li et al., 2023c). The spatial-temporal interpolation methods take advantage
73 of temporal variation patterns of the LST as well as the spatial characteristics. **One of the most representative study come from**
74 **Zhang et al. (2022), which takes full advantage of above patterns and characteristics in their spatiotemporal fitting framework**
75 **to generate a 1-km spatial resolution dataset from 2003 to 2020 over global land. According to our knowledge, this dataset is**
76 **the first seamless daily 1-km resolution LST dataset with global spatial coverage and the only seamless one on Google Earth**
77 **Engine for free applications. Nevertheless, it is crucial to acknowledge that the results obtained by the above methods are the**
78 **hypothetical LST under clear-sky conditions, not the LST in the cloud-contaminated regions (Martins et al., 2019).** To solve
79 the above problems, SEB is proposed as a physical method (Jin and Dickinson, 2000). Under cloudy conditions, this method
80 considers longwave radiation and solar radiation as influences on the LST. Martins et al. (2019) used the SEB method to
81 successfully fill the missing LST using land surface parameters provided by the European Satellite Application Facility on
82 Land Surface Analysis (LSA-SAF) and generate the all-weather LST product **(MSG All-Sky Land Surface Temperature,**
83 **MLST-AS)**. In addition, a more general approach that incorporates the clear-sky LST into the SEB has recently been developed
84 to estimate the LSTs under cloud-contaminated regions based on the MODIS and Visible infrared Imaging Radiometer (VIIRS)
85 data (Jia et al., 2021).

86 At present, multisource data integration methods have been widely used to generate seamless all-weather LST. Present
87 multisource data fusion methods mainly to integrate TIR LST with satellite passive microwave (PMW) observation or
88 reanalysis data. PMW data can be used for estimating all-weather LST retrievals because they are **less affected by the**
89 **atmosphere and clouds** (Holmes et al., 2009; Zhou et al., 2017). However, there are limitations in obtaining all-weather LST
90 from PMW observations. First, the spatial resolution of PMW data differs significantly from TIR, such as the Advanced
91 Microwave Scanning Radiometer 2 (AMSR2) with ~10 km spatial resolution. Second, the spatial coverage of the PMW data
92 is incomplete because there are orbital gaps. Third, the temperature retrieved from PMW observations contains information
93 from the subsurface, **which differs from the TIR LST that exclusively represents skin temperature** (Zhou et al., 2017).
94 Compared with the PMW data, reanalysis data can provide spatially continuous LST and related surface parameters; thus, it
95 can act as an alternative basis to obtain the all-weather LST (Long et al., 2020; Ding et al., 2022). One typical method is the
96 Reanalysis and Thermal infrared remote sensing Merging (RTM) method proposed by Zhang et al. (2021) for integrating the
97 GLDAS and MODIS LST for the Tibetan Plateau.

98 In recent years, based on the aforementioned three typical methods, various all-weather LST datasets were released (Duan et
99 al., 2017; Hong et al., 2022; Jia et al., 2022; Li et al., 2021a; Metz et al., 2017; Muñoz-Sabater et al., 2021; Yao et al., 2023;
100 Yu et al., 2022). However, all-weather LST datasets with both high temporal resolution (4 observations per day or higher) and
101 high spatial resolution (1 km or higher) since 2000 for the Chinese landmass and the surrounding areas are still rare.
102 In this study, we proposed the enhanced RTM (E-RTM) method to produce a daily (four observations per day) 1-km all-
103 weather LST dataset for the Chinese landmass and surrounding areas (19°N–55°N, 72°E–135°E), which is known as the
104 Thermal and Reanalysis Integrating Moderate-resolution Spatial- seamless LST (TRIMS LST). The E-RTM method includes
105 three modules (Sect.3). The original RTM method is used to produce the TRIMS LST during DOY 55 of 2000 (DOY 185 of
106 2002) to DOY365 of 2022. Additionally, based on the physical properties of the LST time component decomposition model,
107 Terra/MODIS-based and Aqua/MODIS-based TRIMS LST during the temporal gaps are produced. Then TRIMS LST is
108 evaluated using *in-situ* sites to provide better-quality data for applications associated with urban thermal environment,
109 meteorology, and hydrology.

110 2 Datasets

111 2.1 Satellite data and reanalysis data

112 In this study, the main satellite data used are the 1-km daily MODIS LST/emissivity product (MOD11A1: February 2000 to
113 December 2022; MYD11A1: July 2002 to December 2022) in version 6.1. This LST product was produced based on the
114 generalized split-window algorithm and has good accuracy for homogeneous surfaces (Wan, 2014). As mentioned previously,
115 it is usually used as the basis in the reconstruction of all-weather LST. In this study, this product is also used as a basis data
116 for producing the TRIMS LST. The other used MODIS datasets used include: (1) the 1-km 16-day Normalized Difference
117 Vegetation Index (NDVI) product (MOD13A2: February 2000 to December 2022) in version 6.1; (2) the 500-m daily
118 Normalized Difference Snow Index (NDSI) product (MOD10A1F: February 2000 to December 2022) in version 6.1
119 (<https://modis-snow-ice.gsfc.nasa.gov/>); and (3) the 500-m daily MODIS land surface albedo product (MCD43A3: February
120 2000 to December 2022) in version 6.1. All of the above products except MOD10A1F are available at EARTHDATA
121 (<https://earthdata.nasa.gov/>). In addition to generation and evaluation of the all-weather LST, we also collected (1) the 90-m
122 Shuttle Radar Topography Mission Digital Elevation Model data (SRTM DEM; <http://srtm.csi.cgiar.org>); (2) Global 1-km
123 daily Synthesis of ‘Satellite Pour l’Observation de la Terre’ (SPOT) VEGETATION (VGT) Images (VGT-S1) (January 2000
124 to February 2000) (<https://services.terrascope.be/>) (Toté et al., 2017); (3) 0.05° 8-day GLASS Albedo product (January 2000
125 to February 2000) (<http://www.glass.umd.edu/Albedo/MIX/>) (Feng et al., 2016); (4) the 30-m yearly China land cover dataset
126 (2000-2015) from Zenodo (CLCD, <https://doi.org/10.5281/zenodo.4417810>) (Yang and Huang, 2021) and (5) the 1-km daily
127 ENVISAT/AATSR LST product (July 2004–April 2012) (<https://climate.esa.int/>).

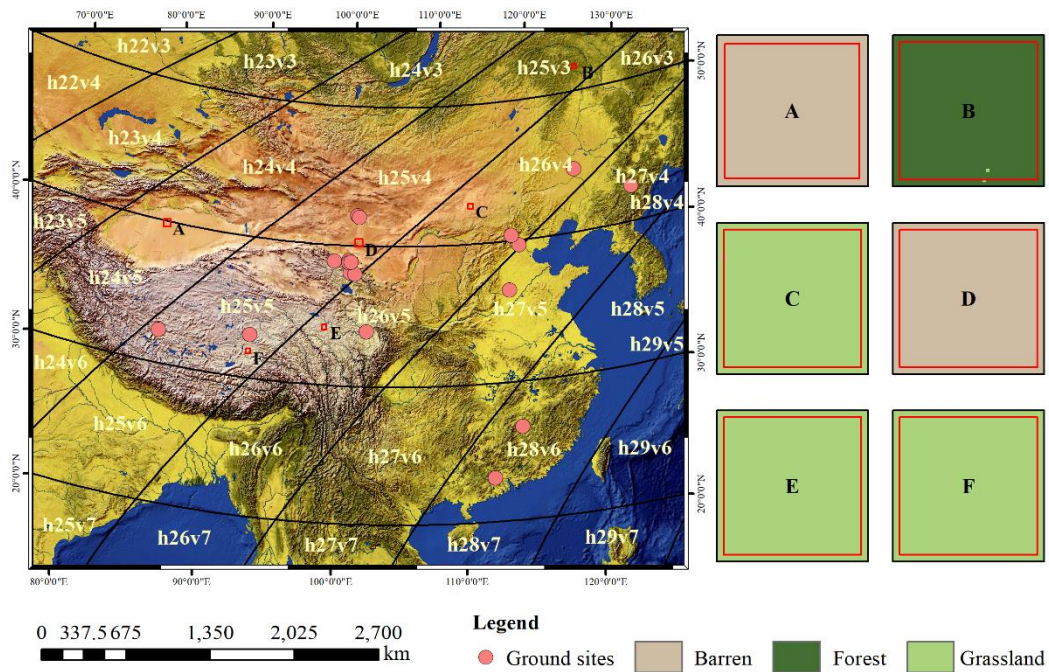
128 The main reanalysis data used in this study are the Global Land Data Assimilation System assimilation (GLDAS) data
129 provided by the Goddard Earth Sciences Data and Information Services Center (GES DISC) (Rodell et al., 2004). GLDAS

130 utilizes an analysis increment, which is obtained through the optimal interpolator using the observed-minus-forecast value for
131 the skin temperature calculated by GLDAS. This analysis increment, along with the bias correction term, is subsequently
132 provided to the land surface models code for energy budget considerations. The bias correction ensures that the modelled state
133 is continually adjusted towards the observed values, thereby improving the accuracy of the skin temperature calculations on
134 an incremental, semi-daily, or daily basis (Radakovich et al., 2001). The accuracy of GLDAS LST has been demonstrated by
135 various studies with MBE ranging from -4.27 K to 8.65 K and RMSE ranging from 3.0 K to 6.02 K (Zhang et al.,2021; Xiao
136 et al.,2023). Specifically, the 0.25° 3-hourly LST from the GLDAS Noah model between January 2000 and December 2022
137 was used as another input of the RTM method. In addition, we also collected the 0.1° hourly ERA5-Land LST datasets (Muñoz-
138 Sabater et al., 2021), and its LST will be compared with the generated TRIMS LST.

139 **2.2 Ground measurements**

140 Table I shows 19 ground sites that recorded longwave radiation data for different time spans. According to geographical
141 locations and land cover types provided in Table I, it is clear that they are distributed in different climate zones. This indicates
142 that they encompass a wide range of land surface and climatic situations for sufficient validation of the TRIMS LST. The
143 measurement device at the selected ground station includes a long-wave radiometer and four-component radiometers,
144 including CNR1, CNR4, and CG4 (Kipp & Zonen, Netherlands; <https://www.kippzonen.com/>). According to the specifications
145 of these radiometers, the uncertainties in daily total for longwave radiation measurements are 3%–10% (Wang et al.,2020).
146 With the measured incoming and outgoing longwave radiation, the LST of the land cover type within the field-of-view (FOV)
147 of the radiometer can be calculated through the radiative transfer equation in the form of the Stephan-Boltzmann's law (Ma et
148 al., 2023, 2021). Considering the uncertainties of the longwave radiation measurement, the uncertainties of the calculated *in-*
149 *situ* LST are approximately 0.6 K–1.2 K (Xu et al., 2013; Yang et al., 2020; Ma et al., 2021).

150 Spatial representativeness of ground sites has different degrees of influence on the validation of TIR-based LST using *in-situ*
151 LST. In this study, to quantify the spatial representativeness, we calculated the standard deviation (STD) of 33 × 33 Landsat
152 LST within MODIS pixels containing ground sites. United States Geological Survey provides this product, which is the 30-m
153 Landsat-7 ETM+ Collection 2 Level-2 (L2C2) LST (U.S. Geological Survey, 2021). For the 19 sites, the STD was 0.64 K to
154 1.53 K, indicating good to acceptable representativeness of these sites for the validation of a 1-km LST (Zhang et al., 2021;
155 Duan et al., 2019). Abnormal measurements, caused by short-term disturbances such as instantaneous shadow from small
156 clouds and birds, were excluded from the ground measured longwave radiation through a quality check. This quality check
157 involved removing the outgoing or incoming longwave radiation that deviated by more than 3σ (standard deviations) from
158 their respective one-hour averages (Göttsche et al., 2016).



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Figure1: The study area and the selected 19 ground sites. A, B, C, D, E, and F are subareas exhibited a single land cover type with no change in T1 and T2 (January 1 2000 to January 3 2005).

162

Table I: Details of the 19 selected ground sites and their measurements.

Site	Latitude and Longitude (°N, °E)	Elevation (m)	Radiometers	Height of radiometer (m)	Diameter of radiometer's FOV (m)	Surface type	Period	STD of 30-m Landsat LST (K)	Source
Arou (ARO)	38.05, 100.46	3033	CNR4	5	37.32	Subalpine meadow	2013–2021	0.68	HiWATER
Daman (DAM)	38.86, 100.37	1556	CNR1	12	89.57	Cropland	2013–2021	0.78	HiWATER
Desert (DET)	42.11, 100.99	1054	CNR4	6	44.78	Desert	2015–2021	0.65	HiWATER
Dashalong (DSL)	38.84, 98.94	3739	CNR4	6	44.78	Marsh alpine meadow	2013–2021	1.29	HiWATER
Ebao (EBA)	37.95, 100.92	3294	CNR1	6	44.78	Alpine Meadow	2013–2016	1.00	HiWATER
Gobi (GOB)	38.92, 100.31	1562	CNR1	6	44.78	Gobi	2013–2015	1.01	HiWATER
Huazhaizi (HZZ)	38.77, 100.32	1735	CNR1	6	44.78	Desert	2013–2021	0.82	HiWATER
Sidaoqiao (SDQ)	42.00, 101.14	873	CNR1	10	74.64	Tamarix	2013–2021	1.53	HiWATER
Shenshawo (SSW)	38.79, 100.49	1555	CNR1	6	44.78	Desert	2014–2015	1.45	HiWATER
Huailai (HLA)	40.35, 115.79	480	CNR4	5	37.32	Cropland	2013–2020	1.32	HBE
D105	33.06, 91.95	5039	CNR1	1.34	10.00	Subalpine meadow	2002–2004	1.29	CEOP-CAMP
Gaize (GAZ)	32.31, 84.06	4416	CNR1	1.49	11.12	Barren land	2002–2004	1.48	CEOP-CAMP
Guantao (GUT)	36.52, 115.13	30	CNR1	15.7	117.19	Cropland	2009–2010	0.71	HBE
Changbaishan (CBS)	42.40, 128.10	736	CNR1	6*	44.78	Mixed forest	2006	1.33	China Flux
Daxing (DXI)	39.62, 116.43	20	CNR1	28	208.99	Cropland	2008-2010	1.46	HBE
Dinghushan (DHS)	23.17, 112.53	300	CNR1	19*	141.82	Broad-leaved evergreen forest	2006	0.67	CERN
Maqu (MQU)	33.89, 102.14	3423	CNR1	1.5	11.20	Grassland	2010	1.20	NIEER-CAS
Qianyanzhou (QYZ)	26.74, 115.06	75	CNR1	1.8	13.44	Evergreen coniferous forest	2010	1.42	CERN
Tongyu (TYU)	44.42, 122.87	184	CG4	3	22.39	Cropland	2003–2004	0.64	CEOP-CAMP

Note: *this height is the instrument's average height above the tree canopy. The ground sites were operated by different field campaigns or programs. CERN: Chinese Ecosystem Research Network (Fu et al., 2010; Pastorello et al., 2020); CEOP-CAMP: the Coordinated Energy and Water Cycle Observation Project (CEOP) and Asia-Australia Monsoon Project (CAMP) (Ma et al., 2006; Liu et al., 2004); China Flux (Pastorello et al., 2020; Yu et al., 2014; Zhang and Han, 2016); HBE: Haihe experiment (Guo et al., 2020; Liu et al., 2013b); HiWATER: Heihe Watershed Allied Telemetry Experimental Research (Che et al., 2019; Li et al., 2013a; Liu et al., 2011, 2018); NIEER-CAS: Northwest Institute of Eco-Environment and Resources, Chinese Academy of Sciences (Wen et al., 2011).

170 3. Methodology

171 TRIMS LST is generated through the E-RTM method, consisting of three modules depicted in Fig.2. Module I runs the original
172 RTM method (Zhang et al., 2021) to merge MOD11A1 (MYD11A1) and GLDAS LST, producing daily all-weather LST at
173 the Terra (Aqua) satellite overpass time from DOY 55 of 2000 (DOY 185 of 2002) to DOY 365 of 2022. Module II employs
174 a Random-Forest based Spatio-Temporal Merging (RFSTM) approach to extend the beginning date of the MOD11A1 LST
175 based all-weather LST to January 1, 2000. Finally, Module III utilizes a Time-SEquential LST based Reconstruction (TSETR)
176 approach to extend the beginning date of the MYD11A1 LST based all-weather LST to January 1.

177 3.1 Module I: the RTM method

178 Details of the RTM method can be found in Zhang et al. (2021). For the convenience of readers, a brief description of RTM is
179 provided here. In the temporal dimension, the time series of LST can be expressed as:

$$180 \quad LST(t_d, t_{avg}, t_{ins}) = LFC(t_d, t_{avg}) + HFC(t_d, t_{avg}, t_{ins}) + HFC_{cld}(t_d, t_{ins}), \quad (1)$$

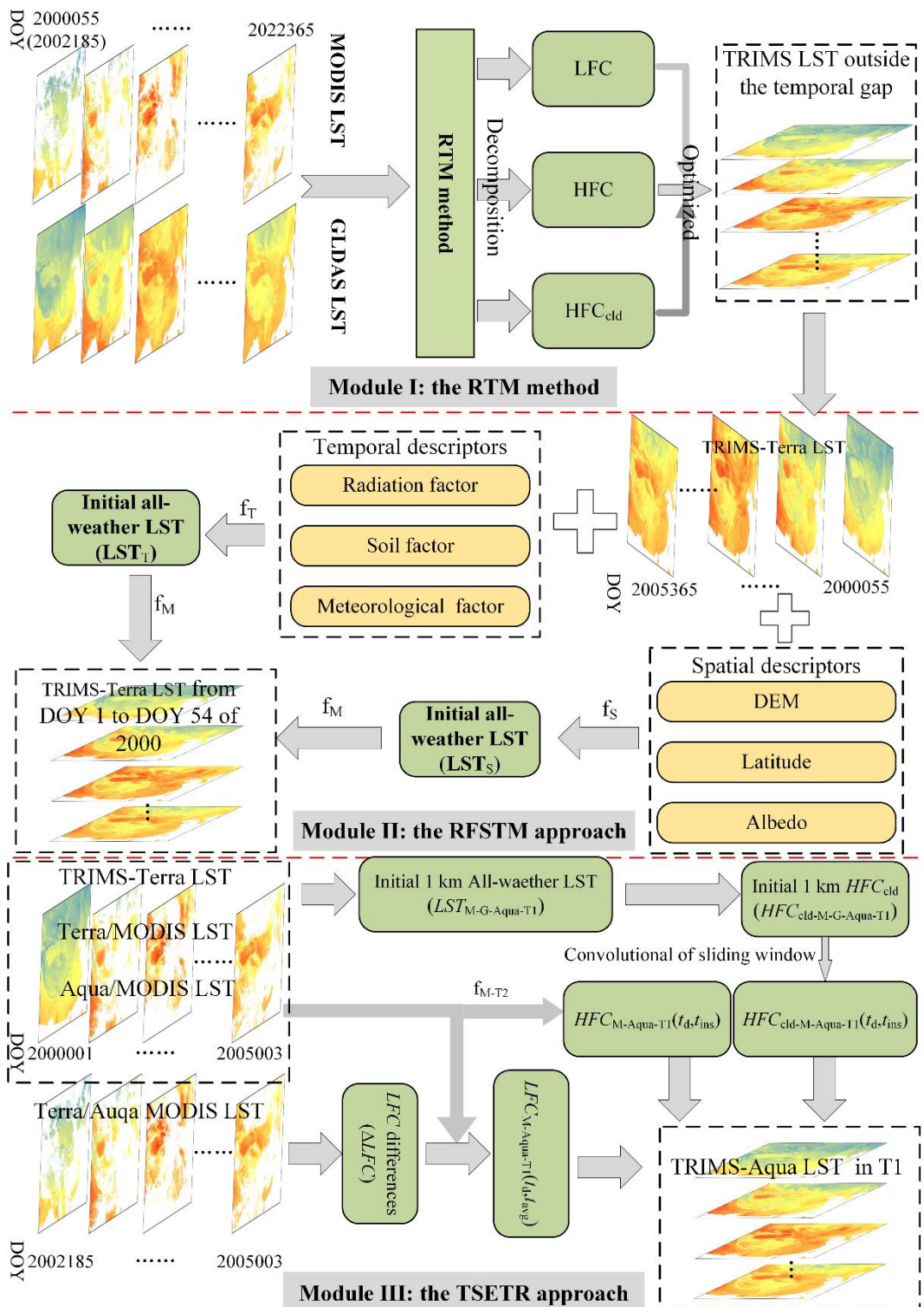
181 where t_d is the day of year (DOY); t_{ins} is overpass time of a satellite TIR sensor (i.e., MODIS) and t_{avg} is the average observation
182 time calculated from t_{ins} ; LFC is the low frequency component that represents the intra-annual variation component of the LST
183 under ideal clear-sky conditions; HFC is the high frequency component, which represents the sum of the diurnal LST variation
184 and the weather variation component (WTC) under ideal clear-sky conditions; HFC_{cld} is a correction term representing the
185 impact on LST triggered by cloud contamination under cloudy conditions; and HFC_{cld} is equal to zero under clear-sky
186 conditions.

187 In the RTM method, LFC , HFC , and HFC_{cld} in Eq.(1) are first determined from the MODIS LST and the GLDAS LST. Then,
188 the optimized models are determined for the three components according to their characteristics and their quality is improved
189 by inputting their descriptors. Finally, three optimized components are integrated to generate the all-weather LST.

190 3.2 Module II: the RFSTM approach

191 The RFSTM approach was developed to predict the all-weather LST during the period of DOY 1-54 2000 during which the
192 Terra/MODIS LST were not available. It is based on the fact that (i) the LST of a pixel in the temporal dimension is strongly
193 affected by the meteorological conditions as well as the underlying surface and (ii) the LST of many pixels at a certain time
194 are closely related to their underlying surfaces (Ma et al., 2021). Therefore, RFSTM has two stages, namely, the temporal stage
195 and the spatial stage.

196



197

198 **Figure 2: Flowchart of the E-RTM method. Note that the date in this figure is in the format of YYYY+DOY.**

199 In the temporal stage, the daily LST (\mathbf{LST}_T) of a pixel Q in a certain period are modelled as:

$$\begin{aligned}
 & \mathbf{LST}_T = f_T(\mathbf{X}_T) \\
 & \mathbf{X}_T = [\mathbf{P}_{T,1} \ \mathbf{P}_{T,2} \ \dots \ \mathbf{P}_{T,m}]^T, \\
 & = \begin{bmatrix} P_{T,1}(t_{d,1}) & P_{T,1}(t_{d,2}) & \dots & P_{T,1}(t_{d,n}) \\ P_{T,2}(t_{d,1}) & P_{T,2}(t_{d,2}) & \dots & P_{T,2}(t_{d,n}) \\ \dots & \dots & \dots & \dots \\ P_{T,m}(t_{d,1}) & P_{T,m}(t_{d,2}) & \dots & P_{T,m}(t_{d,n}) \end{bmatrix}
 \end{aligned} \tag{2}$$

201 where the subscript T denotes the temporal stage; the function f_T expresses the mapping in temporal dimensions from
 202 descriptors to LST; \mathbf{X}_T denotes the matrix including LST descriptors' time series ($\mathbf{P}_{T,i}$, $i=1, 2, \dots, m$); and n is the number of
 203 days within the temporal gap of Terra MODIS LST.

204 Since the MODIS LST is not available as a reference for reconstruction and it is impossible to identify the different weather
 205 conditions (e.g., clear-sky and cloudy conditions), we used the mapping function f_T to predict the 1-km all-weather LST.
 206 However, the relationship between LST and its descriptors cannot be analytically expressed currently. Fortunately, the machine
 207 learning has been reported to be effective in enhancing the spatial resolution of remote sensing images. Specifically, the random
 208 forest (RF) algorithm has shown good performance in mapping the correlation between LST with finer resolution and its
 209 descriptors with coarser resolution (Xiao et al., 2023; Li et al., 2021a; Xu et al., 2021; Zhao and Duan, 2020; Yoo et al., 2020).
 210 Therefore, the RF algorithm was employed here to realize f_T . The temporal descriptors of LST include net longwave radiation,
 211 downward longwave flux, soil moisture profile (e.g., surface, 0–10 cm, and 10–40 cm in GLDAS NOAH model-based data),
 212 wind-speed, soil temperature profile (e.g., surface, 0–10 cm, and 10–40 cm in GLDAS NOAH-model based data), air
 213 temperature, and land surface albedo. The training period for f_T with RF was set as DOY 55 of 2000 to DOY 55 of 2005, and
 214 the prediction period for \mathbf{LST}_T was from DOY 1 of 2000 to DOY 54 of 2000.

215 Considering that LST varies in both temporal and spatial dimensions, the spatial descriptors of LST should also be considered.
 216 In the spatial stage, the LST (\mathbf{LST}_S) at t_d in the prediction period are expressed as:

$$\mathbf{LST}_S = f_S[N_{S,1}(t_d) \ N_{S,2}(t_d) \ \dots \ N_{S,k}(t_d)], \tag{3}$$

218 where the subscript S denotes the spatial stage; the function f_S expresses the mapping in spatial dimensions from the descriptors
 219 to LST; k is the number of spatial descriptors of LST; and N_S denotes the 1-km spatial descriptor of LST ($N_{S,i}$, $i=1, 2, \dots, k$).

220 The spatial descriptors of LST include the DEM, latitude, and albedo. **The selected descriptors in the spatial stage are all from**
 221 **the ancillary data with a 1-km resolution. Albedo serves as a descriptor that informs about land surface, including factors such**
 222 **as vegetation growth, surface/sub-surface moisture distribution, and land surface cover type.**

223 To involve all spatio-temporal LST descriptors and guarantee the best performance of the output, the LST (\mathbf{LST}_T and \mathbf{LST}_S)
 224 need to be merged together to derive the final 1-km LST (\mathbf{LST}_M):

$$\mathbf{LST}_M = f_M(\mathbf{LST}_T, \mathbf{LST}_S), \tag{4}$$

226 where f_M denotes the RF-based mapping which indicates the contributions to the \mathbf{LST}_M from \mathbf{LST}_T and \mathbf{LST}_S , respectively.

227 For a single 1-km pixel, the RF-based regression contribution function is trained using LST_T (obtained by Eq. 2), LST_S
 228 (obtained by Eq. 3) and TRIMS LST in the training period. Then, f_c is applied to estimate the 1-km all-weather LST in the
 229 prediction period via Eq. (4).

230 3.3 Module III: the TSETR approach

231 The TSETR approach was developed to estimate the all-weather LST during the period from DOY 1 of 2000 to DOY 184 of
 232 2002 during which the Aqua/MODIS LSTs were not available (with a temporal gap of 915 days). Previous studies have shown
 233 that it is possible to convert between the Terra MODIS LST and Aqua MODIS LST, considering land cover types, geolocation,
 234 and season (Coops et al., 2007). Therefore, Terra/MODIS LST from 2000-2002 could be transformed to Aqua/MODIS LST
 235 (Li et al., 2018). Since the Terra/MODIS LST (MOD11A1) is available as a reference in the temporal gap, we generated an
 236 all-weather LST based on the TSETR approach, which is reconstruction rather than prediction.

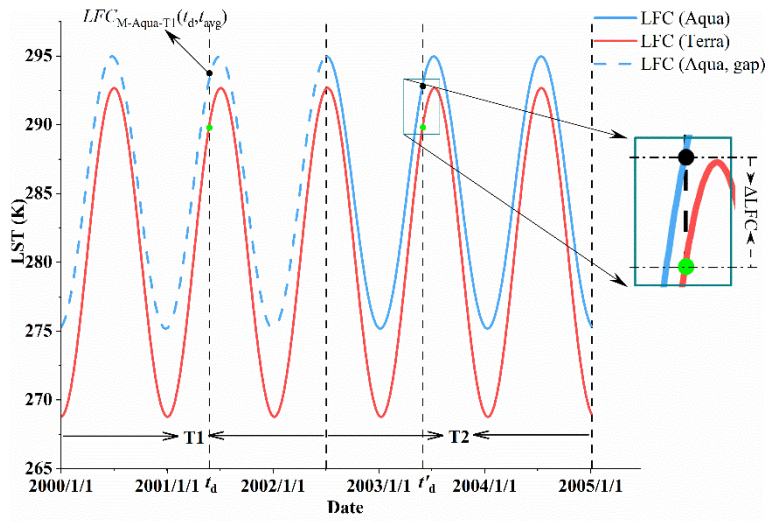
237 According to Eq. (1), the LST time series can be decomposed into LFC , HFC , and HFC_{cid} under all-weather conditions.
 238 Therefore, the TSETR approach has three stages. In the first stage, we need to estimate the LFC during the temporal gap at the
 239 Aqua overpass time. In this case, the temporal gap period was set as T1, and DOY 185 of 2002 to DOY 3 of 2005 was set as
 240 T2 (Fig.3). According to the analytical expression and physical meaning of LFC , there is no underlying trends of change within
 241 the three annual parameters (T_{avg} , A and ω) except for the periodic variation in the LST, which means that the LFC is cyclic-
 242 stationary over a short time period (Bechtel, 2015; Weng and Fu, 2014; Zhu et al., 2022). Once the three annual parameters
 243 are determined, the LFC can be calculated for a given day.

244 Therefore, in the TSETR approach, we assume that the LFC differences (ΔLFC) between the Terra and Aqua overpass times
 245 in T1 and T2 are also cyclic-stationary. In T2, the LFC at the Terra/MODIS and Aqua/MODIS pixels are determined separately.

246 In T1, the LFC at the Aqua overpass time of the pixel M can be expressed as:

$$247 \begin{cases} LFC_{M-Aqua-T1}(t_d, t_{avg}) = LFC_{M-Terra-T1}(t_d, t_{avg}) + \Delta LFC_M(t'_d, t_{avg}) \\ \Delta LFC_M(t'_d, t_{avg}) = LFC_{M-Aqua-T2}(t'_d, t_{avg}) - LFC_{M-Terra-T2}(t'_d, t_{avg}) \end{cases} \quad (5)$$

248 where t_d is a specific day in T1; t'_d is a specific day corresponding to t_d in T2; $LFC_{M-Aqua-T1}(t_d, t_{avg})$ and $LFC_{M-Terra-T1}(t_d, t_{avg})$
 249 denote the LFC corresponding to the Aqua/Terra overpass time in T1, respectively; and $LFC_{M-Aqua-T2}(t'_d, t_{avg})$ and $LFC_{M-Terra-}$
 250 $T2}(t'_d, t_{avg})$ denote the LFC corresponding to the Aqua and Terra overpass time in T2, respectively.



251
252 **Figure 3: Schematic diagram for estimating LFC at daytime Aqua overpass time in T1.**

253 *HFC* is estimated in the original RTM method using a nonlinear mapping established by multiple descriptors. In the second
254 stage of E-RTM, the *HFC* within T1 at the Aqua overpass time can be estimated by using its descriptors through RF (Xu et
255 al., 2021). With Module I and Module II, we have obtained TRIMS-Terra LST in T1. However, it is unfeasible to directly
256 model an RF mapping based on Terra MODIS data and its corresponding descriptors in T1. An important concern that needs
257 to be addressed is the timing discrepancy between Terra and Aqua observations, which results in distinct variations in the
258 pattern of LST changes. When there is no valid Aqua LST available, we have made improvements to the procedure for
259 calculating the *HFC* in the original RTM method as follows:

$$260 \begin{cases} HFC_{M-Aqua-T1}(t_d, t_{ins-Aqua-T1}) = HFC_{M-Terra-T1}(t_d, t_{ins-Terra-T1}) + \Delta HFC_{M-Terra-Aqua-T1} \\ \Delta HFC_{M-Terra-Aqua-T1}(t_d, t_{ins}) = f_{M-T2}(g_M, DEM_M, NDVI_M(t_d), slp_M(t_d), \alpha_M(t_d), v_M(t_d), \Delta LFC_M, \Delta DTC_M) \\ \Delta DTC_M = \Delta DTC_{M-Aqua}(t_d, t_{ins}, t_{avg}) - \Delta DTC_{M-Terra}(t_d, t_{ins}, t_{avg}) \end{cases} \quad (6)$$

261 where ΔLFC characterizes the systematic deviation of the steady state component; g_M is geo-spatial code (Yang et al., 2022);
262 DEM_M , $NDVI_M$, slp_M , α_M , Δt_M and v_M are the latitude, longitude, DEM, NDVI, slope, albedo, difference between t_{ins} and t_{avg} ,
263 and the atmospheric water vapour content, respectively; ΔDTC characterizes the warming effect of solar radiation, and the
264 weather effect can be characterized by the atmospheric water vapor content. According to Zhang et al. (2021), the *HFC*
265 characterizes the change in LFC with ΔDTC and WTC superimposed under ideal clear-sky conditions. The detailed calculation
266 of ΔDTC can be found in Zhang et al. (2019).

267 The f_{M-T2} is constructed as follows. Initially, the correlation image of the target pixel M is determined within the T2 time period
268 and the following two conditions need to be satisfied by the correlation image: (i) the mean bias deviation (MBD) of the DTC
269 estimated from its corresponding GLDAS LST (10:00-14:00 and 21:00-3:00 local solar time) should be lower than 1 K, and
270 (ii) the difference in the average observation time between the GLDAS pixels should not exceed 0.5 h. Using the correlation

271 image, the similar image family S of the target pixel M is determined. Subsequently, in the correlation image, using similar
 272 land surface type criteria, the similar image family S of the target pixel M within the GLDAS pixels is identified. S needs to
 273 meet the following two conditions: (i) it should have the same surface type as M and (ii) the R of the Terra-MODIS LST time
 274 series corresponding to S and M need to be greater than 0.8.

275 In the third stage, we need to estimate the HFC_{cld} within the temporal gap period at the Aqua overpass time. In fact, HFC_{cld} is
 276 essentially an atmospheric correction term and it is obtained from the GLDAS LST in the RTM method. According to the
 277 parameterization scheme of the RTM method, the clear-sky MODIS pixels and their corresponding GLDAS LST are the
 278 necessary inputs for the estimation of HFC_{cld} . It is not possible to obtain HFC_{cld} directly in this stage due to the lack of
 279 Aqua/MODIS in T1.

280 Inspired by the Temporal Component Decomposition (TCD) method (Zhang et al., 2019b) and other methods integrating
 281 PMW and TIR LST (Parinussa et al., 2016; Zhang et al., 2020), the initial value of the 1-km HFC_{cld} can be expressed as:

$$282 \quad HFC_{\text{cld-M-G-Aqua-T1}}(t_d, t_{\text{ins}}) = LST_{\text{M-G-Aqua-T1}}(t_d, t_{\text{ins}}) - LFC_{\text{M-Aqua-T1}}(t_d, t_{\text{avg}}) - HFC_{\text{M-Aqua-T1}}(t_d, t_{\text{ins}}), \quad (7)$$

283 where $HFC_{\text{cld-M-G-Aqua-T1}}$ is the initial 1-km HFC_{cld} of M ; and $LST_{\text{M-G-Aqua-T1}}$ is the initial 1-km LST of M under all-weather
 284 conditions.

285 Based on the findings of Yao et al. (2023), we established the method for acquiring the initial 1-km all-weather LST. Initially,
 286 the GLDAS LST that corresponded to the Aqua overpass time are corrected for systematic bias using the cumulative
 287 distribution function matching (Xu and Cheng., 2021). In T1 time period, since Aqua LST is unavailable, we employ MODIS
 288 LST from 2003-2022 to guarantee an adequately large sample size of MODIS LST. We then downscaled the GLDAS LST to
 289 1 km through the following two steps.

290 (i) Calculating the LST differences between the MODIS and GLDAS:

$$291 \quad \begin{cases} \Delta LST_{\text{M-G-Aqua-T1}}(t_d, t_{\text{ins}}) = LST_{\text{G-Aqua-T1}}(t_d, t_{\text{ins}}) - LST_{\text{M-Aqua-T1}}(t_d, t_{\text{ins}}) \\ LST_{\text{M-Aqua-T1}}(t_d, t_{\text{ins}}) = LFC_{\text{M-Aqua-T1}}(t_d, t_{\text{ins}}) + HFC_{\text{M-Aqua-T1}}(t_d, t_{\text{ins}}) \end{cases}, \quad (8)$$

292 where $LST_{\text{G-Aqua-T1}}$ is GLDAS LST; $LST_{\text{M-Aqua-T1}}$ is ideal MODIS clear-sky LST. $LST_{\text{M-G-Aqua-T1}}$ is LST difference image. One
 293 pixel in GLDAS LST corresponds to 625 (25×25) pixels in MODIS LST. The LST differences are calculated as GLDAS
 294 LST minus 625-pixel average MODIS LST. LST difference image was then directly resampled to 1 km.

295 (ii) Downscaling of GLDAS LST:

$$296 \quad LST_{\text{M-G-Aqua-T1}}(t_d, t_{\text{ins}}) = \Delta LST_{\text{M-G-Aqua-T1}}(t_d, t_{\text{ins}}) + LST_{\text{M-Aqua-T1}}(t_d, t_{\text{ins}}), \quad (9)$$

297 where $LST_{\text{M-G-Aqua-T1}}$ is the initial 1-km downscaled GLDAS LST. The heterogeneity of the underlying land surface within a
 298 0.25° grid is reflected by MODIS LST, and the downscaled GLDAS LST also exhibits the same characteristic. This is based
 299 on the hypothesis that the spatial variations in MODIS LST is the same as that of GLDAS LST. However, $LST_{\text{M-G-Aqua}}$ and
 300 $HFC_{\text{cld-M-G-Aqua-T1}}$ in the results of Eq. (9) may still contain systematic errors due to inadequate downscaling (Eq. 8). Therefore,
 301 a convolutional implementation of a sliding window was used here to reduce the systematic error contained in $HFC_{\text{cld-M-G-Aqua-}}$
 302 T_1 (Chen et al., 2011; Wu et al., 2015; Zhang et al., 2019b).

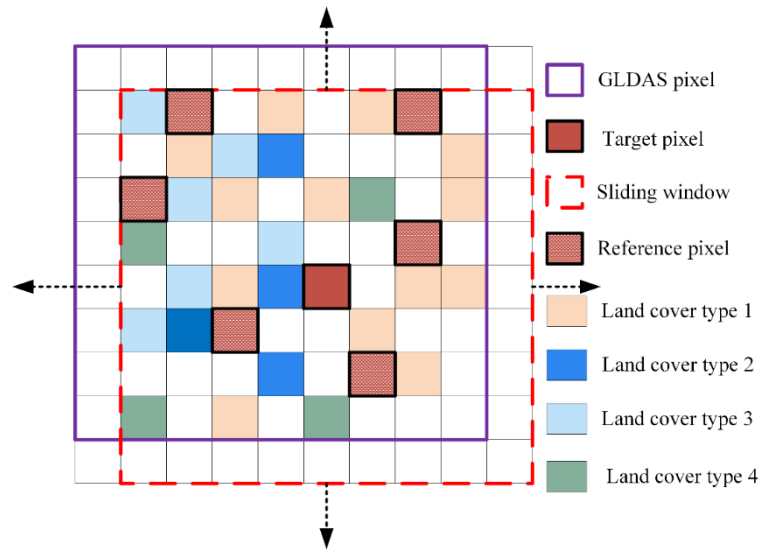
303 The schematic diagram of the convolutional implementation of the sliding window is shown in Fig.4. To fully reduce the
 304 systematic bias, the size of the sliding window should be slightly larger than a GLDAS pixel ($26 \times 26 \text{ km}^2$). According to
 305 Zhang et al. (2019, 2021), HFC_{cld} after optimization of M (i.e., HFC_{cld} after eliminating the systematic errors) can be obtained
 306 by convolving the HFC_{cld} of the surrounding similar pixels by combining geological factors (e.g., land surface type, spatial
 307 distance, and topography). This method is based on the interrelationship of different LST: neighbouring HFC_{cld} are correlated
 308 in a limited spatial domain. Previous studies have shown that the approaches analogous to the convolutional implementation
 309 of sliding windows have a good ability to improve both the accuracy and the image quality of the merged LST (Ding et al.,
 310 2022; Long et al., 2020; Zhang et al., 2019b). Similar pixels (termed as S) need to meet the following criteria: (i) they are
 311 within the same sliding window as the target pixel, and (ii) their land cover type does not differ from the target pixel. Therefore,
 312 the target pixel itself is also a reference pixel. Eventually, the HFC_{cld} of target pixel can be expressed as:

$$313 \quad HFC_{\text{cld-M-Aqua-T1}}(t_d, t_{\text{ins}}) = \sum_{i=1}^n HFC_{\text{cld-S}_i}(t_d, t_{\text{ins}}) \cdot w_{S_i}, \quad (10)$$

314 where n is the number of similar pixels; $HFC_{\text{cld-S}}$ denotes $HFC_{\text{cld-M-Aqua-T1}}$ of the similar pixels; and w_s is the contribution of
 315 similar pixels to M, which can be expressed as:

$$316 \quad \begin{cases} w_{S_i} = D_{S_i} \cdot H_{S_i} \cdot N_{S_i} / \left(\sum_n D_{S_i} \cdot H_{S_i} \cdot N_{S_i} \right) \\ D_{S_i} = (1/d_{S_i}) / \sum_{i=1}^n 1/d_{S_i} \\ d_{S_i} = \sqrt{(x_{S_n} - x_M)^2 + (y_{S_n} - y_M)^2} \\ H_{S_i} = |DEM_{S_i} - DEM_M| \\ N_{S_i} = |NDVI_{S_i} - NDVI_M| \end{cases}, \quad (11)$$

317 where D_s , H_s and N_s are the differences between the similar pixels and M in terms of the spatial distance, DEM and NDVI,
 318 respectively.



319

320 **Figure 4: Schematic of the HFC_{Std} convolutional optimization.**

321 **3.4 Implementation of E-RTM**

322 A detailed description of the implementation process of the RTM method is provided by Zhang et al. (2021) and is not repeated
 323 here. The implementation process of Module II and Module III is explained in this section.

324 **Stage I: Data preprocessing and spatiotemporal matching**

325 In this stage, the data are preprocessed and spatiotemporal matching. First, valid MODIS LST are selected with the following
 326 two standards: (i) the quality control of the pixel was flagged as “good” and (ii) the view angle of the pixel was lower than
 327 60° . Second, the selected temporal descriptors from GLDAS data were temporally interpolated using the cubic spline function
 328 to observation time of MODIS LST for the purpose of temporal-matching. Third, the observation times for cloudy pixels and
 329 temporal gaps were recovered using a 16-day revisiting period. Fourth, the 90-m DEM, 500-m albedo, and 500-m NDSI were
 330 upscale to 1-km to match the MODIS LST. Fifth, the GLDAS water vapor were extended to 1 km by cubic convolution
 331 interpolation. During the temporal gap (DOY 1–54 2000), SPOT VGT served as the NDVI, GLASS albedo was extended to a
 332 1 km resolution using cubic convolution interpolation, and the NDSI was determined by taking the average of the
 333 corresponding days in 2001 and 2002. The 16-day 1-km NDVI are temporally interpolated to daily resolution. The daily
 334 missing albedo caused by cloud-coverage are filled up through Statistics-based Temporal Filter (Liu et al., 2013a). In addition,
 335 all data are spatially matched.

336 **Stage II: Implementation of the RFSTM**

337 (1) For a single 1-km pixel, training the RF regression relationship (i.e., f_r) between TRIMS-Terra LST and the temporal
 338 descriptors from GLDAS data via Eq. (2). The RF parameters were set as follows: n estimators=420, max depth=43, max
 339 features=9, and min samples leaf=1. In the temporal stage of RFSTM, all-weather samples from 2000 to 2005 were compiled.
 340 Two-thirds of the samples are used for model training and the remaining are for model validation (Breiman, 2001).

341 (2) For a specific day (t_d), using the 1-km NDVI (Sobrino et al.,2004) and NDSI to classify the study area into several subareas,
342 including thick vegetation ($NDVI>0.5$), sparse vegetation ($0.2\leq NDVI\leq 0.5$), barren land areas ($NDVI<0.2$), and snow-ice areas
343 ($NDSI>0.1$) (Zhang et al., 2019a) and water ($NDVI<0$). Then, for each subarea, the spatial descriptors of LST are input into
344 f_s via Eq. (3). Note that f_s with RF is trained with the 1-km LST and spatial descriptors of a day, with the same observation
345 time as t_d and the smallest difference in the number of days between t_d .

346 (3) For a single 1-km pixel, train the RF-based regression contribution function (i.e., f_M in Eq. 4) using LST_T , LST_s , and
347 TRIMS-Aqua LST under clear-sky conditions. Then, estimate the 1-km TRIMS-Aqua LST during the period of DOY 1-54
348 2000 by applying f_M to clear-sky and cloudy conditions, respectively.

349 **Stage III: Implementation of the TSETR**

350 1) For a single Aqua-MODIS pixel M in T1, determine its LFC in Eq.(5) using Aqua-MODIS LST (T2) and Terra-MODIS
351 LST(T1 and T2).

352 2) Train the RF measuring (f_{M-T2}) between all of ΔHFC and its descriptors (see section 3.3) of all similar pixels. The RF
353 measuring function tools are also provided by the MATLAB platform. The RF parameters were set as follows: n estimators =
354 100, max depth = 20, max feature = 4, min samples leaf = 1. Determine the reconstructed HFC of M through Eq. (6) by
355 applying the descriptors of HFC in M to f_{M-T2} .

356 3) Implement the bias correction for GLDAS LST of the target GLDAS grid by using cumulative distribution function
357 matching. Then, downscale the GLDAS LST to 1 km through Eqs.(8) and (9).

358 4) Determine the initial 1-km HFC_{clid} of M through Eq.(7).Finally, determine the HFC_{clid} of M through Eqs.(10) and (11).

359 **3.5 Evaluation strategies**

360 As can be seen from Fig. 2, TRIMS LST can be divided into two parts according to the period of data coverage: data within
361 the temporal gap period and data outside the temporal gap period. There are differences in the evaluation strategies within the
362 two periods due to the different availability of validation data.

363 For outside the temporal gap period, the TRIMS LST was compared with LSTs derived from two reanalysis datasets (i.e.,
364 GLDAS and the independent ERA5-Land) and retrievals from two different satellite TIR sensor (i.e., MODIS and the
365 independent AATSR). In comparing different LSTs, samples with time differences greater than five minutes were excluded
366 (Freitas et al., 2010; Göttsche et al., 2016; Jiang and Liu, 2014). The quantitative metrics used in comparison analyses include
367 the MBD, STD of bias, and coefficient of determination (R^2). Then, the TRIMS LST was validated under different weather
368 conditions based on *in-situ* LST from the ground sites listed in Table I. The three metrics used the mean bias error (MBE),
369 root-mean-square-error (RMSE), and R^2 .

370 During the temporal gap period, the TRIMS LST was tested using two methods. Firstly, the results of the original RTM method
371 were cross-referenced and validated empirically with RFSTM and TSETR. In 2003, RFSTM was utilized to merged GLDAS
372 and Terra MODIS data, resulting in a 1-km all-weather LST. Additionally, the TSETR method was employed to generate
373 TRIMS-Aqua LST for the periods of 2003–2005 and 2013–2015. For the actual data generated for the period 2000-2002,

374 specifically Aqua LST, the similarity of the TRIMS LST time series was quantified to examine the reliability of TRIMS LST
375 during the Aqua/MODIS temporal gap. The time series angle (TSA), inspired by the spectral angle that is widely used to
376 measure the similarity between spectral curves (Kruse et al., 1993), was used to quantify the similarity of TRIMS LST time
377 series. The TSA is defined as:

$$378 \quad \theta = \cos^{-1} \frac{\mathbf{LST}_{\text{TRIMS-Aqua}} \cdot \mathbf{LST}_{\text{TRIMS-Terra}}}{\|\mathbf{LST}_{\text{TRIMS-Aqua}}\| \cdot \|\mathbf{LST}_{\text{TRIMS-Terra}}\|}, \quad (12)$$

379 where θ is the TSA (unit: degree); $\mathbf{LST}_{\text{TRIMS-Aqua}}$ and $\mathbf{LST}_{\text{TRIMS-Terra}}$ are time series of TRIMS-Aqua and TRIMS-Terra LSTs,
380 respectively. From this formula, we know that smaller TSA denotes higher similarity.

381 Based on the CLCD described in Section 2.1, six subareas with a single land cover type and no land cover change in T1 and
382 T2 (January 1 2000 to January 3 2005) were selected to extract the corresponding TRIMS-Terra and TRIMS-Aqua LST time
383 series. These six subareas (Fig.1) were recorded as A (82.30°N–83.16°N, 39.63°E–40.03°E, barren land), B (124.73°N–
384 125.17°N, 51.51°E–51.95°E, forest), C (111.84°N–112.30°N, 42.47°E–42.85°E, grassland), D (100.78°N–101.53°N, 39.92°E
385 –40.44°E, barren land), E (98.14°N–98.61°N, 33.92°E–34.25°E, grassland), and F (91.73°N–92.22°N, 31.7°E–32.01°E,
386 grassland). Then, the TSA was calculated to quantify the similarity between the TRIMS-Terra and TRIMS-Aqua LST time
387 series.

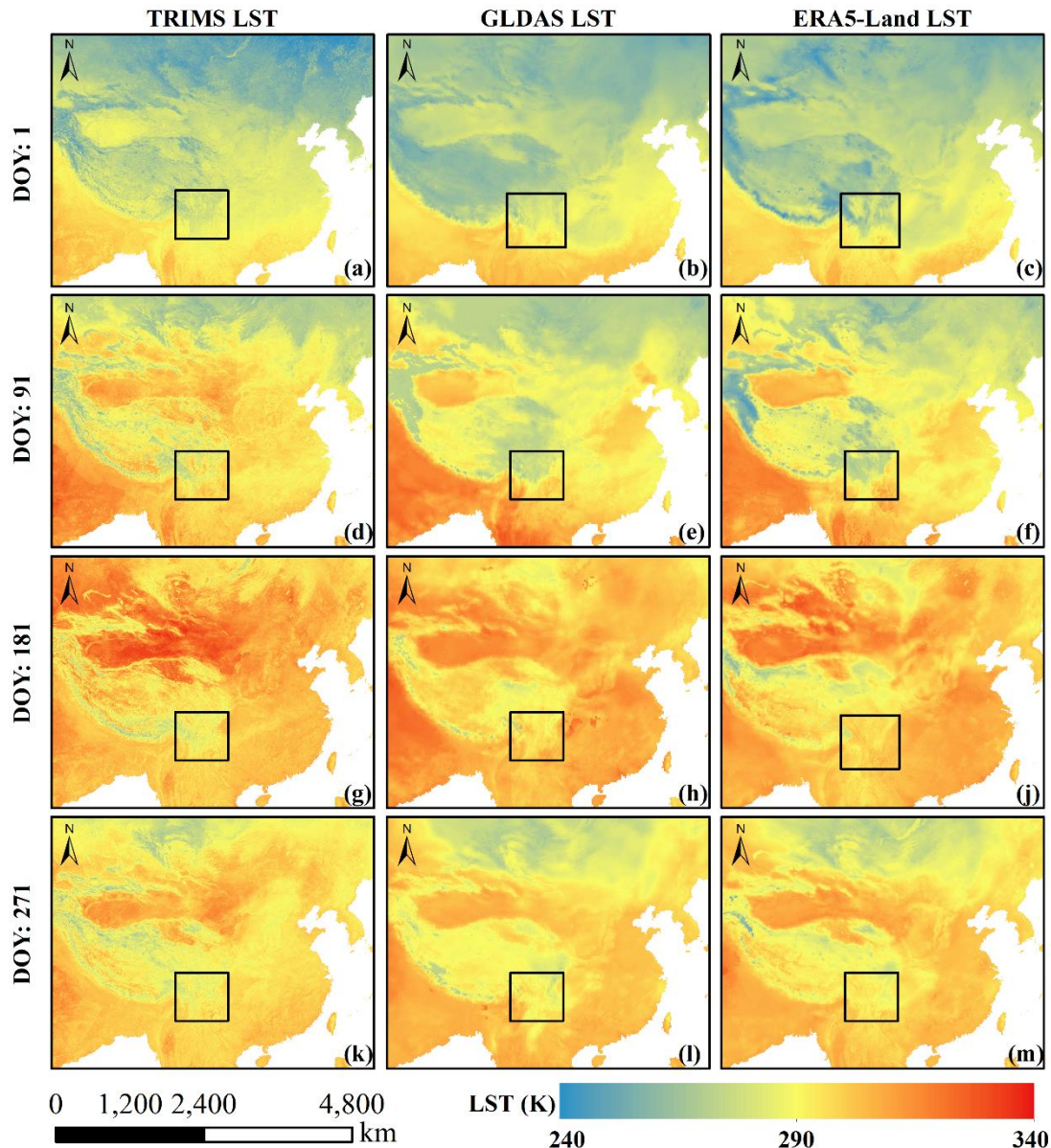
388 4. Results and discussion

389 4.1 Comparison of the TRIMS LST with reanalysis data

390 With the E-RTM method, TRIMS LST products from January 1 2000 to December 31 2022 were generated. The spatial
391 resolution was 1 km. The temporal resolution was four observations per day, which is the same as the overpass time of
392 Terra/MODIS and Aqua/MODIS. Fig. 5 shows the daytime TRIMS-Aqua LST on DOY 1, 91, 181, and 271 as examples.

393 Fig. 5 shows that the TRIMS-Aqua LST has a similar spatial pattern as the GLDAS LST since the latter is an input for the
394 former. Good agreement in the spatial pattern in different seasons can also be observed between TRIMS-Aqua LST and the
395 independent ERA5-Land LST. A careful observation of Fig.4 demonstrates that the TRIMS LST is spatially seamless and its
396 spatial patterns are as expected. Southern China as well as southeast Asia and the south Asian subcontinent in low latitudes
397 are warm in all seasons because of additional absorbed solar radiation. The Tibetan Plateau, with much higher elevation and
398 the regions in high latitudes is much cooler than other regions. In spring (DOY 1), summer (DOY 181), and autumn (DOY
399 271), northwestern China, where the dominant land cover type is barren land, is much warmer than other regions. Further
400 comparison indicates that TRIMS LST is generally slightly warmer than the GLDAS LST and the ERA5-Land LST. For
401 example, on DOY 1 of 2000, the LST are generally below 278 K in the eastern Tibetan Plateau, while the GLDAS LST and
402 the ERA5-Land LST are approximately 3–5 K lower. In the generation scheme of the TRIMS LST, the MODIS LST, which

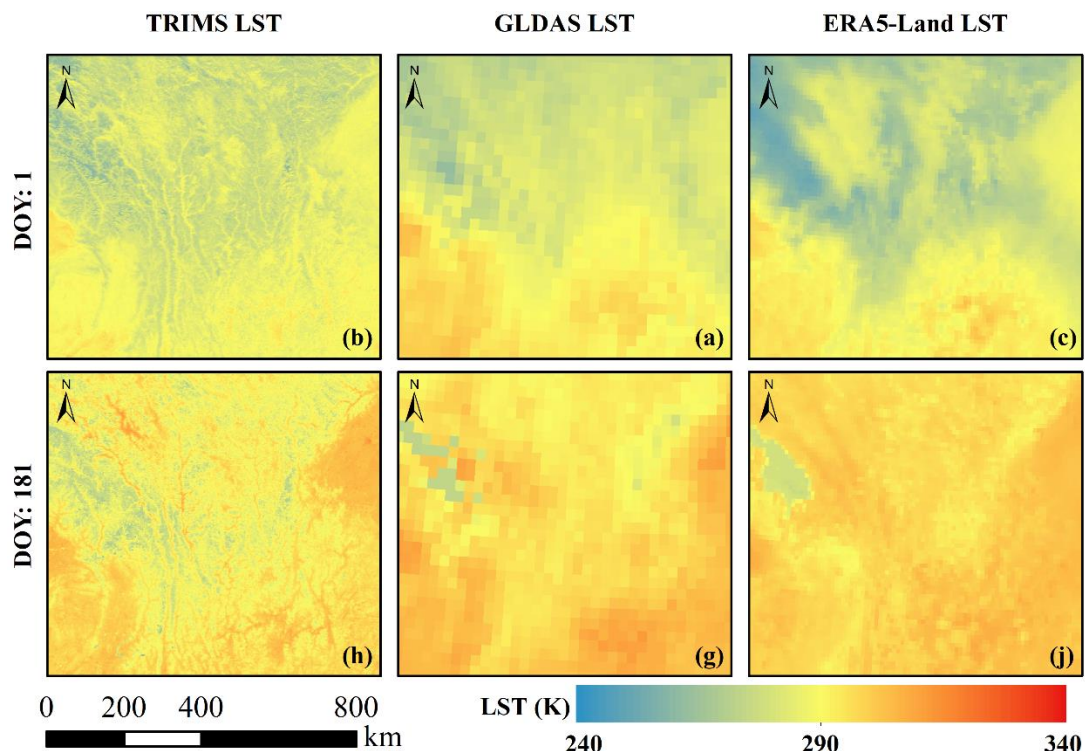
403 is generally warmer than the LST provided by reanalysis data, is an important input as well as a reference to ‘calibrate’ the
 404 GLDAS LST. This induces the ‘merged’ TRIMS LST to be warmer than the GLDAS LST as well as the ERA5-Land LST.
 405
 406



407
 408 **Figure 5: Spatial patterns of the daytime TRIMS-Aqua LST, GLDAS LST, and ERA5-Land LST on four selected days in 2000.**

409 To further examine the image quality of the TRIMS-Aqua LST, Fig. 6 shows the daytime TRIMS-Aqua LST, GLDAS LST,
 410 and ERA5-Land LST of the subarea shown in Fig. 5 at the Aqua overpass time in 2000. Compared with the GLDAS LST and
 411 the ERA5-Land LST, the TRIMS LST offers more spatial details because of its much higher spatial resolution. Thus, one can

412 see clear terrain-induced temperature variations. Furthermore, Fig. 6 shows that no evident spatial discontinuities exist in the
413 TRIMS LST, indicating the E-RTM method performs satisfactorily in addressing the spatial scale mismatch between the
414 MODIS LST and GLDAS LST (Zhang et al., 2021).

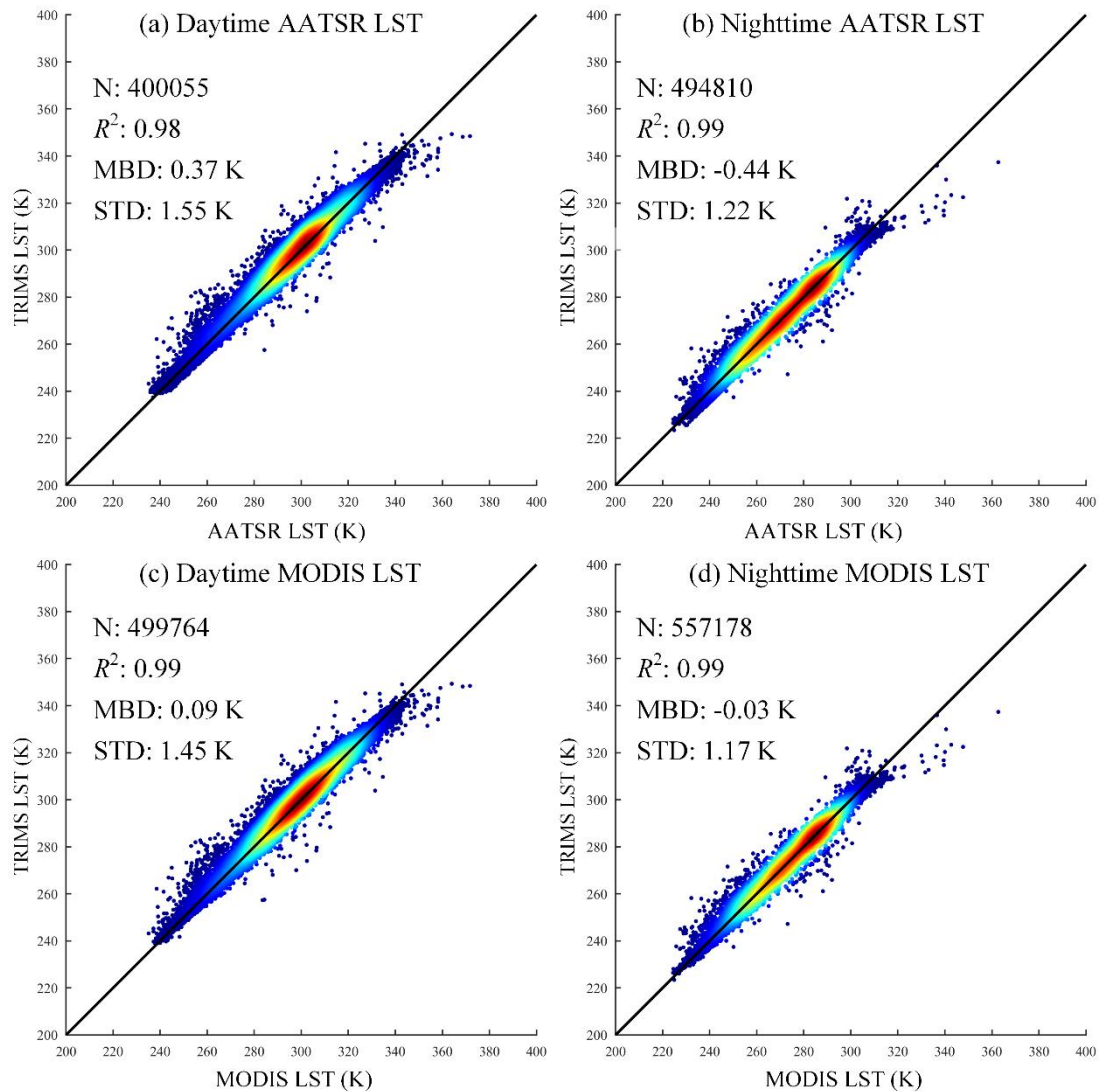


415 **Figure 6: The daytime TRIMS-Aqua LST, GLDAS LST, and ERA5-Land LST of the subarea (shown in Fig.5) in 2000.**
416

417 4.2 Comparison of the TRIMS LST with satellite TIR LST products

418 The daily TRIMS LST was compared with the independent ENVISAT/AATSR LST (from 2004 to 2012) and the Terra/Aqua
419 MODIS LST (from 2000 to 2021 for Terra and from 2002 to 2021 for Aqua). Note that the AATSR and MODIS only have
420 clear-sky LST. The density plots are shown in Fig.7. To facilitate the data processing and presentation, 1%/1‰ matched
421 TRIMS-AATSR/MODIS pairs were randomly extracted. Fig. 7 indicates good consistency between the TRIMS LST and
422 AATSR/MODIS LST. Compared with AATSR, the overall MBD/STD values of TRIMS were 0.37 K/1.55 K and -0.44 K/1.22
423 K for daytime and nighttime, respectively; compared with MODIS, the overall MBD/STD values were 0.09 K/1.45 K and -
424 0.03 K/1.17 K for daytime and nighttime, respectively. Fig. 7 also shows that better agreements exist during nighttime because
425 of lower thermal heterogeneity.

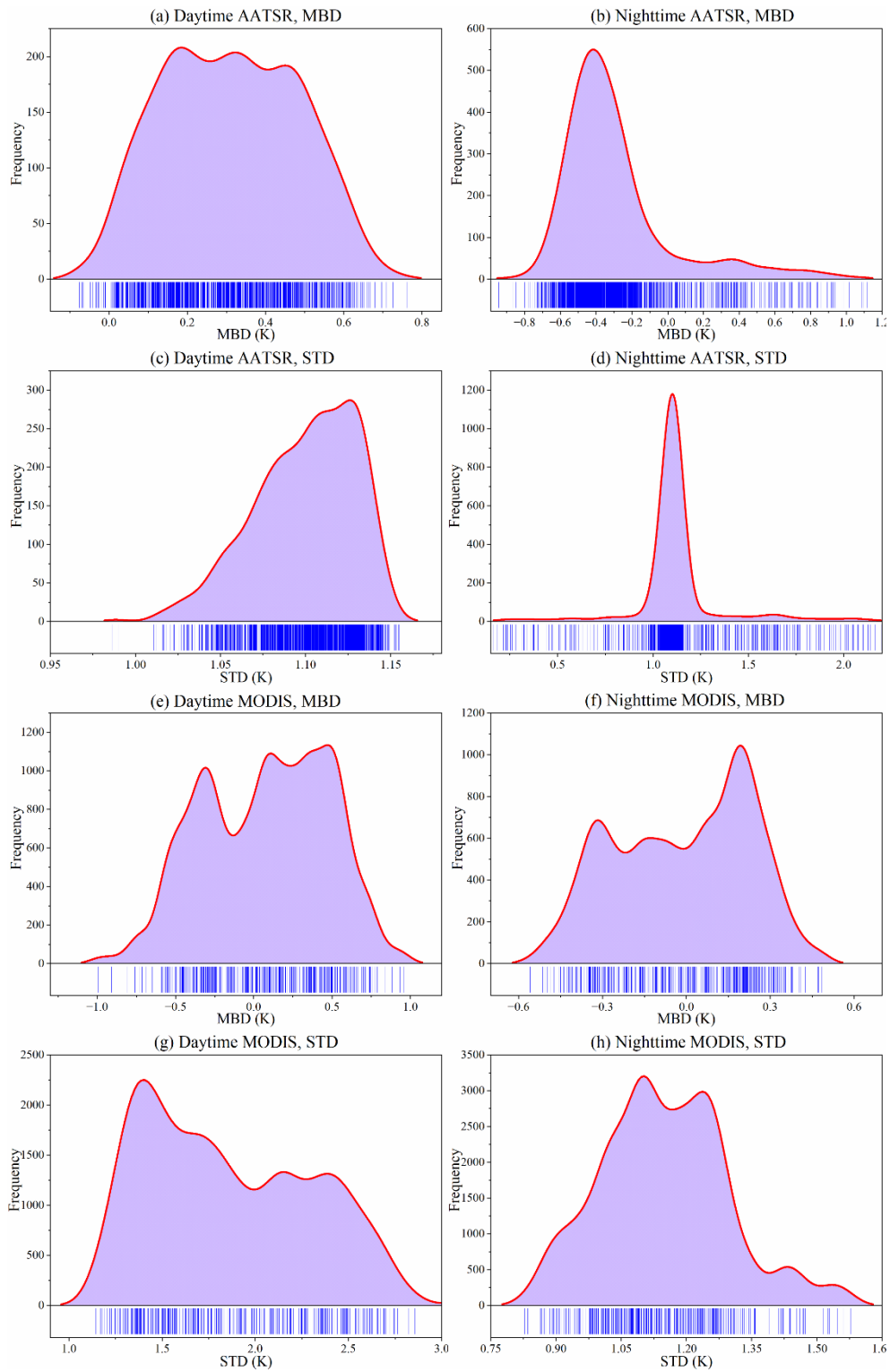
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427

428 **Figure 7: Density plots between the TRIMS LST and the AATSR/MODIS LST.**

429 To further examine the deviation of the TRIMS LST from the AATSR/MODIS LST, the MBD and STD values were calculated
 430 for each day. Fig. 8 shows the corresponding histograms. For AATSR, the daily daytime MBD and STD were mainly
 431 concentrated in the ranges of 0 K–0.60 K and 1.05 K–1.15 K, respectively; the daily nighttime MBD and STD were mainly
 432 concentrated in the ranges of -0.40 K to 1.0 K and 0.75 K to 1.15 K, respectively. The positive deviation and negative deviation
 433 were consistent with those in Fig.8 (a) and Fig.8 (b). For the MODIS case, the daytime MBD was concentrated between -0.6
 434 K and 1.0 K, and STD was concentrated between 1.0 K and 2.50 K; the nighttime MBD was concentrated between -0.6 K and
 435 0.3 K and STD was concentrated between 0.9 K and 1.50 K. As shown above, it should be concluded that the daily differences
 436 between the long-term TRIMS LST and AATSR/MODIS LST remain stable.



437
438

Figure 8: Histograms of the MBD and STD to compare the TRIMS LST and the AATSR/MODIS LST.

439 **4.3 Validation against *in-situ* LST outside the temporal gap**

440 The TRIMS LST was quantitative validated against the *in-situ* LST. Remove anomalies caused by transient environmental
 441 factors based on 3σ (standard deviation) filtering (Göttsche et al., 2016; Yang et al., 2020). **It should be noted that the results**
 442 **for all sites can be found in Tables B1 and B2.** The nineteen ground sites were divided into four groups according to locations
 443 and land cover types (Group I: ARO, D105, DSL, EBA, and MQU; Group II: DET, GAZ, GOB, HZZ, and SSW; Group III:
 444 DAM, DXI, GUT, HLA, and TYU; Group IV: CBS, DHS, QYZ, and SDQ). Table II and Table III show the validation results
 445 of TRIMS LST against the *in-situ* LST under different sky conditions. In addition, the validation results of the clear-sky
 446 MODIS LST are provided for comparison.

447 **Table II: R^2 , MBE, and RMSE of the daytime validation for different groups.**

Group	Land cover type	Condition	Amounts	TRIMS LST			MODIS LST		
				MBE (K)	RMSE (K)	R^2	MBE (K)	RMSE (K)	R^2
I	Grassland	Clear-sky	5370	0.26	2.15	0.95	0.61	2.37	0.95
		Cloudy	6972	0.41	2.18	0.96	–	–	–
II	Desert or barren land	Clear-sky	5930	0.46	2.30	0.98	0.79	2.53	0.98
		Cloudy	5698	0.43	2.26	0.98	–	–	–
III	Cropland	Clear-sky	5738	0.02	2.11	0.97	-0.21	2.52	0.95
		Cloudy	7570	0.04	2.11	0.97	–	–	–
IV	Forest	Clear-sky	3170	0.55	2.46	0.97	0.72	2.38	0.98
		Cloudy	3655	0.68	2.27	0.98	–	–	–

448 **Table III: R^2 , MBE, and RMSE of the nighttime validation for different groups.**

Group	Land cover type	Condition	Amounts	TRIMS LST			MODIS LST		
				MBE (K)	RMSE (K)	R^2	MBE (K)	RMSE (K)	R^2
I	Grassland	Clear-sky	8175	-0.70	1.65	0.98	-0.99	1.69	0.98
		Cloudy	5254	-0.13	1.64	0.97	–	–	–
II	Desert or barren land	Clear-sky	6095	-0.64	1.43	0.99	-0.67	1.53	0.99
		Cloudy	5244	-1.17	1.85	0.99	–	–	–
III	Cropland	Clear-sky	5314	-0.83	1.76	0.98	-0.75	1.60	0.98
		Cloudy	7243	-0.60	1.74	0.98	–	–	–
IV	Forest	Clear-sky	2800	-0.98	1.92	0.98	-0.97	2.09	0.98

		Cloudy	3332	-0.94	1.90	0.99	-	-	-
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450

451 Under clear-sky conditions, the TRIMS LST had an accuracy close to that of the MODIS LST as shown in Table II and Table
452 III. The MBE of the TRIMS LST ranged from -0.98 K to 0.68 K and the RMSE is 1.43 K to 2.46 K. The RMSE of the TRIMS
453 LST under clear-sky conditions is lower than that of the MODIS LST, except for Group IV. The RMSEs of the MODIS LST
454 were reduced by 0.22 K (Group I), 0.23 K (Group II), and 0.41 K (Group III), respectively. The nighttime results were generally
455 better than the daytime results, with an average RMSE of 1.74 K. The R^2 of the TRIMS LST for the four groups of sites were
456 higher than 0.95 under clear-sky conditions, indicating that the TRIMS LST is in good agreement with the *in-situ* LST. The
457 improved accuracy of the TRIMS LST may be due to the reduction of the systematic bias of the original MODIS LST in the
458 E-RTM method by extracting the LFC and HFC (Ding et al., 2022).

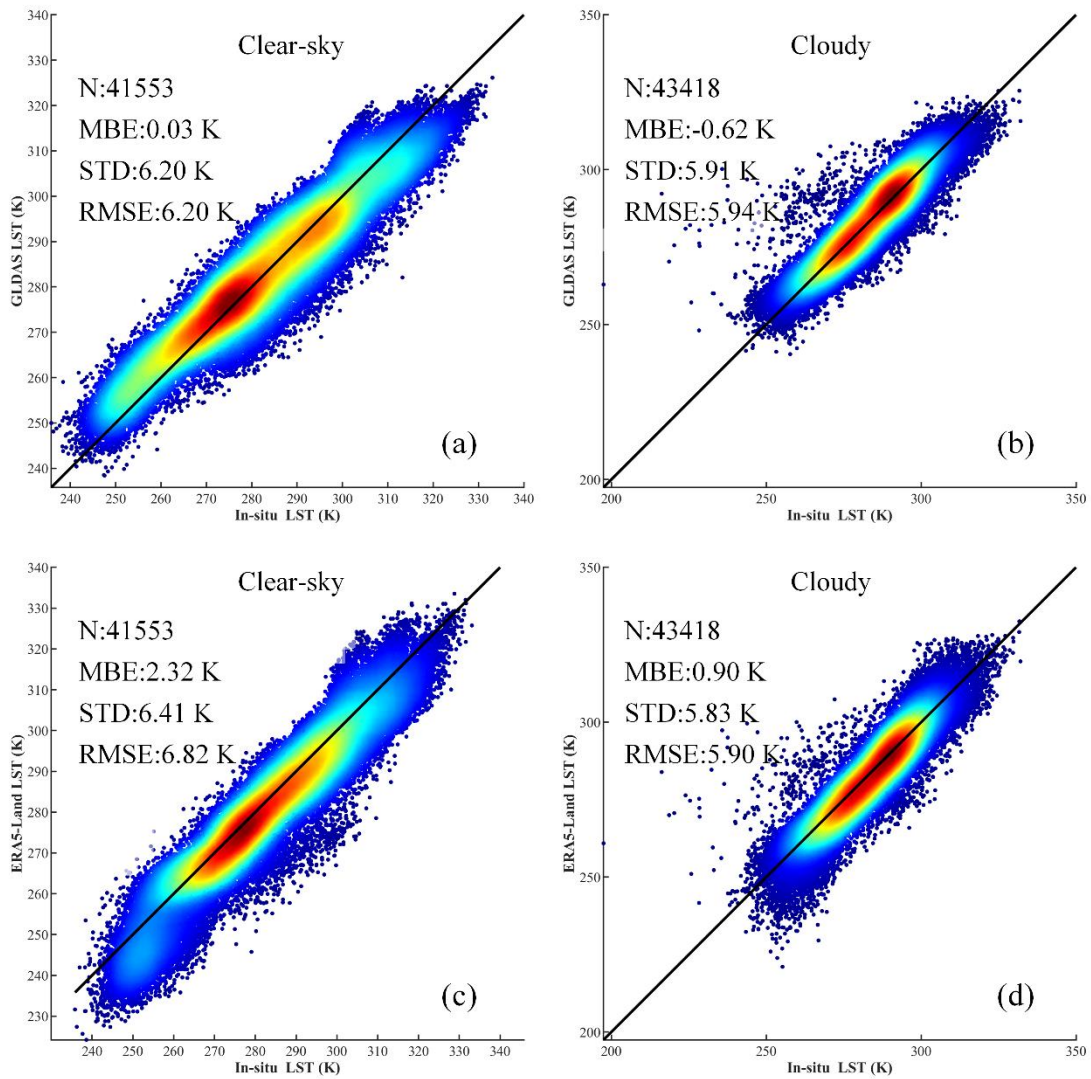
459 Under cloudy conditions, the accuracy of TRIMS LST is slightly lower compared to clear-sky conditions, resulting in a 0.35
460 K increase in the overall RMSE.

461 For TRIMS LST under cloudy conditions, the accuracy is marginally below that under clear-sky conditions, and the overall
462 RMSE increased by 0.35 K. For the four groups of sites, the MBE values of TRIMS LST were -0.13 K (Group I), -1.17 K
463 (Group II), -0.60 K (Group III), and -0.94 K (Group IV), revealing that the TRIMS LST is underestimated under cloudy
464 conditions. According to the parameterization scheme of the E-RTM method, the accuracy of the estimated HFC_{cld} under
465 cloudy conditions is affected by the GLDAS LST, which has a negative deviation from the MODIS LST as shown in Section
466 4.1. In contrast, Although the GLDAS LST is bias-corrected, uncertainty may still exist, which are ultimately detrimental to
467 the accurate recovery of the LST for the cloud-contaminated region. Overall, the validation results indicate that TRIMS LST
468 has good accuracy under cloudy conditions as well as under clear-sky conditions.

469 For ground sites in Group III with a dominant land cover type of desert or barren land, the nighttime validation shows that the
470 TRIMS-Aqua LST is systematically underestimated, with an MBE of -1.17 K to -0.64 K. After checking the calculated STD,
471 we believe the spatial scale mismatch between the ground site and the pixel is not the main reason for the systematic
472 underestimation. Further examination shows that the clear-sky MODIS LST is significantly underestimated: the MBEs of
473 Aqua/MODIS LST are -1.88 K, -1.03 K, -1.33 K, and -0.60 K for GOB, HZZ, SSW, and GAZ, respectively. Such a cold bias
474 in arid and semiarid regions is also been reported by Li et al. (2019) for the MYD11 LST product. The above results indicate
475 that the accuracy of TRIMS LST is largely dependent on the used MODIS LST.

476 Reanalysis LST were also validated against *in-situ* LST. GLDAS LST is generally underestimated compared to *in-situ* LST,
477 with MBE of -0.29 K and RMSE of 5.86 K. Under clear-sky and cloudy conditions, the GLDAS LST exhibits MBE values of
478 0.03 K and -0.62 K, respectively. On the other hand, ERA5-Land LST is overestimated compared with *in-situ* LST, with MBE
479 of 1.60 K and RMSE of 6.37 K. This indicates that the accuracy of the ERA5-Land LST is lower than that of the GLDAS LST.
480 Notably, this discrepancy is more pronounced under clear-sky conditions.

481



482
483 **Figure 9: Density plots between reanalysis LST and *in-situ* LST.**

484

485 4.4 Validation of TRIMS-Aqua LST and TRIMS-Terra LST during temporal gap

486 During T1 period, there are no independent *in-situ* LST measurements available. Observations of D105 and GAZ began on
487 DOY275 (October 2) of 2002. To investigate the generalization ability of the RFSTM in the temporal dimension, the method
488 is implemented as follows: For 2003, the GLDAS and Terra MODIS data are also merged to generate 1-km TRIMS-Terra
489 LST. This study utilized the TSETR method to reconstruct the TRIMS-Aqua LST over a period of 915 days. To ensure a
490 comprehensive analysis, TRIMS-Aqua LST for the years 2003 (DOY1)–2005 (DOY185) and 2013 (DOY1)–2015 (DOY185)

491 were generated using TSETR method. This allowed for the inclusion of a significant number of independent ground sites for
 492 validation purposes.

493 Table IV shows the results of the comparison between the TRIMS-Terra LST generated by the RFSTM-based method and the
 494 TRIMS-Terra LST generated by the RTM-based method. The TRIMS-Terra LST generated by the RTM method and the
 495 TRIMS-Terra LST generated by the RFSTM method have similar accuracies for the sites. The MBEs differ by no more than
 496 0.50 K and the RMSEs differ by no more than 1.2 K. However, the RFSTM method is slightly less accurate than the TRIMS-
 497 Terra LST generated by the RTM method. It is important to note that the RFSTM method is only used in this study to generate
 498 data for a period of 53 days, which has a relatively smaller impact on the overall accuracy of TRIMS LST.

499

500 **Table IV: MBE and RMSE from validation results of TRIMS-Terra LST with the *in-situ* LST**

Site	Condition	TRIMS-Terra LST (RTM)				TRIMS-Terra LST (RFSTM)			
		Daytime		Nighttime		Daytime		Nighttime	
		MBE (K)	RMSE (K)	MBE (K)	RMSE (K)	MBE (K)	RMSE (K)	MBE (K)	RMSE (K)
D105	All	1.63	3.15	-1.05	1.94	1.75	3.3	-1.55	2.20
	Clear-sky	1.78	2.17	-1.17	2.04	1.85	3.34	-2.37	2.66
	Cloudy	1.54	3.25	-0.88	1.78	1.04	3.44	-0.40	1.29
GZA	All	0.93	2.61	-0.78	1.76	1.26	3.10	-1.95	2.26
	Clear-sky	0.79	2.51	-0.68	1.70	0.94	2.72	-1.26	2.10
	Cloudy	1.11	3.71	-0.94	1.85	1.61	4.20	-1.47	2.35

501

502 **Table V: MBE and RMSE from validation results of TRIMS-Aqua LST with the *in-situ* LST**

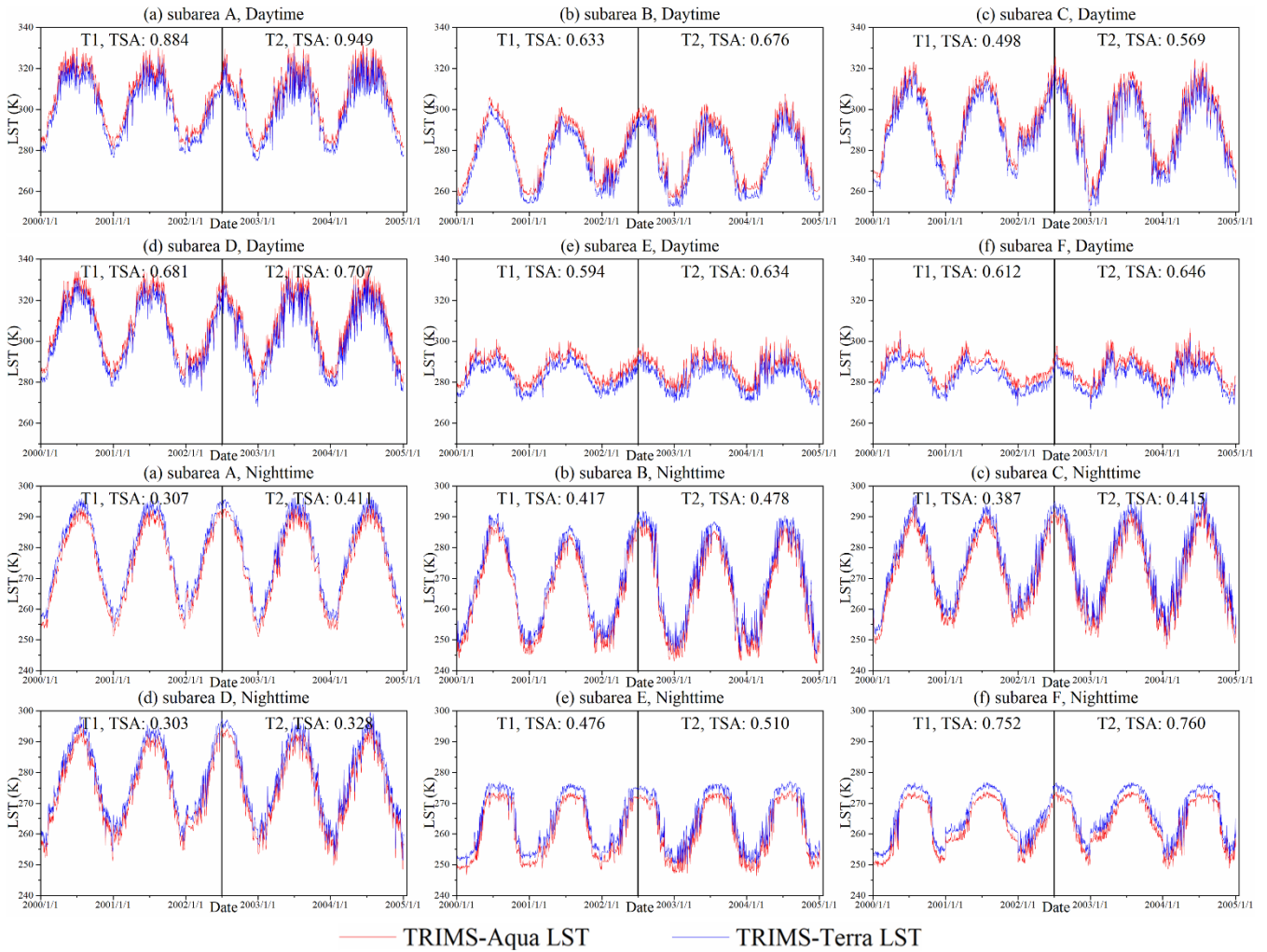
Site	Condition	TRIMS-Aqua LST (RTM)				TRIMS-Aqua LST (TSETR)			
		Daytime		Nighttime		Daytime		Nighttime	
		MBE (K)	RMSE (K)	MBE (K)	RMSE (K)	MBE (K)	RMSE (K)	MBE (K)	RMSE (K)
ARO	All	-0.53	2.14	0.58	1.77	-0.75	2.38	0.64	2.17
	Clear-sky	-0.47	2.11	0.52	1.74	-0.63	2.35	0.75	2.25
	Cloudy	-0.57	2.16	0.70	1.81	-0.87	2.34	0.88	1.85
DAM	All	-0.24	2.06	0.55	1.81	-0.38	2.47	0.60	1.84
	Clear-sky	-0.28	2.03	0.52	1.81	-0.45	2.61	0.53	2.03
	Cloudy	-0.23	2.09	0.56	1.82	-0.30	2.73	0.76	2.32
D105	All	0.80	2.67	-1.01	1.77	1.11	2.31	-1.15	1.88

	Clear-sky	1.55	3.05	-0.94	1.71	1.87	3.22	-1.37	1.86
	Cloudy	0.59	2.54	-1.09	1.85	0.45	1.96	-0.63	1.22
GZA	All	-0.74	2.73	-0.67	1.51	-0.93	3.01	-1.08	2.09
	Clear-sky	-0.60	2.61	-0.65	1.48	-0.98	2.74	-0.68	1.83
	Cloudy	-0.93	2.89	-0.73	1.60	-1.05	3.29	-0.94	2.24
GOB	All	-0.34	2.60	0.21	1.87	-0.62	2.77	0.47	2.15
	Clear-sky	1.88	2.41	1.64	1.93	1.77	2.76	1.66	2.04
	Cloudy	-2.31	2.75	-1.51	1.79	-2.63	2.84	-1.79	2.45
SDQ	All	-0.27	2.41	0.93	1.78	-0.59	2.75	1.23	2.40
	Clear-sky	-0.18	2.37	0.97	1.80	-0.19	2.09	1.26	2.19
	Cloudy	-0.39	2.46	0.87	1.74	-0.81	2.88	1.17	2.37

503

504 Combining the results of Table IV and Table V, it can be observed that the TRIMS-Aqua LST generated by the TSETR method
505 and the TRIMS-Aqua LST generated by the RTM method exhibit similar accuracies at the sites. The differences in MBE and
506 RMSE between these two methods are not significant, with the MBE differing by no more than 0.40 K and the RMSE differing
507 by no more than 0.70 K. These findings demonstrate that the TSETR method maintains high accuracy and stability when
508 generating data over longer time periods. Based on this, it can be concluded that the TRIMS-Aqua LST in the T1 period
509 reconstructed using the TSETR method is reasonably accurate.

510 Table IV and Table V demonstrate the reliability of RFSTM and TSETR. Fig. 10 further shows the quantification results of of
511 the similarity between the TRIMS-Aqua LST and TRIMS-Terra LST time series during the temporal gaps. Overall, the trends
512 in the time series of TRIMS-Terra and TRIMS-Aqua LST are very consistent, and they generally have a high degree of
513 similarity. The daytime time series show that the TRIMS-Aqua LST is generally higher than the TRIMS-Terra LST, while the
514 opposite is observed for the nighttime. In particular, for subareas E and F, the TRIMS-Aqua LST show a significant systematic
515 deviation from the TRIMS-Terra LST during nighttime. The distribution of the curves in Fig. 8 reveals that the daytime LST
516 time series had more large fluctuations, while the nighttime variation is more subdued. The TSA is lower at nighttime than
517 daytime, indicating that the time series similarity between the TRIMS-Aqua LST and the TRIMS-Terra LST is higher at
518 nighttime. In addition, the TRIMS-Terra and TRIMS-Aqua LST are slightly more similar in the T1 than in T2 among these
519 six regions. This situation is as expected, since the TRIMS-Aqua LST in T1 is derived from a mapping created by the data at
520 the Terra overpass time. The differences in the TSA between T1 and T2 ranged from 0.0080 to 0.0710. The mean differences
521 are 0.0465 (daytime) and 0.0433(nighttime). The above results indicate that the similarity of the LST time series of T1 and T2
522 is relatively close. This finding demonstrates that the difference between TRIMS LST at the Aqua and Terra overpass times is
523 stable in T1.



524

525 **Figure 10: TRIMS-Terra and TRIMS-Aqua LSTs from January 1, 2000 to January 3, 2005 and statistics of the time series similarity.**

526

527 4.5 Advantages of TRIMS LST

528 Recently, several all-weather LST datasets have been released by the scientific communities (see Appendix C). Overall, the
 529 uniqueness or advantages of TRIMS LST are in three main areas:

530 First, the TRIMS LST demonstrates comparable or better accuracy than existing publicly released all-weather/spatially
 531 seamless LST datasets. A thorough comparison with satellite TIR LST products has indicated the effectiveness of TRIMS LST,
 532 with MBD ranging from -1.5 K to 1 K and STD ranging from 1 K to 3 K, thus confirming its accuracy and consistency.
 533 Furthermore, *in-situ* LST evaluations show MBE ranging from -1.64 K to 2.88 K and RMSE ranging from 1.82 K to 3.48 K.
 534 Interestingly, no significant difference is observed between clear-sky and cloudy conditions, indicating the robustness of

535 TRIMS LST across various situations. Thus, based on the results of this study, TRIMS LST can be considered a reliable source
 536 of temperature data.

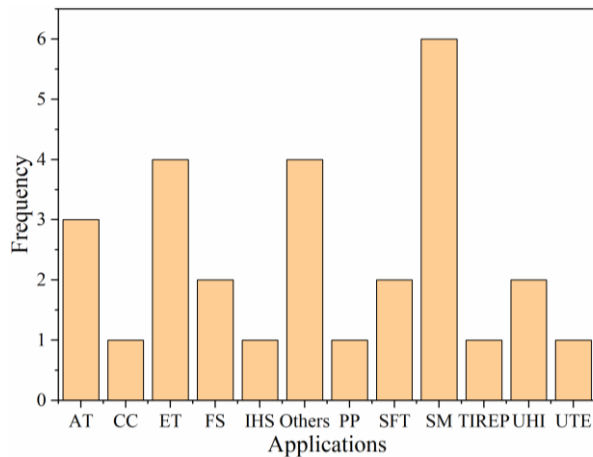
537 Second, the method employed in this study effectively overcomes the issue of boundary effects in reconstructing the all-
 538 weather process. This is achieved through the utilization of the E-RTM method, which is based on a temporal decomposition
 539 model of LST. With this model, the *LFC* and *HFC* components can be directly determined from high-resolution MODIS and
 540 ancillary remote sensing data. Consequently, only spatial downscaling of *HFC_{old}* is required, eliminating the need for direct
 541 downscaling of the GLDAS LST. This approach reduces the possibility of insufficient spatial downscaling. Additionally, the
 542 E-RTM method considers the relationship between LSTs of neighboring pixels, resulting in decreased errors during spatial
 543 downscaling.

544 Third, TRIMS LST offers advantages in effectively recovering LST information and preserving temporal integrity under
 545 cloudy conditions. With a spatial resolution of 1 km, TRIMS LST covers both daytime and nighttime LST from 2000 to 2022,
 546 which is comparable in spatio-temporal resolution to other published seamless LST datasets. The E-RTM method effectively
 547 recovers temperature information under clouds, ensuring clear physical meaning and high accuracy and image quality of
 548 TRIMS LST. Moreover, TRIMS LST extends the all-weather LST coverage of the MODIS temporal gap. This enhances the
 549 completeness of long time series LST datasets, creating a unique and valuable collection.

550

551 4.6 Literature-reported applications of the TRIMS LST

552 TRIMS LST have already been utilized by the scientific communities in various applications (Fig. 11). A literature survey
 553 indicates that there have been 32 related papers published by journals (as of July 31, 2023), including leading journals such as
 554 Remote Sensing of Environment, Agricultural Water Management, and Science of the Total Environment. Typical applications
 555 include the estimation of soil moisture and surface evapotranspiration as well as modelling of urban heat is land and urban
 556 thermal environment. A few typical applications are listed below.



557

558 **Figure 11: Statistics of applications based on TRIMS LST (AT: Air temperature; CC: Climate change; ET: Evapotranspiration;**
559 **FS: Frozen soil; IHS: Industrial heat sources; Others: Active layer thickness, Lake Area, Land desertification, and LST downscaling;**
560 **PP: Plant Phenology; SFT: Soil freeze/thaw; SM: Soil moisture; TIREP: Thermal Infrared Earthquake Prediction; UHI: Urban**
561 **heat island; UTE: Urban Thermal Environment).**

562 Satellite TIR LSTs are an important input data for obtaining SM estimates with high resolution and high spatial coverage.
563 However, most satellite TIR LST products can only be used under clear-sky conditions. The availability of all-sky LST
564 products provides an important opportunity to obtain SMs with spatial seamlessness. Zhang et al. (2023) combined the use of
565 ERA5-Land and TRIMS LST for the fine-scale assessment of soil moisture in in China. They used the model based on 0.1°
566 ERA5 Land and SM data for 1-km TRIMS LST, and finally obtained a daily/1-km SM dataset with satisfactory accuracy.
567 Benefiting from the effective recovery of LST under cloudy conditions, this SM dataset has quasi-full spatial coverage. In
568 addition, Hu et al. (2022) also used the TRIMS LST as input data to construct a soil moisture downscaling model for the
569 Tibetan Plateau. The TRIMS LST was found to successfully overcome the challenges of satellite TIR remote sensing detection
570 due to temporal/spatial gaps and false detections due to clouds and topography. Based on the downscaled soil moisture, they
571 further published the daily 0.05°×0.05° land surface soil moisture dataset of the Qilian Mountain area (northern and
572 northwestern Tibetan Plateau) from 2019–2021 (SMHiRes, V2) (Hu et al., 2022; Qu et al., 2021; Chai et al., 2021, 2022a, b).
573 LST can also be used to investigate the soil freeze/thaw cycles. Li et al. (2023) used the TRIMS LST to obtain thawing degree
574 days and freezing degree days to calculate the soil thermal conductivity and improved the output of the temperature at the top
575 of the permafrost model. Due to the characteristics of TRIMS LST: high spatial and temporal resolution, the above two metrics
576 can be easily obtained on a spatial scale of 1 km. In addition, the TRIMS LST was also used to evaluate the impact of the LST
577 on the classification accuracy on different remote-sensed or model-based freeze/thaw datasets (Li et al., 2022).
578 Based on the TRIMS LST, Li et al. (2021b) investigated the spatial and temporal variations of surface UHI (SUHI) intensity
579 (SUHI). The positive performance of the TRIMS LST in obtaining the LST under cloudy conditions enabled the examination
580 of the SUHI intensity of 305 Chinese cities, especially the cities located in southern China, where clouds frequently appear.
581 Furthermore, Liao et al. (2022) quantified the clear-sky bias of the SUHI intensity in using the MODIS LST based on the
582 TRIMS LST. They emphasized the importance of investigating the SUHI phenomenon under cloudy conditions.

583 **5. Data availability**

584 TRIMS LST is available for free and easy access through **the National Tibetan Plateau Data Center (TPDC):**
585 <https://doi.org/10.11888/Meteoro.tpdc.271252> (Zhou et al., 2021).

586 **6. Conclusions**

587 A long-term 1-km daily all-weather LST dataset is the basis for supporting many applications related to land surface process
588 and climate change. Although some all-weather LST datasets have been released, especially in the last two years, users still

589 lack such data for the period of 2000–2002, during which the MODIS LST is not available. In this study, we report a daily 1-
590 km all-weather LST dataset for the Chinese landmass and surrounding areas – TRIMS LST. In contrast to many all-weather
591 LST products, the TRIMS LST begins from the first day of the new millennium (i.e., January 1, 2000).
592 TRIMS LST is produced based on the E-RTM method. The primary input resources are the Terra/Aqua MODIS LST and
593 GLDAS LST. The TRIMS LST was comprehensively evaluated thoroughly from four aspects, including comparison with
594 satellite and reanalysis LSTs, validation against the *in-situ* LST, and similarity quantification for the TRIMS-Terra and
595 TRIMS-Aqua LST time series. **The results outside the temporal gap period indicate that the TRIMS LST agrees well with the**
596 **original MODIS and GLDAS LST and the independent ERA5 and AATSR LST, but with more spatial details and better**
597 **spatio-temporal completeness. Validation of TRIMS LST using the *in-situ* LST at 19 ground sites show that the MBE was -**
598 **2.26 K to 1.73 K and the RMSE was 0.80 K to 3.68 K, with slightly better accuracy than the MODIS LST and no obvious**
599 **difference under different weather conditions. The results within the temporal gap period show that RFSTM and TSETR have**
600 **similar accuracy performance to the original RTM method, with MBE differences not exceeding 0.40 K and RMSE differences**
601 **not exceeding 0.7 K. The stability of the TRIMS LST differences for T1 at the Aqua and Terra overpass times is also a side**
602 **effect of the excellent quality.**
603 The TRIMS LST has already been released to the scientific communities. A series of applications, such as soil moisture
604 estimation/downscaling, surface evapotranspiration estimation, and urban heat island (UHI) modelling, have been reported.
605 The TRIMS LST was found to successfully address the cloud contamination of satellite TIR LST and with good accuracy,
606 long time series, and spatio-temporal completeness. The TRIMS LST will be continuously updated to satisfy the latest
607 requirements of users.

608

Appendix A: List of abbreviations

Advanced Along-Track Scanning Radiometer	AATSR
Advanced Microwave Scanning Radiometer 2	AMSR2
30-m yearly China land cover dataset (2000-2015)	CLCD
Day of the year	DOY
the Enhanced Reanalysis and Thermal infrared remote sensing Merging method	E-RTM
Evapotranspiration	ET
Field-of-view	FOV
Goddard Earth Sciences Data and Information Services Center	GES DISC
Global Land Data Assimilation System assimilation	GLDAS
Land surface temperature	LST
Mean bias deviation	MBD
Mean bias error	MBE
MSG All-Sky Land Surface Temperature	MLST-AS
Moderate Resolution Imaging Spectroradiometer	MODIS
Normalized Difference Snow Index	NDSI
Normalized Difference Vegetation Index	NDVI
Passive microwave	PMW
Random-Forest based Spatio-Temporal Merging approach	RFSTM
Root mean square error	RMSE
Soil moisture	SM
'Satellite Pour l'Observation de la Terre' (SPOT) VEGETATION (VGT)	SPOT VGT
Shuttle Radar Topography Mission Digital Elevation Model data	SRTM DEM
Standard deviation	STD
Surface UHI	SUHI
Surface UHI intensity	SUHII
Thermal infrared remote sensing	TIR
the National Tibetan Plateau Data Center	TPDC
the Thermal and Reanalysis Integrating Moderate-resolution Spatial- seamless LST	TRIMS LST
Time series angle	TSA
Time-SEquential LST based Reconstruction approach	TSETR
Urban heat island	UHI
Visible infrared Imaging Radiometer	VIIRS

Appendix B: Validation results of the TRIMS LST and the MODIS LST with the *in-situ* LST

Table B1: MBE and RMSE from validation results of the daytime TRIMS LST and MODIS LST with *in-situ* LST

Site	Condition	Sample size		TRIMS LST				MODIS LST			
				MBE (K)		RMSE (K)		MBE (K)		RMSE (K)	
		MOD	MYD	MOD	MYD	MOD	MYD	MOD	MYD	MOD	MYD
ARO	Clear-sky	1418	1029	0.43	0.48	2.30	1.87	0.74	0.57	2.95	2.38
	Cloudy	1228	1541	0.33	0.61	2.04	1.95	–	–	–	–
DAM	Clear-sky	1363	1297	0.97	0.26	1.92	1.98	0.98	0.27	2.31	2.50
	Cloudy	1432	1492	0.67	0.18	1.81	2.07	–	–	–	–
DET	Clear-sky	1191	1180	1.73	1.45	2.45	2.49	1.73	1.88	2.70	2.70
	Cloudy	830	896	1.70	1.45	2.67	2.43	–	–	–	–
DSL	Clear-sky	1109	814	-0.01	-0.33	1.82	1.72	0.00	-0.32	2.38	2.28
	Cloudy	1198	1144	-0.01	0.48	1.91	1.65	–	–	–	–
EBA	Clear-sky	410	289	0.63	0.59	2.06	1.90	0.65	0.53	2.38	2.31
	Cloudy	472	580	0.74	0.61	2.01	1.80	–	–	–	–
GOB	Clear-sky	363	350	-0.58	-1.88	1.73	2.41	-0.61	-1.89	2.25	2.74
	Cloudy	368	390	-0.96	-1.65	1.72	2.71	–	–	–	–
HZZ	Clear-sky	1046	975	1.06	-1.03	1.84	2.06	1.05	-1.04	2.40	3.14
	Cloudy	1219	1354	0.59	-0.66	1.78	2.05	–	–	–	–
SDQ	Clear-sky	1507	1466	0.82	0.23	2.57	2.05	0.81	0.39	3.16	2.57
	Cloudy	1147	1132	0.86	0.37	2.49	2.23	–	–	–	–
SSW	Clear-sky	191	174	-0.42	-1.33	2.09	2.08	-0.43	-1.35	3.10	2.51
	Cloudy	194	203	-1.23	-1.77	2.36	2.45	–	–	–	–
HLA	Clear-sky	1121	946	-0.79	-0.85	2.30	2.18	-0.74	-0.71	2.76	2.60
	Cloudy	1084	1159	-0.68	-0.75	2.68	1.81	–	–	–	–
D105	Clear-sky	92	44	1.61	1.28	3.68	2.53	1.36	0.67	4.09	2.71
	Cloudy	178	138	1.29	0.61	3.94	2.74	–	–	–	–
GAZ	Clear-sky	220	240	0.74	-0.60	2.12	2.17	0.47	-0.55	2.37	2.82

	Cloudy	89	157	1.15	-0.85	2.11	1.96	-	-	-	-
CBS	Clear-sky	54	56	0.49	1.38	2.41	3.41	0.85	1.49	2.39	3.43
	Cloudy	220	262	0.76	1.59	2.42	3.43	-	-	-	-
DXI	Clear-sky	246	226	0.83	0.30	2.13	1.79	0.80	0.28	2.33	2.00
	Cloudy	547	562	0.81	0.54	2.19	1.79	-	-	-	-
DHS	Clear-sky	23	21	0.38	0.77	1.37	1.53	0.30	0.74	0.74	1.18
	Cloudy	292	299	0.42	0.47	1.51	1.22	-	-	-	-
MQU	Clear-sky	101	64	0.15	-1.50	2.43	2.85	0.12	-1.47	3.05	3.13
	Cloudy	77	117	0.05	-1.35	2.27	2.99	-	-	-	-
GUT	Clear-sky	69	63	-0.22	0.02	2.10	2.25	-0.29	-0.07	2.20	2.25
	Cloudy	310	303	-0.28	0.60	1.83	2.22	-	-	-	-
QYZ	Clear-sky	26	19	0.95	1.01	3.00	3.17	0.73	0.90	2.35	2.14
	Cloudy	139	177	0.71	0.91	2.71	3.35	-	-	-	-
TYU	Clear-sky	211	196	0.37	-0.88	2.56	2.14	0.31	-0.90	3.01	2.63
	Cloudy	333	348	0.19	-0.58	2.63	2.03	-	-	-	-

615 Table B2: MBE and RMSE from validation results of the nighttime TRIMS LST and MODIS LST with the *in-situ* LST.

Site	Condition	Sample size		TRIMS LST				MODIS LST			
				MBE (K)		RMSE (K)		MBE (K)		RMSE (K)	
		MOD	MYD	MOD	MYD	MOD	MYD	MOD	MYD	MOD	MYD
ARO	Clear-sky	1617	1757	-0.72	-0.53	1.87	1.67	-0.70	-0.60	2.09	1.90
	Cloudy	1196	1078	-0.68	-0.63	1.62	1.76	-	-	-	-
DAM	Clear-sky	853	973	-0.80	-0.58	2.14	1.70	-0.82	-0.81	2.23	1.87
	Cloudy	1643	1673	-0.86	-0.52	1.98	1.64	-	-	-	-
DET	Clear-sky	1325	1476	-0.08	0.17	0.83	0.90	-0.08	0.16	0.86	0.97
	Cloudy	679	630	0.42	-0.23	0.80	0.83	-	-	-	-
DSL	Clear-sky	1109	1646	-0.90	-0.84	1.82	1.50	-0.45	-0.42	1.92	1.78
	Cloudy	1198	797	-1.13	0.44	1.91	1.24	-	-	-	-
EBA	Clear-sky	566	621	-0.61	-0.60	1.65	2.00	-0.58	-0.64	1.77	2.19
	Cloudy	443	404	-0.55	-0.64	1.56	1.68	-	-	-	-

GOB	Clear-sky	467	381	-1.60	-1.65	2.05	1.93	-1.62	-1.65	1.96	1.96
	Cloudy	376	321	-2.04	-1.51	2.26	1.79	–	–	–	–
HZZ	Clear-sky	772	944	-1.29	-0.94	1.86	1.46	-1.28	-0.93	2.03	1.65
	Cloudy	1348	1296	-1.77	-1.36	2.32	1.86	–	–	–	–
SDQ	Clear-sky	1557	1286	-0.79	-0.94	2.61	2.33	-1.02	-0.93	2.68	2.44
	Cloudy	1112	981	-1.06	-0.94	2.70	2.15	–	–	–	–
SSW	Clear-sky	172	164	-2.26	-1.87	2.53	2.11	-2.27	-1.86	2.59	2.15
	Cloudy	195	190	-1.95	-1.79	2.29	2.00	–	–	–	–
HLA	Clear-sky	1042	1038	-0.82	-0.73	2.24	1.61	-0.85	-0.73	2.34	1.75
	Cloudy	1066	989	-0.85	-0.87	2.24	1.55	–	–	–	–
D105	Clear-sky	131	167	-1.07	-0.92	2.39	2.57	-1.05	-1.12	2.58	2.69
	Cloudy	95	121	-1.05	-1.10	2.81	2.74	–	–	–	–
GAZ	Clear-sky	289	265	-0.63	-0.68	1.85	1.35	-0.68	-0.57	1.90	1.39
	Cloudy	124	86	-0.75	-0.69	1.80	1.32	–	–	–	–
CBS	Clear-sky	95	98	-1.07	-0.55	2.81	2.21	-1.00	-0.50	2.79	2.26
	Cloudy	190	208	-1.00	-0.33	3.31	2.37	–	–	–	–
DXI	Clear-sky	334	349	-1.10	-1.45	3.43	3.06	-1.65	-1.44	3.51	3.13
	Cloudy	454	446	-1.15	-1.42	3.77	2.58	–	–	–	–
DHS	Clear-sky	53	53	-0.82	-0.74	1.97	2.31	-0.74	-0.89	1.83	2.22
	Cloudy	264	262	-0.81	-0.89	2.35	2.30	–	–	–	–
MQU	Clear-sky	85	81	0.68	0.78	2.23	2.41	0.76	0.70	2.16	2.40
	Cloudy	105	90	0.81	0.76	2.32	2.53	–	–	–	–
GUT	Clear-sky	122	126	-0.90	-0.76	2.14	1.80	-0.94	-0.78	2.19	1.81
	Cloudy	237	230	-0.93	-0.70	2.49	1.78	–	–	–	–
QYZ	Clear-sky	32	28	-0.90	-0.91	3.00	2.09	-1.16	-0.80	2.62	1.88
	Cloudy	145	175	-1.13	-0.88	3.49	2.37	–	–	–	–
TYU	Clear-sky	235	242	-1.12	-0.78	2.65	2.26	-0.94	-0.75	2.69	2.25
	Cloudy	258	273	-1.13	-0.79	2.91	2.37	–	–	–	–

Appendix C: Summary of publicly available all-weather/all-sky/gap-free LST products.

Product	Spatial resolution	Temporal resolution	Spatial coverage	Temporal coverage	Download links	References
All-weather 1 km land surface temperature products for China	1 km	1 observation per day	China	2002-2011	http://www.geodata.cn/index.html	Duan et al. (2017)
Global monthly reconstructed minimum, average, and maximum LST data (2003 - 2016)	5.6 km	Monthly Mean	Global	2003-2016	http://doi.org/10.5281/zenodo.1115666	Metz et al. (2017)
Daily 1-km all-weather land surface temperature dataset for Western China V1	1 km	2 observations per day	65.00°-108°E, 45.00°-22°N	2003-2018	https://data.tpdc.ac.cn (Expired)	Zhang et al.(2019b, 2020a)
MSG Land Surface Temperature - All Sky (MLST-AS) (LSA-005)	3-5 km	15 min	Europe and Africa	2020-Now	https://landsaf.ipma.pt/en	Martins et al. (2019)
1 km seamless land surface temperature dataset of China (2002-2020) (2002 - 2020)	1 km	2 observations per day	China	2002-2020	https://data.tpdc.ac.cn	Xu and Cheng. (2021); Zhang and Cheng. (2020b); Zhang et al. (2020c)
A combined Terra and Aqua MODIS land surface temperature and meteorological station data product for China (2003 - 2017)	5.6 km	Monthly Mean	China	2003-2017	https://data.tpdc.ac.cn	Zhao et al. (2020a)
Daily 1-km all-weather land surface temperature dataset for Western China (TRIMS LST-TP; 2000 - 2022) V2	1 km	4 observations per day	72.00°-104°E, 45.00°-20°N	2000-2022	https://data.tpdc.ac.cn	Zhang et al. (2021)
Daily 1-km all-weather land surface temperature dataset for the Chinese landmass and its surrounding areas (TRIMS LST; 2000 - 2022)	1 km	4 observations per day	72.00°-135°E, 19.00°-55°N	2000-2022	https://data.tpdc.ac.cn	Zhang et al. (2021)

Worldwide continuous gap-filled MODIS land surface temperature dataset	1 km	2 observations per day	Global	2002-Now	https://shilosh.users.earthengine.app/view/continuous-lst	Shiff et al. (2021)
Global daily 0.05°spatiotemporal continuous land surface temperature dataset (2002 - 2020)	0.05°	4 observations per day	Global	2002-2020	https://data.tpdc.ac.cn	Yu et al. (2022)
A global seamless 1 km resolution daily land surface temperature dataset (2003 - 2020)	1 km	2 observations per day	Global	2003-2020	https://doi.org/10.25380/iastate.c.5078492	Zhang et al. (2022)
Global spatiotemporally seamless T_{dm} products ranging from 2003 to 2019 (GADTC products)	0.5°	Daily mean	Global	2003-2019	https://doi.org/10.5281/zenodo.6287052	Hong et al. (2022)
0.02° seamless hourly land surface temperature dataset over East Asia (2016 - 2021)	0.02°	Hourly	East Asia	2016-2021	http://data.tpdc.ac.cn/zh-hans/data/06414391-abd4-4d28-a844-bd036a0b8c55/	Dong et al. (2022); Zhou and Cheng. (2020)
Global Hourly, 5-km, All-sky Land Surface Temperature (GHA-LST)	5 km	Hourly	Global	2011-2021	https://doi.org/10.5281/zenodo.6981704;glass.umd.edu/allsky_LST/GHA-LST	Jia et al. (2022)
Daily 1km all-sky time-consistent land surface temperature dataset over the Tibetan Plateau (2001 - 2018)	1 km	Daily	Qinghai Tibet Plateau	2001-2018	https://data.tpdc.ac.cn/zh-hans/data/3eb11507-6742-4f16-bda2-8ea10e0c1606	Zhao. (2023)
Global seamless and high-resolution temperature dataset (GSHTD)	1 km	Monthly Mean	Global	2001-2020	https://cjgeodata.cug.edu.cn/#/pageDetail?id=97	Yao et al. (2023)

Author contribution

620 WBT implemented the E-RTM method, completed the thorough evaluation and wrote the earliest version of the manuscript, JZ examined the entire process of generation and release of the TRIMS LST dataset and provided necessary guidance, JM helped to obtain the measured data and provided the method to quantify the spatial representation, and XDZ and JZ proposed the original RTM method. All co-authors contributed to the writing and carefully reviewed and revised the manuscript.

Competing interests

625 The authors declare that they have no conflict of interest.

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