



GEST: A multi-scale dynamics-based reconstruction of global ocean surface current

Guiyu Wang¹, Ge Chen¹, Chuanchuan Cao¹, Xiaoyan Chen¹, and Baoxiang Huang²

¹Frontiers Science Center for Deep Ocean Multispheres and Earth System, School of Marine Technology, Ocean University of China, Qingdao, China

²Department of Computer Science and Technology, College of Computer Science and Technology, Qingdao University, Qingdao, China

Corresponding to: G.Y. Wang (guiyuwang@stu.ouc.edu.cn)

Abstract A high precision and fine resolution reconstruction of sea surface current is beneficial to the exploration of complicated ocean dynamic processes. Existing studies mainly use satellite sea level and wind stress fields to derive sea surface geostrophic and Ekman currents, and build physical inversion models for global or regional oceans. Despite the obvious success, there are a variety of typical dynamic processes in the ocean such as mesoscale eddies and small-scale waves, and any product of surface current that neglects the contribution of wave motion would be, at best, incomplete. In this context, we present a precise sea surface current product at 15 m depth named GEST (Geostrophic-Ekman-Stokes-Tide) by analyzing the coupling relationship between ocean surface components that correspond to different physical processes and the actual currents as observed by drifting buoys. The GEST was generated based on Ekman, geostrophic currents, and waved-induced Stokes drift and TPX09 tidal currents. Specifically, in the calculation of Ekman currents, local applicability is taken into account to ensure that the friction layer of wind-driven current can reach where drifters could operate as normal. A comparison proves that combining multi-scale theory and the condition of local applicability improves estimation results by up to 3.6 cm/s compared with OSCAR product, and 0.3 cm/s with GlobCurrent. Furthermore, by comparing the reconstructed products with 1° and 0.25° resolution, we find that the higher resolution not only reveals more details of ocean currents especially mesoscale eddy energy associated with geostrophic currents, but also improves the accuracy by up to 5.62 cm/s.



27 **1 Introduction**

28 The ocean surface current is fundamental for climate studies and is closely associated with many
 29 oceanographic applications (Lagerloef et al., 2003; Caniaux et al., 2005; Jin et al., 2014). Detailed
 30 information of these currents significantly affects fisheries management, shipping control and
 31 ocean rescue (Lo et al., 1998). In particular, the knowledge of velocities and directions of ocean
 32 surface current is necessary for the tracking of suspended matter (such as spilled oil, algae, sea ice,
 33 and floating microplastic) (Choi et al., 2013; Yang et al., 2014; Weisberg et al., 2019; Onink et al.,
 34 2019), which can effectively explore plankton ecology and safeguard marine ecology (Wahl et al.,
 35 1996; Garçon et al., 2001). Therefore, high-resolution, long time series of ocean surface current
 36 are needed to extend existing oceanographic datasets, deepen the understanding of refined ocean
 37 dynamic processes, and make accurate predictions about changes in the climate system (Chapman
 38 et al., 2017).

39 Emerging technologies have been effectively applied to the observation of ocean surface current,
 40 but there is no global current observation system to obtain sea surface velocities on a full spatial
 41 and temporal scale so far. Despite the obvious success of the Global Drifter Program (GDP) issued
 42 by the National Oceanic and Atmospheric Administration (NOAA) which has run for about 40
 43 years, limitations and shortcomings like coarse space-time sampling and few coastal distributions
 44 are also existing.

45 It is well understood that satellite-based algorithms can explain about 70 % of the global ocean
 46 current dynamics (Sudre and Morrow, 2008), in which large-scale geostrophic circulation has been
 47 determined over the last 25-30 years. When forming a steady balance between wind-induced
 48 frictional stresses and Coriolis forces, Ekman current is the theoretical basis for understanding
 49 wind-driven ocean component, and is similarly considered as another main dynamic mechanism
 50 of ocean currents (Ekman, 1905). Remarkable progress has been made in estimating long time
 51 series ocean surface current datasets following the construction of global physical estimation
 52 model, such as the OSCAR (Ocean Surface Current Analysis Real Time), GEKCO (Geostrophic
 53 and Ekman Current Observatory) and the GlobCurrent project (Bonjean and Lagerloef, 2002;
 54 Dohan and Maximenko, 2010; Sudre et al., 2013; Rio et al., 2014). Sudre et al. (2013) obtained
 55 wind-driven currents by reanalyzing wind stress fields based on a two-parameter model, in which
 56 parameters were modified by linear stability equations based on the assimilation of drifter data.



57 The global geostrophic component was determined from the gradients ($\partial h/\partial y$, $\partial h/\partial x$) of the ocean
 58 sea surface height (SSH), which was calculated from the sum of the altimeter sea-level anomaly
 59 (SLA) and the mean dynamic topography (MDT). In the equator, a β -plane geostrophic
 60 approximation proposed by Lagerloef et al. (1999) was adopted because of the vanishing of the
 61 Coriolis force. Rio et al. (2014) used a new 0.25° CNES-CLS13 MDT by assimilating drifter
 62 observations, with which the velocities in strong currents were increased by 200 % on average. In
 63 addition, they also calculated a two-level (0 m and 15 m) empirical Ekman model with surface
 64 drifters and Argo floats, and both piece of algorithms lead to more accurate ocean currents.
 65 Bonjean and Lagerloef (2002) gained the improved estimate of tropical circulation with
 66 geostrophic, Ekman, Stommel shear dynamics, and a complementary term from surface buoyancy
 67 gradient, with quasi-linear and steady physics. All these surface currents were directly calculated
 68 from geostrophic and wind-induced Ekman currents. In the actual ocean, however, the movement
 69 of upper oceans is the result of multiple environmental driving mechanisms, and can be broadly
 70 divided into large-scale ocean circulations, micro scale internal waves and storm surges. Wave-
 71 induced transport acts either as an enhancement or attenuation to the mean flow within Ekman
 72 layer, and should also be regarded as an essential source of the ocean current (Bi et al., 2012).

73 In this paper, we examine the inherent coupling relationship between velocities measured by
 74 drifters and components of ocean surface current, including geostrophic and Ekman currents,
 75 wave-induced tidal currents and Stokes drift, which results in a more accurate ocean surface
 76 current product incorporating multi-scale dynamic mechanisms. This global daily product covers
 77 the period of 2013-2019, with a 0.25° spatial resolution, and is compared with the OSCAR product
 78 and the GlobCurrent project.

79 The organization of the remaining parts of this paper is as follows. Section 2 is concerned with the
 80 data used to calculate the components of the flow field. Section 3 presents the method to
 81 reconstruct ocean surface current. Section 4 shows the results of flow field estimates and provides
 82 a discussion of our estimation work. Finally, we reveal the conclusions in Sect. 5.

83 **2 Data**

84 **2.1 Tidal data**

85 Recently, many tidal estimation models with different resolutions and precision have emerged



because of insufficient tidal observation stations (e.g., HAMTIDE, FES, and TPXO) (Lyard et al., 2006; Taguchi et al., 2014). We use the tidal data from the latest version of TPXO models available at the time of the study, the TPXO9 model, which is based on the two-dimensional positive pressure fluid equation, applying the generalized inversion method to assimilate altimetry data (e.g., satellite altimetry from T/P, ERS1, 2, Envisat satellites) and in situ station-based tidal data, and then fitting the data with the least squares (LS) (Egbert et al., 2002; Egbert et al., 2018).

Established by Gary Egbert and Lanna Erofeeva from Oregon State University, USA, the TPXO9-atlas we used for the global hourly tidal data set has accurate and reliable results, which is reflected in the low root mean square error of M2 constituents in the deep ocean, the shallow sea, and the continental shelf (Sun et al., 2022). The derived tidal data has a $1/6^\circ$ resolution and contains the harmonic constant of 15 constituents, including eight major constituents (M2, S2, N2, K2, K1, O1, P1, and Q1).

2.2 Wind data

The global daily wind fields we used were retrieved from QuikSCAT and Windsat satellites launched by the United States during in-orbit operation, with a cell size of $0.25^\circ \times 0.25^\circ$, spanning 14 years from January 2006 to January 2019. This data sets were then used to calculate wind stress fields by a bulk formula, which refers to a drag coefficient (C_d) that curve-fits data for low-to-moderate winds with data for high wind speeds (Oey et al., 2006).

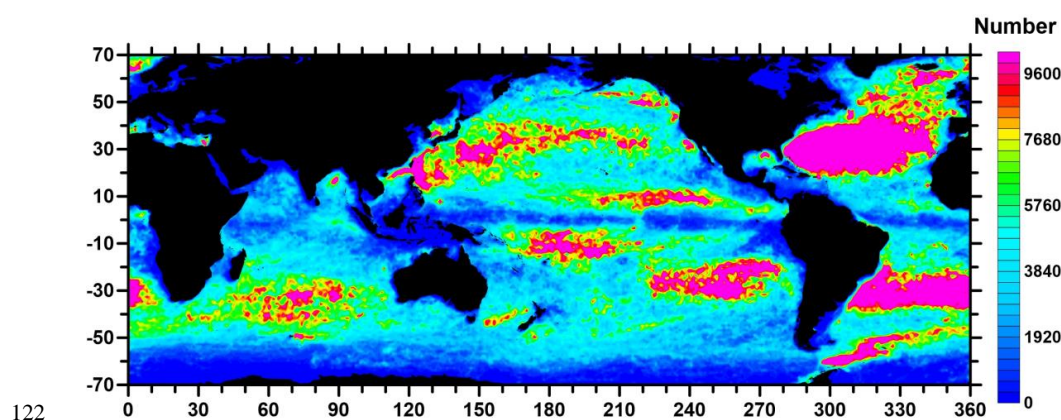
Based on the reanalysis wind stress fields, we aim to obtain wind-induced Ekman currents, which are perpendicular and shifted to the left of the direction of wind stress in the southern hemisphere (the opposite in the Northern Hemisphere), forming a spiral in response to the turbulent viscosity that depends on the local ocean state (Roach et al., 2015).

2.3 CMEMS global geostrophic currents and Stokes drift

The reanalysis daily geostrophic velocities generated by Copernicus Marine Environment Monitoring Service (CMEMS) with a grid size of $(0.25)^\circ \times (0.25)^\circ$ are used in this study (Pujol et al., 2016) covering the years 2006-2019. For latitudes outside $\pm 5^\circ$ N, geostrophic currents are obtained from altimeter maps of the Absolute Dynamic Topography (ADT) using a nine-point stencil width methodology. While near the equatorial zone, the geostrophic balance is not applicable anymore and a β -plane approximation of Lagerloef et al. (1999) is introduced.



115 In addition, the Stokes drift is taken from the Global Ocean Waves Reanalysis (WAVERYS)
 116 numerical assimilation products of CMEMS at grid points with 0.2° longitude and 0.2° latitude
 117 spacing covering the years 2006 to 2019. These products involve 3-hour instantaneous fields of
 118 integrated wave parameters (e.g., Sea surface wave significant height (SWH), sea surface wind
 119 wave from direction (WW), and Stokes drift velocities (VSDXY)), and are derived from the global
 120 wave reanalysis of the MeteoFranceWave-Model (MFWAM) wave model by assimilating the
 121 altimeter wave data and directional spectrum provided by Sentinel-1 (Law-Chune et al., 2021).



122
 123 **Figure 1:** Spatial distribution for the drifter observations per $1^\circ \times 1^\circ$ from 1999 to 2019.

124 2.4 Surface drifting buoys

125 AOML's Global Drift Program consists of a global array of more than 1,000 satellite-tracked
 126 surface drifting buoys (“drifters”) that take large scale measurements of surface velocities and
 127 track the direction of currents by Lagrangian method. In this study, we use the velocities of these
 128 in situ drifters as ‘reference tags’. This global data set with long time series is interpolated at hourly
 129 intervals and contains rich details of global high-frequency and small-scale ocean processes.
 130 Positions and velocities are derived by locally modelling the trajectories to construct first-order
 131 polynomials, whose coefficients are obtained by maximizing the likelihood function (Elipot et al.,
 132 2016; Elipot et al., 2022). To give an idea about the collocated drifter data set, the global spatial
 133 distribution of the drifter observations per $1^\circ \times 1^\circ$ cell is shown in Fig. 1.

134 3 Reconstruction of sea surface current at 15 m depth



135 3.1 Local applicability of wind-driven currents

136 We use the two-parameter empirical model displayed in Eq. (1) to estimate Ekman Currents ($\mathbf{u}_e, \mathbf{v}_e$)
 137 (Niiler and Paduan, 1995; Sudre and Morrow, 2008),

$$138 \quad (\mathbf{u}_e + i\mathbf{v}_e) = B e^{i\theta} (\boldsymbol{\tau}_x + i\boldsymbol{\tau}_y), \quad (1)$$

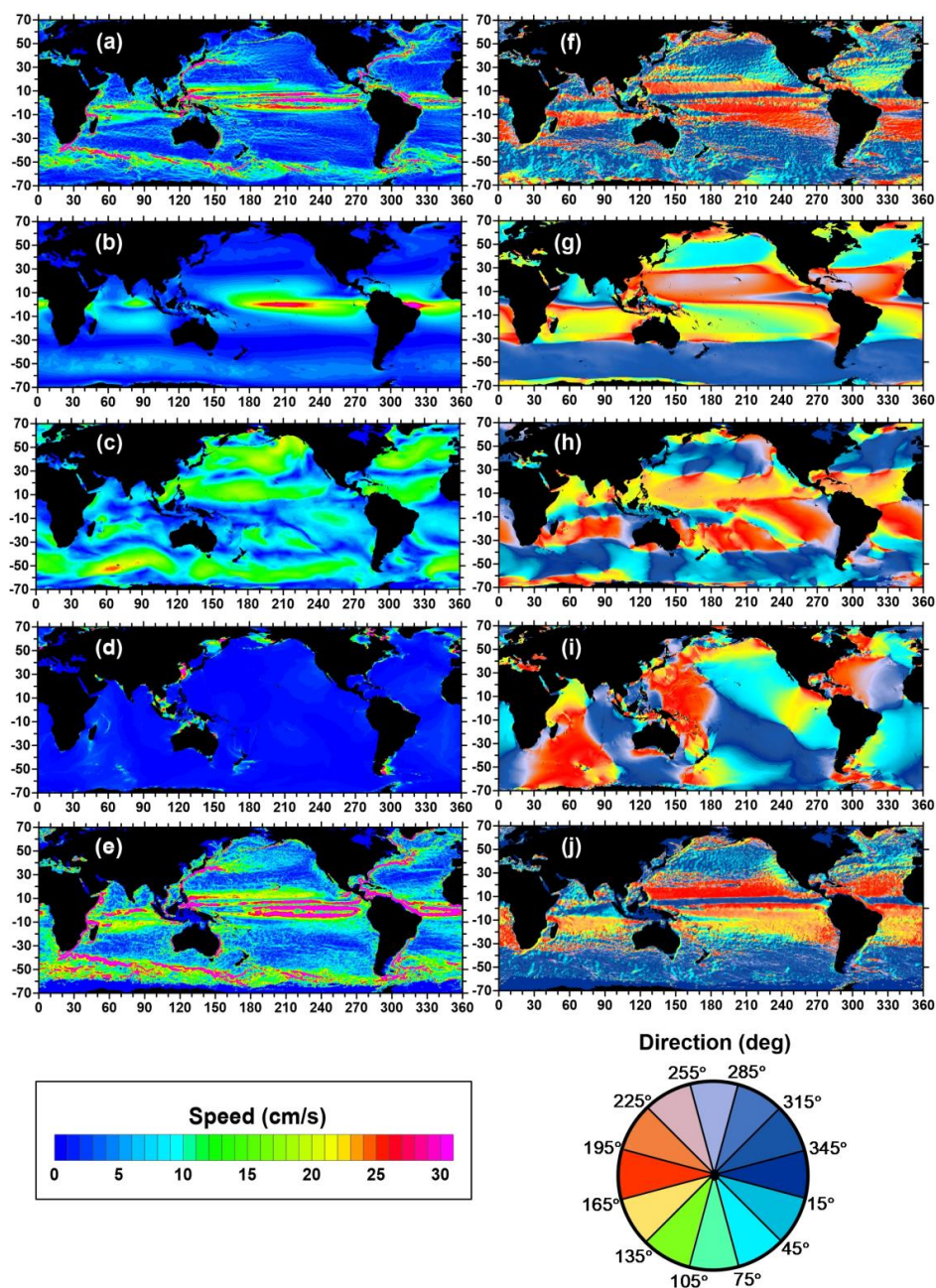
139 where τ_x and τ_y represent zonal and meridional wind stress. In the region out of 25° S-25° N, we
 140 follow the amplitude $B = 0.3 \text{ m s}^{-1} \text{ pa}^{-1}$ and the vectoring angle $\theta = 55^\circ$ with respect to the wind
 141 stress direction. Near the equator (25° S-25° N), the latitude-dependent parameters B and θ derived
 142 by Lagerloef et al. (1999) are adopted which are related to the Coriolis force parameter f , the water
 143 density $\rho = 1025 \text{ kg m}^{-3}$, the linear drag coefficient $r_e = 2.15 \times 10^{-4} \text{ m s}^{-1}$, and the friction depth
 144 ($h_e = 32.5 \text{ m}$),

$$145 \quad B = \frac{1}{\rho} (r_e^2 + f^2 h_e^2)^{-\frac{1}{2}} \quad (2a)$$

$$146 \quad \theta = \arctan \left(\frac{f h_e}{r_e} \right). \quad (2b)$$

147 A climatological annual mean of Ekman currents as well as the geostrophic, Stokes, and tidal
 148 components is shown in Fig. 2. It seems that the uncertain assessment scheme of parameters (B
 149 and θ) within equatorial band proposed by Lagerloef et al. (1999) leads to high Ekman current
 150 velocities, which contradicts the theory of calm belt near the equator. Although previous studies
 151 have calibrated parameters (B, θ) by using the least squares fit based on ageostrophic wind-driven
 152 velocities obtained by subtracting geostrophic component from the drifting buoy velocities, it does
 153 not constitute a fully independent validation with our reference field in this study. Accurate and
 154 independent parameter scheme of wind-driven velocities may be an improvement of this work in
 155 the future.

156 Subject to wind stress intensity and the viscosity coefficient of seawater, the friction depth of wind-
 157 driven currents (or Ekman depth) is locally adaptive, ranging from a few meters to hundred meters.
 158 A verification is necessary that the mixing depth of the Ekman layer reaches the position of the
 159 drogued drifters. Following a linear steady momentum balance in Eq. (3a) and Eq. (3b) proposed



160
 161 **Figure 2:** Global annual climatological flow fields. The left column represents flow speed of (a)
 162 geostrophic currents for 1999-2019, (b) Ekman currents for 1999-2019, (c) Stokes drift for 2013-
 163 2019, (d) tidal currents for 2013-2019, and (e) drifter observations for 1999-2019. While the
 164 right column is the flow direction.

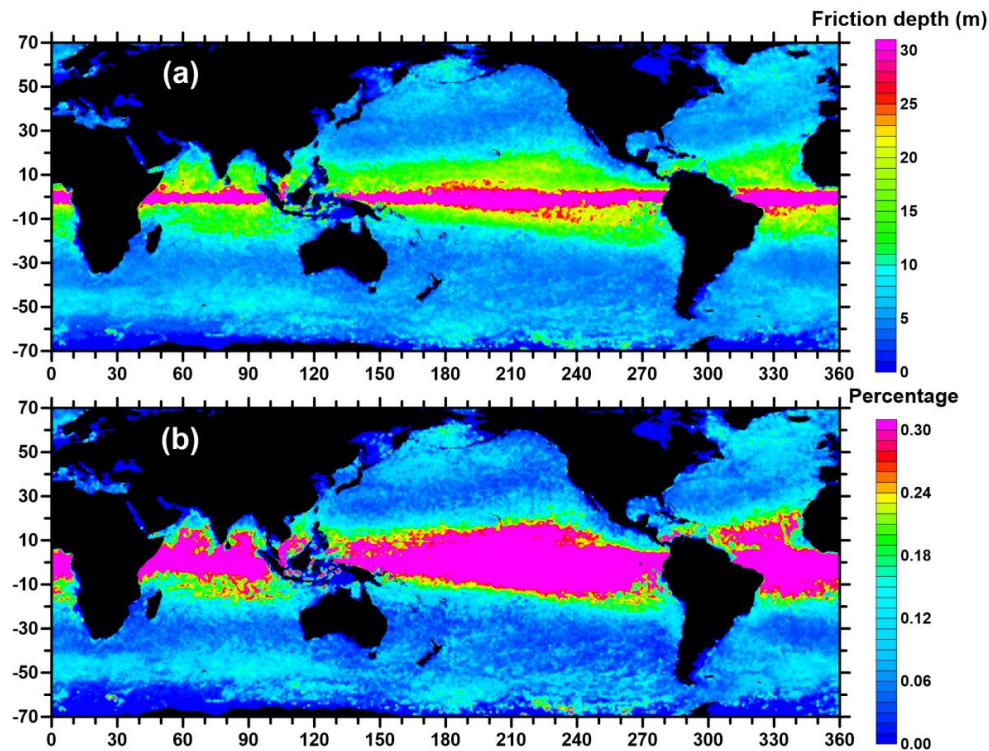


Figure 3: (a) Global mean distribution of the friction depth per $1^\circ \times 1^\circ$. (b) Proportion of friction depth up to 15 m in drifter observations.

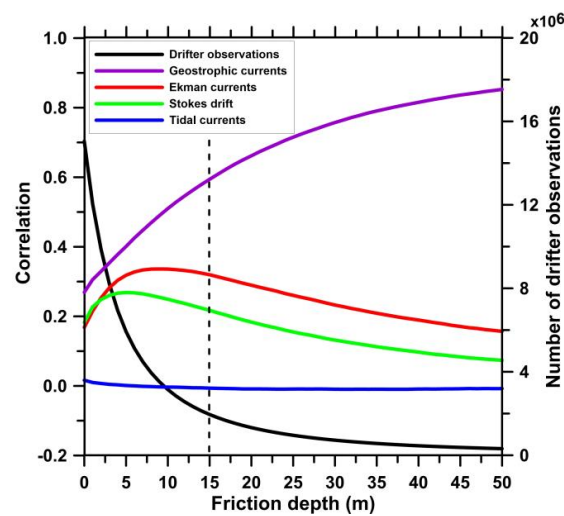


Figure 4: The correlation between four flow fields and observed velocity of drifters (left axis), and the number of drifter observations varying with Ekman depth h_e (right axis).



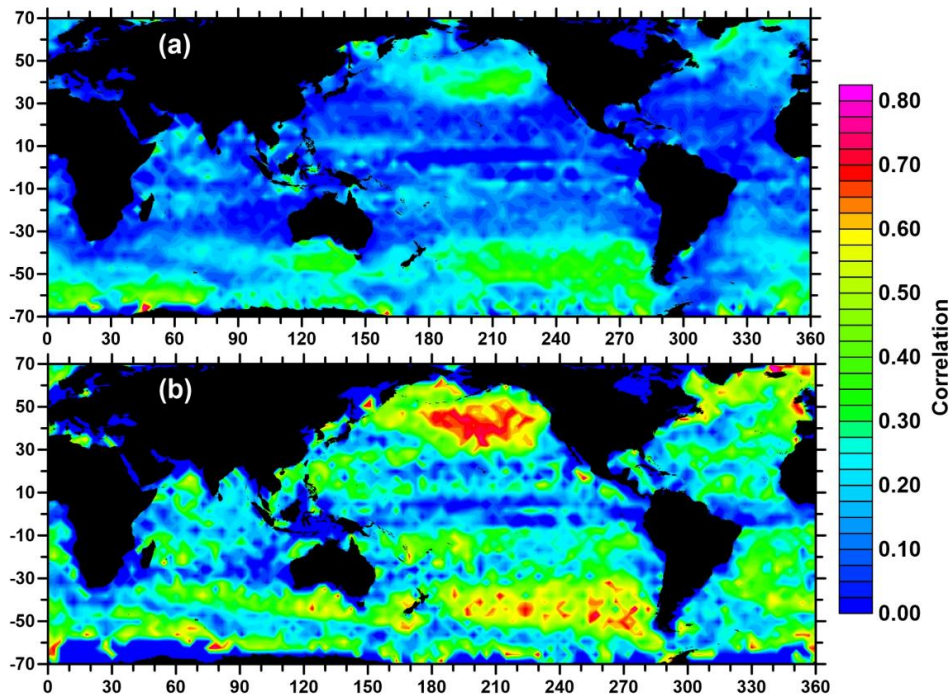
171 by Meurs and Niiler (1997) and Lagerloef et al. (1999), the friction depth h_e of Ekman currents
 172 can be expressed by Eq. (3c),

$$173 \quad fh_e \mathbf{u} + r_e \mathbf{v} = \boldsymbol{\tau}_y / \rho \quad (3a)$$

$$174 \quad r_e \mathbf{u} - fh_e \mathbf{v} = \boldsymbol{\tau}_x / \rho \quad (3b)$$

$$175 \quad h_e = \frac{1}{f} \frac{\boldsymbol{\tau}_y \mathbf{u} - \boldsymbol{\tau}_x \mathbf{v}}{\rho (u^2 + v^2)}, \quad (3c)$$

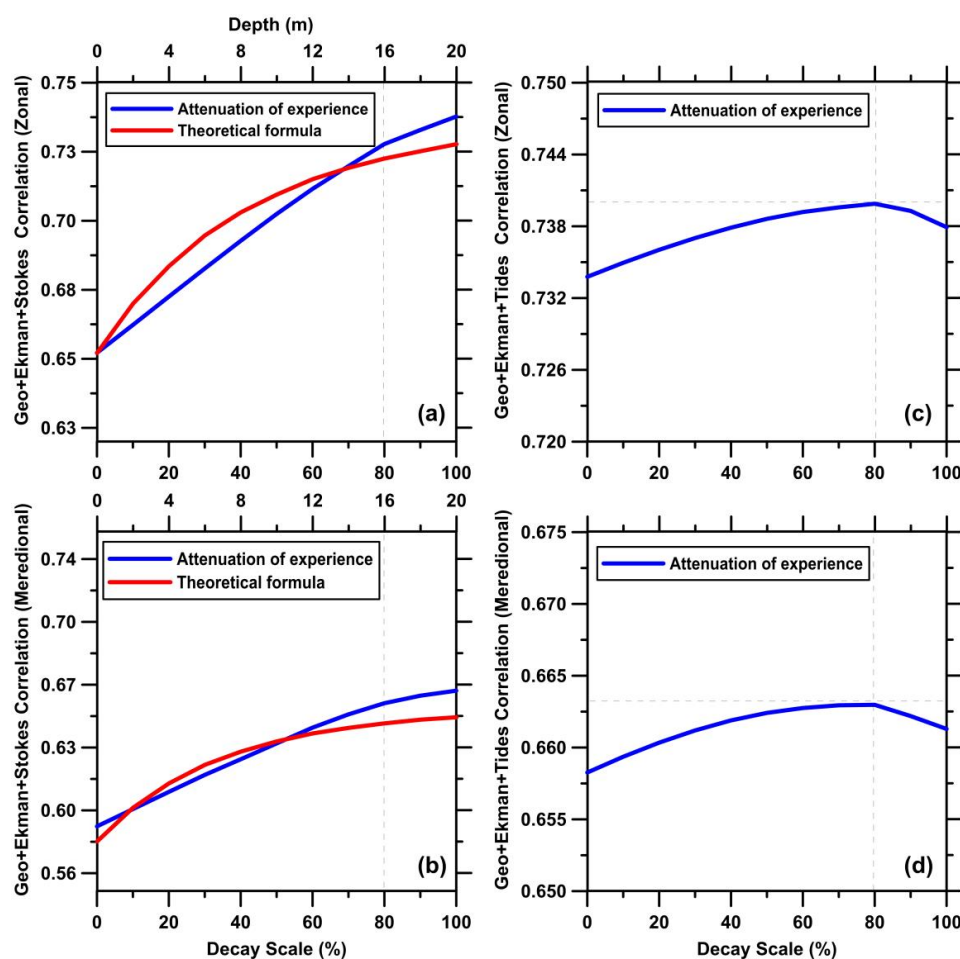
176 where u and v are ageostrophic vectors when removing geostrophic velocities from drifters
 177 observations of monthly climate state. Figure 3a illustrates a global climatological distribution of
 178 Ekman depth per 1° grid. With the deepening of Ekman depth h_e , the correlation between currents
 179 components and drifter velocities shows a trend of increase and then decrease, with the latter
 180 possibly related to the sharp decline in the number of drifter observations after the validation of
 181 wind-driven friction depth (Fig. 4). We select 15 m friction depth as the minimum threshold for



182
 183 **Figure 5:** The correlation between Ekman currents and drifter observations per 3° grid (a) before
 184 and (b) after depth validation.



185 the filtration of Ekman currents datasets by comprehensively considering the location of drogued
 186 drifters, the correlation between ocean components and drifter observations, and the change in the
 187 number of drifter observations. The ratio of drifter observations filtered by the selected friction
 188 depth (15 m) to all drifter observations indicates that about 9/10 of the quantities have been culled
 189 (Fig. 3b). Figures 5a and 5b show that the correlation between Ekman currents and drifter
 190 observations increases by ~15 % after the filtration.



191 **Figure 6:** The correlation of the zonal (top) and meridional (bottom) vector combinations of (a)-
 192 (b) geostrophic, Ekman currents, and Stokes drift, decaying with depth (top coordinate) and
 193 percentage (bottom coordinate), and (c)-(d) geostrophic, Ekman currents, and tidal currents
 194 decaying with percentage.
 195



3.2 Decay scales of Stokes drift and tidal currents

The reanalysis Stokes drift and tidal currents cover 0 m vertically and need to be attenuated by empirical percentage method and exponential method that can be expressed in Eq. (4),

$$\mathbf{u}_s = \mathbf{u}_{s0} \exp(2kz), \quad (4)$$

where u_{s0} denotes the surface Stokes drift, z is the profile derived from a monochromatic wave with wavenumber k and wavelength (Kukulka and Harcourt, 2017). As shown in Figs. 6a-6d, the correlation between drifter observations and different vector combinations of geostrophic, Ekman, tidal currents, and Stokes drift, increases ceaselessly with depth when using the theoretical formula and, for tides, reaches peaks at 80 % attenuation when adopting the percentage decay method. Thus, the 80 % decay ratio is used for Stokes drift and tidal currents before the subsequent estimation of surface current.

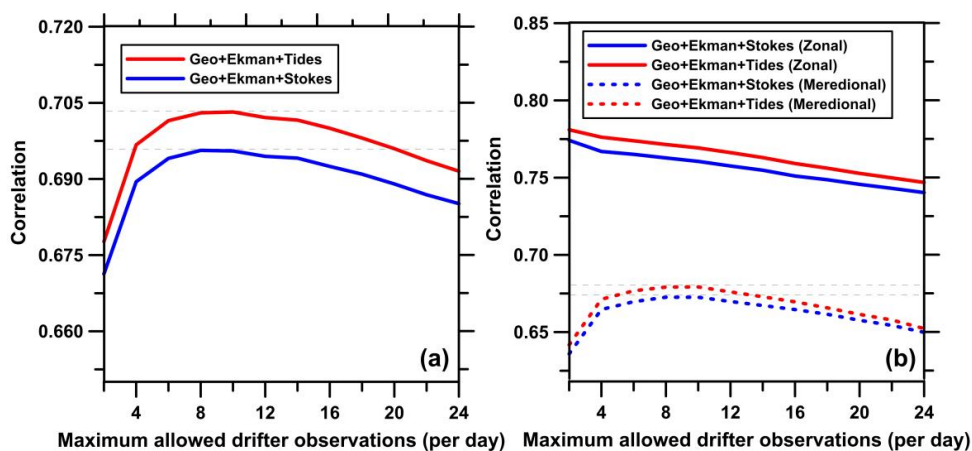


Figure 7: The correlation of different combinations of geostrophic, Ekman, tidal currents, and Stokes drift varying with maximum allowed drifter observations per day corresponding to (a) vector synthesis and (b) zonal and meridional vector.

3.3 Optimal time matching interval between wind fields and drifter observations

Exact correspondence matching with the retrieved time of wind field will result in insufficient drift



observations. Based on a series of experiments, we confirm that the correlation between synthesized vectors or their components of geostrophic, Ekman, tidal currents, and Stokes drift (Figs. 7a and 7b) and the maximum allowed drifter observations per day peaks near the number of 12 (i.e., the time interval is no more than 6 hours).

3.4 Correlation analysis of ocean current components with drifter observations

A new drifter data set has been constructed by matching the pre-processed geostrophic currents, Ekman currents, Stokes drift and tidal currents. We then reveal the coefficient of the Pearson correlation between ocean components and drifter observations referring to Eq. (5) which is related to true observations (x_i, y_i) and the averaged ones (\bar{x}, \bar{y}) ,

$$Pearson = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}}. \quad (5)$$

Going through Figs. 8a-8d, the contribution of each component to the flow field is clearly evident. Geostrophic currents act as the primary mechanism that form the ocean surface current field, and the Pearson correlation coefficient can reach nearly 0.98 in the regions with strong and persistent

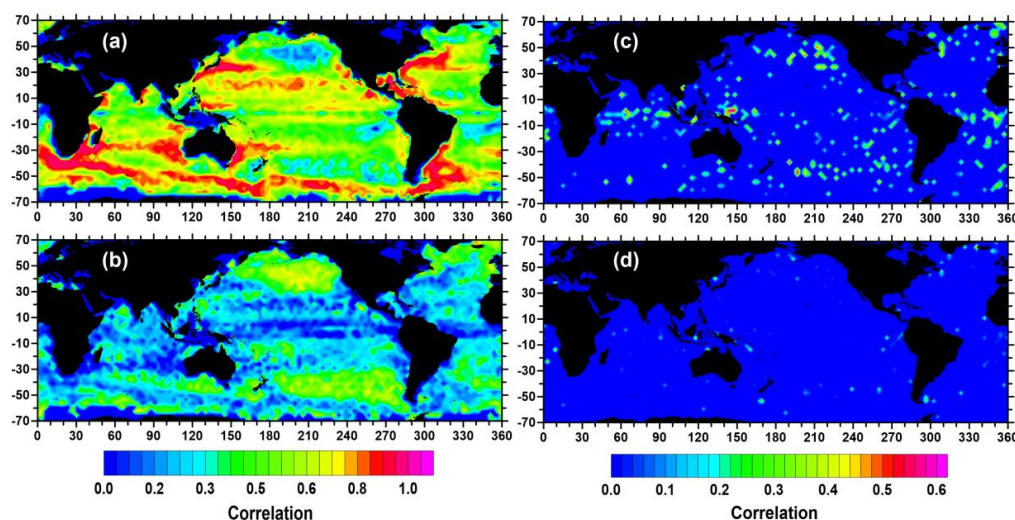


Figure 8: Geographical distribution of the Pearson correlation coefficient of (a) geostrophic currents, (b) Ekman currents, (c) Stokes drift, and (d) tidal currents.



currents along the western boundary. Moreover, wind-induced Ekman currents contribute significantly in the westerly zone of the northern and southern hemispheres, while are not noticeable near the equator, which may be related to the calm zone in the tropics. At the same time, Stokes drift can contribute up to 60 % in the West Pacific, while tidal currents work mainly in the shallow coastal area with the maximum value of 0.5, which is consistent with its higher velocities along the coast.

3.5 Optimal GEST model for estimating ocean surface current

Given the seasonal and local variability in velocity and direction of the surface current, we first build least-squares linear regression (Eq. (6)) on a 3° grid by season using different flow field combinations (Sub-GE (Geostrophic-Ekman), Sub-GES (Geostrophic-Ekman-Stokes), Sub-GET (Geostrophic-Ekman-Tide), and Sub-GEST (Geostrophic-Ekman-Stokes-Tide)) to determine the optimal configuration of the flow field components,

$$E = \sum_{i=1}^n e_i^2 = \sum_{i=1}^n (y_i - \hat{y}_i)^2, \quad (6)$$

where \hat{y}_i is the predicted observation, y_i is the true ones, and n is the number of observations. Four initial datasets, called GEST-1, were obtained based on the sub-models above (Sub-GE, Sub-GES, Sub-GET, Sub-GEST) by using the data from 2006-2012. We verified the error of the GEST-1 versus drifter data with root mean square error (RMSE),

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n (\hat{y}_i - y_i)^2}. \quad (7)$$

Table 1 shows a regional comparison regarding the reconstruction errors of the sub-models. In the Antarctic Circumpolar Current (ACC) where the GE model has a higher accuracy, it seems that the inclusion of tidal currents and Stokes drift contributes to signal noise, while in the equatorial regions of Pacific and Indian Ocean, the results of the Sub-GEST are significantly better than other combinations. In addition, compared with Sub-GE model (Figs. 9a and 9b), the Sub-GES is more effective mainly in the western equatorial Pacific, such as the Peninsular Malaysia and Marshall Islands (Figs. 9e and 9f). Furthermore, as shown in Figs. 9g and 9h, the averaged RMSE of Sub-



GET in the south coast of Kyushu Island decreased to 11.35 cm/s from about 11.75 cm/s of the Sub-GE (Fig. 9c), and the Gulf of Mexico also decreased about 0.3 cm/s than Sub-GE (Fig. 9d) with a maximum decrease of up to 10 % in this region, which is likely related to frequent tropical

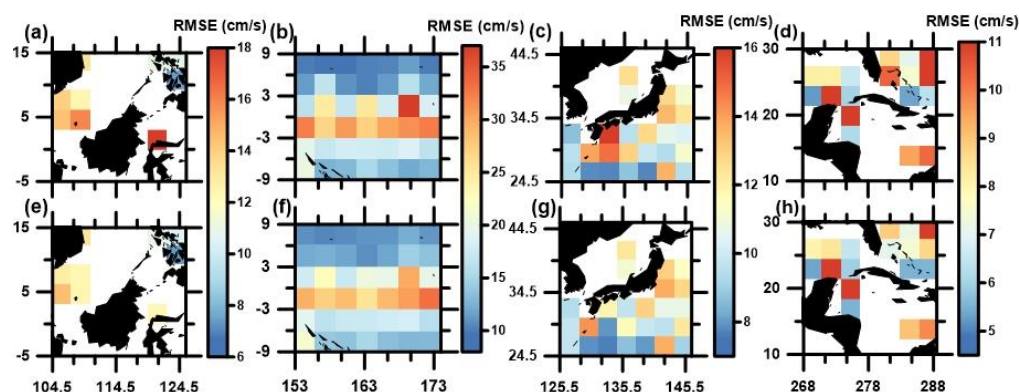
Table 1. Verified RMSE (cm/s) based on Sub-GE/ Sub-GES/ Sub-GET/ Sub-GEST models

Reconstruction Model	Longitude and Latitude			
	55° E-70° E	80° E-100° E	103° E-113° E	125° E-142° E
	10° S-5° N	45° S-60° S	3° N-19° N	22° N-37° N
Sub-GE	22.0333	9.1091	12.3418	11.7525
Sub-GES	20.9319	9.2731	11.9773	11.9136
Sub-GET	23.3724	9.2368	12.4657	11.3579
Sub-GEST	20.6216	9.3872	12.0061	11.4845
Reconstruction Model	Longitude and Latitude			
	156° E-173° E	175° E-195° E	228° E-240° E	260° E-290° E
	10° S-10° N	40° S-55° S	9° S-21° S	18° N-28° N
Sub-GE	16.9963	7.1911	6.5527	7.9553
Sub-GES	16.4886	7.3135	6.5541	8.0693
Sub-GET	17.0196	7.2609	6.5225	7.6361
Sub-GEST	16.5005	7.3945	6.5184	7.8609

cyclone activities in the Gulf of Mexico and the southern coast of Kyushu Island. From August to October, the South Kyushu Island is vulnerable to tropical cyclones in the Northwest Pacific Ocean, while storm surges in the north dominate in the Gulf of Mexico. Driven by typhoons, seawater



261 rises steeply to form storm surges, with water levels sometimes reaching 5 m. When storm surges
 262 are superimposed on astronomical surges, the magnitude of water level changes could be even
 263 greater (Murty et al., 1986; Dube et al., 1997; Bilskie et al., 2016).



264
 265 **Figure 9:** RMSE of (a)-(d) Sub-GE, (e)-(f) Sub-GES, and (g)-(h) Sub-GET models.

266 As mentioned above, wave-induced Stokes drift and tidal currents contribute significantly only in
 267 certain regions (see Table 1) and should not be joined entirely on a global scale. Thus, the optimal
 268 GEST model was chosen from the above sub-models (Sub-GE, Sub-GES, Sub-GET, and Sub-
 269 GEST) per $3^\circ \times 3^\circ$ grid by the error validation of the regression, and then was used for the estimates
 270 of ocean surface current incorporating geostrophic and Ekman currents, Stokes drift, and tidal
 271 currents.

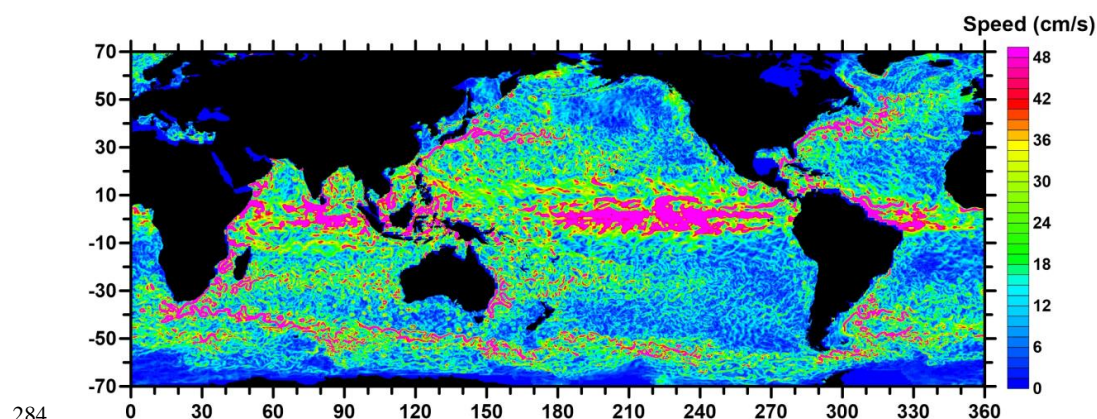
272 4 Result and discussion

273 4.1 GEST products and associated verification

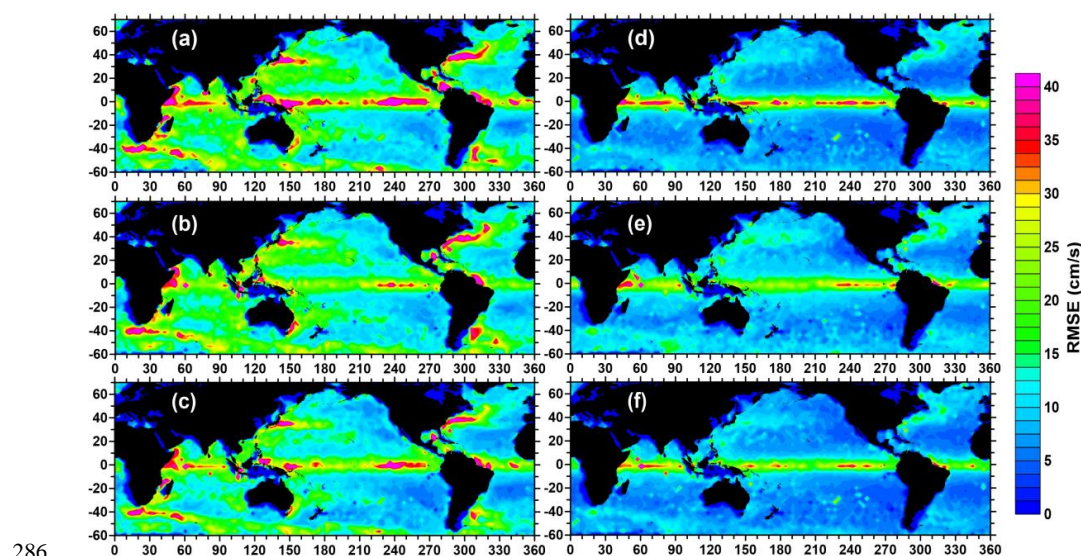
274 Following the optimized reconstruction scheme outlined above, a 0.25° resolution data set named
 275 GEST, such as the daily current velocity on a particular reference date (Fig. 10), was obtained
 276 combining the geostrophic flow with other field components. We have also considered building
 277 products with 1° resolution by matching other flow fields with Ekman currents, but quantitative
 278 validations showed that the 0.25° reconstructed field significantly decreased global averaged
 279 RMSE from about 14.61 cm/s to 9.36 cm/s over the 1° resolution product. Figures. 11a-11c show



280 the global distribution of the RMSE for 1° product, with significant errors in the western boundary
 281 currents and the Kuroshio area. It appears that intense kinetic energies of mesoscale eddies exist
 282 in these regions (Fig. 12) and likely neglected by the coarse spatial resolution (Chen and Han,
 283 2019).



285 **Figure 10:** Daily current field of the GEST product on 01 January 2017.



286 **Figure 11:** The RMSE of the 1° reconstructed field of (a) zonal vector, (b) meridional vector,
 287 and (c) synthetic vector, and the 0.25° reconstructed field of (d) zonal vector, (e) meridional
 288 vector, and (f) synthetic vector with the optimal GEST model.
 289



Moreover, compared with the estimates of regression theory, we find that the optimal vector synthesis scheme has a higher reconstruction accuracy in estimating the 0.25° resolution field, and additionally, traditional geostrophic and Ekman currents model is also available in regions without reference velocities. As shown in Figs. 11d-11f, the RMSE of the optimal vector synthesis method (8.99 cm/s) decreases by almost 0.4 cm/s compared with the optimal regression method (9.36 cm/s).

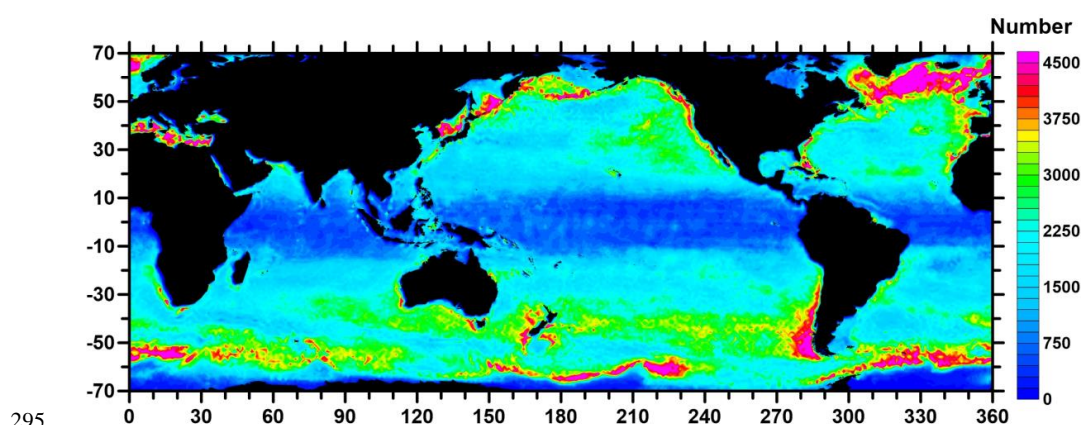


Figure 12: The global distribution of mesoscale eddies.

4.2 Comparison of the GEST to other global surface current products

Excellent achievements have been made in physical model-based reconstructions of ocean surface current. The OSCAR near-surface current with a grid size of 1° on a 5 days basis use the quasi-linear, quasi-steady sea surface momentum equations and improve the equatorial algorithm by fitting 12 orthogonal polynomials (Johnson et al., 2007). Meanwhile, the GlobCurrent data set presents an improved empirical Ekman model and a global 0.25° MDT by exploiting information from geostrophic currents and the drogued drifters. Figures. 13a and 13c show the estimate errors of the OSCAR and GlobCurrent products when compared with the velocity of the drogued drifters. The RMSE of GlobCurrent is, on average, ~ 2 cm/s smaller than OSCAR data due to the coarse temporal resolution and finite spatial distribution of T/P and Jason series altimeter data used in OSCAR currents. Another promising finding is that a reduction of up to 7-8 cm/s in RMSE is observed for both products when compared to drifters of which friction depths of matched Ekman currents are up to 15 m (Figs. 13b and 13d).

In this paper, we are not able to further consider the drogue lost information because 90 % of



drifter observations are discarded with the condition of friction layer. As evidenced in Fig. 11f, the RMSE of GEST product is reduced to 8.99 cm/s compared to 12.55 cm/s for the OSCAR product, and 9.28 cm/s for the GlobCurrent, and especially in the eastern equatorial Pacific, our approach is quite efficient with an error reduction of up to 10 cm/s than that of OSCAR and GlobCurrent. In the tropical Indian Ocean and western Pacific regions, while the GEST currents show better accuracy than the GlobCurrent, the OSCAR currents outperformed both products, possibly related to the improved equatorial algorithm proposed by Bonjean and Lagerloef (2002).

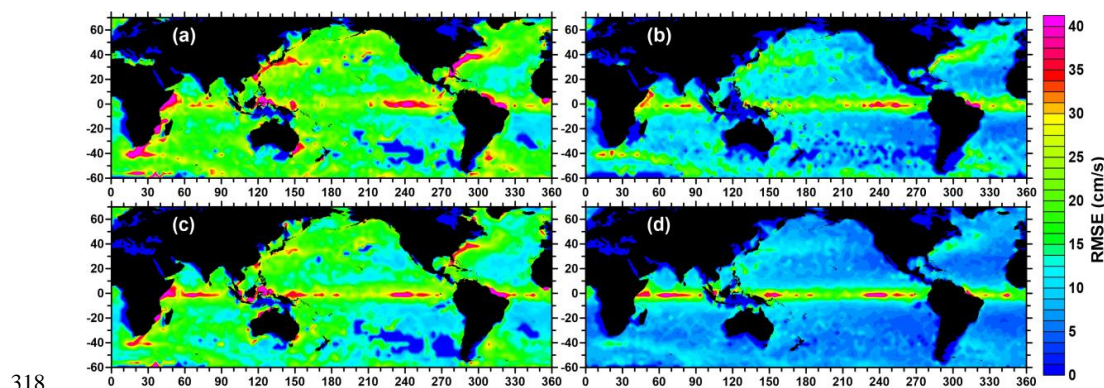
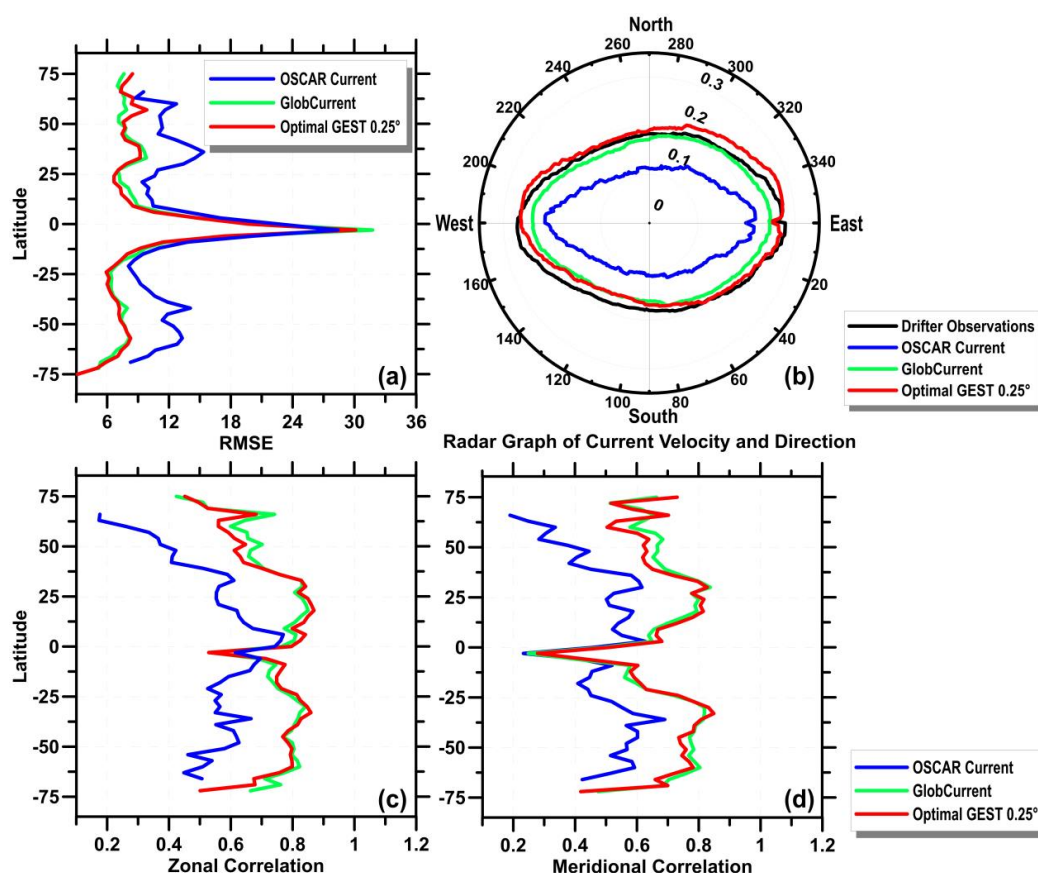


Figure 13: RMSE between (a) OSCAR currents and drogued drifters, (b) OSCAR currents and the drifters verified by a friction depth of 15 m, (c) GlobCurrent and drogued drifters, (d) GlobCurrent and the drifters verified by a friction depth of 15 m covering the years 2013-2017.

In addition, the reconstruction error with 1° latitudinal band was calculated for each product, as well as the comparison of flow direction by radar maps, to assess the regional difference of the estimation accuracy. It is quite evident that both GlobCurrent and GEST reflect better estimation trends outside the equator due to the fine resolution (Fig. 14a). In particular, the GEST product outperforms GlobCurrent within 60° S- 50° N, which is consistent with research showing that tides and Stokes drift reveal significant results in coastal and equatorial regions concentrating at low- and mid-latitudes. At the equator, despite the lower spatial and temporal resolution of the OSCAR data set, it also shows significant consequence with the drifter observations. Figure 14b shows that GEST product has a better estimation of drifter velocity within 0° - 270° angle range of the flow direction than others. The lower efficiency at high latitudes and in the 270° - 320° angle range is



likely related to Rio et al. (2014) assimilating the drift observations used as reference fields in this paper to provide missing short-scale information in the calculation of the CNES-CLS13 MDT and wind-driven parameters with spatio-temporal variability.



335

Figure 14: (a) RMSE based on latitudinal bands between each current product (the global OSCAR current (blue line), the GlobCurrent (green line), the modified 0.25° GEST current (red line)) and the surface drifters verified by a friction depth of 15 m. (b) A radar diagram of flow velocity and direction versus the drifter observations (black line), the global OSCAR current (blue line), the GlobCurrent (green line), and the modified GEST current (red line). (c) The zonal correlations and (d) the meridional correlations for the global OSCAR current (blue line), the GlobCurrent (green line), and the modified 0.25° GEST current (red line).



343 To further verify the robustness of the results, the correlation between the ocean current products
 344 and drifter velocities in each latitudinal zone was calculated separately. As shown in Figs. 14c and
 345 14d, the GEST product is behind GlobCurrent by about 5 % of the correlation within 40° and 55°
 346 in the Northern Hemisphere. And it, in contrast, shows higher correlation coefficients at low to
 347 mid latitudes of the Southern Hemisphere. In the equatorial region, both pieces of products
 348 remained inferior to the OSCAR data for the horizontal component, being consistent with the
 349 results of the RMSE. However, the GEST product delivers better results of meridional correlations
 350 possibly due to the addition of Stokes drift.

351 It is notable that existing current products have poor estimates in the equatorial within 10° S-10°
 352 N and western boundary currents. A plausible interpretation is that the parameters of wind-driven
 353 model and the higher-order balance of geostrophic velocities are still uncertain. Furthermore,
 354 previous studies have indicated that ocean eddies and large-scale planetary waves (e.g., Rossby
 355 and Kelvin waves) correspond to ocean circulation at different scales. Especially in the equatorial
 356 band, the fluctuation significantly contributes well to the upper ocean circulation. In particular, the
 357 scale of the zonal component of the eastward Kelvin wave is more significant than that of the
 358 meridional component (Forbes, 2000), which may influence the inversion accuracy of the zonal
 359 feature in the equatorial region. Meanwhile, the complex aliasing effect between intense ocean
 360 currents, eddies with strong kinetic energies, and large-scale planetary waves with strong
 361 fluctuations, is also likely to be an important factor affecting the reconstruction accuracy in this
 362 study (Hansen and Paul, 1984; Klocker and Marshall, 2014; Huang et al., 2021; Chen et al., 2022).

363 **5 Data availability**

364 All data used in this study are publicly available, and are listed in Table 2. The TPXO9-atlas for
 365 tidal currents is available for academic research and other non-commercial uses under previous
 366 registration from <https://www.tpxo.net/global/tpxo9-atlas> (Egbert et al., 2018). The GEST
 367 product produced in this research can be found at <https://doi.org/10.5281/zenodo.7767202>.

368 Table 2. Remotely sensed, in situ, and reanalysis data sets used in this paper.



Data set	Link	Citation
Geostrophic current	https://data.marine.copernicus.eu/product/SEALEVEL_GLO_PHY_L4_MY_008_047/	Pujol et al. (2016)
Ocean Waves Reanalysis data	https://data.marine.copernicus.eu/product/GLOBAL_MULTIYEAR_WAV_001_032/	Law-Chune et al. (2021)
WindSat products	https://www.remss.com/missions/windsat/	Wentz et al. (2013)
Quikscat products	https://www.remss.com/missions/qscat/	Wentz et al. (2011)
Global Drifter data	https://www.aoml.noaa.gov/phod/gdp/hourly_data.php	Elipot et al. (2022)
OSCAR current	https://search.earthdata.nasa.gov/downloads/6873202440	Johnson et al. (2007)
GlobCurrent product	https://tds0.ifremer.fr/thredds/GLOBCURRENT/GLOBCURRENT.html?dataset=GLOBCURRENT-L4-CUREUL_15M-ALT_SUM-V03.0	Rio et al. (2014)

369

370 **6 Concluding remarks**

371 It is understood that there are multi-scale dynamic processes in ocean surface current, among
 372 which large-scale geostrophic circulation and wind-induced Ekman flow are widely considered,
 373 while small-scale wave phenomena are ignored. In view of the facts, a new reconstruction product
 374 of the global ocean flow field at a depth of 15 m integrating Geostrophic, Ekman, Stokes, and
 375 Tidal components is produced in this research, leading to the following conclusions:

376 (1) Multi-scale dynamics-based GEST product of ocean surface current is reliable because of the



declining RMSE of the 0.25° resolution product which is found to be about 3.6 cm/s lower than the OSCAR product, and 0.3 cm/s lower than the GlobCurrent. In particular, the inclusion of wave-induced tidal currents and Stokes drift improves the precision of the reconstruction mainly in equatorial and coastal regions.

(2) The verification of the wind-driven friction depth with local applicability in reconstructing GEST product is significantly necessary, as evidenced by an 18 % increase in the correlation coefficient between Ekman currents and drifter velocities.

(3) It has been revealed that high-resolution product with a $0.25^\circ \times 0.25^\circ$ cell has a closer agreement to drifting buoys by revealing most of the mesoscale eddy kinetic energy missed by 1° resolution product and is likely to be a better indicator of the real ocean circulation given the improved accuracy of 5.62 cm/s.

It is worth pointing out that, in contrast to the existing ocean current estimation products mentioned above, better results of the proposed GEST dataset at low to mid-latitudes are obtained independently without assimilation of any drifter observation. In the future, complex mechanisms (e.g., planetary waves, eddies, etc.) will be taken into account in the equatorial and strong current regions to achieve a more accurate reconstruction of the global flow field.

Author contribution

GYW drafted the manuscript, developed the data processing, and designed the experiment. GC contributed to conceptualizing the project, supervising, reviewing and editing the paper. CCC developed the data processing and edited the paper. XYZ edited and reviewed the paper. BXH supervised and reviewed the paper.

Competing interests

The authors declare that they have no conflict of interest.

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403 Science Physical Oceanography Program. RSS WindSat data are available at www.remss.com.
 404 QuikScat (or SeaWinds) data are produced by Remote Sensing Systems and sponsored by the
 405 NASA Ocean Vector Winds Science Team. Data are available at www.remss.com.

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