



A global Lagrangian eddy dataset based on satellite altimetry

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1 Abstract.

The methods used to identify coherent ocean eddies are either Eulerian or Lagrangian in nature, and nearly all existing eddy 2 3 dataset are based on the Eulerian method. In this study, millions of Lagrangian particles are advected by satellite-derived surface geostrophic velocities over the period of 1993–2019. Using the method of Lagrangian-averaged vorticity deviation (LAVD), 4 we present a global Lagrangian eddy dataset (GLED v1.0, Liu and Abernathey, 2022, https://doi.org/10.5281/zenodo.7349753 5 6). This open-source dataset contains not only the general features (eddy center position, equivalent radius, rotation property, etc.) of eddies with lifetimes of 30, 90, and 180 days but also the trajectories of particles trapped by coherent eddies over the 7 lifetime. We present the statistical features of Lagrangian eddies and compare them with those of the most widely used sea 8 surface height (SSH) eddies, focusing on generation sites, size, and propagation speed. A remarkable feature is that Lagrangian 9 10 eddies is generally smaller than SSH eddies, with a radius ratio of about 0.5. Also, the estimated mass transport by Lagrangian eddies is nearly an order of magnitude smaller than that by the Eulerian calculation, indicating that the coherent contribution 11 to the total eddy transport is very limited. Our eddy dataset provides an additional option for oceanographers to understand the 12 interaction between coherent eddies and other physical or biochemical processes in the Earth system. 13

14 1 Introduction

Mesoscale eddies, defined as rotating structures ranging typically from tens to hundreds of kilometers and lasting for several 15 weeks to months, are ubiquitous in the global ocean (Fu et al., 2010; Chelton et al., 2011b, hereinafter CS11). And these eddies 16 17 can trap, transport, and stir tracers such as heat, salt, and biochemical components in the ocean, thereby playing significant roles in nutrient distribution (Chelton et al., 2011a; Frenger et al., 2015), large-scale ocean circulation structure (Abernathey 18 19 and Marshall, 2013; Liu et al., 2022b), and modulating climate variability (Busecke and Abernathey, 2019; Li et al., 2022). Isolated mesoscale eddies in the ocean are generally considered as coherent structures with a material barrier that can trap the 20 21 fluid within the eddy interior (Haller, 2015). Therefore, understanding the eddy structure and the degree of material transport by eddies are key issues for more accurate parameterization of mesoscale eddies in coarse-resolution climate models. To achieve 22 this goal, herein we seek to produce a global coherent eddy dataset based on satellite observations. 23



Many methods have been proposed to identify mesoscale eddies from numerous oceanic databases such as satellite maps, 24 25 numerical simulation products, and Argo floats. These existing methods generally fall into two categories: Eulerian and La-26 grangian (Haller, 2015; Abernathey and Haller, 2018). The core idea of Eulerian methods is to detect the eddy boundary based 27 on certain physical or geometrical contours from the instantaneous flow field, and then track these boundaries at neighboring times. Frequently used Eulerian eddy boundaries includes contours of Okubo-Weiss parameter, sea surface height (SSH; 28 CS11), potential vorticity (Zhang et al., 2014), velocity streamlines (Nencioli et al., 2010), etc. By contrast, rather than depend-29 ing on instantaneous images, Lagrangian methods examine trajectories of water parcels over a finite time interval to identify 30 the skeletons of coherent structures. Different techniques such as finite-time Lyapunov exponents (Shadden et al., 2005), finite-31 scale Lyapunov exponents (d'Ovidio et al., 2009), and Lagrangian-avergaed vorticity deviation (LAVD; Haller et al., 2016) 32 have been proposed for eddy detection. Both Eulerian and Lagrangian methods have advantages and disadvantages. 33

34 The most significant advantage of Eulerian methods is their operational simplicity: if continuous images of flow fields are available, then searching for eddy centers and boundaries is not challenging. This feature means that Eulerian methods are used 35 36 extensively, especially for SSH eddies (following geostrophic equilibrium) derived from the sea level anomaly (SLA). And the development of satellite observations facilitates eddy identification on a global scale. Using 16 years of altimetry maps with 37 38 weekly intervals, the first mesoscale eddy dataset was produced (CS11) and the general features of mesoscale eddies were analyzed statistically. Later, Faghmous et al. (2015) presented a global SSH eddy dataset over the period of 1993–2014 using 39 40 the daily altimetry product and a SLA-based method similar to that used in CS11. Until 2016, the eddy census of CS11 was updated routinely by a research team at Oregon State University, then in 2017 its operation was transferred to CLS/CNES, 41 and it is now distributed by AVISO as the Mesoscale Eddy Trajectory Atlas (META). Several versions of this dataset-from 42 META1.0exp to META3.1exp-are available to users, and Pegliasco et al. (2022) described the improvements from one release 43 to the next. In addition, Dong et al. (2022) constructed a multi-parameter eddy dataset based on the velocity vector field from 44 45 satellite observations. These Eulerian eddy datasets have been used widely to study the interaction between mesoscale eddies and other processes of the Earth system. 46

Mesoscale eddies are generally believed to be able to trap and transport the interior fluid when the nonlinearity parameter 47 U/c is greater than 1, where U is the azimuthal eddy speed and c is the eddy propagation speed. Statistics suggest that more 48 49 than 90% of observed SSH eddies satisfy this criterion (CS11). By assuming no effective water exchange between the eddy interior and background flows, many studies have conducted estimates of heat, salt, and mass transports by Eulerian eddies 50 51 on regional and global scales (Dong et al., 2014; Zhang et al., 2014; Frenger et al., 2015; He et al., 2018). Among them, the most appealing result shows that the westward zonal eddy mass transport in the subtropical gyre can reach 30–40 Sv, which 52 53 is surprisingly comparable to the wind-driven gyre transport (Zhang et al., 2014). However, many recent works provide clear evidence that Eulerian methods strongly overestimate the degree of material transport by mesoscale eddies. Observations and 54 55 numerical simulations both suggest that Eulerian eddies are far from coherent structures because there is strong and persistent water exchange across the Eulerian eddy boundary (such as the SSH contour) during the eddy lifespan (Beron-Vera et al., 56 2013; Wang et al., 2016; Liu et al., 2019, 2022a). The contribution of coherent structures to the total eddy transport is very 57 58 limited, and most eddy transport is induced by incoherent motions such as swirling and filamentation outside the eddy cores



(Wang et al., 2015; Abernathey and Haller, 2018; Zhang et al., 2019; Xia et al., 2022). In addition, U/c has been shown to be an ineffective indicator of eddy coherent transport because the leakage magnitude of initially trapped water is generally significant and does not depend on this parameter (Liu et al., 2022a). The overestimation of coherent eddy transport might be attributed to the common shortcomings of Eulerian methods (see discussion in Haller, 2015; Abernathey and Haller, 2018). The essential issue is that Eulerian eddy boundaries detected at neighboring times do not necessarily trap the same fluid, and this can be rectified under the Lagrangian framework.

Lagrangian coherent structures have been identified successfully using different techniques. And these eddies can truly trap 65 and transport materials for a certain distance without obvious leakage. However, few studies employ Lagrangian eddies to 66 estimate eddy material transport for the following potential reasons. First, compared with the contour searching of Eulerian 67 methods, Lagrangian algorithms are much more complicated for calculating some physical parameters (e.g., LAVD; details 68 in Section 2) over a time interval. Second, flow fields with high spatial and temporal resolutions are needed to drive millions 69 of Lagrangian particles, which brings huge calculation and storage pressures. Third, the definition method determines that 70 71 Lagrangian eddies have a preset duration, rather than a free duration like Eulerian eddies, and identifying Lagrangian eddies with different lifetimes is also computationally expensive. 72

73 Recently, Abernathey and Haller (2018) used satellite-derived geostrophic velocities in the eastern Pacific to advect Lagrangian particles, and they used the LAVD method to identify rotationally coherent Lagrangian vortices (RCLVs, also called 74 75 Lagrangian eddies) over a period of 25 years, which is the first large-scale application of objective Lagrangian eddy detection. Based on numerical model outputs, Xia et al. (2022) used the three-dimensional LAVD method to detect global coherent 76 eddies, and they estimated the coherent transport across each latitude or longitude to be only about 1 Sv. Tian et al. (2022) 77 also applied the LAVD method to global eddy detection and presented a 90-day RCLVs dataset, but they adopted a very tight 78 threshold to define the eddy boundary (Tarshish et al., 2018), which would greatly underestimate the size of Lagrangian eddies 79 80 (see Figure 4).

Nearly all public global eddy datasets are based on the Eulerian framework, and identifying coherent eddies is not an easy 81 task. Therefore, it is necessary to develop a global Lagrangian eddy dataset based on observational data. So far, we have 82 conducted a series of works towards this goal, including regional eddy identification (Abernathey and Haller, 2018; Liu et al., 83 84 2022a), parameter sensitivity tests (Tarshish et al., 2018), and numerical experiments (Sinha et al., 2019; Liu et al., 2019; Zhang et al., 2019). In this study, we extend the work of Abernathey and Haller (2018) to the global ocean to identify coherent eddies 85 86 using the LAVD method, and we generate a Lagragnian eddy dataset based on altimetry observations. This dataset provides not only general features (eddy center position, equivalent radius, rotation property, etc.) of eddies with lifespans of 30, 90, and 180 87 days but also the trajectory of particles trapped by coherent eddy boundaries over the lifetime, and to the best of our knowledge 88 this is the first attempt at a public eddy dataset. Also, we compare this dataset to the latest SSH eddy dataset (META3.1exp) 89 90 to understand the statistical differences between the two types of eddies. Our eddy dataset provides an additional option for oceanographers in studying the interactions between coherent eddies and other physical or biochemical processes. 91 This paper is organized as follows. Section 2 presents the complete process of generating the global Lagrangian eddy dataset. 92

92 Fins paper is organized as follows. Section 2 presents the complete process of generating the grobal Lagrangian eddy dataset.93 Section 3 illustrates the basic information of the dataset, the statistical features of coherent eddies, and the comparison with



SSH eddies. Section 4 introduces the availability of the eddy dataset and related algorithms. Finally, Section 5 provides the
summary and conclusions.

96 2 Generation of eddy dataset

97 2.1 Satellite altimetry

98 Because observational data for the subsurface flow field are quite rare, we consider only two-dimensional coherent eddies from $\frac{1}{2}$

99 the near-surface geostrophic velocity field
$$v_g = (u, v)$$
 that can be derived according to the geostrophic relation

100
$$\hat{k} \times v_g = -\frac{g}{f} \nabla \eta,$$
 (1)

where g is the acceleration due to gravity, f is the Coriolis parameter, \hat{k} is the unit vertical vector pointing upward, and η is 101 102 the SSH. In this study, we use the satellite altimetry product (SEALEVEL GLO PHY L4 REP OBSERVATIONS 008 047) distributed by the Copernicus Marine Environment Monitoring Service. This dataset merges along-track measurements from 103 several altimeter missions and interpolates them to a $1/4^{\circ}$ latitude-longitude grid. It provides daily variables including the 104 105 SLA, the absolute dynamic topography (ADT, equivalent to SSH), and the precomputed geostrophic velocities based on (1). Note that velocities in the equatorial region (within $\pm 5^{\circ}$) are estimated based on a higher-order vorticity balance (Lagerloef 106 et al., 1999) since the geostrophy is not satisfied. We choose the time period of 27 years, from 1 January 1993 to 30 December 107 2019. In addition, following the procedure described by Abernathey and Marshall (2013), a small correction to the geostrophic 108 109 velocities is applied to eliminate the divergence due to the meridional change of f and to perform no-normal-flow boundary conditions at the coastlines. 110

111 2.2 Particle advection

The first step in generating the global Lagrangian eddy dataset is to advect particles using surface geostrophic velocities (Figure 112 1). The satellite altimetry product with a $1/4^{\circ}$ grid resolution can well resolve ~ 200 km length structures in the equatorial 113 reigon, ~ 50 km length structures at the mid-latitudes, and ~ 25 km length structures at high latitudes (Ballarotta et al., 2019). 114 To reflect properly the fine structure of material transport barriers and Lagrangian eddies, it is necessary to employ an extremely 115 dense mesh of Lagrangian particles with higher resolution than the forcing velocity field (Haller et al., 2016; Abernathey and 116 Haller, 2018). However, we should not pursue high resolution particle excessively because of the consequent computational 117 and storage burdens. Sensitivity tests by Abernathey and Haller (2018) suggest that a particle spacing of $1/32^{\circ}$ is necessary 118 to identify RCLVs accurately, and in the present study we use the same resolution and release Lagrangian particles over the 119 global ocean (between 0° and 360° longitude and 80°S and 80°N latitude; Figure 2a), a total of 39 848 999 points. To our 120 knowledge, this is the highest resolution to date for a Lagrangian particle mesh applied at global scale. Note that the points on 121 122 land are masked because they never move.

The MITgcm (Adcroft et al., 2018), an open-source ocean general circulation model, is used to solve the kinematic equation for Lagrangian particles dX/dt = u, where X = (X, Y) is the position vector and u is a two-dimensional velocity field.







Figure 1. Flowchart of eddy dataset generation based on satellite observations.

The model can typically operate in either online or offline mode. Here, we employ the offline mode in which the internal dynamical kernel is turned off and velocity fields are read from preset files with a frequency of 1 day. The FLT package is enabled to track Lagrangian particles via implementing fourth-order Runge-Kutta integration. Compared with other tools for particle tracking, MITgcm provides a convenient configuration for parallel computing on a high-performance cluster, making the global calculation more efficient.

From January 1993 to June 2019, the Lagrangian particle mesh is initialized on the first day of every month, and these particles are advected forward for 180 days, amounting to 318 180-day runs in total. In the zonal direction, the periodic boundary condition is used to allow particles crossing zero longitude. Figures 2b and 2c show zonal and meridional displacements of particles in a random time interval, which clearly display some main currents (e.g. western boundary currents, zonal tropical currents, and Antarctic Circumpolar Current) and eddy-like structures. In each model run, the relative vorticity is calculated on the Eulerian grid and interpolated to Lagrangian particle positions. To reduce the storage pressure, the relative vorticity and the particle trajectory are output every 10 days, with the total volume still exceeding 20 TB.

137 2.3 Lagrangian eddy identification

For a coherent eddy, all fluid parcels along its material boundary should have the same average angular speed when rotating around the eddy core, which is analogous to solid body rotation. Based on this physical intuition, Haller et al. (2016) proposed









140 an objective vorticity-based method to identify the material boundary of a coherent eddy by searching for the outermost closed

141 contour of the LAVD. In a two-dimensional flow, given a finite time interval (t_0, t_1) , the LAVD is defined as the average of the 142 vorticity deviation along the Lagrangian particle trajectory, that is,

143
$$LAVD_{t_0}^{t_1}(x_0, y_0) = \frac{1}{t_1 - t_0} \int_{t_0}^{t_1} |\zeta'[X(x_0, y_0, t), Y(x_0, y_0, t), t]| dt,$$
 (2)

where (X, Y) is the position for the particle released initially at point (x_0, y_0) and ζ' is the instantaneous relative vorticity deviation from the spatial average over the whole domain. The LAVD (always positive) examines the average magnitude of





146 local rotation for each Lagrangian particle over the time interval. A larger (smaller) LAVD value implies that the particle rotates 147 faster (slower), with the local maximum representing the eddy center and the eddy boundary being the outermost closed LAVD 148 curve encircling the center. This definition determines that all particles inside the boundary must rotate around the eddy core 149 during the time interval, which is essentially different from Eulerian methods based on instantaneous fields.

The algorithm employed for detecting RCLVs has been described in previous studies (Abernathey and Haller, 2018; Tarshish 150 et al., 2018; Liu et al., 2019; Zhang et al., 2019; Liu et al., 2022a). Once a local LAVD maximum is determined, we search 151 outward for closed LAVD curves. There might be multiple closed contours around a center, which are all objective options for 152 the Lagrangian eddy boundary that is expected to be a convex but allowing small deviations. To confine the boundary choice, 153 two parameters are introduced here: the convexity deficiency (CD, Haller et al., 2016) and the coherency index (CI, Tarshish 154 et al., 2018). The CD is defined as the ratio of the area difference between the contour and its convex hull to the total contour's 155 area (see Figure 7 in Tarshish et al., 2018), which means that the closer CD is to zero, the closer the eddy boundary is to being 156 a convex curve. The CI examines the change in spatial compactness of particles inside the contour over a time interval, which 157 is expressed as 158

159
$$CI = \frac{\sigma^2(t_0) - \sigma^2(t_1)}{\sigma^2(t_0)},$$
 (3)

where $\sigma^2(t) = \langle |\mathbf{X}(t) - \langle \mathbf{X}(t) \rangle |^2 \rangle$, $\langle \rangle$ indicates an average over all particles and || is the standard Euclidean distance. Theoretically, the CI is less than 1 in value, and with decreasing CI, the eddy particle tends to rapidly disperse and develop filaments. The RCLV boundary is determined when the outermost contour satisfies both the CD and CI thresholds.

In this study, the combination of CD < 0.1 and CI > -1 is adopted according to the sensitivity analysis by Tarshish et al. 163 (2018). Their results indicate that CD values of 0.01, 0.1, and 0.25 are three representative thresholds for strictly coherent, 164 moderately coherent, and leaky vortices, respectively, as is shown in Figure 3a and 3b. Although a small amount of filaments 165 exists, the RCLV defined by CD < 0.1 can basically trap the initial water parcels and maintain the coherent structure over 166 the lifetime. It is clear that, the thresholds of 0.25 and 0.01 (adopted by Tian et al., 2022) will greatly overestimate and 167 168 underestimate, respectively, the size of the coherent eddy. This parameter combination has been employed successfully in our 169 previous studies (Liu et al., 2019, 2022a). In addition, we repeatedly conduct the test of RCLV identification in the random regions and time periods, and as shown in Figure 4, the determined parameters perform well in identifying RCLVs with 170 lifetimes of 30 and 90 days. 171

Except for the ability to trap and transport tracers, one of the most significant differences between Eulerian and Lagrangian 172 eddies is the fact that the LAVD is defined over a specific, fixed finite time interval. Eulerian eddy tracking, in contrast, can 173 detect eddies of arbitrary lifetimes (of course, without any guarantee of material coherence). Computational pressure dictates 174 that it is impossible to release Lagrangian particles at any time and identify Lagrangian eddies with an open lifespan, and 175 to date there is no clear solution to reconcile this difference between the Eulerian and Lagrangian frameworks. In this study, 176 177 we choose three typical lifetimes to identify Lagrangian eddies, i.e., 30, 90, and 180 days. Coherent eddies with lifetimes longer than 180 days are not considered because their number is quite limited based on our results (Figure 6) and those of 178 Abernathey and Haller (2018). (While eddies of different lifetimes in a specific location may overlap, we cannot say that they 179







Figure 3. (a) A random example of the 30-day LAVD field (color map) and three identified RCLV boundaries using three different CD values. The green dashed thick line is the eddy boundary defined by the SLA contour. (b) Initial and final particle positions trapped by three boundaries. The dashed black line is the eddy center trajectory and the black dot is the initial eddy center.

180 are the "same" eddy because they will, in general, have different material boundaries.) After identifying boundaries for all

181 eddies over 27 years from 954 LAVD fields, the related eddy parameters (such as radius and movement speed) are calculated,

182 then we conduct quality control to discard eddies with a radius smaller than 25 km and to check that all the eddy parameters

fall within reasonable ranges. At this point, the Global Lagrangian Eddy Dataset (GLED v1.0, Liu and Abernathey, 2022,
https://doi.org/10.5281/zenodo.7349753) has been generated based on satellite observations.

185 3 Results

186 3.1 Description of eddy dataset

187 GLED v1.0 contains two components. First, the general features of coherent eddies are provided in the directory named
 eddyinfo. The information about 30-day, 90-day, and 180-day eddies is stored separately in three JSON files, which contain the
 189 following attributes:

- *id*: an eddy's unique ID composed by identification date, lifetime, and eddy number in the corresponding detection
 interval;
- 192 *date_start*: generation date of the eddy;
- 193 *duration*: eddy lifespan (in days);
- *radius*: equivalent radius (in kilometers) that is derived from the area enclosed by the eddy boundary;
- *cyc*: eddy rotation type (1 for anticyclonic, -1 for cyclonic);







Figure 4. (a) 30-day LAVD (in s^{-1}) field in the northern hemisphere and 90-day LAVD field in the southern hemisphere calculating from 1 October 2016. (b) Identified boundaries (red contours) of 90-day RCLVs in the west of Australia. (c) Initial (red dots) and final (blue dots) positions of 90-day RCLVs, with black lines representing the eddy center trajectories. (d) Identified boundaries (red contours) of 30-day RCLVs in the Gulf Stream region. (e) Initial (red dots) and final (blue dots) positions of 30-day RCLVs, with black lines representing the eddy center trajectories.

- *center_lon, center_lat*: the longitude (in degrees North) and latitude (in degrees East) of the eddy center with a frequency of 10 days;
- *dx*, *dy*: zonal and meridional displacements (in kilometers) of the eddy over the eddy duration;
- *speed_x, speed_y*: averaged zonal and meridional propagation speeds (in meter per second) of the eddy, which equal the
 displacements divided by the eddy duration;
- *vort*: domain-averaged relative vorticity within the eddy boundary (in per second);
- *lavd*: domain-averaged LAVD value within the eddy boundary (in per second);

Researchers can filter the eddy data based on their studying regions, time periods, or other conditions. For example, if investigating the statistical behaviours of coherent eddies generated around the Kuroshio extension region $(25 - 35^{\circ}N, 140 - 150^{\circ}E)$, then 2445 30-day, 210 90-day, and 17 180-day eddies over 27 years will be selected for conducting the related analysis.







Figure 5. Positions of particles (colored dots) inside the eddy boundary every 10 days for randomly selected (a, d) 30-day, (b, e) 90-day, and (c, f) 180-day RCLVs. The subtitle is the unique eddy ID. Different colors denote the different times, and the blue dots represent the initial positions. The SLA fields are overlaid using black contours with solid lines for positive values and dashed lines for negative values.

Second, the trajectories of all Lagrangian particles inside the eddy boundary are provided in the directory named eddytraj, 206 which to the best of our knowledge is the first attempt at an open-source eddy dataset. We use an NC file with a three-207 dimensional array to store the particle positions every 10 days for each eddy, with the array dimensions being particle initial 208 longitude, particle initial latitude, and time. Each NC file is named by its unique eddy ID, and the grid number of the two 209 position dimensions is adjusted according to the eddy size. We randomly load six data records to show the particle positions 210 during the eddy lifetime (Figure 5), and we find that these eddies all perform well in maintaining the coherent structure. An 211 interesting phenomenon is that the eddy in Figure 5a is not initially located around a closed SLA contour, but a coherent 212 213 structure does exist. This type of coherent eddies are all neglected when using the Eulerian method (Liu et al., 2019). Another typical feature is that the coherent eddy is much smaller than the outermost closed SLA contour (Figure 5b), indicating that this 214 215 SSH eddy is highly leaky and far from a coherent structure. The second component of GLED v1.0 clearly displays the detailed process of material transport by coherent eddies, which is significant for understanding further the influence of coherent eddies 216 in the distribution of oceanic tracers, especially some biogeochemical tracers such as chlorophyll (Gaube and McGillicuddy Jr, 217 2017) and nutrients (Hughes and Miller, 2017). 218





219 3.2 General features of global coherent eddies

To assess GLED v1.0, in this subsection we calculate some statistics of global Lagrangian eddies and compare them with those of a new SSH eddy product (META3.1exp, publicly available at https://www.aviso.altimetry.fr/en/data/products/valueadded-products/global-mesoscale-eddy-trajectory-product.html). This dataset updates the detection algorithm and the tracking scheme, and changes the input sea level field from SLA to ADT (Pegliasco et al., 2022), but it is essentially the same as the eddy product proposed by CS11, falling into the Eulerian category.

225 From January 1993 to December 2019, META3.1exp provides 619 510, 166 426, and 44 329 SSH eddies with radii larger than 25 km and lifetimes longer than 30 days, 90 days, and 180 days, respectively. Our dataset contains many more short-lived 226 but fewer long-lived coherent eddies, with the numbers of 30-, 90-, and 180-day RCLVs in GLED v1.0 being 1 095 356, 116 227 656, and 13 643, respectively. Census statistics of the numbers for RCLVs and SSH eddies originating in $2^{\circ} \times 2^{\circ}$ grids over 27 228 years are shown in Figure 6. For RCLVs with the three lifetimes, the peak values of eddy number are generally located close to 229 the eastern boundaries of ocean basins, much higher than that in the western-boundary current regions (Figure 6a, 6c, and 6e). 230 This spatial feature is not in agreement with the previous analysis by CS11 and the pattern based on META3.1exp, which both 231 show SSH eddies to be distributed broadly in the mid-latitude regions between 10° N/S and 60° N/S with no obvious east-west 232 asymmetry (Figures 6b, 6d, and 6f). Compared with SSH eddies with lifetimes longer than 180 days that can be observed nearly 233 everywhere in the global ocean except for the tropics, the number of 180-day RCLVs is quite limited and they are concentrated 234 in the southwest of Australia and the interior ocean of the Atlantic. 235

236 To understand intuitively the differences between RCLVs and SSH eddies, we choose two regions-one in the northeast Pacific and the other in the Antarctic Circumpolar Current (ACC)-to display the location and size features of eddies on a 237 238 random date (Figure 7). These two regions are selected because they represent weak and strong eddy kinetic energy (EKE) scenarios. The global EKE map exhibits that the northeast Pacific is less energetic (Whalen et al., 2018) and is typically 239 240 considered as a "desert" of long-lived eddies (CS11), but numerous short-lived SSH eddies and RCLVs are distributed widely (Figure 7a). The most noteworthy feature is that RCLVs are generally smaller in size than SSH eddies and not necessarily 241 enclosed by the SSH contour. Based on their relative positions to SSH eddies, RCLVs can be classified into two categories (Liu 242 et al., 2019): overlapping and non-overlapping. The latter are quite different from traditional geostrophic eddies and appears 243 244 frequently, deserving further investigation of their structure and evolution. Another feature is that many RCLVs propagate eastward over the lifespan in this region, which has not been noticed before. As one of the most energetic regions, the ACC 245 region is rich in SSH eddies with large radii and amplitudes (Figure 7b), but few of them have a coherent core, indicating that 246 these SSH eddies cannot maintain a coherent structure for as little as 30 days. We identify only 39 30-day RCLVs in region 2, 247 much fewer than the number (124) in region 1 with the same size. The reduced number of coherent eddies along the main path 248 249 of the jet-like current can also be seen clearly in the Gulf Stream and the Kuroshio Extension regions.

We now examine the statistics of eddy radius, zonal propagation speed, and meridional propagation speed for all RCLVs and SSH eddies in 10° latitude bins, which are shown using the box plot in Figure 8. Outside of the tropical region, both types of eddies basically decrease in size with latitude, reflecting the dependence of the Rossby deformation radius on the Coriolis







Figure 6. The geographic distribution of eddy generation number in $2^{\circ} \times 2^{\circ}$ grids for (a, c, e) RCLVs and (b, d, f) SSH eddies over 27 years. Three time intervals (30, 90, and 180 days) are considered and the grid without eddies is masked.

parameter (Chelton et al., 1998), but the averaged RCLV radius is only half of the SSH eddy radius, which is consistent with 253 the regional examples shown in Figure 7 and our previous analysis in the eastern Pacific (Abernathey and Haller, 2018). In 254 the tropics, the RCLV radius is only about 40 km because there are numerous non-overlapping RCLVs with small size (not 255 256 shown). In addition, it is observed that RCLVs and SSH eddies have similar westward propagation speeds, consistent with the phase speed of long Rossby wave (Killworth et al., 1997), except for the tropical region where some RCLVs move eastward 257 with the background tropical flows. For the meridional propagation speed, its magnitude is usually lower an order than that of 258 the zonal speed, and both types of eddies have similar patterns, with the difference emerging in 30° S- 0° where there are many 259 260 RCLVs along the eastern boundary (see Figure 6a).

261 3.3 Global mass transport by coherent eddies

One application of this eddy dataset is to estimating the mass transport by coherent eddies. Following the methods used by Dong et al. (2014) and Zhang et al. (2014), we calculate the averaged zonal and meridional transport across the section for







Figure 7. Locations of 30-day RCLVs (blue dots) and SSH eddies(>30 days, black contours) in (a) region 1 (blue box in Figure 6a) and (b) region 2 (red box in Figure 6a) on 1 January 2009. The red lines are the center trajectories of the RCLVs, and the color map represents the SLA field.

264 each $1^{\circ} \times 1^{\circ}$ grid by

265
$$Q_x = \frac{\sum V_e C_x d}{NL_x}, Q_y = \frac{\sum V_e C_y d}{NL_y}, \tag{4}$$

where V_e , $C_x(C_y)$, and d are the volume, zonal (meridional) propagation speed, and lifetime of an eddy in days, respectively. \sum means the integration of all eddies over the studying period N in days, and $L_x(L_y)$ is the length of one longitude (latitude) degree. The eddy volume is calculated by $V_e = s\pi R^2 h$, where R is the eddy radius, s = 0.5 is a correction factor for the eddy vertical structure from Dong et al. (2014), and h = 500m is the eddy depth. For the purpose of comparison, we use a constant depth factor; the vertical structure of coherent eddies remains an open question, and here the focus is mainly on the *difference* between the two types of eddies. Here, 30-day RCLVs and SSH eddies with lifetimes longer than 30 days are considered from 1993 to 2019.

Figure 9 shows the global distribution of the zonal and meridional transport by RCLVs and SSH eddies (we assume temporarily that SSH eddies are materially coherent). The eddy transport patterns of the two directions based on the SSH boundary are quite similar to the results based on the potential vorticity boundary (see Figure 3 in Zhang et al., 2014) because these two methods are essentially the same. The westward mass transport in the subtropical region and the eastward transport in the ACC region are remarkable (Figure 9b), with the meridionally integrated zonal transport reaching 30–40 Sv as well. However, the estimate based on RCLVs shows different patterns of zonal transport in the northeast Pacific and the tropical regions because







Figure 8. Statistics of (a) radius, (b) zonal propagation speed, and (c) meridional propagation speed for RCLVs and SSH eddies. The box plot shows statistics of all eddies in 10° bins. The box and the black whisker span the 25th to 75th and 10th to 90th percentiles of the distribution, respectively. The black line in the box indicates the median. The means of all eddies in a bin are shown using dashed lines, blue for RCLVs and red for SSH eddies.

of RCLVs moving eastward shown in Figure 8. The eastward eddy transports in these two regions are also captured by Xia
et al. (2022) based on numerical model outputs. The peak value of meridionally-integrated zonal transport by RCLVs is only
about 5 Sv, nearly an order of magnitude smaller than the transport by SSH eddies.

The huge overestimate of eddy coherent transport under the Eulerian framework can be attributed to two potential reasons. First, the material boundary of eddies is not defined appropriately using a contour from the instantaneous flow field. Previous studies (e.g., Beron-Vera et al., 2013; Liu et al., 2019) have shown clearly that the water exchange across the Eulerian eddy boundary is very active during the eddy lifetime and the Eulerian eddy size is usually larger than the real coherent core. Second, the period for which Eulerian eddies can maintain coherency is overrated. The eddy census of Pegliasco et al. (2022) identifies more than 2000 SSH eddies with lifetimes longer than 270 days in the Eastern Pacific, but Abernathey and Haller (2018) suggest that almost no coherent eddies can live that long.







Figure 9. Global distributions of the (a, b) zonal and (c, d) meridional transport by (a, c) RCLVs and (b, d) SSH eddies in $1^{\circ} \times 1^{\circ}$ bins. Note that different colorbar ranges are used here and the transport unit is the sverdrup [Sv].



Figure 10. (a) Meridionally integrated zonal transport (in Sv) and (b) zonally integrated meridional transport by RCLVs (blue lines) and SSH eddies (red lines).

289 4 Code and datasets availablility

Our dataset GLED v1.0 is available at https://doi.org/10.5281/zenodo.7349753 (Liu and Abernathey, 2022). It is convenient to load the data using Python, Matlab, or other programming languages. Detailed examples for reading and analyzing the data using Python can be found in a GitHub repository (https://github.com/liutongya/GLED), in which we also provide the related algorithms to reproduce the generation of GLED v1.0. Users can apply these algorithms to regional or global identification of

294 coherent eddies with different lifespans based on velocity fields from observations or numerical simulations.



295 5 Conclusions

Methods employed to identify oceanic mesoscale eddies can be classified into Eulerian and Lagrangian frameworks, and nearly 296 297 all public global eddy dataset are based on the Eulerian framework (e.g., CS11) because of its operational simplicity. Eulerian eddies are generally treated as coherent structures that can transport tracers such as heat, salt, and nutrients, and they have 298 been used widely to evaluate the material transport by eddies (e.g., Zhang et al., 2014), but recent studies under the Lagrangian 299 framework have provided clear evidence that (i) Eulerian eddies are far from being coherent studies and (ii) using Eulerian 300 301 methods will greatly overestimate the degree of real coherent transport (e.g., Abernathey and Haller, 2018; Liu et al., 2019). To provide an additional option for oceanographers in studying mesoscale eddies, in this study, we proposed a global Lagrangian 302 eddy dataset (GLED v1.0) based on satellite observations. 303

Millions of Lagrangian particles with a resolution of $1/32^{\circ}$ were advected by satellite-derived surface geostrophic velocities for 180 days from the first day of every month over the period from January 1993 to June 2019. Using the LAVD method proposed by Haller et al. (2016), we identified coherent eddies (RCLVs) with lifetimes of 30, 90, and 180 days to generate GLED v1.0. This open-source dataset contains not only general features of coherent eddies (center position, equivalent radius, rotation property, etc.), but also the trajectories of particles trapped by coherent eddy boundaries over the lifetime. To the best of our knowledge, this is the first attempt to date to provide the particle positions in an eddy dataset and these data can be used to track various oceanic tracers, from physics to biology.

We compared the statistical features of RCLVs in GLED v1.0 with those of SSH eddies in META3.1exp. Unlike SSH eddies 311 312 that are broadly distributed in the global ocean basins, RCLVs tend to be generated close to the eastern boundaries, and the RCLV numbers along the main paths of western-boundary currents and the ACC are very limited. The zonal and meridional 313 propagation speeds of RCLVs are found to be qualitatively similar to those of SSH eddies in most regions, but RCLVs are 314 much smaller than SSH eddies with the radius ratio of about 0.5. Using a fixed eddy depth, we calculated the mass transport 315 by RCLVs and SSH eddies. It was found that the zonal transport by SSH eddies can reach about 30-40 Sv, consistent with the 316 PV-based estimate of Zhang et al. (2014), but the transport by RCLVs is only about 5 Sv, nearly an order of magnitude smaller 317 than the Eulerian estimate. 318

Although the estimated coherent eddy transport is quite weak, it does not mean that the role of mesoscale eddies in the material transport is insignificant. Our primary point is the contribution of coherent structures to the total eddy transport is limited, and the incoherent motions such as stirring and filamentation on the periphery of mesoscale eddies might make a leading-order contribution (Hausmann and Czaja, 2012; Abernathey and Haller, 2018). More attention is required to understand material transport by the filamentary structures, and the global particle trajectories produced by this study might be effective for studying the motion behaviour outside coherent cores.

Because of the computation and storage pressures, GLED v1.0 only provides RCLVs identified over three time intervals. And it is still unclear how to reconcile the difference between the free Eulerian lifetime and the fixed Lagrangian lifetime. In order to better satisfy the users' needs, as well as the eddy information in the dataset, we provide the related algorithms to





reproduce our results completely, from driving Lagrangian particles to RCLV identification. Users should feel free to modify the configuration (e.g., the date of releasing particles and the identification time interval) according to their own research.

Although we have produced a useful eddy dataset under the Lagrangian framework, one should note that not all studies must use Lagrangian eddies. Eulerian eddies are still convenient and meaningful when coherent structure is not the main concern. Researchers should select the suitable method and dataset based on their objectives. This present study offers relief from the dilemma that Eulerian eddy dataset is nearly the only option for studying mesoscale eddies.

One limitation of the present dataset is that RCLVs are based on surface geostrophic velocities, and more subsurface flow fields are needed to allow the vertical motion of Lagrangian particles, thus revealing the full image of coherent eddies. In addition, recent studies based on high-resolution simulations (Beron-Vera et al., 2019; Sinha et al., 2019) have noticed that submesoscale flows might change the behavior of mesoscale coherent structures, we except to update this dataset to v2.0 once the observations of the Surface Water and Ocean Topography mission are available.

339 Video supplement. The video supplement is available at https://vimeo.com/773609039.

Author contributions. RA proposed the idea and launched this project. TL and RA developed the related algorithm. TL conducted the offline
 particle advection and data analysis. TL organized the eddy dataset. TL and RA wrote the manuscript.

342 *Competing interests.* The authors declare that they have no conflict of interest.

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