

Mapping 10-m global impervious surface area (GISA-10m) using multi-source geospatial data

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Abstract. Artificial impervious surface area (ISA) documents the human footprints. Accurate, timely, and detailed ISA datasets are therefore essential for global climate change studies and urban planning. However, due to the lack of sufficient training samples and operational mapping methods, global ISA datasets at a 10-m resolution are still lacking. To this end, we proposed a global ISA mapping method leveraging multi-source geospatial data. Based on the existing satellite-derived ISA maps and ~~the~~ crowdsourcing OpenStreetMap (OSM) data, 58 million training samples were extracted via a series of temporal, spatial, spectral, and geometric rules. We then produced a 10-m resolution global ISA dataset (GISA-10m) ~~Combined from~~ with over 2.7 million Sentinel optical and radar images on the Google Earth Engine platform, ~~we produced the~~ 10-m global ISA dataset (GISA-10m). Based on ~~the~~ test samples that are independent of the training set, GISA-10m ~~embraced~~ achieves an overall accuracy of greater than 86%. In addition, the GISA-10m dataset was comprehensively compared with the existing global ISA datasets, and the superiority of GISA-10m was ~~confirmed~~ demonstrated. The global road area was further ~~discussed~~ investigated, ~~by~~ courtesy of this 10-m dataset. It was found that China and the ~~United States~~ embraced have the largest areas of ISA and road ~~area~~. The global rural ISA was found to be 2.2 times that of urban while the rural road area was found to be 1.5 times larger than that of the urban regions. The global road area accounted for 14.2% of the global ISA, 57.9% of which is located in the top ten countries. Generally speaking, the produced GISA-10m dataset and the proposed sampling and mapping method are able to achieve rapid and efficient global mapping, and have the potential for detecting other land covers. It ~~was also indicated~~ is also shown that global ISA mapping can be improved by incorporating OSM data. The GISA-10m ~~dataset could~~ an be used as a fundamental parameter for Earth system science, and will provide valuable support for urban planning and water cycle study. The GISA-10m can be freely downloaded from <http://doi.org/10.5281/zenodo.5791855> (Huang et al, 2021).

1 Introduction

The land dominated by humans has expanded rapidly over the past decades (Friedl et al., 2010), resulting in a large amount of terrestrial surface that is covered by impervious surfaces (Gong et al., 2020a). Impervious surfaces ISA ~~are~~ is mainly composed of artificial materials, such as gravel, glass, asphalt, and metals (Tian et al., 2018). Such impervious surfaces ISA ~~prevents~~ or

decelerates water infiltration, while also blockings evapotranspiration, which affects the terrestrial water cycle and thermal environment (Qin et al., 2018; Yang et al., 2019). With more attention attracted-now being paid to the impact of urban sprawl on the global climate environment (United Nations, 2016), the global monitoring of impervious surface area (ISA) wouldcan depict the anthropic implications on the water cycle, land cover, and biodiversity (Ji et al., 2020; Qin et al., 2017). In addition, ISA morphology is also an important parameter for urban planning, socio-economics, and population studies (Voss, 2007). In summary, accurate and timely monitoring of global ISA dynamics is valuable-important for urban habitability (Herold et al., 2006), sustainable development (Dewan and Yamaguchi, 2009), and terrestrial ecosystem services (Goetz et al., 2003).

GThe global ISA monitoring via satellite remote sensing data has long been conducted-recognized. Early efforts usually focused on global ISA mapping using coarse-resolution data, e.g., DMSP (Defense Meteorological Satellite Program (DMSP)) and MODIS (Moderate Resolution Imaging Spectroradiometer (MODIS)) data (Friedl et al., 2010; You et al., 2021). With the free availability of Landsat data and the advances in geospatial cloud platforms (e.g., Google Earth Engine, GEE), recent studies have focused on global annual ISA mapping at a 30-m resolution (Gong et al., 2020b; Gorelick et al., 2017; Liu et al., 2020c; Woodcock et al., 2008). For instance, Huang et al., (2021b) generated the global-annual Global Impervious Surface Area (ISA dataset-GISA) dataset (Global Impervious Surface Area) f-coveringfrom 1972 to 2019 using over three million Landsat images-data. Although efforts have been paid-to-themade in global ISA monitoring, few studies have focused on global ISA mapping at a 10-m resolution. Recently, Corbane et al., (2021) generated the Global Human Settlement Layer 2018 (GHSL 2018) dataset using Sentinel-2 composites and a convolutional neural network-network models. However, GHSL_2018 focusesd more on human settlements and lacks depiction of ISA, such as transportation facilities. In addition to these thematic datasets, ISA haswas also been documented in land--cover products. For example, Gong et al., (2019) obtained-generated thea land cover map FROM_GLC10 (10 m-Finer Resolution Observation and Monitoring of Global Land Cover map) for 2017 at a 10-m resolution (FROM_GLC10) using Sentinel-2 images. However, the accuracy of ISA in the land--cover datasets may not be sufficient to meet the needs of global climate change studies studies and urban planning, (Gong et al., 2020b). Therefore, there is an urgent need for 10--m global ISA thematic datasets, are in urgent need to support various fine-scale applications.

Synthetic aperture radar (SAR) performs well in the case of ISA mapping due to its clear response to high-rise buildings and its ability to penetrate clouds (e.g., Sentinel--1) (Zhang et al., 2014). SAR data have their potential tofor reduceng the common false alarms that come-derived from the optical images, such as bare soil, but SAR systems it can be affected by complex terrain and shadows. Therefore, the existing studies literatures have investigateded the combination-laboration of radar and optical data to improve ISA mapping. For example, Zhang et al., (2020) combined Landsat 8 and Sentinel-1 data to produce a 30-m global ISA dataset (the Global Land Cover with Fine Classification System, GLCFCS). Similarly, Marconcini et al., (2020) used Landsat -8 and Sentinel-1 data to outline the world settlement footprint (World Settlement Footprint, WSF), based on support vector machine classifiers. Although the current studies have demonstrated the effectiveness of combining multi-source (e.g., radar and optical) remote sensing data for ISA mapping, they have usually focused on regional or national scales (Lin et al., 2020). In addition, combining data with different resolutions for ISA mapping canmay increase the uncertainty of the results. In particular, both Zhang et al., (2020) and Marconcini et al., (2020) generated global ISA (or settlement) datasets

65 by-using Landsat-8 and Sentinel-1 data, but their resolutions were different, at 30-m and 10-m, respectively (Table 1). Generally speaking, 10-m global ISA mapping based on the multi-source remote sensing data (e.g., Sentinel-1 and 2) has been insufficiently investigated in the current literature (Table 1).

Table 1. The existing global ISA datasets.

Name and abbreviation	Data and time span	Nominal resolution	Source of training sample	Classification method and strategy	Type Definition
Global Impervious Surface Area 30 m, <i>GISA</i> (Huang et al., 2021)	Landsat; 1972—2019	30-m	MODIS land cover, Climate Change Initiative land cover, GHSL, FROM_GLC	Random forest classifiers via hexagonal partitioning	Artificial impervious surface
Global Artificial Impervious Area, <i>GAIA</i> (Gong et al., 2020b)	Landsat; 1985—2018	30-m	Visual interpretation	An exclusion-inclusion approach via 3.5° grid	Artificial impervious area
Global Annual Urban Dynamics, <i>GAUD</i> (Liu et al., 2020c)	Landsat; 1985—2015	30-m	GAIA, GHSL, global urban land, global urban footprint	Random forest classifiers via 1° grid; temporal segmentation	Urban extent
Global Human Settlement Layer 2018, <i>GHSL_2018</i> (Corbane et al., 2021)	Sentinel-2; 2018	10-m	Microsoft building footprint, Facebook settlement, European settlement map, GHSL	Convolutional neural network models within Universal Transverse Mercator zones	Human settlement
Finer Resolution Observation and Monitoring of Global Land Cover, <i>FROM_GLC 10</i> (Gong et al., 2019)	Sentinel-2; 2017	10-m	Visual interpretation	Random forest classifiers	Impervious surface
World Settlement Footprint, <i>WSF2015</i> (Marconcini et al., 2020)	Landsat-8, Sentinel-1; 2015	10-m	Thresholding for spectral index, radar, and slope data	SVM classifiers via 1° grid	Human settlement
Global Land Cover with Fine Classification System, <i>GLCFCS</i> (Zhang et al., 2020)	Landsat-8, Sentinel-1; 2015	30-m	GlobeLand30	Random forest classifiers via 5° grid	Impervious surface
Global Impervious Surface Area 10-m, <i>GISA-10m</i> (this study)	Sentinel-1, Sentinel-2; 2016	10-m	GISA, OSM, GlobeLand30, FROM_GLC10	Random forest classifiers via hexagonal partitioning	Artificial impervious surface

70 From the perspective of the global ISA mapping methods, supervised classification has been widely employed (Table 1). The quality of the training samples is the major factor affecting the classification results (Foody, 2009). Visual interpretation and automatic extraction from the existing datasets are two common methods-ways to generate training samples. Visually interpreted samples are usually accurate but labour-intensive. Therefore, they are often used for classifications at a regional scale (Yang et al., 2020). On the other hand, samples generated from the existing datasets have been proved-shown to be efficient for global ISA mapping in recent years (Marconcini et al., 2020; Zhang et al., 2020). In fact, ISA samples are typically diverse, as their response to the different sensors varies with the materials, geometry, atmospheric conditions, and viewing angles. Therefore, accurate and sufficient samples are required to address the above issue for the purpose of consistent ISA mapping at the global scale. Given the higher spatial resolution (10-m) of the Sentinel satellites, it remains challenging to obtain high-quality and adequate training samples for 10-m global ISA mapping.

In general, due to the difficulty of collecting training samples and the limitation of ~~the~~ computational and storage capacity ~~required~~ to deal with ~~the~~-massive data, efficient methods and accurate datasets ~~regarding-for~~ 10-m resolution global ISA mapping are lacking. Therefore, in this study, we proposed a global ISA mapping method that leverages multi-source geospatial data to map ~~the~~ping 10-m global impervious surface area (GISA-10m). To ~~the best of~~ our knowledge, this ~~i~~was the first global 10-m ISA mapping based on ~~Sentinel~~Sentinel-1 and 2 data. Specifically, ~~by~~ combining ~~the~~-multi-source remote sensing ~~data~~ and ~~the~~-crowdsourc~~ed~~ing OpenStreetMap data, we ~~proposed-developed~~ a sample generation method involving a series of temporal, spatial, spectral, and geometric rules to collect training samples with ~~a~~ global coverage. ~~Besides~~Furthermore, an adaptive hexagonal partition~~ing~~ strategy was ~~used-introduced~~ for multi-source feature extraction and classification. Finally, the accuracy of ~~the~~ GISA-10m ~~dataset~~ was assessed ~~using~~by three independent sample sets. Meanwhile, we ~~also~~ compared ~~the~~ GISA-10m with ~~the~~-existing datasets, to better reflect its quality, and the ISA distribution in the global urban and rural regions was ~~analysed~~analyzed. In particular, the global road ISA was further extracted and ~~discussed~~investigated. Ablation experiments were ~~also~~further conducted to demonstrate the feasibility of OSM data in global ISA mapping.

2 Data

2.1 Remote sensing data

Sentinel-2 optical ~~data~~ and Sentinel-1 SAR data were used in the GISA-10m mapping. Sentinel-2 is a high-resolution multispectral imaging mission operat~~ed~~ing by ~~the~~ European Space Agency (ESA) Copernicus program. The first Sentinel-2 satellite (Sentinel-2A) has been acquiring high-resolution Earth observation data since June 2015, consisting mainly of four 10-m resolution visible and near-infrared (~~NIR~~) bands, six 20-m resolution red-edge and short-~~wave~~wave infrared (~~SWIR~~) bands, and three 60-m bands (Drusch et al., 2012; Zhang et al., 2018). After test~~ing~~ed and adjust~~ment~~ed, ~~a~~ complete global coverage was obtained for ~~the~~ Sentinel-2 satellite in 2016 (Fig. S2). Therefore, we used all ~~the~~ available Level-1C top of atmosphere (TOA) reflectance data acquired in 2016 for ~~the~~our 10-m ISA mapping. ~~S~~The-systematic radiometric calibration ~~and~~; geometric and terrain correction have ~~already~~ been performed for the Level-1C TOA data by ~~the~~-ESA. Clouds and shadows were removed via the quality band to obtain cloud-free pixels.

~~The~~ Sentinel-1A ~~satellite~~ was launched ~~i~~on April 2014, carrying a C-band ~~SAR instruments~~synthetic aperture radar. After the launch of Sentinel-1B in 2016, ~~the~~ two satellites ~~now have~~d a return visit period of six days at the equator. We used all ~~the~~ available Ground Range Detected (GRD) images acquired under Interferometric Wide (IW) mode, with a spatial resolution of 10-m. The boundary noise removal, thermal noise removal, radiometric calibration, and terrain correction ~~has-been~~were conducted ~~on~~by the GEE ~~platform~~, with the same processing ~~tools~~ as ~~the~~ Sentinel-1 Toolbox. Sentinel-1 data in both ascending and descending orbit were considered. For the ~~places~~-locations where two orbits were available, only the descending data ~~were~~as used, to avoid the terrain distortion caused by the combination of two orbits (Veloso et al., 2017). In total, over 2.7 million Sentinel images were used to cover the global terrestrial surface (Fig. S2).

110 2.2 Volunteered geographic information data

Volunteered geographic information (VGI) is ~~the~~ geographic information that ~~i~~was created, edited, and updated by volunteers (Goodchild, 2007). The well-known ~~VGI project~~, OpenStreetMap (OSM) ~~VGI project~~, provides online maps that can be edited and used by everyone. Since its launch in 2004, OSM has been updated and maintained by over seven million volunteers (Haklay and Weber, 2008). OSM has been used for positioning and navigation (Fonte et al., 2020), urban modeling (Goetz, 2013), and land-cover mapping (Tian et al., 2019). In fact, over 600 million buildings and roads ~~have~~were ~~been~~ tagged in the OSM ~~data~~base (<https://taginfo.openstreetmap.org/keys>, last accessed: 17 Aug 2021). These data should be important reference ~~data~~ for ISA mapping; but, unfortunately, in the current literature, they have seldom been used for ISA mapping at the global scale. Therefore, we used the OSM data as a source of ~~the~~ training samples for the GISA-10m mapping. Specifically, we extracted the buildings and road networks as potential training samples from the OSM ~~P~~planet data built on January 2, 2017¹.

120 2.3 Existing ISA datasets

We ~~inter~~compared GISA-10m with the existing ISA datasets, ~~i.e., including~~ GISA, GAIA, GAUD, WSF2015, FROM_GLC10, GLCFCS, ~~and GHSL2018~~GHSL 2018 (Table 1). GISA, GAIA, and GAUD are Landsat-derived annual global ISA datasets for the time periods of 1972–2019, 1985–2018, and 1985–2015, respectively. ~~GHSL2018~~GHSL 2018 is a global settlement layer based on a Sentinel-2 composite, where a convolutional neural network model was used to estimate the settlement probability (Corbane et al., 2021). ~~WSF2015 and GLCFCS are global ISA datasets based on Landsat 8 and Sentinel-1 data. Marconcini et al. (2020) collected the samples for WSF2015 based on a set of spectral and topographic rules, and Zhang et al. (2020) derived the samples for GLCFCS from GlobeLand30. WSF2015 collected samples based on a set of spectral and topographic rules, and GLCFCS derived samples from GlobeLand30 (Marconcini et al., 2020; Zhang et al., 2020).~~ Gong et al., (2019) generated the 10-m ~~global land cover product~~FROM_GLC10 using Sentinel-2 data and random forest classifiers.

125 It should be noted that these datasets ~~were~~ ~~different~~ ~~for~~ ~~in~~ ~~their~~ ~~mapping~~ ~~purposes~~ ~~and~~ ~~their~~ ~~the~~ ~~definitions~~ ~~s~~ of the ~~land~~ ~~cover~~ categories ~~and~~ ~~mapping~~ ~~purposes~~. For instance, ~~GHSL2018~~GHSL 2018 and WSF2015 focused ~~on~~ human settlements, while GAUD delineates ~~ed~~ urban extent (Table 1). ~~T~~In this study, he GISA-10m ~~dataset generated in this study~~ ~~monitored~~ reflects the ~~ISA~~impervious surface area (ISA) generated by human activities, including all kinds of human settlements, transportation facilities, industries, and mining ~~locations~~places, ~~by~~ courtesy of the employment of the high spatial resolution satellite data.

130 Therefore, artificial impervious surfaces and human settlements were treated as ISA in this ~~paper~~study.

¹ <https://planet.openstreetmap.org/planet/2017/planet-170102.osm.bz2>, last access: 13 Mar 2021

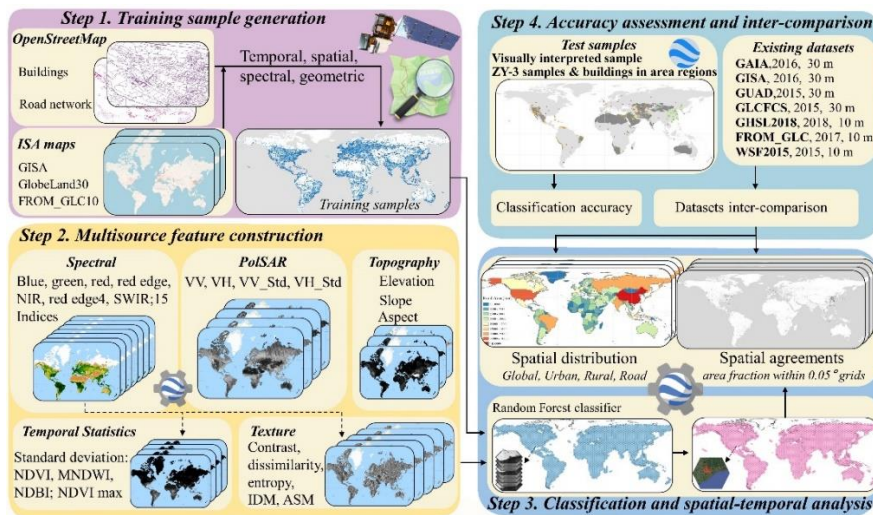


Figure 1. The flowchart for GISA-10m mapping.

3 Methodology

The main objectives of this study were to: 1) investigate the-10_m global ISA mapping (GISA-10m) by combining Sentinel-1 and -2 images with other geographic information; and 2) ~~analyse~~analyze the distribution of urban and rural ISA at a 10-m resolution. The flowchart for GISA-10m mapping ~~i~~was shown in Fig. 1, including training sample generation, multi-source feature construction, ~~random forest~~RF classification, accuracy validation, and dataset comparison. Based on ~~the~~ satellite-derived ISA maps and ~~the~~ VGI data (i.e., OpenStreetMap), we proposed a rule-based approach to automatically generate global training samples. Using more than 2.7 million Sentinel images on the GEE, multi-source features were ~~then~~constructed and fed ~~into~~ ~~the~~ ~~random forest~~RF classifier to obtain the ~~mapping~~ results. The accuracy of ~~the~~ GISA-10m was assessed by visually ~~interpretationed~~ and ~~the~~ third-party samples. To better evaluate the performance of GISA-10m, we compared it with the current state-of-the-art global ISA datasets (Table 1). Finally, the distribution of ISA over urban and rural regions was ~~analysed~~analyzed.

3.1 Global ISA mapping using multi-source geospatial data

3.1.1 Sample collection

In the case of large-scale supervised classification, both the quantity and quality of samples are important (Foody and Arora, 1997). ISA is a highly variable object, and its attributes in the Sentinel-2 multispectral images are related to materials, viewing angles, and atmospheric conditions, while its response to the Sentinel-1 SAR ~~instrument~~ depends on dielectric properties, geometry, and surface roughness. Hence, a large number of training samples were required to address the ~~afore~~mentioned challenges that would be encountered at the global scale. Training samples ~~a~~were usually acquired by means of visual

interpretation or automatic extraction from the existing datasets. ~~However, t~~The visual interpretation methods ~~awere~~ ~~labour~~~~labor-~~ and time-intensive, even for small regions. Therefore, at a large scale, training samples ~~awere~~ usually extracted from the existing datasets with similar temporal and spatial coverages. However, the sample quality ~~iw~~was affected by the quality of the datasets ~~used~~. Theoretically, samples extracted from a single dataset ~~will~~~~may~~ result in more errors and uncertainties, while multi-source datasets can improve the reliability of the training samples (Huang and Zhang, 2013). We ~~therefore~~~~us~~ proposed to collect global training samples by incorporating the existing ISA datasets and the crowdsourcing OSM database. To ~~concisely~~ distinguish the two types of ISA samples, we named the ISA samples extracted from the existing satellite-derived ISA datasets s as ISA_{RS} and those extracted from the OSM as ISA_{OSM}.

The existing ISA datasets generally covered a broad terrestrial surface, but they ~~were~~ different in terms of their definitions, spatial resolutions, and temporal coverage. In this study, the GISA, FROM_GLC10, and GlobeLand30 products were chosen to extract the training samples, ~~due to~~for the following reasons: 1) the GISA is aimed at mapping the global ~~impervious surface area~~ISA, which ~~was~~ consistent with GISA-10m; 2) the team behind the GlobeLand30 employed extensive visual interpretation to detect artificial surfaces, which can effectively reduce the false alarms from other datasets, i.e., GISA and FROM_GLC10 (Chen et al., 2015); ~~and~~ 3) ~~t~~he definition of FROM_GLC10 (impervious surfaces) ~~iw~~was ~~also~~ consistent with that of GISA-10m, and its spatial resolution ~~iw~~was ~~also~~ 10-m. The GHSL_2018, WSF2015, and GAUD were not considered since they aimed to outline human settlements or urban extents (Table 1). We then collected the eligible training samples according to the following rules.

(1) Temporal rule: The GISA ~~iw~~was a global ISA dataset ~~covering~~during 1972–2019, ~~so~~and we selected its results ~~for~~of 2016 to match the ~~time when~~-Sentinel data ~~was~~used in this research. GlobeLand30 documents ~~ed~~ global land cover ~~map~~for 2000, 2010, and 2020, ~~so~~and ~~here~~, the 2010 map was chosen in this study. Although the 2020 map ~~iw~~was more recent ~~than the~~ 2016 ~~map~~, it contained ~~ed~~ ISA that was built after 2016, making it unsuitable for the GISA-10m mapping. Although there is a six-year gap between GlobeLand30 and the other datasets (i.e., GISA and FROM_GLC10), ~~w~~We adopted the commonly used assumption that the transition from ISA to non-impervious surface area (NISA) rarely happened ~~ed~~ (Gong et al., 2020b; Huang et al., 2021, 2022), so that the GlobeLand30 for 2010 ~~could~~an be used for the GISA-10m mapping. The following spatial and spectral rules were used to remove the possible errors.

(2) Spatial rule: We first checked the class labels of the three datasets at each pixel. If these labels were the same (i.e., ISA), the pixel was taken as a potential ISA_{RS} sample. The ~~incorporation~~collaboration of multiple datasets can effectively reduce the errors that existed in a single dataset. In addition, we filtered out the edge pixels in each dataset to reduce the uncertainty, since they were more likely to be mixed pixels. ~~Edge~~ pixels were defined as the outermost pixels of each ISA patch. We removed the edge pixels in each data-set, and then selected their ISA intersection as potential training samples. In this way, the errors contained in the non-edge pixels in the 30-m resolution data (e.g., mixed pixels) ~~could~~an be removed by the edge pixels in the 10-m resolution data.

(3) Spectral rule: After the above steps, ~~there may still be~~ a small amount of errors ~~may still remain~~ in the current samples. Hence, we applied the spectral rule to remove these erroneous samples. Specifically, we measured the

190 ~~mahalanobis~~Mahalanobis distance between each ISA_{RS} sample to the spectral average of each hexagon (the mapping unit adopted in this study), and filtered out the samples with a distance greater than $\mu + \delta$ (where μ and δ represents the mean and standard deviation, respectively) (Huang et al., 2021). Vegetation and water bodies ~~awere~~ common sources of false alarms in the existing datasets (Figs. 2a and &b). However, these errors often accounted for a relatively small proportion, and they can be effectively identified and reduced by the spectral rule. It can be seen in Fig. 2 that most of the water bodies and vegetation (e.g.the red rectangles in Fig. 2) were successfully removed from the initial ISA_{RS} training samples.

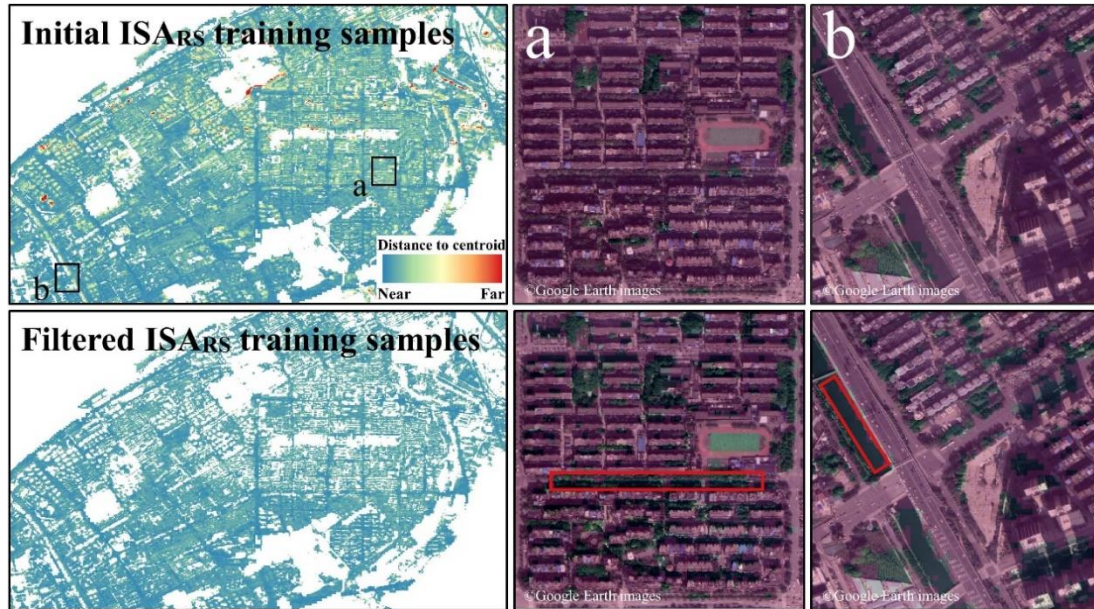


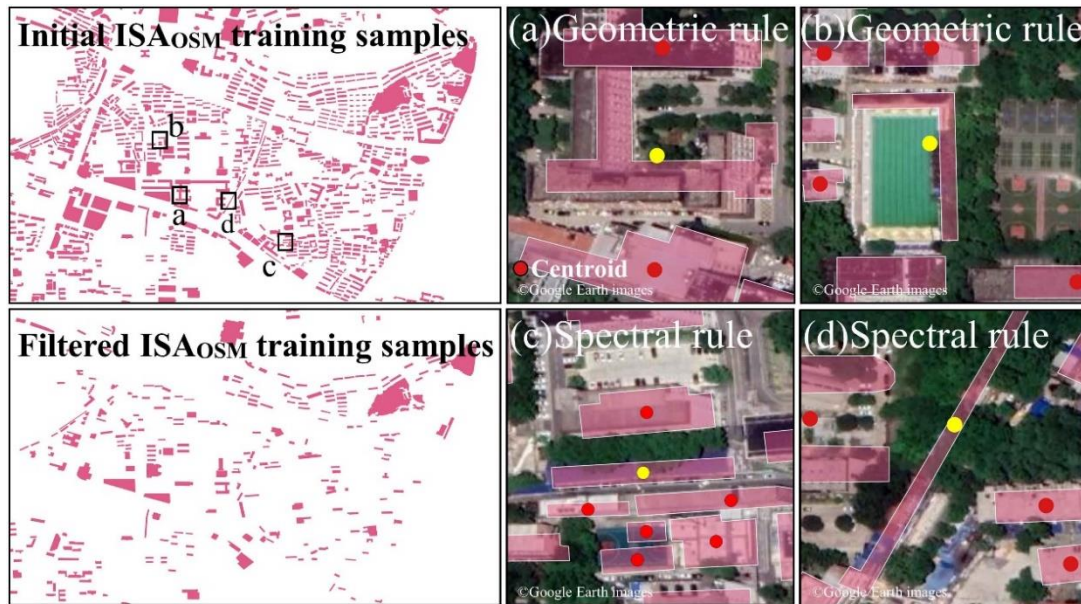
Figure 2. ~~E~~The examples of the initial and filtered ISA_{RS} training samples from the city of Wuhan in China city (30.625382° N, 114.392682° E). The purple in the close-up maps represents the samples.

~~On the other hand,~~ We extracted the ISA_{OSM} samples from the OSM buildings and roads through the following rules.

- 200 (1) Temporal rule: We chose the OSM data built on 2-January 2, 2017, in terms of the time of GISA-10m. This version of the OSM data was employed to ensure that the buildings and roads were constructed in 2016 or before, and hence, ~~it was~~were suitable for the 2016 ISA mapping.
- (2) Geometric rule: A natural way to extract training points from OSM data i~~was~~ to generate random points within the building or road polygons (Liu et al., 2020a). However, random points may contain erroneous or mixed pixels. Such problems can be mitigated by ~~making-~~applying negative buffers to the polygons (Liu et al., 2020a). However, this approach i~~was~~ very time-consuming when applied to global ISA mapping, especially given the more than 200 million buildings in the OSM data~~base~~. Therefore, in this study, we extracted the geometric center of a building polygon as an ISA_{OSM} sample, which was more efficient than buffering and random points. Notably, although we could~~an~~ filter out the erroneous buildings using attribute tags (e.g., dams, swimming pools, playgrounds), the geometric center of a building was not always an ISA sample. Hence, we 210 further required that the geometric center must be contained by the building. As in Figs. 3a and &b, the incorrect building

geometric centers (e.g., the vegetation and water, as indicated by the yellow points) were successfully identified and removed by the geometric rule. In addition, we excluded buildings with an area of less than 100 -m² (approximately a Sentinel pixel), to ensure the reliability of the samples. This is because athe training sample extracted from the geometric center may be NISA; when the area of thea building is smaller than a Sentinel pixel.

215 Compared with the widely used 30-m Landsat data, the high-resolution Sentinel data promotes-allow a better delineation of roads. We thereby also extracted ISA_{OSM} samples from the OSM road networks. The OSM roads usually consisted of centerlines rather than boundaries. Therefore, we extracted the center point of each road, rather than its geometric center, as the road ISA samples. Given that the width of low-grade roads may be smaller-less than 10 -m (i.e., a Sentinel pixel), we kept only the main roads (highway ="primary").



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Figure 3. Examples of the initial and filtered ISA_{OSM} training samples from the city of Wuhan in China city (30.530202° N, 114.356287° E). The yellow points in the close-up maps represent the errors recognized by (a)–(b) the geometric rule and (c)–(d) the spectral rules.

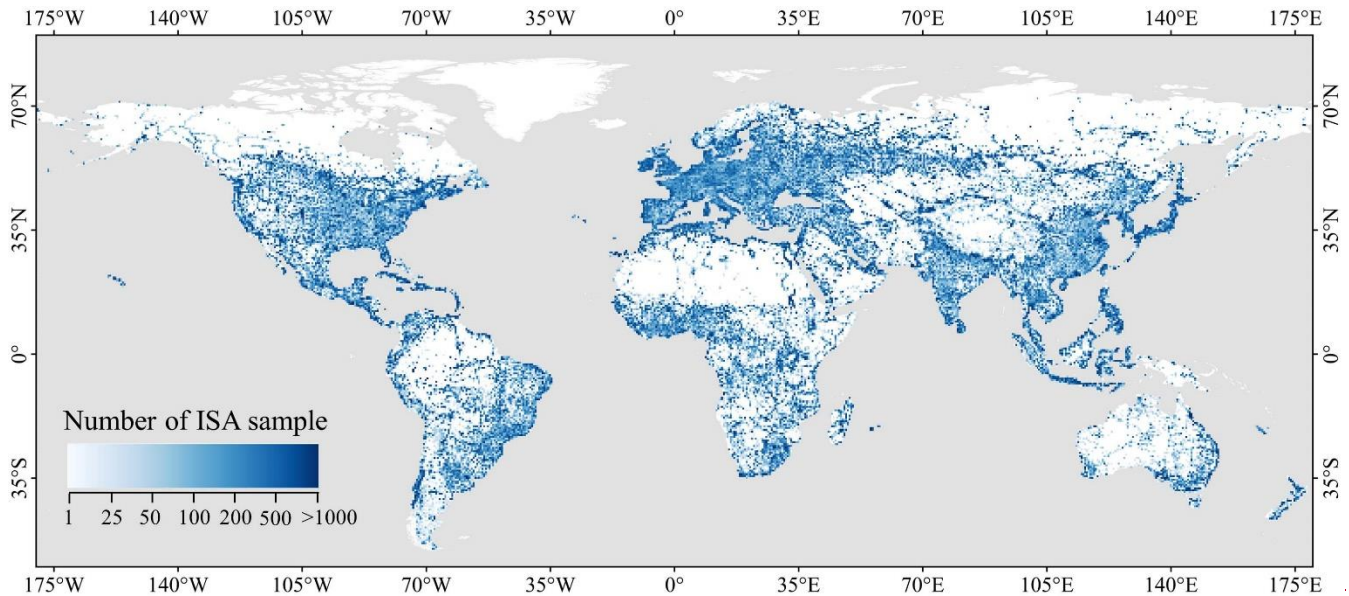
(3) Spatial rule: Given the uneven spatial distribution of OSM data (Tian et al., 2019), we then applied the spatial rule to balance theits distribution at the global scale. Specifically, for hexagons with more than 10,000 OSM records (i.e., buildings and roads), we randomly selected 10,000 records as initial samples. The dilution of OSM data can significantly reduce the subsequent computational cost. In addition, considering that ISA_{OSM} could overlie with ISA_{RS}, we removed the ISA_{OSM} samples that were intersected with ISA_{RS}. In the field of supervised classification, the diversity of the samples iwas important for the generalization ability of the classification model (Huang and Zhang, 2013). Considering that ISA_{OSM} canould overlie with ISA_{RS}, we removed the ISA_{OSM} samples intersected with the ISA_{RS} sample pool, to increase the diversity and reduce the redundancy of the ISA samples.

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(4) Spectral rule: Although OSM uses humans as sensors, ISA_{OSM} samples ~~can~~ still contain erroneous points, such as vegetation and water bodies, ~~beside~~ in addition to roads. As shown in Figs. 3c and d, the yellow points satisfied the temporal, spatial, and geometric rules, but they ~~were~~ actually vegetation. Hence, we applied the spectral rule to filter out these erroneous points. Specifically, the ISA_{OSM} samples whose ~~MNDWI~~ (modified normalized difference water index (MNDWI) or ~~NDVI~~ (normalized difference vegetation index (NDVI)) value ~~was~~ larger than $\mu + \delta$ were removed (μ and δ represent the mean and standard deviation of the indices, respectively), as these points were more likely to be vegetation or a water body (Huang et al., 2021).

After obtaining the ISA candidate samples, we randomly selected 2,500 ISA_{RS} and ISA_{OSM} samples, respectively, within each hexagon as the final ISA training samples (see Section 5.3 for details). It can be seen that ~~the~~ generated ISA samples covered a broad terrestrial surface, especially in India and China, where a large number of small villages are found (Fig. 4).



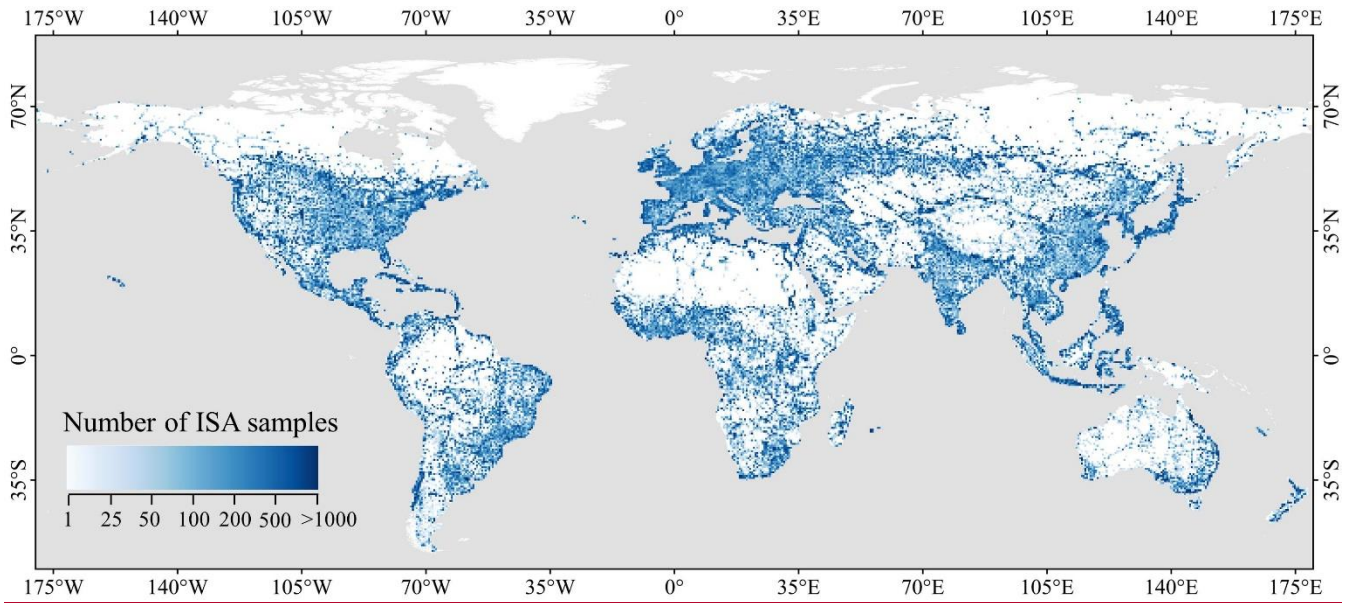


Figure 4. Global distribution of ISA training samples. The number of samples was counted within 0.5° spatial grid.

245 On the other hand, NISA (non-ISA) training samples awere also important for accurate ISA mapping. We used the three existing datasets (i.e., GISA 30 m, FROM_GLC10, GlobeLand30) and the OSM to generate the NISA samples. Firstly, we took the intersection of the NISA regions in the three datasets as the initial NISA sample pool:

$$NISA = NISA_{GISA} \cap NISA_{GlobeLand30} \cap NISA_{FROM_GLC10} - ISA_{OSM} \quad (1)$$

For GlobeLand30 and FROM_GLC10, NISA was defined as all the land--cover types other than ISA. We then-masked the initial NISA sample pool using the OSM buildings and roads to suppress the errors in the existing global datasets. To this end, here-we used the OSM version built in December 2020², which documents see more buildings and road networks than the 2017 version. BesidesIn addition, we buffered the OSM roads with a 30--m buffer to better-mitigate the errors. Subsequently, 30,000 points were randomly selected in each hexagon as NISA samples. The distance between each NISA sample was kept larger than 200 -m, to ensure theits diversity and irrelevance. Finally, we extracted 58 million training samples (51,674,533 NISA samples and 6,897,378 ISA samples) for the GISA-10m mapping.

260 **Table 2. The multi-source features used for the GISA-10m mapping.**

Type	Features	Description	Dimension	Source
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² <https://planet.openstreetmap.org/planet/2020/planet-201207.osm.bz2>, last accessed: 13 Mar 2021

Spectrum	Blue, green, red, red edge_1, red edge_2, red edge_3, NIR, red edge_4, SWIR_1, and SWIR_2	50th percentile value of <u>the</u> reflectance derived from all <u>the</u> available Sentinel-2 images	10	Sentinel-2
Normalized indices	Index1, Index2, Index3, Index4, Index5, Index6, Index7, Index8, Index9, Index10, Index11, Index12, Index13, Index14, Index15	Normalized indices derived from the spectral bands described above . The indices <u>were</u> calculated as: Index1=NI (NIR, blue), Index2=NI (NIR, green), Index3=NI (NIR, red), Index4=NI (NIR, red edge 1), Index5=NI (NIR, red edge 2), Index6=NI (NIR, red edge 3), Index7=NI (NIR, red edge 4), Index8=NI (SWIR_1, blue), Index9=NI (SWIR_1, green), Index10=NI (SWIR_1, red), Index11=NI (SWIR_1, NIR), Index12=NI (SWIR_2, blue), Index13=NI (SWIR_2, green), Index14=NI (SWIR_2, red), Index15=NI (SWIR_2, NIR), where NI represents the function $(b1 - b2) / (b1 + b2)$, <u>and</u> b1 and b2 denote two spectral bands	15	Sentinel-2
SAR	VV, VH	Temporal mean VV and VH backscatter coefficients of <u>the</u> Sentinel-1 images	2	Sentinel-1
Temporal statistics	NDVI_Std, MNDWI_Std, NDBI_Std, NDVIMax, VV_Std, VH_Std	Standard deviation of NDVI, MNDWI, NDBI, VV and VH backscatter coefficients; <u>m</u> Maximum <u>NDVI</u> of the year	5	Sentinel-1 & Sentinel-2
Texture	Contrast, dissimilarity, entropy, IDM, ASM	The GLCM texture derived from <u>the</u> NIR band of <u>the</u> Sentinel-2 data, including entropy, dissimilarity, contrast, angular second moment (ASM), <u>and</u> inverse difference moment (IDM)	5	Sentinel-2
Topography	Elevation, slope, <u>and</u> aspect	Slope and aspect calculated from the elevation	3	SRTM & GMTED

3.1.2 Multi-source feature extraction

The dedicated image pyramid of the GEE platform enabled us to perform pixel-wise feature extraction (Gorelick et al., 2017). Therefore, based on all the available Sentinel data ~~from~~ 2016, we constructed a set of spectral, phenological, texturale, SAR, and topographical features with the temporal composite method (Table 2). This approach used all the available data, and at the same time allowed us to reduce the feature dimension, preserve the temporal information, and minimize the effects ~~offrom~~ clouds and shadows (Yang and Huang, 2021). Firstly, we used the spectral signatures provided by the ~~Sentinel~~Sentinel-2 data to extract the ISA in the visible, red-edge, ~~near infrared~~NIR, and infrared bands (Table 2). Moreover, considering that spectral indices ~~cannot~~ increase the differences between land covers, we also extracted a series of normalized spectral indices to enhance the discriminativeon ability between ISA and NISA (Yang and Huang, 2021) (Table 2). These indices were built according to the following criteria: (1) ~~They~~ They were mainly constructed by ~~near infrared~~the (NIR) and ~~short wave infrared~~ (SWIR) bands, due to their better atmospheric transmission (Huang et al., 2021; Yang and Huang, 2021); and (2) ~~Each~~ Each index contained at least one 10-m band (i.e., visible and NIR bands), to ensure the spatial resolution of the features.

The complex spectral and spatial characteristics in urban environments increase the difficulty of ISA mapping. In this regard, texturale features are usually employed to depict the spatial information of urban ISA (Huang and Zhang, 2013). To further

275 exploit the textural information for the ISA mapping, we computed the gray-level co-occurrence matrix (GLCM) via the NIR band₁ to depict the spatial information of urban ISA. Owing to the high redundancy among GLCM measurements (Clausi, 2002), we chose the contrast, dissimilarity, entropy, ~~HDM~~ (inverse difference moment (IDM)), and ~~ASM~~ (angular second moment (ASM)) for the texture extraction (Rodriguez-Galiano et al., 2012). The window size for the GLCM measurements was set to 7×7 as ~~this~~ it was suitable for urban classification with an image resolution from 2.5 to 10 -m (Puissant et al., 2005).
280 ~~Besides~~In addition, we averaged the GLCM from different directions (0, 45, 90, and 135^o) to maintain the rotational invariance (Rodriguez-Galiano et al., 2012).

Given that the spectra and backscatter of some NISA (e.g., vegetation and water bodies) vary throughout time, the phenological information derived from the multi-temporal spectral and SAR data was utilized to depict the temporal fluctuations. We calculated the maximum NDVI as well as the standard deviation of the NDVI (Tucker, 1979), MNDWI (Xu, 2006), and ~~NDBI~~
285 ~~(normalized difference built-up index (NDBI) (Zha et al., 2003))~~ to further enhance the temporal information. These temporal characteristics were useful in identifying NISA with temporal fluctuations. For example, the spectra of fallow cropland and ISA were similar, and even SAR data may not well-separate them well. However, the NDVI of cropland can describe the changes of crops growth, and hence, its standard deviation can be used to distinguish between ISA and cropland. In addition, to increase the robustness of these temporal features, Sentinel-2 data from ~~adjacent~~ two adjacent years were also
290 ~~included~~considered.

SAR data have their potential ~~to~~ reducing the false alarms caused by bare soil in optical images, and are it is more sensitive to buildings. In addition, ~~it is able~~ SAR signals can't penetrate clouds. ~~Therefore~~ So, in this study, SAR data were it was combined with optical data for the ISA mapping. Specifically, the ~~VV~~ (vertical-vertical (VV) polarization) and ~~VH~~ the (vertical-horizontal (VH) polarization) backscatter coefficients from the ~~Sentient~~ Sentinel-1 images were selected. ~~Specifically~~,
295 Based on all the available ~~Sentient~~ Sentinel-1 data, the annual mean and standard deviation of the VV and VH backscatter coefficients were calculated by the temporal composite method:

$$\sigma_{mean} = \frac{1}{n} \sum_{i=1}^n \sigma_i \quad (2)$$

$$\sigma_{std} = \sqrt{\frac{\sum_{i=1}^n (\sigma_i - \sigma_{mean})^2}{n}} \quad (3)$$

where n denotes the total number of Sentinel-1 observations within a year, and σ_i represents the i th backscatter coefficient
300 observation in the year. The temporal ~~compositemean~~ method can reduce the speckle noise in ~~the~~ SAR images (Lin et al., 2020), while the annual standard deviation can reflect the temporal information. Topography-related features are also necessary for ISA mapping, in order to reduce the confusion between complex terrain and buildings. For instance, topographical features ~~can~~ could help to distinguish steeply hills from buildings (Gamba and Lisini, 2013). Specifically, we used ~~SRTM~~ (Shuttle Radar Topographic Mission (SRTM) digital elevation model (DEM) data in the areas below 58° latitude and ~~GMTD2010~~ (Global
305 Multi-resolution Terrain Elevation Data 2010 (GMTED2010) in the areas above 58° (Huang et al., 2021). Finally, a total of 41 features were constructed ~~from~~ on the 2.7 million Sentinel images (2,613,180 Sentinel-2 and 122,156 Sentinel-1) and DEM data.

3.1.3 Hexagon-based adaptive random forest classification

When dealing with global land-cover classification, the global terrestrial surface ~~was~~ usually divided into homogeneous sub-
310 regions according to criteria such as climate, land cover, or administrative regions (Goldblatt et al., 2018). For global ISA
mapping, regular square grids ~~were~~ commonly used (Table 1), such as 1° and 5° grids (e.g., WSF2015 and GLCFCS). ~~Herein~~
~~In this study,~~ we divided the terrestrial surface into 2° hexagonal grid ~~cells~~ (Fig. 1), due to ~~their~~ symmetry and invariance
(You et al., 2021). ~~Besides~~~~Furthermore,~~ there were no gaps or overlaps between hexagons, and the distance between adjacent
hexagon centers was approximately equal (Richards et al., 2000).

315 ~~The Random forest (RF)~~ classifier has been widely used in global ISA mapping, due to its robustness to erroneous samples,
flexibility ~~with~~ high-dimensional data, and tolerance to noise (Bauer and Kohavi, 1999; Wulder et al., 2018) (Table 1). ~~The~~
~~RF classifier~~ utilizes ensemble learning to obtain predictions by voting on categories through multiple decision trees (Breiman,
2001). Each tree uses a random subset of the input features to increase the generalization ability. In addition, trees are grown
from different subsets of training data (i.e., bagging or bootstrapping), to increase the diversity (Rodriguez-Galiano et al.,
320 2012). RF has been ~~proved~~ ~~shown~~ to outperform other classifiers when dealing with large-scale and high-dimensional data
(Goldblatt et al., 2016). The ~~flexibility~~ ~~ability~~ of RF to handle multi-source data also makes it convenient ~~for us to~~ ~~when~~ ~~dealing~~
with Sentinel radar and optical data. Therefore, together with the afore-mentioned multi-source features and global training
samples, ~~the RF classifier~~ was used for ~~the~~ GISA-10m mapping. As suggested by Yang and Huang, (2021), the number of
trees was set to 200. We divided the global terrestrial surface ~~using into~~ 1,808 hexagons, ~~where and~~ a local RF model was built
325 for adaptive ISA classification in each hexagon. Therefore, a total of 1,808 RF models were built. In terms of the features used
to train each tree, the random forest uses a random subset of features to reduce the correlation between trees. In general, the
diversity of ~~the~~ trees can be increased when fewer features are used for training each tree (Breiman, 2001). In ~~the~~ GISA-10m
mapping, we set the number of features used for each tree to the square root of the total number of features, as suggested by
Liu et al., (2020b).

330 3.2 Accuracy assessment

The test samples ~~for~~ ~~the~~ GISA-10m included: (1) visually interpreted samples via Google Earth; (2) test samples extracted from
~~the~~ ZiYuan-3 (ZY-3) built-up datasets (Liu et al., 2019); and (3) building samples located in ~~the~~ arid areas.

(1) As suggested by Stehman and Foody (2019), we used cluster sampling to collect the visually-interpreted test samples. The
primary sampling unit involved 59 grid ~~cells~~ with a side length of 1°, which ~~were~~ randomly selected based on population,
335 ecoregion, and urban landscape (~~the~~ red squares in Fig. 5). The secondary sampling unit included the random samples within
each grid ~~cell~~. In such ~~a~~ way, samples from different urban sizes and densities were considered for ~~the~~ validation. Specifically,
in each grid ~~cell~~, we randomly selected 100 ISA and 100 NISA points to test their accuracy. An equal allocation of ISA and
NISA test samples could reduce the bias of the accuracy assessment, and hence allow for a more accurate estimation of ~~the~~
user's accuracy (Olofsson et al., 2014; Stehman, 2012). By referring to ~~the~~ high-resolution Google Earth images, a pixel

340 (10 ~~m~~ × 10 ~~m~~) was labeled~~ed~~ as ISA if more than half of its area was covered~~ed~~ by ISA; otherwise, it was identified as NISA. As ~~can be seen from~~ Fig. 5, the test samples involved not only high-density ISA samples ~~from~~ urban areas, but also a large number of low-density samples ~~from~~ suburban and rural regions. Finally, a total of 11,800 test samples were obtained.

345 (2) Liu et al., (2019) proposed a multi-angle built-up index to extract built-up areas from ZY-3 images covering 45 global cities, ~~which obtained~~ an overall accuracy (OA) of greater than 90%. The multi-angle ZY-3 images depicted~~ed~~ the three-dimensional and vertical structure of buildings, which ~~were~~ more effective and accurate than ~~the~~-planar feature extraction for detecting built-up areas. Given the higher spatial resolution (2-m) and better accuracy of ~~the~~ ZY-3 global built-up dataset, we extracted test samples from it ~~for~~ the year of 2016 (Huang et al., 2021a; Liu et al., 2019). A sample (10 ~~m~~ × 10 ~~m~~) was labeled~~ed~~ as ISA if more than 50% of its area was classified as ISA in the ZY-3 dataset, while ~~the~~ NISA samples were those with no built-up pixels in the area (Huang et al., 2021a). For each city, the number of samples was proportional to the area of

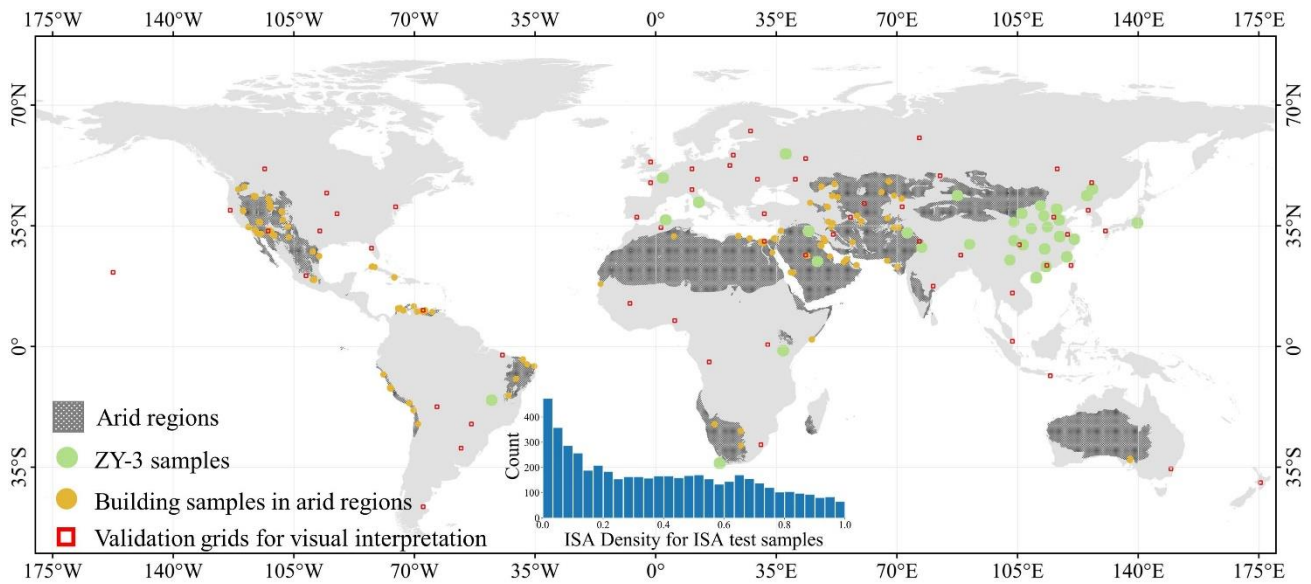
350 the ZY-3 image, and the ratio of ISA and NISA test samples was consistent with the ratio of the built-up and non-built-up ~~classes~~ (Huang et al., 2021a). In this way, we obtained 47,216 NISA ~~samples~~ and 21,152 ISA samples (~~the~~ green dots in Fig. 5) from 24 cities in the ZY-3 built-up dataset.

(3) Considering the difficulty of ISA extraction in ~~the~~ arid regions (Tian et al., 2018), we paid special attention to the accuracy assessment in the arid regions. To this end, we visually interpreted 5,385 building pixels in these regions. A total of 25 photo

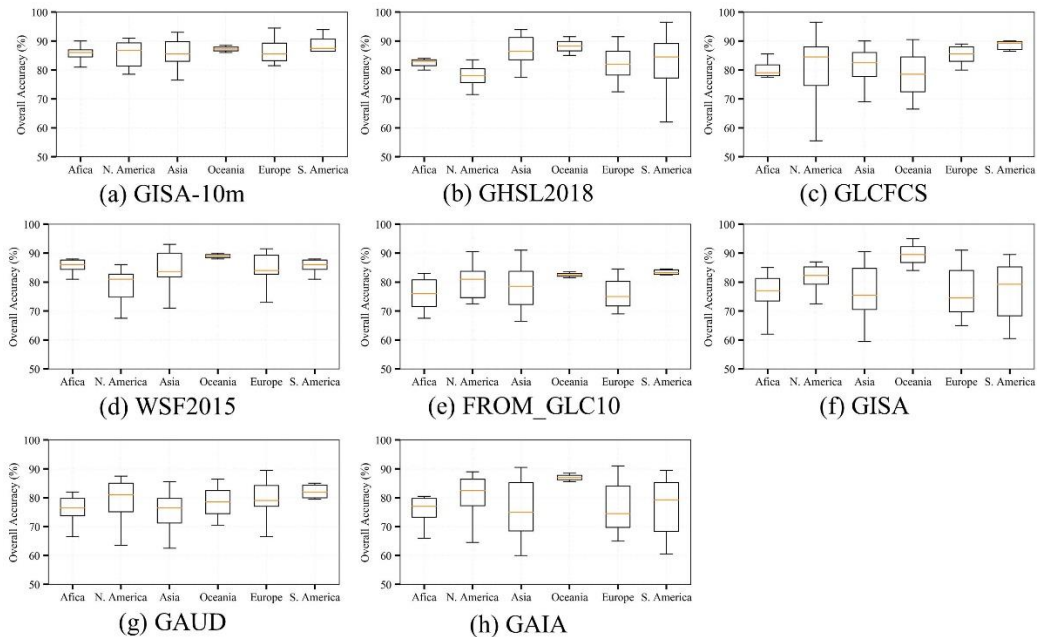
355 interpreters were recruited for this task by referring to the Google Earth images. These samples were ~~then~~ further checked by three experts. The arid regions were defined according to the ~~““Deserts and Xeric sShrublands””~~ biome in Olson et al., (2001).

Based on the three groups of test samples aforementioned, the accuracy of GISA-10m was assessed ~~using theby overall~~ ~~accuracy~~ (OA), kappa, producer's accuracy (PA), user's accuracy (UA), and F1-s~~S~~core (the harmonic mean of ~~the~~ PA and

360 UA). ~~Besides, S~~seven existing global ISA datasets were used for ~~the~~ inter-comparison with GISA-10m, ~~including i.e.,~~ GHSL 2018, GLCFCS, WSF2015, FROM_GLC10, GISA, GAUD, and GAIA (Table 1). The three groups of test samples mentioned above were used to assess and compare the accuracy of these products.



365 **Figure 5. Global distribution of the test samples and grid used in this study, including (1) 59 grids for visual interpretation, (2) ZY-3 reference set covering 23 cities, and (3) 5,385 building samples in the arid regions. The arid regions were extracted from “Deserts and xXeric sShrublands” biome in Olson et al., (2001). The inner graph shows the ISA density within the 0.5-km buffer for the ISA test samples.**



370 **Figure 6. Box plots of the overall accuracy for GISA-10m and existing datasets in the six continents.**

4 Results

4.1 Accuracy assessment of GISA-10m

4.1.1 Global scale

375 The accuracy assessment based on the visually interpreted samples ~~is were~~ shown in ~~the~~ Table 3. GISA-10m exhibit~~ed~~ the highest OA of 86.06%, ~~with representing~~ an increase ~~in OA~~ of +2.73%, +3.73%, and +2.3%, ~~respectively, over with respect to~~ GHSL_2018, GLCFCS, and WSF2015, ~~respectively~~ (Table 3). The ~~k~~-Kappa of GISA-10m ~~was~~ 0.7165, which exceed~~ed~~ the WSF2015, FROM_GLC10, and GAIA by 0.052, 0.1774, and 0.2039, respectively. ~~Alongside,~~ GISA-10m ~~also show~~ ~~ed~~ a higher accuracy ~~than as to~~ the 30-m ~~resolution~~ datasets (i.e., GISA, GAUD, GAIA), which suggest~~ed~~ a better delineation of global ISA, due to ~~the~~ its higher resolution. Fig. 6 summarize~~s~~ the results of the accuracy assessment at the continent level, with the average and standard deviation of ~~the~~ OA for each continent shown in the box plots. ~~In general~~ Overall, GISA-10m exhibit~~s~~ ~~ed~~ stable performance for each continent, with an average OA ~~of~~ more than 85%. Specifically, Oceania and South America ~~obtained show~~ the best OAs of 87.25% and 87.08%, followed by Europe (86.45%) and Asia (85.85%). The results also show~~ed~~ that the average ~~OA overall accuracy~~ of GISA-10m exceeds ~~that of~~ the existing datasets in Africa, North
385 America, and Europe. In addition, it ~~was found~~ ~~is~~ ~~apparent~~ that the performance of GHSL_2018 and GLCFCS ~~was~~ relatively unstable in South America and North America, respectively.

Table 3. Results of quantitative accuracy assessment via visually-interpreted and ZY-3 samples between GISA-10m and the existing ISA datasets. OA represents the overall accuracy.

Global e	Visually interpreted samples (n = 10800)				ZY-3 samples (n = 68368)			
	OA (%)	Kappa	F1-score of ISA (%)	F1-score of NISA (%)	OA (%)	Kappa	F1-score of ISA (%)	F1-score of NISA (%)
GISA-10m	86.06	0.7165	83.65	88.55	86.25	0.6664	76.25	90.32
GHSL 2018	83.33	0.6540	78.66	86.89	84.53	0.6401	75.27	88.74
GLCFCS	82.33	0.6336	77.57	85.96	84.56	0.6280	73.68	89.08
WSF2015	83.76	0.6645	79.68	87.06	85.44	0.6664	77.35	89.27
FROM_GLC10	78.16	0.5391	69.65	83.39	83.66	0.6082	72.39	88.39
GISA	78.84	0.5532	70.65	83.88	85.63	0.6627	76.65	89.63
GAUD	77.36	0.5185	67.46	83.01	85.59	0.6549	75.70	89.76
GAIA	77.05	0.5126	67.13	82.77	84.23	0.6381	75.39	88.40

390

GISA-10m obtain~~ed~~ the best OA of 86.25% on the ZY-3 samples, outperforming ~~GHSL 2018~~ GHSL 2018, GLCFCS, and WSF2015, by 1.72%, 1.69%, and 0.81%, respectively. The ZY-3 images employed by Liu et al., (2019) covered 45 major global cities, and therefore the ZY-3 samples were more inclined to reflect the accuracy in urban regions. Therefore, the accuracy difference between ~~the~~ various datasets ~~was~~ not significant (Table 3). Due to the relatively coarse~~r~~ resolution, the

395 30-m datasets usually tended to overestimate the ISA extent (Gong et al., 2020b), resulting in a higher UA but lower PA (Table S1). For example, the ISA UA of GISA ~~was~~ slightly higher than ~~that of~~ GISA-10m, but its PA ~~was~~ much smaller ~~than the latter~~ (Table S1). However, when the two metrics (PA and UA) ~~are~~ considered at the same time (i.e., ~~the~~ F1-score), GISA-10m outperformed GISA.

4.1.2 Rural, arid, and urban regions

400 The population of rural regions is comparable to that of urban regions (<https://data.worldbank.org/>). ~~The e~~Existing studies, as well as their global ISA datasets, ~~have~~ usually focused on the performance in urban regions, ~~and but~~ the accuracy of ~~the~~ rural ISA regions has not been sufficiently assessed. Hence, in this study, we paid special attention to the accuracy assessment in the global rural regions. Specifically, we divided the GISA-10m into urban and rural regions using the urban boundary defined by Li et al.; (2020). In fact, due to the random sampling strategy, most of ~~the~~ visually ~~-~~interpreted test samples were located in
405 rural regions.

In the case of the visually ~~-~~interpreted samples, GISA-10m exhibited ~~a~~ better OA of 86.19% ~~than against the GHSL2018~~ ~~GHSL 2018~~ (84.92%), GLCFCS (83.25%), FROM_GLC10 (78.83%), and WSF2015 (83.81%). As regards the three 30-m datasets (i.e., GISA, GAIA, GAUD), their ISA accuracy (F1-score) decreased ~~ed~~ significantly in the rural regions, while the NISA accuracy ~~was~~ relatively stable (Tables 2 & 3). ~~Taking~~ ~~Having~~ a closer look at the PA, ~~it is apparent one can notice~~ that the ISA
410 PA decreases by more than 15% for all ~~the~~ three 30-m datasets (Table S2), which suggests ~~that ed~~ ~~there are~~ more omission errors in the rural regions (Fig. 12b). This demonstrated ~~ed~~ the deficiency of ~~the~~ 30-m datasets in depicting rural ISA, and also reflected ~~ed~~ the importance of 10-m global ISA mapping.

415 **Table 4. Results of quantitative accuracy assessment via visually-interpreted and ZY-3 samples in rural regions between GISA-10m and the existing ISA datasets. OA represents the overall accuracy.**

Rural regions	Visually interpreted samples (n = 9547)				ZY-3 samples (n = 43950)			
	OA (%)	Kappa	F1-score of ISA (%)	F1-score of NISA (%)	OA (%)	Kappa	F1-score of ISA (%)	F1-score of NISA (%)
GISA-10m	86.19	0.6794	77.96	90.48	90.85	0.4768	52.46	94.94
GHSL 2018	84.92	0.6297	73.34	89.88	88.95	0.4656	52.82	93.74
GLCFCS	83.25	0.5871	70.15	88.72	89.46	0.4261	48.33	94.13
WSF2015	83.81	0.6012	71.17	89.12	89.37	0.4514	51.05	94.04
FROM_GLC10	78.83	0.4485	57.08	86.24	88.59	0.3884	45.08	93.63
GISA	77.87	0.4082	52.53	85.80	89.83	0.3954	44.66	94.40
GAUD	76.38	0.3516	46.13	85.05	89.70	0.3199	36.35	94.40
GAIA	75.41	0.3213	43.05	84.49	88.93	0.3611	41.85	93.88

Table 5. Results of quantitative accuracy assessment via visually-interpreted and ZY-3 samples in arid regions between GISA-10m and the existing ISA datasets. OA represents the overall accuracy.

Arid Region	Visually interpreted samples (n=1020)				ZY-3 samples (n=10827)			
	OA (%)	Kappa	F1-score of ISA (%)	F1-score of NISA (%)	OA (%)	Kappa	F1-score of ISA (%)	F1-score of NISA (%)
GISA-10m	86.67	0.7358	86.05	88.22	89.64	0.7296	79.95	93.01
GHSL 2018	86.57	0.7336	86.06	87.99	85.13	0.5817	67.68	90.34
GLCFCS	82.16	0.6454	80.32	84.46	85.14	0.6232	72.45	89.82
WSF2015	82.45	0.6516	80.95	84.56	88.37	0.6881	76.53	92.27
FROM_GLC10	76.27	0.5271	70.97	80.59	84.06	0.5755	68.18	89.37
GISA	80.20	0.6058	76.89	83.39	87.72	0.6795	76.23	91.72
GAUD	77.06	0.5424	71.88	81.20	88.66	0.6894	76.37	92.54
GAIA	77.45	0.5506	72.84	81.35	85.78	0.6317	72.79	90.37

Furthermore, we also focused on the accuracy assessment in arid regions. In general, the OA of GISA-10m was higher than that of the existing datasets (Table 5). Although its ISA UA does not always outperform the other datasets, GISA-10m achieves the highest PA among the existing ones (Table S3S4). Specifically, GISA-10m exhibits a notably higher ISA PA compared to GLCFCS, FROM_GLC10, GISA, GAUD, and GAIA (Table S3), indicating its better-superior ability to detecting ISA in arid regions (Fig. 7). Moreover, the accuracy of these global ISA products was assessed using the manually and randomly chosen rural building samples (see Section 3.2). It can be found that GISA-10m detects 15% more buildings in arid regions with respect to FROM-GLC10, GAUD, and GAIA (Table S4S5), which again-further verifies its better-superior performance in describing rural ISA.

In the case of urban regions, GISA-10m exhibits a satisfactory result, with an OA similar to that of the global assessment (Table 6S4). Note that urban ISA only accounts for one-third of global ISA, while nearly 70% of ISA was located in suburban and rural regions. The existing datasets showed relatively more ISA omissions in rural and/or arid regions, suggesting that global ISA mapping at a 10-m resolution (e.g., GISA-10m) is necessary. Moreover, we divided the visually-interpreted samples located in cities into three levels (i.e., small, medium, and large cities) to assess the accuracy of GISA-10m over-for cities of different scales, i.e., Level 1 (population < 250,000), Level 2 (250,000 to 1,000,000), and Level 3 (>1,000,000) (Yang et al., 2019). It was found that the OA of GISA-10m across the three levels of cities was 85.35%, 87.43%, and 85.42%, respectively (Table S5S6). These results indicated that the performance of GISA-10m in different scales of cities was stable, and was the results are also close to the global assessment result (OA of 86.06%).

445 **Table 6. Results of quantitative accuracy assessment via visually interpreted and ZY-3 samples in urban regions between GISA-10m and the existing ISA datasets. OA represents the overall accuracy.**

Urban Regions	Visually interpreted samples (n=2253)				ZY-3 samples (n=24418)			
	OA (%)	Kappa	F1-score of ISA (%)	F1-score of NISA (%)	OA (%)	Kappa	F1-score of ISA (%)	F1-score of NISA (%)
GISA-10m	85.49	0.30	91.93	38.26	77.96	0.52	82.71	69.61
GHSL-2018	76.61	0.20	86.02	31.41	76.56	0.47	82.38	64.99
GLCFCS	78.43	0.18	87.51	27.96	75.75	0.48	80.98	66.55
WSF2015	83.58	0.23	90.73	32.76	78.36	0.49	84.64	63.38
FROM_GLC10	75.32	0.21	85.15	31.66	74.78	0.45	80.35	64.80
GISA	82.96	0.24	90.41	33.15	78.09	0.49	84.25	63.98
GAUD	81.49	0.22	89.49	31.06	78.20	0.50	84.07	65.48
GAIA	84.02	0.20	91.07	29.57	75.77	0.41	83.30	55.83

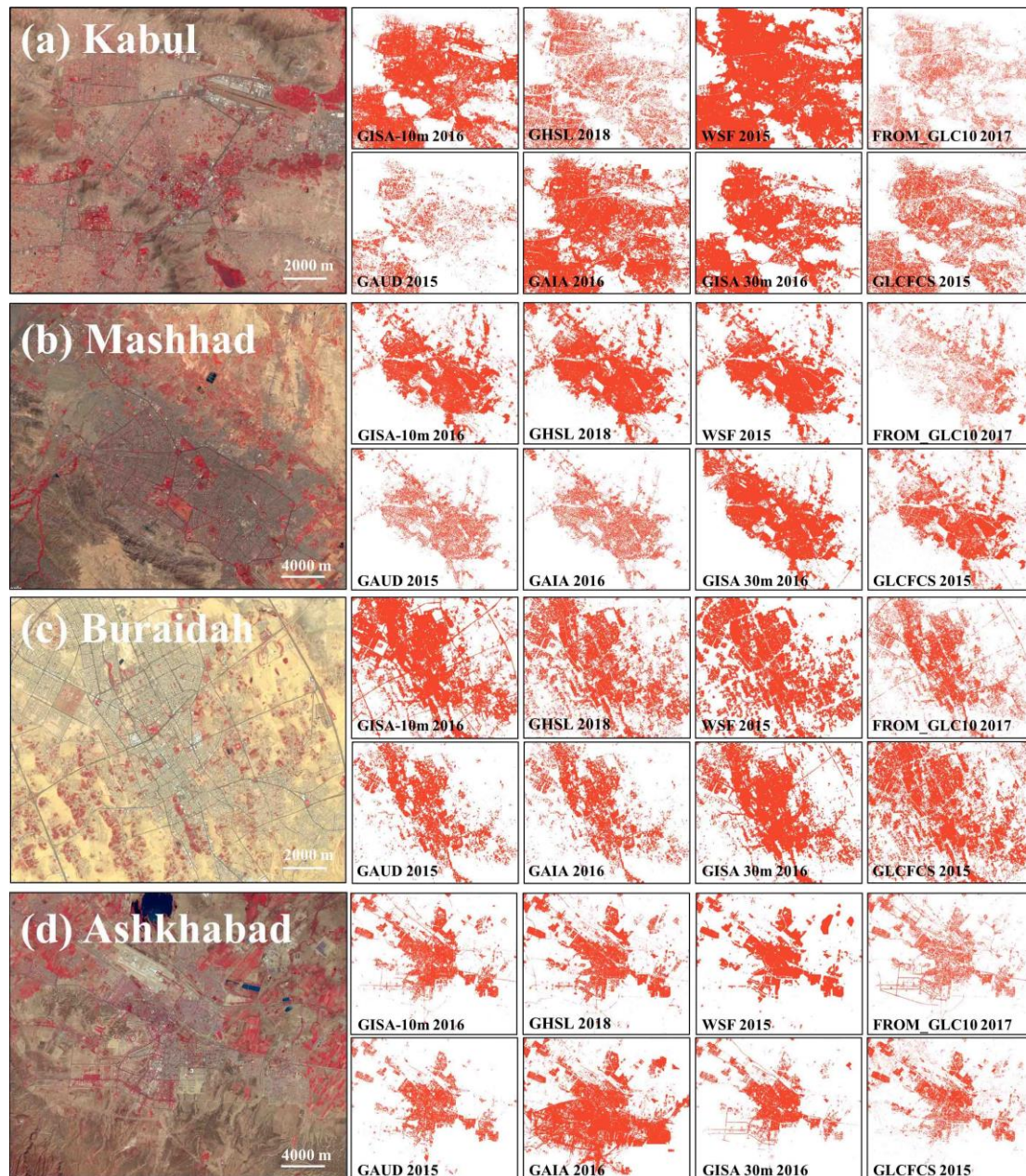


Figure 7. Comparison of the GISA-10m and the other datasets over arid regions in: (a) Kabul, Afghanistan; (b) Mashhad, Iran; (c) Buraidah, Saudi Arabia; (d) Ashkhabad, Turkmenistan. The illustration is of Sentinel-2 images with a false-color combination (R: NIR, G: rRed, B: gGreen) to enhance the ISA.

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4.2 Global ISA distribution

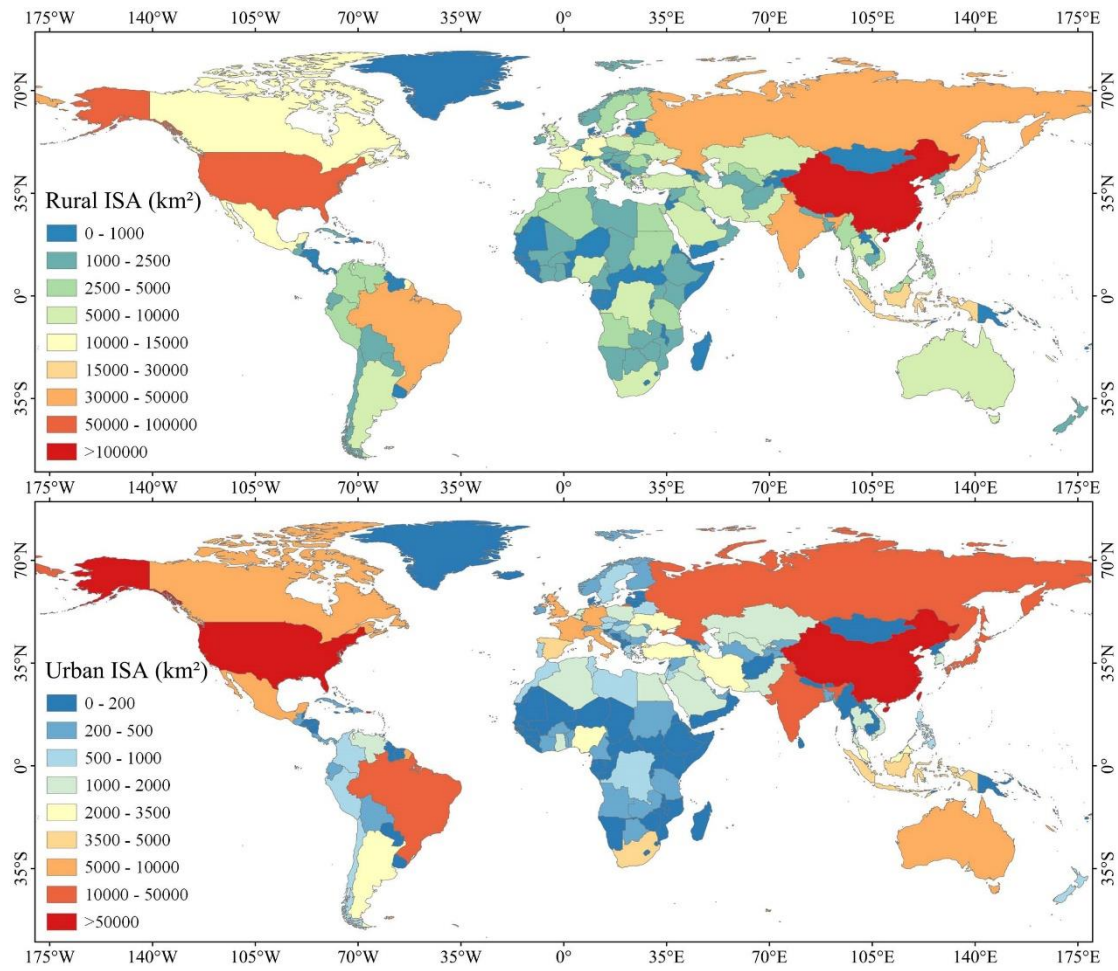
4.2.1 Urban and rural ISA

Based on the GISA-10m, we analyzed the global ISA distribution at a 10-m scale (Fig. S1). Global ~~impervious surface area~~ ISA ~~i~~was mainly distributed in Asia (41.43%), North America (20.59%), and Europe (18.93%), followed by Africa (9.78%) and South America (7.50%). It ~~i~~was found that 67% of global ISA ~~i~~was located in the Eastern Hemisphere, while 85% of ISA ~~i~~was distributed ~~to~~in the north of the equator. Rural ISA ~~i~~was more scattered than urban ISA (Fig. S1), and ~~it~~was mainly located in Asia (42.84%), Europe (19.49%), and North America (16.51%). Asia ~~embraced~~has the largest urban ISA, which is more than twice ~~that of~~as Europe. Although North America only ~~account~~sed for 20% of global ISA, its urban ISA ~~takes~~ook up more than 29% of the global total. Taking a closer look at the ratio of rural and urban ISA (Table 76), ~~one can see~~it can be seen that rural ISA ~~is~~were 2.2 times larger than ~~the~~urban ISA. At the continental level, Africa ~~possesses~~ed the highest “rural-to-urban ratio”, which ~~may be~~is likely related to its large population but relatively poor economy.

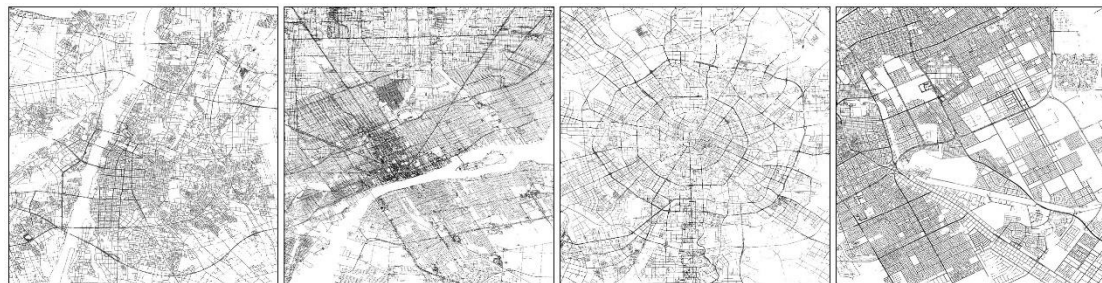
Table 76. Impervious surface area derived from GISA-10m in the six continents.

ISA	Europe	Africa	S. America	Oceania	N. America	Asia	Globale
Total (10 ⁵ -km ²)	1.88 (18.93%)	0.97 (9.78%)	0.75 (7.50%)	0.18 (1.76%)	2.05 (20.59%)	4.12 (41.43%)	9.94 (100%)
Rural (10 ⁵ -km ²)	1.33 (19.49%)	0.78 (11.43%)	0.55 (8.11%)	0.11 (1.62%)	1.13 (16.51%)	2.93 (42.84%)	6.84 (100%)
Urban (10 ⁵ -km ²)	0.55 (17.69%)	0.19 (6.16%)	0.19 (6.17%)	0.07 (2.07%)	0.92 (29.56%)	1.19 (38.35%)	3.10 (100%)
Rural/ <u>U</u> Urban	2.42	4.08	2.89	1.73	1.22	2.46	2.20

At the country scale, China and the ~~United States~~ (US) ~~embraced~~account for 33% of global ISA. Together with Russia, Brazil, India, Japan, Indonesia, France, Canada and Germany, these ten countries ~~accounted~~ for 58% of the world ISA. The urban ISA ~~owned by~~of the top ten countries (US, China, Russia, Brazil, Japan, India, Mexico, France, Germany, and the United Kingdom) ~~took~~makes up 69% of the global total, while the top ten countries in terms of rural ISA (China, US, Russia, Brazil, India, Indonesia, Japan, France, Canada, and Germany) ~~accounted~~ for only 54% of the total. In Africa, the Republic of South Africa ~~has~~ed much more urban ISA than the other countries. However, Nigeria ~~has~~as showed comparable rural ISA to ~~the~~ South Africa (~7738 km²). China ~~ranked~~ed first in terms of rural ISA, most of which ~~i~~was located in the North China Plain (Fig. 9B3b). Indonesia also ~~possesses~~ed a lot of ~~much~~ rural ISA, since it ~~ranked~~ed sixth for ~~in the~~ rural ISA but ~~its urban ISA~~ only ~~ranked~~ sixteenth for urban ISA.



475 **Figure 9. Urban and rural ISA at the country scale based on GISA-10m.**



Toyama

Detroit

Chengdu

Riyadh

Figure 109. Examples of road area derived from GISA-10m and OSM in the Toyama (Japan), Detroit (US), Chengdu (China), and Riyadh (Saudi Arabia).

Roads are major anthropic footprints, ~~so~~ we attempted to ~~analyse~~~~analyze~~ the global road area based on GISA-10m, ~~by~~ courtesy of its high spatial resolution. Firstly, the road networks were extracted from ~~the~~ OSM ~~database~~, and then, the ISA regions in the GISA 10-m ~~data~~ within a 10-m buffer of the road networks were identified as ~~the~~ road areas (Fig. 409). ~~The~~ ~~r~~Results showed that 82.84% of the global road area ~~is~~ located in Asia (30.74%), North America (27.17%), and Europe (24.92%), while the remaining 17.16% ~~was owned by~~~~is found in~~ South America (8.26%), Africa (7.47%), and Oceania (1.44%). Although Asia ~~far exceed~~~~ed~~ the other continents ~~with~~ regard ~~to~~~~ing~~ ISA and rural road area, it possesses ~~ed~~ ~~less~~ ~~a~~ ~~smaller~~ urban road area than North America. China and ~~the~~ US ~~have~~~~ed~~ the largest road area, together accounting for 29% of the global total, ~~which were~~ followed by Brazil, Japan, Russia, Germany, India, France, Indonesia, and Mexico. The top ten countries ~~have owned~~ more than half of ~~the~~ global road ~~areas~~. The global road area account~~ed~~ for 14.18% of the global ISA, and ~~the~~ rural road area ~~is~~ 1.5 times larger than ~~the~~ urban ~~road area~~ (Table 87). However, it should be noted that these estimates might be biased owing to the incompleteness of the OSM data. In addition, narrow roads might be partly detected or missed, ~~due~~ to the limitation of ~~the~~ spatial resolution.

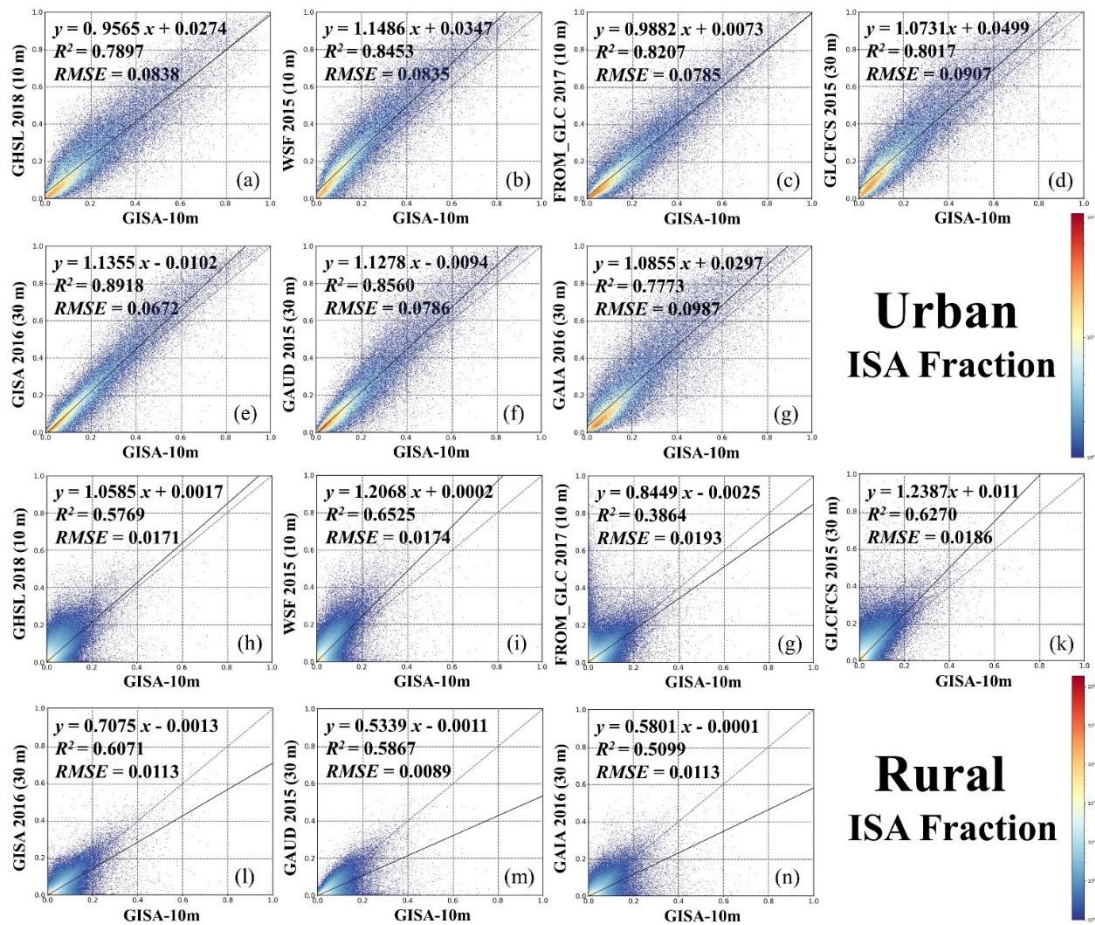
Table 87. Statistics for the road area derived from GISA-10m and OSM in the six continents.

Road	Europe	Africa	S. America	Oceania	N. America	Asia	Global
Total (10 ⁴ -km ²)	3.51 (24.92%)	1.05 (7.47%)	1.16 (8.26%)	0.20 (1.44%)	3.83 (27.17%)	4.34 (30.74%)	14.10 (100%)
Rural (10 ⁴ -km ²)	2.27 (26.88%)	0.71 (8.43%)	0.75 (8.88%)	0.11 (1.26%)	1.84 (21.73%)	2.77 (32.82%)	8.45 (100%)
Urban (10 ⁴ -km ²)	1.24 (21.99%)	0.34 (6.03%)	0.42 (7.34%)	0.10 (1.70%)	2.00 (35.29%)	1.56 (27.65%)	5.66 (100%)
Rural/Urban	1.82	2.09	1.81	1.10	0.92	1.77	1.49

5 Discussions

495 5.1 Inter-comparison with ~~the~~ existing datasets

To further validate the performance of GISA-10m, we compared it with ~~a series of~~~~the~~ existing state-of-the-art global datasets, ~~including i.e.~~, three 10-m ~~resolution~~ datasets (~~i.e.~~ WSF2015, ~~GHSL2018~~~~GHSL 2018~~, FROM_GLC10) and four 30-m ~~resolution~~ datasets (~~i.e.~~ GLCFCS, GAUD, GAIA, ~~and~~ GISA). Their spatial agreements with GISA-10m ~~was~~~~ere~~ measured by the linear fit of ~~the~~ ISA fraction, including metrics such as ~~the~~ correlation coefficient and root-~~mean~~-~~square~~ error (RMSE).
 500 Attention was also paid to the~~r~~ performance ~~of the different products~~ in urban and rural regions, for a comprehensive assessment. Considering the~~r~~ differen~~tee~~-of spatial resolutions, the ISA fraction was calculated within the 0.05° spatial grid.

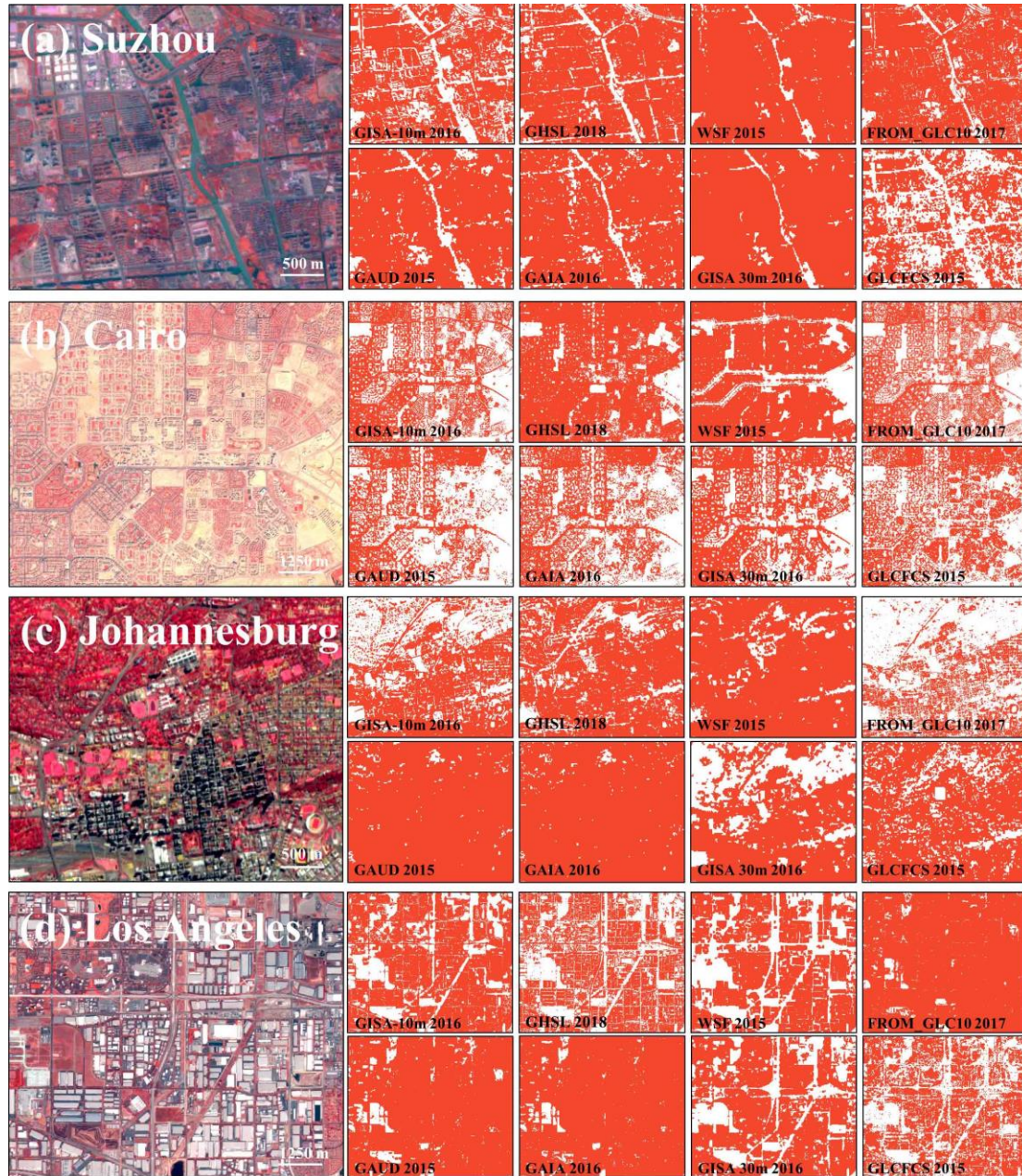


505 **Figure 4.10.** Scatterplots of the urban and rural ISA fraction between GISA-10m with GHSL, WSF, FROM_GLC10, GLCFCS, GAUD, GAIA, and GISA, respectively. The ISA fraction was calculated within a $0.05^\circ \times 0.05^\circ$ spatial grid.

In general, GISA-10m exhibits aed high agreement ($0.777 < R^2 < 0.892$) with these existing datasets over urban regions. In the case of GHSL_2018 and FROM_GLC10, their fitted lines with GISA-10m awere closer to the 1:1 line in the high fraction regions (Figs. 4a-10a and &c). As shown in the-Fig. 4.211, GHSL_2018 and GISA-10m awere generally similar in the dense urban areas (e.g., the urban cores in Fig. 4.211), but GHSL_2018 tendsed to overestimate ISA in the low-density residential areas (Fig. 4.2e11c). The fitted lines for GLCFCS and WSF2015 awere above the diagonal (slope greater than 1 and intercept greater than 0) in both the high and low ISA fraction regions, possibly owing due to their overestimations. For instance, in the case of Cairo (Fig. 4.2b11b), WSF2015 showsed significant overestimations, but the other datasets better depicted the residential areas. According to Marconcini et al., (2020), the overestimations of the-WSF2015 may be related to the employment of the coefficient of variation (COV), which reducesd the omissions in the rural regions, but at the same time

515 leads to overestimations of the ISA extent. The fitted lines for the three 30-m resolution datasets (i.e., GISA, GAIA, GAUD) awere all above the diagonal (Fig. 4.4e10e-g), suggesting that they detected more urban ISA than GISA-10 m. However, in the 30-m resolution datasets, vegetation alongside roads or buildings iwas often identified as ISA, due to the issue of mixed

520 pixels (Gong et al., 2020b). From this perspective, the results of GISA-10m seem appear more reliable, due to its higher spatial resolution. For instance, in the case of Johannesburg and Los Angeles (Fig. 12e-11c and &d), GAIA and GAUD exhibited false alarms in both residential and industrial areas, but these errors awere significantly reduced in GISA-10m, due to the superiorbetter discriminativeeen ability of the 10-m Sentinel data.



525 **Figure 12.11.** Comparison betweenof the GISA-10m and the seven datasets over urban regions in: (a) Suzhou, China; (b) Cairo, Egypt; (c) Johannesburg, South Africa; (d) Los Angeles, USthe United States. The Sentinel-2 images were composited in athe false-color combination (R: NIR, G: rRed, B: gGreen).

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On the other hand, the agreement between GISA-10m and ~~the~~ existing datasets ~~iw~~as slightly lower in rural regions ($0.5099 < R^2 < 0.6525$). The fitted slopes between ~~the~~ three 30-m datasets (i.e., GISA, GAIA, GAUD) and GISA-10m in ~~the~~ rural regions ~~a~~were all less than one. This phenomenon can be attributed to the finer spatial resolution of GISA-10m, which detect~~ed~~ more rural ISA than the 30-m datasets (Figs. ~~13b-12b and &~~d). As ~~for~~ GLCFCS and WSF2015, they possess~~ed~~ more rural ISA than GISA-10m (Fig. ~~14-10i and &~~k), which ~~could~~may be attributed ~~to~~ their overestimations. For example, in Figs. ~~13a-12a and &~~c, GLCFCS and WSF2015 fail~~ed~~ to identify the vegetation in the village. FROM_GLC10 ~~seemed~~appears more consistent with GISA-10m (see the sample ~~from the~~of US ~~in~~, Fig. ~~13d-12d~~), but it tend~~ed~~ to underestimate the rural ISA (see Figs. ~~13a-12a-c~~). GHSL_2018 and GISA-10m show~~ed~~ high agreement in ~~the~~ rural regions. However, GHSL_2018 ~~is~~ aimed ~~at~~the outlin~~ing~~e human settlements, while GISA-10m ~~is~~ focused on artificial ISA (including buildings, parking lot~~s~~, roads).

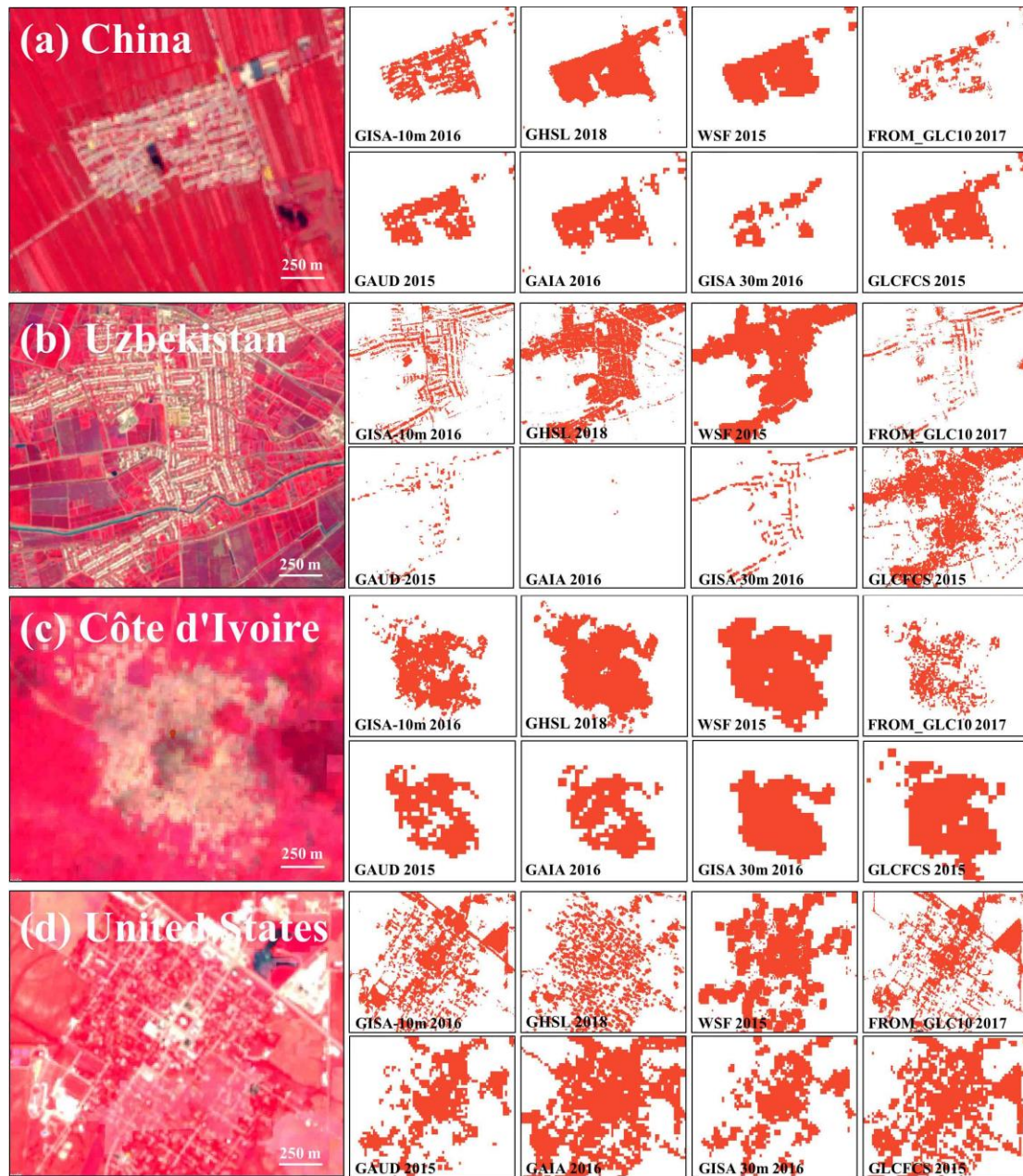


Figure 1312. Comparison of the between GISA-10m and the seven datasets over rural regions in: (a) China (126.348044° E, 45.269079° N); (b) Uzbekistan (60.573313° E, 41.461425° N); (c) Côte d'Ivoire (5.853317° W, 6.820244° N); (d) the United States (90.210747° W, 39.950221° N). The illustration is of Sentinel-2 images with a false-color combination (R: NIR, G: rRed, B: gGreen) to enhance the ISA.

535

540 The differences between GHSL_2018, WSF2015, and GISA-10m were further analysed by taking Beijing and Washington as examples. In Fig. 1413, the overlapping parts between these datasets were marked in different colors, and the regions where the three datasets all agreed were shown in gray. In both examples, WSF2015 and GHSL2018

tended to overestimate the ISA extent (Fig. 14b13b), and they wrongly identified vegetation as ISA in the low-density residential areas (Fig. 14b13h). In particular, GHSL2018GHSL 2018 successfully detects the roads in Beijing, but failed in Washington (see the color-of-purple color in Fig. 1413). This may be related to the fact that GHSL2018GHSL 2018 used different sources of training samples in different regions (Corbane et al., 2021). Although WSF2015 generally obtained similar results to with GISA-10m, its detected roads may stem from the overestimation of building boundaries. For instance, WSF2015 ignored the airport runways in the example of Beijing (Fig. 14d13d). In the case of Washington, WSF2015 was less capable of delineating scattered buildings than GISA-10m and GHSL2018GHSL 2018 (Fig. 14f13f), possibly because it also incorporated the 30-m Landsat data in the ISA detection. It should be mentioned that GHSL2018GHSL 2018 estimates the probability of human settlement, and hence, different thresholds could yield different results. Small thresholds were suitable for capturing scattered settlements, but could result in false alarms. In this study, we chose 0.2 as the threshold, as suggested by Corbane et al. (2021).

less significant role than the -temporal metrics. In contrast, the spectral indices and phenological information awere more effective in this region. For example, as shown in Fig. ~~S4-S5~~ (red squares), in the residential area, the buildings awere often surrounded by dense shrubs, which canmay shrinkreduce the double bounce scattering. Therefore, the spectral and phenological features have ad higher importance since they can better distinguish vegetation from non-vegetation. A similar situation occurs~~red~~ in a desert area (26N_45E), where the SAR features canould-not distinguish ISA from NISA effectively, due to the complex topography~~-of mountains~~. In this case, the spectral indices and textures awere more effective (Fig. ~~4514~~). However, SAR features awere still very important for global ISA mapping, especially for identifying rural buildings (Zhang et al., 2020). Therefore, in this study, we used multi-source features and hexagon-based adaptive RFrandom forest models to ensure that the most suitable features were chosen for the different regions.

5.3 Impact of the training sample size and tree number

Based on the ~~afore-mentionedmentioned~~ randomly selected 30 hexagons in different urban ecoregions, we investigated the relationship between the training sample size and the accuracy (Fig. S1). For each hexagon, we fixed the number of NISA samples to 30,000 and changed the number of ISA_{RS} and ISA_{OSM} samples. Specifically, we first randomly selected 1,000 ISA_{RS}, 1,000 ISA_{OSM}, and 2,000 NISA samples from the candidate pool (see Section 3.1.1) as the test samples and used the remaining ones for the training. We randomly selected 50 ISA_{RS} and 50 ISA_{OSM} samples as the initial training samples; and, subsequently, in an iterative manner, 400 ISA_{RS} and ISA_{OSM} samples were randomly selected from the pool and added to the training samples to train the RF classifier. It can be observed that all the hexagons reached saturation with 2,500 ISA_{RS} and ISA_{OSM} samples (Fig. ~~S5S6~~). Therefore, in this research, we set the number of ISA_{RS}, ISA_{OSM}, and NISA samples to 2,500, 2,500 and 30,000, respectively.

We also analyzed the effect of the tree number on the accuracy of global ISA mapping, using the 30 ~~afore-mentionedmentioned~~ mapping grid cells from global urban ecological regions. The results showed that the OAoverall accuracy iwas low and unstable whenthe the number of trees iwas less than 20 (Fig. ~~S6S7~~). As the number of trees increased, the mapping accuracy increased and then stabilized around 200 trees. Therefore, we used 200 trees for each RFrandom forest model in GISA-10m.

5.4 Advantages of locally adaptive RF classification

We used two hexagons located in China (CHN) and Saudi Arabia (SA) to demonstrate the advantages of the adaptive RFrandom forest classification. Although China and Saudi Arabia are both located in Asia, their urban landscapes and architectural le styles are significantly different, due to their differences in climate, environment, and culture. In this experimentsection, we migrated the training samples from one hexagon to classify the other one. For example, training samples collected in the-SA wereas used to classify the hexagon of China. The accuracy of each hexagon was evaluated by the visually -interpreted samples inside it. ~~It was found that~~The results show that the OA decreased by 34% when the SA samples arewas applied to CHN (written as SA-to-CHN). Similarly, the OA iwas substantially reduced by 23% by the transfer of CHN-to-SA. Furthermore, ~~we found that~~the local samples always outperformed the migrated ones (see Table ~~9S7~~), which verified the

610 necessity of locally ~~and~~-adaptive classification strategies in ~~the~~ global ISA mapping. ~~Furthermore~~~~Besides~~, ~~at~~ the locally adaptive model is more sensitive to the sample quality ~~compared to the~~~~than a~~ global model (Radoux et al., 2014), which further show~~ed~~ the necessity and effectiveness of the local classification strategy.

Table 9. Results of quantitative accuracy assessment for China (CHN) and Saudi Arabia (SA) based on local and transferred samples. OA denotes the overall accuracy.

	Saudi Arabia				China			
	OA (%)	Kappa	F1 score of ISA (%)	F1 score of NISA (%)	OA (%)	Kappa	F1 score of ISA (%)	F1 score of NISA (%)
ISA_SA & NISA_SA	93.00	0.8599	92.39	93.95	79.50	0.5915	77.60	81.86
ISA_SA & NISA_CN	53.00	0.7253	65.44	26.77	55.00	0.5233	4.35	70.59
ISA_CN & NISA_SA	70.50	0.8396	53.23	78.55	48.00	0.6251	63.38	40.53
ISA_CN & NISA_CN	50.50	0.0846	64.77	16.95	89.00	0.7778	86.90	91.30

615 5.5 Influence of the sources of training samples

In this section, the effects of the training sample sources, i.e., ~~from the~~ remote sensing dataset (ISA_{RS}) and the OSM ~~database~~ (ISA_{OSM}), were investigated. Various combinations of the ISA_{RS} and ISA_{OSM} training samples were tested at the global scale using the visually ~~_~~interpreted samples from Section 3.2 (Table ~~10S8~~). In general, it can be found that using both sources yield~~ed~~ the most accurate results, which show~~ed~~ the effectiveness and necessity of ~~incorporati~~~~incorporating on of~~ training samples from ~~both~~ remote sensing and crowdsourc~~ing~~ OSM ~~data~~. By further checking the UA and PA of ISA, ~~one it can be~~ seen that using both sample sources significantly improve~~d~~ the PA and reduce~~d~~ the ISA omissions, since the combination of ISA_{RS} and ISA_{OSM} strength~~en~~~~ed~~ the diversity of the training samples. Similarly, it ~~is~~~~was~~ also found that the multi-source samples significantly raise~~d~~ the PA of NISA and lower~~ed~~ its commission error.

625 **Table 10. Results of global accuracy assessment for ISA_{RS} and ISA_{OSM} sample. OA denotes the overall accuracy, while PA and UA indicate the user's accuracy and the producer's accuracy, respectively.**

Source of training sample	OA (%)	Kappa	F1 score of ISA (%)	F1 score of NISA (%)	UA of ISA (%)	PA of ISA (%)	UA of NISA (%)	PA of NISA (%)
NISA+ISA _{RS} +ISA _{OSM}	86.06	0.7165	83.65	88.55	86.13	81.30	86.01	91.25
NISA+ISA _{RS}	80.24	0.5871	73.85	84.63	88.16	63.54	76.73	94.35
NISA+ISA _{OSM}	82.99	0.6500	78.96	86.34	86.24	72.81	81.17	92.23

Given that geographic bias in the spatial distribution of OSM data ~~can may~~ affect the mapping results (Zacharopoulou et al., 2021), we applied temporal and spatial rules to mitigate the effect of the difference of the spatial distribution. In addition, ~~a~~ spectral rule was used to remove potential errors in ~~the~~ OSM-derived training samples (i.e., ISA_{OSM}). In fact, more than 82% of ~~the~~ OSM ways are buildings and highways, whose total number exceeds 700 million (<https://taginfo.openstreetmap.org/keys>, 630 last access~~ed~~: 20 June 2022). Therefore, OSM data provides a reference for large-scale ISA mapping, but ~~have it has~~ rarely been employed in global ISA mapping. We calculated the ~~OA~~~~overall accuracy~~ for the test grid ~~cells~~ where the number of ISA_{OSM} training samples ~~was~~~~ere~~ less ~~than~~ or larger than 2500 (i.e., the recommended size of training sample in Section 5.3).

The results showed that the accuracy of these regions ~~is~~ was similar to the global accuracy (Table ~~4~~ S9). This phenomenon demonstrates ~~the~~ the stable performance of GISA-10m. Moreover, global ISA mapping using only ISA_{OSM} training samples shows ~~a~~ relatively stable accuracy across the continents (Fig. ~~5~~ S8), suggesting that the refined OSM buildings and roads can reduce the impact of their uneven spatial distribution. This can be attributed to the rule-based method we implemented that improved the reliability and spatial consistency of ISA_{OSM}. In addition, the collaboration of ISA_{OSM} improves ~~the~~ the ~~OA~~ overall accuracy of global ISA mapping by 3% (Table ~~4~~ S8), indicating the feasibility of OSM data in enhancing ~~the~~ the performance of global ISA mapping, after a series of refinements. Overall, although the spatial distribution of ~~the~~ the OSM data is uneven, we tried to balance its spatial distribution through a series of rules, and incorporated multi-source geospatial data (e.g., satellite-derived datasets) to reduce the impact of geographical bias on GISA-10m.

Table 11. Results of quantitative accuracy assessment for test grids with the number of ISA_{OSM} training samples less or more than the recommended size. OA represents the overall accuracy.

Type of test grids	OA (%)	Kappa	F1-score of ISA (%)	F1-score of NISA (%)
#ISA _{OSM} < 2500	85.61	0.7021	81.79	89.01
#ISA _{OSM} > 2500	86.23	0.7218	84.32	88.35
All of the above	86.06	0.7165	83.65	88.55

6 Data availability

The GISA-10m ~~dataset~~ product generated in this study is available in the public domain at <http://doi.org/10.5281/zenodo.5791855> (Huang et al, 2021). ~~The~~ Sentinel data were acquired from the GEE (available at code.earthengine.google.com, last accessed: 6-August 6, 2021). ~~The~~ GHSL data ~~were~~ provided by the Joint Research Centre at ~~the~~ the European Commission (available at <https://ghsl.jrc.ec.europa.eu/datasets.php>, last accessed: 19-December 19, 2021). WSF was provided by the German Aerospace Center (<https://doi.org/10.6084/m9.figshare.c.4712852>, Marconcini et al., 2020). The GlobeLand30 and GAUD were downloaded from the ~~website~~s of the National Geomatics Center of China (available at <http://www.globallandcover.com/>, last accessed: 6-August 6, 2021) and Sun Yat-sen University (available at <https://doi.org/10.6084/m9.figshare.11513178.v1>, Liu et al., 2020b). ~~The~~ FROM_GLC10, global urban boundaries, and GAIA were ~~assessed from the~~ provided by Tsinghua University (available at <http://data.ess.tsinghua.edu.cn>, last accessed: 6-August 6, 2021). The GISA was provided by the Institute of Remote Sensing Information Processing at Wuhan University (available at <https://zenodo.org/record/5136330>, Huang et al., 2021a). ~~The~~ GLCFCS was provided by ~~the~~ the Aerospace Information Research Institute at ~~the~~ the Chinese Academy of Sciences (available at <https://zenodo.org/record/4280923>, Zhang et al., 2021). The Planet files were download from the ~~website of~~ OpenStreetMap ~~website~~ (available at <https://planet.openstreetmap.org>, last accessed: 19-December 19, 2021).

7 Conclusion

660 In this study, we proposed a global ISA mapping method and produced ~~athe~~ 10-m global ISA dataset (GISA-10m). To ~~the best~~
~~of~~ our knowledge, this is the first global 10-m ~~resolution~~ ISA ~~dataset~~~~map~~ based on ~~Sentient~~~~Sentinel~~-1 and 2 data. To this end,
a global training sample generation method was ~~proposed-introduced~~ based on a series of temporal, spatial, spectral, and
geometrical rules, and 58 million training samples were generated from the existing global ISA datasets and ~~the social~~
~~sensing~~~~VGI~~ data (i.e., OSM). On the basis of the 2.7 million Sentinel images available ~~in~~ the ~~GEE platform~~~~google Earth Engine~~
665 ~~(GEE)~~, multi-source features were constructed, including spectral, textur~~ale~~, SAR, and temporal metrics. The global terrestrial
surface was divided with hexagons, and the results were obtained by a series of RF classifiers. In particular, the mapping was
conducted adaptively for each hexagon, by considering the difficulty and diversity for the global ISA detection. The ~~OA~~~~overall~~
~~accuracy~~ of GISA-10m exceeded 86%, based on a set of independent test samples. The inter-comparison between ~~the~~ different
global ISA datasets ~~showed-confirmed~~ the superiority of ~~theour~~ results ~~obtained in this study~~. Based on ~~the~~ GISA-10m ~~dataset~~,
670 the ISA distribution at the global, continental, and country levels was ~~discussed-investigated~~ and compared. In addition, the
global ISA distribution was compared between rural and urban ~~areas~~. In particular, for the first time, ~~by~~-courtesy of the high
spatial resolution, the global road ISA was further identified and its distribution was discussed.

~~The~~ GISA-10m ~~dataset couldan~~ be used for global climate change studies and urban planning. ~~TheOur~~ proposed rule-based
sample generation method ~~couldan~~ also be applied for ~~the~~ global mapping of other land-~~cover~~ categories. For example, ~~the~~
675 millions of cropland and forest tags in the OSM ~~database couldan~~ facilitate global high-resolution cropland and forest mapping.
The ISA mapping method via multi-source geospatial data presented in this paper ~~couldan~~ also be improved by incorporating
additional data sources, such as building footprints from Microsoft and Facebook (Corbane et al., 2021). In the future, we plan
to extend the temporal coverage of GISA-10m and reveal the global ISA dynamics at the 10-m resolution.

680 **Author contributions.** XH conceived the study. XH, JY, WW, and ZL designed and implemented the methodology. JY
prepared the original draft and XH revised the manuscript.

Competing interests. The authors declare that they have no conflicts of interest.

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690 GlobeLand30 ~~product~~ provided by the National Geomatics Center of China, the FROM_GLC10 ~~product~~ provided by Tsinghua
University, and the GISA data provided by Wuhan University. We ~~would also like to~~ thank the Google Earth Engine team for

their excellent work into maintaining the planetary-scale geospatial cloud platform, as well as the volunteers around the world that have contributed to the OpenStreetMap database.

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