

1 **Hyperspectral reflectance spectra of floating matters derived from** 2 **HICO observations**

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6 **Abstract**

7 Using data collected by the Hyperspectral Imager for the Coastal Ocean (HICO) on the International Space Station
8 between 2010 – 2014, hyperspectral reflectance of various floating matters in global oceans and lakes are derived for
9 the spectral range of 400 – 800 nm. Specifically, the entire HICO archive of 9,411 scenes is first visually inspected to
10 identify suspicious image slicks. Then, a nearest-neighbor atmospheric correction is used to derive surface
11 reflectance of slick pixels. Finally, a spectral unmixing scheme is used to derive the reflectance spectra of floating
12 matters. Analysis of the spectral shapes of these various floating matters (macroalgae, microalgae, organic particles,
13 whitecaps) through the use of a Spectral Angle Mapper (SAM) index indicates that they can mostly be distinguished
14 from each other without the need of ancillary information. Such reflectance spectra from the consistent 90-m resolution
15 HICO observations are expected to provide spectral endmembers to differentiate and quantify the various floating
16 matters from existing multi-band satellite sensors and future hyperspectral satellite missions such as NASA’s Plankton,
17 Aerosol, Cloud, and ocean Ecosystem (PACE) mission and Surface Biology and Geology (SBG) mission.

18

19 **Keywords:** Remote sensing, hyperspectral, HICO, OCI, PACE, SBG, floating matters, *Ulva*, *Sargassum*, *Noctiluca*,
20 *Trichodesmium*, *Microcystis*, brine shrimp, oil slicks, whitecaps, marine debris.

21 **1. Introduction**

22 Since the debut of the first proof-of-concept Coastal Zone Color Scanner (CZCS, 1978 – 1986), satellite ocean color
23 missions have evolved from the original goal of mapping phytoplankton biomass and primary production to many
24 other applications. Because of improved spectral resolution and instrument sensitivity, mapping various floating
25 matters also becomes possible (IOCCG, 2014). These floating matters range from living to non-living, including
26 *Sargassum* macroalgae, *Ulva* macroalgae, cyanobacterium *Microcystis*, cyanobacterium *Trichodesmium*,
27 dinoflagellate *Noctiluca*, aquatic plants, brine shrimp cysts, oil slicks, pumice rafts, sea snots, marine debris, among
28 others (Qi et al., 2020; Hu et al., 2022).

29 Currently, mapping floating matters using optical remote sensing requires the detection of a spatial anomaly using the
30 near-infrared (NIR) bands, and then discrimination of the anomaly by comparing its spectral characteristics with
31 known spectra of floating matters (Qi et al., 2020), or by using ancillary information (e.g., in certain regions a spatial
32 anomaly can only be caused by a certain type of floating algae). Spectral discrimination requires the knowledge of

33 spectral signatures of various floating matters. However, despite scattered laboratory or field measurements of certain
34 types of floating matters, hyperspectral data of these floating matters are mostly unavailable. Although medium-
35 resolution (300-m) sensors such as the Ocean and Land Colour Imager (OLCI) has been used to show spectral
36 variations of floating matters (Qi et al., 2020), the data are not hyperspectral, therefore certain spectral features may
37 have been missed. For example, various pigments (e.g., chlorophyll-*a*, *b*, *c*, Fucoxanthin, Zeaxanthin, phycocyanin,
38 carotenoid, etc.) have been found in natural populations of microalgae (i.e., phytoplankton, Bidigare et al., 1990;
39 Bricaud et al., 2004) and macroalgae (e.g., Bell et al., 2015; Wang et al., 2018). These pigments often have narrow
40 absorption and reflectance features that can be missed by multi-band sensors, therefore requiring more spectral bands
41 or hyperspectral data to perform spectroscopic analysis.

42 Data collected by the Hyperspectral Imager for the Coastal Ocean (HICO) on the International Space Station may
43 serve for this purpose. HICO has 128 bands covering a spectral range of 353 – 1080 nm. From its entire mission of
44 2010 – 2014, a total of > 10,000 scenes have been collected at a spatial resolution of about 90 m, each containing
45 about 512×2000 pixels. On average, only 6 scenes were collected per day around the globe, mostly over land and
46 coastal waters. Because of its stable calibration (Ibrahim et al., 2018) and relatively high signal-to-noise ratios (Hu et
47 al., 2012), deriving hyperspectral surface reflectance of water targets should be feasible. Indeed, after vicarious
48 calibration and atmospheric correction, hyperspectral reflectance data over water have been generated (Ibrahim et al.,
49 2018) and made available through the NASA OB.DAAC (<https://oceancolor.gsfc.nasa.gov>). However, these data
50 products are not applicable to image pixels containing floating matters due to their interference with the atmospheric
51 correction scheme.

52 The primary objective of this paper is to derive HICO-based hyperspectral reflectance of various floating matters.
53 This requires customized atmospheric correction and pixel unmixing to account for the small proportion of floating
54 matters within an image pixel. From such derived spectra, a secondary objective is to analyze whether they can be
55 differentiated spectrally. Similar to the compiled hyperspectral dataset for inherent and apparent optical properties to
56 support future hyperspectral missions such as NASA's Plankton, Aerosol, Cloud, and ocean Ecosystem (PACE)
57 mission (Casey et al., 2020), such a dataset for floating matters is expected to help develop or improve algorithms for
58 the PACE mission as well as for the hyperspectral Surface Biology and Geology mission currently being planned by
59 NASA (Cawse-Nicholson et al., 2021).

60 **2. Data and Methods**

61 HICO Level-1B (calibrated radiance) data were obtained from the NASA Goddard Space Flight Center
62 (<https://oceancolor.gsfc.nasa.gov>). Of the total collected >10,000 scenes, 9,411 were available through this data portal.
63 They were all downloaded, and the following 4 steps were used to derive spectral reflectance of various floating
64 matters.

65 Step 1 is to generate quick look Red-Green-Blue (RGB) and False-color RGB (FRGB) images with Rayleigh corrected
66 reflectance (R_{rc} , dimensionless) in three HICO bands using the same methods as in Qi et al. (2020) and in the NOAA
67 OCview online tool (Mikelsons and Wang, 2018). In the FRGB images, a near-infrared (NIR) band is used to represent

68 the green channel, thus making floating matters often appear greenish due to their elevated NIR reflectance. Here, R_{rc}
 69 was generated using the NASA software SeaDAS (version 7.5). Mathematically, it is derived as

$$\begin{aligned}
 70 \quad R_{rc} &= (R_t - R_r) / (t \ t_o \ t_{O_2} \ t_{H_2O}), \\
 71 \quad R_t &= \pi \ L_t^* / F_o \ \cos(\theta_o), \\
 72 \quad R_r &= \pi \ L_r / F_o \ \cos(\theta_o), \tag{1}
 \end{aligned}$$

73 where L_t^* is the at-sensor total radiance after vicarious calibration and adjustment of two-way gaseous absorption (e.g.,
 74 Ozone), L_r is at-sensor radiance due to Rayleigh scattering, F_o is the extraterrestrial solar irradiance, θ_o is the solar
 75 zenith angle, t is the diffuse transmittance from the image pixel to the satellite, t_o is the diffuse transmittance from the
 76 sun to the image pixel, t_{O_2} and t_{H_2O} are the two-way transmittance due to absorption by atmospheric O_2 and H_2O ,
 77 respectively. For simplicity, the wavelength dependency is omitted here.

78 Step 2 is to determine image slicks through visual inspection of both RGB and FRGB images. Fig. 1a shows an FRGB
 79 image captured in the central western Atlantic, where an elongated greenish slick is identified.

80 Step 3 is to derive surface reflectance (R , dimensionless) of the slick pixels (i.e., those containing floating matters)
 81 and nearby water pixels. While the latter is straightforward because R at each pixel is a standard output of the SeaDAS
 82 software, the former is problematic because standard atmospheric correction in SeaDAS fails over floating matters
 83 due to their elevated NIR reflectance. Such elevated NIR reflectance violates the atmospheric correction assumptions
 84 (i.e., negligible reflectance in the NIR, or fixed relationships between the red and NIR wavelengths) for slick pixels.
 85 Therefore, a nearest-neighbor atmospheric correction (Hu et al., 2000) was used to estimate R of the slick pixels.
 86 Specifically, from the SeaDAS output of R_{rs} , we have

$$87 \quad R = \pi \ R_{rs} = (R_t - R_r - R_a) / (t \ t_o \ t_{O_2} \ t_{H_2O}), \tag{2}$$

88 where R_{rs} is the surface remote sensing reflectance (sr^{-1}), R_a is the at-sensor aerosol reflectance (and reflectance due
 89 to aerosol-molecule interactions as well as due to sun glint and whitecaps). The difference between R and R_{rc} in Eqs.
 90 (2) and (1), respectively, is the removal of R_a in (2). Estimation of R_a at each pixel represents the “core” of any
 91 atmospheric correction scheme. The SeaDAS estimation of R_a is valid over water pixels, but not valid over the slick
 92 pixels. Therefore, R_a over water pixels was used as a surrogate to represent R_a over the nearby slick pixels, from which
 93 R over slick pixels was derived. This is why such an approach is called “nearest-neighbor” atmospheric correction
 94 (Hu et al., 2000). In this context, the slick pixel is called “target”, and the nearby water pixel is called “reference”.
 95 Their surface reflectance are called R^T and R^R , respectively. Fig. 1b shows examples of R^T and R^R .

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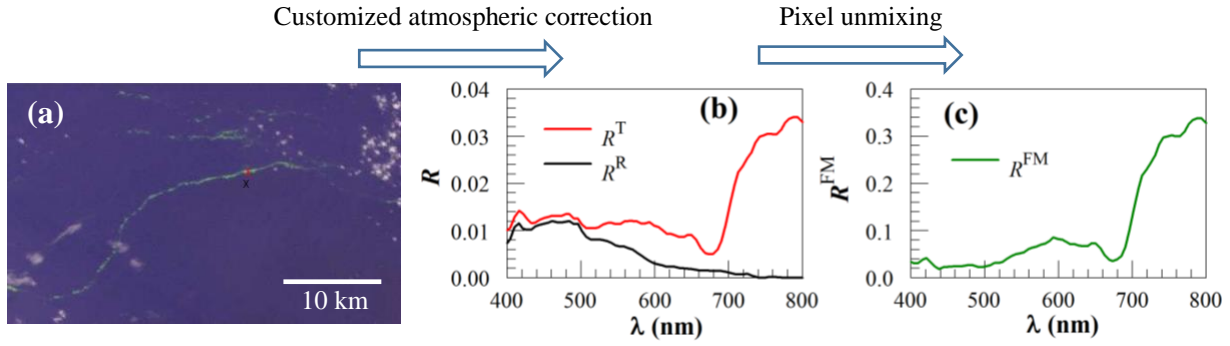


Figure 1. Demonstration of how surface reflectance of floating matter (R^{FM}) is derived. (a) FRGB image on 1 July 2012 showing several greenish image slicks in the Amazon River plume. The image covers a region of about $40 \text{ km} \times 24 \text{ km}$, with the “Target” (6.65914°N , 51.2395°W) and “Reference” (6.64847°N , 51.2411°W) pixels marked with a red “x” and a black “x”, respectively. (b) Their corresponding R^{T} and R^{R} , with the latter derived from SeaDAS and the former derived from a nearest-neighbor atmospheric correction. (c) R^{FM} derived from R^{T} and R^{R} using Eq. (4), with χ being estimated to be 10%.

The final step, Step 4, is to perform spectral unmixing of R^{T} . This is because floating matters often cover only a small portion a pixel (Hu, 2021a). In this step, the derived R^{T} from Step 3 is assumed to be a linear mixture of two endmembers: floating matter (R^{FM}) and water (R^{W}):

$$R^{\text{T}} = \chi R^{\text{FM}} + (1 - \chi) R^{\text{W}} = \chi R^{\text{FM}} + (1 - \chi) R^{\text{R}} \quad (3)$$

Here, χ is the subpixel portion of floating matter which can vary between 0.0% and 100%, R^{W} is assumed to be R^{R} . Then, the final product, R^{FM} , is derived as

$$R^{\text{FM}} = R^{\text{R}} + (R^{\text{T}} - R^{\text{R}}) / \chi \quad (4)$$

In the right-hand side of Eq. (4), the only unknown is χ . In practice, assuming R^{FM} at $750 \text{ nm} \approx 0.3$ as revealed by independent measurements of floating macroalgae (Hu, L. et al., 2017; Wang et al., 2018), χ is estimated through linear unmixing as

$$\chi = [R^{\text{T}}(754) - R^{\text{R}}(754)] / [0.3 - R^{\text{R}}(754)] \quad (5)$$

Here, with $R^{\text{T}}(754)$ varying between $R^{\text{R}}(754)$ and 0.3, χ ranges between 0.0% and 100%. Plugging this mixing ratio into Eq. (4) will derive R^{FM} . Fig. 1c shows the example of how R^{FM} is derived from R^{T} and R^{R} of Fig. 1b once they are known from Step 3, with χ being estimated to be 10%.

Once R^{FM} is derived, a spectral angle mapper index (SAM, Kruse et al., 1993) was used to determine whether different floating matters were spectrally different. SAM was used because it is based on spectral shape only. SAM is the angle between two spectral vectors, defined as (Kruse et al., 1993):

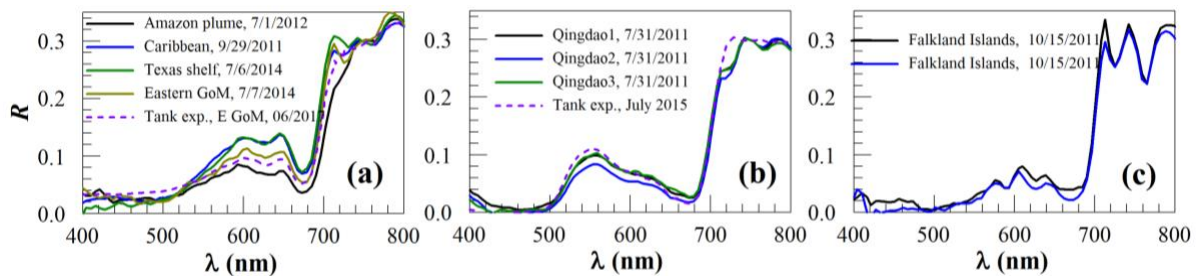
$$\text{SAM (degrees)} = \cos^{-1}[(\sum x_i y_i) / (\sqrt{\sum x_i^2} \sqrt{\sum y_i^2})]. \quad (6)$$

132 Here, x and y represent two spectral vectors with the i^{th} band from 1 to N . An SAM of 0° indicates identical spectral
 133 shapes between x and y regardless of their difference in magnitudes, while an SAM of 90° indicates completely
 134 different spectral shapes. An SAM of $< 5^\circ$ indicates that the two spectra are very similar (Garaba and Dierssen, 2018).

135 3. Results: HICO reflectance spectra of floating matters

136 The approach above was applied to the visually identified image slicks to derive $R^{FM}(\lambda)$. These include: 1) *Sargassum*
 137 *fluitans/natans* in the Atlantic (including the Caribbean Sea and Gulf of Mexico), 2) *Ulva prolifera* in the western
 138 Yellow Sea (near Qingdao, China), 3) *Kelp* in South Atlantic, 4) *Trichodesmium* around Australia, in the Gulf of
 139 Mexico and Persian Gulf, in the South Atlantic Bight, Bay of Bengal, near Hawaii and Pagan Island (middle Pacific),
 140 5) Cyanobacteria of *Microcystis* in Taihu Lake, Lake Woods, and Lake of Victoria, 6) Red *Noctiluca scintillas* (RNS)
 141 in the East China Sea, and coastal waters off Japan, 7) Brine shrimp cysts in the Great Salt Lake, 8) Oil slicks in the
 142 Gulf of Mexico, 9) Whitecaps (foam) in the Arabian Sea, Caspian Sea, and Bohai Sea, 10) Ice in Lake Baykal, 11)
 143 some unknown algae features. For convenience, they are grouped into 4 figures: Fig. 2 for macroalgae (*Sargassum*,
 144 *Ulva*, and kelp), Fig. 3 for microalgae (*Trichodesmium*, *Microcystis*, red *Noctiluca scintillas* or RNS), Fig. 4 for organic
 145 particles and ocean/lake bubbles, and Fig. 5 for unknown algae scums.

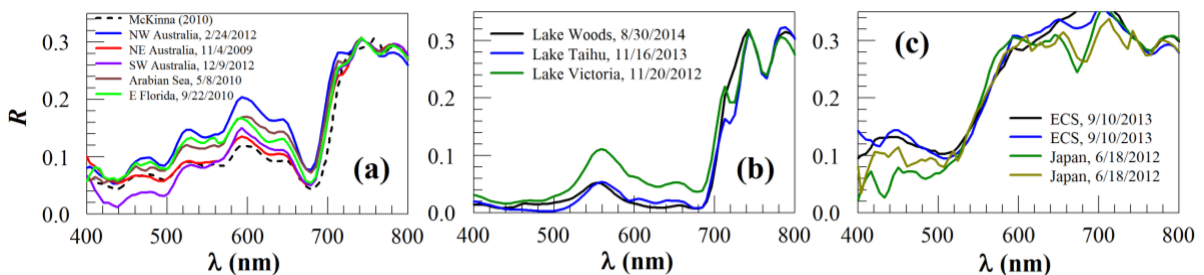
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147 **Figure 2: Surface reflectance (R , dimensionless) of macroalgae: (a) pelagic *Sargassum fluitans/natans*, (b) *Ulva prolifera*, (c)**
 148 **kelp. The dashed lines in (a) and (b) denote R from water tank experiments of Wang et al. (2018) and Hu, L. et al. (2017),**
 149 **respectively.**

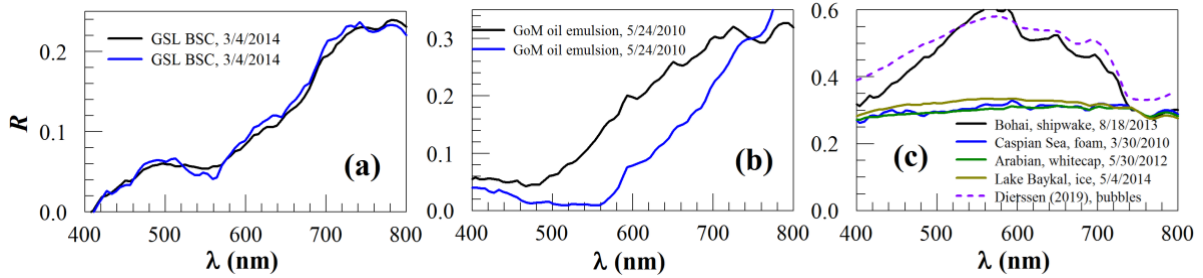
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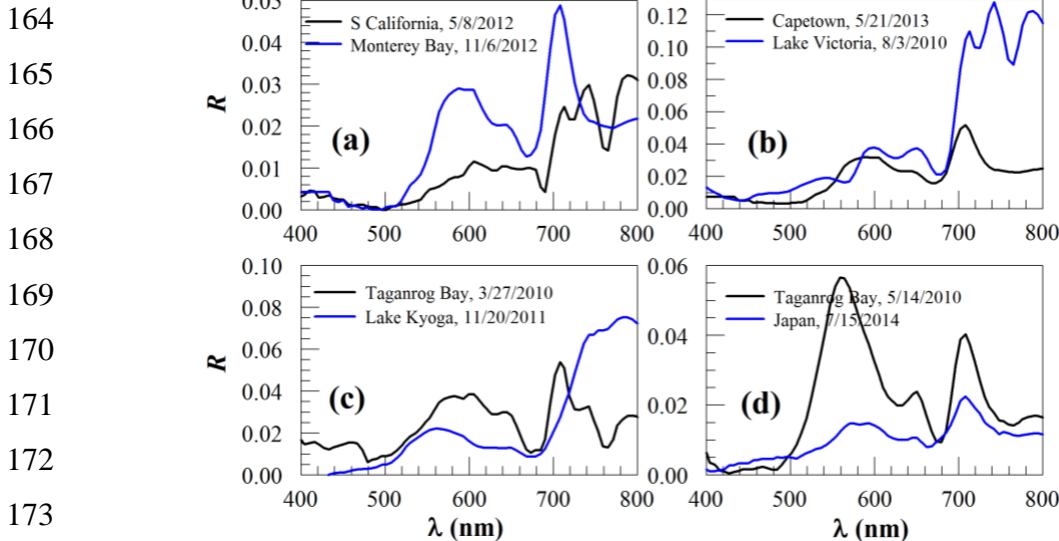
152 **Figure 3. Surface reflectance (R , dimensionless) of floating scums of microalgae: (a) *Trichodesmium*, (b) *Microcystis*, (c)**
 153 **red *Noctiluca* near Yangtze River of the East China Sea and in Sagami Bay of Japan. The dashed line in (a) denote field**
 154 **measured R by McKinna (2010).**
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159 **Figure 4: Surface reflectance (R , dimensionless) of various floating materials: (a) Brine shrimp cysts in the Great Salt**
160 **Lake (GSL), (b) emulsified oil from the Deepwater Horizon oil spill, and (c) shipwake, seafoam, whitecap and ice. The**
161 **dashed line in (c) denotes submersed bubbles measured by Dierssen (2019), which is similar to the shipwake spectrum.**
162 **Note the similarity among other spectra.**

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175 **Figure 5: Surface reflectance (R , dimensionless) of known and unknown algae scums. (a) Blooms off southern California**
176 **and in Monterey Bay that are thought to be *Lingulodinium polyedrum* (Cetinic, 2009) and *Akashiwo sanguinea* (Jessup et**
177 **al., 2009), respectively. (b) Blooms of unknown types of algae off Cape Town (South Africa) and in Lake Victoria, both**
178 **likely to be dinoflagellates. Note the different spectra shape of the Lake Victoria bloom as compared with the cyanobacterial**
179 **bloom in the same lake (Fig. 3b). (c) Blooms of unknown types of algae in Taganrog Bay and Lake Kyoga. (d). Blooms of**
180 **unknown types of algae in Taganrog Bay (note the difference from Fig. 5c) and in Japan coastal waters.**

181 Of all spectra presented in Figs. 2 – 4, one common feature for all floating macroalgae and microalgae (except red
182 *Noctiluca*) is the red-edge reflectance (i.e., the sharp increase from about 670 nm to the NIR wavelengths). Such a
183 common feature is due to both chlorophyll-*a* absorption around 670 nm and high reflectance in the red and NIR
184 wavelengths due to macroalgae mats or microalgae scums (Kazemipour et al., 2011; Launeau et al., 2018). The lack
185 of such a red-edge feature in some of the red *Noctiluca* reflectance spectra (Fig. 3c) is possibly due to the lack of
186 chlorophyll-*a* pigment because red *Noctiluca* is heterotrophic (i.e., it does not contain pigments unless it feeds on other
187 algae). Other than the common red-edge reflectance, the contrasting spectral shapes of the various types of floating
188 macroalgae and microalgae are due to their different pigment compositions (see below). In contrast, the non-leaving
189 floating matters do not show red-edge reflectance or other pigment-induced spectral features in the visible wavelengths
190 (Fig. 4). In Fig. 5, in addition to pigment absorption, high scattering due to high concentrations of algae particles
191 together with sharp increases of water absorption from the red to the NIR wavelengths lead to the local reflectance
192 peak around 700 nm (Fig. 5) and, depending on the particle concentrations, the peak wavelength may be slightly
193 shifted, for example from 700 to 710 nm.

194 4. Discussion

195 4.1. Uncertainties in the derived R^{FM}

196 There are several assumptions used in the nearest-neighbor atmospheric correction and spectral unmixing (Eq. 4).
197 Violations of these assumptions will cause errors in the derived R^{FM} spectra. For example, if the atmosphere over the
198 floating matter pixel is different from over the nearby water, the nearest-neighbor atmospheric correction may not be
199 applicable. In practice, however, because the target and reference pixels are very close (< 1 km), such a violation is
200 unlikely. In Step 4, the water within the FM-containing pixel is assumed to be the same as the nearby water. Because
201 of the close proximity of the two pixels, this assumption should be valid for most cases unless the FM-containing pixel
202 is at an ocean front where different water masses converge. The departure of $R^{FM(754)}$ from the assumed 0.3 will also
203 lead to errors in the estimated χ (and therefore R^{FM}). However, as long as R^W (i.e., R^R) in Eqs. (4) & (5) is $\ll R^{FM}$, the
204 shape of R^{FM} is still retained, although the magnitude departs from the “truth” in proportional to the departure of
205 $R^{FM(754)}$ from 0.3. Indeed, the condition of $R^W \ll R^{FM}$ can be satisfied for $\lambda > 600$ nm for most floating matters unless
206 the water is extremely turbid. Even for turbid waters, for certain floating matters where R^{FM} is elevated at $\lambda > 530$ nm
207 (e.g., red *Noctiluca*, brine shrimp cysts, ice), the shape of the derived R^{FM} should still be valid for $\lambda > 530$ nm. Indeed,
208 when R^W is $\ll R^{FM}$, even a simple subtraction of R_{tc} or TOA radiance between the target pixel and reference pixel, as
209 demonstrated in Gower et al. (2006), may retain the spectral shapes of floating matters.

210 Another uncertainty source can come from the assumption of linear mixing between floating matters and water (Eq.
211 (3)). For macroalgae, the linear mixing up to the reflectance saturation level has been shown in laboratory experiments
212 (Hu. L et al., 2017; Wang et al., 2018). As long as the macroalgae stay on the very surface of water (as opposed to be
213 submerged under the surface), this assumption should be valid not just for macroalgae but for all floating matters. For
214 the same reason, if certain portions of kelp are submerged in water, large uncertainties may result from the linear

215 unmixing scheme. Under high-wind conditions, the strong mixing may result in submerged algae (especially for
216 microalgae), thus violating the linear mixing rule. However, the cases presented in Figs. 2 - 5 were selected very
217 carefully to avoid high wind speed ($> 5 \text{ m s}^{-1}$, where wind speed was obtained from the National Centers for
218 Environmental Prediction). Therefore, such mixing induced uncertainties are unlikely.

219 Additional uncertainties may come from the HICO radiometric calibration, which affects R_t and all derivative products.
220 Through the use of the Marine Optical Buoy (MOBY) and other clear-water sites, HICO has been calibrated
221 vicariously (Ibrahim et al., 2018), which resulted in significant improvements in the retrieved R_{rs} over water as
222 compared with data without vicarious calibration. However, after the vicarious calibration, while the spectral shape
223 of R_{rc} over water appears correct, the shape of ΔR_{rc} over land appears to be biased low at $\lambda > 800 \text{ nm}$. Without vicarious
224 calibration, the opposite is observed. This is possibly due to the non-linear effects in the detector response to incoming
225 light, and currently there appears no reliable way to address this issue (A. Ibrahim, personal comm.). Similarly,
226 calibration for $\lambda < 450 \text{ nm}$ may be subject to larger errors than for λ between 450 and 800 nm. Therefore, R^{FM} in the
227 range of 800 – 900 nm is omitted here, and interpretation of 400 – 450 also requires more caution. Similarly, the
228 spectral wiggling between 700 and 800 nm (e.g., Fig. 3b) appears to come from residual errors in correcting water
229 vapor absorption and oxygen absorption in the atmosphere. Therefore, although the spectral wiggling does not affect
230 the overall shape of the red-edge reflectance, it may not be used for algorithm development to discriminate floating
231 matter types.

232 Indeed, with all these possible sources of uncertainties, such HICO-derived R^{FM} can still be used for spectral
233 discrimination of different floating matters without ambiguity, as shown below.

234 4.2. Implications for spectral discrimination

235 Spectral discrimination can be performed through either visual inspection or the use of certain type of similarity index
236 (e.g., SAM, Eq. 6). Here, results of the SAM analysis are presented in Table 1, followed by descriptions of visual
237 inspection to interpret the spectral similarity or difference. Because nearly all floating algae show typical red edge
238 reflectance, discrimination of different algae type is focused on wavelengths $< 670 \text{ nm}$. To discriminate floating algae
239 from non-living floating matters (e.g., marine debris), on the other hand, the inclusion of 670 nm is critical.
240 Furthermore, because HICO data are noisy for wavelengths $< 450 \text{ nm}$, the SAM calculation was restricted to 450 –
241 670 nm from most R^{FM} spectra of Figs. 2 – 4.

242 Table 1 shows the SAM results for three types of macroalgae (*Sargassum*, *Ulva*, kelp), three types of microalgae
243 (*Trichodesmium*, *Microcystis*, red *Nocticula scintillas* or *RNS*), and one type of organic matter (brine shrimp cysts or
244 *BSC*). **Here, unless noted, *Sargassum* refers to *Sargassum fluitans/natans* (dominant pelagic type in the Atlantic
245 ocean) and *Ulva* refers to *Ulva prolifera* (dominant pelagic type in the Yellow Sea).** For the same floating matter,
246 if field-based R^{FM} is available, then it is used as the reference, otherwise the mean HICO-derived R^{FM} is used as the
247 reference. For SAM between different floating matters, all HICO-derived R^{FM} from both types are used (e.g., 4
248 *Sargassum* R^{FM} of Fig. 2a and 3 *Ulva* R^{FM} of Fig. 2b are used to calculate 12 SAM values), with their mean and
249 standard deviations listed in Table 1.

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251 Table 1. Spectral Angle Mapper values (degrees) between different floating matters for the spectral range of 450 – 670 nm,
252 derived from the HICO-derived and field-measured spectra shown in Figs. 2-4. An SAM of 0° indicates identical spectral
253 shape, while an SAM of 90° indicates completely different spectral shape. *Sarg*: *Sargassum fluitans/natans*; *Ulva*: *Ulva*
254 *prolifera*; *Tricho*: *Trichodesmium*; *Micro*: *Microcystis*; *RNS*: red *Noctiluca scintillas*; *BSC*: brine shrimp cysts. Because all
255 floating algae show similar red-edge reflectance with a reflectance trough around 670 nm, the exclusion of wavelengths of >
256 670 nm is to reduce the similarity among different types of floating algae.

<i>Sarg</i>	4.5±1.6						
<i>Ulva</i>	27.2±2.5	2.9±0.5					
<i>Kelp</i>	13.7±1.8	32.5±1.3	2.7±0.4				
<i>Tricho</i>	15.4±4.6	25.1±2.0	23.1±3.2	2.8±2.0			
<i>Micro</i>	32.9±7.5	16.8±5.6	39.0±7.7	28.8±5.1	4.6±2.5		
<i>RNS</i>	9.9±2.4	31.4±2.8	16.7±3.0	17.2±2.1	34.7±6.7	1.8±0.7	
<i>BSC</i>	20.7±0.9	39.3±2.4	27.0±3.1	21.2±1.6	40.9±5.5	14.5±3.1	1.1±0.0
	<i>Sarg</i>	<i>Ulva</i>	<i>Kelp</i>	<i>Tricho</i>	<i>Micro</i>	<i>RNS</i>	<i>BSC</i>

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258 For each type of floating matter, HICO-derived R^{FM} is very similar to either field-measured R^{FM} or to their mean R^{FM} ,
259 with SAM < 4.6°. In contrast, SAM between different floating matters is always > 9.9°. These results suggest that, if
260 these floating matters represent all that can be found in natural waters, they can be differentiated through spectroscopy
261 analysis without any other ancillary information (e.g., knowledge of local oceanography or dominant floating algae
262 type). This is despite the possible uncertainties in their reflectance magnitude, as discussed above. In the natural
263 environments, however, there may be other types of floating algae whose spectral shapes may be similar to *Sargassum*
264 *fluitans/natans* (e.g., *Sargassum honeria* in the East China Sea or other brown algae) or *Ulva prolifera* (e.g., other
265 green algae). Therefore, some form of ancillary information in addition to spectroscopy is still required in order to
266 differentiate floating algae type.

267 The results from the SAM table can also be explained through visual inspection and interpretation of the spectral
268 shapes, as discussed below.

269 From Fig. 2, it is clear that although the three types of macroalgae all share the same red-edge reflectance in the NIR,
270 they have different spectral shapes in the visible wavelengths. Unlike the *Ulva* reflectance with a local peak around
271 560 nm, the spectral shapes of *Sargassum* reflectance resemble those of typical brown algae where the local reflectance
272 trough around 625 nm is induced by chlorophyll-*c* absorption and the low reflectance below ~520 nm is due to
273 carotenoid pigment absorption. These characteristics make it easy to distinguish *Sargassum* from *Ulva* (SAM > 27°,
274 Table 1). On the other hand, it appears more difficult to spectrally discriminate *Sargassum* from kelp because they

275 both have reference peaks around 600 – 645 nm, and because they also share a common reflectance trough around
276 625 nm. However, considering *Sargassum* is moving in the ocean while kelp is fixed in location, they can be separated
277 using sequential images. Even from a single image, when most visible wavelengths are used, *Sargassum* and kelp can
278 still be spectrally discriminated ($SAM > 13^\circ$, Table 1). Within the group of *Sargassum* spectra (Fig. 2a), there is some
279 variability in the magnitude between 560 – 700 nm. It is unclear what caused such variability, although it could be
280 due to changes in carbon to chlorophyll ratio in *Sargassum* of different environment, as observed from kelp (Bell et
281 al., 2015). Such a variability, however, would not impact the spectral discrimination of *Sargassum* against other
282 floating matters, as SAM between *Sargassum* spectra is $< 5^\circ$, much lower than between *Sargassum* and any other
283 floating matters (Table 1).

284 Similar to the macroalgae, the microalgae scums also show elevated NIR reflectance (Fig. 3), and their spectral shapes
285 in the visible make them straightforward to distinguish from each other ($SAM > 17^\circ$), and also straightforward to
286 distinguish from macroalgae ($SAM > 9.9^\circ$). One exception may be the cyanobacterial scums (blue-green algae blooms)
287 (Fig. 3b) as they show reflectance peak around 550 nm, similar to *Ulva* (Fig. 2b). However, reflectance around 550
288 nm is nearly symmetric for cyanobacterial scums, but asymmetric for *Ulva*. There is also a local reflectance trough
289 around 625 nm for cyanobacterial scums due to absorption of phycocyanin, but such a trough is lacking in the *Ulva*
290 spectra. Such characteristic makes it possible to differentiate between the two even without *a priori* knowledge of the
291 ocean or lake environment, as the SAM between the two groups is $\sim 16.8^\circ$ (Table 1). What's interesting is that within
292 each class, either *Trichodesmium* or *Microcystis*, although the spectral shape is nearly identical from different spectra
293 ($SAM < 5^\circ$), there is substantial variability in the magnitude in the visible wavelengths, which might be due to changes
294 in their carbon to chlorophyll ratios (Behrenfeld et al., 2005). Furthermore, the spectral wiggling features between 450
295 and 660 nm in Fig. 3a are due to *Trichodesmium*-specific pigments such as phycourobilin, phycoerythrobilin, and
296 phycocyanin that absorb light strongly at 495, 550, and 625 nm, respectively (Navarro Rodriguez, 1999). These
297 features are unique to *Trichodesmium* scums, which make it straightforward to develop classification algorithms once
298 certain spectral bands are available to capture these features (e.g., Hu et al., 2010).

299 Of all microalgae scums of Fig. 3, the spectral shapes of red *Noctiluca* (Fig. 3c) appear different from all others, but
300 they show the same characteristics as reported from the limited field measurements (Van Mol et al., 2007): a sharp,
301 featureless increase from ~ 520 nm to ~ 600 nm. This unique spectral shape makes *RNS* different from all other floating
302 matters ($SAM > 9.9^\circ$, Table 1). The difference within this group is that the spectra from Sagami Bay off Japan show
303 reflectance troughs around 670 nm. Because red *Noctiluca* is known to feed on other algae, it is speculated that the
304 670-nm trough is due to chlorophyll pigments of the consumed algae. Once more hyperspectral data are available in
305 the future to test this hypothesis using field data, this characteristic may be used to study how red *Noctiluca* interacts
306 with other algae. On the other hand, once more hyperspectral data are available in the future, it is also possible to test
307 whether other algae (e.g., *Mesodinium rubrum*, Dierssen et al., 2015), once forming surface scums, have similar
308 spectral shapes as those of red *Noctiluca*.

309 The non-algae floating matters in Fig. 4 show spectral characteristics different from both macroalgae and microalgae,
310 for example they lack the typical red-edge reflectance of vegetation, and lack of typical spectral variations in the

311 visible wavelengths due to pigment absorption. Within this group, the organic matters of BSC (Fig. 4a) and emulsified
312 oil (Fig. 4b) show some degrees of similarity as they also have monotonic reflectance increases from a wavelength
313 between 500 – 560 nm to at least 740 nm. The difference between them is that BSC reflectance starts to increase
314 always at ~560 nm with an inflection wavelength ~640 nm, while reflectance of oil emulsions start to increase at
315 variable wavelengths without any inflection between 560 – 740 nm. Indeed, the inflection at ~640 nm appears to be a
316 common feature between BSC slicks and coral spawn slicks (Yamano et al., 2020). In contrast, depending on the oil
317 emulsion state, oil emulsion may have different spectral characteristics (Lu et al., 2019), suggesting that there is no
318 fixed “endmember” spectra for oil spills.

319 The inorganic “particles” (i.e., water bubbles, ice) also have distinctive spectral shapes. The examples in Fig. 4c
320 indicate that submersed bubbles from shipwakes are similar in spectral shapes, but all others are nearly identical in
321 their lack of any spectral features. Rather, foams, whitecaps, and ice all show flat reflectance spectral shapes between
322 400 – 800 nm that are consistent with *in situ* measurements of foams (Dierssen, 2019). The lack of spectral features
323 is similar to marine debris (Garaba and Dierssen, 2020). Such a similarity will make detection of marine debris very
324 difficult, especially around ocean fronts because these are where surface materials tend to aggregate and foams also
325 tend to form.

326 In addition to the spectra of Figs. 2-4 that can be well recognized, HICO also showed reflectance spectra that are
327 difficult to discriminate from spectroscopy alone, as shown in Fig. 5. Without a known reflectance library, one can
328 only speculate what algae type could be responsible for the algae scum spectra from some ancillary information in the
329 literature. For example, the often-reported blooms of *Lingulodinium polyedrum* and *Akashiwo sanguinea* in coastal
330 waters off southern California and in Monterey Bay, respectively, may show spectral shapes of Fig. 5a when they are
331 heavily concentrated in surface waters. Inference may also be made for other cases once similar ancillary information
332 is available. Even when such information is absent, one can still rule out some possibilities simply based on the spectral
333 shapes. For example, the reflectance spectrum in Fig. 5b from Lake Victoria cannot be from cyanobacteria that has
334 been often reported in this lake (Fig. 3b), but it is most likely from a dinoflagellate bloom, as blooms of other algae
335 types have also been reported in this lake (Haande et al., 2011). Likewise, the different spectra from the same Taganrog
336 Bay in Figs. 5c & 5d suggest different algae type. Clearly, although cyanobacterial blooms have been reported in
337 many lakes, without spectral diagnosis one cannot simply jump to the conclusion that a freshwater bloom is caused
338 by a certain type of cyanobacterium.

339 **4.3. Implications for current and future satellite missions**

340 Because HICO is a pathfinder sensor that collected only a limited number of scenes, not all reported floating matters
341 have been captured. For example, no HICO scene appears to have captured pumice rafts, *Sargassum horneri*, sea snots,
342 or marine debris. Therefore, the spectral reflectance dataset presented here is incomplete. The use of data from other
343 similar pathfinders, for example the DLR Earth Sensing Imaging Spectrometer (DESI) on the ISS (235 bands from
344 400 – 1000 nm, 30-m resolution, 2018 – present) and the PRecursores IperSpettrale della Missione Applicativa
345 (PRISMA, 237 bands from 400 – 2505 nm, 30-m resolution, 2019 – present), may complement the spectral data using

346 the same approach (e.g., sea snot reflectance spectra, Hu et al., 2022). Even at its present form, given the large variety
347 of floating matters presented here, the spectral data may lead to several implications for current and future satellite
348 missions.

349 First, although all current multi-band sensors can detect floating matters through their elevated NIR reflectance (Qi et
350 al., 2020), the Sentinel-3 Ocean and Land Colour Imager (OLCI) appears to be the best to differentiate spectral shapes
351 in the visible wavelengths because of its 21 spectral bands between 400 and 1,020 nm, especially because of its 620-
352 nm that can be used to differentiate whether an algae scum appears greenish or brownish, thus providing extra
353 information to discriminate algae type in the absence of hyperspectral data.

354 Second, for the same reason, although only 4 bands (blue, green, red, NIR) are available on the PlanetScope (DOVE)
355 constellation, the recent SuperDOVE constellation is equipped with 4 additional bands with one centered at 610 nm,
356 thus may significantly enhance the capacity of the current high-resolution sensors (~ 3-4 m or 30 m) in differentiating
357 greenish and brownish algae types.

358 Finally, the Ocean Color Instrument (OCI) on NASA's PACE mission, to be launched in 2023, will be the first of its
359 kind to map global oceans with hyperspectral capacity (5 nm resolution between 340 – 890 nm, plus 7 discrete bands
360 from 940 to 2260 nm) with a nominal resolution of 1 km. Unlike HICO, OCI will cover global oceans and lakes every
361 1-2 days, thus providing unprecedented opportunities to detect, differentiate, and quantify various types of floating
362 matters. The spectral reflectance data, derived from one sensor (HICO) with a stable calibration, may serve as a
363 consistent dataset to help select the optimal bands towards future applications once PACE data becomes available, for
364 example, through the use of SAM matrix as demonstrated in Table 1. Likewise, the SBG mission currently being
365 planned by NASA is expected to have hyperspectral capacity between 380 and 2500 nm with a nominal resolution of
366 30 m (Cawse-Nicholson et al., 2021); such a mission will provide unprecedented opportunity to map various floating
367 matters on a global scale where the hyperspectral dataset developed here can help develop algorithms before its launch.

368 **5. Conclusion**

369 Through customized atmospheric correction and spectral unmixing, hyperspectral reflectance in the visible and NIR
370 wavelengths of various floating matters have been derived from HICO measurements over global oceans and lakes.
371 The reflectance dataset shows distinguishable spectral shapes between floating algae (macroalgae and microalgae)
372 and non-algae floating matters (*Sargassum fluitans/natans*, *Ulva prolifera*, *kelp*, *Microcystis*, *Trichodesmium*, red
373 *Noctiluca scintillas*, brine shrimp cysts), and also distinguishable spectral shapes in the visible wavelengths between
374 different floating algae types. While the approach may be extended to other pathfinder missions to complement the
375 findings here, the spectral reflectance dataset is expected to help select optimal bands for future hyperspectral satellite
376 missions to differentiate and quantify the various floating matters in global oceans and lakes.

377 **Data Availability**

378 All HICO data used in this analysis are available at the NASA Ocean Biology Distributed Active Archive Center
379 (OB.DAAC, <https://oceancolor.gsfc.nasa.gov>). The data processing software (SeaDAS) can be obtained from the same
380 source, at <https://seadas.gsfc.nasa.gov>. The derived HICO spectra in digital data form, as shown in the above figures,
381 are available on-line from the Ecological Spectral Information System (EcoSIS) (<http://ecosis.org>, doi:
382 10.21232/74LvC3Kr) (Hu, 2021b).

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