

Atmospheric aerosol, gases and meteorological parameters measured during the LAPSE-RATE campaign by Finnish Meteorological Institute and Kansas State University

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Abstract. Small Unmanned Aerial Systems (sUAS) are becoming very popular as affordable and reliable observation platforms. The Lower Atmospheric Process Studies at Elevation - a Remotely-piloted Aircraft Team Experiment (LAPSE-RATE), conducted in the San Luis Valley (SLV) of Colorado (USA) between July 14th - 20th, 2018, gathered together numerous sUAS, remote sensing equipment and ground based instrumentation. Flight teams from the Finnish Meteorological Institute (FMI) and the Kansas State University (KSU) co-operated during LAPSE-RATE to measure and investigate the properties of aerosol particles and gases at the surface and in the lower atmosphere. During LAPSE-RATE the deployed instrumentation operated reliably, resulting in [an observational dataset described below in detail. a scientifically sound](#). Our observations included aerosol particle number concentrations and size distributions, concentrations of CO₂ and water vapor, and meteorological parameters.

All data sets have been uploaded to the Zenodo LAPSE-RATE community archive (<https://zenodo.org/communities/lapse-rate/>). The dataset DOIs for FMI airborne measurements and surface measurements are available here: <https://doi.org/10.5281/zenodo.3993996>, Brus et al. (2020a), and for KSU airborne measurements and surface measurements are available here: <https://doi.org/10.5281/zenodo.3736772>, Brus et al. (2020b).

1 Introduction

The concentration of aerosol particles released from primary sources or formed by gas-liquid conversion and various trace gases characterize the air quality worldwide. At the same time, planetary boundary layer (PBL) mixing height and lower atmospheric wind speed and direction are influenced by a variety of factors (e.g. solar and surface stored energy and terrain inhomogeneity, Carbone et al. (2010)). Removal of aerosol particles and gases from the atmosphere depends mostly on dispersion rates, transport, [wet](#) deposition and other atmospheric dynamical properties (Tunved et al., 2013). To understand the formation and removal of particles and gases, it is therefore necessary to measure their properties and the atmospheric conditions supporting

20 those properties throughout the vertical profile. In-situ observation of PBL properties are obtained through various techniques, including balloon soundings, tether sondes, dropsondes and hot-air balloons (e.g. Laakso et al., 2007; Greenberg et al., 2009; Nygård et al., 2017), towers (e.g. Heintzenberg et al., 2011; Andreae et al., 2015), and recently, by Unmanned Aerial Systems (UASs) (e.g. Ramanathan et al., 2007; Jonassen et al., 2015; Kral et al., 2018; Nolan et al., 2018; Barbieri et al., 2019; de Boer et al., 2020a) ([Girdwood et al., 2020](#); [Harrison et al., 2021](#); [Jensen et al., 2021](#); [Pinto et al., 2021](#); [Wenta et al., 2021](#))

25 Land-air interactions, including influences of continental, inhomogeneous terrain on lower atmospheric thermodynamic and kinematic states and the vertical distribution of aerosol and gas properties, were investigated during LAPSE-RATE field campaign. LAPSE-RATE took place in the greater SLV, Colorado between July 14th-20th, 2018. The campaign was organized in conjunction with the 6th Conference of the International Society for Atmospheric Research using Remotely-piloted Aircraft (ISARRA, de Boer et al., 2020a). Daily operational plans were developed and executed to observe several atmospheric phenomena, including boundary layer evolution during morning hours, the diurnal cycle of valley flows, convective initiation, and the properties of gases and aerosol particles (de Boer et al., 2020b). LAPSE-RATE flights were conducted under both Federal Aviation Administration (FAA) Certificates of Authorization (COAs) and FAA Part 107, with the COAs allowing maximum flight altitudes of 914 m above the ground level (AGL). In addition to the airborne assets, a variety of ground-based observational assets were deployed (see de Boer et al., 2020b, 2021; Bell et al., 2021, for details). The FMI-KSU flight team consisted of two operators from the [Finnish Meteorological Institute](#) FMI and one operator from the [Kansas State University](#) KSU. The main objective of FMI-KSU team during targeted the LAPSE-RATE was to provide the physical characterization of scientific theme of aerosol properties in vertical column during most flight days, except on July 19th when the team joined the common effort to focus on cold-air drainage flows that set up during the night-time.

35 In general, there was very little known about the background aerosol concentrations within the SLV from the literature. The aerosol and generally any air quality measurements are very sparse in Colorado and are mostly concentrated around larger cities. However, a variety of primary and secondary aerosol particle sources in the SLV, including agriculture, the Great Sand Dunes National Park, wildfires, biogenic emissions, and large-scale advection of particles from the deserts and mountainous regions of the Western United States, made this an interesting location to characterize aerosol properties and their variability. Coupled with the substantial summer diurnal cycles in atmospheric temperature, humidity, turbulence and thermodynamic mixing, as well as the frequent occurrence of thunderstorms in the mountains surrounding the SLV, aerosol properties were found to vary over the course of the week, as documented in Brus et al. (2021). Routine lower-atmospheric profiling allowed our team to document particle sizes and concentrations, including the occurrence of new particle formation (NPF) events, and the connection of these phenomena to boundary layer and synoptic wind regimes.

2 Description of Platforms, Modules and Sensors~~Instrument and Platform Description~~

50 The FMI team deployed two rotorcraft (FMI-PRKL1 and FMI-PRKL2) during LAPSE-RATE. Both rotorcraft were are custom-built around the Tarot X6 hexacopter frame, which was is 960 mm in diameter (rotor-to-rotor). The maximum endurance of these rotorcraft was about 15 min using 22.2V, 16000 mAh rechargeable lithium polymer (LiPo) batteries. The maximum

take-off weight for these rotorcraft was 11 kg. Flights were carried out using a 3DR Pixhawk PX4 flight controller with the Ardupilot software, in a manual (stabilized) mode for FMI-PRK1 and loiter (GPS position fix) mode for FMI-PRKL2. The same propulsion system, consisting of 340 kV brushless motors, 40A Electronic Speed Controllers and 18 inch (5.5 inch pitch) carbon fiber propellers, was used for both rotorcraft. The rotorcraft's setup allowed for lifting approximately 2 kg of active payload (i.e. scientific instrumentation). [The overview of FMI-KSU team instrumentation and their operational characteristics are summarized in Table 1.](#)

The first rotorcraft (FMI-PRKL1) was equipped with a particle measurement module consisting of two condensational particle counters (CPC, model 3007, TSI Corp.), a factory-calibrated optical particle counter (OPC, model N2, Alphasense) and a meteorological Arduino breakout (Bosch BME280, P, T and RH). Each CPC [sampled at frequency of 1Hz and](#) was adjusted at FMI to a different cut-off diameter, 7 and 14 nm, respectively. Such a configuration allows for the observation of freshly nucleated particles in a diameter range of 7 to 14 nm (see e.g. Altstädter et al., 2015, 2018) . The voltage applied to a thermal electric device (TED) of the CPC corresponds directly to the temperature difference between the saturator and condenser and determines how fast particles grow to CPC detectable sizes. The TED values of 2000 and 1000 mV were used for CPC1 and CPC2, respectively, during the campaign. [Each of the CPCs used a 30 cm inlet made of conductive tubing, led from the sides upwards to the top centre of the rotorcraft, where both lines were merged to an additional 10 cm piece of conductive inlet tubing, also facing upwards and ending about 10cm above propeller's plane. Penetration for such an inlet was estimated to be between 90% and 99% for particles with a diameter between 7 and 100 nm and 99 % for particles with a diameter between 100 nm and 1µm. The OPC-N2 was sampling with 0.5 Hz in 16 size bins with mid-bin diameters of 0.46, 0.66, 0.92, 1.19,1.47, 1.83, 2.54, 3.5, 4.5, 5.75, 7.25, 9, 11, 13, 15 and 16.75 µm. The particle module was covered from all sides except the bottom with a polylactide \(PLA\) foam cover \(2.5 cm thick\) to ~~shade the sensors from direct sunprotect the sensors from solar radiation~~ and keep the particle module thermally stable. The BME280 sensor \[sampled with 1 Hz\]\(#\), it was located below the particle module and was shielded from solar radiation, but not forcefully aspirated.](#)

The second rotorcraft (FMI-PRKL2) was equipped with a gas module, consisting of a flow-through CO₂ concentration sensor (Carbocap model GMP343, Vaisala Inc.), a CO₂ and water vapor analyzer (model Li-840A, Li-Cor Environmental) and a sensor for measuring concentrations of CO, NO₂, SO₂, and O₃ (model AQT400, Vaisala Inc.). A meteorological Arduino breakout (Bosch BME280) was used to measure P, T and RH. The BME280 sensor was mounted identically to the BME280 on the FMI-PRKL1. [Unfortunately, we were not able to acquire vertical profiles ~~nor~~ neither the ground level concentrations of gases with the Vaisala AQT400 sensor during LAPSE-RATE. All recorded concentrations of gases \(NO₂, O₃, CO and SO₂\) were far below the manufacturer declared detection limits, that is why no data set for the Vaisala AQT400 sensor is provided.](#)

Both CO₂ sensors were forcefully-aspirated using micro-blowers configured as air pumps (Murata, model MZB1001T02) connected to the exhaust of the sensors with flow rate of 0.6 L.min⁻¹. A Gelman filter ([1 µm filter assembly, Li-Cor Environmental](#)) was placed in the sample airstream in front of both CO₂ sensors to avoid contamination of the optical path. [The sampling frequencies of GMP343, Li-804A and BME280 were 0.5, 1 and 1 Hz, respectively.](#)

~~Unfortunately, we were not able to acquire vertical profiles neither for the ground-level concentrations of gases with the Vaisala AQT400 sensor during LAPSE-RATE. All recorded concentrations of gases (NO₂, O₃, CO and SO₂) were far below the manufacturer declared detection limits, that is why no data set for the Vaisala AQT400 sensor is provided.~~

A third FMI module was operated on the ground. It consisted of a condensational particle counter (CPC, model 3007, TSI Corp.), an optical particle counter (OPC, model N2, Alphasense) and a TriSonica Mini Weather Station (Applied Technologies, Inc.). Both OPCs N2, in the particle and ground module, were used with no additional inlet, as those OPCs were not meant to be used with any kind of inlet due to the use of a fan for aerosol intake. The surface sensor module was covered from all sides with PLA foam (2.5 cm thick) to ~~shade the sensors from direct sun~~protect sensors from solar radiation and keep the particle module thermally stable. The surface module was placed on the roof top of a car at about 2 m from the ground, the TriSonica Mini was mounted on a 45 cm long carbon fiber tube on top of the surface sensor module, i.e. about 2.75 m from the ground. The data of all sensors included in surface module were saved at 1 minute resolution.

Data of both FMI rotorcraft and the FMI surface sensor module were logged separately to embedded Raspberry Pi 3+ minicomputers using Python scripts to produce ASCII comma separated files, which were later converted to NetCDF format.

The KSU used a DJI Matrice 600 Pro rotorcraft without any modifications beyond the payload attachments, with the aircraft controlled with the Matrice 600 Pro remote controller. Both DJI TB47S (6x4500 mAh, 22.2 V) and DJI TB48S (6x5700 mAh, 22.8 V) rechargeable lithium polymer batteries were used, alternating between flights. The maximum gross take-off weight recommended by the manufacturer is 15.5 kg resulting in a maximum payload capacity of roughly 5.5 kg. The Matrice 600 Pro of KSU was equipped with an portable optical particle spectrometer (POPS, Handix Scientific LLC) measuring in the diameter size range of 0.13-3 μm in 16 size bins with mid-bin diameters: 0.138, 0.151, 0.166, 0.183, 0.200, 0.219, 0.250, 0.297, 0.399, 0.534, 0.802, 1.15, 1.47, 1.893, 2.506 and 3.26 μm. During LAPSE-RATE the POPS ~~was used both with~~ a horizontally oriented naked inlet approximately 9 cm (3.5 in.) long with an inner diameter of 1.7 mm (0.069 in.), ~~and a vertically oriented tube inlet of approximately 45 cm (18 inches) long and with an inner diameter of 3.175 mm (0.125 inches).~~ POPS included ~~eustom~~ electronics, and logged data to an onboard microSD card with frequency of 1 Hz. POPS was attached to the top surface of the rotorcraft body with Velcro tape. It was not shielded from direct sunlight during the flights, but was kept in shade while on the ground. A duplicate POPS instrument was operated as a ground reference it was located approximately 1.8 m AGL. and used a vertically oriented tube inlet of approximately 45 cm (18 in.) long with an inner diameter of 3.175 mm (0.125 in.). The penetration through the inlet was estimated to be ~92% for particles with diameter of 3 μm and better for smaller ones. and was located approximately 1.8 meters above the ground level. The overview of FMI-KSU team instrumentation and their operational characteristics are summarized in Table 1.

115 3 Description of measurement location, flight strategies and completed sampling

As mentioned above, the San Luis Valley provided a variety of aerosol particle sources, sinks and processing modes. In combination, the variability resulting from this processing made the San Luis Valley an interesting place to study aerosol properties and their spatial and temporal variability. One of the main sources of income for San Luis Valley inhabitants comes

120 from farming and ranching. The primary crops grown here include potatoes, alfalfa, native hay, barley, wheat, quinoa and
vegetables like lettuce, spinach, and carrots. Crops are irrigated by surface flooding water but mainly by center pivot sprinklers.
Uncultivated land is often covered with low brush such as rabbitbrush, greasewood and other woody species. The land is
also heavily used for grazing ([U.S. Fish and Wildlife Service, 2015](#)) and [references therein](#). The soils of the SLV are generally
coarse, gravelly, sandy soils or loam, and derived mainly from volcanic rocks (Lapham, 1912).

The FMI-KSU team operated from one location throughout the entire LAPSE-RATE campaign. This location was situated
125 along County Road 53, approximately 15 km north from Leach Airport (37°54'32.94" N, 106°2'6.83" W, 2291 m MSL), see
Fig. 1. The location was flat and treeless, surrounded by grazing farmlands and generally very quiet. Occasionally the site
experienced emissions and aerosol production from the operation of local farm trucks. The FMI team was permitted to operate
to a maximum altitude of 914 m AGL under a FAA COA, however the aircraft was only flown to a maximum altitude of 893 m
AGL. All flights operated by the KSU team were conducted up to a maximum altitude of 121 m AGL, the maximum altitude
130 permitted under FAA Part 107.

During July 15th-18th the FMI-KSU team conducted missions focusing on profiling of aerosol particle and gas properties. In
total, the FMI team completed 38 vertical profile flights: 14 flights with the particle module and 24 flights with the gas module
(see Table 2). The KSU team completed a total of 33 flights with their payload, including 40 individual vertical profiles. It
should be noted that some of these KSU profiles were redundant, made within a few minutes of each other, and repeated in the
135 exact same location as another profile. These redundant flights were completed to test the instrument consistency. [It was found
that POPS was counting consistently during vertical sampling. But during the horizontal transects, when the POPS inlet was
facing the direction of flight, we found fluctuations in POPS measured sample flow rate. Only vertical profile data are included
in the dataset.](#) The FMI flight strategy was to conduct only vertical flights and reach as high an altitude as possible in very
short time. FMI ascent rates were between 5-8 and 3-5 m.s⁻¹ and descent rates were about 2-5 and 2-3 m s⁻¹ for flights with
140 the particle module (FMI-PRKL1) and gas module (FMI-PRKL2), respectively. Vertical profiling was performed in cycles by
alternating flights with the aircraft carrying the FMI particle module, the FMI gas module and the KSU platform, with about
30 minutes in between flights (please see Table 2-4 for details on timing, frequency and achieved altitude of all flights). The
FMI surface module and KSU surface POPS were logging continuously during the time periods of flight operations (see Table
[35 and 6](#) for details).

145 On the last day of FMI-KSU operations during LAPSE-RATE (July 19th), the team joined the common effort to evaluate
cold-air drainage from local valleys during the morning hours. The operation started about 11:45 UTC (5:45 a.m. local time)
with vertical profiles every 30 min lasting about 5 hours. Only the FMI-PRKL2 and KSU rotorcraft took part in these cold-air
drainage flights in an alternating fashion. For these flights ascent and descent rates were reduced to about 2 m s⁻¹ given that the
target maximum altitude during these flights only extended to 350 m AGL.

150 4 Data Processing and Quality Control

Data files generated by the FMI particle module (FMI-PRKL1) were formatted in NetCDF format and were named according to the general naming convention for the LAPSE-RATE files (FMI.PRKL1.a1.yyyy.mm.dd.hh.mm.ss.cdf), as outlined in de Boer et al. (2020b). Missing data in the dataset are marked as -9999.9. These files ~~provide information at 1 Hz, and~~ include the Raspberry Pi RTC time stamp, aircraft location (GPS latitude and longitude in degrees and altitude in MSL meters), basic meteorology, including temperature ($^{\circ}\text{C}$), pressure (hPa) and relative humidity (%). ~~Additionally included in these data files are the FMI-PRKL1 aircraft attitude data (pitch, roll, yaw and heading in degrees, GPS ground speed in m s^{-1} and vertical ascent rate, also in m s^{-1}). These variables are published as they were measured without any corrections.~~ Finally, these files include the total particle concentration measured by the pair of CPCs (model 3007, TSI Inc.). As a reminder, these two CPCs had different cut-off diameters (D_{50}) at 7 and 14 nm (the lower size boundaries), with the upper boundary particle size more than $1\ \mu\text{m}$. The CPC calibration was done in the same way as described in Hämeri et al. (2002); the uncertainty of D_{50} values was determined to be $\pm 0.8\ \text{nm}$. The total count was compared to a desktop, full-sized, more precise CPC (model 3772, TSI Corp.) with an accuracy of about 20%, when the ambient air was sampled.

NetCDF files created from the measurements of the OPC-N2 particle counter were saved separately under the file name FMI.PRKL1OPC-N2.a1.yyyy.mm.dd.hh.mm.ss.cdf. These files ~~include~~contain 0.5 Hz resolution data, including the time stamp, aircraft location (GPS latitude and longitude in degrees and altitude in meters, total aerosol number concentration in cm^{-3} and total aerosol volumetric concentration in $\mu\text{m}^3.\text{cm}^{-3}$, both in a size range of $0.38\text{--}17\ \mu\text{m}$). Also included are particle number concentrations (cm^{-3}) in each bin, including measurements in 16 size bins with mid-bin diameters of 0.46, 0.66, 0.92, 1.19, 1.47, 1.83, 2.54, 3.5, 4.5, 5.75, 7.25, 9, 11, 13, 15 and $16.75\ \mu\text{m}$, the calculated $dN/d\log D_p$ (cm^{-3}) values in each size bin, and measured PM1, PM2.5 and PM10 mass concentrations in $\mu\text{g}.\text{m}^{-3}$, respectively. The positioning data were~~These quantities are also~~ provided in the files as they were measured, meteorological parameters were cleaned off outliers and no corrections were applied, particle concentrations were cleaned of extremely high peaks caused by vehicle emissions.

The FMI gas module dataset (FMI.PRKL2.a1.yyyy.mm.dd.hh.mm.ss.cdf) includes NetCDF files ~~containing 1 Hz data, m-~~Missing data in the dataset are marked as -9999.9. These files include the Raspberry Pi RTC time stamp, aircraft location (GPS latitude and longitude in degrees, and aircraft altitude in MSL meters), and basic meteorology including temperature in degrees $^{\circ}\text{C}$, pressure in hPa and relative humidity in %. ~~All of these data are published as they were measured without any corrections or additional quality control.~~ Additionally, for both aircraft FMI-PRKL1 and FMI-PRKL2 identically, included in these data files are aircraft attitude data (pitch, roll, yaw and heading in degrees, GPS ground speed in m s^{-1} and vertical ascent rate, also in m s^{-1}). The attitude data are published as they were recorded without any corrections.~~In addition, these files contain the PRKL2 aircraft attitude data (pitch, roll, yaw and heading in degrees, GPS ground speed in m s^{-1} , and vertical ascent rate in m s^{-1}).~~ Also included are the measured CO_2 concentration in parts per million (ppm) and dew point temperature in $^{\circ}\text{C}$ as measured by Licor Li-840A. ~~The CO_2 concentrations (ppm) measured by the Vaisala GMP343 probe are reported at 0.5 Hz.~~ The CO_2 concentrations measured by the Licor Li-840A are internally compensated for water vapor concentration, pressure changes and atmospheric temperature (for details please see the Licor Li-840A Instruction manual). Data from the Vaisala GMP343

185 sensor were compensated for pressure, temperature, RH (obtained from the BME280 sensor) and oxygen in post-processing
by using the proprietary compensation algorithm provided by Vaisala. Even though, the BME280 sensor showed a bias of
about +2 °C in temperature, -12% in RH and +2 hPa in pressure during the LAPSE-RATE inter-comparison measurements
(Barbieri et al., 2019), the bias impact on compensation was minimal, less than 1%. Even when accounting for the maximum
error in T, RH and P, the resulting change (increase) in CO₂ concentration was only 2 ppm. Furthermore, both CO₂ sensors
were calibrated in the laboratory before and after LAPSE-RATE and showed no drift in calibration. The sensors were calibrated
190 against standard carbon dioxide gases (traceable to WMO CO₂ scale X2007 at the FMI) at several concentrations (zero gas and
436 ppm before the campaign, and 370, 405.4 and 440.2 ppm after the campaign). The following, laboratory-derived calibration
constants were applied to the data sets collected by both sensors: $Licor_{new}=0.95785 \times Licor_{measured} + 8.66055$ with $R^2=0.9999$
and $GMP_{new}=0.99878 \times GMP_{compensated} + 8.77014$ with $R^2=0.99999$. Please note $GMP_{compensated}$ used in the equation above
and that the Vaisala compensation algorithm is confidential. Also, both sensors were tested in the FMI lab at sea level pressure
195 against a calibrated, high-precision gas concentration analyzer (Picarro model G2401, Picarro, Inc.) at ambient CO₂ concen-
tration. The GMP343 data were biased on average -3.4 (±1.3) ppm and the Licor 0.3 (±1.1) ppm. The dew point measurement
from the Licor LI-840A was calibrated against a DewMaster Chilled Mirror Hygrometer (Edgetech Instruments Inc.).

Measurements collected by the FMI ground module (NetCDF file names FMI.GROUNDTRISONICA-CPC.a1.
yyyymmdd.hhmmss.cdf) ~~are saved in files that include data at 1-minute resolution, including~~ include the Raspberry Pi RTC
200 time stamp, wind speed ($m \cdot s^{-1}$), wind direction (deg), temperature (°C), relative humidity (%), and pressure (hPa) measured by
the Trisonica mini weather station. Also saved is the total aerosol number concentration (cm^{-3}) measured by CPC (model 3007,
TSI Inc.). The second ground module dataset (FMI.GROUNDOPC-N2.a1.yyyyymmdd.hhmmss.cdf) includes ~~also 1-minute
resolution data of~~ the Raspberry Pi RTC time stamp, total aerosol number concentration (cm^{-3}), total aerosol volumetric con-
centration ($\mu m^3 \cdot cm^{-3}$) in a size range of 0.38-17 μm . Also included are the particle number concentrations in each bin (16
205 size bins), calculated $dN/d\log D_p$ (cm^{-3}) values in each bin (16 size bins), and the measured PM1, PM2.5 and PM10 mass
concentrations ($\mu g \cdot m^{-3}$) respectively. Missing data in both of these datasets are marked as -9999.9.

The KSU airborne dataset (KSU.M600POPS.a1.yyyyymmdd.hhmmss.cdf) includes ~~1-Hz measurements including~~ the POPS
internal RTC time stamp, aircraft location (GPS altitude (m MSL), altitude (m AGL), latitude and longitude (deg)), total aerosol
particle count and total aerosol particle concentration (cm^{-3}) in the size range 0.13–3 μm . Also included are atmospheric
210 pressure (hPa), internal air flow ($cm^3 \cdot s^{-1}$), counts per bin (16 size bins) and calculated $dN/d\log D_p$ (cm^{-3}) values in each bin (16
size bins).

Additionally, the KSU ground dataset (KSU.SURFACEPOPS.a1.yyyyymmdd.hhmmss.cdf) includes ~~1-Hz resolution data
of~~ POPS internal RTC time stamp, total aerosol particle count in the diameter size range 0.13–3 μm , total aerosol particle
concentration (cm^{-3}) in the diameter size range 0.13–3 μm , pressure (hPa), internal air flow ($cm^3 \cdot s^{-1}$), counts per bin (16 size
215 bins) and calculated $dN/d\log D_p$ (cm^{-3}) values in each bin (16 size bins with mid-bin diameters: 0.138, 0.151, 0.166, 0.183,
0.200, 0.219, 0.250, 0.297, 0.399, 0.534, 0.802, 1.15, 1.47, 1.893, 2.506 and 3.261-38, 4.51, 4.66, 4.83, 2.00, 2.19, 2.50, 2.97,
3.99, 5.34, 8.02, 11.52, 14.66, 18.93, 25.06 and 32.56 μm). The datasets were cleaned off the outliers and extremely high

particle concentrations caused by vehicle emissions, no additional corrections were applied to data~~All variables published as they were measured without any corrections.~~

220 4.1 Dataset remarks

Throughout the collected data set, there were occasional peaks in detected aerosol number concentration caused by farm vehicles passing our sampling location. Some of these peaks resulted in particle counts up to 40 000 cm⁻³ from the CPC and up to 16 000 cm⁻³ from the POPS. These peaks typically lasted approximately 3 minutes, and were removed from the datasets. Also, a short inter-comparison (about 5 minutes) was performed before each flight among the surface and airborne particle
225 counters to check their performance. Based on data post-processing, the CPCs of particle and surface modules compared well within the manuscript stated uncertainty of 10%, except for July 16th when NPF at the surface level took place. This is due to different calibrated cut-off diameter of each CPC. The OPCs compared within factor of 2, however it has to be considered that very low particle concentrations were measured, about 2 cm⁻³ in the OPCs size range. There were no inter-comparison measurements made for POPS instruments. For more details please see Supplementary Materials of Brus et al. (2021), where
230 the detailed analysis was provided.

Since hysteresis in T and RH profiles collected by both FMI aircraft was noticeable, we recommend to use only data from the ascending portion of the flown profiles. The ascent data copied quite well the T and RH slopes, when compared to balloon sounding profiles made from Leach Airport. The descent data were found rather flat.

Data from the Vaisala GMP343 probe suffer from an inaccurate pressure compensation algorithm provided by Vaisala. As
235 mentioned above, the GMP343 performed well at the sea level, however the bias increased with elevation. Therefore, we recommend use of Licor-840A data over those from the Vaisala GMP343 probe.

The merged data sets on meteorology, aerosol and gases concentrations are presented in Fig. 2 and Fig. 3 for airborne and surface measurements respectively.

5 Data Availability

240 Data sets collected by the ~~FMI Finnish Meteorological Institute~~ and the ~~KSU Kansas State University~~ during LAPSE-RATE were published together under the LAPSE-RATE community at Zenodo open data repository. For data collected using the platforms outlined in this paper, the airborne data sets of Finnish Meteorological Institute FMI-PRKL1, FMI-PRKL2 and the FMI surface module data sets can be all found here: <https://doi.org/10.5281/zenodo.3993996>, Brus et al. (2020a). The airborne
245 data sets of Kansas State University KSU M600 and KSU surface data sets can be found both here: <https://doi.org/10.5281/zenodo.3736772>, Brus et al. (2020b).

All data sets have undergone preliminary quality control and false readings were eliminated. All files are available in netCDF format for each individual UAS flight and the surface data sets are available as separate daily files.

6 Summary

This publication summarizes measurements collected and data sets generated by the FMI and KSU teams during LAPSE-RATE. LAPSE-RATE took place in the San Luis Valley of Colorado during the summer of 2018. In section 2, we provided an overview of the rotorcraft deployed by these teams during this campaign, and offer insight into the types of payloads that were deployed. In Section 3 we described the teams' scientific goals and flight strategies while section 4 provides a glimpse at the data sets obtained, including a description of the measurement validation techniques applied. Section 5 provided information on data sets availability. [The dataset was divided into two parts: FMI dataset containing 60 files \(21 MB\) and KSU dataset containing 31 files \(11.3 MB\), all files are available in netCDF format.](#) To our knowledge, the data collected by these flights represent some of the only known profiles of aerosol properties collected over the San Luis Valley.

While the overall data set is limited in temporal and spatial coverage, these measurements offer unique insight into the vertical structure and diurnal variability of atmospheric thermodynamic, aerosol and gas parameters in a new location. Such observations would be difficult to obtain with other profiling methods (such as ground-based remote-sensing instrumentation). The temporal frequency and spatial extent covered by these profiles is unique to data collected using unmanned aircraft systems. This data set offers a nice example of how these systems can help to inform our general understanding of these parameters, which can be very important to understanding weather ~~and~~ climate.

~~Finally, work to analyze these data is ongoing.~~ A description of the vertical structure of key parameters as observed during LAPSE-RATE ~~was provided in~~ [has been submitted for publication](#) Brus et al. (2021), [e.g. it includes analysis and discussion on acquired parameters and provides insight, however limited, on](#) ~~and includes evidence of~~ new particle formation events occurring over the San Luis Valley. ~~Additional work is planned to assess the thermodynamic and aerosol particle properties associated with the cold-air drainage flows that were found to occur during the night in the valley.~~

Author contributions. D.B. and G.B. planned and coordinated FMI missions during LAPSE-RATE campaign, D.B. conducted particle module measurements, processed, analyzed and QC FMI dataset, ~~wrote~~ [written](#) the manuscript. J.G. provided technical support during the campaign, conducted measurements with gas module. A.H. wrote the manuscript and QC FMI dataset. O.K. conducted all KSU flights. G.B. and D.B. prepared and QC KSU dataset. All authors edited the manuscript.

Competing interests. The authors declare no conflict of interest.

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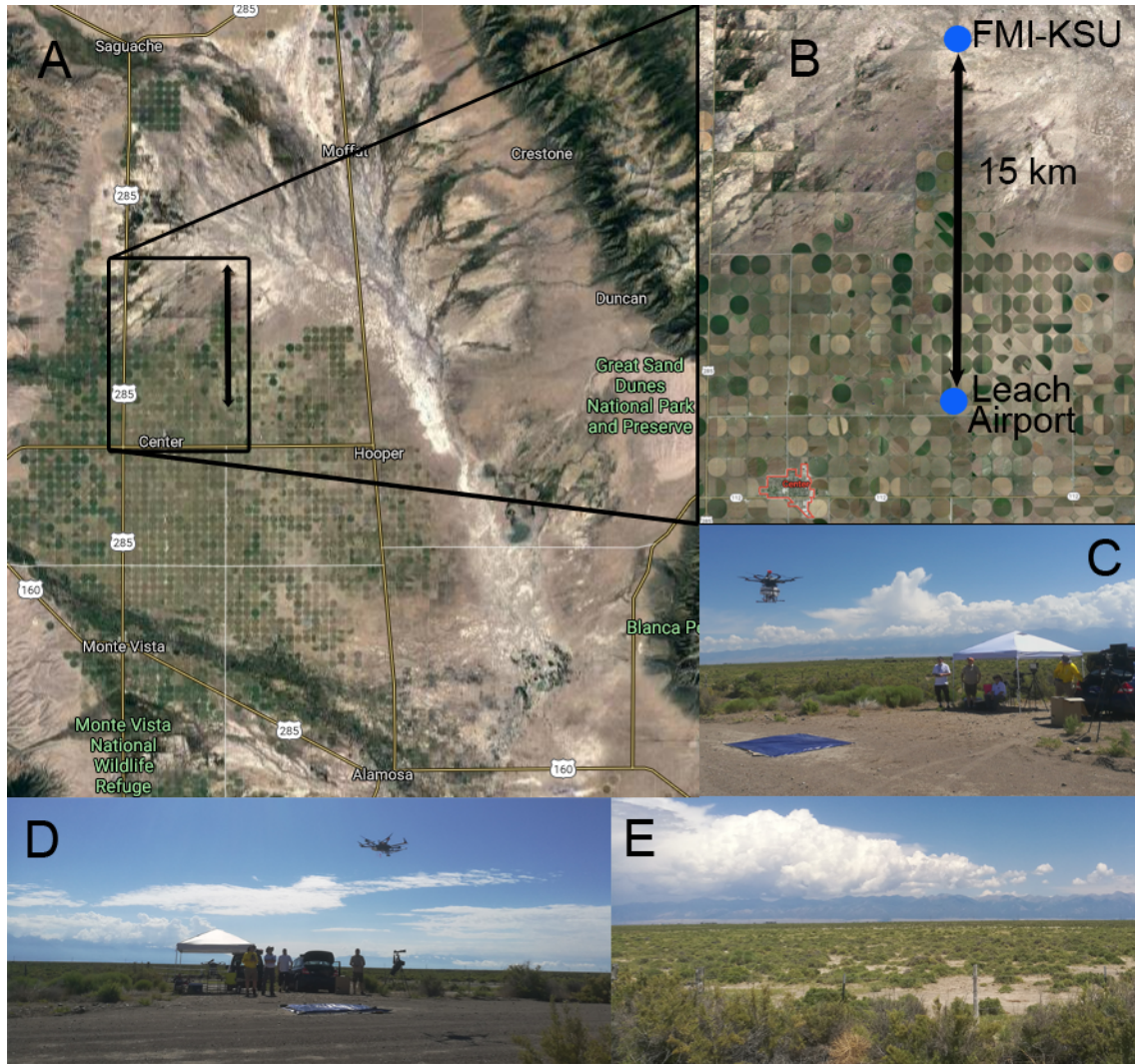


Figure 1. A) Map of wider San Luis Valley, CO, B) map cutout of FMI-KSU team location - 15 km north of Leach airport, located approximately 3.2 km ENE of the commercial district of Center, Colorado and 32 km NNW of Alamosa, Colorado. ©Google Maps C) FMI-KSU team operation spot NE view, D) FMI-KSU team operation spot view towards E, E) view of typical surroundings of FMI-KSU team spot.

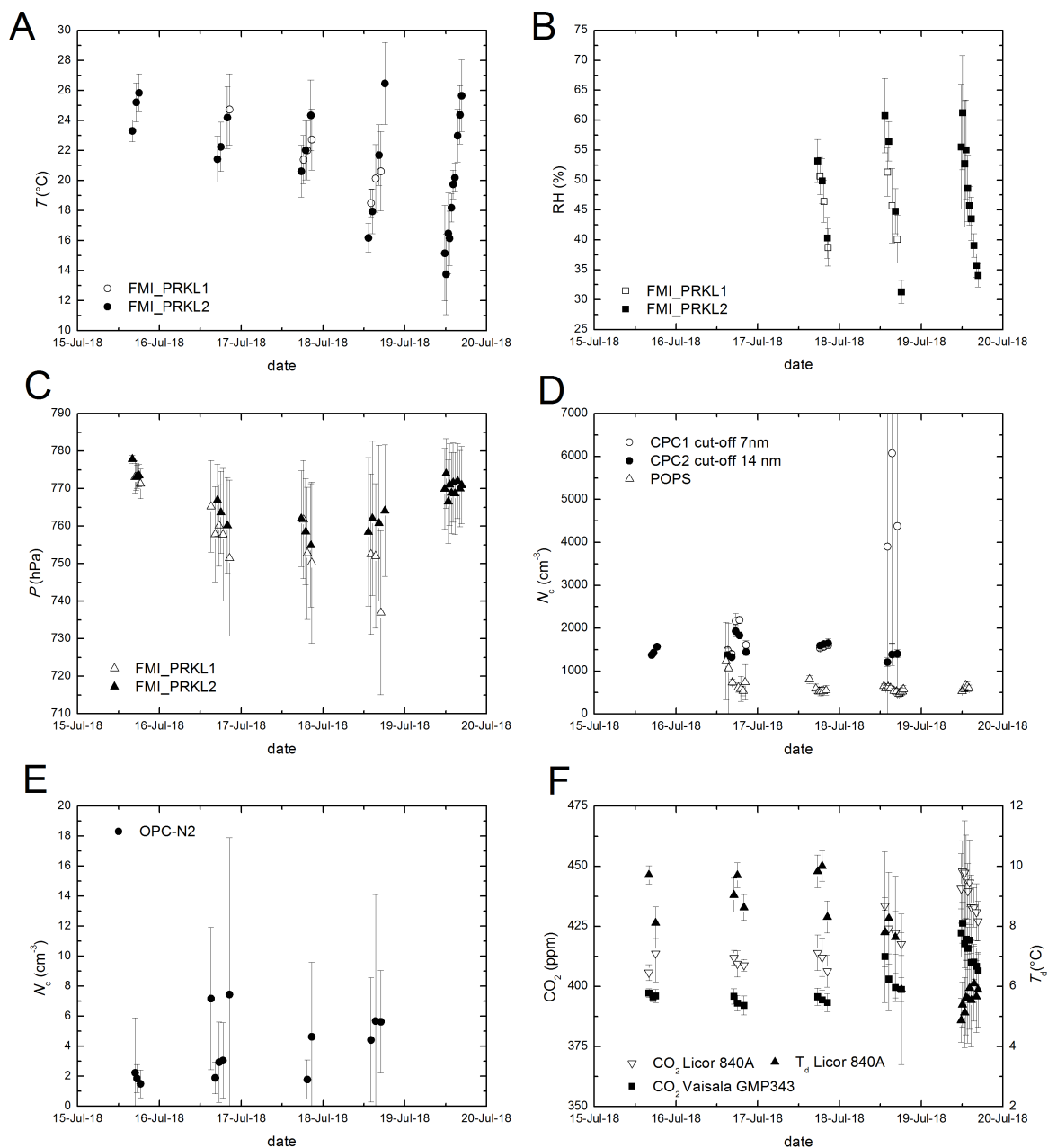


Figure 2. Overview of data collected in vertical profile, mean values with standard deviations as error-bars: A) temperature, B) relative humidity, C) pressure, D) total aerosol number concentration by CPCs and POPS (0.13–3 μm), [note the elevated concentration measured by CPC1 characterizing the event](#), E) aerosol number concentration by OPC-N2 (0.3–18 μm) and F) CO₂ concentration by Licor Li-840A and Vaisala GMP343 and dew point temperature by Licor Li-840A.

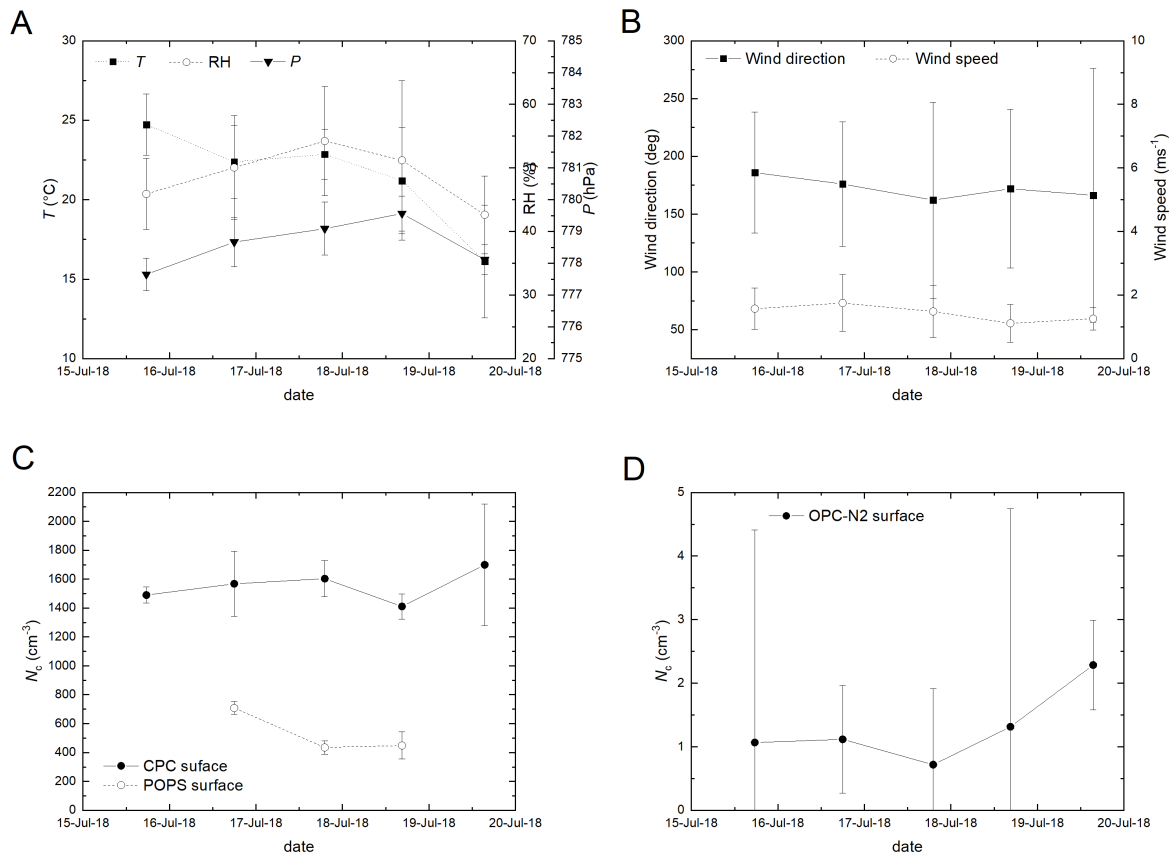


Figure 3. Overview of data collected [without](#) the [FMI](#) surface [module placed on car roof about 2.75 m AGL](#), mean values with standard deviations as error-bars: A) temperature, relative humidity, pressure, B) wind direction and speed by Trisonica mini weather station C) total aerosol number concentration by CPC and POPS (0.13–3 μ m, [placed about 1.8 m AGL](#)), and D) aerosol number concentration by OPC-N2 (0.3–18 μ m)

Table 1. An overview of sensors and their operational characteristics [provided by manufacturer](#) . The sensor use in airborne and/or ground based measurements is specified in sensor name column as [mission: a-airborne, g-ground based](#)

Sensor	Resolution	Accuracy	Range	Flow rate	Response time
CPC, TSI 3007 Particle conc. (cm ⁻³) mission: a & g			0-10 ⁵ cm ⁻³ , Diameter: 0.01->1 µm	0.7 L.min ⁻¹	1 s
OPC, Alphasense N2 Particle conc. (cm ⁻³) mission: a & g			0-10 ⁴ part.s ⁻¹ , Diameter: 0.38-17 µm at 16 bins	1.2 L.min ⁻¹	1 s
BME280 T (°C) RH (%) Pressure (hPa) mission: a & g	0.01 <0.01 0.18 Pa	±0.5 °C ±3 % ±1 hPa	-40-85 °C 0-100 % 300-1100 hPa		1 s 1 s 6 ms
GMP343, Vaisala CO ₂ (ppm) mission: a	14-bits	±3ppm +1% of reading	0-1000 ppm	0.6 L.m ⁻¹	2s
Li-840A, Licor CO ₂ (ppm) T _d (°C) mission: a	14-bits across user-specified range 14-bits across user-specified range	<1.5% of reading <1.5% of reading	0-20000 ppm -25-45 °C, RH: 0 to 95% RH Non-Condensing	0.6 L.m ⁻¹ 0.6 L.m ⁻¹	1s 1s
TriSonica Mini WS, Applied Tech. T (°C) RH (%) Pressure (hPa) Wind speed (m.s ⁻¹) Wind direction (deg.) mission: g	0.1 0.1 1 0.1 1	±2°C ±3% ±10 hPa ±0.1 m.s ⁻¹ ±1 deg.	-25-80 °C 0-100 % 500-1150 hPa 0-30 m.s ⁻¹ x/y: 0-360 deg., z: ±30 deg.		1 s 1 s 1 s 1 s 1 s
POPS, Handix Sci. Particle conc. (cm ⁻³) mission: a & g		±10% <1000 cm ⁻³ at 0.1 L.m ⁻¹	0-1250 cm ⁻³ , Diameter: 0.13 – 3 µm at 16 bins	0.18 L.min ⁻¹	1 s

Table 2. UAS vertical profile measurements - an overview of platforms, missions, flight times and achieved altitudes

[Tables 2, 3, and 4 were merged to one UAS measurements table](#)

platform	mission	date	start time (UTC)	end time (UTC)	altitude (m MSL)	altitude (m AGL)	
FMI-PRKL1	aerosols/meteo	15/07/18	16:51:49	16:56:55	2483.49	175.49	
			17:24:40	17:32:00	2436.60	128.60	
			18:24:54	18:33:12	2449.68	141.68	
			16/07/18	15:06:47	15:14:55	2819.67	511.67
				16:20:53	16:29:21	2823.44	515.44
				17:30:33	17:41:14	2730.81	422.81
				18:37:31	17:47:36	2949.73	641.73
				20:33:20	20:42:56	2994.55	686.55
			17/07/18	18:17:18	18:26:03	2924.22	616.22
19:24:35				19:35:13	2992.33	684.33	
20:41:37				20:53:53	3119.02	811.02	
		18/07/18	14:03:55	14:14:33	3155.00	847.00	
			15:26:03	15:36:27	3028.59	720.59	
			16:59:06	17:05:55	3201.53	893.53	
FMI-PRKL2	gases/meteo	15/07/18	16:02:28	16:06:28	2356.88	48.88	
			17:12:39	17:17:13	2441.78	133.78	
			17:59:24	18:05:11	2409.02	101.02	
			16/07/18	17:00:44	17:08:28	2675.27	367.27
				18:00:08	18:08:55	2703.60	395.60
				19:57:24	20:06:33	2781.37	473.37
			17/07/18	17:37:19	17:46:52	2773.00	465.00
				18:53:43	19:02:34	2814.49	506.49
				20:27:20	20:36:53	2910.11	602.11
			18/07/18	13:19:00	13:31:21	2971.37	663.37
				14:29:00	14:44:16	3004.27	696.27
				16:25:00	16:40:26	3013.40	705.40
				18:10:00	18:24:36	2912.85	604.85
			19/07/18	11:44:33	11:53:42	2669.10	361.10
				12:07:00	12:24:09	2658.34	350.34
12:46:00				12:53:43	2667.16	359.16	
13:08:00				13:19:10	2666.06	358.06	
13:41:00				13:49:25	2667.75	359.75	
14:11:00				14:22:36	2669.65	361.65	
14:42:00				14:55:43	2664.22	356.22	
15:30:00				15:45:19	2657.98	349.98	
16:12:00				16:22:25	2658.15	350.15	
			16:42:00	16:53:32	2663.10	355.10	

platform	mission	date	start time (UTC)	end time (UTC)	altitude (m MSL)	altitude (m AGL)
KSU POPS	aerosols	16/07/18	14:40:46	14:49:51	2401.3	125.4
			15:23:44	15:37:17	2419.4	142.4
			16:32:25	16:41:06	2410.6	126.6
			18:17:44	18:24:58	2416.7	126.4
			19:01:43	19:09:54	2333.0	39.4
			19:43:41	19:47:18	2354.6	52.1
			20:17:20	20:22:46	2429.7	126.8
		17/07/18	15:10:38	15:24:49	2401.3	125.7
			17:02:14	17:09:42	2401.6	129.0
			17:58:12	18:04:40	2403.5	127.5
			18:29:15	18:40:16	2379.9	100.0
			19:15:14	19:26:11	2417.7	131.3
			20:03:59	20:09:49	2424.7	127.4
		18/07/18	12:59:49	13:04:27	2397.5	127.4
			13:31:21	13:42:29	2398.4	127.2
			14:16:06	14:22:23	2400.8	131.3
			14:58:05	15:02:03	2394.9	126.2
			15:59:52	16:08:59	2402.2	127.2
			16:44:06	16:46:37	2408.2	128.2
			17:30:21	17:38:37	2408.4	126.4
			17:59:11	18:03:40	2415.5	128.6
			18:29:37	18:33:06	2417.9	126.5
			18:45:25	18:49:16	2419.4	126.1
		19/07/18	12:01:01	12:05:05	2433.6	138.8
			12:28:54	12:31:35	2435.9	142.8
			12:59:42	13:02:06	2429.7	139.1
			13:29:40	13:32:18	2427.4	139.0
			13:59:47	14:02:37	2425.1	137.4

Table 3. [Surface measurements at altitude 2291 m MSL - overview of platform and data coverage](#)

[Tables 5 and 6 were merged to one surface measurements table](#)

platform	date	start time (UTC)	end time (UTC)
FMI surface module	15/07/18	15:34:35	19:36:35
	16/07/18	14:45:29	22:10:47
	17/07/18	17:01:53	21:08:15
	18/07/18	13:03:29	19:05:08
	19/07/18	11:37:20	16:56:36
KSU POPS surface	16/07/18	15:52:34	16:16:44
	17/07/18	18:17:46	20:31:13
	18/07/18	13:30:39	18:13:44

Acronyms

375 **AGL** above ground level. 2, 4, 5, 16

CPC condensation particle counter. 3, 4, 6–8, 15–17

FMI Finnish Meteorological Institute. 1–10, 14, 16, 18, 20

KSU Kansas State University. 1, 2, 8

LAPSE-RATE The Lower Atmospheric Process Studies at Elevation - a Remotely-piloted Aircraft Team Experiment. 1–10

380 **MSL** mean sea level. 5, 20

NPF new particle formation. 2, 8

OPC optical particle counter. 3, 4, 6, 8, 15–17

PBL planetary boundary layer. 1

POPS portable optical particle spectrometer. 4, 5, 7, 8, 10, 15–17, 19, 20

385 **SLV** San Luis Valley. 1, 2, 5

sUAS Small Unmanned Aerial Systems. 1