

1 **Long-term trends of ambient nitrate (NO₃⁻) concentrations across China based on ensemble**
2 **machine-learning models**

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13 **Abstract**

14 High loadings of nitrate (NO₃⁻) in the aerosol over China significantly exacerbates the air quality
15 and poses a great threaten on ecosystem safety through dry/wet deposition. Unfortunately, limited
16 ground-level observation data makes it challenging to fully reflect the spatial pattern of NO₃⁻ level
17 across China. Up to date, the long-term monthly particulate NO₃⁻ datasets at a high resolution were
18 still missing, which restricted the assessment of human health and ecosystem safety. Therefore, a
19 unique monthly NO₃⁻ dataset at 0.25 ° resolution over China during 2005-2015 was developed by
20 assimilating surface observation, satellite product, meteorological data, land use types and other
21 covariates using an ensemble model combining random forest (RF), gradient boosting decision tree
22 (GBDT), and extreme gradient boosting (XGBoost). The new developed product featured excellent
23 cross-validation R² value (0.78) and relatively lower root-mean-square error (RMSE: 1.19 μg N m⁻³)
24 and mean absolute error (MAE: 0.81 μg N m⁻³). Besides, the dataset also exhibited relatively

25 robust performance at the spatial and temporal scale. Moreover, the dataset displayed good
26 agreement with ($R^2 = 0.85$, $RMSE = 0.74 \mu\text{g N m}^{-3}$, and $MAE = 0.55 \mu\text{g N m}^{-3}$) some unlearned
27 data collected from previous studies. The spatiotemporal variations of the developed product were
28 also shown. The estimated NO_3^- concentration showed the highest value in North China Plain (NCP)
29 ($3.55 \pm 1.25 \mu\text{g N m}^{-3}$), followed by Yangtze River Delta (YRD ($2.56 \pm 1.12 \mu\text{g N m}^{-3}$)), Pearl River
30 Delta (PRD ($1.68 \pm 0.81 \mu\text{g N m}^{-3}$)), Sichuan Basin ($1.53 \pm 0.63 \mu\text{g N m}^{-3}$), and the lowest one in
31 Tibetan Plateau ($0.42 \pm 0.25 \mu\text{g N m}^{-3}$). The higher ambient NO_3^- concentrations in NCP, YRD, and
32 PRD were closely linked to the dense anthropogenic emissions. Apart from the intensive human
33 activities, poor terrain condition might be a key factor for the serious NO_3^- pollution in Sichuan
34 Basin. The lowest ambient NO_3^- concentration in Tibetan Plateau was contributed by the scarce
35 anthropogenic emission and favorable meteorological factors (e.g., high wind speed). In addition,
36 the ambient NO_3^- concentration showed marked increasing tendency of $0.10 \mu\text{g N m}^{-3}/\text{year}$ during
37 2005-2014 ($p < 0.05$), while it decreased sharply from 2014 to 2015 at a rate of $-0.40 \mu\text{g N m}^{-3}/\text{year}$
38 ($p < 0.05$). The ambient NO_3^- levels in Beijing-Tianjin-Hebei (BTH), YRD, and PRD displayed
39 gradual increases at a rate of 0.20, 0.11, and $0.05 \mu\text{g N m}^{-3}/\text{year}$ ($p < 0.05$) during 2005-2013,
40 respectively. The gradual increases of NO_3^- concentrations in these regions from 2005 to 2013 were
41 due to that the emission reduction measures during this period focused on the reduction of SO_2
42 emission rather than NO_x emission and the rapid increase of energy consumption. Afterwards, the
43 government further strengthened these emission reduction measures, and thus caused the dramatic
44 decreases of NO_3^- concentrations in these regions from 2013 to 2015 ($p < 0.05$). The long-term NO_3^-
45 dataset over China could greatly deepen the knowledge about the impacts of emission reduction

46 measures on air quality improvement. The monthly particulate NO_3^- levels over China during 2005-
47 2015 are open access in <https://doi.org/10.5281/zenodo.3988307> (Li et al., 2020c).

48 **1. Introduction**

49 Reactive nitrogen (N_r) emissions displayed remarkable increases in the past decades owing to
50 the high-speed industrial development and urbanization (Cui et al., 2016; Singh et al., 2017).
51 Ambient reactive N emissions were mainly characterized with nitrogen oxides (NO_x), accounting
52 for about 30% of the gross N_r emissions (Chen et al., 2015; Liu et al., 2011). These important N-
53 bearing precursors could be transformed into the nitrate (NO_3^-) via multiple chemical pathways (e.g.,
54 heterogeneous or liquid phase reaction), and finally deposited in the terrestrial or aquatic ecosystem
55 (Jia et al., 2016; Qiao et al., 2015; Zhao et al., 2017). On the one hand, heavy loadings of NO_3^-
56 greatly degraded the atmospheric visibility and cool the surface of the Earth system because
57 particulate NO_3^- significantly scattered solar radiation (Fu and Chen, 2017). Moreover, enhanced N
58 deposition might pose a negative effect on the ecosystem health such as biodiversity losses,
59 freshwater eutrophication, and oceanic acidification (Compton et al., 2011; Erisman et al., 2013).
60 Hence, deepening the knowledge about the spatial patterns and long-term trends of particulate NO_3^-
61 in the atmosphere is beneficial to accurately evaluate the ecological and environmental effects of N
62 deposition.

63 Ground-level observation is often acknowledged to be an effective means to explore the spatial
64 patterns of ambient NO_3^- concentrations. Many long-term monitoring networks including Clean Air
65 Status and Trends Network (CASTNET) and Canadian Air and Precipitation Monitoring Network
66 (CAPMoN) were established to quantify the ambient NO_3^- concentration and inorganic N deposition.
67 Du et al. (2014) revealed that the NO_3^- deposition showed significant decrease across the United

68 States during 1985-2012 based on these observation data. To date, most of these observation
69 networks focused on North America and Europe, whereas few monitoring sites were located on East
70 Asia especially on China. Fortunately, China has constructed some ground-level observation
71 networks such as CARE-China Observation Network in recent years. On the basis of these
72 observation networks, the overall spatiotemporal trend of particulate NO_3^- concentration has been
73 clarified (Wang et al., 2019c; Xu et al., 2018a). Xu et al. (2018a) observed that the particulate NO_3^-
74 concentration ($< 4.5 \mu\text{m}$) over China did not show significantly temporal variation during 2011-
75 2015. Very recently, Wang et al. (2019) found that the NO_3^- level in the fine particle ($\text{PM}_{2.5}$)
76 decreased by 34% during 2015-2017. Although the overall spatial patterns have been preliminarily
77 revealed based on these isolated sites, these sparse ground-observed sites did not accurately reflect
78 the high-resolution NO_3^- pollution especially the regions far away from these sites because each
79 station only possessed limited spatial representative and NO_3^- concentration was often highly
80 variable in space and time (Liu et al., 2017a). More importantly, the current studies only investigated
81 the ambient NO_3^- concentrations in recent years, while the long-term variation of NO_3^- level
82 remained unknown. It was well known that the energy consumption in China displayed remarkable
83 increase in recent decades (Zhan et al., 2018). Meanwhile, Chinese government also proposed
84 pollutant emission reduction policies since 2005 to ensure the coordinated development of economic
85 growth and environmental protection (Ma et al., 2019). However, the synergistic effects of air
86 pollution control policies and increased energy consumption on long-term evolution trend of NO_3^-
87 pollution over China were not assessed yet, which were extremely critical for the implementation
88 of emission control measures.

89 To complement the gaps of ground-level observations, satellite product of NO_2 is regarded as a

90 welcome addition to investigate the long-term trends of N-bearing components in the atmosphere.
91 Ozone Monitoring Instrument (OMI) was regarded as the typical satellite product applied to
92 simulate the ambient NO_3^- concentration (Liu et al., 2017b; Vrekoussis et al., 2013). Jia et al. (2016)
93 firstly used the linear regression method to predict the NO_3^- levels and dry deposition fluxes at the
94 global scale based on OMI-derived NO_2 column amount. However, the dry deposition fluxes of
95 NO_3^- modelled by Jia et al. (2016) showed weak correlation with the measured value ($R = 0.47$),
96 which might be attributable to the simple linear assumption between NO_2 column amount and NO_3^-
97 deposition flux. It was well documented that the nonlinearity relationship between multiple
98 predictors and NO_3^- concentration were hard to reveal on the basis of the simple linear model (Zhan
99 et al., 2018a; Zhan et al., 2018b). To enhance the predictive performance of NO_3^- concentration, Liu
100 et al. (2017) used the chemical transport models (CTMs) to estimate the dry deposition fluxes of N-
101 bearing species recently based on the remotely sensed NO_2 column amount. However, CTMs often
102 suffered from high uncertainty because of the limited knowledge about the generation pathways for
103 particulate NO_3^- in the atmosphere (Zhan et al., 2018a). Recently, the emergence of machine
104 learning models provided unprecedented opportunities to estimate the concentrations of N-bearing
105 components (Chen et al., 2019b; Zhan et al., 2018b). It was well known that the machine-learning
106 models generally showed the better predictive accuracy than CTMs and traditional statistical models
107 when the training samples were sufficient (Zang et al., 2019; Zhan et al., 2017). Zhan et al. (2018b)
108 employed random forest (RF) coupled with spatiotemporal Kriging model to simulate the ambient
109 NO_2 levels over China, and achieved the moderate modelling performance ($R^2 = 0.62$). Afterwards,
110 Chen et al. (2019) used the extreme gradient boosting (XGBoost) model combined with kriging-
111 calibrated satellite method to estimate the national NO_2 concentration and significantly improved

112 the predictive performance ($R^2 = 0.85$). Up to date, no study utilized the machine-learning models
113 to significantly improve the predictive accuracy of NO_3^- concentration. Moreover, nearly all of the
114 current studies only focused on the spatial pattern of particulate NO_3^- level in China (Liu et al., 2017;
115 Jia et al., 2016), while they cannot establish a long-term NO_3^- dataset across China.

116 Here, we firstly developed a high-resolution (0.25°) monthly particulate NO_3^- dataset across
117 China during 2005-2015 based an ensemble model including RF, XGBoost, and gradient boosting
118 decision tree (GBDT) algorithms. At first, the modelling performance and improvement of this new-
119 developed product compared with previous datasets were evaluated. Afterwards, we analyzed the
120 spatial variation and long-term evolution trend of estimated NO_3^- concentration over China and
121 explored the potential impacts of air pollution control measures on NO_3^- variation. The long-term
122 NO_3^- datasets could supply scientific judge for policy makers to mitigate the severe nitrate pollution
123 in China.

124 **2. Input data**

125 2.1 Ground-level NO_3^- data

126 The monthly NO_3^- monitoring data during 2010-2015 were collected from nationwide nitrogen
127 deposition monitoring network (NNDMN) including 32 sites (Fig. 1, Fig. S1, and Fig. S2), and
128 these sites could be divided into three types including urban, rural, and background sites (Xu et al.,
129 2018a). Ambient concentrations of particulate NO_3^- were determined on the basis of an active
130 DENuder for Long-Term Atmospheric sampling system (DELTA). The system comprises of a pump,
131 a filter sampling instrument, and a dry gas meter with high sensitivity. Two set of filters in a 2-stage
132 filter pack was applied to sample the aerosol particles, with a first K_2CO_3 /glycerol impregnated filter
133 to obtain NO_3^- particles in PM_{10} . All of the monitoring sites kept the same sampling frequency at

134 the month scale, and these samples were continuously collected over a month. The detailed sampling
135 and analysis procedures have been described by Xu et al. (2018a) and Xu et al. (2019). The detection
136 limit of particulate NO_3^- concentration over China is 0.01 mg N/L.

137 2.2 Satellite product of NO_2 column density

138 The OMI- NO_2 level-3 tropospheric column densities (0.25° resolution) were used to predict the
139 NO_3^- concentration (Fig. S3). The OMI aboard on the Aura satellite was available since September,
140 2004, which displayed global coverage and crossed the entire earth each day. OMI possessed three
141 spectral channels ranging from 270 to 500 nm, and thus was often applied to monitor the gaseous
142 pollutants such as NO_2 , SO_2 , and O_3 .

143 In this study, we downloaded the daily NO_2 columns during 2005-2015 from
144 <https://earthdata.nasa.gov/>. The tropospheric NO_2 column density data of poor quality (e.g., cloud
145 radiance fraction > 0.5 , solar zenith angles $> 85^\circ$, and terrain reflectivity $> 30\%$) should be removed.
146 Additionally, the cross-track pixels sensitive to significant row anomaly also must be deleted.
147 Finally, the monthly NO_2 columns were estimated by averaging the daily NO_2 columns.

148 2.3 Meteorological factors, land use types, and other variables

149 These independent variables for particulate NO_3^- estimates were gained from multiple sources.
150 The meteorological data on a daily basis (European Centre for Medium-Range Weather Forecasts
151 reanalysis (ECMWF ERA-Interim) datasets (0.25° resolution)) were downloaded from the website
152 of <http://www.ecmwf.int/> (Table S1). Among all of the daily meteorological data in ECMWF
153 website, 2-m temperature (T_{2m}), 2-m dewpoint temperature (D_{2m}), 10-m latitudinal wind component
154 (U_{10}), 10-m meridional wind component (V_{10}), sunshine duration (Sund), surface pressure (Sp),
155 boundary layer height (BLH), and total precipitation (Tp) were applied to estimate national NO_3^-

156 levels. The elevation, gross domestic production (GDP), and population density (PD) data over
157 China were downloaded from the website of <http://www.resdc.cn/>. PD and GDP in 1995, 2000, 2005,
158 2010, and 2015 were linearly interpolated to calculate PD and GDP in each year. Then, the yearly
159 GDP data were divided by 12 to estimate the monthly GDP. Afterwards, these data were
160 incorporated into the sub-model to predict the particulate NO_3^- concentration over China. In addition,
161 the land use data (e.g., grassland, forest, urban, and agricultural land) were also downloaded from
162 the website of <http://www.resdc.cn/>.

163 These independent variables collected from various sources were uniformly resampled to 0.25°
164 $\times 0.25^\circ$ grids. For instance, the land use area, GDP, and PD in 0.25° grid was calculated based on
165 area-weighted average algorithm. To ensure the better predictive performance, it was necessary to
166 employ the appropriate variable selection method to remove some redundant predictors. The basic
167 principle of the variable choice was to remove the variables with the lower importance values. The
168 variables could be regarded as the redundant ones when the R^2 value of the final model showed
169 dramatic decrease after removing them. Based on this method, in the final sub-model, all of the
170 variables except GDP, PD, and grassland have been applied to estimate the ambient NO_3^-
171 concentrations across China.

172 **3. Methods**

173 3.1 Ensemble model development

174 In the previous studies concerning about air pollution prediction, RF, gradient boosting decision
175 tree (GBDT), and extreme gradient boosting (XGBoost) showed good predictive performance (Li
176 et al., 2020a). RF model possesses a large amount of decision trees, and each one suffered from an
177 independent sampling process and these trees displayed the same distribution (Breiman, 2001). This

178 model generally shows the higher prediction accuracy due to the injected randomness. The model
 179 performance mainly relies on the number of trees, the variable group, and the splitting features. The
 180 detailed algorithms are shown as follows:

$$181 \quad f(x) = \sum_{z=1}^Z c_z I(x \in M_z) \quad (1)$$

$$182 \quad c_z = \overset{\Delta}{\text{mean}}(y_i | x_i \in M_z) \quad (2)$$

$$183 \quad L_1(m, n) = \{X | X_j \leq n\} \& L_2(m, n) = \{X | X_j > n\} \quad (3)$$

$$184 \quad \min_{m, n} \left[\min_{M_1(m, n)} \sum (y - c_1)^2 + \min_{M_2(m, n)} \sum (y - c_2)^2 \right] \quad (4)$$

$$185 \quad c_1 = \overset{\Delta}{\text{mean}}(y_i | x_i \in M_1(m, n)) \& c_2 = \overset{\Delta}{\text{mean}}(y_i | x_i \in M_2(m, n)) \quad (5)$$

186 where (x_i, y_i) denotes the sample for $i = 1, 2, \dots, N$ in M regions (M_1, M_2, \dots, M_Z) ; I denotes the
 187 weight of each branch; L denotes the branch of decision tree; c_m represents the response to the model;
 188 c_z denotes the best value, m represents the feature variable; c_1 denotes the mean value of left
 189 branch; c_2 denotes the mean value of right branch; n is the split point.

190 GBDT model is often considered to be a typical boosting method. Compared with RF model,
 191 each classifier is applied to decrease the residual of the last round. The detailed equations are as
 192 follows:

$$193 \quad c_{ij} = \arg \min_{x_i \in R_{t_j}} \sum L(y_i, f_{t-1}(x_i) + c) \quad (6)$$

$$194 \quad f_t(x) = f_{t-1}(x) + \sum_{j=1}^J c_{tj} I \quad (7)$$

195 c_{ij} denotes the predicted the estimation error in the last round; R_{ij} denotes each leaf node for the
 196 decision trees; y_i represents the observed value; $f_{t-1}(x_i)$ is the predicted value in the last round. c was
 197 regarded as the optimal value when c_{ij} reaches the least value.

198 XGBoost method is an updated version of GBDT model and loss functions are expanded to the
 199 second order function. On the basis of the pioneering studies (Chen et al., 2019a), XGBoost
 200 generally shows excellent performance because of its high efficiency and impressive accuracy. The
 201 detailed XGBoost algorithm is shown as the following formula (Zhai and Chen, 2018):

$$202 \quad L^{(t)} = \sum_{i=1}^n [l(y_i, y^{\Lambda(t-1)}) + \partial_{y^{(t-1)}} l(y_i, y^{\Lambda(t-1)}) f_t(x_i) + \frac{1}{2} \partial_{y^{(t-1)}}^2 l(y_i, y^{\Lambda(t-1)}) f_t^2(x_i)] + \Omega(f_t) \quad (8)$$

203 where $L^{(t)}$ represents the cost function at the t-th period; ∂ denotes the derivative of the function;
 204 $\partial_{y^{(t-1)}}^2$ denotes the second derivative of the function; l is the differentiable convex loss function that
 205 reveals the difference of the predicted value (y^{Λ}) of the i-th instance at the t-th period and the target
 206 value (y_i); $f_t(x)$ denotes the increment; $\Omega(f_t)$ represents the regularizer.

207 However, each model still shows some disadvantages in the prediction accuracy. Consequently,
 208 it was proposed to combine these models with multiple linear regression (MLR) model to further
 209 estimate monthly NO_3^- concentration in the atmosphere over China. As shown in Fig. 2, three
 210 submodels including RF, GBDT, and XGBoost were stacked through MLR model to estimate the
 211 monthly NO_3^- concentration over China. At first, a 5-fold cross-validation method was adopted to
 212 train each submodel to determine the appropriate parameter. Afterwards, the MLR model was
 213 trained with the final simulated concentrations of three submodels and observations. Finally, the
 214 high-resolution ambient NO_3^- level over China were estimated based on the optimal ensemble model.
 215 The detailed algorithms are shown as follows (Fig. 2):

$$216 \quad \text{NO}_3^- = A \times \text{Pred_RF} + B \times \text{Pred_GBDT} + C \times \text{Pred_XGBoost} + e_{ij} \quad (9)$$

217 where Pred_RF , Pred_GBDT , and Pred_XGBoost denote the predicted NO_3^- concentrations by RF,
 218 GBDT, and XGBoost, respectively. A, B, and C represent the partial regression coefficients of RF,
 219 GBDT, and XGBoost predictors, respectively. e_{ij} denotes the residual error. Based on the estimates,

220 the regression coefficients including A, B, C, and the residual error (e_{ij}) determined by the MLR
221 model were 0.42, 0.77, 0.09, and -0.87, respectively. The variance inflation factors of RF (2.01),
222 GBDT (2.69), and XGBoost (2.08) were significantly lower than 10, which suggested the MLR
223 model was robust.

224 The RF model was trained using matlab2019a with a package named random forest-master. Both
225 of GBDT and XGBoost algorithms were conducted using many packages named *gbm*, *caret*, and
226 *xgboost* in R software.

227 3.2 The error estimation and uncertainty assessment

228 The estimation performance of the ensemble model was evaluated based on 10-fold cross-
229 validation algorithm. The principle of this method meant that the entire datasets were divided into
230 10 groups with the same capacity randomly. Nine groups were applied to develop the model and the
231 remained one was used to predict the NO_3^- level. After ten rounds, every observed NO_3^-
232 concentration showed a corresponding predicted value. Some key indices such as determination
233 coefficient (R^2), root mean square error (RMSE), and mean absolute prediction error (MAE) were
234 selected as the key indicators to identify the optimal modelling method.

235 The uncertainty of ensemble model were mainly derived from input ancillary variables. For
236 instance, both of the satellite data and meteorological data often suffered from some uncertainties.
237 To quantify the uncertainties derived from meteorological data, the meteorological data at 0.25°
238 across China were validated using ground-measured meteorological data downloaded from the
239 website of Chinese Meteorology Bureau (<http://data.cma.cn/>). Additionally, NO_2 columns generally
240 suffered from some uncertainties, whereas the uncertainties of these NO_2 columns cannot be
241 determined because the data about the ground-level NO_2 columns were not open access. In our study,

242 we only estimated the missing ratio of NO₂ column, thereby evaluating the uncertainty of NO₃⁻
243 dataset.

244 3.3 Trend analysis

245 The trend analysis of particulate NO₃⁻ concentration was performed using the Mann-Kendall
246 nonparametric test. This method has been widely applied to analyze the historical trends of carbon
247 fluxes (Tang et al., 2019) and air quality (Kong et al., 2019), which could reflect whether these data
248 suffered from significant changes at a significance level of 0.05. The detailed calculation process is
249 summarized in Mann (1945) and Kendall (1975).

250 4. Results and discussion

251 4.1 Descriptive statistics of observed NO₃⁻ concentrations

252 The ensemble model were applied to fit the NO₃⁻ estimation model based on 1636 matched
253 samples across China during 2010-2015. In general, the ground-observed NO₃⁻ concentration over
254 China ranged from 0.3 μg N m⁻³ in Bayinbrook of Xinjiang province to 7.1 μg N m⁻³ in Zhengzhou
255 of Henan province with the mean value of 2.7 ± 1.7 μg N m⁻³. The monthly particulate NO₃⁻
256 concentrations displayed the highest and lowest values in North China Plain (NCP) and Tibetan
257 Plateau, respectively. Besides, the monthly NO₃⁻ level exhibited significantly temporal variation
258 during 2010-2015. The ambient NO₃⁻ concentrations in most of sites displayed the gradual increase
259 during 2010-2014, while they decreased sharply from 2014 to 2015. The spatiotemporal variation
260 of ambient NO₃⁻ concentration over China shared similar characteristic with NO₂ column amount
261 (Fig. S3). The Pearson correlation analysis revealed that the monthly particulate NO₃⁻ level showed
262 the significantly positive relationship with NO₂ column amount ($r = 0.57$, $p < 0.01$) and urban land
263 area ($r = 0.35$, $p < 0.05$) (Fig. S4). However, D_{2m} showed the remarkably negative correlation with

264 ambient NO_3^- concentration ($r = -0.31$, $p < 0.05$).

265 4.2 The validation of new-developed NO_3^- dataset and comparison with previous products

266 In our study, the ensemble model was applied to develop a monthly particulate NO_3^- dataset over
267 China based on various predictors. Besides, other three individual models were also trained to
268 compare with their predictive performances. The cross-validation result indicated that the R^2 value
269 of the new product developed by ensemble decision trees model reached 0.78, significantly higher
270 than those developed by RF (0.57), GBDT (0.73), and XGBoost (0.45). Nonetheless, both of RMSE
271 and MAE exhibited the opposite trends. The RMSE value was in the order of XGBoost ($1.98 \mu\text{g N}$
272 m^{-3}) > RF ($1.67 \mu\text{g N m}^{-3}$) > GBDT ($1.35 \mu\text{g N m}^{-3}$) > ensemble model ($1.19 \mu\text{g N m}^{-3}$). The MAE
273 value followed the similar characteristic with the order of XGBoost ($1.29 \mu\text{g N m}^{-3}$) > RF ($0.99 \mu\text{g}$
274 N m^{-3}) > GBDT ($0.95 \mu\text{g N m}^{-3}$) > ensemble model ($0.81 \mu\text{g N m}^{-3}$). In some previous studies (Xiao
275 et al., 2018), XGBoost often showed the better performance compared with RF, which seemed to
276 be in contrast to our study. It was assumed that XGBoost showed the better performance for big-
277 data samples. However, the size of training samples in our study was relatively less than those in
278 previous studies. Xiao et al. (2018) also verified that the XGBoost showed the better accuracy than
279 RF in some developed regions such as East China, while RF showed the better performance than
280 XGBoost in Northwest China because the monitoring sites in Northwest China was relatively scarce.
281 Wolpert (1992) suggested the combination of various machine-learning models can significantly
282 strengthen the transferability of models. Chen et al. (2019a) demonstrated that the ensemble model
283 significantly outperformed the individual machine-learning model because the ensemble model can
284 overcome the weaknesses of individual model. Besides, we also assessed the annual modelling
285 performance of NO_3^- estimation. Figure S5 shows that the R^2 value of annual NO_3^- estimation

286 reached 0.81, slightly higher than monthly NO_3^- prediction (0.78). However, both of RMSE (1.23
287 $\mu\text{g N m}^{-3}$) and MAE (0.85 $\mu\text{g N m}^{-3}$) for annual NO_3^- estimation were slightly higher than those of
288 monthly NO_3^- prediction.

289 The new developed NO_3^- dataset showed the markedly temporal discrepancy. The R^2 values of
290 NO_3^- estimates during 2011-2015 (0.88, 0.89, 0.83, 0.74, and 0.78) were notably higher than that
291 during 2010 (0.62) (Table 1 and Fig. 3). The relatively lower R^2 value in 2010 attested to the
292 dominant role of sampling size on the predictive accuracy for machine-learning models. The training
293 samples in 2010 (135 samples) were notably less than those in other years due to the lack of
294 observation data in spring. However, both of RMSE and MAE were not sensitive to the sampling
295 size. The higher RMSE and MAE focused on the 2010, 2014, and 2015. The higher RMSE and
296 MAE observed in 2010 might be contributed by the relatively scarce training samples, while the
297 higher RMSE and MAE likely attained to the higher NO_3^- levels during other years. In addition, the
298 performance of the NO_3^- dataset varied greatly at the seasonal scale. The R^2 value was in the order
299 of summer (0.85) > spring (0.80) = autumn (0.80) > winter (0.75) across China (Table 2). The
300 seasonal variation of NO_3^- concentration was in contrast to the results of fine particle modelled by
301 previous studies (Li et al., 2020a; Qin et al., 2018). It was supposed that aerosol optical depth (AOD)
302 was sensitive to the precipitation and relative humidity, and thus showed the worse performance in
303 summer. However, the predictive accuracy of NO_3^- estimation based on NO_2 column amount was
304 closely linked with the chemical transformation from NO_2 to NO_3^- .

305 The performance of NO_3^- dataset also displayed markedly spatial variation. The highest R^2 value
306 was observed in NCP (0.70), followed by Southwest China (0.60), Southeast China (0.59),
307 Northwest China (0.55), and the lowest one in Northeast China (0.44) (Table 3). The highest R^2

308 value occurring in NCP was mainly attributable to the largest training samples (> 400) compared
309 with other regions. Southeast China and Southwest China showed satisfactory cross-validation R²
310 values because the valid training samples in both of these regions were higher than 300. Although
311 both of Northeast China and Northwest China possessed limited training samples (< 200), the
312 predictive performances of these regions showed significant discrepancy. It was assumed that the
313 sampling sites in Northeast China were very centralized, while the sampling sites in Northwest
314 China were uniformly distributed across the whole region. Geng et al. (2018) revealed that the
315 modelling accuracy based on statistical models were significantly affected by the distribution
316 characteristics of sampling sites. However, both of RMSE and MAE showed different spatial
317 distributions with the R² value and slope of fitting curve. Note that the higher values of RMSE and
318 MAE were concentrated on Southwest China (2.08 and 1.41 $\mu\text{g N m}^{-3}$) and Northwest China (2.06
319 and 1.38 $\mu\text{g N m}^{-3}$) rather than NCP (1.74 and 1.06 $\mu\text{g N m}^{-3}$). There are two reasons responsible for
320 the result. At first, the predictive performances of Southwest China and Northwest China were
321 significantly worse than that of NCP, thereby leading to the higher RMSE and MAE. Moreover,
322 most of the sampling sites in Southwest China were focused on Sichuan Basin, which often showed
323 severe NO₃⁻ pollution all the year round. Meanwhile, the annual mean NO₃⁻ concentrations in
324 Yangling and Wuwei reached 4.1 and 4.5 $\mu\text{g N m}^{-3}$, respectively. The higher loadings of NO₃⁻
325 concentrations for training samples led to the higher RMSE and MAE for Northwest China.

326 Although the cross-validation result suggested the new developed dataset achieved the better
327 modelling accuracy, the cross-validation algorithm cannot test the transferability and agreement of
328 this dataset in the past years. Hence, the unlearned data (annual mean NO₃⁻ concentration in 10 cities)
329 collected from previous references were employed to validate the transferability of this product. As

330 shown in Fig. 4 and Table S2, we found that the R^2 value of new-developed NO_3^- product and
331 historical data reached 0.85 (Fig. 4), and the out-of-range R^2 value was even slightly higher than the
332 cross-validation R^2 value. Moreover, the out-of-bag slope based on these unlearning data reached
333 0.81, and equaled to the slope of cross-validation database. In addition, the site-based cross-
334 validation was also applied to validate the transferability of this dataset. The basic principle is that
335 all of the sites were evenly classified into ten clusters based on the geographical locations.
336 Afterwards, nine of ten were used to train the model and then test the model based on the remained
337 one. After ten round, all of the observed values versus estimate values was considered to be the final
338 result to validate the spatial transferability of this model. As depicted in Fig. S6, the site-based cross-
339 validation R^2 value reached 0.73, which was slightly lower than the cross-validation R^2 value of the
340 training model (0.78). The result suggested the new-developed dataset showed excellent
341 performance in the past decade.

342 Owing to the severe air pollution issue frequently observed in recent years, especially nitrogen-
343 bearing haze events, many studies have tried to predict the NO_3^- concentrations in China. Most of
344 these studies employed CTMs to simulate the ambient NO_3^- concentrations over China. Huang et al.
345 (2015) employed WRF-CMAQ to estimate the inorganic nitrogen deposition over PRD, and
346 confirmed that the R value only reached 0.54. Afterwards, Han et al. (2017) used RAMS-GMAQ to
347 predict the dry deposition flux of reactive nitrogen, and significantly underestimated the NO_3^-
348 concentration in the atmosphere. Very recently, Geng et al. (2019) used CMAQ to estimate the NO_3^-
349 concentrations over East China, and the predictive performance ($R = 0.53$) showed the similar result
350 to Huang et al. (2015). Apart from these CTMs, the statistical models also has been applied to
351 estimate the ambient NO_3^- concentration over China. Unfortunately, the predictive accuracy was not

352 good based on traditional statistical models (e.g., linear regression) ($R = 0.47$) (Jia et al., 2016). In
353 terms of model performance, the developed NO_3^- product in our study was much better than those
354 developed by pioneering studies. Furthermore, this product showed many extra advantages than
355 those obtained by CTMs especially for the estimates of air pollutants. For instance, CTMs generally
356 required continuous emission inventory data, which were often not available and showed high
357 uncertainties. Moreover, CTMs generally needed substantial computing time and big-data input data
358 to ensure the reliable predictive accuracy. Thus, the NO_3^- product retrieved by CTMs often lacks of
359 long-term dataset (> 10 yr), and our study fills the gaps of previous studies.

360 4.3 Spatial pattern of new-developed NO_3^- dataset

361 The monthly NO_3^- concentration displayed the similar distribution characteristic with $\text{PM}_{2.5}$ and
362 PM_1 (Wei et al., 2019). Overall, the NO_3^- concentration in East China was much higher than that in
363 West China. The higher NO_3^- concentration was concentrated on NCP ($3.55 \pm 1.25 \mu\text{g N m}^{-3}$),
364 followed by Yangtze River Delta (YRD ($2.56 \pm 1.12 \mu\text{g N m}^{-3}$)), Pearl River Delta (PRD ($1.68 \pm$
365 $0.81 \mu\text{g N m}^{-3}$)), Sichuan Basin ($1.53 \pm 0.63 \mu\text{g N m}^{-3}$), and the lowest one observed in Tibetan
366 Plateau ($0.42 \pm 0.25 \mu\text{g N m}^{-3}$) (Fig. 5). Most provinces over NCP such as Beijing, Hebei, Henan,
367 and Shandong suffered from severe NO_3^- pollution due to dense human activities and strong industry
368 foundation (Li et al., 2017) (Fig. S7), which released a large amount of N-bearing gaseous pollutants
369 to the atmosphere especially in winter. In BTH ($2.97 \pm 1.97 \mu\text{g N m}^{-3}$), Wang et al. (2016) verified
370 that these fresh NO_x emitted from power plants or cement industries could be transformed into the
371 nitrate in the particulate phase by the aid of low air temperature. In YRD and PRD, the combustion
372 of fossil fuels and traffic emissions were considered to be the major source of NO_x emission, which
373 favored to the formation of nitrate event through the gas-particle conversion processes (Fu et al.,

374 2017; Kong et al., 2020; Ming et al., 2017). Apart from the contributions of smelting industries, the
375 poor topographical or meteorological conditions were also responsible for the severe NO_3^- pollution
376 in Sichuan Basin (Tian et al., 2017; Wang et al., 2017). Tibetan Plateau generally showed the clean
377 air quality due to the unique landform and scarce industrial activity (Yang et al., 2018). In addition,
378 it was interesting to note that the Altai region and Taklimakan desert in Xinjiang autonomous region
379 also showed some NO_3^- hotspots, though these regions were often believed to be the remote region.
380 It was assumed that the many petrochemical industries (e.g., Karamai oil field) were located in the
381 Altai region (Liu et al., 2018). Besides, Qi et al. (2018) verified that the resuspension of soil dust
382 might trigger the accumulation of NO_3^- concentration in the aerosol.

383 4.4 Long-term trend of ambient NO_3^- across China

384 The temporal variation of NO_3^- levels from 2005 to 2015 over China has been clarified in Fig.
385 6, Fig. 7 and Table S3. Overall, the ambient NO_3^- concentration in China showed the significant
386 increasing trend of $0.10 \mu\text{g N m}^{-3}/\text{year}$ during 2005-2014, while it decreased sharply from 2014 to
387 2015 by $-0.40 \mu\text{g N m}^{-3}/\text{year}$. Overall, more than 90% areas of Mainland China showed consistent
388 temporal variation with the gradual increase from 2005 to 2013/2014, and then rapid decrease from
389 2013/2014 to 2015. However, the decreasing/increasing speed displayed significantly spatial
390 difference in some major regions of China. For instance, the ambient NO_3^- level in BTH showed the
391 remarkable increase during 2005-2013 by $0.20 \mu\text{g N m}^{-3}/\text{year}$. Afterwards, the NO_3^- level decreased
392 rapidly from 2013 to 2015 at a rate of $-0.58 \mu\text{g N m}^{-3}/\text{year}$. The NO_3^- concentrations in YRD (0.11
393 $\mu\text{g N m}^{-3}/\text{year}$) and PRD ($0.05 \mu\text{g N m}^{-3}/\text{year}$) both showed the slight increases during 2005-2013,
394 though the statistical test revealed the increases were significant ($p < 0.05$). However, the NO_3^-
395 concentrations in YRD and PRD showed the dramatic decreases with -0.48 and $-0.36 \mu\text{g N m}^{-3}/\text{year}$

396 during 2013-2015, respectively. As seen from 2005 to 2015, the NO_3^- concentration in BTH
397 displayed the slight increase during this period. Nevertheless, the NO_3^- levels in YRD and PRD both
398 displayed the slow decreases by -0.01 and $-0.03 \mu\text{g N m}^{-3}/\text{year}$, respectively.

399 Furthermore, the different provinces displayed disparate temporal variations especially during
400 11th five year plan (2005-2010). 31 provinces (municipalities/autonomous region) of China can be
401 classified into three clusters based on the temporal trends of NO_3^- concentrations during 11th five
402 year plan. The first cluster featured the gradual increase of NO_3^- concentration during this period,
403 which consisted of three provinces in Northeast China (e.g., Heilongjiang) and central provinces in
404 South China (e.g., Jiangxi, Anhui) (Table S3). The second cluster represented the provinces with the
405 stable increases of NO_3^- during 2005-2007 and slight decreases during 2007-2010. Some provinces
406 of NCP (e.g., Beijing, Hebei, Henan) and Northwest China (e.g., Gansu, Inner Mongolia, Ningxia)
407 fell into the second cluster. The last cluster featured the opposite temporal trend to the second cluster
408 during 2005-2010, which included many southern provinces such as Fujian, Guangdong, Zhejiang,
409 and Guangxi. Although the central government proposed the emission reduction goal in 2006, the
410 ambient NO_3^- concentrations in most provinces did not display pronounced decreases, which was
411 totally different from the decrease of $\text{PM}_{2.5}$ since 2007 (Xue et al., 2019). Especially in the provinces
412 of Northeast China (e.g., Liaoning), the ambient NO_3^- concentrations in these provinces still showed
413 the rapid increases after the proposal of emission control measures. It was assumed that these
414 provinces generally possessed a large amount of energy-intensive industries and coal-fired power
415 plants (Zhang et al., 2018). Moreover, the result might be associated with the fact that the emission
416 reduction measures focused on the reduction of SO_2 emission rather than NO_x emission (Kanada et
417 al., 2013). Schreifels et al. (2012) revealed that major control measures during this period included

418 shutting down inefficient industries, increasing the pollution levy for excessive SO₂ emissions, and
419 implementing energy conservation projects. Therefore, the total SO₂ emission in 2010 decreased by
420 more than 14% compared with the emission in 1995 and the ambient SO₂ concentrations in many
421 provinces since 2005 displayed significant decreases compared with those in 1990s (Li et al., 2020b;
422 Lu et al., 2013; Zhou et al., 2015). Nonetheless, the NO_x emission in China did not display
423 significant decrease during this period (Duncan et al., 2016; Granier et al., 2017), and thus the
424 ambient NO₃⁻ in many provinces still kept the higher concentrations. It should be noted that the
425 NO₃⁻ concentrations in some provinces of NCP exactly exhibited the slow decreases after 2007. It
426 was supposed that the energy structure adjustment and elimination of backward production capacity
427 promoted the small decrease of NO₃⁻ concentrations (Ma et al., 2019). Unfortunately, the slight
428 decreases were quickly offset by the rapid increase of energy consumption. Zhang et al. (2018)
429 demonstrated that the industry added values and private car number in BTH have been increasing
430 by 189.4% and 279.6% during 2005-2010, respectively. In addition, the decrease of SO₂ emission
431 rather than NO_x emission can further lead to NO₃⁻ increase because of decreased aerosol acidity,
432 which was dictated by SO₄²⁻ in particulate matter (Xie et al., 2020; Vasilakos et al., 2018).

433 Since 2010, the central government began to implement severe limitations in PM_{2.5}, NO_x, and
434 soot emissions, and thus the total NO_x emission during 11th five year plan (2011-2015) showed
435 slow decrease (10%) across China (Ma et al., 2019). However, the NO₃⁻ concentrations across China
436 did not show rapid response to the emission control measures. For instance, the NO₃⁻ concentrations
437 in most provinces of China still showed rapid increases during 2010-2013 (2014) (Fig. 7 and Fig.
438 8). The result suggested that the control measures about the NO_x emissions from vehicles and ships
439 might be not very effective. Until 2013, the central government issued Action Plan for Air Pollution

440 Prevention and Control (APPC-AP) in order to enhance the air pollution prevention measures (Li et
441 al., 2017; Li et al., 2019). Many powerful economic and policy means including pricing (tax) policy
442 and optimization of industrial layout caused the rapid decreases of NO_3^- concentrations after 2013
443 in many provinces (e.g., Beijing, Hebei, Zhejiang). Wang et al. (2019b) also verified that the NO_3^-
444 level in $\text{PM}_{2.5}$ over BTH has decreased by 20% during 2013-2015, which was in accordance with
445 the finding of our study. In addition to the impact of emission reduction, the rapid decrease of NO_3^-
446 concentration over China after 2013 might be linked with the beneficial meteorological factors
447 because Chen et al. (2019c) has demonstrated that favorable meteorological conditions led to about
448 20% of the $\text{PM}_{2.5}$ decrease in BTH during 2013-2015. However, the decreasing trend of NO_3^-
449 concentration during 2014-2015 in PRD ($-0.36 \mu\text{g N m}^{-3}/\text{year}$) was significantly slower than that in
450 BTH ($-0.58 \mu\text{g N m}^{-3}/\text{year}$) and YRD ($-0.48 \mu\text{g N m}^{-3}/\text{year}$) (Table 4). Wang et al. (2019b) found
451 that the ambient NO_3^- concentration in a background site of PRD even showed an upward trend
452 during 2014-2016. Thus, it was necessary to strengthen the control of nitrogen oxide emissions.

453 In general, the ambient NO_3^- concentration varied greatly at the seasonal scale (Fig. 9). China
454 undergone the most serious NO_3^- pollution in winter ($1.57 \pm 0.63 \mu\text{g N m}^{-3}$), followed by autumn
455 ($1.09 \pm 0.52 \mu\text{g N m}^{-3}$), spring ($0.78 \pm 0.50 \mu\text{g N m}^{-3}$), and the lowest one in summer (0.63 ± 0.40
456 $\mu\text{g N m}^{-3}$) (Table S4). The higher NO_3^- concentration observed in winter might be contributed by
457 the dense coal combustion in North China and unfavorable meteorological conditions (Itahashi et
458 al., 2017; Quan et al., 2014; Wang et al., 2019d). The lightest NO_3^- pollution in summer was
459 attributable to the abundant precipitation, which promoted the diffusion and removal of pollutants
460 and reduced ambient NO_3^- level (Hu et al., 2005). The ratio of NO_3^- concentration in winter (NO_3^-
461 $_{\text{winter}}$) and that in summer (NO_3^- $_{\text{summer}}$) varied greatly at the spatial scale. The NO_3^- $_{\text{winter}}/\text{NO}_3^-$ $_{\text{summer}}$

462 in some provinces (municipalities) including Tianjin (2.11), Hebei (2.25), and Henan (2.84)
463 displayed the higher values compared with other provinces. The higher NO_3^- winter/ NO_3^- summer in NCP
464 might be affected by the fossil fuel combustion for domestic heating, while some southern provinces
465 did not need domestic heating in winter. In contrast, the ratio of NO_3^- winter/ NO_3^- summer exhibited the
466 lower values in some western provinces such as Tibet and Qinghai. It might be probably associated
467 with the less aerosol emission from anthropogenic source and the higher wind speed (Wei et al.,
468 2019).

469 4.5 Uncertainty analysis of NO_3^- estimation

470 The ensemble model of three machine-learning algorithms captured the better accuracy in
471 predicting the NO_3^- level from OMI data. Nonetheless, the ensemble model still showed some
472 improvement space in terms of the R^2 value. At first, meteorological data collected from reanalysis
473 in ECMWF website generally showed high uncertainty, which inevitably increased the error of NO_3^-
474 estimation. In our study, we validated the gridded T_{2m} and T_p datasets against the ground-observed
475 datasets and found that the R^2 values of T_{2m} and T_p reached 0.98 and 0.83 (Table S5), respectively.
476 The result suggested that T_{2m} showed the lower uncertainty, while T_p displayed relatively higher
477 uncertainty. Except T_{2m} and T_p , the ground-level datasets for other meteorological factors were not
478 open access, and thus we cannot assess their uncertainties. Thus, we only reviewed some references
479 and evaluated their uncertainties. For instance, Guo et al. 2019 found that the reanalysis BLH data
480 also exhibited large uncertainties because few sounding data were assimilated. These uncertainties
481 derived from predictors could be passed to the ensemble model, and thus increased the uncertainties
482 of ambient NO_3^- estimates.

483 The second reason was closely linked to the missing NO_2 column amount across China. The

484 NO₂ column amount retrieval showed many nonrandom biases especially for the arid or semi-arid
485 area with high surface reflectance. The missing NO₂ column amounts over China were not filled in
486 our study due to the increased uncertainty of filling NO₂ column. Moreover, it should be noted that
487 the monthly NO₂ column amounts were averaged based on the daily one, and the missing ratio of
488 daily NO₂ columns during 2005-2015 reached 57.64%, the higher missing ratio might increase the
489 uncertainty of NO₃⁻ simulation.

490 Lastly, the developed ensemble model did not integrate the direct spatiotemporal weight
491 indicators (e.g., the distance of observed sites and contiguous grids) though many predictors (e.g.,
492 month of year) reflecting spatiotemporal autocorrelation were input into the original model as the
493 key predictors. Furthermore, the developed model was the ensemble one of three original models,
494 which ignored the spatiotemporal autocorrelation of estimation residues from first-stage model. In
495 the future work, the ensemble model could be combined with a space-time model to further enhance
496 the modelling performance.

497 **5. Data availability**

498 The monthly NO₃⁻ datasets at 0.25° resolution across China during 2005-2015 are available at
499 <https://doi.org/10.5281/zenodo.3988307> (Li et al., 2020), which can be downloaded in xlsx format.

500 The missing values are shown in NaN.

501 **6. Conclusions and implications**

502 In this study, RF, GBDT, and XGBoost algorithms were combined to establish a high-resolution
503 (0.25°) NO₃⁻ dataset over China during 2005-2015 on the basis of multi-source predictors. The NO₃⁻
504 product showed high cross-validation R² value (0.78), but low RMSE (1.19 μg N m⁻³) and MAE
505 (0.81 μg N m⁻³). The NO₃⁻ dataset showed the markedly spatiotemporal discrepancy. The R² value

506 was in the order of summer (0.85) > spring (0.80) = autumn (0.80) > winter (0.75) across China,
507 and the R^2 showed the highest value in NCP. In addition, the dataset exhibited excellent
508 transferability ($R^2 = 0.85$, $RMSE = 0.74 \mu\text{g N m}^{-3}$, and $MAE = 0.55 \mu\text{g N m}^{-3}$) on the basis of the
509 unlearning observed data in ten sites.

510 The new-developed NO_3^- dataset showed remarkably predictive accuracy compared with
511 previous products developed by CTMs and linear regression model. The result might be linked to
512 two key reasons. First of all, the new product assimilated high-resolution NO_2 column amount
513 instead of the NO_x emission inventory used by CTMs. The imperfect knowledge about the chemical
514 modules with regard of the NO_3^- formation and the inaccurate emission inventory decreased the
515 predictive performance of CTMs. In contrast, the new product was obtained using ensemble
516 machine-learning model, which did not need to consider the photochemical or aqueous process from
517 gaseous NO_2 to particulate NO_3^- . Compared with the NO_3^- product estimated by linear regression
518 model ($R^2 = 0.21$), the new product significantly elevated the modelling performance of NO_3^-
519 concentration. It was supposed that the ensemble model for the development of the new NO_3^- dataset
520 did not predefine the potential relationships between explanatory variables and NO_3^- level as the
521 multiple regression model, which must assume the linear linkage between dependent variable and
522 predictors before model establishment.

523 On the basis of the such dataset, the spatiotemporal variation of NO_3^- concentration over China
524 during 2005-2015 were clarified. The annual mean NO_3^- concentration followed the order of NCP
525 ($3.55 \pm 1.25 \mu\text{g N m}^{-3}$) > YRD ($2.56 \pm 1.12 \mu\text{g N m}^{-3}$) > PRD ($1.68 \pm 0.81 \mu\text{g N m}^{-3}$) > Sichuan
526 Basin ($1.53 \pm 0.63 \mu\text{g N m}^{-3}$) > Tibetan Plateau ($0.42 \pm 0.25 \mu\text{g N m}^{-3}$). The higher NO_3^-
527 concentrations in NCP, YRD, and PRD were mainly contributed by the intensive industrial and

528 traffic emissions. Sichuan Basin suffered serious NO_3^- pollution due to the high loadings of aerosols
529 and unfavorable terrain condition. Tibetan Plateau shared with the lightest NO_3^- pollution because
530 of the scarce anthropogenic emissions and favorable meteorological factors. Additionally, we also
531 found that the ambient NO_3^- concentration showed significant increasing trend of $0.10 \mu\text{g N m}^{-3}$
532 $^3/\text{year}$ during 2005-2014, while it decreased sharply from 2014 to 2015 at a rate of $-0.40 \mu\text{g N m}^{-3}$
533 $^3/\text{year}$. The ambient NO_3^- levels in BTH, YRD, and PRD displayed slight increases at the rate of
534 0.20, 0.11, and $0.05 \mu\text{g N m}^{-3}/\text{year}$ during 2013-2015, respectively. Afterwards, the NO_3^-
535 concentrations decreased sharply at the speed of -0.58 , -0.48 , and $-0.36 \mu\text{g N m}^{-3}/\text{year}$. Although
536 National Economic and Social Development of China has issued the emission reduction goal in
537 2006, the NO_3^- concentrations in most provinces did not show the significant decreases during 2005-
538 2010. It might be contributed by the increase of energy consumption and non-targeted emission
539 control measures. Since 2010, the government began to decrease the NO_x emission over China,
540 whereas the NO_3^- concentrations in many provinces still showed slight increases during 2010-2014
541 because the benefits of control measures for NO_x emission could be neutralized by elevated energy
542 consumption along with the rapid economic development. Since 2014, Chinese government issued
543 APPC-AP and further enhanced the emission control measures, and triggered the dramatic decrease
544 of NO_3^- concentration over China. Apart from the effect of emission reduction, the favorable
545 meteorological conditions might lead to the rapid decrease of NO_3^- level over China during 2014-
546 2015. Compared with the powerful emission control measures, meteorological factors only
547 contributed a small portion of NO_3^- reduction in China. Besides, the decrease speed of NO_3^- level
548 in China also displayed pronounced spatial heterogeneity and some background region even
549 featured the upward of air pollutant in recent years. Therefore, it is still imperative to strengthen the

550 emission reduction measures.

551 It must be acknowledged that our study still suffers from some limitations. First of all, the NO_3^-
552 dataset was developed by machine-learning models, which lacked of the chemical module
553 concerning about the transformation pathway from NO_2 to NO_3^- , and might underestimate the
554 ambient NO_3^- concentration across China. In the future work, the output results of CTMs including
555 conversion ratio from NO_2 to NO_3^- , dry/wet deposition flux of NO_2 and NO_3^- in the atmosphere
556 should be incorporated into the machine-learning model to develop next-generation NO_3^- product.
557 Second, the low time-resolution (monthly) observation data hindered the daily estimation of NO_3^-
558 concentration. The daily NO_3^- datasets are warranted in the future because it could be used to assess
559 the potential impact on human health. Besides, the ultrahigh-resolution satellite (TROPOMI) can
560 allow continuation and enhancement of the spatiotemporal NO_3^- estimation though the OMI product
561 could capture enough spatial variations across China.

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565 **Author contributions**

566 Rui Li, Lulu Cui, and Hongbo Fu conceived and designed the study. Rui Li, Lulu Cui, Yilong Zhao,
567 Wenhui Zhou collected and processed the data. Rui Li wrote this paper with contributions from all
568 of the coauthors.

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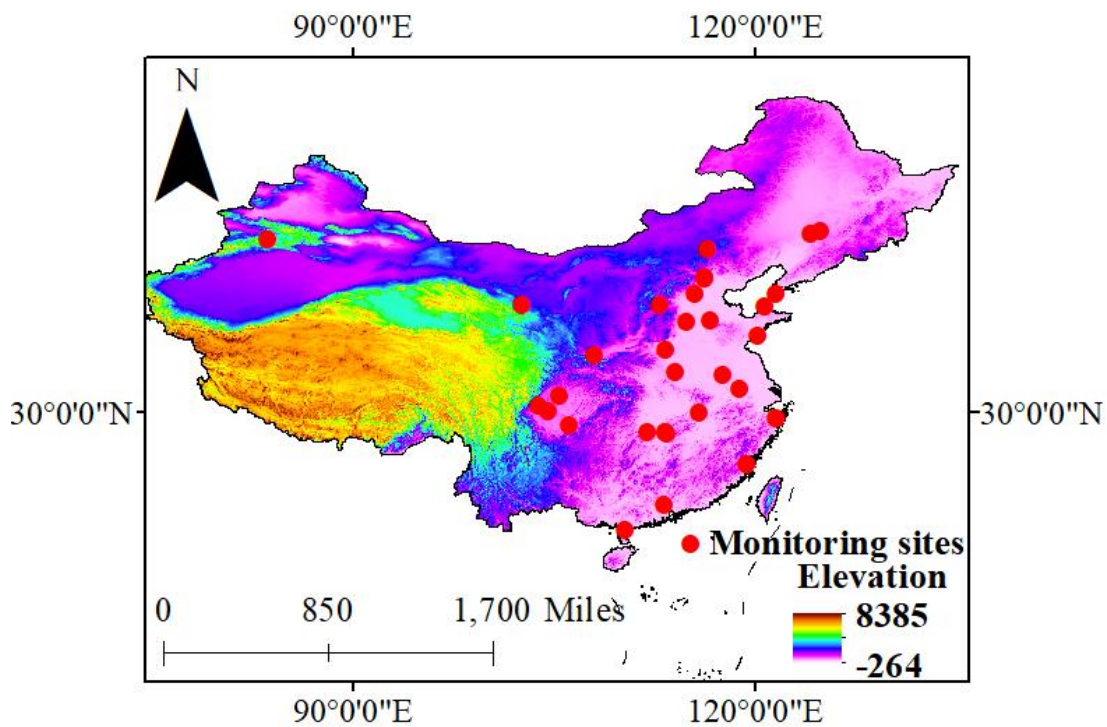
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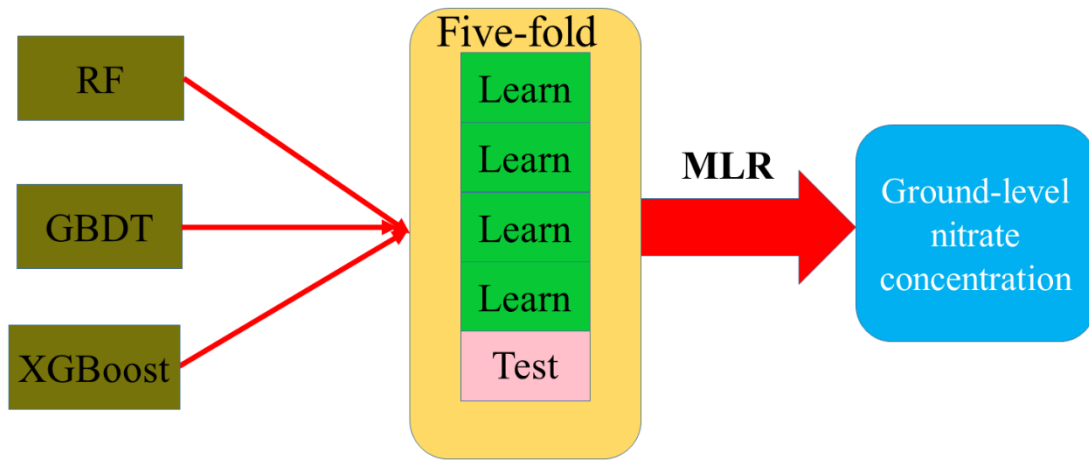
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781 **Fig. 1** Spatial distributions of ground-level NO_3^- monitoring sites used for model establishment. Red
782 circles represent the ground-level sites during 2010-2015. The colormap denotes the elevation
783 distribution across China.



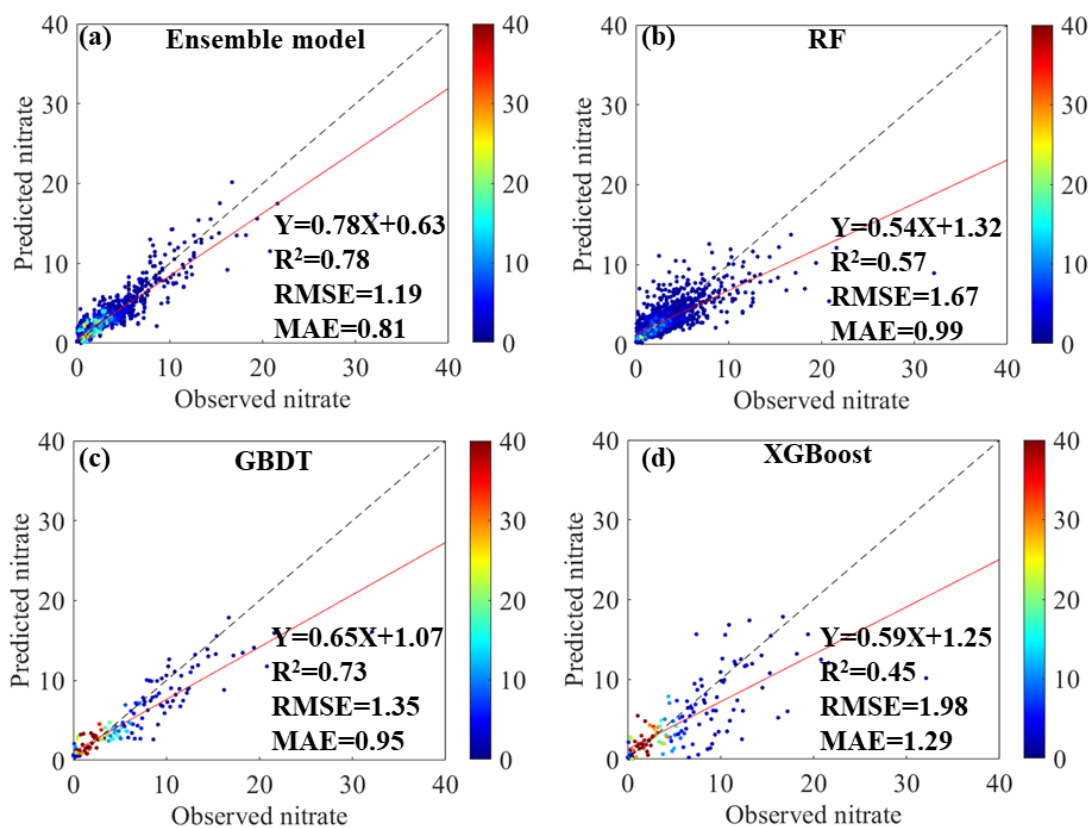
784

785 **Fig. 2** The workflow of the ensemble model development for ambient NO_3^- estimates.



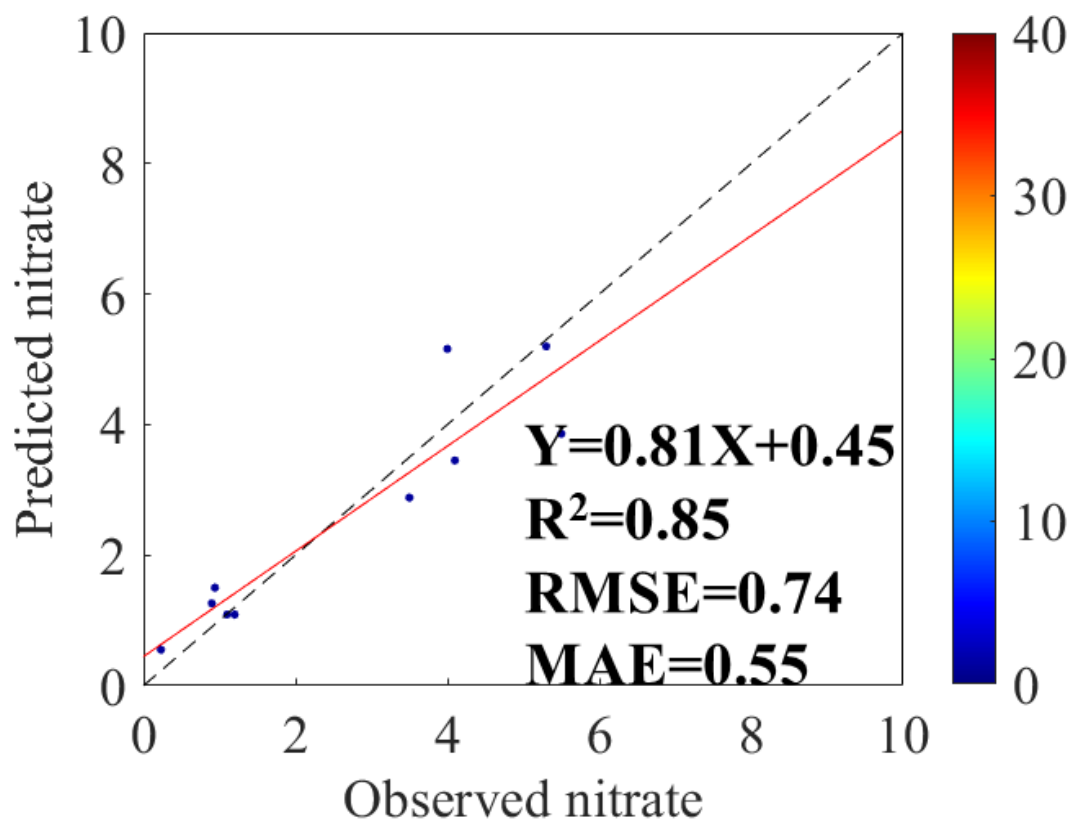
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787 **Fig. 3** Density scatterplots of 10-fold cross-validation results for monthly NO_3^- estimation (Unit: μg
 788 N m⁻³) across China for the ensemble decision trees model (a), RF (b), GBDT (c), and XGBoost
 789 (d), respectively. The color bar reflects the sampling size of each model. The red solid line denotes
 790 the best-fit line through the data points (1636 points). The black dashed line denotes the diagonal,
 791 which could be used to reflect the deviation of data points.



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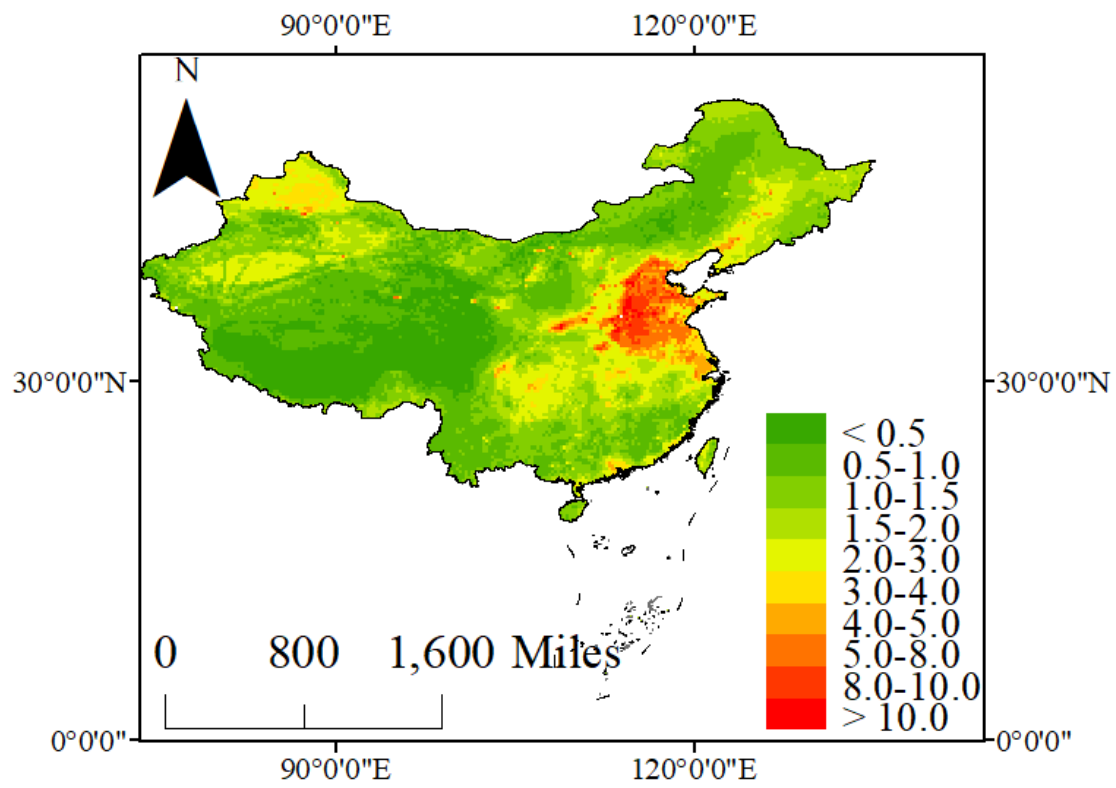
793 **Fig. 4** The transferability validation of the ensemble model in estimating NO_3^- concentration over
794 China based on the unlearning observation data (Shen et al., 2013; Shen et al., 2009; Wang et al.,
795 2019a; Xu et al., 2018b). The color bar reflects the sampling size of each model. The red solid line
796 denotes the best-fit line through the data points. The black dashed line denotes the diagonal, which
797 could be used to reflect the deviation of data points.



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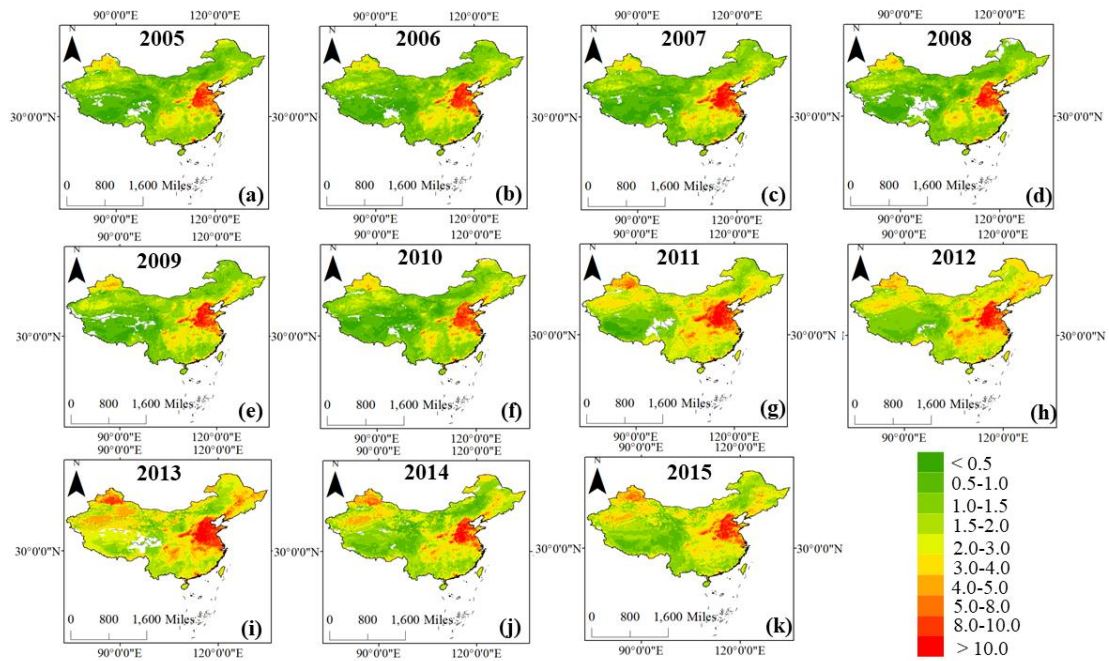
799 **Fig. 5** The spatial pattern of estimated NO_3^- concentration ($\mu\text{g N m}^{-3}$) over China during 2005-2015

800 based on the ensemble model.



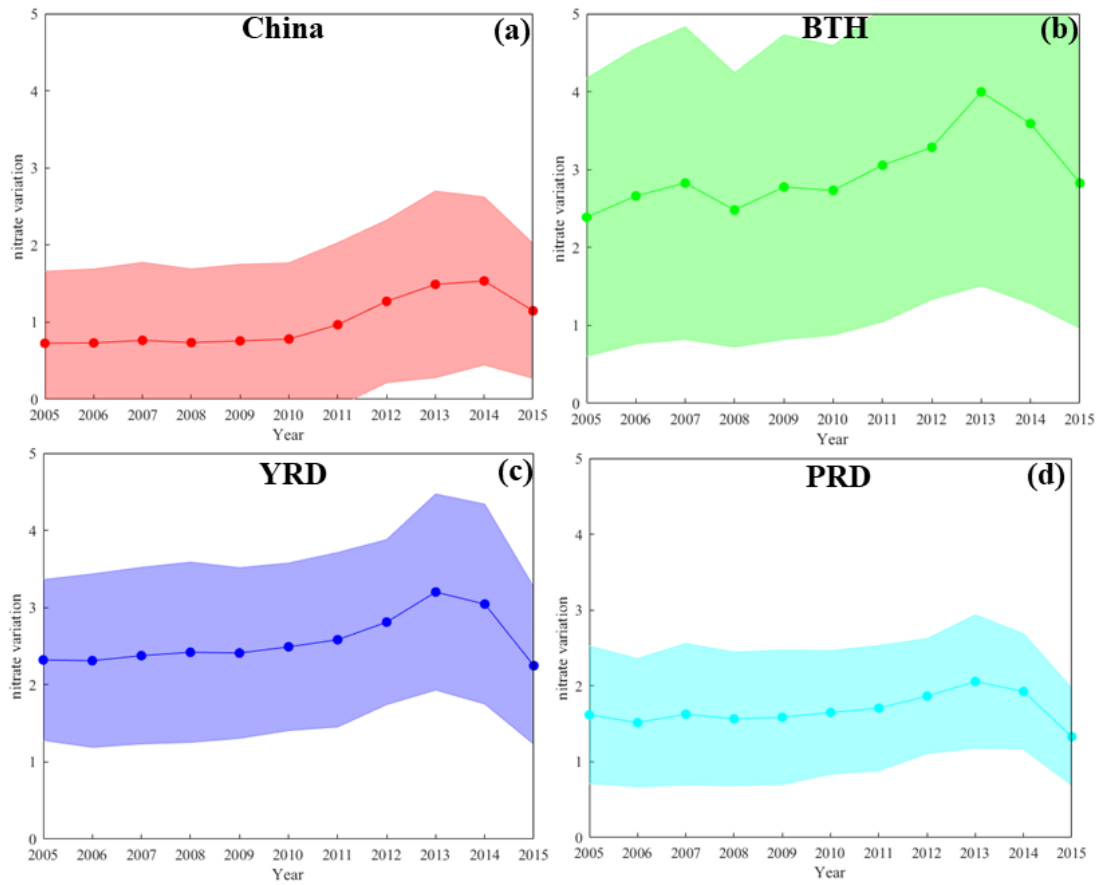
801

802 **Fig. 6** The annual mean predicted NO_3^- concentrations ($\mu\text{g N m}^{-3}$) across the entire China from (a)-
803 (k) 2005-2015 based on the ensemble model.



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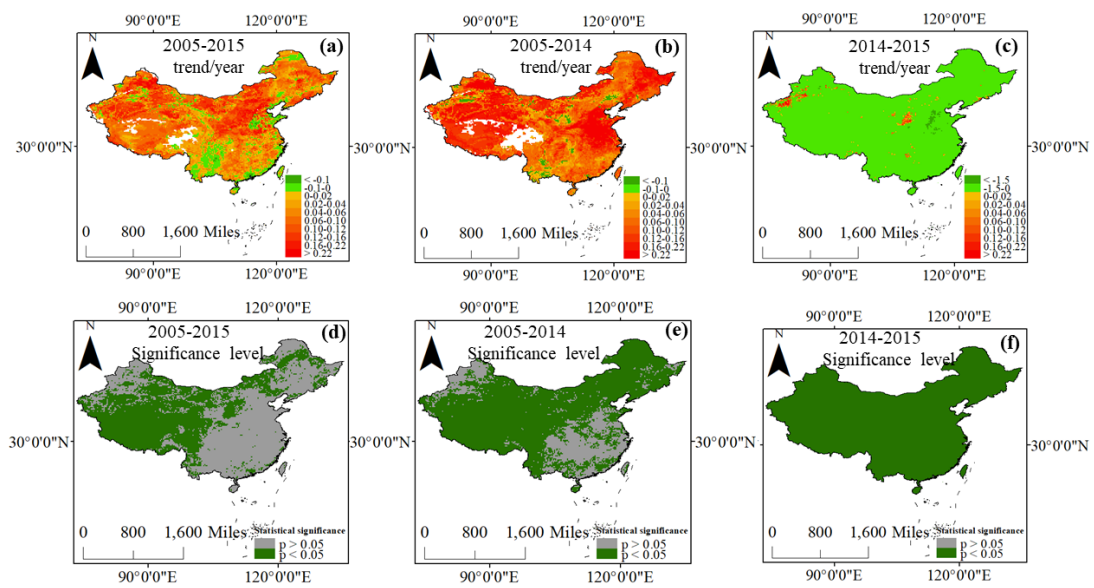
805 **Fig. 7** The annual mean NO_3^- concentrations in major regions across China during 2005-2015. The
806 solid lines denote the mean NO_3^- concentrations and the shadow represents the range of NO_3^-
807 concentrations.



808

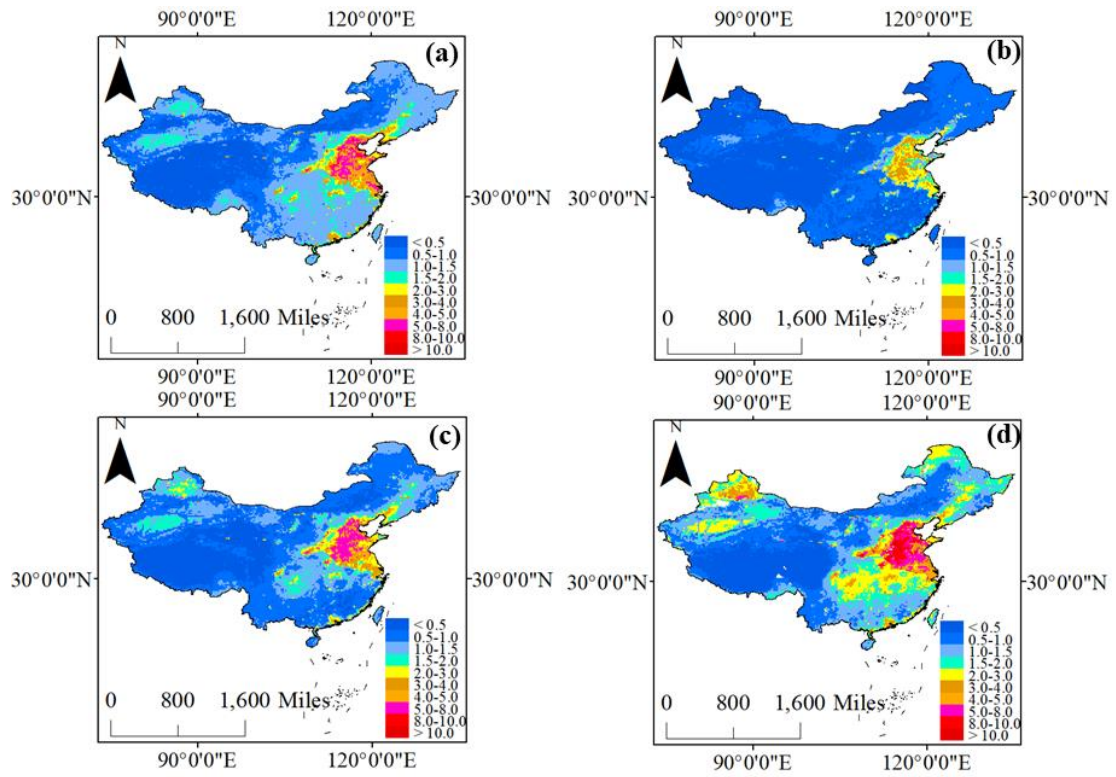
809

810 **Fig. 8** The long-term trends of NO_3^- concentrations ($\mu\text{g N m}^{-3}$) and significance levels in China (a,
 811 b, and c denote the annual variation of ambient NO_3^- concentration during 2005-2015, 2005-2014,
 812 and 2014-2015, respectively. d, e, and f represent the significance level of NO_3^- trend during these
 813 periods). The pale green color denotes the regions with the significant variation of ambient NO_3^-
 814 concentrations ($p < 0.05$), while the gray color represents the regions with insignificant variation of
 815 NO_3^- concentrations.



816

817 **Fig. 9** The mean concentrations of ambient NO_3^- in spring (a), summer (b), autumn (c), and winter
818 (d) during 2005-2015 over China, respectively.



819

820 **Table 1** The cross-validation result of NO₃⁻ estimation over China during 2010-2015.

Year	Sample size	R ² value	Slope	RMSE (μg N m ⁻³)	MAE (μg N m ⁻³)
2010	135	0.62	0.60	1.39	0.90
2011	291	0.88	0.85	0.32	0.24
2012	274	0.89	0.86	0.33	0.28
2013	312	0.83	0.82	0.64	0.43
2014	306	0.74	0.76	1.50	1.04
2015	318	0.78	0.78	1.35	0.86

821

822 **Table 2** The cross-validation result of NO₃⁻ estimation over China in four seasons.

Season	Sample size	R ² value	Slope	RMSE (μg N m ⁻³)	MAE (μg N m ⁻³)
Spring	395	0.80	0.80	0.71	0.48
Summer	418	0.85	0.84	0.29	0.20
Autumn	437	0.80	0.78	1.10	0.70
Winter	386	0.75	0.73	1.85	1.23

823

824 **Table 3** The cross-validation result of NO₃⁻ estimation over China in different regions (Northeast
 825 China includes Heilongjiang, Jilin, and Liaoning provinces; NCP includes Beijing, Tianjin, Hebei,
 826 Henan, Shandong, and Shanxi provinces; Southeast China includes Jiangsu, Zhejiang, Fujian,
 827 Guangdong, Jiangxi, Anhui, Hunan, Hainan, Shanghai, and Hubei provinces; Southwest China
 828 includes Yunnan, Guangxi, Sichuan, Tibet, Chongqing, and Guizhou provinces; Northwest China
 829 includes Inner Mongolia, Xinjiang, Gansu, Qinghai, Ningxia, and Shaanxi.

Season	Sample size	R ² value	Slope	RMSE (μg N m ⁻³)	MAE (μg N m ⁻³)
Northeast	175	0.44	0.43	1.30	0.81
China					
NCP	492	0.70	0.64	1.74	1.06
Southeast	395	0.59	0.57	1.50	0.84
China					
Southwest	384	0.60	0.59	2.08	1.41
China					
Northwest	190	0.58	0.52	2.06	1.38
China					

830

831 **Table 4** The trend analysis of NO₃⁻ concentrations in China, BTH, YRD, and PRD regions during
 832 2005-2015.

Period	Trend	China	BTH	YRD	PRD
2005-2014	Trend (μg N m ⁻³ /year)	0.08	0.13	0.08	0.03
	Significance	p < 0.05	p < 0.05	p < 0.05	p < 0.05
2014-2015	Trend (μg N m ⁻³ /year)	-0.40	-0.76	-0.79	-0.59
	Significance	p < 0.05	p < 0.05	p < 0.05	p < 0.05
2005-2015	Trend (μg N m ⁻³ /year)	0.04	0.04	-0.01	-0.03
	Significance	p < 0.05	p > 0.05	p > 0.05	p < 0.05

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835