

Response to Reviewers' comments

We would like to thank the two anonymous reviewers for their detailed assessment of our manuscript and the associated data. Their comments were very valuable for improving both. We addressed all remarks, as detailed below in blue font. Line references refer to the tracked-changes document.

Reviewer #1

Summary.

The manuscript “Ship- and island-based atmospheric soundings from the 2020 EUREC4A field campaign” by Stephan et al. describes the experimental design, measurements, and post-processing of the radiosonde program at EUREC4A, which was distributed across five platforms east of Barbados in January and February 2020. The manuscript is well-written and concise. It provides useful documentation for users of the data sets and is appropriately scoped for ESSD. The description of the level 2 data is disappointing as it does not appear to include additional quality control expected for this stage of processing that could have been implemented using available software like ASPEN. I also have some questions about the data acquisition and processing because it is not clear if the baseline corrections were implemented or omitted. The answers to these questions may only require some clarifying statements, or perhaps a more significant revision of the data set is needed.

We thank the reviewer for their positive feedback. We clarified the information on data acquisition, treatment and quality control applied to Level 2. Details are listed below.

Major Comments

(1) You state that the descent data was collected. I am not certain if this applies to MW41, but for older Vaisala systems, collecting descent data meant running in “research mode”, which does not include the standard corrections for solar heating or pendulum motions and omits some quality control procedures too. It is therefore not clear to me if this standard Vaisala processing is included in level 1 or not. If it is, please clarify. If it is not, the data likely needs to be reprocessed.

The MW41 software processes the descending phase of a sounding in the exact same way as the ascending phase. No “research mode” was turned on. We clarified this important point at line 224: “The MW41 software applies the same correction and quality control steps to the descending and ascending phases of a sounding.”

(2) Descent data is subject to some well-documented biases, some of which I noted above. While Figure 6 and discussion provides good documentation of the relative differences observed between up and down data at EUREC4A, the presentation implies the two types of data are equitable when they are not. It should be made clear that the confidence in the ascent data is higher and you should describe the limitations of the descent data.

We clarified that descent data are associated with greater uncertainties by adding to the quality control section (2.3.1) at line 225: “Descending sondes, however, can be subject to uncontrollable factors. For example, a falling device may be affected by the remaining debris of a balloon. For this reason, Vaisala does not guarantee the same above-mentioned error margins for data from descending soundings.”

The discussion of Fig. 7 (old Fig. 6) is now motivated in the following way (line 263): “Despite corrections and quality control steps applied by MW41, measurements taken during descent may be accompanied by larger uncertainties due to less favorable and more variable measurement conditions. To establish what degree of confidence we may attribute to the descent data, Fig. 7 compares the measurements of horizontal wind speed, air temperature and relative humidity between ascending and descending soundings.”

(3) Level 2 data: ASPEN is mentioned at Line 205, but it is not defined or referenced. The roadmap provided by Ciesielski et al. (2012, <https://doi.org/10.1175/BAMS-D-11-00091.1>), which you state that your data is consistent with (Line 180), suggests this step is necessary for a level 2 data set, but it is not clear if this algorithm (or similar) was applied to the level 2 data or not. What were the quality control procedures applied in level 2?

The treatment of the data by the MW41 software is equivalent to the quality control procedures that ASPEN applies. Reference to ASPEN and clarification of this aspect are now given at line 235: “..., which is also used by the Atmospheric Sounding Processing ENvironment (ASPEN) software (Suhr and Martin, 2020) for EUREC⁴A dropsonde measurements. Surface-launched soundings were not reprocessed with ASPEN, as the ASPEN manual warns against duplicating quality control procedures applied by the Vaisala MW41”

It is also important to consider additional sources of error: e.g., even with sonde equilibration, previous experiments on the Brown have identified biases associated with localized heating of the sonde by the ship’s superstructure during equilibration, pressure errors associated with relative wind direction, spurious data caused by the ship’s exhaust, and other problems (Hartten et al. 2018, www.earth-syst-sci-data.net/10.1165/2018/). Have you considered any of these potential sources of error and if so how did you address them?

This is the reason why we set values below 40 m to missing in the Level-2 data. We now state this explicitly at line 239: “Discarding the lowest 40 m avoids potential biases in the soundings associated with local ship effects, like heating or exhaust plumes, and other problems that are discussed by, e.g. Hartten et al. (2018).”

Minor Comments

Introduction: Consider adding a statement clearly indicating that the current manuscript addresses only the surface-based radiosonde program and not the dropsonde program, which are implied to be closely linked in the experimental design of EUREC4A. Also, if you have it, cross-referencing the doi and or paper describing the dropsondes somewhere in the manuscript would be helpful to users.

We agree that the introduction may have given the wrong idea about the focus of this paper. We moved and modified the following sentence (line 40): “This article introduces the radiosonde observations and their resulting data sets. Other measurements, including the dropsonde data, are described in the overview paper by Stevens et al. (2020) and the references therein.”

The dropsonde data paper has not been submitted at the time of this resubmission. We hope to add the reference to the final version of this manuscript.

Figure 2.

(a) I realize the array was positioned over a featureless region of open ocean and this is essentially the map. However, more geographical context is needed for the reader. Having this map include the Caribbean Islands and the northern coast of South America would help, but perhaps some of the details of the transects would be too small after zooming out. Instead, maybe you could include a map with this figure with 6-16N and -60 - -50E displayed as a box to highlight the study region. Indeed, Fig. A1, which includes the inset as well as a useful pattern of SST as a backdrop is an improvement over Figure 2.

We added the island of Barbados and the South American coastline to Fig. 2. We agree that this modification is helpful and thank the reviewer for suggesting it.

(b) Can you mark the aircraft pattern too?

We appreciate this idea to give context to the ship tracks. The aircraft pattern is now marked in Fig. 2c and we refer to it at line 75.

(c) It would also be useful to see the location of BCO on a map of the island with the prevailing wind direction and maybe the drift tracks of the sondes launched from that station (e.g., context for Lines 247-248)

We thank the reviewer for this remark. In following the suggestion by reviewer #2 (marked by ^^ below in this document), we made the panel showing the sonde tracks a stand-alone figure (now Fig. 3). The figure also shows the location of the BCO on Barbados and the prevailing wind direction at 500 m altitude derived from the soundings. We refer to the new figure at lines 86, 109 and 268.

Lines 87-88: (a) This sentence is confusing as written. I think you mean that you launched 6 times per day (every 4 hours) and that this schedule included 2 launches per day that were timed to match the 0 and 12 Z synoptic times.

We clarified this sentence by rephrasing to (line 96): “The default launch times were 0245, 0645, 1045, 1445, 1845, and 2245 UTC. This schedule was selected to include two launches per day that were timed to match the 00 and 12 UTC synoptic times.”

(b) Those synoptic-schedule times would be the 10:45 and 22:45 launches, but this seems early. Normally for a 90 min launch (Line 82) you would launch 45 min early, so 11:15 and 23:15. Is there an explanation for this?

We clarified the timing of the launches by adding at line 98: “In practice the soundings reached 100 hPa on average in 60 minutes and burst after 90 minutes.”

The precise timing of soundings used to be more critical for numerical weather prediction. Recent advances, including 4D-Var assimilation, allow for more flexibility. Moreover, preferred reporting times differ between GTS entry points.

Section 2.1:

(a) It is not clear if the operators from the platforms followed an agreed-upon standard set of operational procedures or if they acted independently. For example, was the balloon filling amount consistent? Was the balloon size the same? Was the equilibration procedure consistent? Was the met station and use of met data consistent?

The balloon sizes are now listed: “Vaisala sondes were attached to 200 g balloons (BCO, *Atalante*, *Merian*, *Meteor*) or 150 g balloons (*Brown*). When present, the balloons were equipped with internal parachutes (see Table 1 for the use of parachutes). A modification took place on the *Atalante*, where after 0800 UTC on February 8, 350 g balloons with external parachutes were used instead.” (line 89)

“In addition to the Vaisala soundings, 47 sondes of MeteoModem type M10 attached to 150 g balloons without parachutes were launched...” (line 153).

We added a summary before describing the details for each platform (line 101): “In the following section, we describe specific issues and aspects of the launch procedure and surface equipment particular to each platform. All stations followed best practices for different equipment, which were established by several experienced teams at in-person sounding orientations prior to the campaign. For instance, every platform used a different empirical way of gauging the fill amount of gas, to arrive at desired ascent rates. Equipment and procedures differed between the platforms, but this does not introduce systematic biases to Level-2 data, as these data only start at 40 m height (see Section 2.3.2), where measurements are independent of the surface procedures..”

(b) There was apparently a large temperature difference between the labs where the sondes were prepared and the release point outside, yet only the Brown’s procedures note an equilibration period on deck. If the other locations did not equilibrate the sondes, please note this and provide a warning about the potential for thermal instabilities or shock in the lower atmosphere within the data set.

Such shocks would be filtered out by the software, already at Level-1. We now provide this information in Section 2.3.1 (line 223): “Periods of super-adiabatic cooling are interpolated, and this also applies to temperature differences right above the surface.”

We mention in the description of procedures (Sections 2.1.1 to 2.1.5) which platforms released sondes out of a container. For all other platforms the open-air release provides ample time for equilibration given that the response time of the instruments is only a few seconds (see

paragraph at line 215). Attaching the sonde to a balloon already takes longer than several multiples of this time. With regard to the container releases, local abrupt changes in measured profiles could exist below 40 m. These near-surface problems are discussed at line 239, and to avoid them we set Level-2 data below 40 m to missing values.

Section 2.2:

(a) Please provide the WMO station ID numbers used for the GTS in the text or table for all platforms.

We added this information to Table 1 and refer to it in the text at line 190:

“The WMO station identifiers and designators for tracking the data within the GTS are listed in Table 1 for each station.”

(b) Were all soundings sent to GTS or only the subset on the 6 or 12 hour standard schedule?

We clarified the sentence at line 183: “...we aimed to disseminate as much of the full 1-second resolution radiosonde data from the EUREC⁴A campaign as possible over the GTS, regardless of the launch time.”

Section 2.3.2:

(a) Are the bin heights centered, top, or bottom of the averages?

The bins are centered, as we now state at line 233. We now also give their bounds in the level 2 data set (variable `alt_bnds`).

Line 215: change “smaller” to “slower”

We changed this (line 250).

Reviewer #2

The manuscript by Stephan et al. describes the radiosonde data set obtained during the EUREC4A field campaign. Weather balloons were launched from 4 ships and one island station at Barbados. All data were obtained using the Vaisala radiosonde system. The paper describes the setup, launch operations, data collection, and processing. The three levels of data processing are publicly available. Some analysis of the data set demonstrates its huge potential and usefulness for atmospheric science. The raw data are complete, the level 1 and level 2 data are ncdf files following the CF convention and appear to be properly formatted. The paper is overall well written and the data set overall well documented. However, there are a number of smaller issues, which should be addressed. I would recommend publication after some corrections.

We are grateful to the reviewer for their careful check of our published data. The issues they raised helped to improve the data set as well as the manuscript.

Detailed comments:

The data set of the Meteor contains a set of corrected raw data files. Can you elaborate why a correction was needed and how it was applied?

****** We thank the reviewer for pointing this out and added an explanation to section 2.1.2 at line 126: “By mistake, the heights of the pressure sensor, the GPS antenna and the launching altitude were incorrectly entered at the beginning of the cruise. In addition, we noticed large delays between the time at which surface measurements were entered and the launch. Therefore, we reprocessed the raw data using the MW41 software, after correcting the sensor heights and surface data in the raw files. This post-processing is lossless and the reprocessed data have the same quality standard as the data from the other platforms. We included both the original and reprocessed Level-0 data in the dataset.”

Lines 80: Please describe here down to what altitudes descent data were typically recorded. This is given later in the manuscript, but should be moved to here.

We moved the text to line 81.

Lines 81: add “...nearly match fall speeds in the middle and lower troposphere to balloon ascent speeds”.

This is a very sensible correction. We modified the sentence at line 84 accordingly.

Line 82: “somewhere above each platform”: Could you please make a statement about the drift of the soundings over the vertical region of interest. Something like the average horizontal distance between ascent and descent measurement at a relevant altitude.

This is nicely visualized in Fig. 3. We rephrased the text at line 84 to: “Given that a typical ascent takes about 90 min, a radiosonde was sampling the air somewhere close to each platform nearly continuously during regular operation. The horizontal drift of the sondes is shown in Fig. 3 for the example of the BCO.”

Line 83: Which software version of the MW41 system was used at each station? Since the RS41 SGP sondes were used, I assume the reported pressures are the measured pressures. Since the Modem sondes used GPS height for that purpose, it might be useful to highlight that difference.

The software versions of the MW41 system were added to Table 1. These and the variables measured by the RS41 SGP sondes are introduced at line 86: “All platforms deployed Vaisala RS41-SGP radiosondes, which measure wind, temperature, relative humidity, and pressure, and used Vaisala MW41 ground station software to record and process the sounding data. The software versions of the MW41 system are given in Table 1 for each platform. Basic algorithms and data processing did not change between these versions.”

The difference to Modem sondes is made explicit at line 427: “Unlike with RS41 SGP sondes, the pressure is deduced from the altitude and the surface station pressure measurement, using the hydrostatic approximation.”

Line 95: add “...which sometimes delayed soundings...”

We rephrased the sentence accordingly (line 112).

Throughout the description of the balloon filling at the different platforms, it was not very clear, how the amount of fill gas was gauged. Do I understand correctly, that the volume was estimated based on for example a marker (e.g. R/V Meteor) inside the container? Or was there some attempt to measure the amount of gas by monitoring the gas pressure, explicitly measuring the volume or measuring lift? Please clarify. What balloon size/sizes were used at the different stations? On soundings with parachutes, were balloons with internal parachutes used, or were parachutes externally? If this was different on the Meriam, it could possibly explain their larger number of faster falling sondes.

The balloon sizes are now listed: “Vaisala sondes were attached to 200 g balloons (BCO, *Atalante*, *Merian*, *Meteor*) or 150 g balloons (*Brown*). When present, the balloons were equipped with internal parachutes (see Table 1 for the use of parachutes). A modification took place on the *Atalante*, where after 0800 UTC on February 8, 350 g balloons with external parachutes were used instead.” (line 89)

“In addition to the Vaisala soundings, 47 sondes of MeteoModem type M10 attached to 150 g balloons without parachutes were launched...” (line 153).

We added a summary before describing the details for each platform (line 101): “In the following section, we describe specific issues and aspects of the launch procedure and surface equipment particular to each platform. All stations followed best practices for different equipment, which were established by several experienced teams at in-person sounding orientations prior to the campaign. For instance, every platform used a different empirical way of gauging the fill amount of gas, to arrive at desired ascent rates. Equipment and procedures differed between the platforms, but this does not introduce systematic biases to Level-2 data, as these data only start at 40 m height (see Section 2.3.2), where measurements are independent of the surface procedures..”

Lines 118: The nighttime soundings during leg 1 used less helium to increase the vertical resolution. This was changed after that. Was there no value in doing so? Was anything useful learned? The authors could briefly explain this change.

We added an explanation at line 140: “To avoid the potential for biasing analyses of the diurnal cycle with systematic diurnal differences in ascent rates, after January 24, the same target ascent rate was used for day and night.”

Line 231: Figure 11 is referenced before Figure 10, which needs to be corrected.

We thank the reviewer for noticing this and swapped the figures.

Line 106f, 122ff, 133 ff, 155ff and lines 207ff: The influence of a ship on observations near the surface is well documented and understood. It is not very clear how this was handled here. I understand that the operators tried to minimize that effect by launching from a location on a ship that minimizes this effect to the extent possible. Was any additional data screening done to evaluate and filter the effect of a ship in the lowest 50 m or so? The Vaisala system has a setting that filters out data showing a superadiabatic lapse rate. If that setting was used, then some of the ships influence may be filtered out by the Vaisala system in their level 1 data.

This is correct. Such super-adiabatic lapse rates would be filtered out by the software, already at Level-1. We now provide this information in Section 2.3.1, the section that describes Level-1 (line 223): “Periods of super-adiabatic cooling are interpolated, and this also applies to temperature differences right above the surface.”

The setup of sounding systems on ships can be tricky, since launch site, receiving antenna, reference pressure sensor, and wind measurements may be several 10s of m separated vertically. Have you verified that the altitudes in the lowest 50 m are all reasonable and consistent? I noticed that there may be unreasonable jumps of more than 20 m in the first second after launch.

Yes, we now verified that the altitudes in the lowest part of the soundings are reasonable. Please see our response above marked by **.

In addition, we added to Section 2.3.1 (line 204): “Sometimes the launch detection did not work properly, which resulted in differences of more than 30 m between the surface altitude and the first reported sonde altitude. Such profiles were reprocessed by correcting the launch time in the raw files. The files were then processed like the corrected files from the Meteor (see Section 2.1.2). “

I checked the altitude of the BCO launch site, which is set at 25 m in the files, but may only be 13 m in reality.

The height of the launch site is measured with two independent GPS devices. We can confirm that 25 m are correct for the height of the launch site.

It’s not clear at what level above msl the balloons were launched from the ships. Maybe the authors could comment how important the lowest 50 m of profile are in their studies. I guess they were not very important, but offsets like 10 may shift the entire profile and may be significant in high resolution studies.

The launch heights are given in Table 1 for each platform and the lowest 40 m of ship soundings in the Level-2 data are set to missing values as described in section 2.3.2 in order to exclude influences of the ships’ superstructure on the measurements. We clarified in the caption of

Table 1 that the listed altitudes and offsets refer to the waterline of the ship which is indeed not necessarily identical to mean sea level at all times.

Lines 230ff: I assume that the difference in atmospheric conditions downwind and an later would increase the scatter between ascent and descent measurements, but should not cause any systematic bias. A different sensor response (including GPS) between ascent and descent is more likely to cause systematic biases.

We thank the reviewer for pointing this out and agree with them. The text was adapted accordingly: “Despite corrections and quality control steps applied by MW41, measurements taken during descent may be accompanied by larger uncertainties due to less favorable and more variable measurement conditions. To establish what degree of confidence we may attribute to the descent data, Fig. 7 compares the measurements...” (line 263).

Then at line 268: “Meridional horizontal drift could create systematic biases.”, and at line 269: “Second, there are variable time lags of the order of a couple of hours between ascending and descending measurements, which we expect might increase the scatter between ascent and descent measurements but not create systematic differences. A systematically different response of the sensors during descent might be the most important factor for biases.”

Line 255: Please move the definition of the hydrolapse from the legend of Figure 7 to here.

We followed this suggestion and moved the definition of the hydrolapse from the caption of Figure (now) 8 to now line 296.

Lines 270ff: The patterns Sugar, Gravel, Flower and Fish are not obvious and scientifically accepted patterns. Please describe these here.

We added the following sentence to the manuscript (line 312): “While the low and small Sugar clouds appear with little organization, Gravel clouds reach deeper extents and organize along gust fronts. The fish--bone like organization of clouds on horizontal scales of 200---2000 km is described by the Fish pattern, and large stratiform, often circular-shaped cloud clumps are labeled as Flowers.”

Line 351: Change to “...together with the NRT SST maps produced by...”. Can you add, which satellite(s) is used for these maps?

We made the change, and added the list of satellites at line 388: “The CLS SST NRT product is derived from nighttime observations (to avoid diurnal warming of the sea surface) by the MODerate-resolution Imaging Spectroradiometer (MODIS) on board TERRA and AQUA satellites, the Advanced Very High Resolution Radiometer (AVHRR) on board METOP-A and -B, the Visible Infrared Imager Radiometer Suite (VIIRS) on board Suomi-NPP, the Advanced Himawari Imager (AHI) on board HIMAWARI-8, and the Advanced Baseline Imager (ABI) on board GOES-16 and -17.”

Line 384: Was there a particular reason to use the Magnus-Tetens formula for the M10sonde humidity calculations? This could have been handled the same as the Vaisala sondes. However, I do not expect that the differences are significant over the region of interest.

We modified the processing of the MeteoModem soundings to be the same as that of the Vaisala soundings by beginning with the raw data instead of starting from the BUFR files. The text was adapted at line 430: “The raw MeteoModem data are processed in the same way as the Vaisala soundings....”

Figure 5: The spread of the rise rate appears a little large, in particular in the stratosphere, where the balloon rise rate becomes a lot more uniform. I don’t believe that ascent rates are calculated on 500 m bins, rather I assume that the 1 s calculated rise rates were binned in 500 m bins. The spread shown in this Figure is most likely due to noise in the pressure data. If the rise rate was calculated based on GPS altitude or better still based on 500 m altitude bins, the spread should decrease significantly. I do not think it is necessary to redo this plot, but it would be good to explain the spread.

The reviewer is correct with their assumption about the computation. We now explain how the figure was computed at line 247: “The figure is based on the ascent (or descent) rates with a 10-m vertical resolution included in the Level-2 data.”

It is our intention to present the data that we publish and therefore we agree that the figure should not be changed. Regarding the spread, we decided not to discuss this further, as there are several possibilities for changes in the spread, including noise (as suggested by the reviewer), interpolation artifacts, true differences, sample size (please note that the stratosphere has a much smaller sample size!), stratospheric gravity waves. Investigating these aspects is beyond the scope of this paper. However, the interested reader has got the opportunity to investigate this question, as all required (raw) data are available.

Figure 6: What does “time averaged” mean in this Figure? If the same time averaging was used on ascent and descent and then the data were binned to consistent altitudes, I would not be surprised of biases due to the different descent rate profile compared to ascent. However, that may not be the case. Please clarify.

The wording “time averaged” was a poor choice as it is confusing. Shown is simply the average of the soundings. We rephrased the caption of (now) Fig. 7 to clarify this point.

Figure 7: What is the axis label “LTS [K]”? I assume this is the 700 hPa potential temperature, but the axis label indicates something else.

We thank the reviewer for catching this mistake. The panel shows Lower Tropospheric Stability, that is the difference of potential temperature at 700 hPa and the mean potential temperature in the lowest 200 m. The figure caption of now Figure 8 was corrected accordingly and we added the definition of the LTS to the text at line 297.

Figure 8: The legend refers to humidity profiles on descent below the last received data. However, the Figure does not refer to descent measurements. This sentence can probably be deleted.

We thank the reviewer for catching this inconsistency. The figure does in fact combine ascending and descending soundings. We corrected the first sentence in the caption (now Fig. 9) to read: "Comparison between ascending and descending soundings and ceilometer measurements on the Meteor."

^^Figure 11 f shows some trajectories but does not fit with the rest of the panels and is not described in the text. This panel could be made a standalone figure and address my point regarding the average drift.

We agree with the reviewer and made old Fig. 11f into the standalone figure (Fig. 3), which we now refer to at lines 86, 109 and 268. Panel 11f was replaced with a contour plot of the Brunt-Vaisala frequency.

Figure 12: The legend indicates that this Figure shows 437 profiles, but the sum of North and South does not add up to that number. More than 100 profiles seem to be missing.

We thank the reviewer for catching this error and corrected the caption of (now) Fig. 13.

The appendix describes some results of the Modem radiosonde launches. I would suggest to add a few sentences to the general data processing similar as the description of the Vaisala data. Was all data QC done by the Modem software? Were similar data levels (0/1/2) generated?

As mentioned above, we now process the Modem soundings like the Vaisala soundings. We give the following description at line 430: "The raw MeteoModem data are processed in the same way as the Vaisala soundings to create Level-1 and Level-2 files that match the format of the corresponding Vaisala data. The only difference is that the description of the MeteoModem corrections that are automatically applied by the software is a trade secret and therefore not known to us. However, the M10 sondes are currently in the process of being certified by the Global Climate Observing System Reference Upper-Air Network (GRUAN). If the GRUAN certification is granted, details on these corrections will become available. We checked for and corrected spurious data in the surface observations using handwritten log-sheets filed during the campaign."

Ship- and island-based atmospheric soundings from the 2020 EUREC⁴A field campaign

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Abstract. To advance the understanding of the interplay among clouds, convection, and circulation, and its role in climate change, the EUREC⁴A and ATOMIC field campaigns collected measurements in the western tropical Atlantic during January and February 2020. Upper-air radiosondes were launched regularly (usually 4-hourly) from a network consisting of the Barbados Cloud Observatory (BCO) and four ships within 51–60 °W, 6–16 °N. From January 8 to February 19, a total of

5 811 radiosondes measured wind, temperature and relative humidity. In addition to the ascent, the descent was recorded for
82 % of the soundings. The soundings sampled changes in atmospheric pressure, winds, lifting condensation level, boundary
layer depth, and vertical distribution of moisture associated with different ocean surface conditions, synoptic variability, and
mesoscale convective organization. Raw (Level-0), quality-controlled 1-second (Level-1), and vertically gridded (Level-2) data
in NetCDF format (Stephan et al., 2020) are available to the public at AERIS (<https://doi.org/10.25326/137>). The methods of
10 data collection and post-processing for the radiosonde data set are described here.

Copyright statement. TEXT

1 Introduction

A number of scientific experiments have focused on the trade-cumulus boundary layer over the tropical Atlantic Ocean. The
Barbados Oceanographic Meteorological Experiment (BOMEX 1969; Kuettner and Holland, 1969), Atlantic Trade-Wind Ex-
15 periment (ATEX 1969; Augstein et al., 1973), Atlantic Stratocumulus Transition Experiment (ASTEX 1992; Albrecht et al.,
1995), and Rain in Shallow Cumulus Over the Ocean (RICO 2006; Rauber et al., 2007) experiment measured thermodynamic
and wind profiles of the Atlantic trade regime (reviewed by Baker, 1993). With these profiles as initial and environmental
conditions, models of the cumulus clouds explain their interaction with the environment (e.g. Arakawa and Schubert, 1974;
Albrecht et al., 1979; Krueger, 1988; Tiedtke, 1989; Albrecht, 1993; Bretherton, 1993; Xue et al., 2008; vanZanten et al.,
20 2011).

Arrayed networks of soundings have been used to characterize the interaction of clouds, convection, and the synoptic envi-
ronment. In many examples, they have been used to diagnose tendencies of the heat, mass, and moisture budgets for the tropical
atmosphere (e.g. Reed and Recker, 1971; Yanai et al., 1973; Nitta and Esbensen, 1974; Lin and Johnson, 1996; Mapes et al.,
2003; Johnson and Ciesielski, 2013). These experiments in the deep tropics monitored the synoptic (100–1000 km) variations
25 of vertical motion and moisture convergence as context for the evolution of the ensemble of convective clouds observed within
their sounding networks.

These sounding arrays measure horizontal divergence, which is used to estimate mean large-scale vertical motion. In
DYCOMS-II, Lenschow et al. (2007) used stacked flight circles to estimate subsidence on a fine scale relevant to marine
stratocumulus clouds. Studying the variations of mesoscale (~ 100 km) organization of the trade wind shallow cumulus clouds
30 likewise requires fine horizontal resolution. The Next-Generation Aircraft Remote Sensing for Validation Studies (NARVAL;
Stevens et al., 2016, 2019; Bony and Stevens, 2019) demonstrated that circles of dropsondes released from aircraft above the
shallow clouds reliably measure a snapshot of vertical motion.

The shallow trade cumulus clouds over the tropical Atlantic Ocean are a focus also of the Elucidating the Role of Clouds-
Circulation Coupling in Climate Campaign (EUREC⁴A; Bony et al., 2017) and associated campaigns, i.e, the Atlantic Tradewind

35 Ocean–Atmosphere Mesoscale Interaction Campaign (ATOMIC)¹. The experimental design of EUREC⁴A involved 85 drop-
sonde circles from aircraft flights combined with regular around-the-clock upper air observations from surface-launched ra-
diosondes. The regular sampling from surface-launched radiosondes complemented the mesoscale vertical velocity measure-
ments from dropsonde circles by continuously measuring time-height profiles of the atmosphere, synoptic variability for an
extended time period, and diurnal variability. Radiosondes sampled when research aircraft were not flying, notably at night.

40 This article introduces the radiosonde observations and their resulting data sets. Other measurements, including the drop-
sonde data, are described in the overview paper by Stevens et al. (2020, under review) and the references therein. Between
January 8 and February 19, 2020, 811 radiosondes were launched from Barbados and the northwestern tropical Atlantic Ocean
east of Barbados. A focus of the campaign was on shallow cumulus clouds, their radiative effects, and their response to the
large-scale environment, contributing progress toward the World Climate Research Programme’s Grand Challenge on Clouds,
45 Circulation and Climate Sensitivity (Bony et al., 2015). Other EUREC⁴A investigations focus on air-sea interactions due to
ocean mesoscale eddies, cloud microphysical processes, and the effect of shallow convection on the distribution of winds.

Radiosondes were launched from Barbados and four research vessels. The island-based launches took place at the Barbados
Cloud Observatory (BCO; 59.43 °W, 13.16 °N), situated at Deebles Point on the windward coast of Barbados. Surface and
remote sensing observations at BCO have been in operation since April 1, 2010 (Stevens et al., 2016).

50 Four research vessels launched radiosondes over the northwestern tropical Atlantic east of Barbados (51–60 °W, 6–16 °N)
during EUREC⁴A: two German research vessels, *Maria S. Merian* (hereafter *Merian*) and *Meteor*, a French research vessel,
L’Atalante (hereafter *Atalante*), and a United States research vessel, *Ronald H. Brown* (hereafter *Brown*). The BCO and the
research vessels all measured surface meteorology and deployed various other measurements for remote sensing of clouds and
the atmospheric boundary layer.

55 In Section 2 we describe the measurement strategy for the coordinated EUREC⁴A radiosonde network, the data collection
procedures for each platform, and the post-processing steps that were applied to create the final data set. Section 3 shows an
overview and some characteristics of the data and is followed by a summary in Section 4. The *Atalante* additionally launched
a different type of sonde, which is described in the appendix.

2 Sounding measurements

60 2.1 The EUREC⁴A sounding network

The number of launches per day as well as the dates of regular observations (Fig. 1) differ from platform to platform, reflecting
availability of ships and personnel. Soundings supported specific research interests on each platform, in addition to the coor-
dinated EUREC⁴A sounding network. We designed the radiosonde network to optimize the joint contribution of all platforms
to the overarching goals of EUREC⁴A. Sounding platforms were usually spaced to optimally sample the scales of the synoptic
65 circulation. The *Meteor* remained nearly stationary at a longitude of 57 °W and moved within a meridional corridor between

¹Because the sounding network and EUREC⁴A comprised many projects, or component campaigns, we refer to the union of these simply as EUREC⁴A.

12.0–14.5 °N to support coordinated aircraft measurements in its vicinity (Fig. 2a). The *Brown* occupied a southwest-northeast transect along the direction of the climatological surface trade winds, and approximately orthogonal to *Meteor*’s sampling line. The *Brown*’s transect between the BCO (59.43 °W, 13.16 °N) and the Northwest Tropical Atlantic Station for air-sea flux measurements buoy (NTAS) at 51.02 °W, 14.82 °N (Fig. 2b) sampled airmasses upwind of the BCO that move westward with the climatological easterly trade winds within 12.5–14.5 °N. This elongated region between BCO and NTAS is referred to as the ‘Trade-wind Alley’. The *Merian* and *Atalante* ventured southward to a minimum latitude of ~6.5 °N to observe oceanic and atmospheric variability associated with Brazil Ring Current Eddies as they tracked northwestward along the corridor referred to as ‘Boulevard des Tourbillons’. The *Atalante* and *Merian* thus often form the southern points of the radiosonde network (Fig. 2c, d).

Aircraft operations included a circular flight pattern of 180–200 km diameter centered at ~13.3 °N, -57.7 °E (Fig. 2c). Dropsondes were deployed along the circle to estimate the area-averaged mass divergence, as described in Bony and Stevens (2019). To sample larger scales than represented by this circle, we aimed at 4-hourly soundings from all five stations while platforms were separated by more than 200 km. The launch frequency was reduced when such a separation could not be maintained or when vessels left the key region of the network, i.e. moved south of 12 °N. These scenarios occurred from time to time in order to support other measurements. Figure 4 shows that the network sampled large scales for 30 consecutive days.

To increase the number of vertical profiles, we recorded the ascent as well as the descent of the radiosondes. For descending soundings the raw data near the surface are missing as the signal is lost due to Earth’s curvature at 300–800 m above mean sea level. The median of the lowest descent measurement is at 340 m. Except for the *Brown*, balloons were equipped with parachutes, which nearly match fall speeds in the middle and lower troposphere to balloon ascent speeds. Given that a typical ascent takes about 90 min, a radiosonde was sampling the air somewhere above close to each platform nearly continuously during regular operation. The horizontal drift of the sondes is shown in Fig. 3 for the example of the BCO. All platforms deployed Vaisala RS41-SGP radiosondes, which measure wind, temperature, relative humidity, and pressure, and used Vaisala MW41 ground station software to record and process the sounding data. The software versions of the MW41 system are given in Table 1 for each platform. Basic algorithms and data processing did not change between these versions. Vaisala sondes were attached to 200 g balloons (BCO, *Atalante*, *Merian*, *Meteor*) or 150 g balloons (*Brown*). When present, the balloons were equipped with internal parachutes (see Table 1 for the use of parachutes). A modification took place on the *Atalante*, where after 0800 UTC on February 8, 350 g balloons with external parachutes were used instead.

To start a sounding, a radiosonde sensor was placed on the ground station for an automated ground check initialization procedure, which took about 5–6 min. The frequency at which the radiosonde transmits its signal to the receiver was set manually to a designated value for each platform (listed in Table 1) to avoid radio interference.

The default launch times were 0245, 0645, 1045, 1445, 1845, and 2245 UTC. This schedule was selected to include two launches per day that were timed to match the 00 and 12 UTC synoptic times. ~~to have radiosondes reach 100 hPa at standard synoptic times (00 and 12 UTC). In practice the soundings reached 100 hPa on average in 60 minutes and burst after 90 minutes.~~ Departures from this schedule occurred due to a variety of reasons, including defective radiosondes, balloon bursts before the launch, collisions of ascending radiosondes with other on board instrumentation, and air traffic safety. In the following section,

we describe specific issues and aspects of the launch procedure and equipment particular to each platform. All stations followed best practices for different equipment, which were established by several experienced teams at in-person sounding orientations prior to the campaign. For instance, every platform used a different empirical way of gauging the fill amount of gas, to arrive at desired ascent rates. Equipment and procedures differed between the platforms, but this does not introduce systematic biases to Level-2 data, as these data only start at 40 m height (see Section 2.3.2), where measurements are independent of the surface procedures.

2.1.1 Barbados Cloud Observatory (BCO)

The BCO is located at the eastern-most point of Barbados (59.43 °W, 13.16 °N) and thus directly exposed to easterly trade winds from the ocean (Fig. 3). The BCO launched 182 sondes, of which 162 measured descents. Radiosondes were prepared inside an air-conditioned office container with air temperature and relative humidity adjusted to 20 °C and 60 %, respectively. Balloons were prepared outside and placed into a launcher whose size provided rough guidance for achieving the desired filling level (Fig. 5a). Launches were coordinated with Barbados Air Traffic Control, which sometimes delayed soundings by up to 15 min. Surface conditions obtained from the weather station observations at the BCO were entered into the software after automatic release detection.

2.1.2 R/V Meteor

The *Meteor* launched 203 sondes and collected data for 167 descents during the EUREC⁴A core period (January 8 to February 19). Eight additional ascents and descents, respectively, were recorded after February 20. Radiosondes were prepared inside a laboratory on the top deck of the ship with the antenna placed on the roof. Before February 9 the soundings were launched from the container of the German Weather Service (DWD) on the port side at the stern of the ship (Fig. 5b). This container had a marker to indicate the optimum fill level of the balloons.

On February 9 the DWD launcher broke and a launcher of the type shown in Fig. 5a was used, located at the stern of the ship. An awning over the balloon indicated the fill level. Ground data were obtained from on-board instruments of the DWD. In addition to sondes launched by the EUREC⁴A science crew, the DWD launched one radiosonde per day. The 31 ascending DWD sondes launched during the EUREC⁴A core period, plus an additional eight after February 20, are included in the Level-1 and Level-2 data sets, described in Section 2.3.

By mistake, the heights of the pressure sensor, the GPS antenna and the launching altitude were incorrectly entered at the beginning of the cruise. In addition, we noticed large delays between the time at which surface measurements were entered and the launch. Therefore, we reprocessed the raw data using the MW41 software, after correcting the sensor heights and surface data in the raw files. This post-processing is lossless and the reprocessed data have the same quality standard as the data from the other platforms. We included both the original and reprocessed Level-0 data in the dataset.

2.1.3 R/V *Ronald H. Brown* (*Brown*)

The *Brown* released 169 sondes and collected data for 158 descents. The radiosondes were initialized and ground-checked inside an air-conditioned laboratory. Near-surface measurements were recorded from the ship's meteorological sensors via the ship computer system display. The ground station antenna was located on the aft 02 deck railing above the staging bay.

135 Initialized radiosonde sensor packages were placed for 1–5 min on the main deck to equilibrate to ambient environmental conditions and check GPS reception and telemetry. The balloons were filled by hand in the staging bay (Fig. 5d), which was mostly sheltered. Operators avoided unnecessary contact with the balloon body but restrained it by hand if the wind was strong.

On leg 1 (January 8–24) at night, less helium was used to reduce the buoyancy of the balloons in order to achieve lower ascent rates and better resolve the fine-scale vertical structure of the atmosphere. The ascent rate for day launches was $4.4 \pm 0.5 \text{ m s}^{-1}$.

140 ~~; for night launches, ascent was about 12 % slower, $3.9 \pm 0.6 \text{ m s}^{-1}$~~ Ascent was about 12 % slower for night launches ($3.9 \pm 0.6 \text{ m s}^{-1}$). To avoid the potential for biasing analyses of the diurnal cycle with systematic diurnal differences in ascent rates, after January 24, the same target ascent rate was used for day and night. Operators obtained consistent balloon volumes by timing the filling.

Balloons were launched from a location on the deck to minimize the effect of the ship and obstructions on the sounding.

145 The ship usually turned or slowed to improve the relative wind for the sounding. The relative wind carried the sounding away from the ship, but the ship's aerodynamic wake made the first $\sim 5 \text{ s}$ of the balloon's flight unpredictable. The sounding was sometimes launched up to 10 min earlier or later to accommodate other ship operations.

2.1.4 R/V *L'Atalante* (*Atalante*)

The *Atalante* launched 139 Vaisala sondes and measured 138 descents. A coordinated sounding phase was performed with 150 the *Merian* to increase the temporal resolution from January 30 at 2045 UTC to February 2 at 1645 UTC around $52\text{--}54^\circ \text{W}$ and $6\text{--}8^\circ \text{N}$. During this period launching times were shifted by 2 hours aboard the *Atalante* (0045, 0445, 0845, 1245, 1645, 2045 UTC) while the *Merian* launched at regular times. In addition to the Vaisala soundings, 47 sondes of MeteoModem type M10 attached to 150 g balloons without parachutes were launched from the *Atalante* to measure the lower atmosphere across mesoscale sea surface temperature (SST) fronts, as detailed in the appendix.

155 The radiosondes were prepared aft of the bridge. This open space was right next to the top building of the ship, which may have affected measurements at low levels. Before launching, operators asked the bridge for direction change if necessary and possible. The balloons were launched by hand from the rear deck of the bridge, where the launcher was situated (Fig. 5e). The Vaisala antenna was installed on the roof top. Surface measurements were obtained from local measurements on board. At the beginning of the campaign a frequency of 401.0 MHz was selected, which later on had to be switched to 401.2 MHz because of 160 radio interference at 400.9 MHz from an unknown source. This interference caused loss of signal for two radiosondes during their ascent. When a previous sounding was not terminated at the launch time of a subsequent sounding, a frequency of 400.7 MHz was selected.

The *Atalante* experienced substantial instabilities of the Vaisala acquisition system at the initialization step of the system (system location unavailable) and with the reception of the GPS signal by the Vaisala antenna and radiosondes. These problems required multiple restarts of the software and the acquisition system (between 1 and 8 times), creating delays between 10 min and 1 h. However, they did not affect the quality of the soundings. The operators checked the cables and replaced the GPS antenna of the Vaisala system with an antenna that had a larger DC voltage range (15 V instead of 4 V). Nevertheless, the problems persisted during the cruise with the need to restart the system several times before each launch.

2.1.5 R/V *Maria S. Merian* (*Merian*)

The *Merian* launched 118 sondes and recorded 38 descents. Fewer sondes were launched on the *Merian* than other platforms (Fig. 1) due to difficulties and priority of *Atalante* sondes when the ships were close to one another. The radio signal was often lost using the first antenna location, which the team suspected was due to blocking by the chimney. A new location improved the reception of the signal.

The *Merian* was equipped with a launch container (Fig. 5c). The helium fill level was decided by inflating the balloon until it reached the upper edge of the launch container. During the day, temperatures in the container rose considerably higher than ambient, but the container was well ventilated as the launch was prepared, such that the instruments experienced typical temperatures of 28–31 °C during synchronization, with only few exceptions. Nonetheless, the residual warming could be a source of bias relative to the surface meteorology observations and persist for tens of meters after the launch. Near-surface data were taken from ship measurements.

2.2 Real-time sounding data distribution

Sounding observations distributed in real-time over the Global Telecommunication System (GTS) improve atmospheric analyses for initializing and verifying weather forecasts, and improve subsequent reanalyses. Therefore, we aimed to disseminate as much of the full 1-second resolution radiosonde data from the EUREC⁴A campaign as possible over the GTS, **regardless of the launch time**. Radiosonde data (ascent and descent) from the *Atalante* (114 reports during the campaign) and the BCO (60 reports in February) were sent to the GTS through a Météo-France entry point. This allowed their assimilation in numerical weather prediction (NWP) systems. Most of the *Brown* data were sent to the US National Center for Environmental Prediction (NCEP). From here they were ingested into US Weather Service and Navy NWP systems, yet not European ones. None of the data from the *Merian* and *Meteor* could be transmitted to the GTS by satellite internet. However, during EUREC⁴A, 29 daily ascent soundings from the *Meteor* were sent to the GTS via the EUMETNET Automated Shipboard Aerological Program (E-ASAP), at around 1630 UTC. **The WMO station identifiers and designators for tracking the data within the GTS are listed in Table 1 for each station.**

World Meteorological Organization Binary Universal Form for the Representation of meteorological data (BUFR) were submitted to the GTS and exchanged among the platforms during the EUREC⁴A campaign. **BUFR supports ascending soundings (BUFR 309057), descending soundings (BUFR 309056, since BUFR Table version 31.0.0), and dropsondes released from aircraft (BUFR 309053).** The Vaisala MW41 sounding software writes quality-controlled BUFR files. The sounding instru-

ments measure relative humidity, but the BUFR files only contain the derived dew point temperature. We obtain the relative humidity from the dew point by inverting the dew point formula exactly.

2.3 Quality control and data formats

The Vaisala RS41 temperature and humidity measurements are highly robust and accurate, even in cloudy environments. The humidity sensor is actively heated to prevent water condensation and frost formation on the sensor surface. The Vaisala MW41 software writes proprietary .mwx binary files which are ZIP-archives that contain both the raw as well as the processed measurements. These data make up our Level-0 data set. We also provide Level-1 and Level-2 data, which we describe in the following. Our assignment of levels for the data sets adheres to the standards laid out in Ciesielski et al. (2012).

Sometimes the launch detection did not work properly, which resulted in differences of more than 30 m between the surface altitude and the first reported sonde altitude. Such profiles were reprocessed by correcting the launch time in the raw files. The files were then processed like the corrected files from the *Meteor* (see Section 2.1.2).

2.3.1 Level-1 data

Level-1 data in NetCDF format are quality controlled and averaged to 1-second resolution from the Level-0 data. Because the pressure, temperature and humidity are measured with a different sensor (PTU) than wind and position, the data are synchronized to the PTU time. This synchronization is done by the Vaisala MW41 software and the results are included in the Level-0 archive files. The Level-1 data were processed from these results.

The Vaisala MW41 sounding system applies a radiation correction to daytime temperature measurements by subtracting increments that vary as a function of pressure and solar zenith angle. The uncertainty of the radiation correction is typically less than 0.2 °C in the troposphere; uncertainty gradually increases in the stratosphere.

The Vaisala system applies algorithms to adjust for time lags of the RS41 sensors. At 10 hPa the response time of the temperature sensor is 2.5 s for an ascent speed of 6 m s⁻¹. At 18 km (75 hPa) with a temperature lapse rate of 0.01 °C m⁻¹ and an ascent rate varying from 3 to 9 m s⁻¹, the remaining uncertainty in the temperature reading due to time lag is 0.02 °C. At lower altitudes the uncertainty is even smaller. A time-lag correction is also applied to measurements of humidity. The response time of the humidity sensor is dependent on the ambient temperature. For example, at an ascent rate of 6 m s⁻¹ and at 1000 hPa it is <0.3 s for +20 °C and <10 s for -40 °C. The remaining combined uncertainty during the sounding is 4 % relative humidity.

After time-lag adjustments, the Vaisala MW41 quality control algorithm detects outliers and smooths the data to reduce noise. Periods of super-adiabatic cooling are interpolated, and this also applies to temperature differences right above the surface. The MW41 software applies the same correction and quality control steps to the descending and ascending phases of a sounding. Descending sondes, however, can be subject to uncontrollable factors. For example, a falling device may be affected by the remaining debris of a balloon. For this reason, Vaisala does not guarantee the same above-mentioned error margins for data from descending soundings. Our software (Schulz, 2020a) reads the processed Vaisala mwx, and MeteoModem BUFR cor files, and converts them to self-describing NetCDF files. We also add the ascent or descent rate, calculated from the geopotential

height and time information between consecutive measurements, to the NetCDF files. The resolution of the measurements is 1 s. The resulting NetCDF files are the Level-1 data set distributed here.

2.3.2 Level-2 data

To facilitate scientific analyses, Level-2 data are provided on a common altitude grid with bin sizes of 10 m, by averaging the Level-1 data. Mean temperature, wind components, position, and logarithm of pressure are directly averaged within height centered bins. Relative humidity is calculated from the mean of the Level-1 water vapor mixing ratio, calculated from the water vapor pressure formula of Hardy (1998), which is also used by the Atmospheric Sounding Processing ENvironment (ASPEN) software (Suhr and Martin, 2020) for EUREC⁴A dropsonde measurements. Surface-launched soundings were not reprocessed with ASPEN, as the ASPEN manual warns against duplicating quality control procedures applied by the Vaisala MW41.

In case of missing data within a sounding, we linearly interpolate gaps of up to 50 m. Gaps larger than 50 m, as well as data below 40 m in our Level-2 data set originating from the ship soundings, are filled with missing values. Discarding the lowest 40 m avoids potential biases in the soundings associated with local ship effects, like heating or exhaust plumes, and other problems that are discussed by, e.g. Hartten et al. (2018). Yoneyama et al. (2002) found ship influences on radiosonde measurements to extend no further than 40 m above the deck. For descending soundings the raw data near the surface are missing as the signal is lost due to Earth's curvature at 300–800 m above mean sea level. The median of the lowest descent measurement is at 340 m.

3 Data characteristics

3.1 Ascending versus descending soundings

We begin with an examination of instrument ascent and descent speeds for the different platforms (Fig. 6). The figure is based on the ascent (or descent) rates with a 10-m vertical resolution included in the Level-2 data. The median ascent speed in the mid-to-upper troposphere is between 4.5 and 5 m s⁻¹ for radiosondes launched from the BCO, *Atalante* and *Merian* (Fig. 6a, g, i). Radiosondes launched from the *Meteor* and the *Brown* ascended at slightly smaller slower rates of about 4 m s⁻¹ (Fig. 6c, e). For all platforms and at all altitudes the 10th and 90th percentiles are roughly symmetric about the median ascent rate and fall mostly within ± 1 m s⁻¹ of the median. Radiosondes from the *Atalante* and *Merian* appear to have experienced stronger updrafts in the upper troposphere. This is consistent with sampling the more convectively-active conditions in the south, where there is a warmer ocean surface, more precipitable water, deeper convection and a greater chance of land influences. Above 20 km, the median ascent rate and the spread in ascent rates increase for all platforms.

Descent speeds exhibit a much stronger functional dependence on altitude (Fig. 6b, d, f, h, j). For platforms that employed parachutes (BCO, *Meteor*, *Atalante* and *Merian*), descent rates decrease towards the ground to a minimum of about 5 m s⁻¹ in the lowest kilometers. Instruments without a parachute from the *Brown* have descent rates of slightly less than 15 m s⁻¹ in the lowest few kilometers. The positive skewness of the distributions associated with stations that used parachutes is due to

260 descending radiosondes with broken or detached parachutes, or with unexpected behavior of the torn balloon remains. With the exponential decrease of air density with altitude, descent rates increase non-linearly and rapidly with altitude, exceeding 20 m s^{-1} between 20–25 km when parachutes were used and exceeding 40 m s^{-1} in case of the *Brown*.

Despite corrections and quality control steps applied by MW41, measurements taken during descent may be accompanied by larger uncertainties due to less favorable and more variable measurement conditions. To establish what degree of confidence we may attribute to the descent data, Fig. 7 compares the measurements of horizontal wind speed, air temperature and relative humidity between ascending and descending soundings. We do not expect perfect agreement between ascending and descending soundings, for several reasons. First, the instruments drift substantial horizontal distances and hence systematically sample a downwind location (as illustrated in Fig. 3 for the BCO). Meridional horizontal drift could create systematic biases. Second, there are variable time lags of the order of a couple of hours between ascending and descending measurements, which we expect might increase the scatter between ascent and descent measurements but not create systematic differences. A systematically different response of the sensors during descent might be the most important factor for biases. We also note that the number of descent profiles available for computing statistics is in some cases substantially smaller than the number of ascent profiles (Fig. 1). The numbers of available measurements are again listed on the left hand side of Fig. 7. All quantities shown in Fig. 7 are computed from matched ascent-descent pairs of the same instrument.

275 Measurements of horizontal wind speeds do not show statistically significant differences between ascent and descent (the mean lies within the 95 % confidence intervals), with the exception of the *Brown*. Here, wind speeds at around 20 km altitude are stronger for the ascent. This systematic difference could be related to excessively rapid descent rates. Similar results are found for measurements of air temperature (Fig. 7b, d, f, h, j). In case of the *Brown*, stratospheric temperature observations during descent are warmer by more than 1°C , suggesting a bias due to high descent rates. The same bias exists for the other
280 platforms, but the effect is smaller and not statistically significant at the 95 % confidence level. Differences in relative humidity are not statistically significant inside the troposphere.

3.2 Synoptic conditions

We first present the synoptic situation for the region defined by the *Meteor* and the BCO soundings. Our initial analysis focuses on the soundings for these two platforms because they define a more or less fixed geographic area – radiosondes launched
285 from the *Meteor* were almost all launched between 12.5°N and 14.5°N along 57.15°W – bounding the subdomain that was most intensively sampled. A comparison between twelve BCO soundings with coincident and nearly co-located ship-based soundings (ships were positioned just offshore of the BCO) showed no evidence (Fig. A4) of a systematic influence of the island on the BCO soundings. Hence, the BCO soundings appear representative of the western most boundary of the marine measurement area. Focusing on a fixed region during the period of most intensive airborne operations, between January 20 and
290 February 17, also provides a reference for quantifying differences in soundings taken outside of this region, or time period, as is discussed at the end of this subsection.

Synoptic differences among variables believed to be important for patterns of low-level cloudiness suggest that: (i) the *Meteor* and the BCO sample the same synoptic environment; and (ii) changes in the environment can usefully be described by

week-to-week variability over the four weeks starting on Monday, January 20. The lower tropospheric stability (LTS), the near surface winds, the lifting condensation level (LCL) of near-surface air, and the hydrolapse track each other well (Fig. 8). The hydrolapse marks the depth of the trade-wind cumulus layer. It is defined as the mean height where mean relative humidity on a centered running 500 m range first drops below 30 %. LTS is defined as difference of potential temperature at 700 hPa and the mean potential temperature in the lowest 200 m. Fig. 9 further illustrates that the LCL tracks well the lowest cloud bases as measured by the *Meteor* ceilometer. Week-to-week variations as deduced from the soundings of either platform show the first and last week to be characterized by a deeper moist layer, and lessened lower tropospheric stability, the latter primarily explained by changes in the potential temperature at 700 hPa. The two week period starting on January 27 has a much shallower trade-wind layer and stronger stability. Near surface winds vary somewhat out of phase with the moisture variability, with winds stronger in the second half of the four week period, and weaker in the first half. The LCL shows very little synoptic variability.

Cloud observations are also included in Fig. 8. Reports of mid-level (C_M) and high-level (C_H) clouds are derived from 3 hourly SYNOP observations reported by the Barbados Meteorological Service at Grantley Adams International Airport. If a reported mid or high-level cloud type was persistent through the day (more than three reports) it is included via its WMO cloud symbol² in Fig. 8. Notable are mid-level clouds that coincide with the deepening of the marine layer, particularly during the period at the end where a layer of altocumulus ($C_M = 4$) persisted for several days (Fig. 9). Observations of low clouds (C_L) indicated that $C_L=8$ and $C_L=2$ where the dominant low-level clouds; both evident on almost every day with little evidence of synoptic variability. This is also evident from the *Meteor* ceilometer measurements (Fig. 9). For this reason, in Fig. 8 we instead identify days when particular patterns of mesoscale variability were in evidence. We adopted the four patterns, Sugar, Gravel, Flowers, Fish following Stevens et al. (2020). While the low and small Sugar clouds appear with little organization, Gravel clouds reach deeper extents and organize along gust fronts. The fish-bone like organization of clouds on horizontal scales of 200–2000 km is described by the Fish pattern, and large stratiform, often circular-shaped cloud clumps are labeled as Flowers. Whether or not one particular pattern was identified was taken from a cloud classification activity organized by one of the authors (H. Schulz). These patterns suggest that the initial moist period has the satellite presentation of Fish, and that the period of increased lower-tropospheric stability and strengthening winds on February 2 is associated with the pattern Flowers, consistent with the analysis of Bony et al. (2020).

To give a better impression of the synoptic variability, the period identified with the Fish pattern, between January 22–24, is investigated further. The visible satellite imagery from MODIS on Aqua (Fig. 10a) illustrates the large-scale characteristics of the observed Fish cloud pattern, covering the BCO and the northern latitudes of the observations region. The pattern resembles a spine in a surrounding cloud-free area and was accompanied by unseasonably large amounts of surface precipitation. Fig. 10b illustrates the moistening of the atmosphere and the deepening of the boundary layer, as measured at the BCO, over the course of this event. Between January 20–26, the increase of integrated moisture up to 55 kg m^{-2} coincides well with the deepening moist layer, thus also with changes in cloud top height and trade wind inversion height. Before and after the event, the inversion layer height was around 2 km (Fig. 8), and the boundary layer was characterized by a mixture of Gravel and Sugar, albeit the latter not on a scale that lent itself to identification from the satellite imagery. During the peak of the event on January 22 and

²These symbols are taken from the 2017 edition (Table 14) of the WMO Cloud Atlas (www.wmocloudatlas.org).

23, the moisture layer deepened up to 5 km. While the Fish cloud pattern passed over BCO, the pressure in the boundary layer decreased by up to 4 hPa (see Fig. 11e) and the temperature in the upper middle troposphere (6–8 km) showed a slight positive anomaly (see Fig. 11a). The rain intensity, measured at BCO with a Vaisala WXT-520 ground station, peaked at 15 mm h⁻¹, and precipitation events were persistent, in contrast to the short rain showers more typical of the dry season (Stevens et al., 2016). Bony et al. (2020) found that the Fish cloud pattern often occurs under weaker surface trade wind speeds below 8 m s⁻¹; the sounding data confirm this, as the measured wind speeds lie well below this threshold in the lower boundary layer, e.g. Fig. 8.

Given that the vertical structure of the humidity field appears to be a strong indicator of synoptic variability, time-height humidity plots for all of the platforms are used to explore the coherence of synoptic conditions sampled by individual platforms. This analysis (Fig. 12) shows that soundings from the *Brown*, which moved around more, but stayed mostly north of 12.5 °N and east of the *Meteor*, sampled a similar synoptic environment. The *Merian* and *Atalante* however were further south and their soundings show a humidity structure and evolution that is less coherent than seen by the ships in the Trade-wind Alley. Based on this finding and because performing the same analysis for any one station does not change the big picture, we composite the soundings from all of the platforms north of 12.5 °N. Figure 11 shows the temporal evolution of atmospheric conditions for the full period of data coverage averaged north of 12.5 °N, i.e., over the Trade-wind Alley. Before January 22 the mid-troposphere is relatively cool and zonal winds in the upper troposphere are strong. From January 22 onward the observational domain experienced warmer temperatures, weaker upper-tropospheric westerlies, as well as weaker easterlies near the surface. Positive pressure anomalies first appear in the upper troposphere and reach the surface at the end of January when a ridge starts to dominate the area. Surface and upper-tropospheric winds strengthen again after February 6 when the positive pressure anomaly fades. A strong moistening of the mid and upper levels is seen around February 13, which coincides with a directional change of the meridional winds at these levels, favoring the aforementioned extensive and persistent altocumulus cloud layer (Fig. 8).

Most differences between the structure of the atmosphere within the Trade-wind Alley (North of 12.5 °N) and the ‘Boulevard des Tourbillons’ (southern corridor) are confined to the structure of the lower-tropospheric humidity. South of 12.5 °N, the atmosphere was on average much more humid in the lower and middle troposphere, as shown in Fig. 13. This humidity anomaly is not persistent, as dry conditions, similar to those observed north of 12.5 °N, were also present; it can rather be associated with more frequent periods of a deep moist layer and deeper convection, for example as observed during the period around January 29 (see Fig. 12). Additional, albeit less substantial differences (not shown), are that middle-upper troposphere relative humidities (between 7–10 km) are actually somewhat drier in the South. There is very little evidence of systematic differences in the temperature structure between the northern and southern soundings, except for a hint of enhanced stability in the upper troposphere (11–15 km) in the North. Over the ‘Boulevard des Tourbillons’, the depth of the near surface easterly layer is 1–2 km shallower and between 5–15 km, the westerlies have a stronger northerly component.

The EUREC⁴A field campaign during January–February 2020 included among its wide range of observational platforms an extensive radiosonde network, consisting of the Barbados Cloud Observatory and four research vessels. 182 radiosondes of type RS41-SGP were successfully launched in a regular manner between January 16 and February 17 from the BCO, 203 between January 18 and February 19 from the *Meteor*, 169 between January 8 and February 12 from the *Brown*, 139 between
 365 January 21 and February 16 from the *Atalante*, and 118 between January 20 and February 19 from the *Merian*. In addition, 47 MeteoModem radiosondes of type M10 were launched from the *Atalante* during intensive observational periods to sample variability associated with sea surface temperature fronts. These are described in the appendix.

We made data at three stages publicly available. Level-0 data contain the raw .mwX binary files, which can be read and processed with the MW41 software. Level-1 data were subject to Vaisala’s standard quality control algorithm, which detects
 370 outliers in the profiles, performs a smoothing to reduce noise, and applies time-lag and radiation corrections. The Level-1 file format is NetCDF with a temporal resolution of 1 s. To facilitate scientific analyses, Level-2 data are vertically gridded by averaging Level-1 data in 10-m bins. All soundings, ascending and descending, from each platform were collected into one NetCDF file for the Level-2 data.

The *Meteor* and the *Brown* followed nearly-orthogonal sampling lines, mostly in the latitude band 12.5–14.5 °N, whereas
 375 the *Atalante* and *Merian* sampled conditions further to the south. It was a central goal of EUREC⁴A to better understand the formation and feedbacks of different patterns of shallow cumulus clouds. We were fortunate that nature provided us with a wide variety of cloud conditions, which are reflected in the radiosonde data. The six weeks of sounding data at high temporal resolution should render the radiosonde data described herein useful for a large variety of scientific analyses.

5 Code and data availability

380 Raw Level-0 data consist of single files per sounding in .mwX. format, which combine ascent and descent from each instrument. Quality-controlled Level-1 data consist of single files per sounding in NetCDF format, with separate files for ascent and descent. Level-2 data are stored in a single file per station and include data on a 10-m vertical resolution grid, including all available ascents and descents. Ascent and descent can be distinguished by a flag that indicates the direction. All data (Stephan et al., 2020) are archived and freely available for public access at AERIS (<https://doi.org/10.25326/137>). Our software, which we
 385 used to convert to NetCDF format is also publicly available (Schulz, 2020a; <https://doi.org/10.5281/zenodo.3712223>).

Appendix A: Extra soundings on board the *Atalante*

In addition to the regular Vaisala soundings, further soundings were performed from the *Atalante* primarily to sample the lower atmosphere across sea surface temperature (SST) fronts associated with oceanic mesoscale dynamics. An independent radiosonde receiver was used to not interfere with the regular soundings depicted in this article. MeteoModem M10 radiosondes
 390 were chosen for availability and cost. In order to decide the period of intensive sampling using these sondes, we first identified

on a daily basis the ocean mesoscale eddies and currents by applying the TOEddies detection algorithm (Laxenaire et al., 2018) to the Ssalto/Duacs Near Real Time (NRT) altimeter products (Absolute Dynamic Topography – ADT – and the associated surface geostrophic velocities; Ablain et al., 2017, Taburet et al., 2019).

These data were successively analyzed together with the NRT SST produced by Collecte Localisation Satellites (CLS), the ship's ThermoSalinoGraph (TSG) 5 m-depth temperature measurements, and ARPEGE and ECMWF forecasts in order to decide in real time the launching strategy. The NRT CLS SST is produced as a 1-day average, high-resolution product, which is a simple data average of the satellite measurements taken over the previous day, and has a resolution of 0.02° in latitude and longitude. This product may have local gaps due to the presence of clouds or missing data. **The CLS SST NRT product is derived from nighttime observations (to avoid diurnal warming of the sea surface) by the MODerate-resolution Imaging Spectroradiometer (MODIS) on board TERRA and AQUA satellites, the Advanced Very High Resolution Radiometer (AVHRR) on board METOP-A and -B, the Visible Infrared Imager Radiometer Suite (VIIRS) on board Suomi-NPP, the Advanced Himawari Imager (AHI) on board HIMAWARI-8, and the Advanced Baseline Imager (ABI) on board GOES-16 and -17.**

Precisely setting the sounding periods was difficult because the satellite observations were only available for the previous day with additional uncertainties in the location of SST fronts due to cloud screening. Furthermore, this strategy was defined in coordination with the *Merian* to take into account the oceanographic observation goals common to both ships.

The first targeted and intensive radiosonde observation leg took place on January 26. 11 MeteoModem sondes were launched while crossing a SST front associated with a relatively cold filament (-0.5 to -1°C SST anomaly) steered from the Guyana coast by a mesoscale anticyclonic eddy (Fig. A1a). During this leg, the ship crossed a front of about 0.5°C extending over 30 km with near surface wind of $6\text{--}7\text{ m s}^{-1}$ magnitude and $60^\circ\text{--}70^\circ$ direction. During this leg the ship was heading eastward, almost into the wind. Figure A1a shows the February 25 SST map, chosen as clouds prevented retrievals on the following day. According to the satellite product, one would have expected to meet the front further east. Fortunately, a first diagonal transect during the night provided us with the actual front location.

The second targeted and intensive radiosonde observation leg took place on February 2–3. This leg lasted for about 24 hours during which 28 MeteoModem radiosondes were launched while the ship was zigzagging in order to sample several times the northeastern edge of a cool SST anomaly of nearly -1°C associated with coastal upwelling off the Suriname and French Guyana coast (Fig. A1b). During this leg, the ship was moving westward and sampled SST variations of $0.3\text{--}1^\circ\text{C}$ extending over 50–60 km. At this time the near surface wind was variable in direction, $40^\circ\text{--}80^\circ$, and relatively strong ($8\text{--}11\text{ m s}^{-1}$).

The remaining MeteoModem radiosondes were launched on few diverse occasions: two were launched in the center of the warm core of a second eddy on January 27. Another radiosonde was launched under a convective system on February 10. The last four launches took place in cloud streets on February 17.

We used M10 GPS radiosondes with an SR10 station and EOSCAN (1.4.200306) software. **With the exception of one sounding**, only ascent data are available for these soundings as most of the launches were stopped manually at about 10 km height to increase the sampling frequency of the lower atmosphere in regions characterized by SST fronts. Launch frequencies reached up to one sounding every 40 min during the intensive launch periods. Therefore, several radiosondes were emitting at the same time, so frequencies had to be changed within the 400.4–403.4 MHz band to avoid interference. M10 radiosondes measure rela-

tive humidity and temperature, from which dew point temperature is deduced. The altitude and horizontal displacements of the radiosondes are measured by GPS and are used to diagnose the horizontal wind components. Unlike with RS41 SGP sondes, the pressure is deduced from the altitude and the surface station pressure measurement, using the hydrostatic approximation. Our published data formats, NetCDF and ASCII formatted files (.cor files), both contain data reported every second. The raw

430 MeteoModem data are processed in the same way as the Vaisala soundings to create Level-1 and Level-2 files that match the format of the corresponding Vaisala data. The only difference is that the description of the MeteoModem corrections that are automatically applied by the software is a trade secret and therefore not known to us. However, the M10 sondes are currently in the process of being certified by the Global Climate Observing System Reference Upper-Air Network (GRUAN). If the GRUAN certification is granted, details on these corrections will become available. We checked for and corrected spurious

435 data in the surface observations using handwritten log-sheets filed during the campaign. ~~Note that in Level-1 data, constructed from BUFR reports that do not contain relative humidity, the latter is deduced from the dew point temperature using the Magnus-Tetens formula and might therefore slightly differ from the value in the raw .cor files that provide the direct measurement of the radiosondes.~~

Figure A2 illustrates the outcome of these targeted and intensive radiosonde observations with results from the February

440 2–3 intensive observation period (Fig. A1b). Profile color (Fig. A2a–c) denotes the SST measured by the ship at the time of the launch (Fig. A2d). Blue (red) profiles are thus on the cold (warm) side of the SST front. These profiles are from raw data (level-0) and no attempt was made to validate, correct or remove doubtful data such as the surprisingly cold layer between 800–900 m altitude that can be seen in one of the blue potential temperature profiles (Fig. A2a). No attempt has either been made to disentangle diurnal or synoptic scale variability from the imprint of the SST front on the lower atmosphere. However,

445 one can note that the warm side of the SST front was sampled mostly during nighttime (local noon at 1530 UTC, nighttime from 22–10 UTC). There is a clear tendency for warmer boundary layers over the warm side of the front than over the cold side (Fig. A2a). On the other hand, the height of the mixed layer, that can be defined as near homogeneous potential temperature layers close to the surface, tends to be deeper over the cold side than over the warm side. This contrasts with results obtained over stronger SST fronts from observation (Ablain et al., 2014) and modeling studies (e.g., Kilpatrick et al., 2013; Redelsperger

450 et al., 2019) and suggests that the lower atmosphere does not solely respond to the SST gradient. Over the cold side, wind speed tends to decrease with altitude (Fig. A2b). Over the warm side, and despite a larger variability from a profile to another, the wind speed tends to be more homogeneous in the vertical than on the cold side. Because the mixed layer depth is shallower over the warm side, it is however difficult to interpret this as the result of a stronger vertical turbulent mixing. Overall, near surface wind speed tends to be slightly weaker on the warm side than on the cold side. There is also a noticeable change in

455 wind direction throughout the boundary layer from E-NE over the warm side to NE over the cold side (Fig. A2c).

Finally, we provide a first assessment of the quality of MeteoModem M10 measurements based on the *Atalante* soundings, as also Vaisala soundings were launched during the intensive MeteoModem periods. We compare MeteoModem and Vaisala wind, temperature and relative humidity profiles for 8 pairs of soundings that were launched within 25 min (Fig. A3). Choosing such a small time period certainly limits the number of difference profiles that can be computed, but it ensures that the two

460 radiosondes sampled comparable situations. Mean difference profiles and corresponding standard deviations are computed on

100 m bins. Neither horizontal wind components (Fig. A3a, b) nor temperature (Fig. A3c) show any clear bias, although the differences between MeteoModem and Vaisala can be a few m s^{-1} for the wind components (standard deviation of about $0.5\text{--}1 \text{ m s}^{-1}$) and about 1°C for temperature (standard deviation of about $0.1\text{--}0.2^\circ\text{C}$). On the other hand, despite a large noise below 4 km height, relative humidity shows a rather homogeneous moist bias of about 5 % ($1\text{--}5\%$ standard deviation) in MeteoModem measurements compared with Vaisala (Fig. A3d). No correction was applied, neither to the temperature nor to the relative humidity measurements. In particular, corrections for the relative humidity seem necessary but are still a matter of research. An example of such corrections, developed for soundings in the continental mid-latitude can be found in Dupont et al. (2020).

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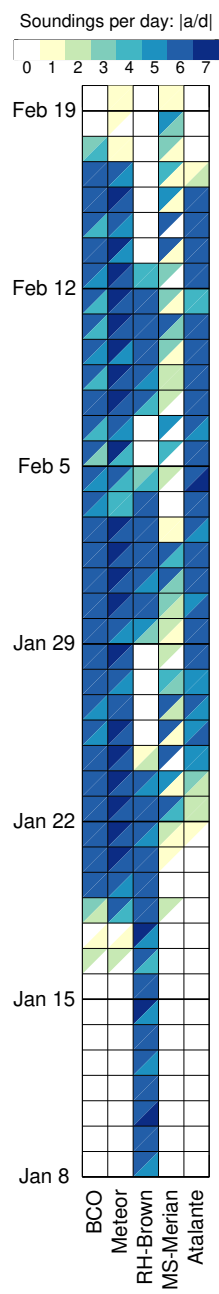


Figure 1. Daily number of ascending (upper left triangles) and descending (lower right triangles), respectively, soundings associated with each platform.

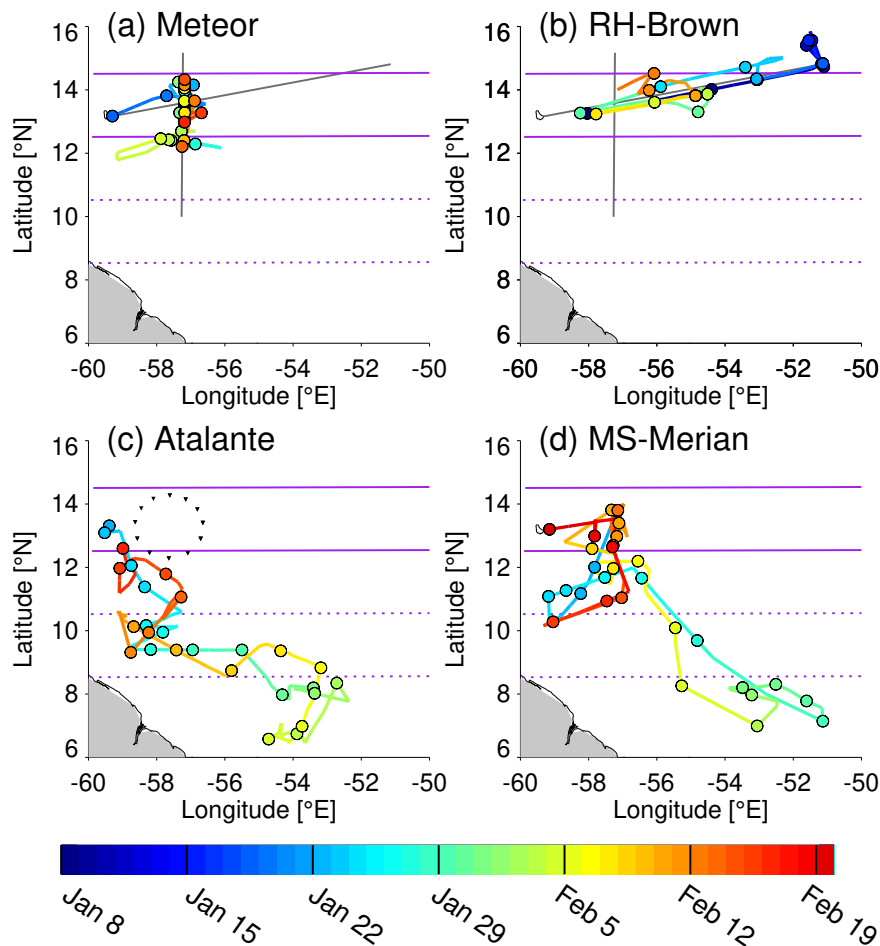


Figure 2. Routes and launch coordinates of radiosondes for the four research vessels colored by date. Circles mark the locations of the first radiosonde launch on each day. The gray lines in (a) and (b) mark the nearly orthogonal lines that were sampled by the *Meteor* (North–South) and the *Brown* (West–East). Purple lines mark the northern (12.5–14.5 °N; solid) and southern (8.5–10.5 °N; dashed) latitude bands that we later use to define a North (Trade-wind Alley) and South (Boulevard des Tourbillons) domain. Downward pointing black triangles in (c) mark the locations of dropsonde releases during regular circular aircraft flights.

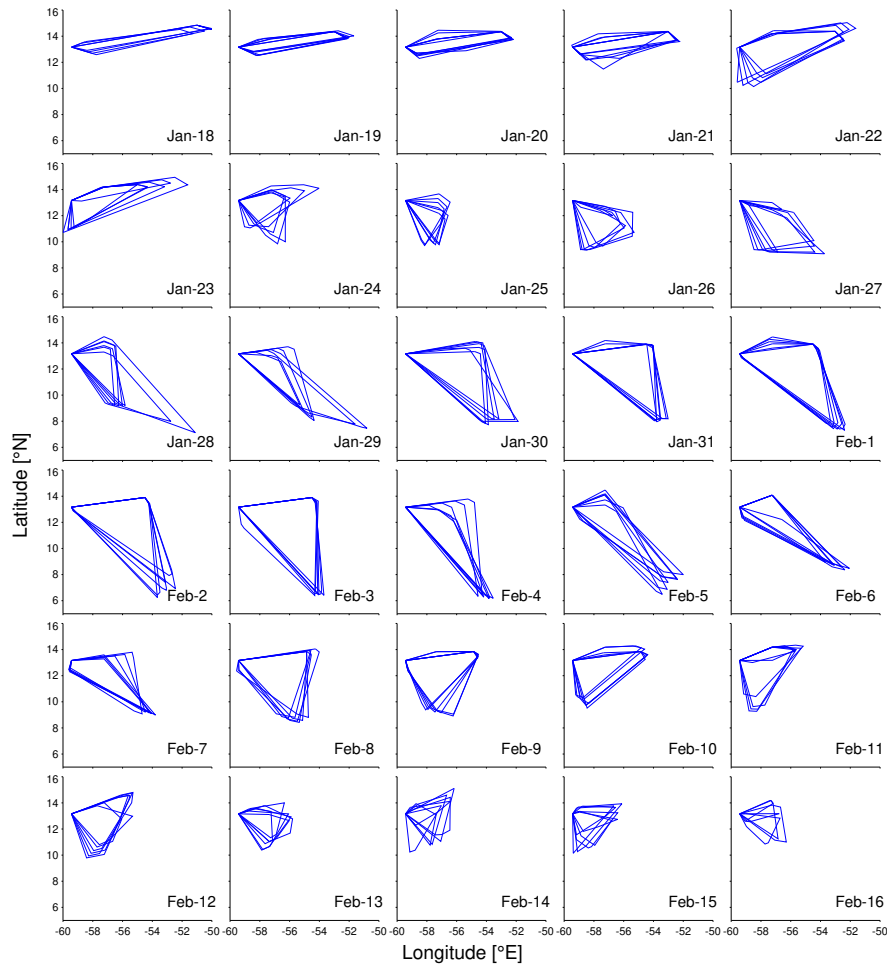


Figure 3. For each day between Jan-18 and Feb-16, 4-hourly polygons mark the outer bounds of the radiosonde network. Polygon vertices correspond to starting locations of either ascending or descending soundings that occurred within ± 2 hours of a fixed time.

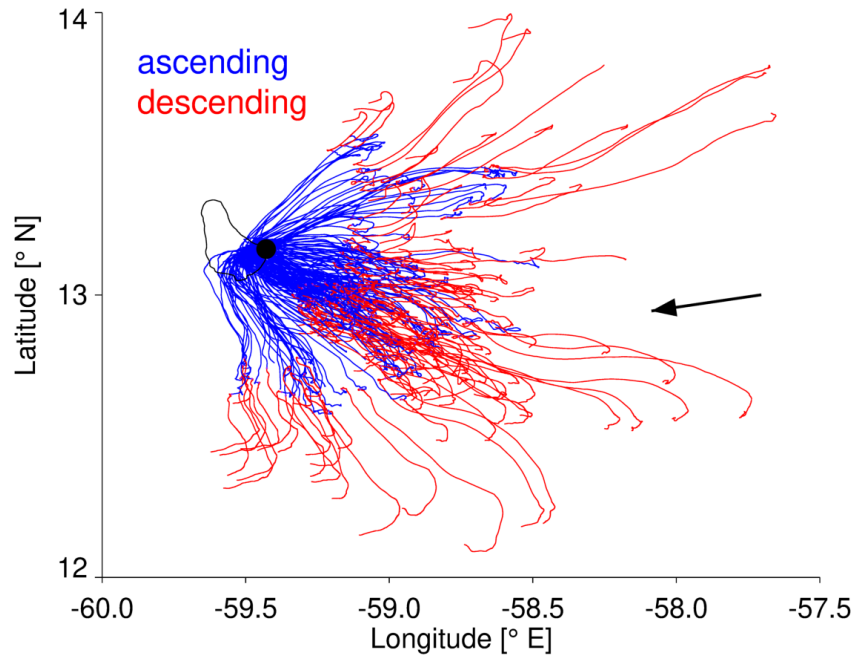


Figure 4. The horizontal trajectories of ascending and descending, respectively, radiosondes launched from the BCO. The location of the BCO on Barbados is marked by the thick black dot. The black arrow is the mean wind direction at 500 m as measurement by ascending soundings launched from the BCO.

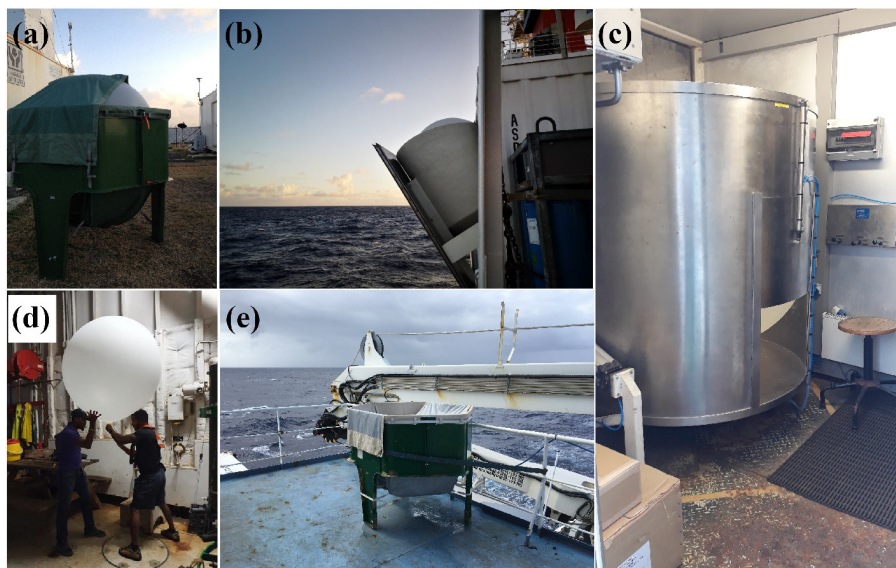


Figure 5. Photographs of the (a) launcher with balloon at the BCO, (b) DWD launcher with balloon on board the *Meteor*, (c) launch container with balloon on board the *Merian*, (d) manual balloon filling procedure on board the *Brown*, (e) empty launcher on board the *Atalante*.

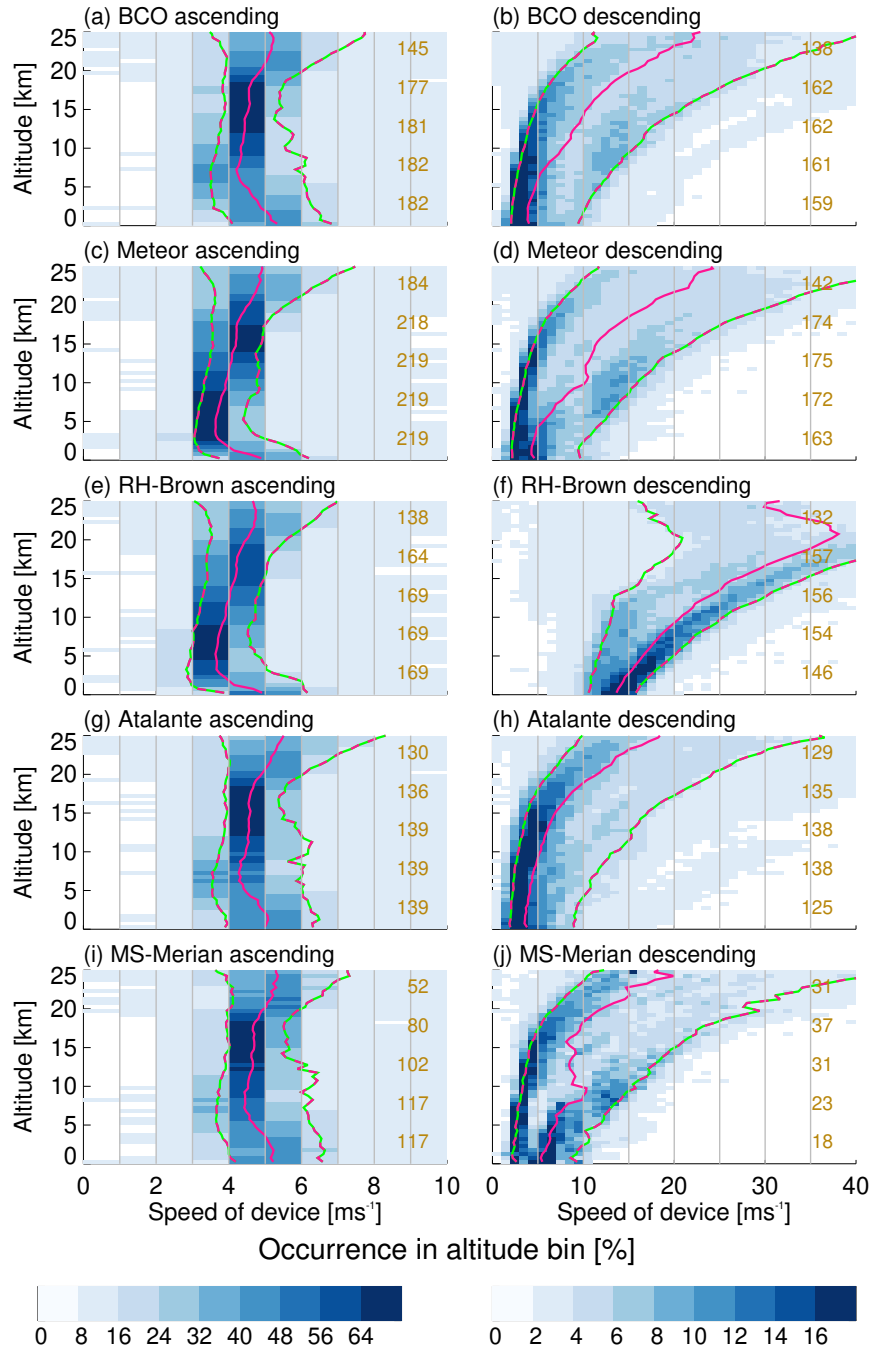


Figure 6. Instrument (left) ascent and (right) descent speeds as a function of height. The sum of occurrence frequencies in each altitude bin is 100 %. The pink line shows the median profiles and the pink-green lines show the 10th and the 90th percentiles, respectively. Altitude bins are 500 m deep and speed bins are 1 m s^{-1} wide. The numbers of radiosondes that crossed the corresponding height-levels (2.5, 7.5, 12.5, 17.5 and 22.5 km, respectively) are shown in each panel.

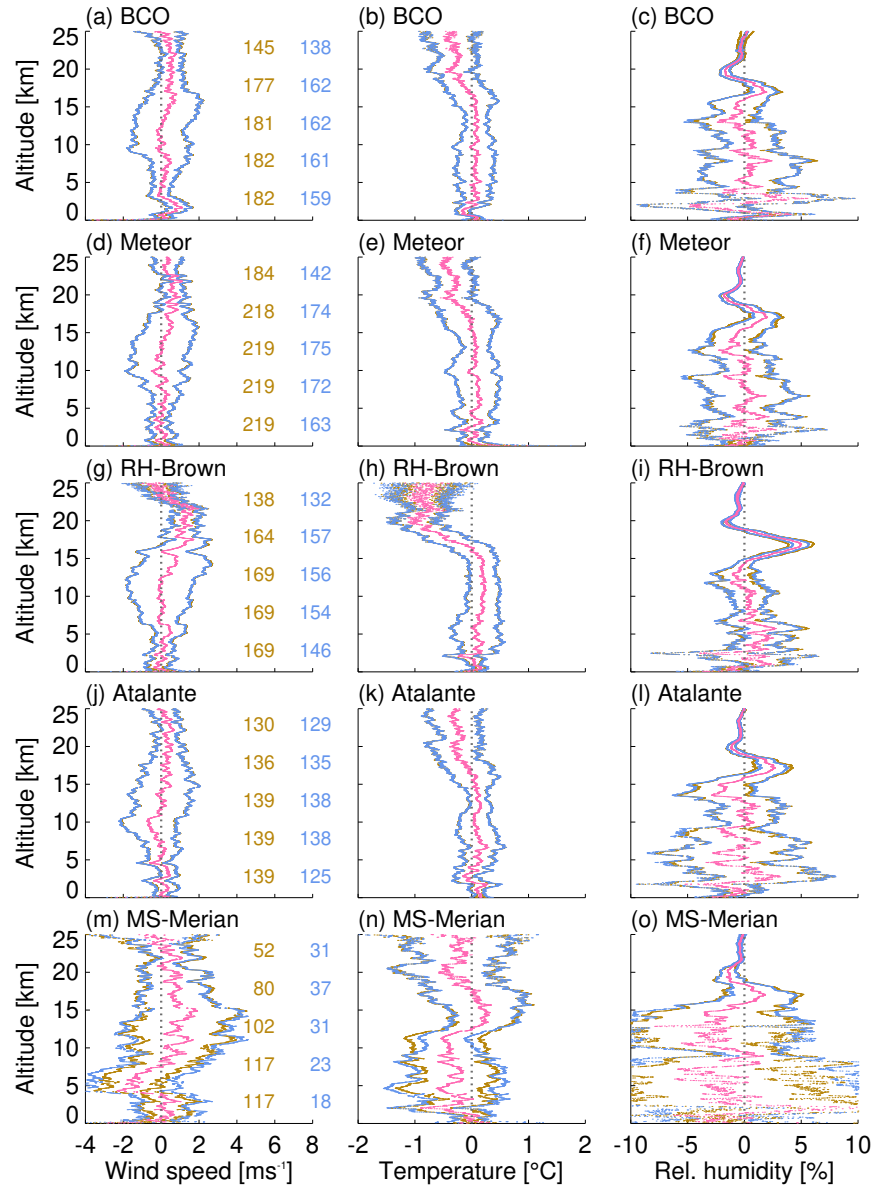


Figure 7. Comparison of (left) horizontal wind speed, (middle) air temperature, and (right) relative humidity, measured during ascent and descent. The pink dots show the time-averaged values average over all included ascent profiles minus the time-averaged values average over all included descent profiles. Brown (blue) dots show the 95 % confidence intervals for ascent (descent). Numbers inside the panels on the left-hand side show the counts of ascending (brown) and descending (blue) radiosondes that crossed the corresponding height-levels (2.5, 7.5, 12.5, 17.5 and 22.5 km, respectively.)

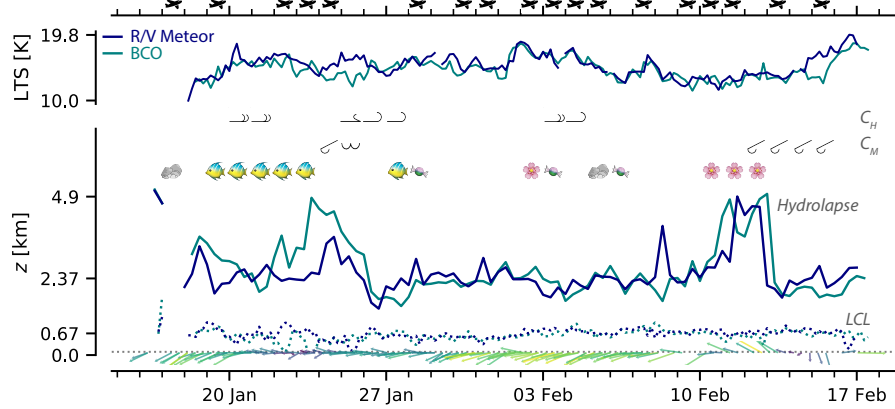


Figure 8. Synoptic overview of period and region of intensive aircraft measurements. Plotted are the ~~potential temperature at 700 hPa~~ **lower tropospheric stability (LTS)**, the height of the hydrolapse ~~defined as the mean height of a running 500 m range in which mean relative humidity first drops below 30 %~~, the lifting condensation level (LCL) and the wind vector averaged over the lower 200 m. Winds are 12 h median values, other quantities are resampled on a 4 h interval, with median values plotted except for the LCL where minimum values are plotted. For the wind vectors the maximum and minimum wind speeds are 12.3 m s^{-1} and 2.0 m s^{-1} , respectively. Tick marks denote maximum and minimum θ_{700} **LTS**, and maximum and median height of *Meteor* hydrolapse and the mean height of the LCL (*Meteor*). Also shown are days when aircraft with dropsondes were flying, the synoptic cloud observations of mid-level (C_M) and high (C_H) clouds with the associated WMO cloud-symbol (Table 14 of 2017 World Meteorological Organization Cloud Atlas, <https://cloudatlas.wmo.int/en/home.html>) that predominated for that day. Cloud types are taken from the Barbados Meteorological Service SYNOP reports. Days on which a mesoscale pattern of shallow convection, following the classification activity of Schulz (2020b), was readily identified are indicated by the emojis for Fish, Sugar (candy), Flowers or Gravel (rocks).

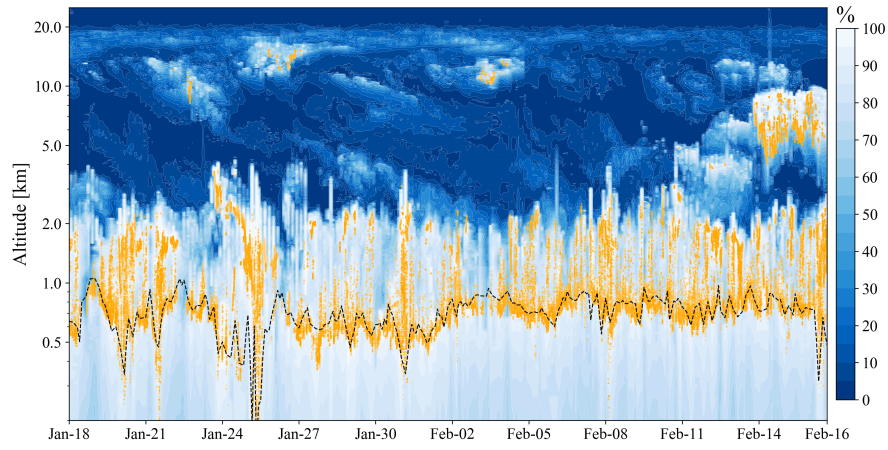


Figure 9. Comparison between ascending and descending soundings and ceilometer measurements on the *Meteor*. The relative humidity from radiosonde measurements is shown in blue-to-white shading. The black dashed line represents the lifting condensation level calculated based on Bolton (1980). Cloud base heights as observed by the ceilometer are marked with orange dots. The vertical axis is chosen to be logarithmic for better visibility of the moisture distribution near the surface. The time-axis for the soundings uses launch time. The temporal resolution of the ceilometer data is 10 s. Low-altitude relative humidity profiles (300–800 m) of the descending soundings were recovered by assuming a dry adiabat temperature and a constant humidity profile.

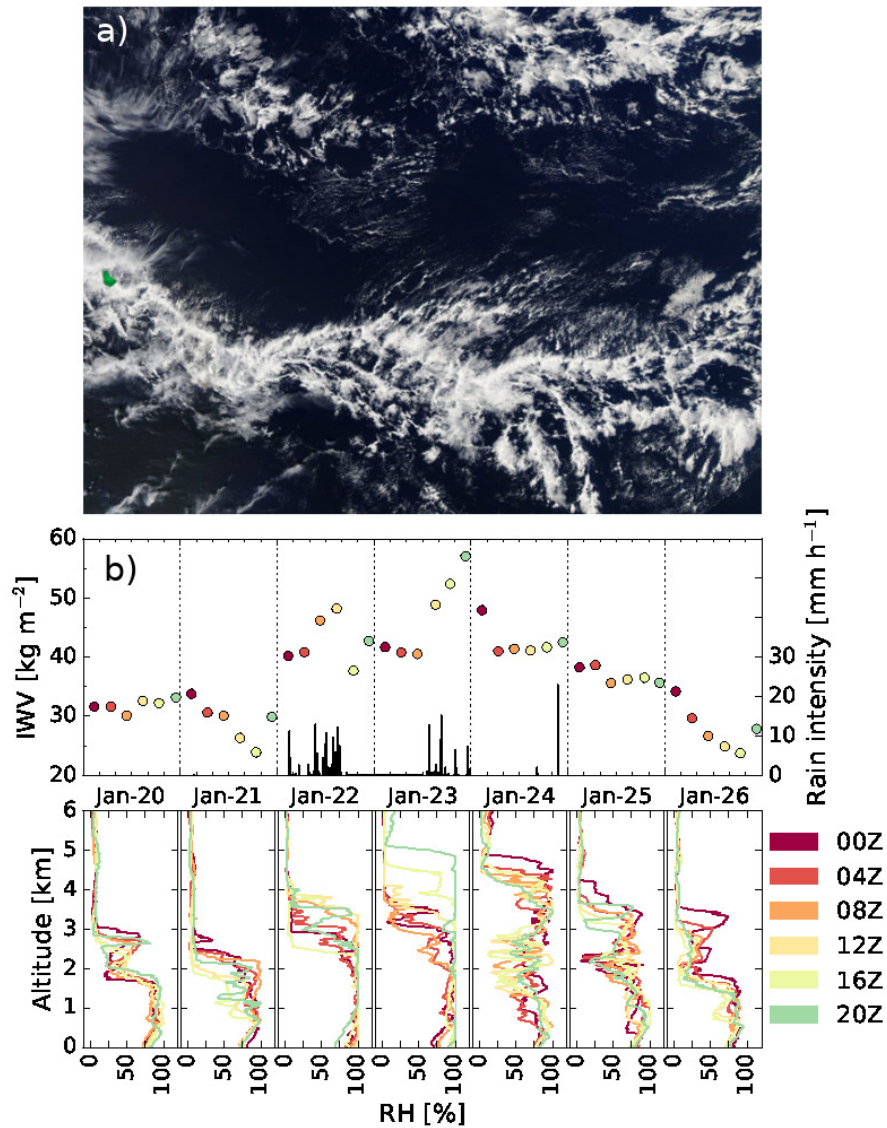


Figure 10. Fish cloud pattern passing Barbados between January 22–24, 2020. (a) MODIS-Aqua scene from January 22. The image covers 9–18 °N, 48–60 °W with Barbados shown in artificial green. (b) Temporal evolution of relative humidity (lower panel) and integrated water vapor (IWV; upper panel, color-coded) as measured by the BCO soundings January 20–26. Profiles and calculated IWV values are color-coded according to the nearest hour of the sounding reaching 100 hPa. The upper panel also shows a one-minute running mean of rain intensity recorded at BCO (black).

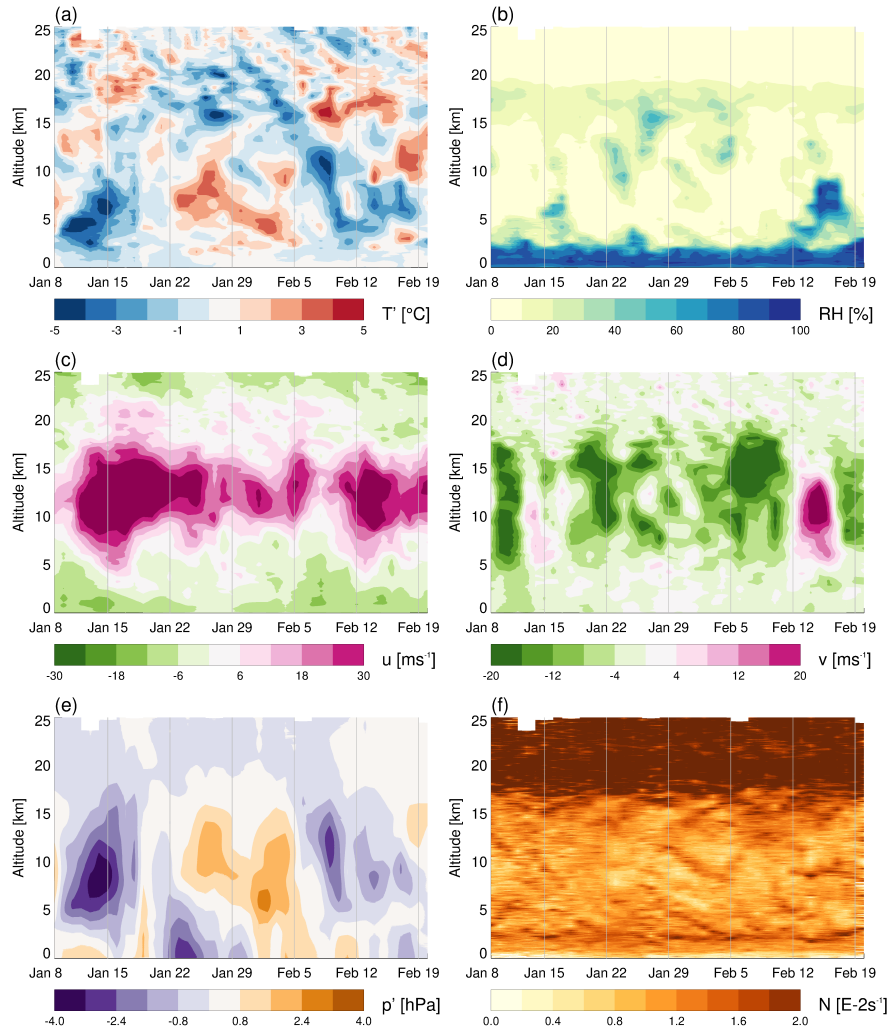


Figure 11. (a-e) Time-height cross sections of daily (a) temperature anomaly, (b) relative humidity, (c) zonal wind, (d) meridional wind anomaly, (e) pressure anomaly and (f) Brunt-Väisälä frequency (units of 10^{-2}s^{-1}), computed from ascending soundings north of 12.5°N . The data combine 182 soundings from the BCO, 169 from the *Brown*, 159 from the *Meteor*, 30 from the *Merian* and 4 from the *Atalante*. Anomalies are defined as deviations from the time average at each altitude.

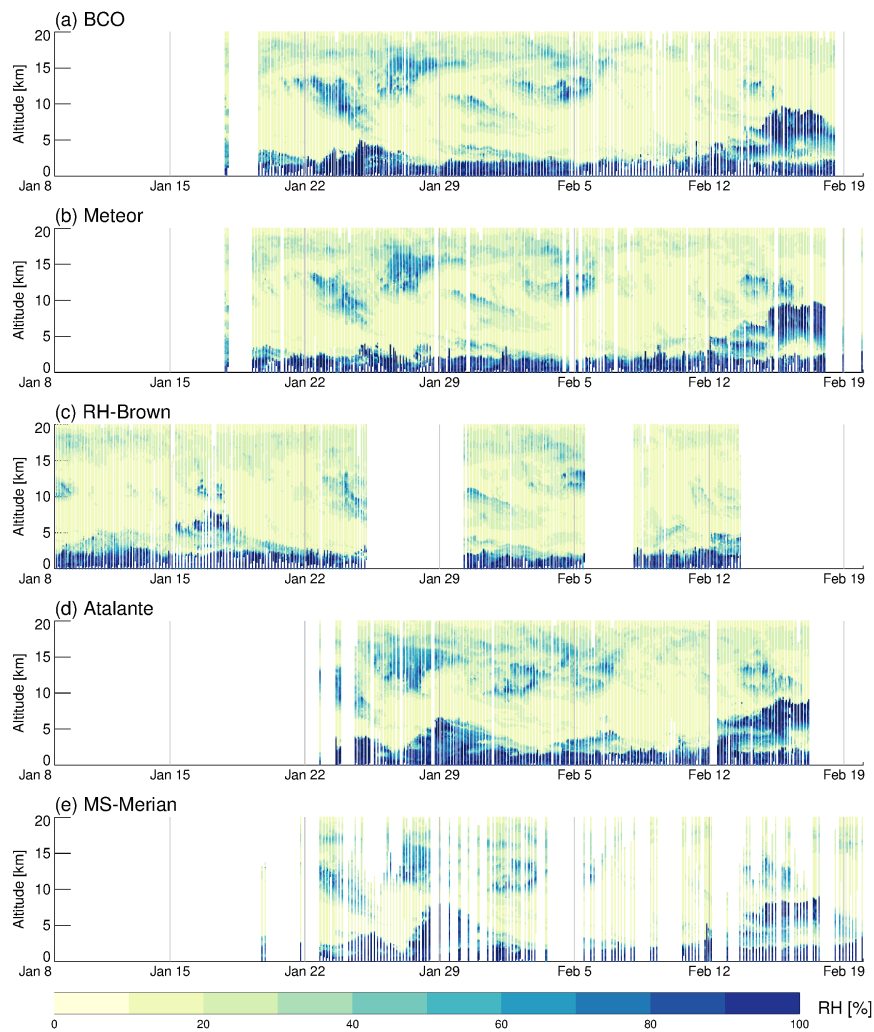


Figure 12. Time-height series of relative humidity measurements from all platforms. The plot combines ascending and descending soundings.

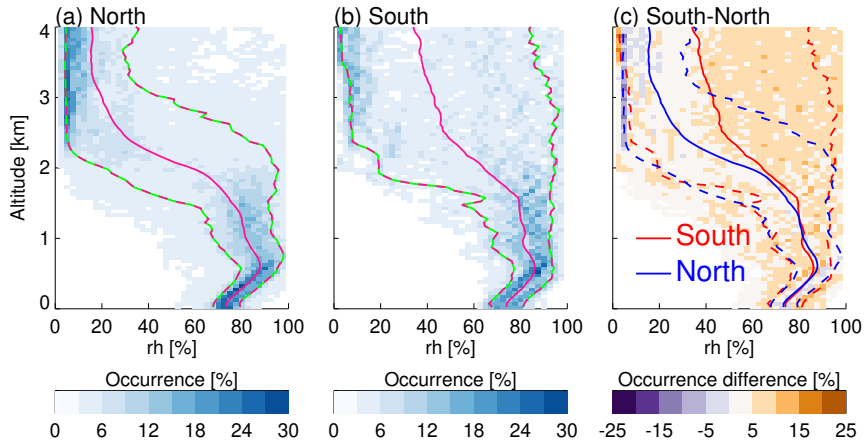


Figure 13. Occurrences of relative humidity as a function of height below 4 km for all soundings launched between January 26 and February 12 (437 profiles). The sum of occurrence frequencies in each altitude bin is 100 %. Altitude bins are 50 m deep and each x -axis contains 40 bins. North (panel a) designates soundings from the northern (12.5–14.5 °N; 261 profiles) latitude band, and South designates soundings from southern (8.5–10.5 °N, 63 profiles) latitude band. Solid lines show the mean profiles in each region and dashed lines the 10th and the 90th percentiles. Only data from ascending radiosondes are used in this comparison.

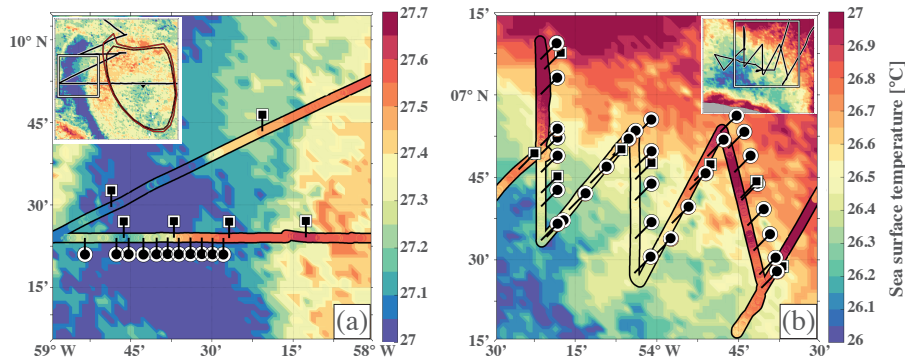


Figure A1. Maps of CLS SST ($^{\circ}\text{C}$) for (a) January 25, 2020, and (b) February 2, 2020, with the *Atalante* track during the first (January 26) and second (February 2–3) intensive leg, respectively. The color shows the SST measured by the ship’s ThermoSalinoGraph (TSG) at 5 m depth and the ticks show the location of Vaisala (squares) and MeteoModem (circles) radiosonde launches. Inserts in the upper corners, where the black lines indicate the ship’s course, show the larger scale view of the corresponding scenes with the geographical imprint indicated by white squares. In the panel insert a, the closed contours and the black diamond indicate, respectively, the edges of an anticyclonic eddy and the position of its center.

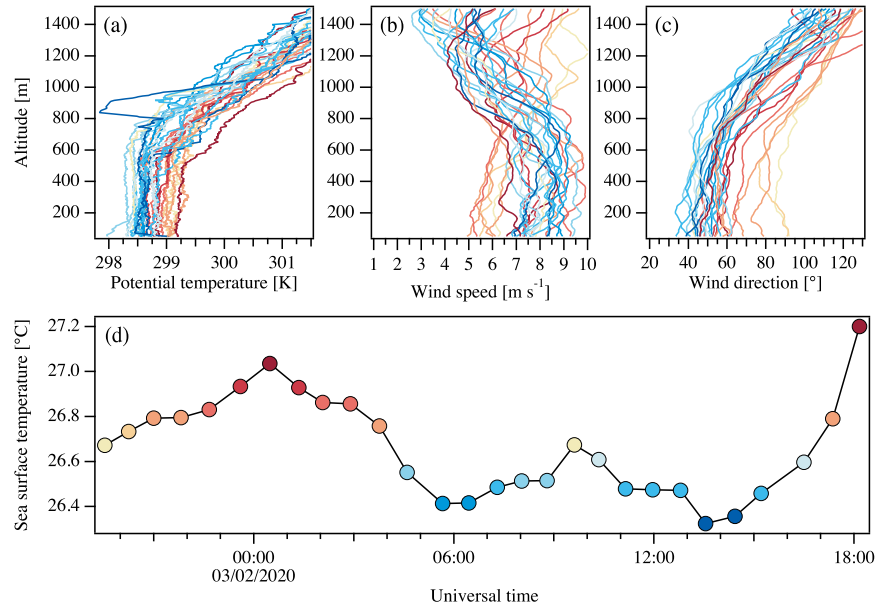


Figure A2. Vertical profiles (50–1500 m) from MeteoModem M10 sondes launched during the second targeted intensive radiosonde period (Figure A1b) for (a) potential temperature, horizontal wind (b) speed and (c) direction, and (d) the corresponding SST time series from the *Atalante* TSG with each circle corresponding to a MeteoModem launch. Colors are indicative of the SST ($^{\circ}\text{C}$) at the time of each launch. Vertical profiles are built from Level-0 raw measurements.

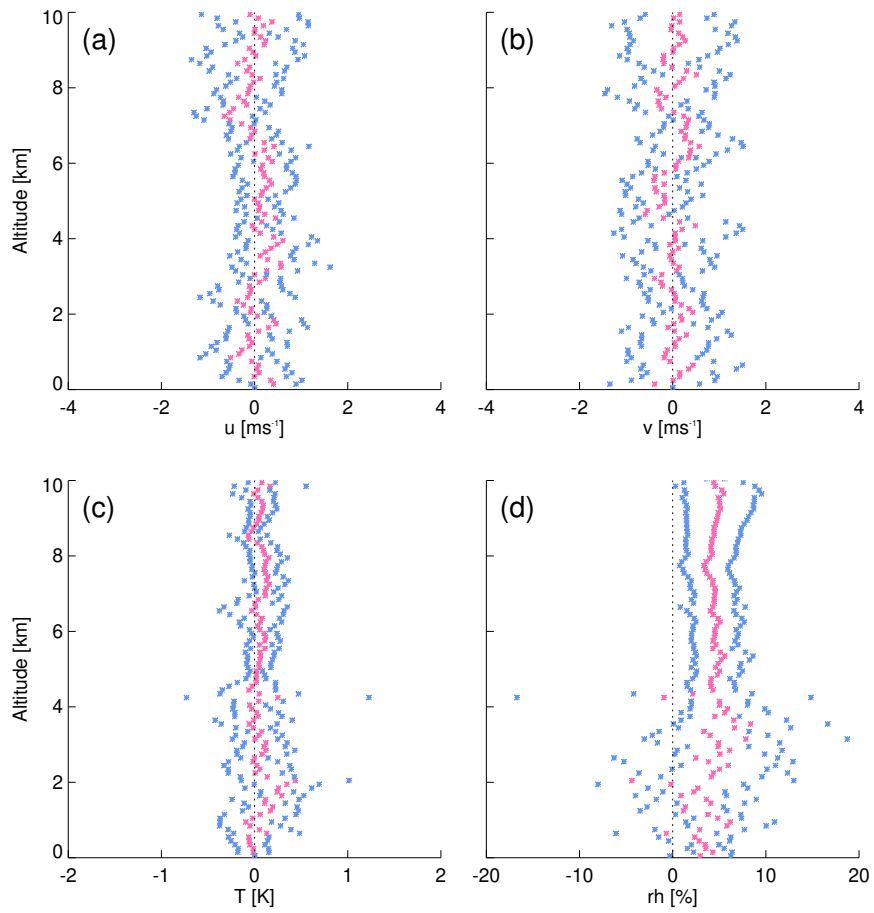


Figure A3. For *Atalante* soundings launched within ± 25 min, the mean difference MeteoModem-Vaisala (pink) and ± 1 standard deviation (blue) computed on 8 difference profiles with a vertical resolution of 100 m. Shown are difference profiles for (a) zonal wind, (b) meridional wind, (c) temperature, and (d) relative humidity.

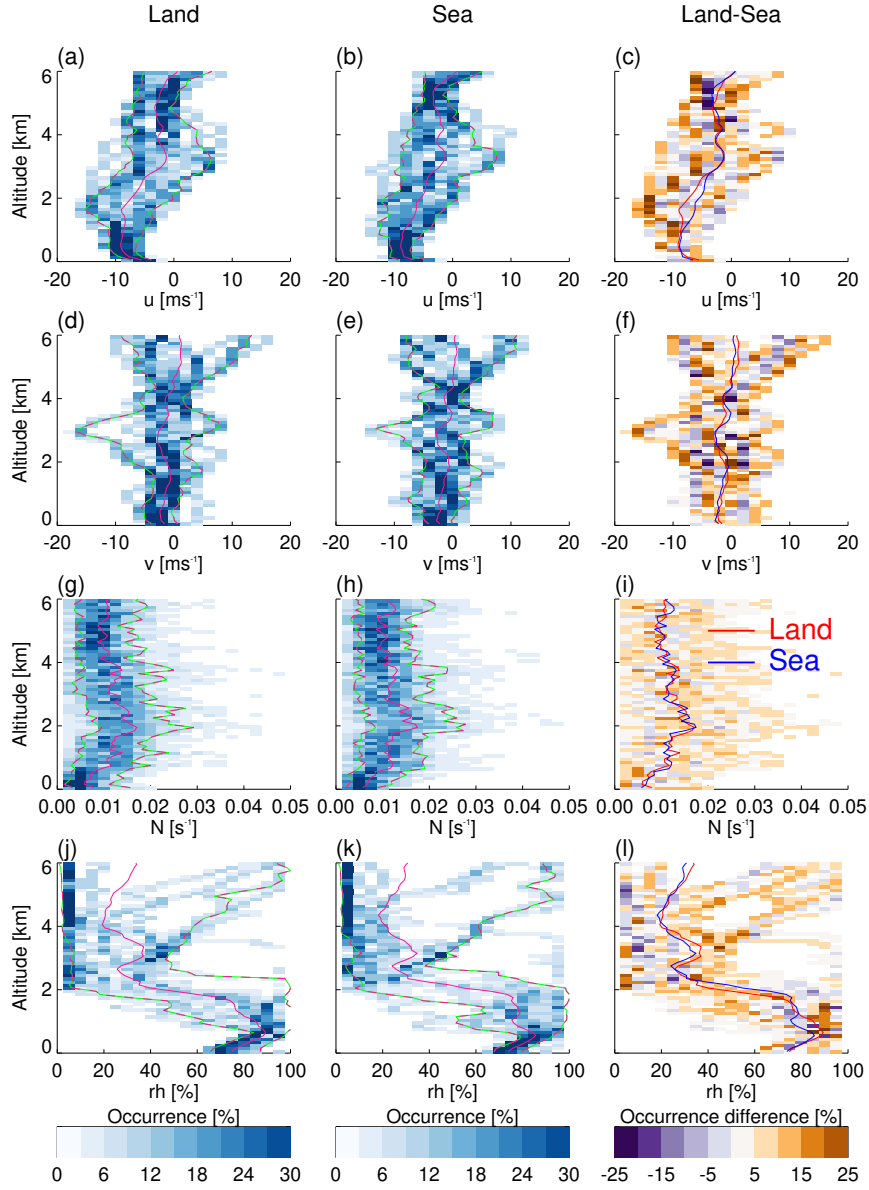


Figure A4. As Fig. 13, but instead of comparing different regions, we here compare ascending soundings launched from BCO with ascending soundings launched within ± 90 min from nearby ships (within 1° longitude to the east and $\pm 1^\circ$ latitude of BCO, resulting in 12 matching soundings). Altitude bins are 100 m deep and there are 20 bins on the x -axis.

Table 1. For each platform the rows list (1) the numbers of recorded ascending soundings, (2) the numbers of recorded descending soundings, (3) the first date of data coverage, (4) the last date of data coverage, (5) whether or not parachutes were used, (6) the station altitude relative to sea level (for ships: apparent sea level, for BCO: mean sea level), (7) the GPS antenna offset relative to the station, (8) the launch site offset relative to the station, (9) the surface barometer offset relative to the station, (10) the frequency used to transmit the signal from the radiosonde to the antenna, (11) the MW41 software version (12) the WMO station ID, (13,14) the abbreviated heading used for exchange on the Global Telecommunication System, consisting of (13) data designators (TTAAii) and (14) international four-letter location indicators (CCCC) (WMO, 2009).

	BCO	<i>Meteor</i>		<i>Brown</i>	<i>Atalante</i>	<i>Merian</i>
		MPI-M	DWD			
Number ascents	182	180 ¹	39 ¹	169	139	118
Number descents	162	175 ¹	-	158	138	38
Start date	Jan 16	Jan 16	Jan 18	Jan 8	Jan 21	Jan 18
End date	Feb 17	Mar 1	Feb 26	Feb 12	Feb 16	Feb 19
Use of parachutes	yes	yes	no	no	yes	yes
Station altitude (msl m)	25.0	16.9	5.4	4.3	13.1	10.4
GPS antenna offset (m)	4.3	2.5	3	5.5	2.6	1.6
Launch site offset (m)	0.0	-11.5, -14.2 ²	0.0, -2.7 ²	0.5	-0.6	0.0
Surface barometer offset (m)	1.0	-16.9	-5.4	-4.3	0.2	0.6
Frequency (MHz)	400.2	401.5	403.0	400.5	400.7 – 401.2	402.0
MW41 software version	2.15.2.0-37	2.15.2.0-37	2.6.1.60	2.4.0.75	2.15.2.2-42	2.15.2.0-37
Station IDs	BCO	ZVQEQCM		WTEC	Atalante	FPUW5GN
TTAAii	IUSN74	IUSX40, IUKX40		IUSE01	IUSN72	IUSX40, IUKX40
CCCC	LFPW	EDZW		WTEC	LFPW	EDZW

¹includes 8 additional soundings after Feb 20, 0 UTC

²Feb 9, 18 UTC - Feb 20, 0 UTC