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Measurement of the water balance components of a large green roof in Greater Paris Area

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Abstract. The Blue Green Wave of Champs-sur-Marne (France) represents the largest green roof (1 ha) of the Greater Paris Area. The Hydrology, Meteorology and Complexity lab of Ecole des Ponts ParisTech has chosen to convert this architectural building as a full-scale monitoring site devoted to study the performances of green infrastructures in stormwater management. For this purpose, the relevant components of the water balance during a rainfall event have been monitored: rainfall, water content in the substrate and the discharge flowing out of the infrastructure. Data provided by adapted measurement sensors were collected during 78 days between February and May 2018. The related raw data and a python program transforming them into hydrological quantities and providing some first elements of analysis have been made available. These measurements are useful to better understand the processes (infiltration and retention) conducted their hydrological performances, and their spatial variability due to substrate heterogeneity.

Link to the data set (Versini et al., 2019): https://doi.org/10.5281/zenodo.3467300 (doi: 10.5281/zenodo.3467300)

Keywords: green roof; stormwater management; water balance

1 Introduction

Considered as Blue Green Solutions (BGS), green roofs are recognized as multifunctional assets able to provide several ecosystem performances (Francis and Jensen, 2017; Oberndorfer et al., 2007) to face climate change and unsustainable urbanization consequences (as biodiversity conservation or thermal insulation). They appear to be particularly relevant in stormwater management as they have the ability to store a more or less significant part of precipitation (Stovin et al., 2012; Versini et al., 2016). Indeed, at the building scale, green roofs contribute to: (i) reduce runoff volume at the annual scale, and (ii) attenuate and delay the peak at the rainfall event scale. These performances depend on the green roof properties (substrate depth, porosity, or vegetation type), rainfall intensity and antecedent soil moisture conditions (Berndtsson, 2010). Considered as some stormwater Source Control facilities, they can act to manage rainwater at a small-scale (about 10 –10 m) to solve or prevent intermediate scale (10 – 10 m) stormwater issues.

By increasing the storage of water, green roofs contribute to reduce the rainwater reaching the network. It is particularly useful to respect regulation rules that are generally adopted by local authorities in charge of stormwater management, usually divided in two categories: flow-rate based regulation and volume-based regulations (Petrucci et al., 2013). As green roofs perform in both retention (ability to permanently hold back water by storing the water for subsequent removal by evapotranspiration) and

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detention (ability to temporarily hold back the water) (Johannessen et al., 2018), they can be used as relevant tools to ensure both kinds of regulation.

Indeed, for a green roof, the water balance during a rainfall event can be reduced to 3 components (see Eq. 1) as evapotranspiration can be neglected:

$$P = Q + \Delta S \tag{1}$$

Where *P* is the precipitation, *Q* the discharge flowing out of the structure, and ΔS the variation of water stored in the substrate conducting both retention and detention properties. All quantities are expressed in m³

Many experimental set-up have been implemented to monitor, assess and understand the hydrological behavior of green roofs (see (Berndtsson, 2010) for a review). Most of them were conducted on small green roof modules or plots (Berretta et al., 2014; Getter et al., 2007; Li and Babcock, 2015; Locatelli et al., 2014; Loiola et al., 2019; Poë et al., 2015; Stovin et al., 2015; Wong and Jim, 2015; Zhang et al., 2015) characterized by an area ranging 0.5 to 3 m². These modular structures make possible the modification of green roof configuration and study of the effects of substrate (depth and nature), vegetation type, slope, or climate conditions on their performances. Some of them were also monitored in controlled conditions (Ouldboukhitine et al., 2011; Poë et al., 2015) to assess the respective impacts of temperature, irrigation, and light on green roof behavior for instance.

In addition, few studies were conducted at full-scale green roofs. Indeed, such large infrastructures are harder to monitor, as this operation was not generally planned during their construction. For instance, once built, electric connection is rarely compatible with the conservation of the roof sealing. To the knowledge of the authors, only the following works can be mentioned.

(Palla et al., 2009) studied an instrumented portion (170 m²) of a green roof in Genoa (Italy) under Mediterranean climate. This pilot site was equipped to monitor the different components of the water balance with: a meteorological station for rainfall, several Time Domain Reflectometry probes installed horizontally along a vertical profile for retention in the substrate, and a triangular weir and a tipping bucket devices to follow the outflowing discharge.

(Hakimdavar et al., 2016) used the data collected on three full-scale extensive green roofs in New York City (USA) to validate a modeling approach based on the Soil Water Apportioning Method (SWAM).

Under a humid continental climate, these monitored drainage areas were comprised between 310 and 940 m². The three main components of the water balance were measured: rainfall with a weather station, water content with soil moisture and water content reflectometer sensors, and discharge with a custom designed weir placed in the drain of the green roof.

(Fassman-Beck et al., 2013) assessed several green roofs in Auckland (New Zeland) under sub-tropical climate. Their areas were comprised between 17 and 171 m². As the experimental setup was focused on rainfall-runoff relationship, only these components were measured: rainfall with a tipping bucket rain gauge and discharge (deduced from water level) from a water pressure transducer and a custom-designed orifice restricted device.

(Cipolla et al., 2016) analyzed runoff from a 60 m² extent green roof in Bologna (Italy) characterized by a humid temperate sub-continental climate. Continuous weather data and runoff were especially monitored for modeling development. Runoff was estimated by using an in-pipe flow meters consisting of a runoff chamber with an outlet weir and an ultrasonic sensor (to detect water level). The site was also equipped with a weather station measuring several meteorological variables (rainfall, wind speed, wind direction, relative humidity, atmospheric temperature, ...).

Although these works were focused on the hydrological behavior of green roofs, few of them have actually monitored the 3 components of the water balance. Rainfall and discharge were generally considered as sufficient to assess their performances. Some additional studies can also be mentioned, but as they were focused on other topics (evapotranspiration processes (Feng et al., 2018), or water quality (Buffam et al., 2016)), only one component on the water balance was assessed.





- The full-scale monitoring experiments mentioned above also suffer from two limitations. First, they are still dedicated to rather small green roof areas. As the hydrological performance of a green roof is influenced by the size of the plot (water detention depends on water routing in the structure for instance), larger infrastructure should be studied. Second, very few measurements are performed (usually only one!) to assess water content on the whole vegetated surface. Indeed, green roof substrates —which are usually largely composed of mineral components are very heterogeneous, causing variability in their infiltration and retention capacities. Therefore, large-scale monitoring setups able to capture this heterogeneity are required to better understand green roof hydrological behavior and to study the space-time variability of the involved processes.
- Based on these considerations, this paper aims to present and make available the water balance data collected on a large green roof (called Blue Green Wave) located close to Paris (temperate climate) in order to study its hydrological behavior and its ability to be used as stormwater management tool. The monitoring set-up has been particularly tailored to take into account the space-time variability of the water balance components.

115 2 Materials and method

2.1 The Blue Green Wave

- The Blue Green Wave (BGW) is a large (1 ha) wavy-form vegetated roof located in front of Ecole des 120 Ponts ParisTech (Champs-sur-Marne, France). For now it represents the largest green roof of the Greater Paris area. From its implementation in 2013, the BGW has been considered as a demonstrative site oriented to Blue Green Solutions research (Versini et al., 2018). This experimental set-up started during the European Blue Green Dream (BGD) project (http://bgd.org.uk/, funded by Climate-KIC) that aimed to promote a change of paradigm for efficient planning and management of new or 125 retrofitted urban developments by promoting the implementation of BGS (Maksimovic et al., 2013). The monitoring was anticipated and the building could be adapted to experimental purpose during its construction. It has also been supported by RadX@IdF, a regional project that notably aimed at analysing the benefits of high-resolution rainfall measurement for urban storm water management. Today the BGW is also part of the Fresnel multi-scale observation and modelling platform created in 130 the Co-Innovation Lab at École des Ponts ParisTech. Fresnel aims to facilitate synergies between research and innovation, as well as the pursuit of theoretical research, the development of a network of international collaborations, and various aspects of data science (https://hmco.enpc.fr/portfolioarchive/fresnel-platform/).
- From a technical point of view, the BGW is covered by two types of vegetation: green grass that represents the large majority of its area and a mix of perennial planting, grasses and bulbous (see Figure 1). They are based on a substrate layer of about 210 mm depth, a filter layer made of synthetic fiber, and a drainage layer made of expanded polystyrene. The substrate is composed of volcanic soil (around 85%) completed by organic matter and is characterized by a total porosity of 60% and a density of 1446 g/l (see (Stanic et al., 2019) for a detailed description).





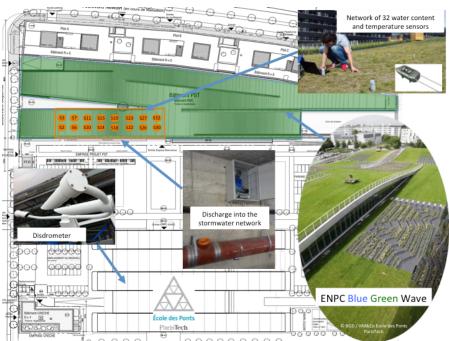


Figure 1. The Blue Green Wave monitoring site of ENPC

From a hydrological point of view, the BGW is connected to three storage units that collect rainwater coming from the roof (with pipes) but also from several impervious parts around the greened building. One of the storage units is preceded by a smaller unit dedicated to irrigation. The water is then routed to a large retention basin to collect excess volumes of water during a rainfall event before being routed to the rainwater network. This retention basin has been designed (and oversized) as it was considered that the green roof (representing 50% of the total contributive area) was totally impervious without any retention capacity. Until now in France, there is no rule or guideline devoted to retention basin sizing and taking into account the retention properties of green areas. That is why the follow-up of such infrastructure is particularly important to develop new guidelines or legislations. For this purpose, the 3 components of the water balance have been monitored on the BGW. The implemented set-up is described in the following.

2.2 Devices

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2.2.1 Rainfall measurement

Local rainfall is analysed with the help of an optical disdrometer Campbell Scientific[®] PWS100. This device is made of two receivers, which are not aligned with a transmitter generating four laser sheets. By analyzing the signals received from the light refracted by each drop passing through the 40 cm² sampling area, their size and velocity are estimated. A rain rate can then be derived. Disdrometers are now considered as a reliable rainfall measurement instrument (Frasson et al., 2011; Gires et al., 2016; Thurai et al., 2011). The device is installed since September 2013 on the roof of the Ecole des Ponts ParisTech building (see Fig.1). This disdrometer and its corresponding data have already been presented in details in a previous data paper (Gires et al., 2018) that summarizes a measurement campaign that took place in January-February 2016. Here, the rainfall data provided by this





disdrometer and characterized by a time step of 30 seconds is used.

2.2.2 Water content measurement

- Estimation of soil moisture represents a difficult challenge, as it deals with a highly spatially and temporally variable process (Lakshmi et al., 2003), essentially due to soil type and depth. Hence, suitable systems are required to properly assess soil moisture. Nowadays a large number of sensors based on different methods are available for this purpose (Jackson et al., 2008). Among them, indirect methods based on electromagnetic (EM) principles have gained wide acceptance over the last decades.

 They have the advantage to deliver fast, in-situ, non-destructive and reliable measurements with acceptable precision (Stacheder et al., 2009).
- Here Time Domain Reflectometry technique (TDR also known as capacitance) has been selected. It is an EM moisture measurement that determines an electrical property called electrical conductivity or dielectric constant (k_a). It is based on the interaction of an EM field and the water by using capacitance/frequency domain technology (Stacheder et al., 2009). The TDR sensor measures the propagation time of an EM pulse, generated by a pulse generator and containing a broad range of different measurement frequencies. The electrical pulse is applied to the waveguides (traditionally a pair of parallel metallic rods) inserted in the soil. The incident EM travels across the length of the waveguides and then is reflected back when it reaches the end of the waveguides. The travel time required for the pulse to reach the end of the waveguides and come back depends on the dielectric constant of the soil.

$$k_a = \left(\frac{c \cdot \Delta t}{2 \cdot L}\right) \tag{2}$$

Where $k_{a \text{ is}}$ the bulk soil dielectric permittivity [-], L the effective probe length [m] Δt is the two-way travel time along the probe (s), and c the velocity of EM wave in free space (c=2.298×10⁸ m/s)

Then it is possible to estimate soil moisture content by analyzing the dielectric constant changes into the soil. The usual relationship between volumetric water content and dielectric constant is known as Topp's Equation (Topp et al., 1980). It is adapted to a homogeneous conventional soil:

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$$\theta = -5.3 \times 10^{-2} + 2.92 \times 10^{-2} k_a - 5.5 \times 10^{-4} k_a^2 + 4.3 \times 10^{-6} k_a^3$$
 (3)

Where θ is the volumetric soil water content [m³.m⁻³].

Consequently, an ubiquitous wireless TDR sensor network has been implemented on the ENPC Blue Green Wave to measure both water content and temperature. For this purpose 32 CWS665 wireless 200 TDR sensors (produced by Campbell Scientific®) were initially installed. The data were collected by 4 CWB100 wireless bases, able to store each the data of 8 sensors. Then the data was transferred to a data-logger CR6 from Campbell Scientific[®]. The initial selected time step was 1 minute. It appeared that this first configuration was responsible of many gaps in the time series due to interferences between the different TDR sensors and the bases. To avoid this problem, only 16 TDR sensors were 205 used, all of them connected to the same CWB100 base. For this same reason of possible interferences between the sensors, the time interval has been enlarged to 4 minutes. Indeed, it is recommended to let 15 seconds by sensor to ensure its connection to the base. The final network aimed to capture the space-time variability of water content in a heterogeneous soil as the BGW substrate. It was particularly adapted to assess the influence of the slope on infiltration and evapotranspiration 210 processes.

2.2.3 Discharge measurement

Direct discharge measures are difficult to obtain in drainage pipes. For this reason, indirect measures using water level measurements are usually carried out. Here, water level inside the pipes was measured by a UM18 ultrasonic sensor (SICK, 2018) produced by SICK. This sensor has been especially developed to perform non-contact distance measurement or detection of objects. The sensor head emits an ultrasonic wave and receives the wave reflected back from the target. Ultrasonic sensors





- measure the distance to the target by measuring the time between the emission and reception. 220 Implemented face to the water surface, it also measures the variation of the water level. The UM18 sensor is characterized by a nominal range of 250 mm, and an accuracy of 1% on this measurement
- One UM18 sensor has been implemented inside a pipe located in the garage in the building basement 225 (see Figure 1). With a diameter of 300 mm, this pipe collects the water coming from a large part of the BGW (approximately 1143 m²). A standard 4–20 mA current loop is used to monitor or control remotely these analogue sensors. The current is then transformed in voltage by a resistance of 100 Ω . The resulting transmitted signal also ranges 400-2000 mV. In order to translate the electric signal in water level values, the following relationship has been applied 230

 $H_0 = (U - 460) \times \frac{250}{1600}$ (4)

 H_0 is the water level in mm, U the measured voltage in mV, 460 represents the offset, 250 the modified nominal range in mm, 1600 the nominal range in mV.

235 The water level is then transformed in discharge by using the Manning-Strickler equation (Eq. 5). This formula is usually used to estimate the average velocity (and discharge) of water flowing in an open channel. It is commonly applied in sewer design containing circular pipes.

$$Q_0 = V \times S = K \times R^{\frac{2}{3}} \times i^{-\frac{1}{2}} \times S \tag{5}$$

240 Where V is the average water velocity $[m.s^{-1}]$, K the friction coefficient [-], S the wet surface $[m^2]$, R the hydraulic radius [m], and i the pipe slope [m/m]. R and S are directly linked to the water level:

$$R = \frac{S}{P} \tag{6}$$

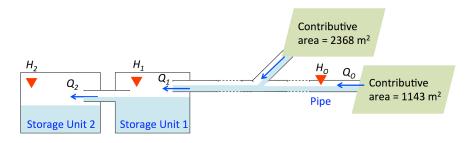
$$S = \frac{\left(\theta - \sin(\theta)\right) \times r^2}{2} \tag{7}$$

$$P = r \times \theta \tag{8}$$

$$P = r \times \theta$$

$$245 \qquad \theta = 2 \times \arccos\left(\frac{r - H}{r}\right)$$
(8)

K has been chosen to 85. This value corresponds with a cast iron material.



Water level sensor

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Figure 2. Location of the water level sensors in the stormwater network

Two additional UM18 sensors have been implemented in the two consecutive storage units collecting the rainwater drained by a large contributive area of 3511 m², and including the previous monitored area. The first storage unit is a rainwater tank (characterized by a floor area of 32.2 m²) devoted to irrigation. Filled most of the time, the excess water is routed by a pipe toward the second unit (floor area of 22.5 m²). A similar relationship to Eq. 4 between the voltage measurement and the water level has been adjusted for both units:

$$H_i = (U - 0.38) \times \frac{20}{1.62} - dh \tag{10}$$



Here U the measured voltage in V, the nominal range is 20 cm and dh (equal to 1.06 cm) corresponds to an additional offset due to the elevation of the sensor

By studying both water level variations, a relationship between the water level measured in the first unit (H_1) and the outflow routing to the second unit Q_2 (and related to H_2) has been established (see Figure 2). Finally, the total discharge reaching the first unit and collecting the downstream rainfall can be assessed by the following equation depending only on H_1 :

$$Q_{1} = Q_{2} + \frac{dH_{1}}{dt} \times A1 = f(H_{1}) + \frac{dH_{1}}{dt} \times A1$$
 (11)

Where Q_l is the discharge reaching the first unit and Q_2 the second respectively, $Al = 33.2 \text{ m}^2$ is floor area of the first unit.

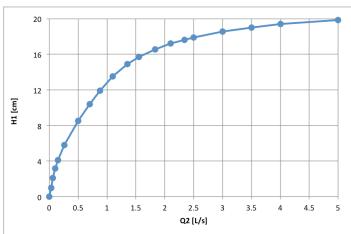


Figure 3. Relationship adjusted between the water level H_I and the downstream discharge Q_I

Finally, discharge data was recorded with a time step of 30 seconds for the sensor implemented in the conduit, and 15 seconds for the one in the storage unit.

2.3 Available output, data processing and period of study

As already presented in details in (Gires et al., 2018), precipitation data is collected in real time and stored through daily files. Here, these files for 30 s time step rain rate have been gathered with the help of a Python script to create a long time series covering the whole period of study. Each line contains the time step expressed as YYYY-MM-DD HH:MM:SS and the corresponding rainfall intensity (in mm/h) separated by a coma.

Water content and water level data inside the pipe are collected and stored every night on the HM&Co server in two different files. For this purpose, the Loggernet software produced by Campbell Scientific[®] has been used. It supports programming, communication, and data retrieval between data loggers and a PC. Concerning the water level file, each line corresponds to a time step for which the following information is recorded (in each line, these values are separated by a coma):

- Exact definition of the time step expressed as YYYY-MM-DD HH:MM:SS
- Item number

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- Voltage indicator to ensure the quality of the measurement (it should be close to 12 V)
- Internal temperature of the datalogger box
- 295 Unused data coming from a non operational sensor
 - Water level measured inside the pipe (U in Eq. (4), expressed in mV)
 - Unused data coming from a non operational sensor
 - Unused data coming from a non operational sensor

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- 300 Similar format has been chosen for volumetric water content data (note that names of the 16 VWC sensors are indicated in the header and also are reported on Figure 1):
 - Exact definition of the time step expressed in YYYY-MM-DD HH:MM:SS
 - Item number
 - Voltage indicator to ensure the quality of the measurement (it should be close to 12 V)
- 305 Internal temperature of the datalogger box
 - Volumetric water content (expressed as k_a) for the 16 TDR sensors
 - STT B3: Summary Transfer Time for basis, which is related to the total time required for collecting information from all the sensors that are collected to that base.
- 310 Water level data inside the storage units have been collected by using the open-source Arduino Uno microcontroller board that works in the offline regime. Data are continuously stored on the 64 MB memory card implemented on the board, and copied manually to the HM&Co server once per week. Data contain the following information (in each line, these values are separated by a space):
- 315 Voltage values for the first storage unit – U1 (in mV)
 - Voltage values for the second storage unit U2 (in mV)
 - Exact definition of the time step expressed in YYYY-MM-DD HH:MM:SS

By using Equation (10) U1 values are transformed into H1 as a part of post-processing. Note that U2 data have been used only for a short period of time after the implementation of UM18 sensors, until Q2 = f(H1) functionality has been obtained. After that they were no longer necessary.

3 Data availability

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Conversely to rainfall and discharge, which are measured continuously at the same locations, water 325 content sensors can be moved from a location to another on the BGW. Moreover they were rarely conserved during the night for security reason. Nevertheless, during several months at the beginning of 2018, they were maintained on the same section of the BGW (that showed in Figure 1). This time period corresponds to 78 days, from February 19^{th} to May 7^{th} 2018. It has been selected to provide water balance components measurements to potential users. This data set is available for download 330 from the following web page (Versini et al., 2019): https://doi.org/10.5281/zenodo.3467300

3.1 Presentation of the available data set

This data set presented in details in the next section contains the following files:

- 335 A rainfall file: 2018 0219-0507 Data rainfall.dat

 - A water content file: 2018_0219-0507_VWC.dat
 A water level inside the pipe file: 2018_0219-0507_Data_discharge.dat
 - A water level in the storage file: 2018 0219-0507 Data Arduino.dat
 - A python script to select the data, transform the raw data in physical measurements and carry out some initial analysis.

In details, the python script is structured as follow:

- Time period selection: this part could be changed to select a study time period by choosing an initial and final date.
- 345 Data selection and transformation: the data corresponding to this time period are selected in the different files. Electric signals measured by the water level sensors are converted in water level (by using Eq. 4 and 10), then in discharge by using Manning-Strickler equation (Eq. 5) for the pipe and Eq. 11 for the storage unit. In order to smooth the erratic 15s-signal produced by storage unit measurements, the computed discharge data are averaged on a moving 350 window, whose number of time steps can be modified. Dielectric constants measured by the 16 TDR sensors are converted in water content by using Topp equation (Eq. 3).
 - Representation of the computed data: Several figures are drawn to illustrate the variation of the hydrological components in time. The first one represents the corresponding hydrographs for both discharges computed inside the pipe and in the storage unit. The second one synthetizes the water content measured by the 16 TDR sensors. In each figure, the precipitation is drawn on an invert y-axis.
 - Computation of runoff coefficients: runoff coefficient is the ratio between the total amount of precipitation (computed by multiplying the rain depth by the corresponding contributive area)

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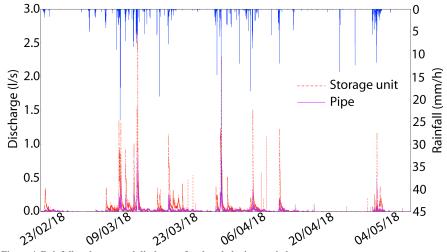
and the total volume of water flowing through the monitored pipe or the storage unit. This value ranging 0 to 100% illustrate the capacity of the green roof to retain rainwater.

3.2 Presentation of the time series

During the available time period including half of winter and half of spring, it rained a total amount of 123.1 mm (see Figure 3). The rainfall file has no missing value, and at least 7 rainfall events can be defined. They correspond to a precipitation higher than 5 mm that caused discharge in both pipe and storage unit: 7th march (9 mm), 10 and 11th March (14 mm), 17th March (7.5 mm), 27th march (6.5 mm), 28th March (8.5 mm), 9th April (9.5 mm), 29 and 30th April (24.5 mm).

Concerning the 16 VWC sensors, 5.6% of the time steps are considered as missing data. This is essentially due to 2 particular sensors that were out of service from 16th March to the end of the study time period. The 16 sensors follow the same dynamic, responding to the several rainfall events (see Figure 4). Water content measurements decrease simultaneously during two long dry periods, at the end of February and from mid-April to the beginning of May. The sensors show a significant spatial variability in terms of absolute values. These differences illustrate the heterogeneousness of the substrate, due to its granular composition and its wavy-form.

Discharge data are almost complete. Only two data are missing for the measure in the pipe and 0.2% of total amount of time steps for the storage unit. These missing data correspond to the short periods during which the manually collection of the data is carried out. Note that in order to avoid the lost of relevant data, this operation is done during a dry period. On this time period of 78 days, runoff coefficient computed for both pipe and storage unit are equal to 70.6% and 71.1% respectively. These close values demonstrate the relevance of the monitored set-up. The missing water corresponds to the water retained by the substrate and the vegetation. It should be returned to the atmosphere by evapotranspiration. Note that Topp equation (Eq. 3) used to convert dielectric constant in water content could be not adapted to the specific substrate implemented on the BGW. Essentially formed of mineral matters, its composition seems far from that of the conventional soils on which it was defined.



390 Figure 4. Rainfall and computed discharges for the whole time period



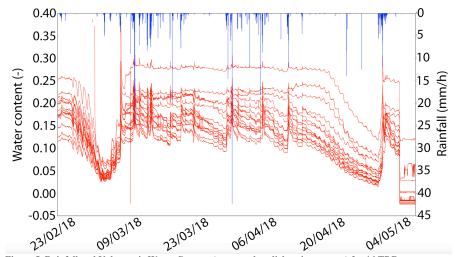


Figure 5. Rainfall and Volumetric Water Content (expressed as dielectric constant) for 16 TDR sensors

4 Conclusion

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This paper presents the data collected by several devices devoted to the assessment of the water balance of a particular green roof located close to Paris. The dataset made available for research purposes contain 3 types of data, representing the relevant components of the water balance during a rainfall event: rainfall, water content in the substrate and the discharge flowing out of the infrastructure. They were collected during 78 days between February and May 2018. These measurements are useful to study the capacity of such vegetated infrastructures to store rainwater and act as stormwater management tool. They could also be useful to develop and validate some appropriate modeling approaches (Stovin et al., 2013; Versini et al., 2016).

This data set is available for download free of charge from the following web page (Versini et al., 2019): https://doi.org/10.5281/zenodo.3467300

- 410 It is provided by the Hydrology, Meteorology, and Complexity laboratory of École des Ponts ParisTech (HM&Co-ENPC). The following references should be cited for every use of the data: Versini, P.-A., Stanic, F., Gires, A., Scherzer, D., and Tchiguirinskaia, I. (2019). Measurement of the water balance components of a large green roof in Greater Paris Area. Earth System Science Data. XXXXX
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- Researches focused on the assessment of ecosystem services provided by Blue Green Solutions is continuing at HM&Co-ENPC, and particularly on the BGW. The monitoring set-up has been recently extended to the energy balance measurement. The objective is to assess its different components (radiation balance, conduction, sensitive and latent heat flux). Such data will be particularly useful to study the ability of Blue Green Solutions to mitigate urban heat islands. The French ANR EVNATURB project (https://hmco.enpc.fr/portfolio-archive/evnaturb/), that aims to develop a platform to assess some of the eco-system services (ie stormwater management, cooling effect, or biodiversity conservation) provided by BGS is now pursuing this work of monitoring (Versini et al., 2017).

Author contribution

Pierre-Antoine Versini supervised the study, reviewed, and wrote a large part of the manuscript; Filip Stanic and Auguste Gires worked on the implementation of some of the presented sensors, the collection of the data and participate to the review of the paper; Daniel Schertzer and Ioulia Tchiguirinskaia collaborate to the study supervision and the review process.





Competing interests

The authors declare that they have no conflict of interest.

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