Interactive comment on “Glider data collected during the Algerian Basin Circulation Unmanned Survey from 2014 to 2016” by Y. Cotroneo et al.

Anonymous Referee #1

Received and published: 25 November 2018

In this manuscript, the authors present glider datasets collected during fall 2014, 2015 and 2016. The trajectories passed along altimetry tracks (SARAL and Sentinel-3) which is very useful to perform altimetry data validation and/or to study structures with a multi-platform strategy. The campaigns took place in the Algerian Basin, which is quite under sampled and are thus an interesting contribution to study this region of the Mediterranean Sea. A complete description of the instruments as well as the quality control and data validation steps is given. Then a comparison with historical data is made and finally the authors focused on the representation of water masses characteristics by the glider. The paper is easy to read, well-structured and provide detailed description of the methods and data which are of full interest for the community. Datasets are easy to access via the given identifier and seem of high quality. I consider that this paper must be published after minor revision. Here are some comments or questions and a few technical remarks about typographical and grammatical errors that need to be corrected.

We are glad that the referee appreciated our effort in providing a useful and carefully quality checked dataset for main water column parameters in the Algerian Basin.
The manuscript will be improved accepting all the received suggestions and the revised version will be provided soon.
According to suggestions received from both reviewers, some sentences in the text and even the title have been updated.
A point by point response (in red) to the specific comments received is provided below.
Best regards, Dr Yuri Cotroneo

Specific comments:

p3, lines 111-113: here you mention a change in the sampling strategy in 2014 and 2016 but in p4 line 142 it is in 2014 and 2015. Regarding Figure 2, I think that the introduction must be changed.

The Reviewer is right. Sampling track was changed in 2014 and 2015. We corrected the information mentioned in the introduction paragraph.

p4 line 133: in the introduction you write that gliders collect data in the first 975 m but here you mention that they can reach a depth of 1000 m. Why this difference?

This difference is linked to the beginning of the ascending procedures of the gliders when reaching its maximum depth and to the existence of a security margin of 25 m. In fact, a very well ballasted glider could need about 10 meters to change the direction of the vertical motion (sign change in diving-speed in meters/second). Technically, 975m is the ‘diving target depth’ meaning the glider will begin the bottom-inflection when reaching that depth so it won’t stop descending at that depth but will need 10-15 meters to begin ascending.
Accordingly, we effectively collect data down to 975 m depth, where the lower inflection depth is located, while the glider has its maximum navigation depth at about 1000 m.
In the new version of the manuscript we highlight that data collection is always limited to the maximum depth of 975 m (i.e. lines:41, 111, 132, 151, 194, 332, 414, 447, 460, 462, 464).

p5 line 151: I don’t understand how many gliders you use. Is this a single glider which has been reused for the different missions or three distinct gliders from the same constructor and with the same characteristics?

We thank the Reviewer for this comment. The 2014 and 2016 missions were realized with the same glider (named SLDEEP 001), while the 2015 mission was realized with a different glider (named SLDEEP000) from the same constructor, with the same characteristics and undergoing the same calibration procedures.
The name of the glider used for each cruise can be found in the dataset page, as well as in the file name of the data available for each mission.
A new sentence has been added in the text at line 248:
“All these operations were performed on the two SLOCUM gliders used during the ABACUS missions (SLDEEP001 for 2014 and 2016; SLDEEP000 for 2015) as part of the pre-missions tests, and contributed in assessing the quality of the collected data.”

p5 line 162: I understood from p2 line 92 that gliders have a horizontal velocity of 0.25 m/s.

Horizontal speed usually ranges between 0.35 and 0.50 m/sec but this is very variable and context dependent.
Velocity data reported at line 94 are referred to a general range of glider velocities, while values reported at line 161 are calculated by trigonometry considering vertical speed and diving angle for the specific glider sampling configuration adopted during ABACUS missions.
Text has been modified at line 94 to describe the wider range of horizontal velocities that the glider can reach excluding any influence from ocean currents.
A reference has now been added, also considering the following comment by the Reviewer.

p5 line 161-162: do you have a reference or a technical sheet for the velocities?

Some details about glider velocities are available in:

- Griffiths, G., Ed., Davis, R. E., C. C. Eriksen, and C. P. Jones, 2002. Autonomous buoyancy-driven underwater gliders, In: Technology and Applications of Autonomous Underwater Vehicles, Taylor and Francis, London.
- Rudnick, DL, Davis RE, Eriksen CC, Fratantoni DM, Perry MJ. 2004. Undersea gliders for ocean research. Marine Technology Society Journal. 38:73-84.
- Jones, C., E. Creed, S. Glenn, J. Kerfoot, J. Kohut, C. Mudgal, and O. Schofield, 2005. Slocum gliders — A component of operational oceanography. Proc. 14th Int. Symp. on Unmanned Untethered Submersible Technology, Lee, NH, Autonomous Undersea Systems
- Merckelbach, L., D. Smeed, and G. Griffiths, 2010. Vertical Water Velocities from Underwater Gliders. J. Atmos. Oceanic Technol., 27, 547–563, https://doi.org/10.1175/2009JTECHO710.1

p7 lines 241-259: I think you can add a table with the dates of the campaigns because the readers don’t know exactly when they start and end. Moreover, are there two campaigns during fall 2014? Because table 2 is split in two cases for this year.

The Reviewer is right. During 2014 two separate legs were realized and the glider was retrieved on land between the two legs. In the new version of the manuscript, we added the specific dates of the missions in the text (lines 254-278). Additionally, we added date information in Table 2, were the indication of the months for each mission was already shown.

p8 line 290: how did you filter the data?

Filters applied during the generation of level 1 and Level 2 data by the SOCIB DATA CENTRE are described in a series of internal report and published documents (e.g. Troupin et al., 2016).
In level 1 and 2, filters are mainly focused on the processing of pressure data and on the interpolation of missing values. Pressure is filtered using a low pass filter described in the Seabird Data Processing Manual.

- Troupin, C., Beltran, J.P., Heslop, E., Torner, M., Garau, B., Allen, J., Ruiz, S., and Tintoré, J.: A toolbox for glider data processing and management. Meth. Oceanogr. 13–14. http://dx.doi.org/10.1016/j.mio.2016.01.001, 2016.

p8 line 291: how do you average data vertically?

Did you assume that one dive represents one vertical profile and one corresponding latitude or longitude?

According to Troupin et al. (2016), whose toolbox is at the basis of the SOCIB Data Centre dataset production, Level 1 contains processed glider data, as sequences of measurements along the glider trajectory, with interpolated position coordinates to match the times of measurement by the sensor, and with unit conversions and filters applied. Level 2: contains gridded glider data, which means that the glider data are interpolated onto a user configured grid in the vertical (1m in the ABACUS project dataset) and stored as vertical profiles. The profiles are obtained by interpolation of level 1 data to produce regular homogeneous and instantaneous profiles from each up or downcast, using the mean time and position of the corresponding cast for the profile location and time.

p8 lines 295-298: I understood from p5, line 163 that there was no data acquisition between the surface and the 20m-depth layer.

We thank the Reviewer for this comment, as it gave us the opportunity to better explain the data sampling strategy of ABACUS. The data collection in the first 20 m of the water column was realized during each glider mission, but with a strategy that changed during the three years of the project according to the need of improving the sampling in this layer.
In particular, in 2014 we collected data in the 0-20 m layer every 4th profile with a final spatial resolution of about 8.4 km. This resolution, relatively low for glider operations, is the result of the combined effect of the data collection (limited at downcast only) and the navigation strategy (breaking the surface every second couple of ascending/descending profiles) adopted in 2014.
In 2015, we collected a complete cast from surface to bottom about every 5 km. This was obtained acquiring data on both downcast and upcast.
Finally, in 2016 we tested the glider possibility to sample the entire water column from 0 to 1000 m depth at the resolution of 2.8 km. This was obtained sampling during both upcast and downcast and setting the glider to break the surface after every ascending cast. The experiment was successful, but limited in time due to battery constraints. For this reason, during ABACUS 3, the layer between 0 and 20 m depth is sampled at a variable resolution between 2.8 and 5 km.
The text has now been improved with a better description of the data collection in the very surface layer (lines 161-175). Figure 3 has been modified accordingly.

Figure 4: I understood from the text that in 2014, the glider did not reach the surface. However, on the figure, you seem to have measurement from the surface down to 20m.

Figure 4 includes data in the first 20 m depth as data acquisition in this layer was realized each year, but was not sufficiently described in the text.
Now the sampling in the layer 0-20 m is better explained in the text at lines 161-175 also according to the previous comment from the Reviewer.

Figure 5: maybe you can add as a legend the start and end dates of the profiles.

Starting and ending date of each transect, resulting in mean profiles showed, are now reported in figure 5.

p10 line 331: I see a larger maximum mean standard deviation value on Figure 5.

The reviewer comment is probably generated by a lack of explanation about the numbers reported in the text and of the standard deviation values plotted in figure 5.
The standard deviation reported in the text at lines 344-350 have been calculated through a mean of the standard deviations calculated at every single depth among all the available profile for each transect. These means involve all depths, generating low values of mean standard deviation.

On the other hand, shadowed values in figure 5 are the standard deviation values calculated at each depth among all the available profile for each transect.
Aiming at comparing the magnitude of the natural variability and the instrument precision, we consider that comparing values of line 344-350 is the worst hypothesis, (very low mean natural standard deviation), thus enforcing the idea that glider in situ measurements are precise enough to represent the basin variability.
In the new version of the manuscript, a deeper description of the standard deviation values showed in figure 5 is now included to better explain the difference between what is reported in text and figure. Standard deviation values reported in figure 5 are also commented at lines 350-352.

p12 line 351: could you rapidly mention these standard quality control procedures?

The text has been modified mentioning the spike removal and the comparison between adjacent profiles as standard QC procedures.

Figure 6: Why don’t you consider the saw-tooth green track in Figure 1?

The Reviewer is right. Data were missing.
Data have been added in figure 6 and 7

p12 line 353: How many ABACUS and historical observations profiles did you get? Maybe you can indicate the number here as you did in the conclusions.

The number of ABACUS and historical profiles have been added and updated according to the addition of the data from the saw-tooth glider sampling in figures 6 and 7.
The manuscript has been modified to include the updated number of ABACUS and historical profiles both in this paragraph and in the conclusions.

p14 line 405: is this transect representative of the others?

Yes, it is representative of the general data distribution and ocean circulation of the study area. Additionally, it is the most recent transect available in the dataset. This is the main reason why it was chosen.
This information has been added to the text.

Technical corrections:

p2 line 66: no capital letter to “Km”
Corrected

p2 line 87: no capital letter to “Km”
Corrected

p2 line 92; p5 lines 161, 162: please be consistent through the whole text between cm/s or m/s
Corrected

p3 line 107: please put a space between the point and “These”
Corrected

p4 line 138: please replace “JERCIO” by “JERICO”
Corrected

p4 line 149: please put a capital letter to “altiKa”
Corrected

p5 lines 151: please remove capital letters from “Temperature, Salinity”
Removed

p5 line 159: please put a space between the point and “ABACUS”
Corrected

p7 line 222: no capital letter to “Kg/m3”
Corrected

p19 line 492: please remove the capital letter from “We”
Corrected

Interactive comment on “Glider data collected during the Algerian Basin Circulation Unmanned Survey from 2014 to 2016” by Y. Cotroneo et al.

Anonymous Referee #2

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The paper presents data recorded by gliders in the Algerian Basin in an under-sampled area (between Balearic Island and Algerian waters). Eight transects have been performed in fall 2014 (3 transects), 2015 (1 transect), 2016 (4 transects), following different altimetric tracks. Moreover, taking advantage from the adaptative sampling ability some mesoscales process where investigated, deviating from the planned route.

Parts of this dataset were already discussed in two scientific papers dealing with an Algerian eddy (ABACUS 2014) or with a concomitant use of altimetry (ABACUS 2014, ABACUS 2015). Nevertheless, a rapid examination of the dataset demonstrates its potential interest for further studies (mainly mesoscale or even sub-mesocale processes).

The monitoring of the dynamics of this area is less achieved as the dataset cover only three consecutive years. Ones should encourage the authors to add progressively their more recent data in the same data base, as they suggest in the conclusion. A quick overview on the SOCIB website reveals that similar experiments were conducted in May 2016, in Fall 2017 and in May 2018. If the authors agree, a less restrictive title should be proposed (an unrestricted time period?) and the potential future extension of the database should be mentioned in the abstract.

Data processing and data quality check are the state of the art and well described. The paper is well written and organized. I tested the data repository and I appreciate the Netcdf file organisation. The on-line data visualisation is a little bit frustrating and not very informative. One would appreciate alternatively quick locks of the transects (on line or in an attached pdf file).

My general feeling is very positive and I recommend the publication of this paper and of the associated dataset, with minor modification.

We thank the Reviewer for his work and comments, and we are glad that he appreciated this version of our manuscript.

We agree with him on the possibility of removing the reference years from the title and will contact the Editor about it.

A new sentence about data extension has been added to the abstract as more recent data (years 2017/2018) will be added to the same DOI database soon.

Suggestions from the Reviewer on the online visualization of the data have been forwarded to the SOCIB Data Centre to improve ABACUS plot accessibility.

A point by point response (in red) to the specific comments received is provided below.

Best regards, Dr Yuri Cotroneo

Detailled comment:

line 52: What is exactly MW? - Modified Atlantic Water interacting with newly inflowing AW - Deeper water masses as LIW?

At line 52, we used the acronym MW to refer to all water masses that are typically formed or resident in the Mediterranean Sea.

The acronym was removed to clarify.

Please choose a unified name for your different dataset. Sometime you wrote (ABACUS ABACUS 2, ABACUS 3 (figure 5) or ABACUS 1, ABACUS 2, ABACUS 3 (line 139) or ABACUS 2014 (line 315). Note that this classification disappears on the data repository.

The text has been corrected and the “ABACUS 1, ABACUS 2, ABACUS 3” format has been adopted for the different missions. “ABACUS” will now describe the entire research programme.

Glider data collected during the Algerian Basin Circulation Unmanned Survey ~~from 2014 to 2016~~

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Abstract

We present data collected in the framework of the Algerian BAsin Circulation Unmanned Survey - ABACUS project. ABACUS main objective is the monitoring of the basin circulation and of the surface and intermediate water masses physical and biological properties in a key region of the Mediterranean Sea circulation. Data presented here have been collected through deep glider cruises in the Western Mediterranean Sea during the autumns of 2014, 2015 and 2016; activities at sea are expected to be repeated during the coming years, so that the dataset will be extended. Glider missions were realized in the Algerian Basin, between the Island of Mallorca and the Algerian Coast. Across the three glider missions, eight repeated transects were obtained which enabled us to investigate the basin scale circulation and the presence of mesoscale structures utilising both the adaptive sampling capabilities of the gliders and the higher resolution of the data.

After collection, all data passed a quality control procedure and were then made available through an unrestricted repository host by the SOCIB Data Centre at https://doi.org/10.25704/b200-3vf5. The actual dataset spans three fall seasons, providing an important contribution to the data collection in the chronically undersampled Algerian Basin.

Temperature and salinity data collected in the first 975 m of the water column allowed us to identify the main water masses and describe their characteristics improving the understanding of the dynamics of the region. On the time scale of the project, data show a large variability at the surface layer and reduced variability at the intermediate and deep layers.

Our measurements have been successfully compared to data previously collected in the area from 1909 to 2011. Results showed similar overall distribution, ranges and variability as the historical data, with no outliers in the surface or deep layers.

1 Introduction

The southwestern Mediterranean Sea is an important transit region characterized by the presence of both fresh surface waters coming from the Atlantic (Atlantic Water, hereafter AW) and more saline waters which typically reside in the Mediterranean region~~ (Mediterranean Water, MW)~~. At intermediate levels (400 – 1000 m) there is the Levantine Intermediate Water (LIW), typified by subsurface temperature and salinity maxima, while deeper layers (>1000 m) are occupied by the Western Mediterranean Deep Water (WMDW) (Millot, 1999; Millot et al., 2006). Most of the Western Mediterranean is occupied by the Algerian Basin (AB), a wide and deep basin comprised between the Balearic Islands, the Algerian Coast and the Sardinia Channel, where an intense inflow/outflow regime exists and complex circulation patterns take place (e.g., Pascual et al., 2013; Cotroneo et al., 2016; Aulicino et al., 2018). Typically, AW entering through the Strait of Gibraltar flows eastward at the AB surface, mainly inside the Algerian Current (AC), while more saline ~~MW~~water masses, formed in the eastern and northern parts of the Mediterranean, flows westward at the intermediate and deep layers (Millot, 1985; Testor et al., 2005). As previously demonstrated by several studies, AW and ~~MW ~~Mediterranean waters interact at different scales, from basin-scale to mesoscale and sub-mesoscale (Robinson and Golnaraghi, 1994; Fusco et al., 2003; Vidal-Vijande et al., 2011), allowing a high seasonal and interannual variability in the basin. This aspect is favoured by the presence of the AC. After leaving the Alboran Sea (Tintoré et al., 1991), this 30-50 km wide along-slope current flows eastward along the Algerian coast, carrying the AW eastwards (Testor et al., 2005). Typically, the AC becomes unstable along its path due to complex hydrodynamic processes, and forms several meanders which frequently evolves to isolated cyclonic and anticyclonic mesoscale eddies (e.g., Millot, 1985; Moran et al., 2001; Ruiz et al., 2002; Font et al., 2004; Escudier et al., 2016; Cotroneo et al., 2016; Pessini et al., 2018) promoting an intense mesoscale activity all over the AB. These structures present high levels of kinetic energy (Pascual et al., 2013; Escudier, 2016) and impact the distribution of physical and chemical properties of water masses, especially at surface and intermediate depths (Taupier-Letage et al., 2003; Olita et al., 2011).

In the last two decades, both satellites and numerical simulations data have been largely used to study mesoscale processes, partially balancing the scarcity of in situ observations. This improved our knowledge of the large-scale surface features (Vignudelli et al., 2003; Isern-Fontanet et al., 2016), but a complete understanding of mesoscale and submesoscale processes in the basin is still needed. To this aim, frequent dedicated observations at higher horizontal and vertical resolution, along the water column, are essential (Pascual et al., 2017). Multi-platform monitoring strategies, which enable the integration of data from satellites, Autonomous Underwater Vehicles (AUV) and numerical models, have already demonstrated their capabilities in the assessment of oceanographic processes in different regions of the global ocean, such as the Atlantic Ocean (Shcherbina et al., 2015) and the Mediterranean Sea (Carret et al., 2018; Troupin et al., 2018; Pascual et al., 2017; Aulicino et al., 2016). The value of these is improved when implemented along repeated monitoring lines coincident with the satellite groundtracks (Aulicino et al., 2018). Among other AUVs, measurements at small sampling intervals collected through gliders (<5 km spatial resolution) have contributed to several ocean studies (Rudnick, 2016, Heslop et al., 2012), from dynamics (e.g., Ruiz et al., 2009; Bosse et al., 2016; Cotroneo et al., 2016; Thomsen et al., 2016) to physical and biogeochemical exchanges (e.g., Ruiz et al., 2012; Bouffard et al., 2010; Cotroneo et al., 2016; Olita et al., 2017) or assessment of altimetry data (Heslop et al., 2017). However, gliders generally have a limited speed ranging between 0.35 m/s and 0.50 m/s in the horizontal (Griffiths et al., 2002; Rudnick et al., 2004; Jones et al., 2005; Merckelbach et al., 2010) that can arise synopticity problems when monitoring mesoscale phenomena (Rudnick and Cole, 2011; Alvarez and Mourre, 2012; Aulicino et al., 2016; Cotroneo et al., 2016) or wide areas (Liblik et al., 2016). Thus, their combination with reliable satellite products, numerical simulations and, when available, other platforms such as drifters, ARGO floats and ship-borne CTDs or a multiple glider missions represent the good strategy for implementing observatories for marine science research which aim to study basin scale and/or coastal processes (Aulicino et al., 2018) where issues of synchronicity are a concern.

Furthermore, this integrated glider-based approach is also important for validating new satellite products, such as the now fully-operational Sentinel-3 mission (Drinkwater and Rebhan, 2007; Heslop et al., 2017) and the upcoming Surface Water and Ocean Topography (SWOT) wide-swath radar interferometer (Fu and Ferrari, 2008), where multi-platform data are expected to help distinguishing noise from small dynamical structures, as a result of cross calibrations between the different sensors (Bouffard et al., 2010; Pascual et al., 2013).

In this study, we present data collected through three SLOCUM G2 (Figure 1) glider missions carried out in the AB during fall 2014, 2015 and 2016. These cruises were developed along a repeated monitoring line set across the AB and allowed the collection of a huge dataset of physical and biological ocean parameters in the first 975 m of the water column. For each mission, glider main track was chosen to lie under overflying altimeter satellites tracks, in order to optimize the inter-comparison of the data from the two platforms. Additionally, during the 2014 and 2015 glider cruises, the sampling track was changed in order to sample specific mesoscale circulation structures in the area. Even though this study is restricted to a particular area, i.e. the AB, we strongly believe that the scientific community could use these data to enlarge the knowledge of the western Mediterranean Sea and to refine the implementation of glider missions and integrated multi-platform observatories in other regions. Glider characteristics, sensors details, paths and mission strategies are described in Section 2; data format and quality control procedures are presented in Section 3. In section 4, a comparison between ABACUS observations and historical data, as well as sample ABACUS transects, are presented. Finally, Section 5 reports main conclusions.

Figure 1. The SLOCUM G2 *glider during the ABACUS pre-mission test at sea. Credit M. Torner.*

2 Glider field activities and technical details

Gliders are AUV able to provide high resolution hydrographic and bio-chemical measurements. These vehicles control their buoyancy to allow vertical motion in the water column and make use of their hydrodynamic shape and small fins to make horizontal motions. Changing the position of the center of gravity with respect to the center of buoyancy helps controlling both pitch and roll (Webb et al., 2001). This results in a typical saw-toothed navigation pathway to a maximum depth of 975 m.

During the autumns from 2014 to 2016, three deep SLOCUM G2 glider missions were carried out in the AB (Figure 2) using two gliders from the same constructor, with the same characteristics and overpassing the same calibration procedures.

ABACUS glider missions were performed in the framework of the SOCIB (Balearic Islands Coastal Observing and Forecasting System) Glider Facility Open Access Programme and supported by the Joint European Research Infrastructure network for Coastal Observatories (JERICO) Trans National Access (TNA). Funding agreements were developed under the JERICO TNA third call (grant No 262584) for ABACUS 1, the SOCIB external access for ABACUS 2 and JERICO-NEXT TNA first call (grant No. 654410) for ABACUS 3.

Up to 2016, a total of 8 repeated transects were realized between the Island of Mallorca and the Algerian Coast. In 2014 and 2015, after the realization of the defined transects, the glider track was changed in order to sample specific mesoscale structures in the study area (Figure 2).

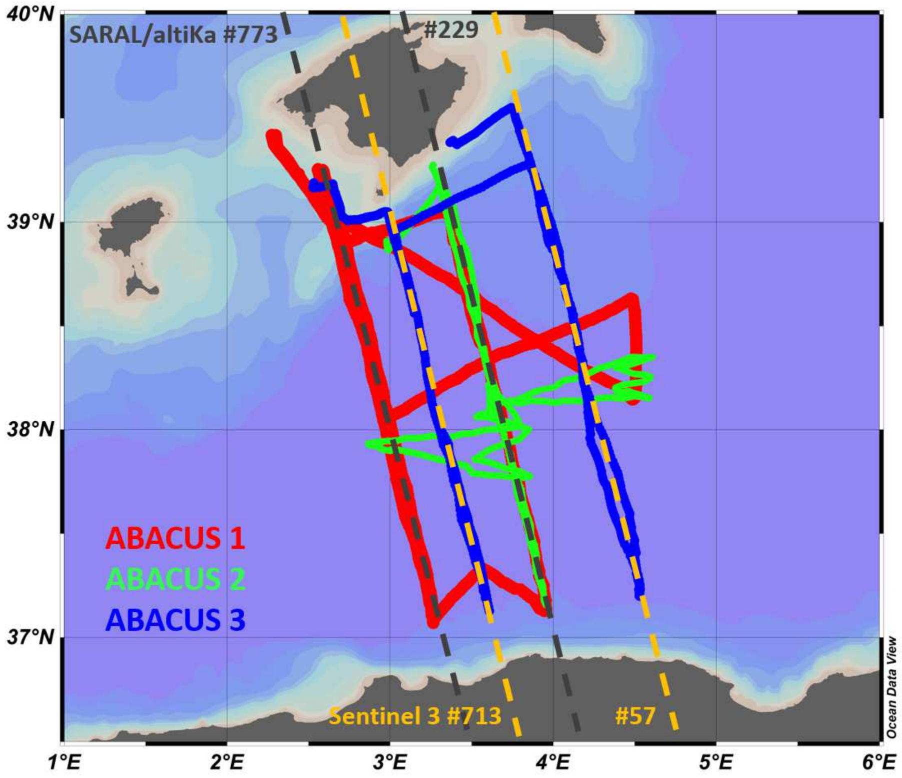

Figure 2. Glider tracks during the missions: ABACUS 1 (red dots), ABACUS 2 (green dots) and ABACUS 3 (blue dots). The deviations from the monitoring line were undertaken to sample some mesoscale structures identified through near real time satellite altimetry and SST maps. The groundtracks of the SARAL/AltiKa (grey dashed lines) and Sentinel 3 (yellow dashed lines) satellites over the study area are also showed.

During these cruises ABACUS gliders collected temperature, salinity, turbidity, oxygen and chlorophyll (CHLA) concentration data in the first 975 m of the water column. Each mission had an average duration of about 40 days and was always performed between September and December. In situ data collection was supported by remotely sensed data from different platforms over the Western Mediterranean Sea. In particular, gridded altimetry data provided by the Archiving, Validation and Interpretation of Satellite Oceanographic data (AVISO), Sea Surface Temperature (SST) and CHLA concentration information from MODerate resolution Imaging Spectroradiometer (MODIS) data acquired by NASA were used to provide a large scale description of the dynamics and surface water masses. ABACUS field activities were performed in collaboration with SOCIB and the Mediterranean Institute for Advanced Studies (IMEDEA) using a SLOCUM G2 glider for deep water (975 m maximum sampling depth) with a vertical speed of 0.18 ± 0.02 m/s, resulting in a horizontal velocity of about 0.36 m/s. During all missions, the general data acquisition design was set to dive with a descending angle of 26° between 20 m and maximum depth (Figure 3) with limited presence and sampling in the layer 0 – 20 m depth. In particular, during the 2014 mission, data collection in the surface (0-20 m depth) was limited at every third ascending profile, resulting in a sampling spatial resolution of 8.4 km for depths shallower than 20 m. In 2015 we collected a complete cast from surface to bottom at about 5 km resolution, as a result of the increased general resolution of the glider sampling, that was now performed during both upcast and downcast. Finally, in 2016 we tested glider possibility to sample the entire water column from 0 to 975 m depth at the resolution of 2.8 km. This was obtained sampling during both upcast and downcast and programming the glider to reach the surface after every cast. The experiment was successful, but limited in time due to battery constraints. For this reason, during ABACUS 3, the layer between 0 and 20 m depth is sampled at a variable resolution between 2.8 and 8 km.

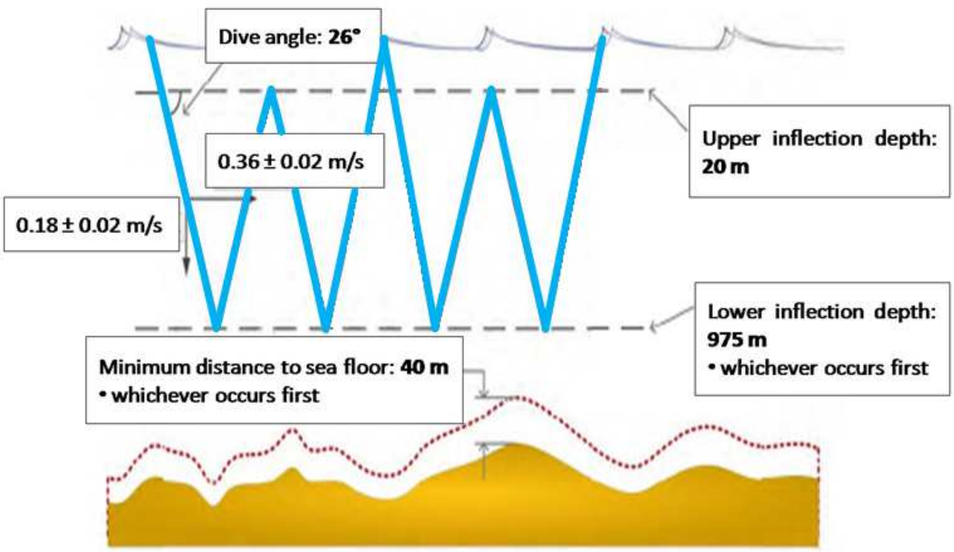

Figure 3. Glider navigation scheme during the ABACUS missions. The upper inflection depth was changed after the ABACUS 1 mission in order to allow the glider reaching the surface more frequently.

As described, the glider was programmed to reach the surface at different rates/spatial resolution during the three ABACUS missions and this resulted in a variable resolution of sampling of the very surface layer (0 – 20 m depth).

Several physical and optical biochemical sensors were carried aboard the glider for measuring the ocean temperature, salinity, oxygen, turbidity and CHLA concentration, at different rates according to depth. In particular, ABACUS gliders were equipped with a glider-customized CTD by Seabird-Scientific (http://www.seabird.com/glider-payload-ctd) measuring temperature, salinity (derived from conductivity) and depth, and a two-channel combo Fluorometer-Turbidity sensor by Wetlabs-Instruments (http://www.seabird.com/eco-puck), both of them embedded inside the central hull segment of the glider commonly known as the “science-bay”. Additionally, an oxygen optode to measure absolute oxygen concentration and saturation (%) by AADI (https://www.aanderaa.com/productsdetail.php?Oxygen-Optodes-2) was externally mounted on the aft, and wet, section of the glider.

The accuracy of the measurements, their vertical resolution and depth range vary according to the specific instrument and measured variable as reported in Table 1.

Temperature, salinity and oxygen data were sampled to full diving depth (0-975 m depth) while the acquisition of the other optical parameters ceased at 300 m depth.

Parameter	**Instrument**	**Sampling rate (Hz)**	**Vertical resolution (m)**	**Depth range (m)**	**Accuracy**	**Resolution**
Temperature (T), Conductivity (C), Depth (D)	Seabird GPCTD Glider payload pumped CTD	1/2	0.4	-5 to -975	T ± 0.002 °C C ± 0.0003 S/m D ± 0.1% fsr*	T 0.001 °C C 0.00001 S/m D 0.002% fsr*
Oxygen	AADI Optode 5013	1/4	0.8	-5 to -975	<8 µM or 5%	<1 µM
Fluorescence (F), Turbidity (Tu)	WetlabsFLNTUslk	1/8	1.6	-5 to -150	**Sensitivity** F 0.015÷0.123 µg/L Tu 0.005 ÷0.123 NTU	
		1/16	3.2	-150 to -300		

*Table 1. Sampling rate and vertical resolution of ABACUS gliders data (adapted from Cotroneo et al., 2016; Aulicino et al., 2018). * Full Scale Range*

A specific sampling rate was defined for each instrument (Table 1). Physical parameters (temperature and salinity) were sampled at 1/2 Hz, resulting in a vertical resolution of 0.4 m along the water column. Oxygen concentration was acquired at 1/4 Hz (vertical resolution 0.8 m) whilst turbidity and chlorophyll were sampled at 1/8 Hz until 150 m depth and at 1/16 Hz from that level until 300 m depth, with a vertical resolution of 1.6 m and 3.2 m respectively.

Calibration processes and regular maintenance were carried out before and after every glider mission and guarantee the quality of the measurements. While temperature and salinity sensors were regularly calibrated, unfortunately the optical sensors used during the ABACUS missions were not calibrated before the cruises. This results into the impossibility to use the derivated-variable values as absolute values. Nonetheless, gradients along space, depth and time can successfully be observed and discussed.

Generally, real time data transmission from the glider can be adaptively configured before and during the mission. For the ABACUS missions, it was set to occur at about every 6 hours, in correspondence with every second upcast for most of the glider transects. Real time data (having a file size ranging between 20 and 90 Kb) were transmitted using Iridium satellite link and contained a subset of all measurements, populated taking one out of every three samples for each parameter. This strategy permitted the retrieval of a first overview of the data collected, as well as the eventual transmission of new sampling and navigation directives to the glider. The full resolution dataset remained stored locally inside the glider until the vehicle was physically brought back to SOCIB facilities once the mission was completed. Then, data were transferred to SOCIB Data Center where pre-processing, processing and validation were carried out and NetCDF files created.

The structure and content of the ABACUS NetCDF file is described in section 3.

The pre-mission activities were carried out at the SOCIB glider facility (Tintoré et al., 2013) and included all ballasting, pressure tests, compass validation, and adjustment operations needed to assure the glider capability to reach the surface. This capability is provided by adjusting the overall weight of the vehicle and by distributing part of that weight so that inclination and roll are neutral when the glider sets its mechanical actuators (pump, mass shifter, air bladder and fin) in neutral mode (0 cc, 0 inch, no inflation and 0 rad respectively). That tuning is driven by the hydrographical characteristics of the target waters to be navigated, i.e. their minimum density, since they condition the execution of the mentioned operations. Within this scope, the climatological maximum value of temperature and minimum value of salinity for the studied area and period have been analysed. These data were used as extreme hydrographic characteristics of the target waters and allowed us to derive the minimum density (1024.0683 kg/m^3) needed to precisely tune the glider for the target waters. This tune up is required in order to make sure that the vehicle will always be able to break into the surface and to raise its tail above the water to have clear and robust communications.

As regards compass, Merckelbach et al (2008) developed a method to assess the glider compass error in SLOCUM gliders. This approach has been followed for gliders used during the later ABACUS experiments. The methodology should take place at any location away from sources of hard or soft electromagnetic material (e.g. sport ground), thus it was performed in a forest cleaning to minimize electromagnetic interference effects. Using a wooden platform, the glider was placed horizontally and a plastic-made compass stand aligned with the true North was used allowing precise and repetitive heading gradients of 15 degrees. The measurement error was then estimated by calculating the difference between the heading measured by the glider and the heading that was physically imposed using the stand. A maximum error of less than 10 degrees was observed during the three tests so that compass re-calibration was not considered necessary.

All these operations were performed on the two SLOCUM glider used during the ABACUS missions (SLDEEP001 for 2014 and 2016; SLDEEP000 for 2015) as part of the pre-missions tests and contributed in assessing the quality of the collected data.

The glider tracks were designed to cross the basin from the island of Mallorca (Spain) to about 20 miles off the Algerian coast (Figure 2). The timing of the missions was accurately planned in order to provide synoptic in situ data with respect to the satellite SARAL/ALtiKa and Sentinel-3A passages, being also comparable among the different ABACUS missions (Aulicino et al., 2018).

In 2014, during the ABACUS 1 mission, three glider transects were completed along the neighbouring SARAL/AltiKa groundtracks 229 and 773 from 15th September to 19th December 2014. The satellite overpassed the glider on 17 September and 26 November 2014 (track 773) and on 12 December 2014 (satellite track 229). During ABACUS 2 mission, carried on from 18th November to 11th December 2015, the glider was overflown by the SARAL/AltiKa satellite on 23

October, along the groundtrack 229 with the glider halfway along the transect. In fact, analysis of the data collected during the 2014 mission, highlighted the need of a higher degree of synopticity between the glider and satellite data. A specific deployment plan was then designed for the following ABACUS missions in order to have the glider approximately in the middle of the transect during the satellite passages. The improvement obtained in synopticity are extensively discussed in (Cotroneo et al., 2016; Aulicino et al., 2018).

During October 2014, a deviation from the planned sampling track was realized in order to investigate the presence and sample a mesoscale eddy (see red butterfly shape track in Figure 2). The eddy presence was first identified on the basis of near real time satellite altimetry and SST, then the glider track was modified during one of the glider surface communication periods. The adaptive sampling capabilities of the glider were then successfully used to perform two full depth transects across the mesoscale eddy (Cotroneo et al., 2016). After that, the scheduled ABACUS sampling track was restarted. The same strategy was applied in 2015 when the glider deviated twice from the planned track to monitor the edge of a possible mesoscale eddy (saw-tooth green track in figure 2).

Finally, during the ABACUS 3 mission was realized from 4th November to 23rd December 2016 and two new glider transects were performed along the Sentinel-3A groundtracks 57 and 713. The latter being located between the SARAL/AltiKa groundtracks 229 and 773 (see Figure 2). During this mission the glider was overflown on 12 November 2016 (track 57) and 5 December 2016 (track 713). All the details about dates of the missions and main water masses identified are reported in Table 2.

Resolution of sampling was defined according to the energetic constraints of the platform and to the scientific aims of the missions, which required high resolution in both horizontal and vertical directions to monitor large scale, as well as, mesoscale processes. During the ABACUS 1 mission, the glider was programmed to sample only during downcasts with a final along-track resolution of almost 4 km once the oblique profiles are projected into the vertical. As a result of the first data analysis, the sampling plan for the following missions was modified. During ABACUS 2 (2015) and ABACUS 3 (2016) cruises, both downcasts and upcasts data were collected, thus obtaining an improved spatial along-track resolution of about 2 km, while diving angle and speed remained unchanged. Apart from increasing horizontal sampling resolution, this new strategy also has an effect on data quality, enabling the application of the thermal lag correction developed by Garau et al. (2011) which requires consecutive up and down profiles of temperature and salinity.

3 Data quality control

After each mission, data were transferred from the internal glider memory to the SOCIB Data Center, where data processing was carried out and production of delayed time NetCDF files at different elaboration levels (i.e., level 0, level 1, level 2) occurred (Troupin et al., 2016; Cusi et al., 2013) before web dissemination of the data.

Each NetCDF file comprises the main cruise information, data and a short abstract. Level 0 contains the raw data collected by the glider without any elaboration or correction and organized in vectors. Level 1 includes data regularized, corrected and/or derived from raw glider data. Each variable is stored as sequences of measurements along the glider trajectory, with interpolated position coordinates to match the times of measurement by the sensor, and with unit conversions and filters applied. Each variable is described and commented individually. Level 2 dataset includes the regularly sampled vertical profiles generated from depth binning of already processed (level 1) glider data. The profiles are obtained by interpolation of level 1 data to produce regular homogeneous and instantaneous profiles from each up or downcast, using the mean time and position of the corresponding cast for the profile location and time. In this level, each variable is stored in matrix. Depth increases with the number of rows, with each row corresponding to 1 m depth, while time and consequently the number of profiles changes along the columns.

Delayed mode data processing for level 1 and 2 included thermal lag correction, filtering and 1 m bin vertical averaging (Troupin et al., 2016). In particular, in level 1 and 2, filters are mainly focused on the processing of pressure data through a low pass filter and on the interpolation of missing values. Nevertheless, some unexpected high oxygen concentration and high salinity values, as well as abrupt temperature value changes, were still present in the surface layer after this standard quality control protocol. The presence of these doubtful values at the shallower turning depth of the glider supports the hypothesis of a possible effect of glider navigation phase change on the sampling capability.

For this reason, during the 2015 and 2016 missions, the glider was programmed to reach the surface after every profile in order to avoid this issue, improve the data collection in the very surface layer (depth < 20 m) and provide a more suitable dataset for the comparison with satellite data.

Nevertheless, an additional quality control procedure was developed and regularly performed at University of Naples “Parthenope” on all ABACUS data. In particular, this procedure includes an additional single-point spike control, the interpolation of single missing data along the profiles, the application of a dedicated median filter, a 5-point running mean along the depth and, finally, an iterative comparison between adjacent profiles. This tool allowed us to identify and discard bad data and artefacts that were still present after the standard quality control. This final product is indicated as level 3 of the ABACUS dataset. An example of the level 3 elaboration steps is given in Figure 4. This additional procedure was routinely adopted for the quality control of all ABACUS glider missions for each geophysical parameter.

All dataset elaboration levels from 0 to 2 are available at https://doi.org/10.25704/b200-3vf5, while level 3 data are freely available upon direct request to the authors. Data samples presented in this manuscript are obtained from level 3 data.

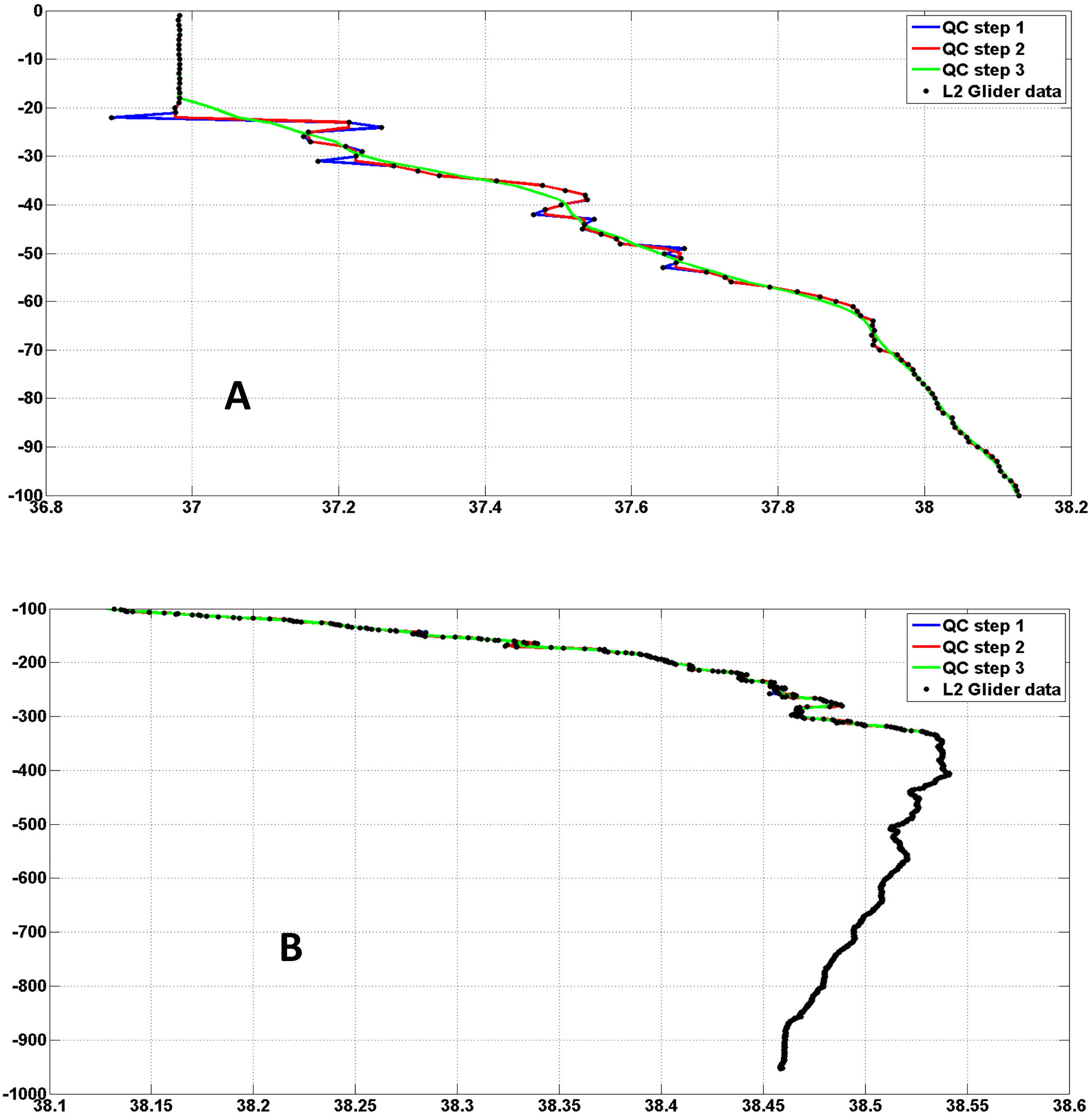

Figure 4. Effect of the additional quality control used to generate level 3 data. An example is shown for a salinity profile of the ABACUS 1 mission. The surface layer is shown in panel A (0-100m depth) while the intermediate and deep water layers are shown in panel B (from 100 to 975 m depth). Black dots represent the original level 2 data after the standard quality control procedures, blue line shows the single missing data interpolation, the median filter effect is shown through the red line, finally the green line represents the effect of the 5-point running mean on the data.

Figure 5 shows the mean temperature and salinity profile calculated for each transect completed during the ABACUS cruises from 2014 to 2016. For each mission, a mean profile was calculated using data of a single Mallorca-Algerian coast (or vice versa) transect. In this figure, the first available mean profile for each mission is shown in blue, the second in black, the third in red and the fourth in green. Standard deviation along depth during each transect was also computed for both temperature and salinity (shaded areas in Figure 5).

The ABACUS profiles are characterized by a high level of variability in the surface layer that considerably decreases in the intermediate and deeper layers, in agreement with existing literature in the area (Manca et al., 2004; Fusco et al., 2008). Salinity mean standard deviation values calculated over the entire water column for each available transect range between 0.01 (ABACUS 2nd transect) and 0.04 (ABACUS 1 1st and 3rd transect; ABACUS 2; ABACUS 3 from 2nd to 4th transect. Mean standard deviation values, calculated for the temperature, range between 0.05°C (ABACUS 2) and 0.15°C (ABACUS 3 1st, 3rd and 4th transect). Higher standard deviation values (up to 0.43 for salinity and 7.3°C for temperature in the surface layer of ABACUS 1 1st transect and ABACUS 2 respectively) are found when single depths are considered.

These values are generally larger than the precision of the glider sensors previously described (Table 1).

This supports the assumption that glider measurements are accurate enough to represent the variability of the basin. Ship-based CTD profiles collected at the same time and location of the ABACUS casts and corrected to bottle samples could provide material for an interesting comparison between glider and CTD probe data, but unfortunately, no ship-based CTD data were collected in correspondence of the ABACUS missions up to 2016.

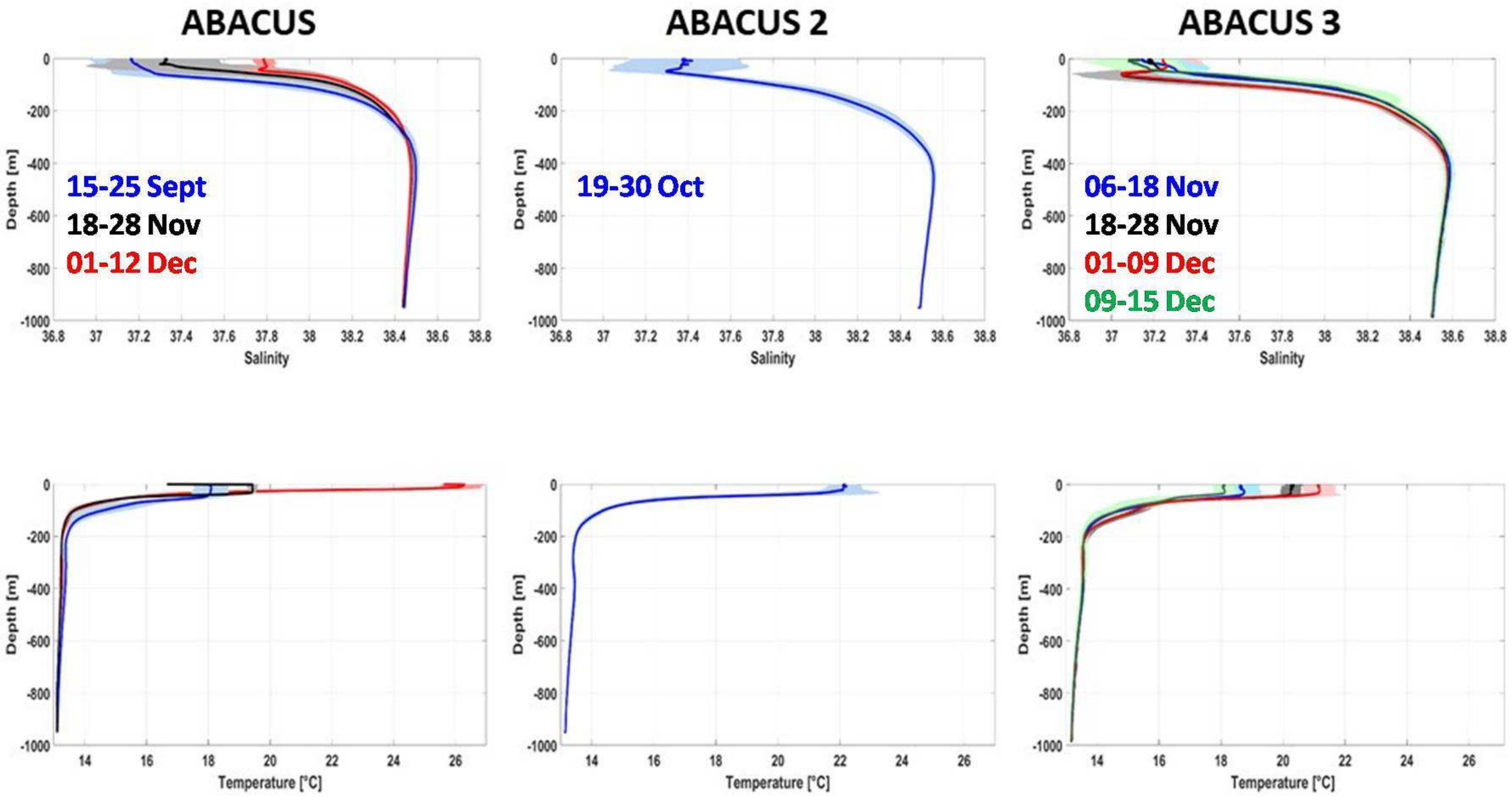

Figure 5. Mean salinity (upper panels) and temperature (lower panels) profiles (thick lines) for each ABACUS transect. From left to right, ABACUS 1, ABACUS 2 and ABACUS 3 data are represented. For each mission, the first available mean profile is shown in blue, the second in black, the third in red and the fourth in green. Shaded area represents the standard deviation calculated at each depth for each mean profile.

4 Data comparison and transect samples

In order to test the reliability of ABACUS dataset, a comparison was performed between glider data and a set of historical oceanographic measurements collected in the study area. In particular, a composite dataset including temperature and salinity data along the water column was realized merging data from the MedarMedatlas II project (MEDAR group, 2002), from the Coriolis CORA-3.4 Dataset (Cabanes et al., 2013) and from the World Ocean Hydrographic Profiles (WOHP - V1.0 database, in agreement with Viktor Gouretski). The resulting dataset, consisting of about 2450 profiles, spans from 1909 to 2011 with a regular distribution of the data across the different seasons. After the application of standard quality control procedures, including spike removal and the comparison among nearby profiles, the calculation of potential temperature (Θ) was carried out and the Θ/S couples from this dataset and the ABACUS observations were compared.

Figure 6 shows the comparison between ABACUS Θ/S data and all the available observations in the study area. ABACUS dataset consists of 2415 profiles with the same data distribution of the historical data, and no outliers in the surface or deep layers. These results confirm that glider ABACUS data captured, and correctly describe, the main thermohaline properties of the AB water masses and their variability.

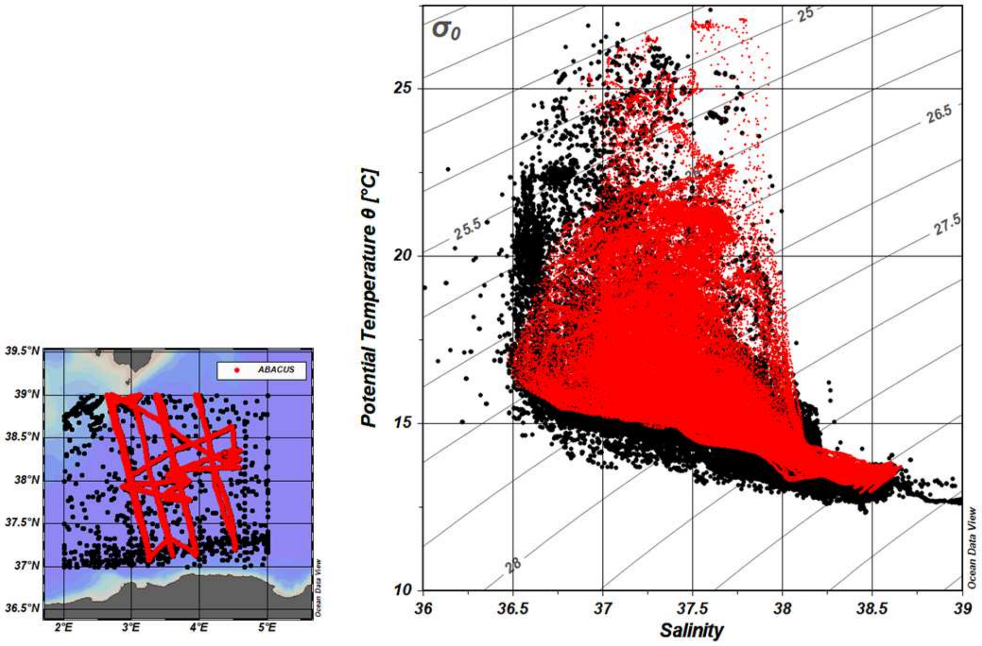

Figure 6. Θ/S diagram comparing historical oceanographic observations from 1909 to 2011 (black dots) to ABACUS data (red dots). The associated map shows the spatial distribution of the data.

In order to perform an additional and more accurate test on the data reliability, we selected the data collected during the fall season (September – December) from the merged historical dataset. This subset, consisting of 400 profiles was then used for a second comparison with the ABACUS data. Results are showed in the Θ/S diagram in Figure 7. Again, the ABACUS data successfully represent the hydrographic variability of the area, even when analysing data from a selected season. Furthermore, the reduced number of historical data in the fall season and their sparse distribution are a clear indication of the relative importance of ABACUS dataset for studying the AB.

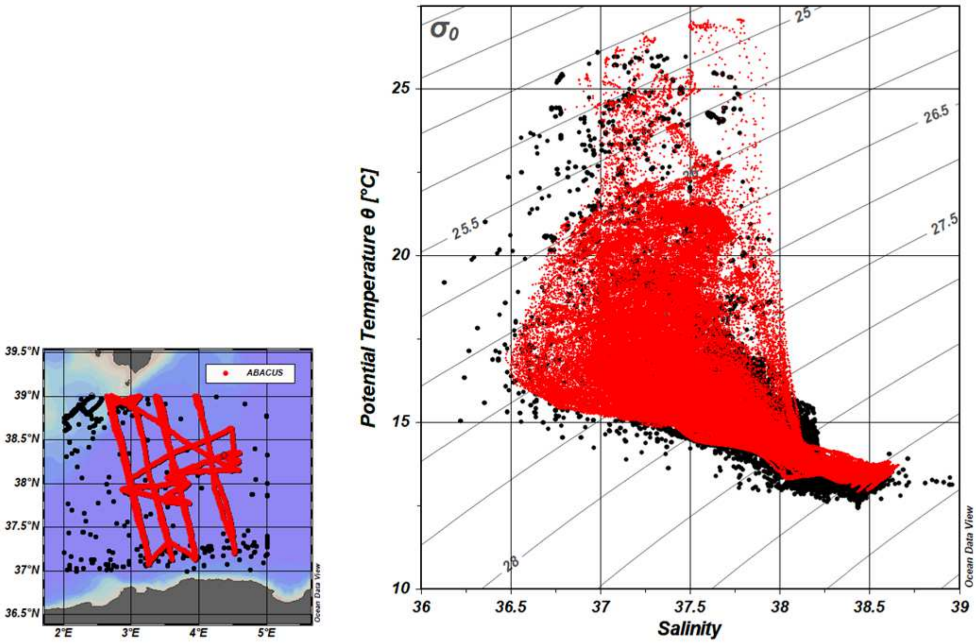

Figure 7. Θ/S diagram comparing historical oceanographic observations (black dots) during the fall season (September – December from 1909 to 2011) to ABACUS data (red dots). The associated map shows the spatial distribution of the data.

Several typical Mediterranean water masses have been identified in the θ-S diagrams derived from the glider mounted CTD during the three ABACUS missions at sea. A summary overview is provided in Table 2. The surface layer (0 to 50 m depth) was occupied by AW whose properties vary greatly according to different stages of mixing, precise geographical position and residence time in the Mediterranean Sea. Potential temperature, for example, ranges between 14.4°C and 27.0°C with colder waters always identified in the southern part of the AB. More mixed and modified waters are present in its northern sector due to the influence of Balearic waters (Cotroneo et al., 2016). As expected, the effect of seasonal cooling can be detected too; in fact, December missions presents lower mean surface water temperatures (below 19°C).

As for salinity, its values in the surface layer range between 36.51 and 38.04, with higher values measured next to the Mallorca Channel, characterized by shallow bottom and easier intrusion of saltier waters (Aulicino et al., 2018).

The intermediate layers were typically occupied by LIW, characterized by a potential temperature generally lower than 13.5 °C, a salinity of about 38.5 and a low oxygen concentration (see an example in Figure 8c). Its presence was mostly identified between 300 and 550 m depth.

The deepest observed layers (between 700 and 975 m depth) were usually characterized by the presence of WMDW with typical θ values ranging between 12.9°C and13.2°C and salinity ranging between 38.44 and 38.49. These waters were saltier (about 0.05) during fall 2015 and 2016 than in the 2014 glider mission.

Glider mission	AW	LIW	WMDW
ABACUS 1.1 15 Sept - 25 Sept 2014	14.44 ≤ θ ≤ 27.01 °C 36.56 ≤ S ≤ 37.98	13.21≤ θ ≤ 13.35 °C 38.48 ≤ S ≤ 38.52	12.91 ≤ θ ≤ 13.17 °C 38.44 ≤ S ≤ 38.49
ABACUS 1.2 18 Nov - 19 Dec 2014	15.82 ≤ θ ≤ 18.99 °C 36.73 ≤ S ≤ 37.34	13.29≤ θ ≤ 13.35 °C 38.49 ≤ S ≤ 38.53	12.92 ≤ θ ≤ 13.17 °C 38.44 ≤ S ≤ 38.49
ABACUS 2 19 Oct - 11 Dec 2015	16.11 ≤ θ ≤ 23.88 °C 36.52 ≤ S ≤ 38.04	13.32≤ θ ≤ 13.51 °C 38.53 ≤ S ≤ 38.59	12.99 ≤ θ ≤ 13.17 °C 38.49≤ S ≤ 38.54
ABACUS 3 4 Nov - 23 Dec 2016	15.18≤ θ ≤ 20.64 °C 36.51 ≤ S ≤ 37.84	13.29≤ θ ≤13.51°C 38.49≤ S ≤ 38.63	13.09 ≤ θ ≤ 13.23°C 38.49 ≤ S ≤ 38.55

Table 2. Temperature and salinity range values measured for Atlantic Water (AW), Levantine Intermediate Water (LIW) and West Mediterranean Deep Water (WMDW) during ABACUS 1, ABACUS 2 and ABACUS 3 missions.

The main properties of the water masses, as well as their spatial and vertical variability and distribution can be successfully observed through the analysis of vertical transects.

Figures 8 and 9 show the vertical sections along latitude of temperature, salinity, oxygen concentration, CHLA concentration and turbidity collected along the most recent transect of the ABACUS project. This North-South transect was realized during ABACUS 3, from December 1st to December 9th 2016 along the Sentinel 3 groundtrack number 713.

Temperature and salinity data collected in the surface layer (fig. 8 a,b) show a clear signature of the AC presence. Lower temperatures and salinities are registered in the southern part of the transect, highlighting the presence of AW recently entering the Mediterranean Sea. On the other hand, the northern part of the transect is characterized by more saline and warm waters with typical Mediterranean properties. Oxygen concentration in the surface layer presents the expected distribution, without any significant latitude pattern (Fig. 8c)

The North-South pattern is again evident in the CHLA concentration section (fig. 8d). An increase in the chlorophyll signal is registered in correspondence of the AC system at 50 m depth and, with lower intensity, at the northern edge of the transect where terrestrial nutrient input from the Mallorca island can be more important.

The CHLA concentration increase in the southern part of the transect shows the presence of a lower concentration area at about 37.3°N. This signal may be associated to meanders or filaments of the AC that deviate from the Eastward pattern of the current and impact on the biological properties of the water masses.

The same signal can also be identified in the temperature and salinity sections, even if with reduced intensity. The deeper layers (from 200 m to 975 m depth) are mainly characterized by the presence of the LIW. The relatively low oxygen concentration values and increased salinity signals registered between 300 and 500 m depth along most of the transect are a clear signature of the LIW presence (Fig. 9).

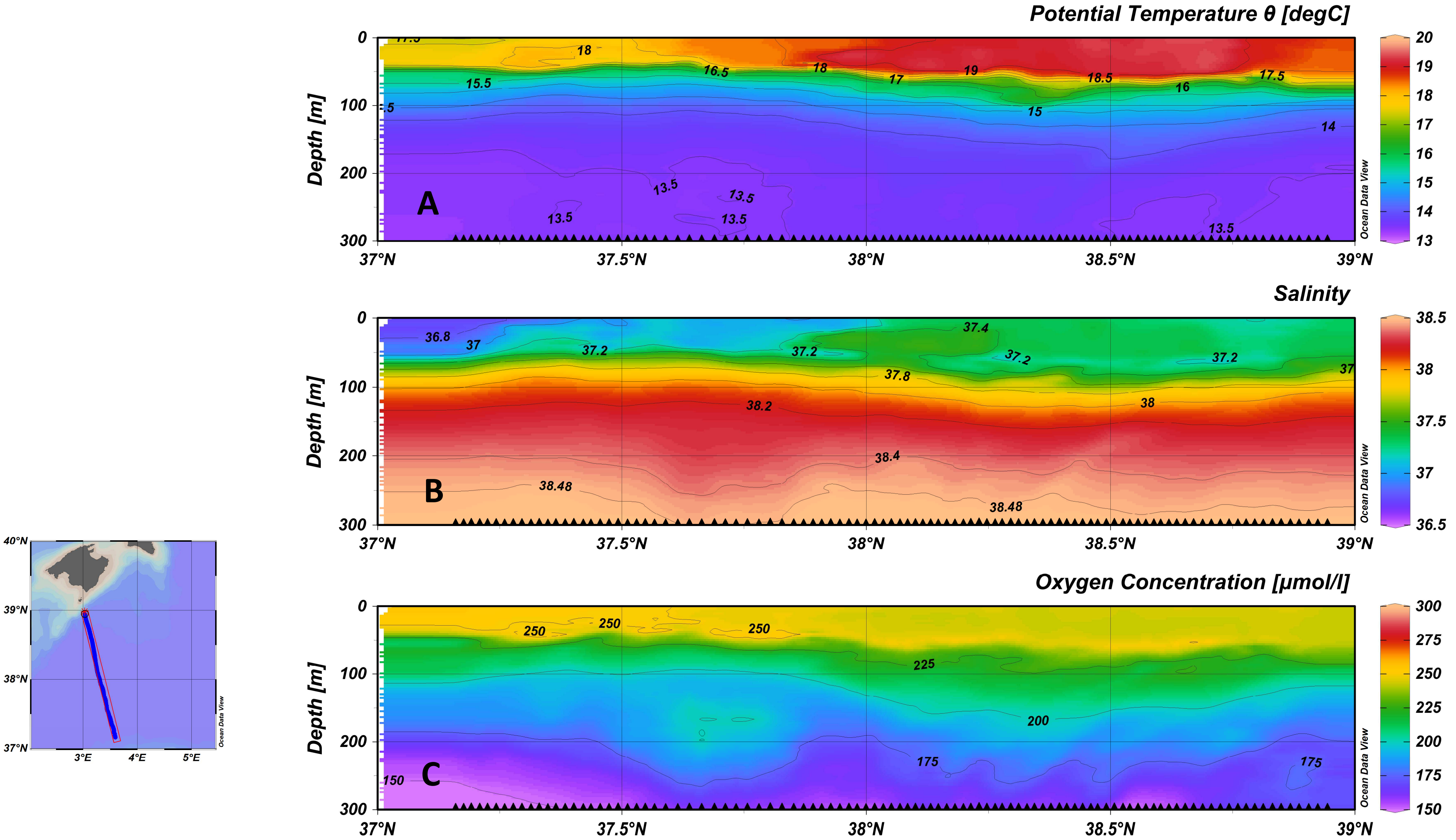

Figure 8. Surface layer (0-300 m depth) along track sections of potential temperature (a), salinity (b) and oxygen concentration (c) realized through ABACUS 3 glider data. Black triangles indicate the position of the single glider profiles.

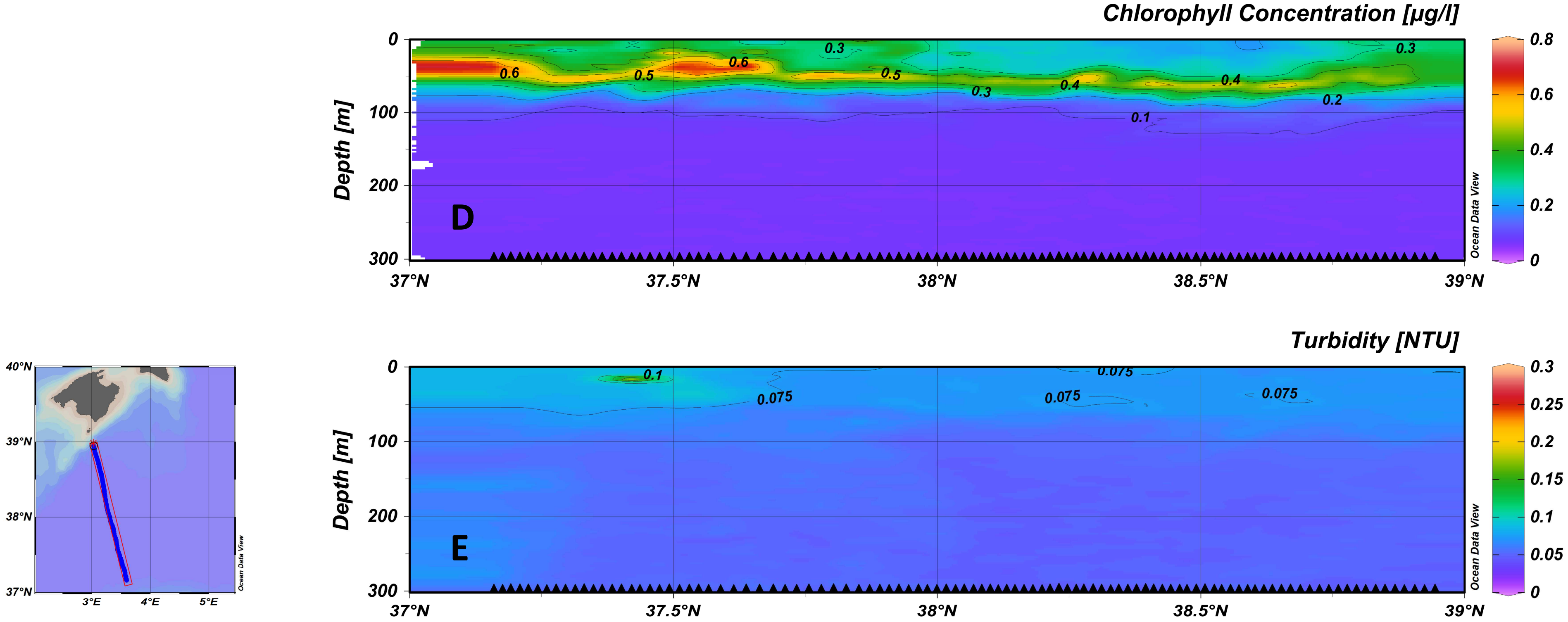

Figure 8. Surface layer (0-300 m depth) along track sections of Chlorophyll concentration (d) and turbidity (e) realized through ABACUS 3 glider data. Black triangles indicate the position of the single glider profiles.

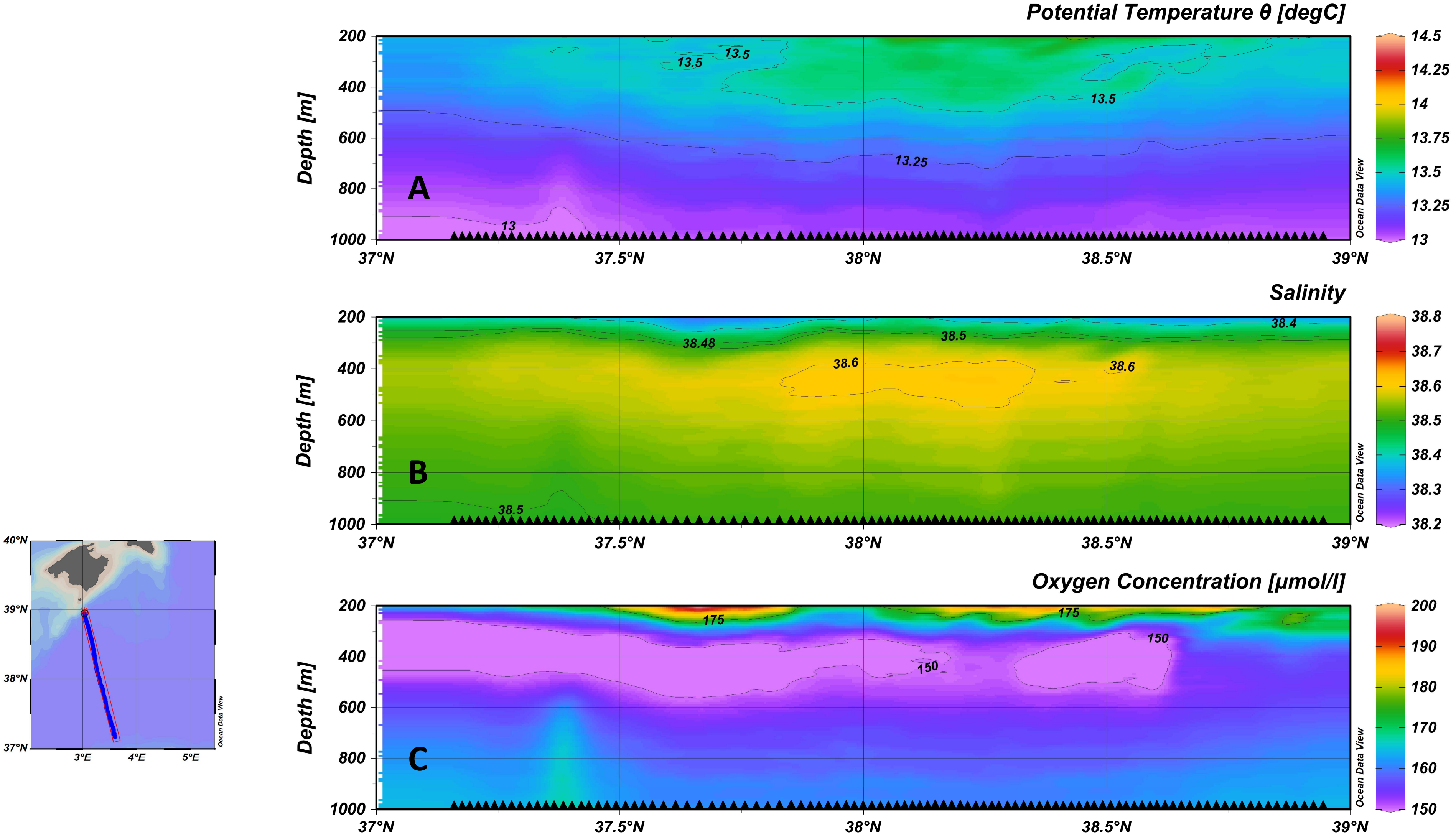

Figure 9. Intermediate and deep layer (200-975 m depth) along track sections of potential temperature (a), salinity (b) and oxygen concentration (c) realized through ABACUS 3 glider data. Black triangles indicate the position of the single glider profiles.

The 800-975 m depth layer, also shows the presence of a small scale structure at about 37.3°N. In this layer, a lower temperature and salinity signal associated to increased oxygen concentration can be found from 600 m to 975 m depth. This structure may be associated to the signals observed in the surface layer and surely deserves further investigations. All these data confirm the glider ability to describe the main water mass properties at all scales from basin to mesoscale and capture small scale structure along the water column and the investigated track. An example of mesoscale variability analyzed through ABACUS 1 glider data can be found in Cotroneo et al. (2016) which present the vertical sections of multiparametric observations collected across a mesoscale eddy.

5 Conclusions

The Mediterranean Sea is known to be particularly sensitive to changes in external forcings, thus being one of the most responsive areas to climate change (Schroeder et al., 2017; Gualdi et al., 2013) and its waters have already shown the presence of significant trends even in the deepest layers (Fusco et al., 2008; Budillon et al., 2009). In this framework, the ABACUS dataset provides about 2400 complete casts along the water column down to 975 m depth across the Algerian Basin one of the key areas of the western Mediterranean where monitoring programmes should be improved and intensified.

In particular, here we present data collected during a series of glider missions carried out from 2014 to 2016 in the framework of the ABACUS project. This effort allowed the collection of a large dataset of physical (temperature and salinity) and biochemical (oxygen concentration, turbidity and chlorophyll concentration) high resolution in situ observations. The reliability of these measurements was tested and assessed through different quality control procedures, as well as through comparisons with available historical datasets.

This dataset is available through an unrestricted repository at https://doi.org/10.25704/b200-3vf5, where NetCDF files including different elaboration levels (from 0 to 2) and documentation are easily accessible. This multiparametric dataset is expected to be particularly beneficial to oceanographic studies focusing on the characterization of the hydrographic and biochemical structure of the Western Mediterranean at all spatial scales. In fact, the presence of AW (at different modification stages), LIW and WMDW, as well as their interannual variability, can be observed and analysed, as reported by Aulicino et al. (2018). They included part of the presented dataset in their multiplatform analyses, stressing the usefulness of glider repeated monitoring in combination with altimetry and numerical simulations. Still, these observations already proved their contribution to the analyses of the mesoscale and sub-mesoscale processes in the study region (Cotroneo et al., 2016) whose study needs to be based on an appropriate high resolution in situ dataset to possibly be coupled with satellite remote sensing data.

Then, we believe that the ABACUS glider dataset represents a valid unrestricted product which could partially fill the lack of information in the AB, and a valuable tool for improving, together with similar information collected in the framework of other AUV projects, our knowledge about the dynamics of the Western Mediterranean and its physical and bio-chemical characteristics at different spatial scales.

Moreover, we expect that this data could be used to improve and validate information derived through numerical simulations, as well as to calibrate and validate present and future satellite observations, especially those acquired through radar altimetry.

In a future perspective, cost efficient repeated glider cruises can then contribute to create a network of endurance lines, monitoring both the short and long-term variability of the main physical and biochemical parameters of the Mediterranean Sea. At a larger scale, the use of gliders is crucial in the Global Ocean Observing System to fill gaps in transition regions between the open ocean and shelf areas (Liblik et al., 2016) and to increase the array of observations in areas traditionally lacking of in situ measurements, such as the Southern Mediterranean Sea. The synergy between multiple gliders surveys and other data sources, i.e., satellites, models, coastal radars, buoys and drifters, possibly including advisable occasional classical oceanographic cruises, could represent the best strategy to be implemented.

As for the AB, the ABACUS monitoring activities are expected to be repeated and enhanced during the coming years, taking into account the lesson learned through this study. From 2017 we enlarged the ABACUS network and realized more glider missions per year in order to monitor both seasonal and interannual variability along the Mallorca-Algerian coast transect.

Data availability

ABACUS glider data from 2014 to 2016 are available to the public in NetCDF format through an unrestricted repository at https://doi.org/10.25704/b200-3vf5. A set of NetCDF files for data from level 0 to level 2 is created for each glider deployment.

The SOCIB Data Centre hosts the data repository and offers a useful interface for data visualization and download.

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SOCIB Data Server hosts ABACUS data which are available at https://doi.org/10.25704/b200-3vf5.

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