

# 1 Hydrography in the Mediterranean Sea during a Cruise 2 with RV POSEIDON in April 2014

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## 10 11 **Abstract**

12 We report on data from an oceanographic cruise in the Mediterranean Sea on the German  
13 research vessel POSEIDON in April 2014. Data were taken on a west-east section, starting at  
14 the Strait of Gibraltar and ending south-east of Crete, as well on sections in the Ionian and  
15 Adriatic Sea. The objectives of the cruise were threefold: to contribute to the investigation of  
16 the spatial evolution of the Levantine Intermediate Water (LIW) properties and of the deep  
17 water masses in the Eastern Mediterranean Sea, and to investigate the mesoscale variability of  
18 the upper water column. The measurements include salinity, temperature, oxygen and currents  
19 and were conducted with a CTD/rosette system, an underway CTD and an ADCP. The  
20 sections are on tracks which have been sampled during several other cruises, thus supporting  
21 the opportunity to investigate the long term temporal development of the different variables.  
22 The use of an underway CTD made it possible to conduct measurements of temperature and  
23 salinity with a high horizontal spacing of 6 nm between stations and a vertical spacing of 1  
24 dbar for the upper 800m of the water column.

## 25 26 **Data coverage and parameter measured**

27 Repository-Reference:

28 <http://doi.pangaea.de/10.1594/PANGAEA.838923> (for CTD)

29 <http://doi.pangaea.de/10.1594/PANGAEA.838924> (for UCTD)

30 <http://doi.pangaea.de/10.1594/PANGAEA.838934> (for ADCP)

31 Coverage: 34°N-43°N, 6°W-26°E

1 Location Name: The Mediterranean Sea

2 Date/Time Start: 3. April 2014

3 Date/Time End: 28. April 2014

4

## 5 **1. Introduction**

6 The Mediterranean Sea is a marginal sea, as it is partly isolated from the Atlantic Ocean  
7 through the narrow Strait of Gibraltar. It consists of two sub-basins, the Western (WMed) and  
8 the Eastern (EMed) Mediterranean, which communicate through the broad (145 km) and  
9 shallow (maximum depth 550 m) Sicily Channel. Due to its dimensions (2.500.000 km<sup>2</sup>) and  
10 position, i.e. enclosed by continents, it can rapidly be affected by atmospheric forcing and  
11 anthropogenic influences (Schroeder et al., 2013). Several forces drive the circulation,  
12 external ones like wind-stress, strong topographic constraints and internal dynamic processes  
13 (Robinson et al., 2001, Pinardi et al., 2013). The emerging Mediterranean general circulation,  
14 therefore, encloses three predominant and interacting spatial scales: basin scale, sub-basin  
15 scale and mesoscale. Free and boundary currents and jets, permanent and recurrent, sub-basin  
16 scale, cyclonic and anticyclonic gyres populate both basins (Robinson et al., 2001). The  
17 associated eddy field to the mesoscale circulation consists of semi-permanent eddies with a  
18 spatial scale of about 120 km in diameter (Hecht et al., 1988).

19 The WMed and EMed show distinct differences, both in their hydrography and circulation.  
20 Different attempts to schematize surface as well as intermediate and deep paths of the  
21 circulation have been made in the past, based on observational evidences (see e.g. Malanotte-  
22 Rizzoli et al., 1997, 1999; Robinson et al., 2001; Roether et al., 2007; Schroeder et al., 2012).

23 The heat and freshwater budgets in the Mediterranean Sea are negative with a net loss of  
24 about 5 Wm<sup>-2</sup> and 0.7 my<sup>-1</sup>. The deficits are balanced by exchanges through the Strait of  
25 Gibraltar. The steady-state is balanced at multi-decadal time scales; at seasonal and  
26 interannual time scales heat loss and gain is possible due to single wintertime large  
27 evaporation events (Garrett et al., 1993; Pettenuzzo et al., 2010, Pinardi et al., 2013).  
28 However, it might be questionable if a steady state is a reliable assumption for the  
29 Mediterranean Sea circulation. As known the EMed went through drastic changes in the past.  
30 The largest climatic event, named Eastern Mediterranean Transient (EMT), took place in the  
31 EMed during the end of the eighties and beginning of the nineties, where the deep-water

1 formation switched from the Adriatic to the Aegean Sea. This episode changed the  
2 thermohaline characteristics of the outflow through the Sicily Channel significantly, which  
3 consequently modified the characteristics of the WMed (Millot et al. 2006, Schroeder et al.,  
4 2006). Thus, since 2005 the deep waters of the WMed experienced significant physical  
5 changes, which are comparable to the EMT, both in terms of intensity and observed effects  
6 (Schroeder et al., 2008). This event is often called the Western Mediterranean Transient  
7 (WMT). Therefore, the existence of both transients contradicts this assumption. On the other  
8 hand, it was proven that the EMT was never observed before (Roether et al., 2013).

9 The water mass formation cycle is characterized by the inflow of low-salinity Atlantic Water  
10 (AW) in the upper 100 m of the water column and with identification values of  $S = 36.0-36.5$   
11 psu in the Strait of Gibraltar (Said et al., 2011), and a return flow of the salty Levantine  
12 Intermediate Water (LIW), formed in the Levantine Basin and positioned in the intermediate  
13 layer (typically at a depth of 200-600m). The depth variability of the LIW salinity maximum  
14 is largely regional: generally, depths increase westward. The Sicily Channel, with a depth  
15 lower than 550m, acts as a natural barrier between the WMed and EMed. Deep and  
16 intermediate water formation takes place in each of the basins. In the WMed the abyssal water  
17 mass is produced by shelf and open-ocean convection in the Gulf of Lyons, namely the  
18 Western Mediterranean Deep Water (WMDW, see e.g., Leaman and Schott, 1991). The  
19 EMed instead is characterized by two deep-water formation regions, where the Adriatic Deep  
20 Water (AdDW) and the Cretan Deep Water (CDW) are produced. Thus, the predominant  
21 water mass of the bottom layers, filling the abyssal plains of the Ionian and Levantine basins,  
22 namely the Eastern Mediterranean Deep Water (EMDW), is a mixture of AdDW, CDW and  
23 shallower water masses. Detailed descriptions of the general circulation and hydrography of  
24 the EMed can be found in Lascaratos et al., 1999, Hamad et al., 2005, Rubino and  
25 Hainbucher, 2007, Klein et al., 2010, Gačić et al., 2011, Cardin et al. 2015 and others.

26 The principal scientific objective of the cruise is threefold:

- 27 a) To add knowledge to the understanding of the dispersion of LIW water masses from  
28 the eastern basin of the Mediterranean Sea to the Strait of Gibraltar
- 29 b) To investigate the mesoscale variability of the upper water columns of the two basins  
30 of the Mediterranean Sea
- 31 c) To continue the documentation and to contribute to the understanding of the evolution  
32 of the deep water masses in the EMed since the appearance of the Eastern  
33 Mediterranean Transient.

1 According to the Med-Ship Program (CIESM Monographs 43, 2012) the cruise supports the  
2 investigation of its relevant objectives which are, amongst others, engaged in the  
3 determination of changes and of long-term variability of hydrographic parameters in the  
4 Mediterranean Sea. Although most of the data of this campaign are not “full water column  
5 observations”, this survey is a valuable contribution to improve the database of the  
6 Mediterranean Sea for a better understanding of the variability on multiple time scales and for  
7 numerical model evaluations.

8 To our knowledge, there exists just one further campaign which covers an east-west transect  
9 through the whole Mediterranean Sea but with a much lower sampling rate (Meteor cruise  
10 M84-3, Tanhua et al., 2013). More frequently, several campaigns at the level of sub-basin for  
11 both the WMed (Schroeder et al., 2008) and the EMed (Cardin et al., 2015) have been carried  
12 out during the past decades.

## 13 **2. Data Provenance**

14 The survey was carried out on the German RV POSEIDON from 3<sup>rd</sup> of April to 28<sup>th</sup> of April  
15 2014. The cruise started in Portimão, Portugal and ended in Bari, Italy (fig. 1). The data set is  
16 composed of three components: profiles from a CTD, profiles from an underway CTD  
17 (UCTD) and velocity profiles from an ADCP (table 1). Figure 2, 3 and 4 show examples for  
18 the calibrated and quality controlled data of the UCTD, CTD and ADCP.

## 19 **3. Methods and Quality Control**

20

21 The most recent campaign (April 2011), including an east-west transect through the whole  
22 Mediterranean Sea, was the RV METEOR cruise M84/3 (Tanhua et al., 2013). On M84/3  
23 CTD and ADCP measurements were conducted. Additionally to the physical parameters,  
24 chemical variables like nutrients, helium, tritium, SF<sub>6</sub>, CFC-12 and others were taken.  
25 Compared to the cruise here, the sampling rate of M84-3 was coarse accommodating the  
26 demand to take a variety of parameters during a reasonable time. Contrariwise, the campaign  
27 of POSEIDON was restricted to measurements of physical components, but with the aim to  
28 achieve a high horizontal resolution in order to resolve hydrographic phenomena on  
29 mesoscales.

30

### 1 **3.1 CTD/rosette**

2 During the cruise, altogether, 37 full depth standard hydrographic stations (fig. 1) were  
3 collected with a 24 Hz sampling Sea-Bird SBE 911 plus CTD, fastened to a 12 bottles SBE 32  
4 Carousel Water Sampler. The instrument was equipped with double conductivity and  
5 temperature sensors and two SBE 43 dissolved oxygen sensors. Specifications for the CTD  
6 sensors are given in table 2.

7 At almost all stations water samples were taken at 12 pre-defined depths along the water  
8 column for oxygen analysis and at three of which also for salinity analysis. The salinity  
9 samples were analysed on board using a Guildline Autosal Salinometer. The batch-no. of the  
10 standard seawater samples is 38H11 which have a K15-factor of 1.07631 (24°C). An  
11 explanation of standard seawater definitions can be found in Bacon et al. (2007).

12 Temperature and salinity CTD data were post-processed by applying standard Seabird  
13 software and MATLAB routines. At this stage spikes were removed, 1dbar averages  
14 calculated, and the downcast profiles of temperature and salinity were corrected with a  
15 regression analysis. Data from the double sensors were correlated, and the salinity  
16 measurements were additionally corrected by comparison with the discrete salinity water  
17 samples to improve the level of precision. Since the corrections to the parameters were  
18 negligible, the data quality was excellent. Overall accuracies are within expected ranges:  
19 0.002°C for temperature and 0.003 for salinity.

20 Dissolved oxygen samples were analysed on board by means of the Winkler potentiometric  
21 method. The dissolved oxygen CTD data were treated in the same way as for temperature and  
22 salinity. A comparison between CTD oxygen sensors and the discrete water samples was  
23 carried out also for this parameter. The accuracy of the data reached approximately 2  $\mu\text{mol kg}^{-1}$   
24 <sup>1</sup>.

25 All procedures fit the guidelines of the GO-SHIP Repeat Hydrography Manual (McTaggart et  
26 al., 2010)

27

### 28 **3.2 Underway-CTD**

29 Underway measurements of pressure, temperature and conductivity profiles were made with  
30 an Ocean Science UCTD system in order to increase the spatial resolution of the survey, but  
31 without having to perform several additional time-consuming CTD casts. Altogether, we took  
32 378 casts (fig. 1). Initially we used three probes (s/n 0068, 0155 and 0183), but after the loss

1 of a probe right at the beginning of the cruise, we decided to use only the Tow-Yo (Ullman  
2 and Hebert, 2014) deployment procedure in the following, where no spooling on the probe's  
3 spindle was carried out. The sampling strategy included a sampling distance between UCTD  
4 casts of approximately 6 nm or about 1 hour keeping a ship's speed of 6 knots. The ship  
5 reduced speed to 2-3 knots, while the probe was falling for a maximum of 480 sec. The ship  
6 enhanced speed again to 6 knots during the recovery of the probe. We reached maximum  
7 depths of around 850m, minimum depths of 500m. The average depth was approximately  
8 650m. Specifications for the UCTD sensors are given in table 3.

9 The data are logged internally and are downloaded to a computer after recovery of the  
10 instrument. No processing is done internally. Since the probes are not georeferenced, ship  
11 navigation data were used. During processing one has to account for mainly two factors which  
12 cause inaccuracies: Different probes show different offsets to the CTD, and the accuracy of  
13 results depends on the variable descent rate during deployment. For the correction of the  
14 offset we used data of CTD stations, as we carried out a UCTD measurement at each CTD  
15 position. Additionally, we run one CTD station with the remaining two UCTD probes  
16 installed at the CTD rosette. For each probe we determined the mean deviation from the  
17 UCTD with respect to the CTD casts and corrected all UCTD results accordingly. To account  
18 for the variable descent rate, we carried out the steps suggested by Ullman and Hebert, 2014.  
19 Hence, we corrected for a descent-rate-dependent alignment of temperature and conductivity,  
20 for the effect of viscous heating and for the conductivity cell thermal mass.

21

### 22 **3.3 Shipborne ADCP**

23 Underway current measurements were taken with a vessel-mounted 75 kHz Ocean Surveyor  
24 (ADCP) from RDI in narrow band mode covering approximately the top 600-800m of the  
25 water column. The bin size was set to 8 m. The instrument was controlled by computers using  
26 the conventional VMDAS software under a MS Windows system. Pinging was set as fast as  
27 possible. No interferences with other used acoustical instruments were observed. The ADCP  
28 data was post-processed with the software package *ossi14* (ocean surveyor sputum interpreter)  
29 developed by the Leibniz Institute of Marine Sciences (GEOMAR, T. Fischer, 2011), Kiel,  
30 which also corrects for the misalignment angle. The misalignment angle was calculated at  
31 approximately -3.5 degrees.

32

#### 1 **4. Discussion and Conclusion**

2 The TS-diagram (fig. 3) gives an overview of the TS characteristics in the whole  
3 Mediterranean Sea during April 2014. The results are comparable to those we found already  
4 in April and June 2011 on cruises with RV Meteor and RV Poseidon (Hainbucher et al.,  
5 2013), and they highlight the differences which exist between the EMed and WMed. The  
6 horizontal distance between CTD stations were too coarse to consider the transects reliable,  
7 yet, the high resolution of UCTD (figure 2) and ADCP data (figure 4) show nicely the  
8 mesoscale variability in both basins during the cruise. Both Alboran gyres and high eddy  
9 activity along the section through the WMed can be identified. Some of these structures can  
10 be related to well-known features like the Almeria-Oran Gyre or the South-Western  
11 Tyrrhenian Gyre (Pinardi et al., 2013). In the EMed we found a lot of mesoscale eddies along  
12 the track between Sicily and Crete. Presumably, we touched, amongst others, the Western  
13 Cretan Cyclonic Gyre and the Ierapetra Gyre (Pinardi, et al., 2013). Hence, some of the  
14 positions of the gyres, that we found, have confirmed those already present in the literature by  
15 observations or results of models. But not all of the gyres can be related to well-known  
16 features. We conclude from this fact, that a lot of the gyres are non-permanent, and that even  
17 the location of the permanent eddies are subject to high spatial variability. This has to be  
18 concretized and proofed further on. The tool for the investigation of such highly variable  
19 phenomena were up to now numerical models, but with such UCTD measurements it is  
20 possible to resolve the structures with a reasonable effort in time and money.

21 The salinity distribution (figure 2) furthermore reflects the spatial development of LIW from  
22 east to west. The LIW signal is stronger in the EMed than in the WMed and can be identified  
23 by the salinity maximum in the 100-600 m depth layer.

#### 24 **5. Data access**

25 Data are published at the information system PANGAEA; [http://doi.pangaea.de/](http://doi.pangaea.de/10.1594/PANGAEA.838923)  
26 [10.1594/PANGAEA.838923](http://doi.pangaea.de/10.1594/PANGAEA.838923) for CTD data, [http://doi.pangaea.de/10.1594/](http://doi.pangaea.de/10.1594/PANGAEA.838924)  
27 [PANGAEA.838924](http://doi.pangaea.de/10.1594/PANGAEA.838924) for UCTD data and <http://doi.pangaea.de/10.1594/PANGAEA.838934>  
28 for ADCP data.

29

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1 Table 1. List of parameters from Poseidon cruise P468 as seen in the PANGAEA database.

2 PI: Dagmar Hainbucher

Parameter Name	Short name	Unit	Method	Comments
<b>DATE/TIME</b>	Date/Time			Geocode
<b>LATITUDE</b>	Latitude			Geocode
<b>LONGITUDE</b>	Longitude			
<b>Pressure, water</b>	Press	dbar	CTD, SEA_BIRD SBE 911plus	
<b>Temperature, water</b>	Temp	°C	CTD, SEA_BIRD SBE 911plus	
<b>Salinity</b>	Sal		CTD, SEA_BIRD SBE 911plus	PSU
<b>Oxygen</b>	O2	µmol/l	CTD with attached oxygen sensor calibrated, corrected using Winkler titration	
<b>Pressure, water</b>	Press	dbar	UnderwayCTD (UCTD), Oceanscience	
<b>Temperature, water</b>	Temp	°C	UnderwayCTD (UCTD), Oceanscience	
<b>Salinity</b>	Sal		UnderwayCTD (UCTD), Oceanscience	PSU
<b>DEPTH, water</b>	Depth water	m		Geocode
<b>Current velocity east-west</b>	UC	cm/s	Shipboard Acoustic Doppler Current Profiling (SADCP)	
<b>Current velocity north-south</b>	VC	cm/s	Shipboard Acoustic Doppler Current Profiling (SADCP)	

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1 Table 2: Used CTD instrument and sensors. Owner of instruments are either the University of  
 2 Hamburg, Germany (IFM-CEN) or the National Institute of Oceanography and Geophysics  
 3 (OGS), Italy.

<i>Instrument/Sensor</i>	<i>Serial Number (owner)</i>
SBE 911plus / 917plus CTD	285 (IFM-CEN)
Temperature 1: SBE-3-02/F	1294 (IFM-CEN)
Conductivity 1: SBE-4-02/2	1106 (IFM-CEN)
Pressure 410K-105	50633 (IFM-CEN)
Temperature 2: SBE-3-02/F	1717 (OGS)
Conductivity 2: SBE-4-02/2	3442 (OGS)
Altimeter PSA 916D	885 (IFM-CEN)
Oxygen 1 SBE 43	1761 (IFM-CEN)
Oxygen 2 SBE 43	2513 (OGS)

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5 Table 3: Used UCTD sensors.

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Probe 1	Device Type	Serial Number (owner)
0068	90560 UCTD /SBE49 FastCat CTD	70200068 (IFM-CEN)
0155	90745 UCTD / SBE 37 MicroCat	70200155 (IFM-CEN)
0183	90745 UCTD / SBE 49 FastCat CTD	70200183 (IFM-CEN)

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1 **Figure Legend**

2 Figure 1: Cruise track of P468 with CTD stations marked in red and UCTD stations marked in  
3 blue.

4 Figure 2: Temperature and salinity distribution along a west-east section through a) the  
5 western Mediterranean and b) the eastern Mediterranean Sea. Data are gained by an underway  
6 CTD. Inner panels show the location of UCTD stations. White areas: data are out of  
7 instrument range.

8 Figure 3: TS diagram determined by CTD data. The inner panel shows the location of CTD  
9 stations. The colors correspond with the colors of the profiles.

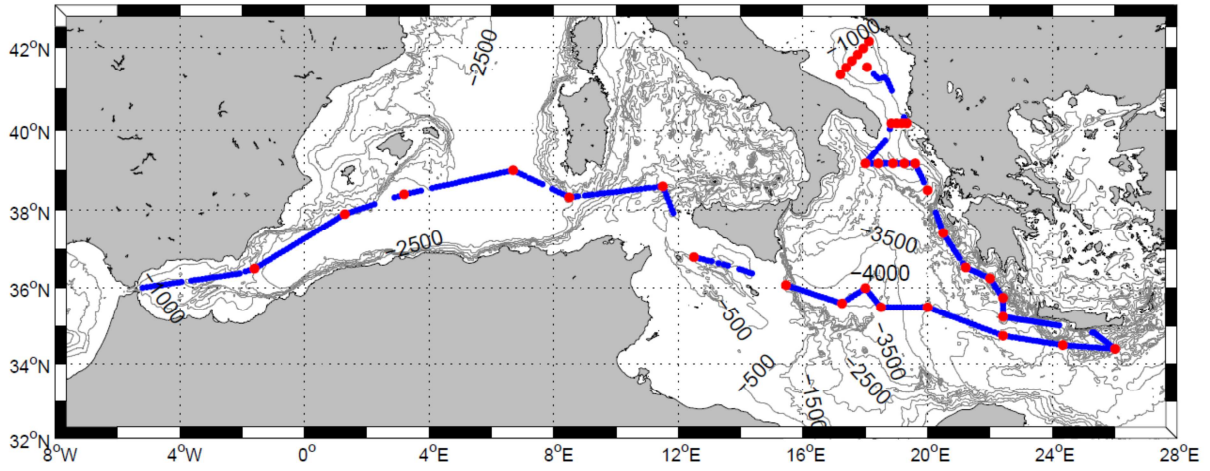
10 Figure 4: Velocity distribution of the upper 400m of the water column along a west-east  
11 section through a) the western Mediterranean and b) the eastern Mediterranean Sea. Data are  
12 gained by a shipborne ADCP. Shown are the east-west and north-south velocity component,  
13 respectively. Inner panels indicate the location of the ship track. White areas: no data are  
14 available. X-axes: east-west distance (km). Y-axes: depth (dbar).

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3 Figure 1: Cruise track of P468 with CTD stations marked in red and UCTD stations marked in  
4 blue.

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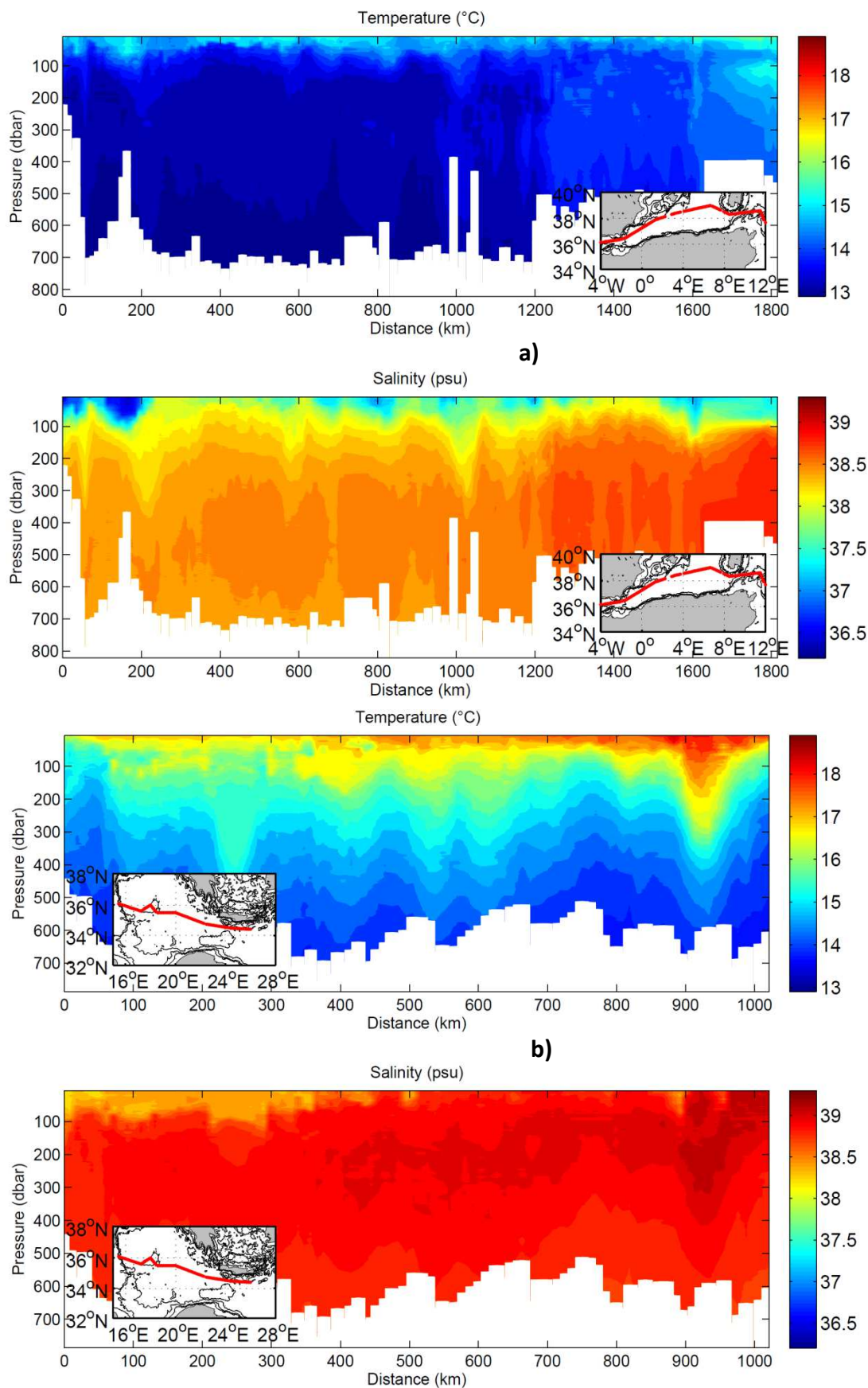


Figure 2: Temperature and salinity distribution along a west-east section through a) the western Mediterranean and b) the eastern Mediterranean Sea. Data are recorded by an underway CTD. Inner panels show the location of UCTD stations. White areas: data are out of instrument range.



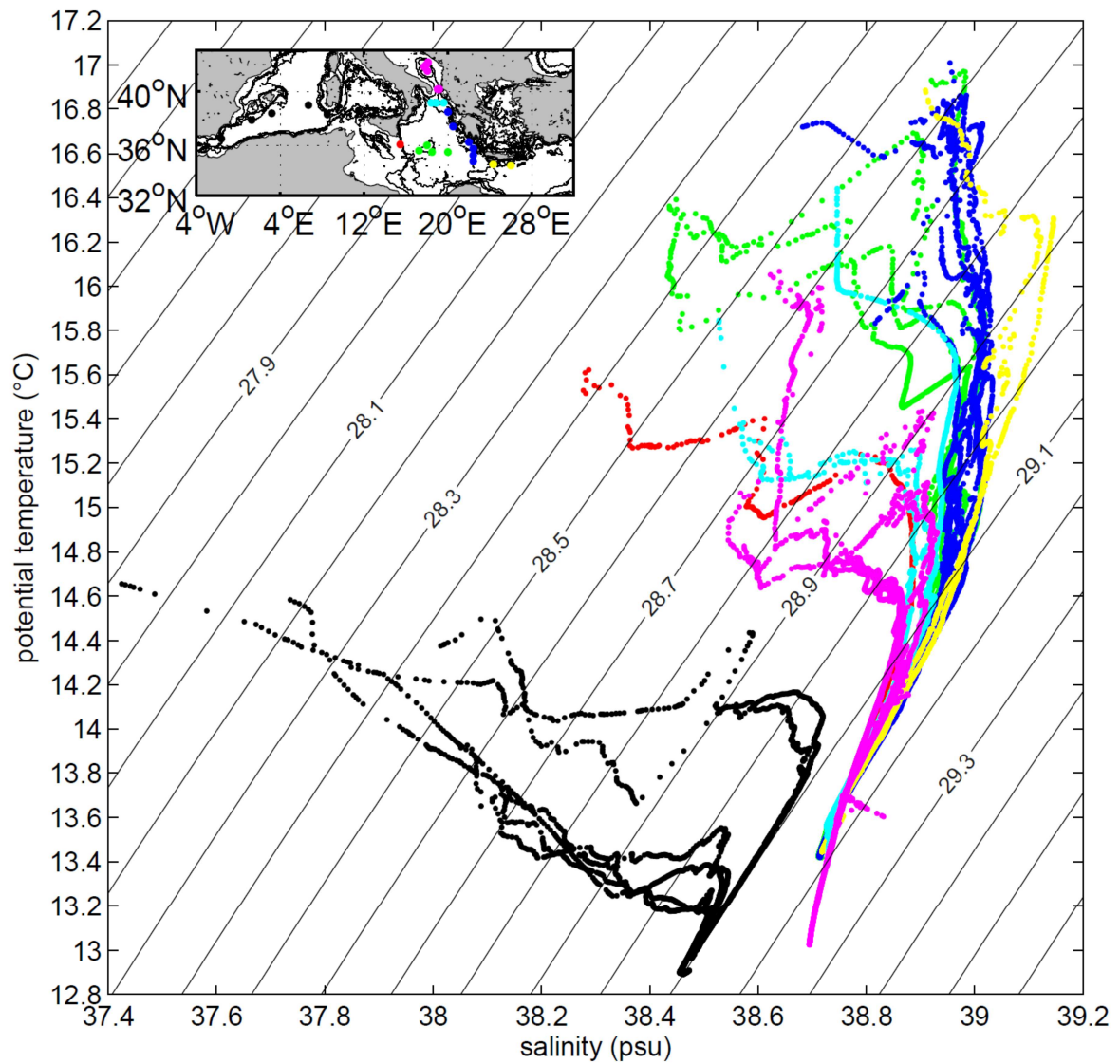


Figure 3: TS diagram determined by CTD data. The inner panel shows the location of CTD stations. The colors correspond with the colors of the profiles.

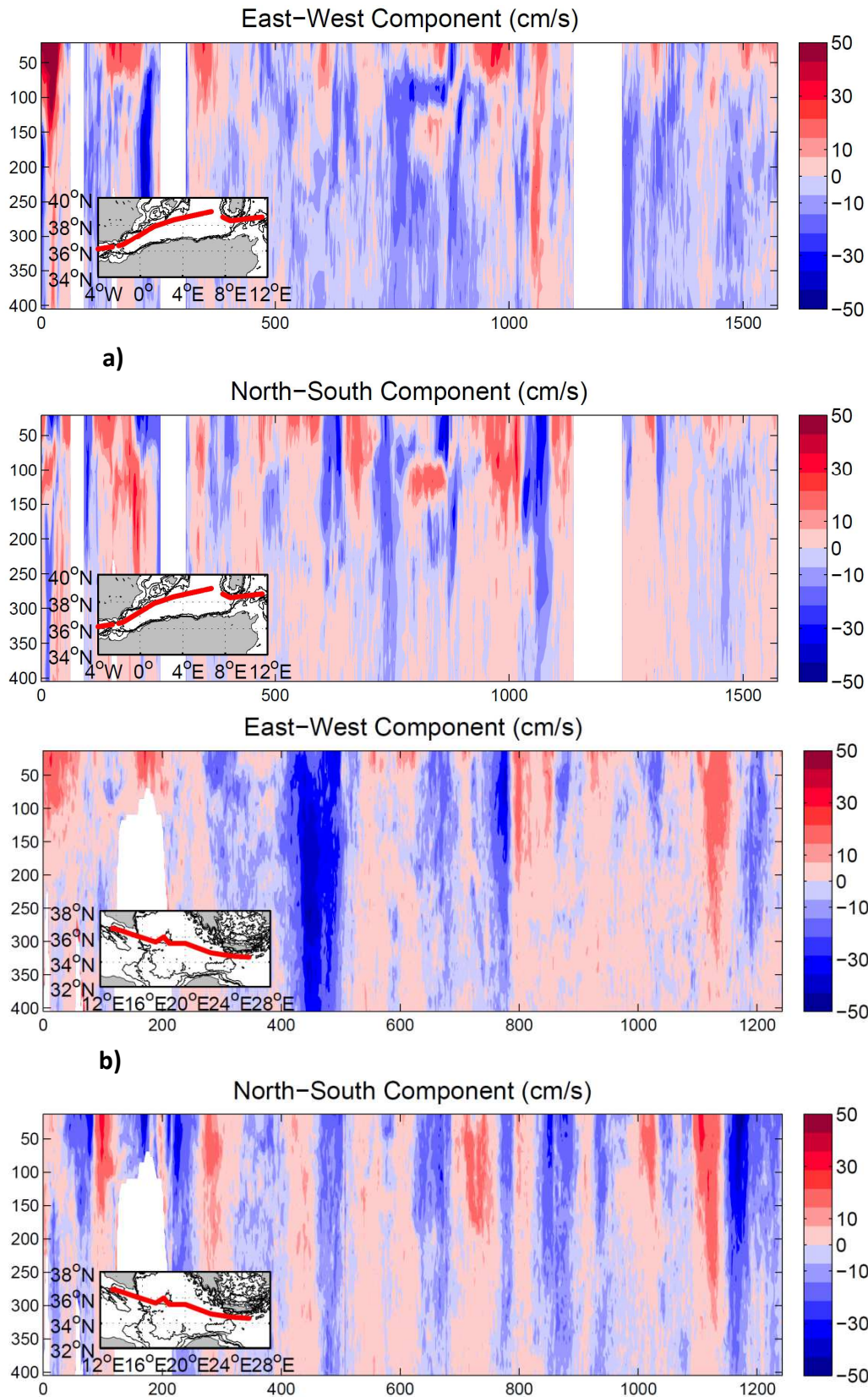


Figure 4: Velocity distribution of the upper 400m of the water column along a west-east section through a) the western Mediterranean and b) the eastern Mediterranean Sea. Data are recorded by a shipborne ADCP. Shown are the east-west and north-south velocity component,

respectively. Inner panels indicate the location of the ship track. White areas: no data are available. X-axes: east-west distance (km). Y-axes: depth (dbar).