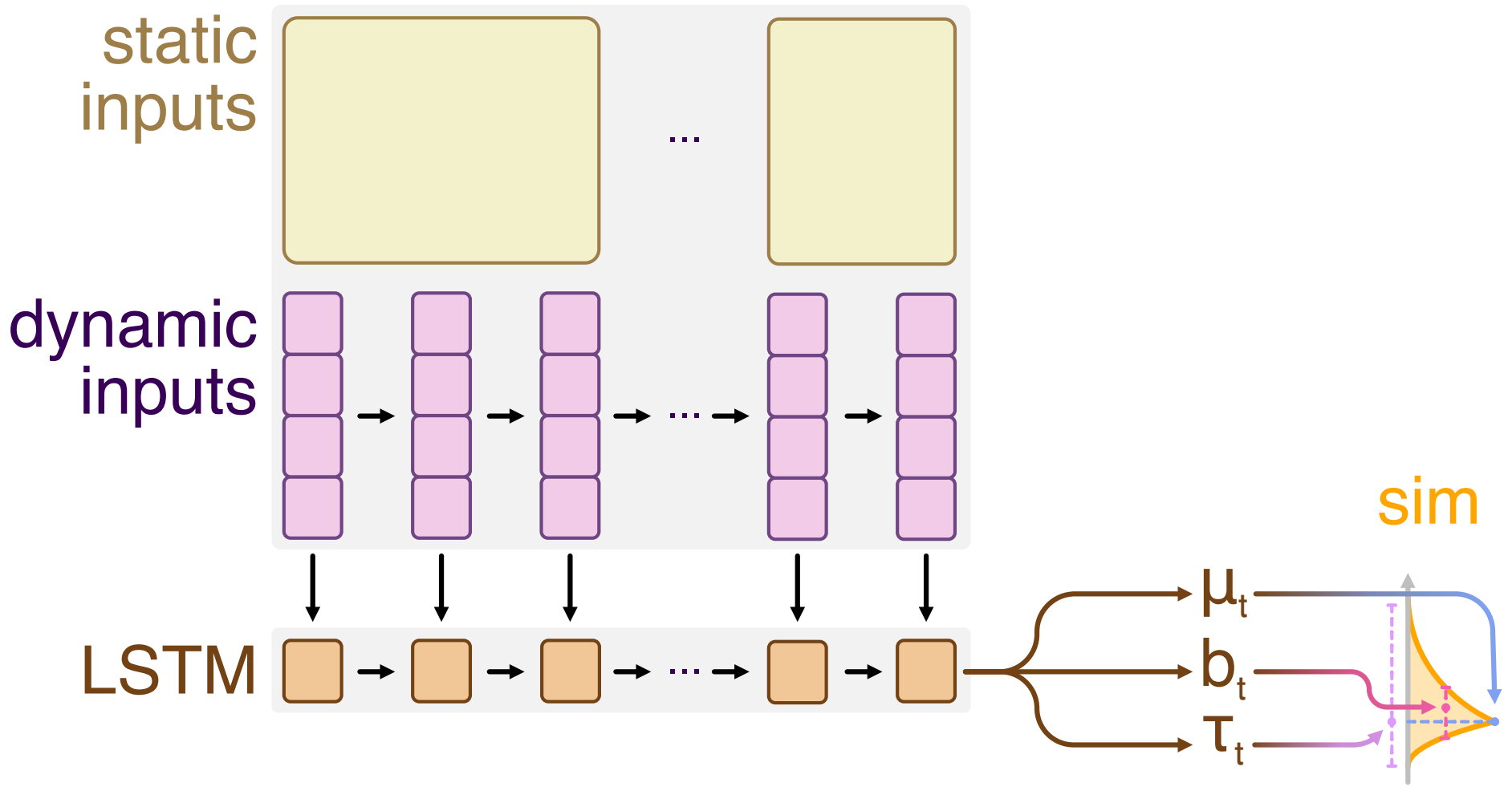
static inputs
dynamic inputs
LSTM
sim
μ_t
b_t
τ_t