



State-of-the-art hydrological datasets exhibit low water balance consistency globally

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Abstract. The proliferation and diversification of hydrological datasets have significantly advanced hydrological research. However, the coherence across these datasets remains poorly understood, hindering the comparability of findings derived from different data sources and variables. Here, we demonstrate that state-of-the-art hydrological datasets exhibit overall low consistency when evaluated through the lens of water balance – specifically, the relationship between variations in soil moisture and the difference between precipitation, evapotranspiration, and runoff. Our analysis reveals that satellite-based precipitation datasets generally show the highest consistency, while gauge-based datasets perform better in densely monitored regions of the Northern Hemisphere. For evapotranspiration, runoff, and soil moisture, reanalysis datasets demonstrate broader areas of higher consistency compared to gauge- or satellite-based products. Spatial patterns of consistency for most assessed datasets are strongly influenced by aridity and temperature, which affect measurement and modelling accuracy. Notably, dataset consistency has improved significantly in northern mid-latitudes over recent decades, likely reflecting advancements in observational technologies and the effects of climate warming. These findings underscore the importance of continued efforts to enhance dataset coherence and reliability for robust hydrological assessments.

1 Introduction

Over the past decades, the advancement of hydrological science and interconnected water-related research fields was accompanied by the emergence of datasets that depict the spatiotemporal changes of variables in the water cycle (Tang et al., 2024; Zarei and Destouni, 2024; Gebrechorkos et al., 2024; Douville et al., 2021; Oki and Kanae, 2006; Wang-Erlandsson et al., 2022; Mehta et al., 2024; Markonis et al., 2024). At the same time, understanding the consistency across the increasing suite of datasets is crucial not only for research on the responses and interactions within hydrology, but also for practitioners and management in terms

of regional water scarcity (Mekonnen and Hoekstra, 2016; Mehta et al., 2024), ecosystem function and water availability (Denissen et al., 2022), and the Earth system resilience (Wang-Erlandsson et al., 2022; Jaramillo and Destouni, 2015). Nevertheless, the water balance consistency among different suites remains largely unknown, while current studies mostly detail the dataset performance in terms of accuracies against observations and/or reference data, modeling behaviors, or water and energy balance closure (Tang et al., 2024; Gebrechorkos et al., 2024; Pan et al., 2020; Zarei and Destouni, 2024; Abolafia-Rosenzweig et al., 2021; Zhang et al., 2016).

Gridded hydrological datasets are derived based on different types of observations and methods, such as (i) spatial interpolation based on gauge/station/in-situ measurements (Harris et al., 2020), (ii) radiative transfer modelling based on satellite measurements (McCabe et al., 2017), (iii) land surface modelling with integrated data assimilation of hydrological and other variables (Muñoz-Sabater et al., 2021). Meanwhile, datasets also could be developed based on a combination of these approaches and observations (Beck et al., 2019; Yao et al., 2014), and machine-learning methods started to be implemented for parameterization (Ashouri et al., 2015). In this context, each of these approaches is characterized by inherent advantages and disadvantages. For example, in the case of precipitation (PR), gauge-based datasets are based on ground truth but at the same time they are influenced by errors related to wind and air flow anomalies around the gauges, by the spatial distribution of gauges which potentially misses some of the spatial heterogeneity of precipitation patterns, and by uncertainties in spatial interpolation (Lanza et al., 2022; Mishra and Coulibaly, 2009; La Barbera et al., 2002). By contrast, satellite-based PR datasets can capture spatial patterns more consistently (Tang et al., 2022a; Ashouri et al., 2015; Funk et al., 2015), but have difficulties in estimating PR amounts arriving at the surface. Further, reanalysis datasets based on land surface models show strengths in addressing temporal gaps caused by missing records and incomplete observation periods (Hersbach et al., 2020; Gelaro et al., 2017), but they suffer from inadequate or incomplete consideration of land surface processes that affect hydrological dynamics.

With the developing observation networks and data synthesis (Dorigo et al., 2021; Pastorello et al., 2020; Do et al., 2018), machine-learning algorithms present an alternative opportunity instead of interpolation to produce seamless observation-based datasets globally for evapotranspiration (ET), runoff (RO), and soil moisture (SM) datasets (Nelson et al., 2024; Ghiggi et al., 2019a; O and Orth, 2021a). Although Penman-Monteith and the simpler Priestley-Taylor models are still the key physical algorithms to estimate ET through remote sensing, the relevant products tend to leverage recent advances in satellite data and climate reanalysis (Fisher et al., 2008; Miralles et al., 2025; Zhang et al., 2019). Differently, satellite-based SM datasets follow different technical roadmaps, such as merging retrievals from various sensors (Gruber et al., 2019) or assimilating radiometer observations into land surface modeling (Reichle et al., 2019). In this way, the latter additionally provides an SM-constrained RO dataset (Reichle et al., 2019). At the same time, there are updated parametrizations for the land surface model in reanalysis to better describe the soil water balance and hydrological cycle (Hirschi et al., 2025; Muñoz-Sabater et al., 2021). It has been documented that those technical discrepancies could improve datasets' performance in terms of agreement with observations, while the influence of environ-

mental factors remains unclear (Markonis et al., 2024; Tang et al., 2024).

As a result of the different derivation approaches and the influence of environmental factors, disagreements between hydrological datasets remain (Hirschi et al., 2025; Markonis et al., 2024; Sun et al., 2018). These uncertainties limit the fundamental understanding of patterns, changes, and variabilities of water balance components (Markonis et al., 2024; Wang et al., 2024; Han et al., 2024; Douville et al., 2021; Greve et al., 2014; Zhang et al., 2024a; Denissen et al., 2022). The scarcity of observations across time, space, and hydrological variables hinders a comprehensive analysis of datasets' performance and reliability. However, observations are not our only source of knowledge about Nature, but known physical laws also provide information. This way, for example the water balance equation can be used to evaluate the consistency across combinations of hydrological datasets, a question which has remained largely unclear because assessments are usually specific to individual datasets (Zarei and Destouni, 2024; Abolafia-Rosenzweig et al., 2021). Such a combinatorial and factorial analysis requires (i) gridded datasets of all involved variables and (ii) independence between them in the sense that they are not derived with, e.g., the same model or approach which inherently enforces water balance closure. Thanks to the recent emergence of many hydrological datasets (Muñoz-Sabater et al., 2021; Ghiggi et al., 2019a; Miralles et al., 2025), these requirements are now met, opening a novel opportunity for hydrological dataset evaluation.

In this study, we evaluate the water balance consistency across a comprehensive set of PR, ET, RO and SM datasets. This encompasses gauge/station-based, satellite-based and reanalysis-based datasets, and offers 8294 combinations of water balance-variables from independently derived datasets (Fig. 1a). For each combination, we evaluate adjusted R^2 as the performance of linear regression of temporal changes in PR–ET–RO against changes in SM (ΔSM) to determine its water balance consistency since R^2 corresponds to the coefficient of determination. Then, combining an individual dataset with all possible combinations of datasets for the remaining water balance-variables we can assess its performance through the average of the R^2 scores obtained for all considered combinations. This way, the common limitations and strengths of different derivation-based datasets for each variable (i.e., PR, ET, RO, and SM) are distinguished across space and time. In addition to determining the performance of a large set of considered hydrological datasets across the globe, we also evaluate the resulting spatial patterns for possible causes in order to provide guidance for further dataset development.

2 Materials and Methods

2.1 Data and Independent combinations

We utilized 20 PR datasets, 11 ET datasets, 7 RO datasets, and 9 SM datasets to obtain respective monthly values across the global land area, where the PR, ET, and RO values are monthly amounts and Δ SM values are the soil moisture differences between the last day and the first day of each month. According to their sources, these datasets were summarized into three categories:

- Gauge/station-based products: CPC (Xie et al., 2010), CRU TS v4.06 (Harris et al., 2020), UDel v5.01 (Legates and Willmott, 1990), EM-EARTH (Tang et al., 2022a), GPCP v2022 (Schneider et al., 2022), and PREC/L (Chen et al., 2002) for PR, X-BASE (Nelson et al., 2024) for ET, GRUN (Ghiggi et al., 2019a) for RO, as well as SoMo.ml (O and Orth, 2021a) for Δ SM.
- Satellite-based products: CHIRPS v2.0 (Funk et al., 2015), CMAP (Xie and Arkin, 1997), CMORPH v1 (Xie et al., 2017), GPCP(M) v2.3 (Adler et al., 2018), GPCP(D) v1.3 (Huffman et al., 2001), GPM IMERG v07 (Huffman et al., 2023), PERSIANN-CDR (Ashouri et al., 2015), MSWEP v2.8 (Beck et al., 2019) for PR, MODIS (Running et al., 2021), PT-JPL (Fisher et al., 2008), PML-v2 (Zhang et al., 2019), GLASS (Yao et al., 2014) for ET, GLEAM v4.1 (Miralles et al., 2025) for both ET and Δ SM, SMAP L4 v7 (Reichle et al., 2019) for both RO and Δ SM, as well as ESA CCI v08.1 (Gruber et al., 2019) for Δ SM.
- Reanalysis products: 20CR v3 (Slivinski et al., 2021), JRA-55 (Japan Meteorological Agency, 2013), ERA5 (Hersbach et al., 2020), NCEP-NCAR R1 (Kistler et al., 2001), and NCEP-DOE R2 (Kanamitsu et al., 2002) for PR, MERRA-2 (Gelaro et al., 2017) for PR, ET, RO, and Δ SM, as well as GLDAS-2.0 (Rodell et al., 2004), GLDAS-2.1 (Rodell et al., 2004), GLDAS-2.2 (Li et al., 2019), ERA5-land (Muñoz-Sabater et al., 2021) for ET, RO, and Δ SM.

All datasets were either provided at or resampled to 0.25° resolution by bilinear interpolation, and their temporal coverage spans January 2000 to December 2022. Various components of GLDAS (i.e., –2.0, –2.1, and –2.2) were used here because they are based on different forcings, models, and data assimilation strategies (see more details in Tables S1–S4 in the Supplement). The Δ SM from different datasets were the depth-weighted averages of their available soil layers (Li et al., 2023a). SoMo.ml Δ SM covers 0–50 cm related to the commonly observed depths in in-situ measurements; ESA CCI Δ SM represents the top surface layer (of < 5 cm thickness) captured by satellite observations; GLEAM Δ SM, SMAP Δ SM, and MERRA-2 Δ SM represent a root zone layer of 0–100 cm; and GLDAS-2.0/2.1/2.2 and ERA5-land

Δ SM cover deeper depths (> 100 cm). Despite differences in depth, the Δ SM was assumed to capture the variability of PR–ET–RO in the water balance, on the basis that its variability accounts for a large portion of the variability in terrestrial water storage (Freedman et al., 2014). In this context, a suite of PR, ET, RO, and SM datasets forms a considered combination, such as

PR_{CPC}, ET_{X-BASE}, RO_{GRUN}, and Δ SM_{SoMo.ml}

Among the considered datasets as listed above, 13 860 combinations (that is $20 \times 11 \times 7 \times 9$ for PR, ET, RO, and SM) were initially available. However, considering the temporal availability and the dependence between dataset sources of different water balance components, parts of combinations were excluded by three rules:

1. The combinations with short overlapping time periods cannot be considered. In particular,
 - SMAP L4 products have only one year overlap (i.e., 2015) with 20CR v3, so the combinations with PR from 20CR v3 and RO and/or Δ SM from SMAP were not considered;
 - The combinations with GRUN RO (covering until 2014) and RO and/or Δ SM from SMAP (starting from 2015) were not available;
 - The combinations with water balance components from GLDAS-2.0 (also covering until 2014) and SMAP were not available;
 - The combinations with SMAP L4 products and either PT-JPL or UDel v5.01 (covering until 2017) were not considered.
2. The combinations with water balance components from the same dataset source were not considered, which include the combinations with GLEAM ET and Δ SM, the combinations with SMAP ET and Δ SM, and the combinations with any two or more variables from MERRA-2/GLDAS/ERA5-land. In this perspective, since the difference between ERA5 and ERA5-land was mainly because of the non-linear dynamical downscaling technique (Muñoz-Sabater et al., 2021), the combinations with ERA5 PR and ERA5-land ET/RO/ Δ SM were also not considered.
3. If a dataset was driven by another dataset, the water balance components from these two datasets were also not considered in combination. In particular:
 - GRUN was driven by GSWP3, a dynamically downscaled and bias-corrected version of the 20CR, so the combinations with 20CR PR and GRUN RO were excluded;
 - SoMo.ml was driven by meteorological data from ERA5, so the combinations with ERA5 PR and SoMo.ml Δ SM were excluded;

- PML-v2 used the GLDAS-2.1 meteorological forcings, which includes GPCP(D) v1.3, so the combinations with GPCP(D) PR and PML ET, as well as those with GPCP(D) PR and GLDAS-2.1 ET, were excluded;
- GLEAM v4.1 used PR from MSWEP v2.8 as one of the inputs, so the combinations with MSWEP PR and GLEAM ET/ Δ SM were excluded;
- The input PR for SMAP L4 was from CPC and GPCP(M), and therefore, the combinations with CPC/GPCP(M) PR and SMAP RO/ Δ SM were excluded;
- Since the land surface component of MERRA-2 bias adjusted PR by using CPC, CMAP, and GPCP(M), the combinations with CPC/CMAP/GPCP(M) PR and MERRA-2 ET/RO/ Δ SM were excluded;
- The GLDAS-2.2 was forced with the meteorological analysis fields from the European Centre for Medium-Range Weather Forecasts (ECMWF) Integrated Forecasting System (IFS)(Rui et al., 2022), which includes ERA5, so the combinations with ERA5 PR and GLDAS-2.2 ET/RO/ Δ SM were excluded.

At the same time, there are different levels of (in)dependence such that the decision on whether or not to consider certain datasets as independent is not always straightforward. The following cases are not fully independent but are considered sufficiently independent for the context of our study:

- The datasets driven by similar forcings, such as SoMo.ml Δ SM and ERA5-land ET and RO, are considered to form independent combinations;
- MSWEP generated based on a group of PR datasets including ERA5 is considered sufficiently independent from the ERA5-land ET, RO, and Δ SM;
- ESA CCI Δ SM which was assimilated into GLEAM Δ SM is considered independent from GLEAM ET.

After applying these exclusion rules, there remained 8294 independent combinations.

2.2 Performance assessment in terms of water balance consistency

Under our water balance assumption, we build a linear regression model in each grid cell of each considered combination of hydrological datasets, considering all available months, and assess its adjusted R^2 score:

$$(\mathbf{PR} - \mathbf{ET} - \mathbf{RO})_s = k \cdot \Delta\mathbf{SM}_s \quad (1)$$

where s is the spatial index (grid cell) and k is the proportionality factor. Note that this is not supposed to equal to 1 in our context because of the differences in units between the left side of the equation (mm for **PR**, **ET**, and **RO**) and the right side ($\text{m}^3 \text{m}^{-3}$ for $\Delta\mathbf{SM}$). The linear regression model lets us avoid the conversion of $\Delta\mathbf{SM}$ unit from $\text{m}^3 \text{m}^{-3}$ to mm, reducing uncertainties from considering soil moisture datasets with different soil depths. **PR**, **ET**, **RO**, and $\Delta\mathbf{SM}$ are $M \times 1$ vectors, where M is the number of months. We removed the models with M smaller than 36 to ensure enough input data. The adjusted R^2 score for each model was used to represent the ability of each combination of datasets to describe the variability in water balance at each grid point. Since the water balance is a physical law that should be obeyed according to mass balance, the ability of describing variability here is attributed to the performance of each combination for each grid cell.

Different independent combinations have different temporal coverages (i.e., different M), so we analyzed whether the varying M would affect the accuracy results. For this purpose, a fixed study period from February 2003 to December 2014 (where M is fixed to be 143) was selected. We calculated the water balance consistency based on the adjusted R^2 score, for all available independent combinations with this fixed M . We compared the R^2 values between varying M and fixed M for each considered combination by calculating their linearly regressed R^2 scores and slopes. Most of the regressed R^2 and slopes are distributed between 0.9 and 1 (Fig. S1 in the Supplement). This indicates that the considered time period has no significant influence on the resulting water balance consistency. Therefore, we assessed the performance in terms of water balance consistency across different time periods for different combinations of datasets, depending on their temporal coverage and overlap (ensuring a minimum overlap of 3 years). This allows us to involve a larger number of combinations compared to a fixed M , while we also provided the results calculated based on the combinations used in the following temporal changes analysis, which have only large and less varying M (Fig. S2).

In the next step, the overall performance in terms of water balance consistency for each individual dataset in each grid cell was inferred from the averaged R^2 across all combinations of datasets containing the respective dataset. In other words, the performance of each individual dataset is assessed through the R^2 scores in water balance for describing variability when combining it with all suitable combinations of state-of-the-art datasets for the other water balance components.

Since the performance inferred from water balance consistency is based on the ability to describe variability in water balance, different temporal resolutions directly affected magnitudes and frequencies of the variability (Maurer and Hidalgo, 2008). Accordingly, we repeated the above calculations for the datasets available at daily and yearly resolutions, where 3647 and 8294 (the same as monthly) independent

combinations were considered, respectively (Sects. S1–S2 in the Supplement). In addition, unconsidered water variables, like glacier, snow, and surface water storage, might introduce bias into our water balance assumption, leading to a nonlinear response of ΔSM to PR–ET–RO. We thereby used terrestrial water storage from GRACE instead of SM in Eq. (1) to evaluate the performance of the PR, ET, and RO datasets, based on their combinations with GRACE data (Sect. S3). In this case, the number of combinations is decreased by one order of magnitude (933 remained), but ranking results are similar to using ΔSM (Fig. S3).

2.3 Potential influence factors on dataset performance

To further understand how the global spatial patterns of each dataset's performance (Figs. S4–S7) were influenced, we considered a set of potential influence factors of the spatial patterns: soil texture, aridity index, tree cover fraction, area equipped for irrigation, artificial impervious area, monthly mean temperature, observation density, and potential influence of lateral flow. For the first six factors, we calculated them for each independent combination because the factors are changing from dataset to dataset, and then obtained the averages for each dataset through all the considered combinations that include this dataset. In detail,

- Soil clay content was used to indicate soil texture influence, since small particles and large surface areas can create small pore sizes to hold water tightly, affecting SM conditions and through local water cycles to influence other water balance components (Cleophas et al., 2022). The clay contents were provided by the Harmonized World Soil Database version 2.0 (HWSD v2.0) (Nachtergaele et al., 2023) for seven soil layers, and the layers used for each independent combination were selected according to the depth of SM dataset in that combination and depth-weighted for a whole layer.
- Regarding the aridity index, we used the multi-year averages of ET and divided them by those of PR to obtain an aridity index map for each independent combination (O and Orth, 2021a; Li et al., 2022).
- The tree cover fraction from NASA Vegetation Continuous Fields Version 1 data product (Hansen and Song, 2018).
- Area equipped for irrigation from Mehta et al. (2024) was averaged among the available periods for each independent combination.
- Global artificial impervious area from Gong et al. (2020) was also averaged among the available periods for each independent combination.
- The monthly mean 2 m air temperature was averaged based on the daily average temperature from ERA5 and

calculated for each month in each considered combination.

- Unlike the upper factors, the observation density is different from variable to variable, not from combination to combination. We counted the number of stations/sites for different observation networks of the water variables: CPC global stations for PR, eddy covariance sites in FLUXNET2015 (Pastorello et al., 2020) and AmeriFlux for ET, streamflow stations in the Global Streamflow Indices and Metadata Archive (GSIM) (Do et al., 2018) for RO, and sites of in-situ measurement in the International Soil Moisture Network (ISMN) (Dorigo et al., 2021) and the National Center for Monitoring and Early Warning of Natural Disasters of Brazil (CE-MADEN) (Zeri et al., 2020) for SM. Here, we referred to Ruiz-Vásquez et al. (2022) to sum up the stations/sites located in each grid cell and its eight neighboring grid cells (Fig. S8).
- The global impact of lateral flow has been evaluated by Miguez-Macho and Fan (2025), where the differences of (PR + lateral flow)/PET and PR/PET (with PET as the potential evapotranspiration) represent the influence of subsidies by rivers and groundwater on regional water cycles (Fig. S9).

An explainable machine learning method was applied for quantitative attribution (Li et al., 2022) in order to determine the relative roles of the considered factors for the resulting global spatial patterns of each dataset's performance. For each dataset, we trained one random forest model, where the global performance map was the target variable, the eight maps of the above-described factors were the predictors, and a common hyperparameter setting (numbers of estimators: 100; maximum features: 30%) was used (Li et al., 2022). Before training, the correlation matrix of the eight predictors was calculated for each random forest model to assess potential collinearity. Since the correlations are within a range of -0.2 – 0.5 (Figs. S10–S13 for PR, ET, RO, and SM datasets, respectively), collinearity is not a major issue affecting our model predictions (Dormann et al., 2012). The performance of random forest models was determined by the cross-validation out-of-bag R^2 , which mainly distributes around 0.8 for all the trained models and therefore indicates the usefulness of these models for the following attribution (Fig. S14). Then, SHapley Additive exPlanations (SHAP) feature importance was calculated to quantify the marginal contributions of predictors to each dataset's overall accuracy (Li et al., 2023a), and we identified the relative importance among predictors by ranking their global averaged absolute SHAP values (Li et al., 2023b).

2.4 Temporal changes in dataset performance

Since the temporal coverages of independent combinations are inconsistent, the independent combinations with less than two-thirds of available monthly data for either the first period of January 2000 to December 2010 or the second period of January 2011 to December 2022 were removed in the temporal changes analysis. The remaining independent combinations ($n = 2589$) were used to separately calculate water balance consistency for the first and second periods. The overall performance in terms of water balance consistency was calculated for the first or second period of each dataset by averaging the respective period's adjusted R^2 scores across all independent combinations of the datasets considered in this study. In this way, the temporal change in performance for each dataset was obtained by subtracting the overall performance of the first period from that of the second period.

To account for the uncertainties of these temporal changes, bootstrap confidence intervals (Kulesa et al., 2015) were calculated for the performance in both the first and the second periods of the 2589 independent combinations. For each of these independent combinations, whose number of available monthly data for the first and the second periods is denoted as M_1 and M_2 , respectively, we obtained 100 random samples for the first/second period with replacement. The amount of data in one sample is M_1 for the first period and M_2 for the second period, and 100 samples indicate that 100 adjusted R^2 scores were calculated for the first/second period based on Eq. (1). Accordingly, a bootstrap distribution for the first/second period with 100 samples was obtained, and its confidence interval was evaluated by the 5th and 95th percentiles. When the 5th percentile of the second period is higher than the 95th percentile of the first period, or the 95th percentile of the second period is lower than the 5th percentile of the first period, the change in performance of this independent combination from the first to the second period is significant. Finally, grids in the map of temporal changes in performance for each dataset were masked by n/a (i.e., not available) if they did not have over 50 % independent combinations showing significant changes.

3 Results

3.1 Water balance consistency of considered datasets

Figure 1b–e summarizes the performance of considered datasets in terms of their water balance consistency, based on monthly calculations (see Methods). Colors distinguish gauge-based, satellite-based and reanalysis datasets. Overall, the R^2 scores are fairly low, indicating prevailing inconsistencies across considered datasets in terms of the water balance. From the combinations with top ten performance, it is likely that the PR from PERSIANN-CDR, ET from PT-JPL, RO from GRUN, and SM from GLDAS-2.1 would contribute to high water balance consistency (Fig. S15).

For PR datasets, the overall performance of satellite-based datasets is generally higher than gauge-based and reanalysis datasets, where the CHIPRS v2.0 and PERSIANN-CDR show the highest global medians (Fig. 1b). This is related to their limited spatial coverage omitting high-latitude regions with typically low water balance consistency (Fig. S4), while for 50°S – 50°N , PERSIANN-CDR, GPM IMERG v07, and MSWEP v2.8 show the highest medians (Fig. 1b). Besides, GPM IMERG v07 and MSWEP v2.8 exhibit the largest areas with the best performance across datasets (Fig. S16). Figure 2 maps the types of datasets with the highest water balance consistency for each considered variable. It shows that given the comparatively good performance of GPM IMERG v07 and MSWEP v2.8, satellite-based precipitation dataset types perform best across most of the globe, particularly in the tropics and subtropics (Figs. S16 and 2a). Gauge-based PR datasets perform best in high-latitude regions which in the Northern Hemisphere are characterized by abundant in-situ observations (Fig. S8).

ET and RO datasets show similar global patterns and medians of overall performance among the different dataset types (Figs. S5–S6 and 1c, d). However, for the spatial patterns, PT-JPL and GLDAS-2.2 have distinctly larger areas with the best performance compared to other ET datasets (Fig. S16b), leading to comparable best-performance areas between satellite-based and reanalysis ET datasets (Fig. 2b). Similarly, gauge-based and reanalysis RO datasets show the largest areas with the best performance (Fig. 2c), where GRUN and ERA5-land datasets are the respective main contributors (Fig. S16c).

Among SM datasets, SoMo.ml and ESA CCI v08.1 have the lowest global medians of overall performance. This is because they only represent the surface layers instead of the entire soil column (Fig. 1e). Meanwhile, the SM datasets with simulations of deep soil layers generally performed better in most global regions, such as the reanalysis and GLDAS-2 products (Figs. 2d and S16d).

Additionally, we calculated our analysis at daily and annual time scales. Results indicate substantially less water balance consistency with the lowest R^2 scores at the annual scale (Fig. 1b–e). However, different temporal resolutions did not alter the relative ranking patterns among the datasets (Fig. 1b–d), except for SM whose memory is likely to be more sensitive to the varying resolutions (Fig. 1e).

3.2 Potential reasons influencing water balance consistency

Next, we aim to diagnose possible reasons for regional discrepancies of dataset performance in terms of water balance consistency. For this purpose, we consider a large set of variables that may affect the water balance consistency of a given dataset, including soil and vegetation characteristics, climate, and gauge density (Methods). By applying an explainable machine learning method (i.e., SHAP), temper-

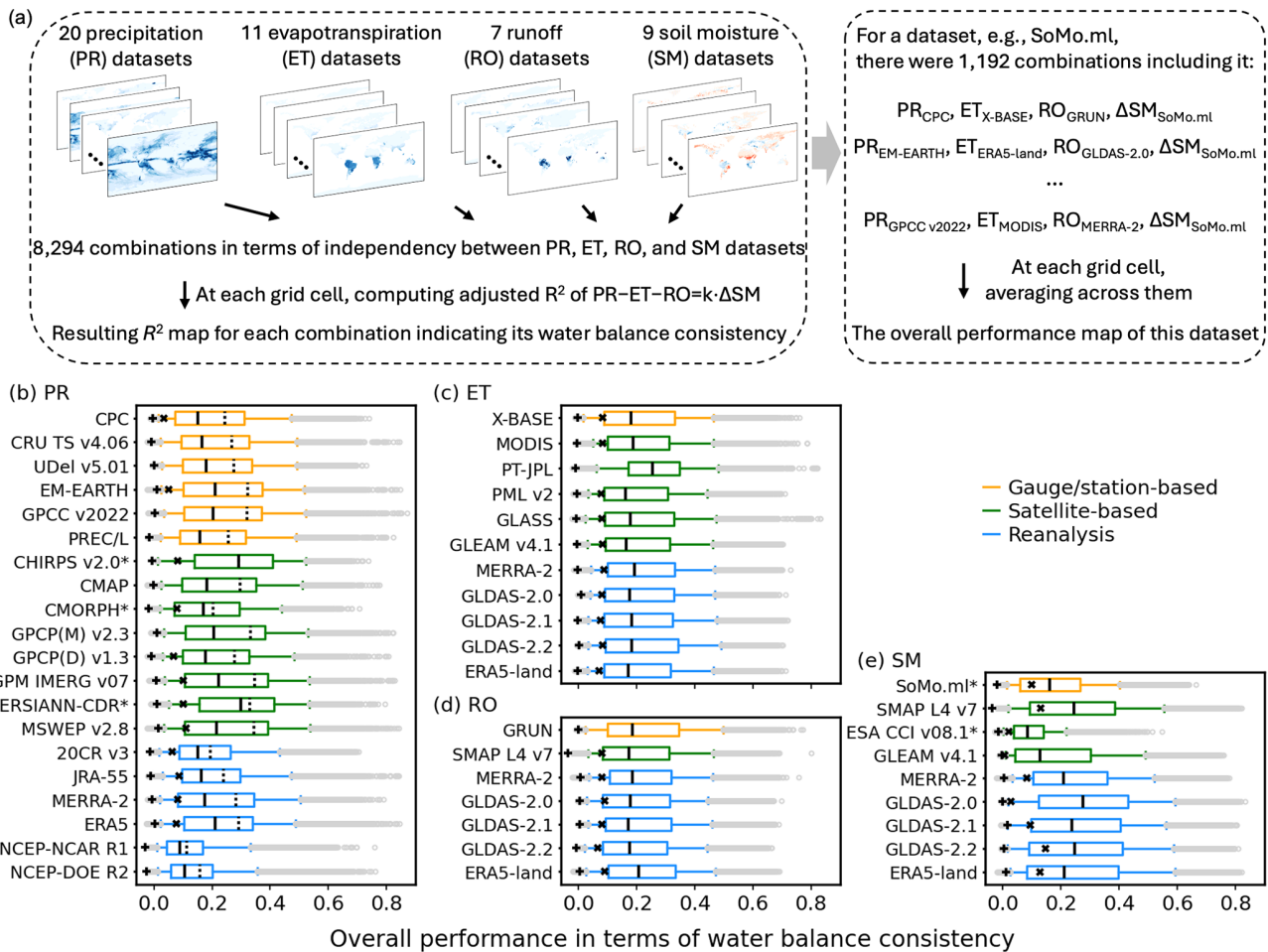


Figure 1. Illustration of water-balance approach and calculated performance of considered datasets. (a) Performance is determined based on R^2 scores measuring consistency of each dataset when combined with all independent datasets in terms of the water balance (Methods). (b–e) The boxplots summarize the performance of considered datasets. Colors indicate the type of each dataset. Each box shows the median value, as well as the 5th, 25th, 75th, and 95th percentiles of the global pattern of water balance consistency derived from monthly data. Median results for performing the analysis with daily and annual data are indicated through crosses (\times) and pluses ($+$), respectively (Sects. S1–S2). Asterisks (*) following the name of PR dataset indicate its limited spatial coverage omitting high-latitude regions with typically low performance, and dashed line in each box indicates median of only 50° S–50° N. * of SM dataset indicates that the dataset does not consider the entire soil column.

ature and aridity (i.e., ET/PR) were diagnosed as the key factors influencing the spatial performance patterns of the datasets (Figs. 3 and S17–S20). At the same time, factors like irrigation, urbanization, and lateral flow play relatively minor roles (Figs. S17–S20). For the key factors, our results demonstrate that the performance of PR datasets is higher in the sub-humid and sub-arid regions (where the aridity index is 0.6–1.0) with monthly mean temperatures between 10 and 15 °C (Figs. 3a and S21). The results for ET, RO, and SM datasets are largely similar to those of PR datasets (Figs. 3b–d and S22–S24). These influence patterns were summarized according to medians across dataset performance, while using maximum does not alter the results (Fig. S25).

3.3 Temporal changes in water balance consistency of dataset

We furthermore assess changes in the diagnosed dataset performance inferred from water balance consistency over time. This is done by splitting our study period and repeating the analysis for the sub-periods 2000–2010 and 2011–2022, and includes an assessment of significance (Methods). For the PR datasets, the majority of global grid cells show no temporal change in water balance consistency, and among the grid cells with temporal changes, we found mostly increases (Fig. 4a). These increasing changes were mainly observed in middle- and high-latitude regions of the Northern Hemisphere, while the PR dataset from ERA5 shows the highest median level of performance improvement (Fig. S26). At the

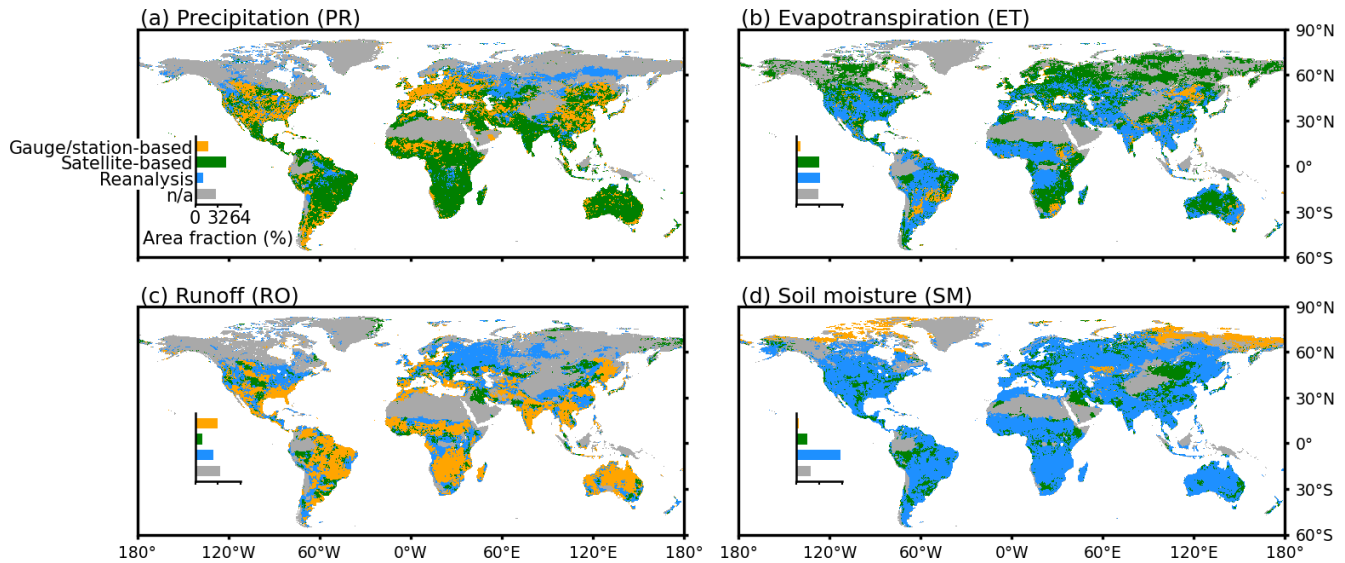


Figure 2. Types of best-performing datasets across hydrological variables. Colors indicate type of dataset with the highest water balance consistency. Gray color indicates that multiple datasets show similar water balance consistency (with R^2 scores varying by less than 5 %) or low water balance consistency (with all R^2 scores below 0.2).

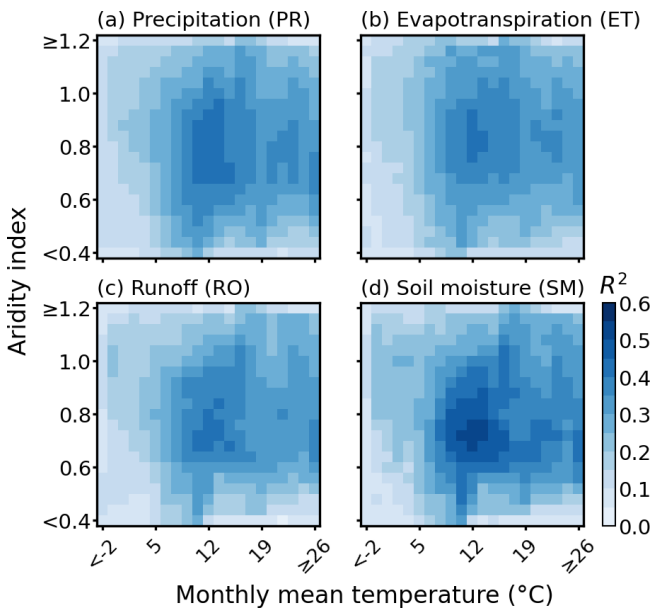


Figure 3. Influence of temperature and aridity on water balance consistency of datasets. Consistency in water balance is quantified by R^2 scores (Fig. 1), and median R^2 scores across PR/ET/RO/SM datasets for each climate class are shown (Figs. S21–S24).

same time, we find similar spatial patterns of changes in water balance consistency for ET, RO, and SM datasets, with most grid cells showing no change (Fig. 4b–d). Among the grid cells with significant changes, performance in terms of water balance consistency increases prevail and are mostly located in high-latitude regions and in regions with scarce

observations in the Northern Hemisphere (Figs. 4b–d, S8 and S27–S29).

4 Data availability

All data needed to evaluate the conclusions in the paper are present in the paper and/or the online repository. Additionally, their access links are provided in the following. CPC is available at <https://www.psl.noaa.gov/data/gridded/data.cpc.globalprecip.html> (last access: June 2024; Xie et al., 2010); CRU TS v4.06 is available at https://crudata.uea.ac.uk/cru/data/hrg/cru_ts_4.06/ (last access: July 2024; Harris et al., 2020); UDel v5.01 is available at <https://climate.geog.udel.edu/> (last access: July 2024; Legates and Willmott, 1990); EM-EARTH is available at <https://doi.org/10.20383/102.0547> (last access: July 2024; Tang et al., 2022a, b); GPCC v2022 is available at https://opendata.dwd.de/climate_environment/GPCC/html/fulldata-monthly_v2022_doi_download.html (last access: July 2024; Schneider et al., 2022); PREC/L is available at <https://psl.noaa.gov/data/gridded/data.precl.html> (last access: July 2024; Chen et al., 2002); CHIRPS v2.0 is available at <https://www.chc.ucsb.edu/data/chirps> (last access: July 2024; Funk et al., 2015); CMAP is available at <https://psl.noaa.gov/data/gridded/data.cmap.html> (last access: July 2024; Xie and Arkin, 1997); CMORPH v1 is available at <https://doi.org/10.25921/w9va-q159> (last access: July 2024; Xie et al., 2017); GPCP(M) v2.3 is available at <https://psl.noaa.gov/data/gridded/data.gpcp.html> (last access: July 2024; Adler et al., 2018); GPCP(D) v1.3 is available at <https://doi.org/10.5065/ZGJD-9B02> (last access: April 2024; Adler et al., 2020; Huff-

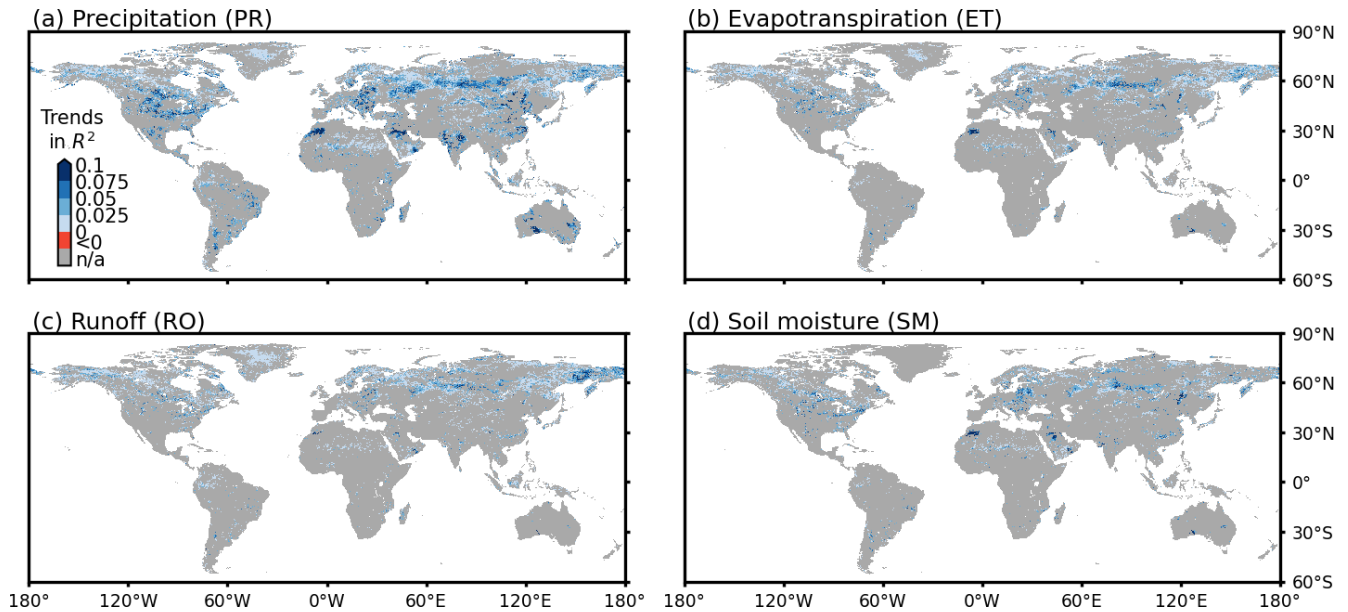


Figure 4. Temporal changes in water balance consistency of PR, ET, RO, and SM datasets from 2000–2010 to 2011–2022. Based on the changes in R^2 scores for each dataset (Figs. S26–S29), median values are shown in each grid cell where at least half the considered datasets showed significant changes (Methods), representing common temporally changing patterns.

man et al., 2001); GPM IMERG v07 is available at <https://doi.org/10.5067/GPM/IMERGDF/DAY/07> (last access: October 2024; Huffman et al., 2023); PERSIANN-CDR is available at <https://www.ncei.noaa.gov/products/climate-data-records/precipitation-persiann> (last access: July 2024; Ashouri et al., 2015); MSWEP v2.8 is available at <https://www.gloh2o.org/mswep/> (last access: April 2024; Beck et al., 2019); 20CR v3 is available at https://psl.noaa.gov/data/gridded/data.20thC_ReanV3.html (last access: July 2024; Slivinski et al., 2021); JRA-55 is available at <https://doi.org/10.5065/D6HH6H41> (last access: July 2024; Japan Meteorological Agency, 2013); ERA5 is available at <https://doi.org/10.24381/cds.adbb2d47> (last access: April 2024; Hersbach et al., 2020, 2023); NCEP-NCAR R1 is available at <https://psl.noaa.gov/data/gridded/data.ncep.reanalysis.html> (last access: October 2024; Kistler et al., 2001); NCEP-DOE R2 is available at <https://psl.noaa.gov/data/gridded/data.ncep.reanalysis2.html> (last access: October 2024; Kanamitsu et al., 2002); MERRA-2 is available at https://gmao.gsfc.nasa.gov/reanalysis/MERRA-2/data_access/ (last access: July 2024; Gelaro et al., 2017); X-BASE is available at <https://doi.org/10.18160/5NZG-JMJE> (last access: March 2024; Nelson et al., 2023, 2024); MODIS is available at <https://doi.org/10.5067/MODIS/MOD16A2GF.061> (last access: March 2024; Running et al., 2021); PT-JPL is available at <http://josh.yosh.org/> (last access: July 2024; Fisher et al., 2008); PML-v2 is available at <https://doi.org/10.5281/zenodo.10647618> (last access: July 2024; Zhang et al., 2024b); GLASS is avail-

able at <http://www.glass.umd.edu> (last access: July 2024; Yao et al., 2014); GLEAM v4.1 is available at <https://www.gleam.eu/> (last access: August 2024; Miralles et al., 2025); GLDAS-2.0/2.1/2.2 are available at <https://disc.gsfc.nasa.gov/datasets?keywords=GLDAS> (last access: July 2024; Rodell et al., 2004; Li et al., 2019); ERA5-land is available at <https://doi.org/10.24381/cds.e2161bac> (last access: August 2024; Muñoz Sabater, 2019; Muñoz-Sabater et al., 2021); GRUN is available at <https://doi.org/10.6084/m9.figshare.9228176> (last access: April 2024; Ghiggi et al., 2019a, b); SMAP L4 v7 is available at <https://doi.org/10.5067/EVKPQZ4AFC4D> (last access: May 2024; Reichle et al., 2019); SoMo.ml is available at <https://doi.org/10.6084/m9.figshare.c.5142185.v1> (last access: November 2023; O and Orth, 2021b); ESA CCI v08.1 is available at <https://climate.esa.int/en/projects/soil-moisture/> (last access: June 2024; Gruber et al., 2019).

5 Code availability

The core codes for calculating the water balance consistency of each combination and each dataset, as well as assessing the potential influence based on explainable machine learning and uncertainties of the temporal changes based on bootstrap confidence intervals, are available at <https://doi.org/10.5281/zenodo.19468433> (Huang, 2026).

6 Discussion

The spatial performance patterns derived from our water balance consistency approach reveal high similarity among PR datasets (Fig. S4), consistent with findings from recent studies on PR dataset agreement (Markonis et al., 2024; Dosio et al., 2021). For the medians of 50° S–50° N, several PR datasets like PERSIANN-CDR, GPM IMERG v07, and MSWEP v2.8 are also comparable, which might be related to their close genealogical relationships (Markonis et al., 2024; Vargas Godoy et al., 2025). Beyond these similarities, our grid cell-level comparisons suggest that satellite-based PR datasets outperform others in large regions of southern America, Africa, south and Southeast Asia, and inner Australia, while gauge-based PR datasets excel in many grid cells across the United States, Europe, and East Asia (Fig. 2). This suggests that the satellite-based PR datasets are superior in regions with sparse or no gauging stations (Fig. S8), compared to gauge-based and reanalysis datasets. However, all PR datasets exhibit higher water balance consistency in moderately humid or dry regions, with long-term mean temperature also influencing the performance (Fig. 3 and Fig. S21). Lower consistency of gauge-based datasets in humid and dry regions may stem from challenges in mapping spatial variability of extreme rainfall (Mishra and Coulibaly, 2009) and accurately recording light precipitation events (Lanza et al., 2022), as consistency is based on seasonal variabilities in water balance. Additionally, PR datasets show lower consistency in cold regions because of difficulties in measuring solid precipitation (La Barbera et al., 2002). Similarly, satellite-derived precipitation is relatively insensitive to light rainfall (Laviola et al., 2013), struggles with extreme rainfall estimates (likely due to retrieval algorithms and infrequent temporal sampling of polar orbits) (Barlow et al., 2019), and often fails to detect snowfall or perform well over snow- and ice-covered surfaces (Alijanian et al., 2017). In contrast, reanalysis datasets perform better in cold regions, benefiting from assimilated meteorological observations and atmospheric states (Barlow et al., 2019; Dosio et al., 2021; Sun et al., 2018).

The ET, RO, and SM datasets generally show global spatial performance patterns similar to those of PR datasets (Figs. S4–S7). This is partly because uncertainties in PR datasets propagate through the water cycle (Fallah et al., 2020), affecting the water of the water balances of ET, RO, and SM datasets. Limitations in representing snowpack and permafrost processes, along with difficulties in satellite retrievals over snow- and ice-covered high-latitude regions, also contribute to this issue (Hirschi et al., 2025; Muñoz-Sabater et al., 2021). Nevertheless, our approach identifies distinct relative performances across hydrological variables and dataset types (Figs. 2 and S16), as it considers independent combinations of datasets. For ET, the satellite-based PT-JPL dataset performs comparatively well, likely due to its advanced consideration of plant physiological limitations

and water stress. The reanalysis dataset GLDAS-2.2 also performs comparatively well, probably due to its assimilation of terrestrial water storage (Table S2 and Fig. S16). For RO, the machine-learning model-driven GRUN, constrained by PR and temperature in large basins, and ERA5-land dataset, perform best in most regions (Table S3 and Fig. S16). For SM, reanalysis datasets perform best, likely because they are constrained by physical laws and consider deeper soil moisture variability (Table S4 and Fig. S16). In contrast, low penetration depths ($\sim 2\text{--}5\text{ cm}$) of microwave sensors limit the ability of ESA CCI v08.1 to capture deeper-layer SM variations (Hirschi et al., 2025). Overall, our results highlight the importance of physical constraints and of data assimilation in enhancing water balance consistency of hydrological variables (Pan et al., 2020; Tang et al., 2024; Yang et al., 2023; Ruiz-Vásquez et al., 2023).

Dataset performance varied significantly across time scales, with the highest correspondence at the monthly scale, where seasonal variability is well-captured and synoptic weather variability is mitigated. This explains the markedly lower water balance consistency observed at the annual scale for all datasets, where seasonal signals are strongly smoothed. At a daily time scale, the variability of the involved variables is high, including more extreme values and high noise, and apparently under-constrained by available observations (Maurer and Hidalgo, 2008; Fisher et al., 2008). Furthermore, we find widespread increases in water balance consistency across hydrological variables during our study period in mid-to-high latitude regions of the Northern Hemisphere (Fig. 4). These regions have experienced reduced snow-cover durations (Bormann et al., 2018) and extents (Mudryk et al., 2020), as well as less snowfall (O’Gorman, 2014), which has weakened RO seasonality (Wang et al., 2024) and enhanced the influence of PR variability on RO seasonality (Han et al., 2024). Given the influence patterns in Fig. 3, higher temperatures and reduced solid precipitation likely enhance PR dataset performance. Also, the absence of strong increases in extreme precipitation events in these regions (Asadieh and Krakauer, 2015) may contribute to improved consistency. Previous studies have shown that models incorporating updated vegetation information, such as leaf area index (LAI) seasonality, perform better in these regions (Ruiz-Vásquez et al., 2023; Nogueira et al., 2021), aligning with our observed improvements over time (Fig. 4). This indicates the role of vegetation characteristics in accurately representing the coupling between ET and SM for dataset performance, as inferred from our approach.

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gregated the datasets used in this study, did the analysis, and prepared the original paper. H.H., J.L., A.C., M.R.V., and R.O. contributed to interpreting the results and discussion and improving the paper.

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