Earth Syst. Sci. Data, 17, 181–203, 2025
https://doi.org/10.5194/essd-17-181-2025

Open Access Earth System Science Data

A new multi-grid bathymetric dataset of the Gulf of Naples (Italy) from complementary multi-beam echo sounders

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Received: 18 April 2024 – Discussion started: 13 June 2024
Revised: 2 October 2024 – Accepted: 24 October 2024 – Published: 20 January 2025

Abstract. High-resolution bathymetry provides critical information to marine geoscientists. Bathymetric big data help characterise the seafloor and its benthic habitats, understand sedimentary records, and support the development of offshore engineering infrastructures. From 27 September to 20 October 2022, the new CNR research vessel *Gaia Blu* explored the seafloor of the Naples and Pozzuoli gulfs and the Amalfi coastal area (Tyrrhenian Sea, Italy) from 50 to more than 2000 m water depth, acquiring about 5000 km^2 of multi-beam echo sounder data. This area is particularly vulnerable to abrupt changes driven by the dynamics of several volcanic complexes, active in the area, and by human-induced impacts reflecting the proximity to the highly populated and touristic coastal area of Naples and nearby famous islands. For these reasons, the seafloor of the area needs to be known and constantly monitored. The digital bathymetric data previously available are restricted to the shallow highly dynamic area of the Gulf of Naples and appear fragmented as they were acquired in successive years, with different goals thereby using a variety of devices, with markedly different spatial resolutions. In this paper, we present bathymetric maps of the Gulf of Naples and adjacent slope basins at unprecedented resolution using three state-of-the-art multi-beam echo sounders. These high-resolution data highlight the technological advances of geophysical surveys achieved over the last 20 years and contribute to assessing the most dynamic areas where changes in the seafloor over time can be quantified. The new digital multi-resolution bathymetric products are openly accessible via Marine Geosciences Data System MGDS (refer to "Data availability" section, Table 8, for datasets and product DOIs), perfectly matching the FAIR (findable, accessible, interoperable, and reusable) and open science principles.

Published by Copernicus Publications.

1 Introduction

In 2018, GEBCO and the Nippon Foundation joined forces to establish the Nippon Foundation GEBCO Seabed 2030 Project (Mayer et al., 2018), an international effort to foster the complete mapping of the world ocean by 2030. Despite many years of mapping efforts unveiling increasingly larger portions of the seabed, only about 25 % of the world ocean's seafloor is mapped to date at high resolution (https://seabed2030.org/our-mission/, last access: 10 December 2024). Obtaining a high-resolution map of the world's seafloor is crucial to understanding how oceans work, from geodynamics and geohazard aspects to the interactions between seafloor morphology and bottom-current dynamics and to the distribution and ecological status of benthic habitats to cite a few applications. In the last 40 years, almost two-thirds of marine environments have been "severely altered" by human activity (Díaz et al., 2019), resulting in significant biodiversity loss and erosion of the ecological services and goods (Worm et al., 2006). In this context, the European Union has implemented a governance framework specifically aiming at assessing, monitoring, and preserving the status of the marine benthic natural heritage (Marine Strategy Framework Directive MSFD, 2014/89/EU) but also at promoting the sustainable exploitation of marine and coastal resources (European MSP Directive, 2008/56/EC). Among the European seas, the Mediterranean Sea is a hotspot of biodiversity, hosting more than 7.5 % of global biodiversity (Bianchi and Morri, 2000), with a high percentage of endemic species (Myers et al., 2000) and unique ecosystems. However, the basin is recognised to be "under siege" due to the historical and still ongoing impacts from multiple stressors such as littering and dumping, trawling, ghost fishing, seaborne traffic, and modification of the seafloor (Coll et al., 2012; Puig et al., 2012; Madricardo et al., 2017, 2019; Canals et al., 2021; Budillon et al., 2022; Pellegrini et al., 2023; Trincardi et al., 2023). This is particularly evident in the Gulf of Naples, a densely populated coastal region stretching along 385 km on the eastern Tyrrhenian Sea, which represents an important tourist destination including the gulf islands (Capri, Ischia, and Procida); Sorrento Peninsula; Vesuvius National Park; Phlegraean Fields; and archaeological sites of Pompeii, Herculaneum, Pozzuoli, and Cuma.

The underwater landscape of the Gulf of Naples is geomorphologically complex, with large canyon systems, marine landslides, debris flow deposits, and volcanic apparatuses; the area includes various benthic habitats of ecological relevance from the shore to the deep sea, such as *Posidonia oceanica* meadows (e.g. Gaglioti et al., 2020), animal forests (e.g. Bavestrello et al., 2014), cold-water corals (CWCs; Taviani et al., 2019; Angiolillo et al., 2023), and hydrothermal vent communities (e.g. Appolloni et al., 2020; Donnarumma et al., 2019). The gulf region also hosts numerous archaeological and cultural heritage sites, threatened by natural and human pressures (Mattei et al., 2019). To preserve marine biodiversity and the historical value of the area, four marine protected areas (MPAs) have been established: the underwater parks of Baia and Gaiola MPAs, the Regno di Nettuno MPA, and the Punta Campanella MPA (Appolloni et al., 2018).

The first extensive high-resolution mapping of the seafloor of the gulf was performed in the framework of the Italian geological mapping research programme (1997–2017) through bathymetric surveys of the continental shelf and slope system of the Campania region, using numerous multibeam echo sounders (MBESs) with a vertical resolution of < 0.25 % of the water depth and position accuracy better than 10 m. The data, acquired at different resolutions, were merged to create a digital terrain model (DTM) with a homogeneous grid and with a cell spacing of 20 m (Aiello et al., 2020). This map highlighted the most prominent geomorphological features in the coastal zone such as the canyons, banks, debris avalanches, hydrothermal vents, and volcanoclastic basement outcrops, with high-ecological-value habitats in urgent need of preservation (Taviani et al., 2019). This valuable dataset was shared in gridded form, within the EMODnet project, as 1/16 arcmin (ca. 115 m) DTMs. High-resolution data for selected areas are also available as 1/128 or 1/256 arcmin (ca. 15 or 7 m) HR-DTMs (https://emodnet.ec.europa.eu/geoviewer/, last access: 10 December 2024).

Despite the significant effort of ongoing national and international projects and infrastructures worldwide to make data available, such as GEBCO (https://www.gebco.net, last access: 10 December 2024) and EMODnet (https://emodnet.ec.europa.eu/en, last access: 10 December 2024), local high-resolution datasets and raw data are typically not yet accessible (Sievers et al., 2021). Indeed, local datasets are often generated, hosted, and administered by various institutes in the world with dissimilar data policies, which often do not follow the findable, accessible, interoperable, and reusable (FAIR) data principles (Stall et al., 2019).

This study presents the results of a high-resolution geophysical survey named JammeGaia22 conducted in October 2022 on board R/V *Gaia Blu* using three different state-of-the-art MBESs (Kongsberg EM 2040, EM 712, and EM 304) and aims at improving the knowledge of the seascape of the Gulf of Naples by enhancing the analysis and visualisation of seabed morphology through high-resolution digital bathymetric models.

Our contribution aims at highlighting the innovative approach used during JammeGaia22 (Sect. 3.1 and 3.2), where data are processed daily on board and can be made available to the scientific community and the generic public in very short time via a geoportal, making the datasets FAIR and facilitating interdisciplinary research within the open science principles. We describe the bathymetric and backscatter datasets in detail (Sect. 4), highlighting their potential applications thanks to the good quality of the data collection,

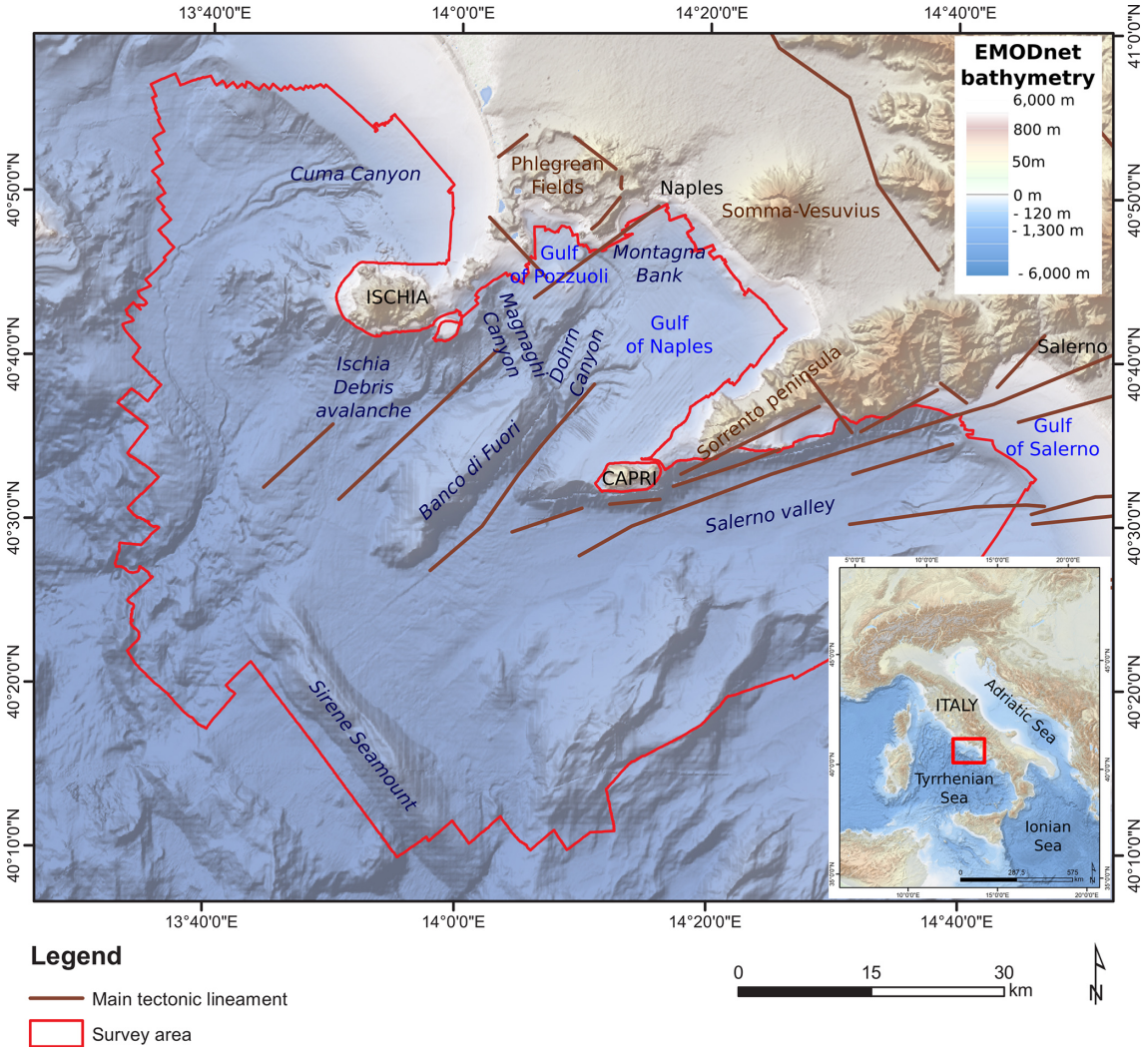

Figure 1. Map of the study area in the central Tyrrhenian Sea, showing the main physiographic and tectonic features (modified from Aiello et al., 2020). Elevation and bathymetry from EMODnet bathymetry (https://emodnet.ec.europa.eu/en/bathymetry, last access: 10 December 2024).

discussed in Sect. 4.3. Finally, we provide full access to the whole dataset, the bathymetric grids and backscatter mosaics produced, and the metadata as explicated in the "Data availability" section.

Given the unprecedented high- and multi-resolution survey conducted in the study area and the availability of ancillary data such as backscatter and water-column data, this dataset represents a unique benchmark for future studies related to geohazards assessment, sediment transport, fishery management, resource exploration and sustainable exploitation, maritime spatial planning and decision making, marine ecosystem and habitat mapping, and oceanographic modelling including storm surges and scenarios of tsunami wave propagation.

2 Study area – geological and geomorphological background

The investigated area belongs to the central-eastern margin of the Tyrrhenian Sea, encompassing the region between the western margin of the Southern Apennines thrust belt and the Tyrrhenian abyssal plain (ca. 3000 m deep; Fig. 1). The Tyrrhenian Sea is the youngest back-arc basin of the Mediterranean Sea that has developed since the middle Miocene (Trincardi and Zitellini, 1987; Kastens et al., 1988; Lymer et al., 2018; Loreto et al., 2021; Miramontes et al., 2023) reflecting the east- and south-eastward retreat of the Ionian slab, guided by the Africa–Europe convergence (Moussat et al., 1985; Malinverno and Ryan, 1986; Kastens et al., 1988). The Campania segment of the eastern Tyrrhenian margin is characterised by a series of NE–SW-trending half-grabens

bounded by structural highs that have developed since the Early Pleistocene and accommodate the tectonic-controlled subsidence of the alluvial plains along with their submerged counterparts, namely the Gaeta Gulf, the Gulf of Naples, and the Gulf of Salerno (Fig. 1; Romano et al., 1984; Ruberti et al., 2022; Amato et al., 2011; Bellucci et al., 2006).

Structural lineaments also control the preferential pathways of volcanic activity, particularly in the last 2 Myr. Volcanic activity followed an eastward migration, governing the geomorphological setting of the region and promoting deposition of sedimentary sequences up to 3 km thick (Milia, 1999; Milia et al., 2003). The Phlegraean Fields volcanic area is a 78 kyr old active poly-calderic system (Scarpati et al., 2012) that has affected its territory in the last millennia and has strongly influenced the evolution of the adjacent coasts during the Late Pleistocene and Holocene, which has been mainly shaped by three super-eruptions. The oldest one was the Campanian Ignimbrite (CI) eruption that occurred at ca. 35–40 ka (Giaccio et al., 2017). After this main event, the northern part of the just-formed caldera was submerged by the sea. The second eruption, which led to the formation of the Masseria del Monte Tuff, occurred at 29.3 ka (Albert et al., 2019). The Neapolitan Yellow Tuff (NYT; Deino et al., 2004) eruption at ca. 15 ka contributed to the formation of the youngest caldera (Orsi et al., 1992), nowadays also well documented offshore (Sacchi et al., 2014; Steinmann et al., 2016, 2018). Besides volcanic eruptions, alternating long-term magma/hydrothermal fluid inflation and deflation processes controlled the morphological evolution of this area. Further, short-term vertical, metre-scale ground movements characterised times immediately preceding and following each eruption, which produced rapid relative sea-level variations along the entire coastal sector (Isaia et al., 2019, and reference therein). The area experienced high rates of subsidence (approx. 4.0 mm yr^{-1}) through the Pleistocene (Torrente et al., 2010; Milia et al., 2017; Iannace et al., 2018), accompanied by the activity of major NE–SW-striking faults. At present, intense seismicity, including the M_d 4.0 earthquake that occurred on 2 October 2023, is instead associated with the 18.0 mm yr^{-1} uplift of the central portion of the Phlegraean Fields area.

Volcanic activity, long-term vertical ground movements, glacio-eustasy, and the rapid dismantling of the emerging landscapes have driven a rapid geomorphological evolution of the margin, resulting in steep slopes, canyoning, deep-sea fan accretion, and gravitational slope instability. Extensive lateral collapses of the volcanic edifices have been documented offshore, south of Ischia island (Chiocci et al., 1998; Chiocci and de Alteriis, 2006; de Alteriis et al., 2010), possibly occurred also in historical time, and two others of minor extent to the west and north of Ischia island (Budillon et al., 2003; Violante et al., 2003) and in the Gulf of Naples (Milia et al., 2008, 2012; Passaro et al., 2018). The rapid aggradation of volcaniclastic deposits in a shallow marine environment and the entrance of pyroclastic flows into the seawater also led to seafloor instability and creep in the prodelta offshore the main rivers (Sacchi et al., 2005, 2009).

Three main turbiditic systems, namely Cuma, Magnaghi, and Dohrn canyons, and the deep structurally controlled Salerno Valley, have developed along with the rising of intra-slope reliefs and volcanic activity and acted as main conduits delivering sediment towards deeper-water domains (Passaro et al., 2016b). These features characterise the present-day seafloor morphology and, although partially inactive, are of paramount interest as hotspots of biodiversity in the Mediterranean Sea (e.g. Taviani et al., 2019; Mussi et al., 2022).

3 Materials and methods

3.1 Multi-beam data acquisition

Multi-beam data were collected during the JammeGaia22 cruise from 27 September to 20 October 2022 using three different MBESs: the Kongsberg EM2040-04 MKII 0.4° × 0.7°, suited for water depths between 50 and 150 m; Kongsberg EM712 1° × 0.5° for water depths between 150 and 1000 m; and Kongsberg EM304 MKII 1° × 1° for water depths greater than 1000 m (Table 1 for acquisition settings).

The MBESs were hull-mounted on the R/V *Gaia Blu* gondola with a T configuration of linear transducer arrays. A Seapath 380 system was used for ship positioning, supplied by a Fugro HP differential Global Positioning System (DGPS), with Marinestar GNSS signal accuracy better than 5 cm. The Kongsberg motion sensor MRU (Motion Reference Unit) 5 and a dual-antenna GPS integrated into the Seapath were used to correct for pitch, roll, heave, and yaw movements (reaching 0.02° roll and pitch accuracy and 0.075° heading accuracy). A Valeport mini sound velocity sensor (SVS) was positioned close to the transducers to measure the sound velocity for the beam forming. This sound velocity (SV) value was continuously compared to that from sound velocity profiles (SVPs) in use to warn when a new profile was required. However, the difference between SV from the SVS and in-use profile never reached warning values since SVPs were systematically collected at least twice a day with a Valeport Midas SVP, for a total of 40 SVPs. Data were logged, displayed, and checked in real time by the Kongsberg data acquisition and control software SIS 5 (Seafloor Information System). A tool included in SIS 5 software was used to extend the SVPs down to 12 000 m water depth. Since the Mediterranean Sea is characterised by a stratified water column with peculiar changes in the physical–chemical properties (Tanhua et al., 2013; Rossi et al., 2014; Basterretxea et al., 2018), a linear regression based on the collected SVP data was run in R software (R Core Team, 2019) to estimate the sound velocity values down to 12 000 m depth.

Professional topographers measured the offsets of the instruments with millimetric accuracy using a dedicated dimensional survey of the ship's hull at dry dock.

Table 1. Acquisition settings for the three multi-beam echo sounder systems.

MBES	Water depth (m)	Frequency (kHz)	Angular coverage (°)	Ping rate (Hz)	Acquisition mode
EM2040	50–100	300	65	1.5	Deep
EM2040	100–150	200	70	1.5	Very deep
EM712	150–600	70–100	70	2	Shallow
EM712	600–1000	40–100	70	2	Deep
EM304	> 1000	30	65	> 5	Auto

Table 2. Calibration values applied after the Sea Acceptance Test.

MBES	Pitch	Roll	Heading
EM2040	+0.10°	+0.5°	−0.20°
EM304	00.00°	+0.2°	0.00°
EM712	−0.10°	−0.07°	−0.15°

Sensors were calibrated during the Kongsberg Sea Acceptance Tests (roll, pitch, time, and heading offsets) and were also regularly checked in post-processing (Table 2 for calibration values).

We kept a 20 % overlap between lines to ensure 100 % of bathymetric coverage, avoiding the influence of external beams of bad quality given by possible residual errors in roll, sound speed profile measurements, and poor seafloor detection. The acquisition was carried out with an average swath opening angle of approximately 65/70° for each multi-beam system (Table 1). The vessel sailed with a reasonably constant speed of 8 kn (4.12 m s^{-1}), considered ideal to have the minimum noise and tested during the Sea Acceptance Test. Sea conditions were good and stable for the entire survey, with wave height almost always lower than 1 m. Seafloor and water column backscatter data were collected simultaneously during bathymetric data acquisition.

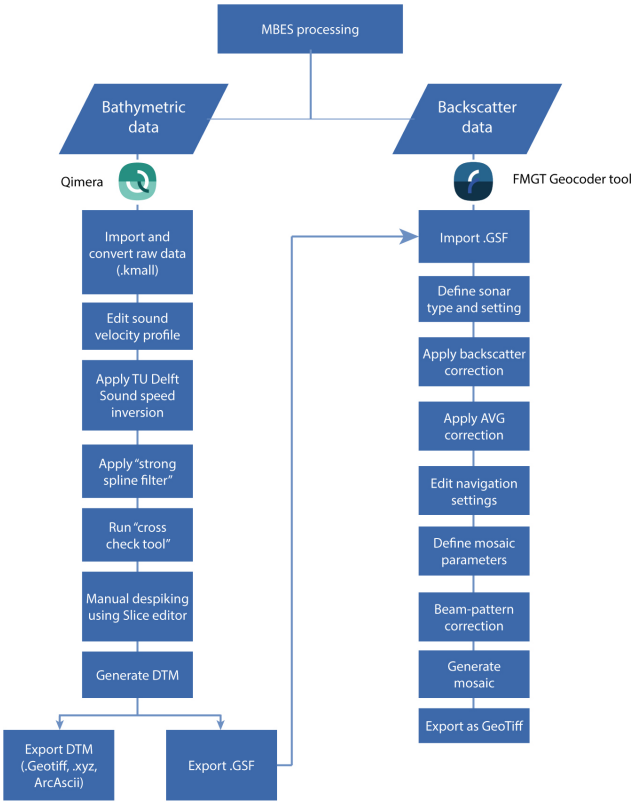

Figure 2. Workflow of bathymetric and backscatter data processing, described in Sect. 3.2.1 and 3.2.2.

3.2 Multi-beam data processing

The bathymetric data collected every day were processed on board during the night shift to produce DTMs and backscatter mosaics, which were then uploaded the next morning in a dedicated WebGIS to inform the scientific community on the progress of the campaign and make the data openly available. The data-processing workflow is summarised in Fig. 2.

3.2.1 Bathymetric data processing

The processing of the raw data was carried out using the QPS Qimera v.2.5.0 software (Quality Positioning Services BV, Zeist, Netherlands) following a standard procedure, which includes sound speed correction, removal of erroneous soundings, and correction of vertical offsets from a previous swath. The quality of the data was initially checked using the "Cross Check Tool" to check for soundings with significant offsets from the local mean water depth.

When sound velocity errors were evident in the data, the TU Delft Sound Speed Inversion tool (Beaudoin et al., 2018) was used to correct the profile. The tool applies an algorithm that allows a completely automated refraction error correction. It works by taking advantage of the overlap between survey lines to simultaneously estimate sound speed correction for a given set of pings and their neighbours, by computing a best-fit solution that minimises the mismatch in the areas of overlap between lines (Mohammadloo et al., 2019). The settings applied for TU Delft Sound Inversion were data-specific, depending on the quality of the SVP, upon initial assessment.

After the sound speed correction, the strong spline filter of Qimera allowed removal of soundings beyond the local mean water depth (offsets); the remaining offsets (if any) were removed manually using the "Slice editor" of Qimera. The processed bathymetric data were exported into GSF format for backscatter processing and to a gridded surface data (GeoTIFF). The resolution of the GeoTIFF was defined based on the water depth and the footprint calculated for each sonar used (Table 3).

3.2.2 Backscatter data post-processing

The MBES backscatter data were processed using the QPS Fledermaus Geocoder Tool (FMGT) v.7.10.2 software. The processed MBES data (.gsf) were used to apply backscatter corrections, beam pattern correction, and angle-varying gain (AVG) corrections to the backscatter data. After these corrections, FMGT applied the sonar's navigation data (i.e. XY coordinates, roll, heading, pitch, heave) to georeference the backscatter value. The DTM generated in Qimera provided a bathymetric grid to improve backscatter corrections. The reference grid was included by the FMGT software to determine topographic slope, while the corrected bathymetry in the source files (i.e. GSF) was regularly used to georeference the snippet trace from a single ping to the correct position on the seafloor. Finally, the backscatter snippets were mosaicked with the "no nadir possible, 25 % overlap" algorithm to reduce the banding effect, and 30 %–40 % line blending was applied to blend the pixels in the overlapping areas. The mosaics were gridded in various resolutions (Table 4), with intensity values (dB) cropped to $\pm 3\sigma$ and logarithmically mapped to 8 bit scale. These mosaics were exported as "One Merged Colored GeoTIFF format".

3.3 Bathymetric derivatives

A geomorphometric analysis of the seabed was carried out using ArcGIS to emphasise any subtle variation in seafloor morphology. The geomorphometric indices calculated were slope, broad-scale and fine-scale Bathymetric Position Index (BPI), and vector ruggedness measure.

The slope is a first-order derivative of the bathymetry and represents seabed maximum inclination (in any direction) in degrees, and the slope was measured in ArcGIS as the maximum rate of change in value from a cell to its immediate neighbours. The calculation is performed using the average maximum technique (Burrough and McDonell, 1998), picking an area of 3×3 pixels around each cell. Values are real numbers between 0.0 and 90.0°, and areas of no data have a conventional value of -1.0. Depth values in input were smoothed before calculation of the slope using a user-defined smoothing window of 3×3. This approach served to removed local changes giving a regional value for slope and diminishing edge effect (Dolan, 2012).

Broad- and fine-scale BPIs were calculated using the Benthic Terrain Modeler (BTM) toolbox for ArcGIS (Walbridge et al., 2018; Lundblad et al., 2006). BPI is derived from an input bathymetric data set and is a modification from the topographic position index as defined by Weiss (2001) and Iampietro and Kvitek (2002). It evaluates differences in elevation between a focal point and the mean elevation of the surrounding cells within a user-defined window. Values range from -1 to $+1$, with negative values reflecting depressions in the seabed, null values for planar areas, and positive values denoting positive reliefs. Broad-scale BPI allows the identification of main regional features within the seafloor, while fine-scale BPI helps identify smaller features of the benthic landscape. The values used to calculate BPIs for all the bathymetric surfaces are reported in Table 5.

The vector ruggedness measure (VRM) quantifies terrain ruggedness by measuring the dispersion of vectors orthogonal to the terrain surface (Sappington et al., 2007). VRM shows low values in both flat and steep areas but high values in areas that are both steep and rugged.

4 Results and discussion

4.1 Multi-grid bathymetric dataset

The bathymetric dataset covers an area of about 5000 km^2 offshore of the Gulf of Naples from 50 to more than 2000 m water depth (Fig. 3). The different resolutions, depending on the water depth and the MBES footprint, of the acquired data reveal the complexity of the seafloor with unprecedented details and allow geomorphological features already described in the literature to be better discriminated (D'Argenio et al., 2004).

Coupled with other indices, this high-resolution bathymetry not only is valuable information to study sediment dynamics, morphotectonics of canyons, structural highs, and seamounts but also represents a baseline to investigate the presence and distribution of benthic habitats and infer hydrological transients at the seafloor. To demonstrate how the newly acquired data allow the variations of the seafloor to be appreciated, broad-scale BPI and fine-scale BPI were calculated from the bathymetry in three selected sectors of the study area using the parameters reported in Table 5.

4.1.1 Canyons of the Gulf of Naples

The morphology of the Dohrn and Magnaghi canyons is possibly controlled by the presence of extensional faults coupled with the volcanic activity characterising the area. Both canyons acted as large drainage systems within this proximal marine area during the late Quaternary (Aiello et al., 2020, and references therein). The two branches of Dohrn Canyon are about 500 m wide and show a V-shaped profile in the upper part and a U-shaped profile in the lower part,

Table 3. Calculated footprints of ensonified seafloor area at different water depths for each MBES, relative grid resolution chosen, and mean of the number of soundings in each grid cell. Products and datasets are available in the "Data availability" section.

MBES	Water depth (m)	TX footprint (m)	RX footprint (m)	Insonifed area (m^2)	Grid resolution (m)	Number of soundings per grid cell
EM2040 (0.4° × 0.7°)	50	0.4363	0.6109	0.92	2	7.12
	60	0.5236	0.7330	1.10		
	70	0.6109	0.8552	1.28		
	80	0.6981	0.9774	1.46		
	90	0.7854	1.0996	1.65		
	100	0.8727	1.2217	1.83		
EM712 (0.5° × 1°)	150	1.3090	2.6181	3.28	5	23.87
	200	1.7453	3.4907	4.37		
	300	2.6180	5.2361	6.56	10	17.35
	400	3.4907	6.9815	8.75		
	500	4.3634	8.7269	10.94		
	600	5.2360	10.4722	13.12	15	9.96
	700	6.1087	12.2176	15.31		
	800	6.9814	13.9630	17.50	20	13.9
	900	7.8540	15.7084	19.69		
	1000	8.7267	17.4537	21.87		
EM304 (1° × 1°)	1000	17.4537	17.4537	30.94	30	21.72
	1100	19.1991	19.1991	34.03		
	1200	20.9445	20.9445	37.12		
	1300	22.6899	22.6899	40.22	40	25.45
	1400	24.4352	24.4352	43.31		
	1500	26.1806	26.1806	46.40		
	1600	27.9260	27.9260	49.50		
	1700	29.6714	29.6714	52.59		
	1800	31.4167	31.4167	55.68		
	1900	33.1621	33.1621	58.78		
	2000	34.9075	34.9075	61.87		

Table 4. Resolution of backscatter mosaic for each MBES. Products and datasets are available in the "Data availability" section.

MBES	Mosaic resolution (m)
EM2040	5 m
EM712	10 m
EM304	30 m

suggesting uniform sediment fill of the thalweg. The bathymetric derivatives confirm the complexity of these drainage patterns, related to the stratigraphy of the eroded terrains and to the recurrence and or competence of the flows flushing the two systems: straight gullies characterise the flanks of Dohrn Canyon and normally do not indent the outer shelf, with the exception of the area NW of Capri (Fig. 4). Dohrn Canyon emanates from the Ammontatura channel, on the inner shelf, a possibly active sediment conduit also during sea-level rise and high-stand conditions; Dohrn Canyon undercuts its secondary branch located north of Capri Island, under-excavating its base by 50 m. The straight gullies on the flanks of Dohrn Canyon are hanging above the canyon thalweg, suggesting the activity of powerful flows along the axis of the canyon. Moreover, the fine-scale BPI highlights terrace rims along Dohrn Canyon flanks and slide scars with a slide deposit at their foot (Aiello et al., 2020), as well as the gullies with head scarps and along-slope small-scale sand splays located on the southern flank of Banco di Fuori. Dohrn Canyon shows a radial bedform field in its lower portion where the canyon broadens, and its floor decreases its gradient. Comparison with pre-existing data in this area suggests that the bedform field has not moved in the last 2 decades.

In contrast, Magnaghi Canyon is shorter, less deeply incised, and not gullied on its flanks, possibly reflecting its lack of connection to a major source of sediment-laden flows. The right-hand side of the canyon shows short and straight incisions with marked bedforms that appear reminiscent of cyclic

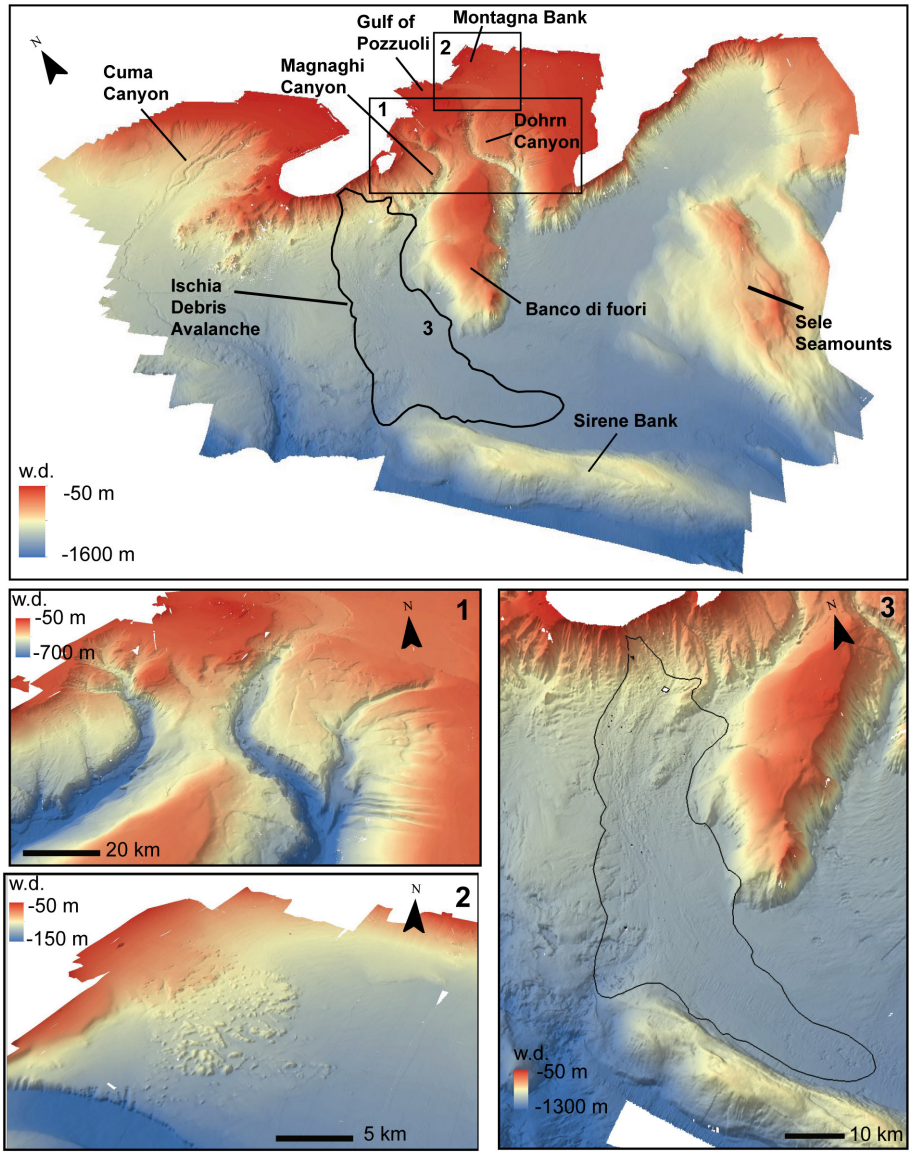

Figure 3. Bathymetric map of the study area (20 m resolution, 2 vertical exaggeration) showing the main seabed features: (1) multi-beam bathymetry (20 m resolution, ×2 vertical exaggeration) of the Dohrn and Magnaghi canyon systems, (2) multi-beam bathymetry of the Montagna Bank area, and (3) multi-beam bathymetry of the debris avalanche offshore Ischia island.

steps (Kostic, 2011; Slootman and Cartigny, 2020) and can be clearly discerned on the slope map and on the BPI maps.

4.1.2 Cuma Channel

Cuma Channel is a complex sediment conduit characterised by (1) an upper section, between the shelf-edge and the base of Gaeta basin, where three independent sub-parallel channels present gullied heads, low sinuosity, and a flat channel floor; (2) a relatively narrow thalweg characterised by a prominent high sinuosity on the sub-horizontal floor of Gaeta Basin; and (3) a straighter channel, proceeding in deeper waters across the steepening slope region.

Pairing both bathymetric and backscatter images prompts several questions that will be worth addressing in future cruises, after collecting complementary core and seismic-stratigraphy data. In particular, the following is established:

1. There is no continuity between either of the three channels dissecting the upper slope and the high-sinuosity channel on the floor of Gaeta basin; however, backscatter images hint to a seaward continuity of the most meridional of the three slope channels characterised by higher backscatter and, likely, coarser-grained sediment. This channel reaches a north–south orientation

Table 5. Inner and outer radius used for calculation of Bathymetric Position Index (BPI) for selected areas by depth range.

Area	Depth range (m)	Resolution (m)	Broad-scale BPI inner–outer radius (cells)	Fine-scale BPI inner–outer radius (cells)
Canyons of the Gulf of Naples	50–100	2	30–60	2–5
	101–200	5	12–30	2–5
	201–500	10	6–15	2–5
	501–700	15	4–9	2–5
	701–1000	20	3–8	2–5
	1001–2500	30	2–5	2–5
Montagna Bank	50–100	2	30–60	5–8
	101–200	5	12–30	5–8
	201–500	10	6–15	5–8
Ischia debris avalanche	50–100	2	30–60	1–3
	101–200	5	12–30	1–3
	201–500	10	6–15	1–3
	501–700	15	4–9	1–3
	701–1000	20	3–8	1–3
	1001–1900	30	2–5	1–3

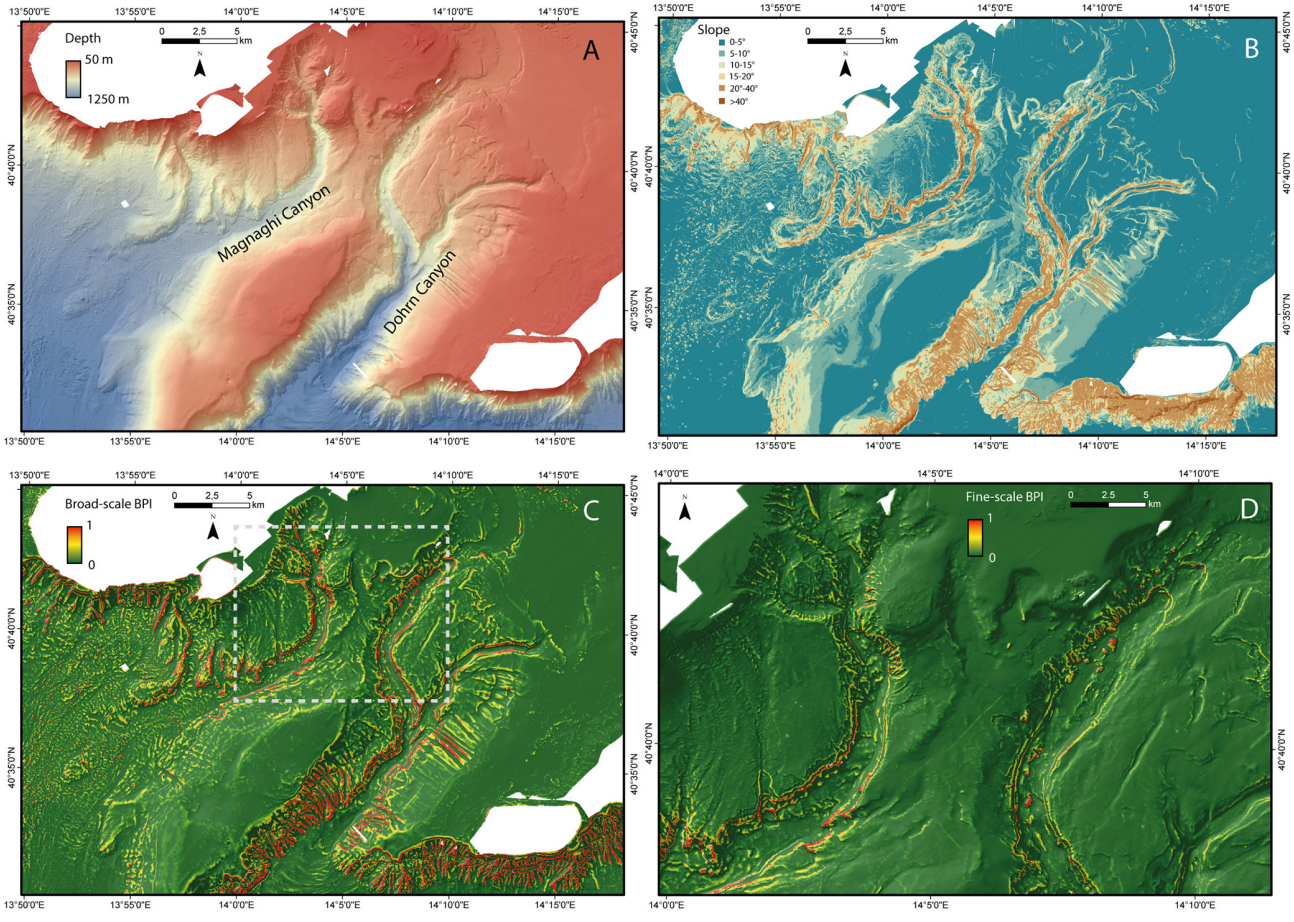

Figure 4. **(a)** Bathymetric data of canyons of the Gulf of Naples. **(b)** Slope. **(c)** Positive values of broad-scale and **(d)** fine-scale BPI of a portion of the area (dashed rectangle in **c**) calculated from the newly acquired multi-resolution grid, showing the drainage pattern of the Dohrn and Magnaghi canyons.

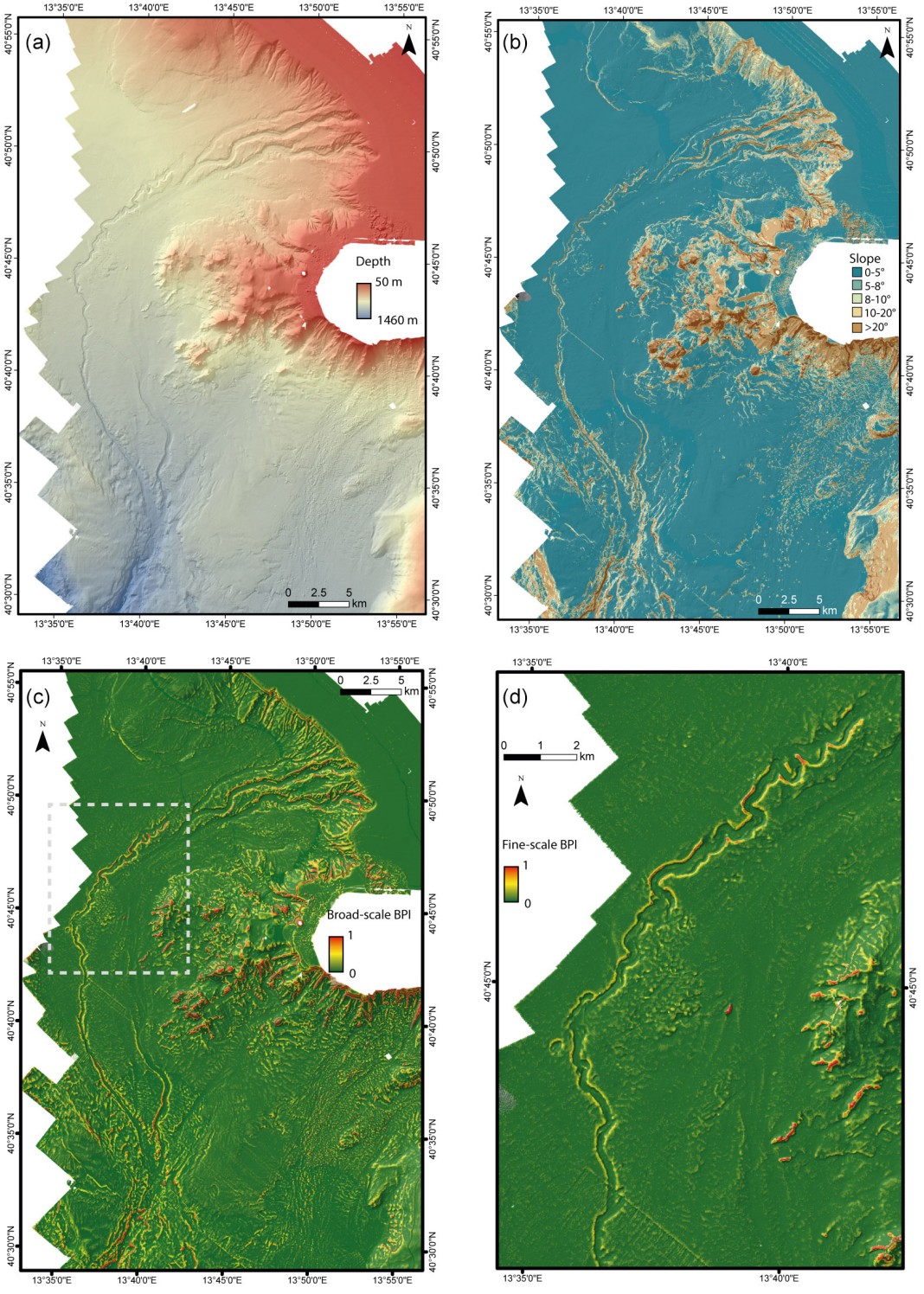

Figure 5. **(a)** Bathymetric data of Cuma Channel. **(b)** Slope. **(c)** Positive values of broad-scale and **(d)** fine-scale BPI of a portion of the area (dashed rectangle in **c**) calculated from the newly acquired multi-resolution grid.

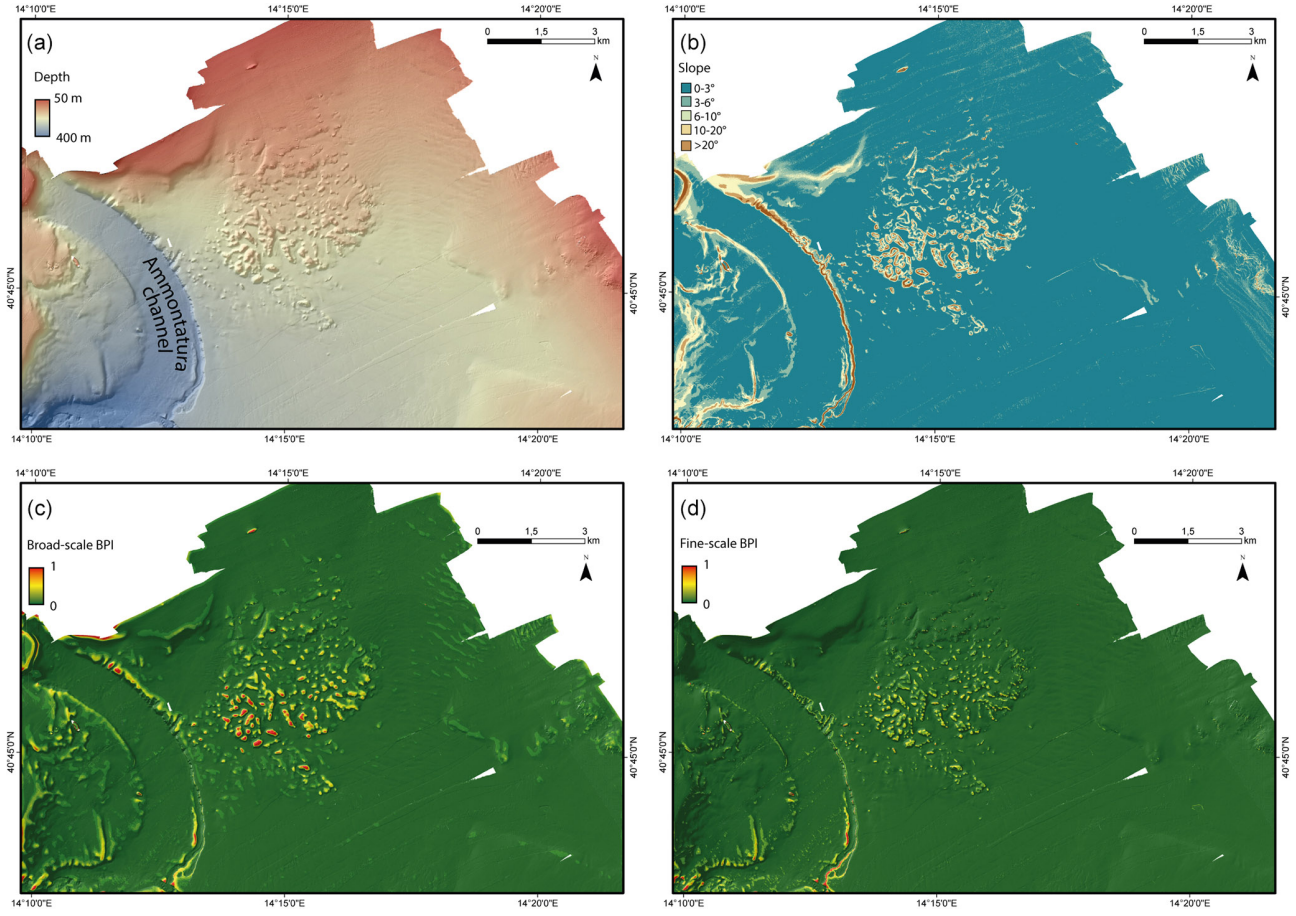

Figure 6. **(a)** Bathymetric data of the Montagna Bank. **(b)** Slope. **(c)** Broad-scale and **(d)** fine-scale BPI calculated from the newly acquired multi-resolution grid, showing the morphology of the Montagna Bank.

before widening and rapidly reducing its seafloor reflectivity.

2. The high sinuosity to the west is therefore disconnected from its original feeder, upslope, and, proceeding downslope, it bends gently to the southeast and then to the southwest in the lowermost tip of the mapped area; interestingly, the region located west of this gentle, multi-kilometric bend is carved by several barchan-like scours that can be hypothetically ascribed to overflows of a much larger volume compared to the size of the channel conduit.

3. Knowing that the Volturno prodelta has reached the shelf edge, it is possible that hyperpycnal flows from the river ignite flows on the slope that are capable to hug the seafloor and reshape its morphology, as documented during the modern sea-level high stand in some other example of high-discharge systems like the Crati River (Lucchi et al., 1983).

4.1.3 Montagna Bank

In the shallower area of the Gulf of Naples, Montagna Bank is a morphological high extending over 25 km^2 (Passaro et al., 2014, 2016b, 2018; Ventura et al., 2016), where volcanoclastic materials (dominantly low-density pumice) underwent small-scale deformation, leading to the growth of metre-scale sediment diapirs and possible fluid-escape features; in particular, this hummocky area includes 280 mounds, 650 cones with metre-scale height, and 30 pockmarks (Sacchi et al., 2019), between 100 and 150 m water depth. The slope calculated for the Montagna Bank (Fig. 6) shows the inclinations of both the whole morphological high and the individual bedforms surrounding it (i.e. the flanks of the Ammontatura channel and sedimentary bedforms located W of the Montagna Bank). Furthermore, the calculated BPIs reveal large and small mounds constituting the hummocky-like morphology of the large-scale relief.

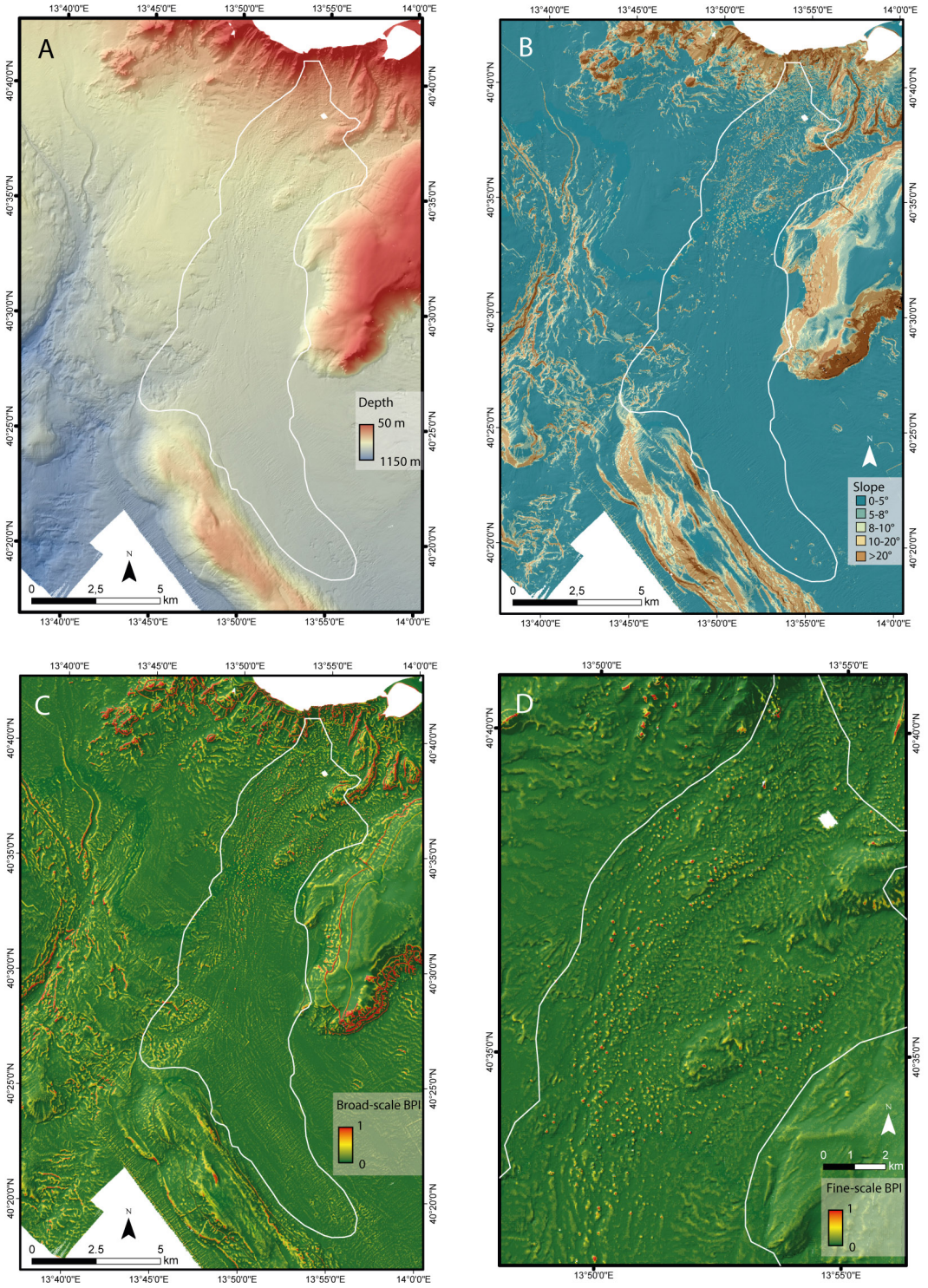

Figure 7. **(a)** Bathymetric data of the Ischia debris avalanche. **(b)** Slope. **(c)** Broad-scale and **(d)** fine-scale BPI calculated from the newly acquired multi-resolution grid, showing the location and morphology of debris blocks. The white square delimitates the area that contains the debris avalanche.

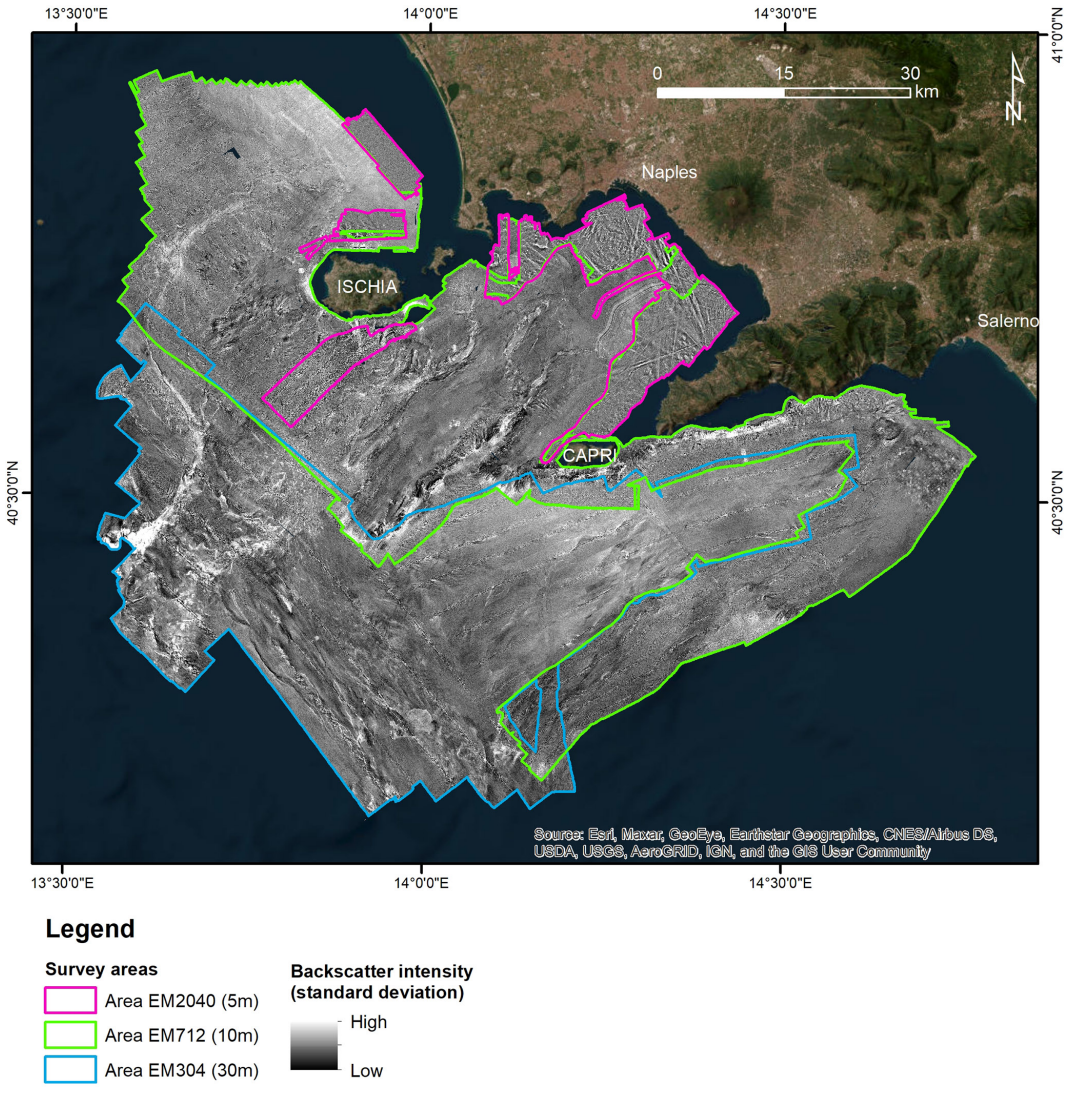

Figure 8. Backscatter mosaics acquired during the JammeGaia22 cruise with the survey areas covered by the three MBESs.

4.1.4 Ischia debris avalanche

The Ischia debris avalanche is located south of Ischia island and is a 50 km long tongue characterised by a hummocky topography extending for about 200 km^2, with fields of giant blocks spanning in size from a few metres to > 200 m across and with larger blocks being up to 30–50 m high (Chiocci and de Alteriis, 2006; de Alteriis et al., 2010). The hummocky deposit follows the local pre-collapse topography, and, on its eastern side, it overflows into the Magnaghi Canyon. The slope (Fig. 7b), the broad-scale (Fig. 7c), and fine-scale (Fig. 7d) BPI obtained using different inner and outer rays (Table 5), calculated from the newly acquired bathymetric data, allow the morphology of the deposits to be better appreciated and individual debris blocks to be clearly identified, allowing better measurement of their size and volume.

4.2 The multi-grid backscatter mosaic

The backscatter intensity data acquired during the JammeGaia22 cruise represent the first dataset covering the entire Gulf of Naples, Ischia surroundings, Salerno Valley, and Sirene Seamount. Three mosaics were exported at different spatial resolutions: 5 m for the dataset acquired using the EM2040 system, 10 m for EM712, and 30 m for EM304 (Fig. 8).

Details are shown for four areas: Montagna Bank, Sorrento Peninsula, north and west Ischia island, and Magnaghi canyon head (Fig. 9). The backscatter highlighted the hummocky-like morphology of the Montagna Bank and the trawl marks on the seabed around it. The backscatter dataset of the Sorrento Peninsula revealed the occurrence of patterns likely associated with coralligenous bioconstructions (the lighter areas) and seagrass meadows along the coast, as

Table 6. Parameters used to calculate total horizontal uncertainty and total vertical uncertainty.

	EM2040	EM712	EM304
Echo sounder			
Pulse length	2, 3, 6, and 12 ms	2 ms	7.5 ms
Sampling frequency	200, 300 kHz,	70 kHz	25 kHz
Sound velocity			
SD surface sound speed	0.02 m s^{-1}	0.02 m s^{-1}	0.02 m s^{-1}
Beam width			
Beam width along (Tx)	0.4°	0.5°	1.0°
Beam width across (Rx)	0.7°	1.0°	1.0°
Offsets (Argo)			
SD roll offset	0.04°	0.04°	0.04°
SD pitch offset	0.02°	0.02°	0.02°
SD heading offset	0.02°	0.02°	0.02°
POS			
SD horizontal	0.1 m	0.1 m	0.1 m
SD vertical	0.1 m	0.1 m	0.1 m

Table 7. Mean horizontal and vertical uncertainties of bathymetric data collected using different multi-beam systems and the accepted IHO error limits, which show that the data collected are within the IHO standards.

	THU (m)	TVU (m)	Order 2 maximum allowable THU (m)	Order 1 maximum allowable THU (m)	Order 2 maximum allowable TVU (m)	Order 1 maximum allowable TVU (m)
EM2040	1.66–4.94	0.88–4.77	25 at 50 m	7.5 at 50 m	1.52 at 50 m	0.82 at 50 m
EM712	8.98	1.29	35 at 150 m	12.5 at 150 m	3.29 at 150 m	2.01 at 150 m
EM304	20.03	3.67	120 at 1000 m	55 at 1000 m	23.02 at 1000 m	13.01 at 1000 m

previously highlighted in other studies (CARG – Geological CARtography project, 2024; EMODnet Seagrass cover (Essential Ocean Variable) in European waters, 2023; Russo et al., 2008; Buonocore et al., 2020). Also, the hummocky morphology of the debris avalanches occurring north and west of Ischia island is enhanced by the seabed reflectivity, together with features of fluid escapes (white spots in Fig. 9c) around Ischia island and in the head of the Magnaghi canyon, due to the hydrothermal activity characterising the area.

4.3 MBES data quality

The uncertainty of the bathymetric data was calculated in Qimera v.2.5.4 according to the *IHO Standards for Hydrographic Surveys*, S-44 6th Edition, 2022. Total horizontal uncertainty (THU) and total vertical uncertainty (TVU) were calculated considering the standard deviation offsets of the MRU, MBES, sound velocity probe, and positioning system. Parameters used for the calculation of THU and TVU were taken from the data sheet of the MBESs and installation report (Table 6). The uncertainty values of EM2040 vary depending on the sampling frequency and depth changes during the survey. Hence, the values presented below are the range of uncertainty calculated for 200 and 300 kHz and different pulse lengths that were used during acquisition.

Although the scope of our survey was not related to navigation safety, we evaluated whether the horizontal uncertainty (THU) and vertical uncertainty (TVH) values met the IHO Standards for Hydrographic Surveys S-44 6th Edition, 2022. Since we operated deep areas and the under-keel clearance was not an issue, THU and TVU were compared with the maximum allowable THU and TVU calculated at the minimum depth sampled for each MBES according to IHO standards for Order 2 and 1b.

The results show the lowest horizontal uncertainty for data collected using EM2040 (THU = 1.66 to 4.94 m), while those collected with EM304 present the highest uncertainty (THU = 20.03 m) (Table 7). The lowest vertical uncertainty was obtained for EM712 (TVU = 1.29 m), whilst the highest was obtained for EM2040 (TVU = 4.77 m).

The estimated THUs and TVUs of EM712 and EM304 were below their maximum allowable values for both Or-

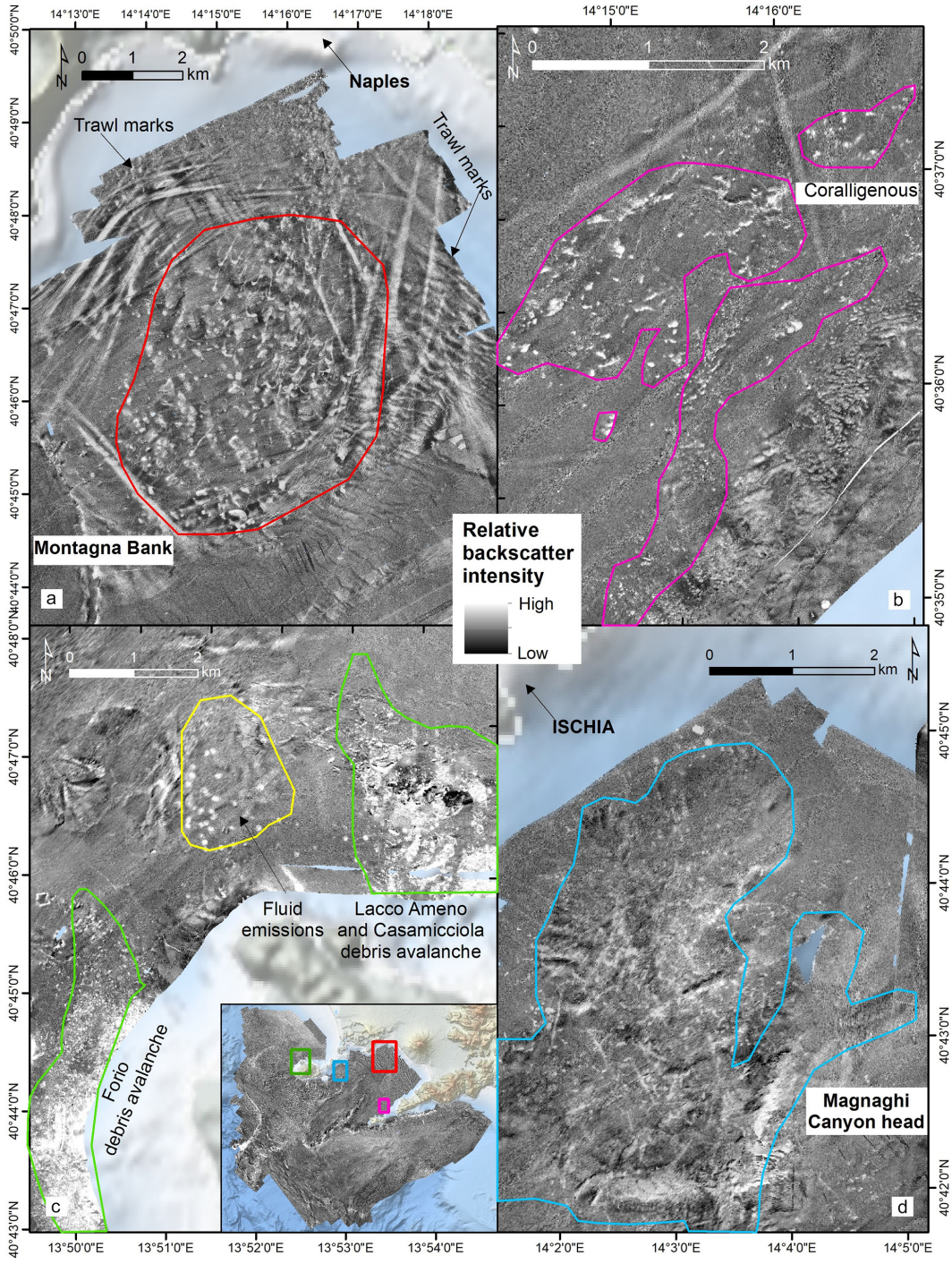

Figure 9. Details of the seabed backscatter in different locations: **(a)** Montagna Bank hummocky morphology and trawl marks (EM2040 – 5 m). **(b)** Coralligenous bioconstructions west of the Sorrento Peninsula (EM712 – 10 m). **(c)** Debris avalanches north and west of Ischia island and fluid-escape features (EM712 – 10 m). **(d)** Head of the Magnaghi Canyon characterised by fluid-escape features, trawl marks, and areas potentially hosting cold-water corals (EM712 – 10 m).

ders 2 and 1. The TVU calculated for the EM2040 is above its maximum allowable value for Orders 2 and 1. However, the quality of the data acquired was high enough to produce high-resolution bathymetry and for the scopes of our survey.

The uncertainty values calculated for JammeGaia22 survey data testify that the seafloor map of the Gulf of Naples obtained with the new technologies installed on board the R/V *Gaia Blu* represents a product of high quality. This new

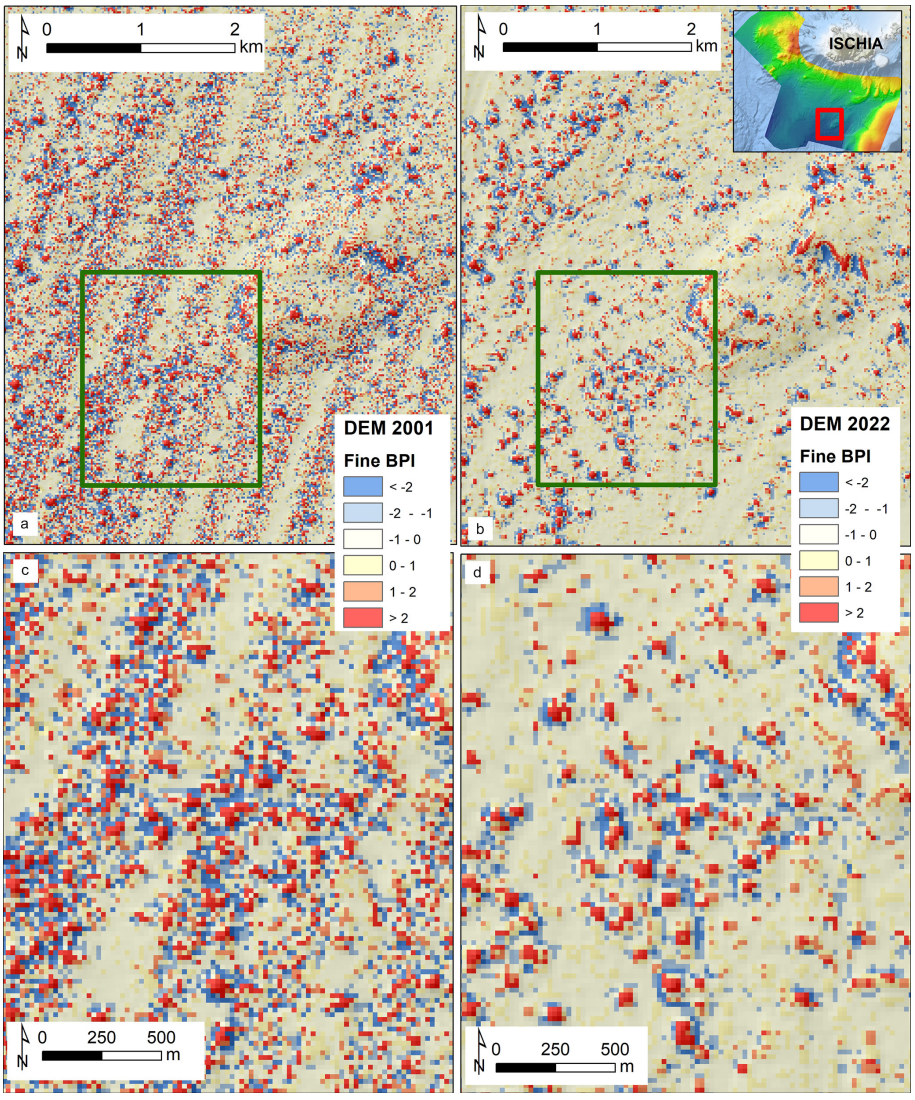

Figure 10. Fine-scale BPI calculated on the 2001 DTM **(a)** and JammeGaia22 DTM **(b)** for the area of the Ischia debris avalanche; noticeably, the 2001 dataset is very noisy. Detail of the blocks accumulation for 2001 DTM **(c)** and JammeGaia22 DTM **(d)**: despite both datasets having the same spatial resolution (20 m), the newly acquired dataset allows blocks to be better discriminated and mapped.

dataset will serve as a crucial baseline for future in-depth analysis of the geomorphology of the area, favouring the identification of seabed features at unprecedented resolution.

A significant improvement in the resolution of the data appears evident when comparing the morphology of the Ischia debris avalanche from DTM at 20 m horizontal resolution generated from the ancient and modern datasets. The newly acquired dataset shows better coverage and less noise than the 2001 dataset (Fig. 9). The blocks of the landslide deposit can be also clearly identified in the new dataset, whilst the identification is not obvious for some areas in the 2001 dataset.

To test if this increase in the resolution has an impact on geomorphological indices derived from the bathymetry, we calculated the fine-scale BPI from the 20 m-resolution DTMs (2001 and the JammeGaia22 surveys) using the same parameters for both the datasets, reported in Table 5. The results show a much higher noise level for the 2001 DTM with respect to the JammeGaia22 dataset (Fig. 10). The noise was higher, especially at the overlap among the swaths on the western part of the dataset and the central beams of the swath in the central part of the data, where most of the landslide blocks occur. Such blocks are better detected and isolated through BPIs in 2022 DTM, rather than in 2001 DTM.

4.4 Comparison to previous data

The area for this study was selected not only for its intriguing dynamic, tectonic, and volcanic activity; benthic boundary processes and seafloor biodiversity; and widespread human

Table 8. Products of the JammeGaia22 oceanographic cruise with relative links.

Product	Typology	Depth range	Spatial resolution	Format	Link CNR-ISMAR catalogue (last access for all URLs: 10 December 2024)	DOIs
Survey JammeGaia22	Cruise report	–	–	PDF	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/6cd1080c-f41f-4c9d-907b-297d25f554e5	Foglini et al. (2024a), https://doi.org/10.26383/CNR-ISMAR.2024.4
JG22_SwathLines_EM2040	MBES processed lines	–	–	GSF	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/6213658d-ca9a-4e40-af07-e4f7b329203a	Foglini (2024a), https://doi.org/10.60521/331589
JG22_SwathLines_EM712	MBES processed lines	–	–	GSF	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/6213658d-ca9a-4e40-af07-e4f7b329203a	Foglini (2024b), https://doi.org/10.60521/331587
JG22_SwathLines_EM304	MBES processed lines	–	–	GSF	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/6213658d-ca9a-4e40-af07-e4f7b329203a	Foglini (2024c), https://doi.org/10.60521/331584
JG22_50_120_2m	Bathymetric surface	50–120 m	2 m	ASCII GeoTIFF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/927334e6-021a-4eed-a0a6-f209df3b17ad	Foglini et al. (2024b), https://doi.org/10.60521/331667
JG22_100_200_5m	Bathymetric surface	100–200 m	5 m	ASCII GeoTIF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/5e384b50-ea4d-4e68-b023-d5b64ebd5ed8	
JG22_180_500_10m	Bathymetric surface	180–500 m	10 m	ASCII GeoTIFF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/e956cee4-ba1c-41b7-932b-4031932c9a9d	
JG22_480_700_15m	Bathymetric surface	480–700 m	15 m	ASCII GeoTIFF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/5124f1d9-982c-4996-8333-298eb62e5c73	
JG22_680_1000_20m	Bathymetric surface	680–1000 m	20 m	ASCII GeoTIFF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/214811a5-1700-413f-9b3f-95d2ddd29996	
JG22_980_1300_30m	Bathymetric surface	980–1300 m	30 m	ASCII GeoTIFF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/a43cf1d4-abc6-43e4-9f66-fac08827c5dd	
JG22_1280_2120_40m	Bathymetric surface	1280–2120 m	40 m	ASCII GeoTIFF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/96388cc5-2c58-4ba3-9816-7231c69d96e8	
JG22_2040_5m	Backscatter mosaic from EM2040	–	5 m	ASCII GeoTIFF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/6ec52054-ac6c-46e6-966b-8a88d1cf4351	Foglini et al. (2024c), https://doi.org/10.60521/331668
JG22_712_10m	Backscatter mosaic from EM712	–	10 m	ASCII GeoTIFF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/d4c1635f-69f2-4ebc-9174-d2a9d60a1e58	
JG22_304_30m	Backscatter mosaic from EM304	–	30 m	ASCII GeoTIFF ESRI_grid	http://libeccio.bo.ismar.cnr.it:8080/geonetwork/srv/eng/catalog.search#/metadata/94f61db5-c186-48a6-b82b-7d9685c2a541	

impacts of various origins. An additional reason was offered by the opportunity to compare the newly acquired data with a previous high-standard multi-beam study of the area. In fact, this area has been already mapped since the late 1990s with state-of-the-art (for that time) instrumentation and presented in extremely accurate 3D views (D'Argenio et al., 2004; de Alteriis et al., 2010; Passaro et al., 2014; Sacchi et al., 2014; Budillon et al., 2014; Paoletti et al., 2016; Passaro et al., 2016a, b; Di Martino et al., 2021; Aiello and Sacchi, 2022). The limitation of that original database came from the need to acquire the data in a succession of surveys spanning several years and using instruments with rather variable resolutions. Nevertheless, also thanks to the extreme accuracy of the data processing performed at that time, this 20-year-old database provided an excellent basis for comparison with the newly acquired, more homogenous, database. Of course, the comparison cannot be pushed to the highest resolution offered by the modern instruments on *Gaia Blu*, but, even at lower resolution, the comparison among 20 m grids from the two data sets can be extremely valuable.

5 Data availability

All datasets, products and web services are managed through the ISMAR Marine Spatial Data Infrastructure – MSDI (Foglini and Grande, 2023) and follow the ISMAR-CNR Data Policy (https://doi.org/10.26383/CNR-ISMAR.2023.6, CNR ISMAR, 2023). Bathymetric datasets gathered by the MBESs in the format GSF (generic sensor format) and bathymetric and backscatter surfaces (GeoTIFF) are shared in the Marine Geoscience Data System (MGDS) (2024) (Table 8).

Data are also available as Web Map Services (WMS), which are interoperable with other infrastructures and permit the integration of the spatial data into other geoportals or directly into a desktop environment (e.g. QGIS, ArcMap). Data are freely accessible thought two main interfaces: the metadata catalogue and the WebGIS.

The CNR-ISMAR GeoNetwork metadata catalogue (http://seamap-catalog.data.ismar.cnr.it:8080/geonetwork, last access: 10 December 2024; CNR ISMAR, 2024a) allows users to find the JammeGaia22 products (refer to Table 8 for direct links to products), containing information about access and use policy, links to download the data, how to cite the data, the DOI, and links to external repositories (such as EMODnet and MGDS). The WebGIS (http://seamap-explorer.data.ismar.cnr.it:8080/mokaApp/applicazioni/ismarBoApp, CNR ISMAR, 2024b) publishes survey areas, multi-beam navigation lines, bathymetric surfaces, and backscatter mosaics. Users can navigate the map to the JammeGaia22 survey area, explore the layer list, and open the geophysical data and products. By clicking on spatial objects on the map, users can access the related information, such as the download link.

6 Conclusions

The JammeGaia22 cruise led to the creation of DTM and backscatter mosaics at different resolutions for the Gulf of Naples, using three different state-of-the-art MBESs. The dataset has been obtained through a reproducible processing workflow and corresponds to a major upgrade of a pre-existing bathymetry of the area. The vertical and positioning uncertainties of the bathymetric data fall within the IHO standards and satisfy Order 1b for EM2040 and Order 2 for EM712 and EM304.

The newly acquired multi-beam maps reveal submerged morphologies at a scale and resolution never achieved before for the study area, allowing for a wide range of local and regional studies, spanning from geological and geomorphological research to marine habitat mapping and seafloor monitoring. Furthermore, these high-resolution bathymetry and backscatter datasets can be useful for many and diverse applications, such as maritime spatial planning and for designing innovative conservation strategies.

The new database is released to the community as a benchmark reference against which future seafloor changes can be quantified and ascribed to either the activity of subaqueous volcanic apparatuses, in particular in the vicinity of the Phlegraean Fields, the flux of density flows along major conduits like Cuma Channel, and Magnaghi and Dohrn canyons, slope instability leading to mass-transport deposits or sand splays at the mouth of slope gullies. Large-scale bedforms are particularly developed in regions flow rearrangement like in a bend of Cuma Channel, west of Ischia island, or in the area of possible cyclic steps, on the slope south of Ischia. Backscatter data help to recognise areas of potential occurrence of cold-water coral colonies and coralligenous bioconstructions, a key element of the Mediterranean biodiversity richness. Finally, both bathymetric and backscatter data help define the areas most impacted by fish trawling, smoothing and remoulding of the seafloor, fluid-escape features, and landslides.

Author contributions. FF: supervision, data collection and processing, conceptualisation, and writing. MR: supervision, data collection, and conceptualisation. RT: supervision and data collection and processing. GC and DSG: data collection, data processing, and first-draft writing. VG and MP: data management, data processing, and first-draft writing. LP, CP, FB, FM, MC, MS, MFL, and PM: data collection and review. GDM, SI, ANT, AP, AM, and AR: data collection and processing. FT: supervision and review.

Competing interests. The contact author has declared that none of the authors has any competing interests.

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Acknowledgements. We thank the captain, crew, and scientific staff of R/V *Gaia Blu* for their skilful and efficient cooperation during operations at sea. This is ISMAR-Bologna scientific contribution no. 2088.

Review statement. This paper was edited by Simona Simoncelli and reviewed by Thierry Schmitt and Gaël Morvan.

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